```
\iter@HP:~/DOS_2241019468/Dosass5$ gedit q1.c
\iter@HP:~/DOS_2241019468/Dosass5$ gcc q1.c -o q1 -pthread
\iter@HP:~/DOS_2241019468/Dosass5$ ./q1
Producer: Produced 1
Consumer: Consumed 1
Producer: Produced 2
Consumer: Consumed 2
Producer: Produced 3
Consumer: Consumed 3
Producer: Produced 4
Consumer: Consumed 4
Producer: Produced 5
Consumer: Consumed 5
Producer-Consumer simulation completed.
```

```
\iter@HP:~/DOS_2241019468/Dosass5$ gedit q2.c
\iter@HP:~/DOS_2241019468/Dosass5$ gcc q2.c -o q2 -pthread
\iter@HP:~/DOS_2241019468/Dosass5$ ./q2
Thread A: 1
Thread B: 2
Thread A: 3
Thread B: 4
Thread A: 5
Thread B: 6
Thread A: 7
Thread B: 8
Thread A: 9
Thread B: 10
Thread A: 11
Thread B: 12
Thread A: 13
Thread B: 14
Thread A: 15
Thread B: 16
Thread A: 17
Thread B: 18
Thread A: 19
Thread B: 20
Alternating number printing completed.
```

```
\iter@HP:~/DOS_2241019468/Dosass5$ gedit q4.c
\iter@HP:~/DOS_2241019468/Dosass5$ gcc q4.c -o q4 -pthread
\iter@HP:~/DOS_2241019468/Dosass5$ ./q4
Countdown: 10
Countup: 1
Countdown: 9
Countup: 2
Countdown: 8
Countup: 3
Countdown: 7
Countup: 4
Countdown: 6
Countup: 5
Countdown: 5
Countup: 6
Countdown: 4
Countup: 7
Countdown: 3
Countup: 8
Countdown: 2
Countup: 9
Countdown: 1
Countup: 10
Countdown and Countup completed.
\iter@HP:~/DOS_2241019468/Dosass5$ gedit q5.c
\iter@HP:~/DOS_2241019468/Dosass5$ gcc q5.c -o q5 -pthread
\iter@HP:~/DOS_2241019468/Dosass5$ ./q5
A1 B2 C3 A4 B5 C6 A7 B8 C9 A10 B11 C12 A13 B14 C15 A16 B17 C18 A19 B20
Sequence Printing Completed.
\iter@HP:~/DOS_2241019468/Dosass5$
```

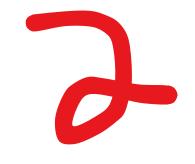
45

```
3 #include <pthread.h>
4 #include <semaphore.h>
5 #include <unistd.h>
6 #define BUFFER SIZE 10
7 #define ITERATIONS 5
8 int buffer[BUFFER SIZE];
9 int count = 0;
10 pthread mutex t mutex;
11 sem t empty;
12 sem t full;
13 void* producer(void* arg) {
      for (int i = 1; i <= ITERATIONS; i++) {</pre>
14
          sem wait(&empty);
15
          pthread_mutex_lock(&mutex);
16
17
          buffer[count] = i;
          printf("Producer: Produced %d\n", buffer[count]);
18
19
          count++;
          pthread mutex unlock(&mutex);
20
21
          sem post(&full);
22
          sleep(1);
23
      pthread_exit(NULL);
24
25 }
26 void* consumer(void* arg) {
27
      for (int i = 1; i <= ITERATIONS; i++) {</pre>
          sem wait(&full);
28
          pthread mutex lock(&mutex);
29
30
         count--;
          int item = buffer[count];
31
          printf("Consumer: Consumed %d\n", item);
32
33
          pthread mutex unlock(&mutex);
34
          sem post(&empty);
35
          sleep(1);
36
      pthread_exit(NULL);}
37
38 int main() {
      pthread_t producer_thread, consumer_thread;
39
      pthread mutex init(&mutex, NULL);
40
      sem init(&empty, 0, BUFFER_SIZE);
41
      sem init(&full, 0, 0);
42
      pthread_create(&producer_thread, NULL, producer, NULL);
43
      pthread create(&consumer thread, NULL, consumer, NULL);
44
      pthread join(producer thread, NULL);
45
      pthread join(consumer thread, NULL);
46
      pthread mutex destroy(&mutex);
47
      sem destroy(&empty);
48
      sem destroy(&full);
49
      printf("Producer-Consumer simulation completed.\n");
50
      return 0;
51
52 }
```

