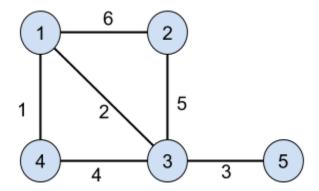
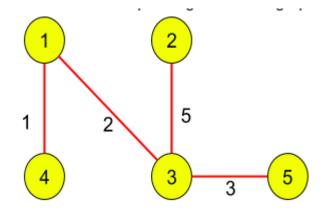
Minimum Spanning Tree in Undirected Weighted Graphs using Prim's and Krukshal's Algorithms CodeStudio

A minimum spanning tree is a subset of the edges of a connected, edge-weighted undirected graph that connects all the vertices without any cycles and with the minimum possible total edge weight.



Output: 11



addEdge Function:

• Purpose:

Adds edges to the undirected graph, considering the weights.

• Explanation:

- Iterates through each edge in the **edges** vector.
- Extracts the source vertex **u**, destination vertex **v**, and weight **w**.
- Adds edges from both **u** to **v** and **v** to **u** in the adjacency list.

- Time Complexity:
 - O(E), where E is the number of edges in the input vector.
- Space Complexity:
 - O(E), where E is the number of edges. Each edge results in the creation of entries in the adjacency list.

Approach 1: Prim's Algorithm to find Minimum Spanning Tree Weight

- Purpose:
 - Finds the MST weight using Prim's algorithm.
- Explanation:
 - Initializes vectors to store key values, MST set, and parent vertices.
 - Uses a priority queue to efficiently find the minimum key value.
 - Iteratively selects the vertex with the minimum key value not yet in the MST.
 - Includes the selected vertex in the MST and updates key values and parent vertices for neighboring vertices.
 - Calculates and returns the total weight of the MST.
- Time Complexity:
 - O((V + E) * log(V)), where V is the number of vertices and E is the number of edges.
- Space Complexity:
 - O(V + E), where V is the number of vertices and E is the number of edges.

Approach 2: Kruskal's algorithm to find the minimum spanning tree weight

- Purpose:
 - Finds the MST weight using Kruskal's algorithm.
- Explanation:
 - Sorts edges based on their weights.
 - Initializes parent array and rank array for union-find operations.

- Iterates through sorted edges and calculates the weight of the MST if it doesn't form a cycle.
- Returns the total weight of the MST.
- Time Complexity:
 - O(E * log(E)), where E is the number of edges.
- Space Complexity:
 - O(V), where V is the number of vertices. The parent array is used for union-find operations.

Conclusion:

- The **addEdge** function has a time complexity of O(E) and space complexity of O(E), directly proportional to the number of edges.
- Prim's algorithm is efficient for dense graphs, while **Kruskal's algorithm may be** preferable for sparse graphs or scenarios where edge sorting is inexpensive.