# Flood Fill LeetCode

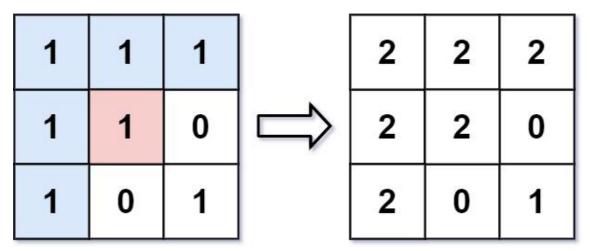
An image is represented by an m x n integer grid image where image[i][j] represents the pixel value of the image.

You are also given three integers sr, sc, and color. You should perform a **flood fill** on the image starting from the pixel image[sr][sc].

To perform a **flood fill**, consider the starting pixel, plus any pixels connected **4-directionally** to the starting pixel of the same color as the starting pixel, plus any pixels connected **4-directionally** to those pixels (also with the same color), and so on. Replace the color of all of the aforementioned pixels with color.

Return the modified image after performing the flood fill.

#### Example:



## Approach 1: Function to perform flood-fill using DFS

#### • Explanation:

- The **floodFillDFS** function uses recursive DFS traversal to modify pixels in the image.
- It explores neighboring pixels, checks conditions, and continues the traversal.

## • Time Complexity:

- The time complexity is O(N \* M), where N is the number of rows and M is the number of columns in the image.
  - Visiting each pixel once in the DFS traversal.

- Space Complexity:
  - The space complexity is O(N \* M), attributed to the recursive call stack.
    - Storing information about each pixel during traversal.

### Approach 2: Function for flood fill using BFS

- Explanation:
  - The **floodFillBFS** function uses BFS traversal to modify pixels in the image.
  - It explores neighboring pixels, checks conditions, and enqueues valid pixels for further exploration.
- Time Complexity:
  - The time complexity is O(N \* M), where N is the number of rows and M is the number of columns in the image.
    - Visiting each pixel once in the BFS traversal.
- Space Complexity:
  - The space complexity is O(N \* M), attributed to the BFS queue.
    - Storing information about each pixel during traversal.

#### Conclusion

Both DFS and BFS approaches successfully achieve flood fill in the image. The time and space complexities for both approaches are O(N \* M), where N is the number of rows and M is the number of columns in the image. The choice between them depends on specific requirements, such as memory constraints or desired exploration order. In this scenario, both approaches demonstrate similar time and space complexities.