1 #include <stdio.h>

2 #include <stdlib.h>

```
*q1.c
1 #include <stdio.h>
2 #include <stdlib.h>
3 #include <pthread.h>
1 #include <semaphore.h>
5 #include <unistd.h>
5 #define MAX NUMBER 20
7 // Semaphores to control the order of execution
3 sem t odd sem;
3 sem t even sem;
) // Function for thread A (prints odd numbers)
l void* print odd(void* arg) {
     for (int i = 1; i <= MAX NUMBER; i += 2) {</pre>
         sem wait(&odd sem); // Wait for the odd semaphore
         printf("Thread A: %d\n", i);
         sem post(&even sem); // Signal the even semaphore
     pthread exit(NULL);
3
)// Function for thread B (prints even numbers)
void* print even(void* arg) {
     for (int i = 2; i <= MAX NUMBER; i += 2) {</pre>
         sem wait(&even sem); // Wait for the even semaphore
         printf("Thread B: %d\n", i);
         sem post(&odd sem); // Signal the odd semaphore
5
     pthread exit(NULL);
7 }
3
3 int main() {
     pthread t threadA, threadB;
     // Initialize semaphores
     sem init(&odd sem, 0, 1); // Start with odd sem available
     sem_init(&even_sem, 0, 0); // even_sem is initially unavailable
     // Create threads
     pthread create(&threadA, NULL, print odd, NULL);
     pthread create(&threadB, NULL, print even, NULL);
     // Wait for threads to finish
     pthread join(threadA, NULL);
     pthread join(threadB, NULL);
     // Destroy semaphores
     sem destroy(&odd sem);
     sem_destroy(&even_sem);
     printf("Alternating number printing completed.\n");
```

