

Thomas Algorithm

April 9, 2015

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In [1]: # Using Thomas algorithm to solve the linear BVP
import sys
import numpy as np
import matplotlib.pyplot as plt

def thomas_algorithm(a, b, c, d):
    """
    Solves the Tridiagonal Linear System
    -- -- -- --
    /b_1 c_1      / |f_1|  |d_1|
    /a_2 b_2 c_2  / | . |  | . |
    /   a_3 . . . / | . | = | . |
    /           / | /  /  | /
    /           / | /  /  | /
    /           / | /  /  | /
    /           a_n b_n / |f_n| |d_n|
    -- -- -- --
    """
    assert len(a) == len(b) == len(c) == len(d)
    N = len(c)
    c_ = [None for i in range(N)]
    d_ = [None for i in range(N)]
    f = [None for i in range(N)]
    c_[0] = c[0]/b[0]
    d_[0] = d[0]/b[0]

    for i in range(1, N):
        c_[i] = c[i]/(b[i] - a[i]*c_[i-1])
        d_[i] = (d[i] - a[i]*d_[i-1])/(b[i] - a[i]*c_[i-1])

    f[N-1] = d_[N-1]
    for i in range(N-2, -1, -1):
        f[i] = d_[i] - c_[i]*f[i+1]

    return f

def solve_BVP(coeffs, initial_cond, final_cond, h):
    """
    Read the input file to returns a dict
    The equation is in form:  $A y'' + B y' + C y - D = 0$ 
    and the boundary_conditions are  $y(l) = y_l$  and  $y(r) = y_r$ 
    """
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"""

A, B, C, D = coeffs
l, y_l = initial_cond
r, y_r = final_cond

N = (r - l)/h
assert int(N) == N
N = int(N)

a = [None for i in range(N-1)]
b = [None for i in range(N-1)]
c = [None for i in range(N-1)]
d = [None for i in range(N-1)]

for i in range(N-1):
    a[i] = A/(h**2) - B/(2*h)
    b[i] = -2*A/(h**2) + C
    c[i] = A/(h**2) + B/(2*h)
    d[i] = D
    if i == 0:
        d[i] = D - y_l*(A/(h**2) - B/(2*h))

d[N-2] = D - y_r*(A/(h**2) + B/(2*h))

f = [y_l] + thomas_algorithm(a, b, c, d) + [y_r]
return f

In [11]: # solving BVP  $y'' - y = 0$ 
coeffs = (1, 0, -1, 0)
initial_cond = (0, 0)
final_cond = (1, 1)
h = 0.1
f = solve_BVP(coeffs, initial_cond, final_cond, h)
print f

[0, 0.08524468862598464, 0.17134182413822913, 0.25915237789185586, 0.3495544554244011, 0.44345207751119]

In [12]: %matplotlib inline
import matplotlib.pyplot as plt
X = np.linspace(0, 1, 11)
plt.plot(X, f)

Out[12]: [<matplotlib.lines.Line2D at 0x7fb5f3f26090>]

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