

EDUCATION

Carnegie Mellon University

Master of Science, Electrical and Computer Engineering

- GPA: 4.00/4.00

Bachelor of Science, Electrical and Computer Engineering

- GPA: 3.17/4.00

Pittsburgh, PA
Expected Dec '18

EXPERIENCE

347C Extreme Environment Robotics, NASA Jet Propulsion Laboratory

JPL Summer Internship Program, ISEE Perception Intern

- Researched composition and visible characteristics of planetary ice, discovering methods to replicate natural processes
- Crafted C++ test suite for evaluating different mapping methods on ice walls using PCL

JPL Summer Internship Program, LEMUR Perception and Navigation Intern

- Refactored and standardized Catkin C++/Python codebase and build tooling of robot control, perception, and planning software
- Investigated cause of artifacts in 3D terrain scans and implemented filtering to reduce falsely detected surfaces

JPL Summer Internship Program, LEMUR Perception and Navigation Intern

- Simulated sensor configurations and filters to optimize design and placement of surface approach sensors on rock climbing robot limbs
- Implemented C++ interface for Realsense R200 on Linux for ROS

Pololu Robotics and Electronics

Electrical Engineering Intern

- Designed and brought to market consumer motor driver shield in Altium
- Documented product and created Arduino library for product info page

Pasadena, CA
Jun - Aug '18

May - Aug '17

May - Aug '16

Las Vegas, NV
Jun - Aug '14

RESEARCH EXPERIENCE

Biorobotics Lab, Carnegie Mellon University

Undergraduate Research Assistant, Modsnake

- Planned, specced, and routed a densely packed control, sensor and power board to attach to a high powered brushless DC motor
- Migrated several ongoing lab projects from Redmine to Github
- Managed lab infrastructure including project repos, wikis, and servers
- Oriented and trained new electrical and software researchers

Planetary Robotics Lab, Carnegie Mellon University

Undergraduate Researcher, Andy Rover

- Developed space-grade power conversion and distribution board
- Conducted feasibility review on camera configurations for rover mast
- Investigated compatibility of a more rugged FPGA based image processing approach versus fragile GPU kit in computation subsystem

Pittsburgh, PA
Aug '14 - Aug '16

Pittsburgh, PA
Aug '14 - Jun '15

SKILLS

Software: ROS, Unix, CMake, OpenCV, OpenGL, Qt, Altium, Solidworks, Simulink, Photoshop

Hardware: PCB assembly, Circuit Debugging, 3D Printing, Laser Cutting, Basic Machining

Programming Languages: C, C++, C#, MATLAB, Python, Java, Javascript

Spoken Languages: English (Native), Portuguese (Fluent), French (Conversational)

SELECTED PROJECTS

SLAM Scan: Mixed Reality, ECE Capstone, Team Project

- Fused depth camera with a VR beacon to perform realtime 3D scans
- Adapted teammate's OpenGL visualizer to render in VR using OpenVR

Biogenicity Classifier, Pattern Recognition Theory (Graduate)

- Performed analysis on a set of images from cave expedition in MATLAB
- Discovered underlying discriminant for biological origins

Spring '18

Fall '17

ADDITIONAL EXPERIENCE

School of Computer Science, Carnegie Mellon University

Teaching Assistant, 15-294/15-394 Rapid Prototyping Technologies

Teaching Assistant, 15-122 Principles of Imperative Computation

Pittsburgh, PA
Aug '18 - Present
Aug '15 - Dec '15