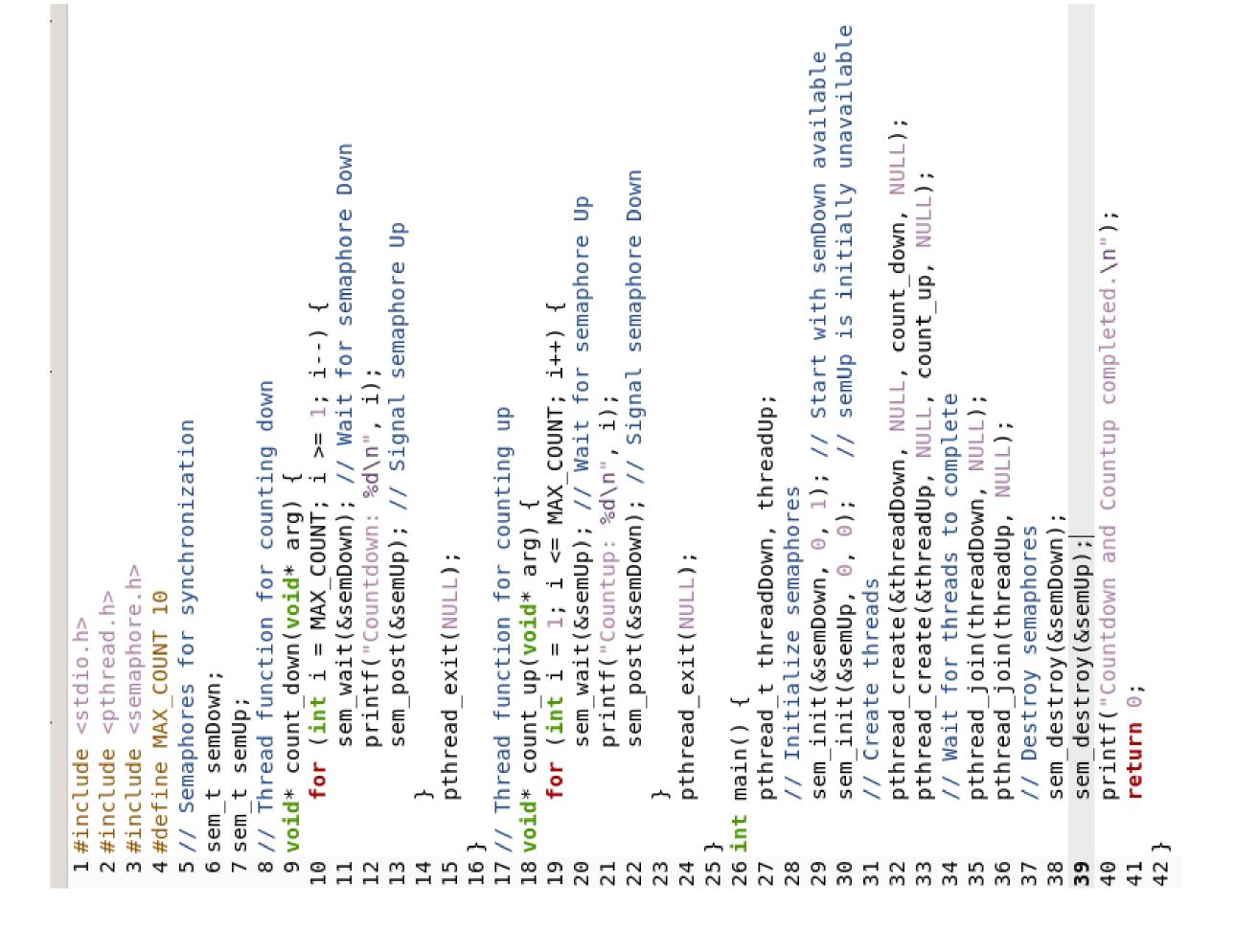






```
#define MAX_COUNT 20
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     #include
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                void* thread_B(void* arg) {
   for (int i = 2; i <= MAX_COUNT; i += 3) {
      sem_wait(&semB); // Wait for semaphore</pre>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   sem_t semA, semB, semC;
void* thread_A(void* arg) {
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             #include <semaphore.h>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          #include
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     void* thread_C(void* arg) {
   for (int i = 3; i <= MAX_COUNT; i += 3) {
      sem_wait(&semC); // Wait for semaphore C</pre>
                                                                                                                                                                                                                                                                                                                                                                      7
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          for (int i = 1; i <= MAX_COUNT; i += 3) {
    sem_wait(&semA); // Wait for semaphore A</pre>
                   printf("\nSequence
                                    sem_destroy(&semC);
                                                                                      sem_destroy(&semA);
                                                                                                            pthread
                                                                                                                                   pthread
                                                                                                                                                      pthread_join(threadA, NULL);
                                                                                                                                                                               pthread_create(&threadC, NULL,
                                                                                                                                                                                                   pthread_create(&threadA, NULL,
pthread_create(&threadB, NULL,
                                                                                                                                                                                                                                                                      sem_init(&semA, 0, 1); // Start with Thread A sem_init(&semB, 0, 0); // Thread B waits initially sem_init(&semC, 0, 0); // Thread C waits initially
                                                                                                                                                                                                                                                                                                                                          pthread
                                                                                                                                                                                                                                                                                                                                                                     main()
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               pthread_exit(NULL);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  pthread_exit(NULL);
                                                                                                                                                                                                                                                                                                                                                                                                               pthread_exit(NULL);
return 0;
                                                                                                                                                                                                                                                      Create threads
                                                               destroy(&semB);
                                                                                                                                                                                                                                                                                                                                                                                                                                                          printf("C%d ", i);
sem_post(&semA); // Signal semaphore
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           printf("B%d ", i);
sem_post(&semC); // Signal semaphore C
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               printf("A%d ", i);
sem_post(&semB); // Signal semaphore
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          <stdio.h>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  <pthread.h>
                                                                                                             _join(threadC,
                                                                                                                                                                                                                                                                                                                                          t threadA,
                                                                                                                                  join(threadB,
                                                                                                                                                                                                                                                                                                                                        threadB, threadC;
                    Printing Completed.\n"
                                                                                                                                   NULL);
                                                                                                               NULL);
                                                                                                                                                                                                   thread_A, NULL);
thread_B, NULL);
                                                                                                                                                                                 \mathsf{thread}_\mathsf{C},
                                                                                                                                                                                                   В,
                                                                                                                                                                                   NULL);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                W
```





## Theory Assignment 2

## On

## Design Principles of Operating System CSE 3249)

## Submitted by

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Section : 016

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