

Parametric estimation of line spectra

Linear time series (part 2)
TSIA202b





Sinusoidal modeling of audio signals

- Sounds that generate pitch perception have a quasi-periodic waveform





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- Spectrum made of harmonic multiples of the fundamental frequency :





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 - pairs or triplets of strings in a piano, plus coupling of the vertical and horizontal vibration modes





Part I

Parametric signal model





Exponential Sinusoidal Model (ESM)

- Exponential amplitude modulation to model the natural damping of free vibrating systems





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- The observed signal x_t is modeled as the signal s_t plus a complex Gaussian white noise b_t of variance σ^2 (sequence of complex IID

r.v. of PDF $p(b) = \frac{1}{\pi\sigma^2} e^{-\frac{|b|^2}{\sigma^2}}$



Spectral estimation by Fourier analysis

■ Peak detection in the Fourier transform





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 - trade-off between the width of the principal lobe and the height of the secondary lobes induced by the window shape





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 - widening of the peak in case of exponential damping





Resolution problems

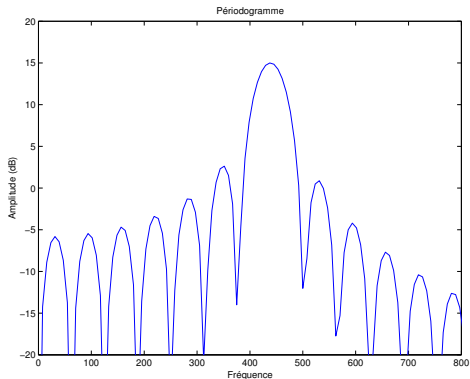
Test signal :

- Sampling frequency : 8000 Hz
- First sinusoid : 440 Hz (A)
- Second sinusoid : 415,3 Hz (G#)
- No damping, all amplitudes equal to 1
- Length of the rectangular window : $N = 128$ (16 ms)
- Length of the transform : 1024 samples



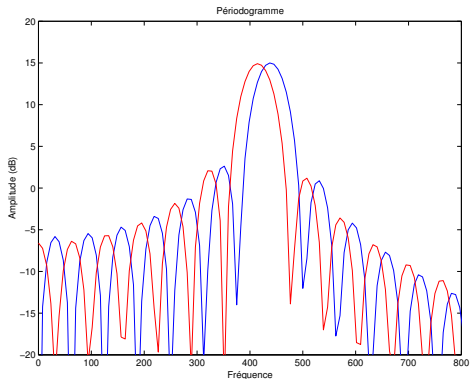


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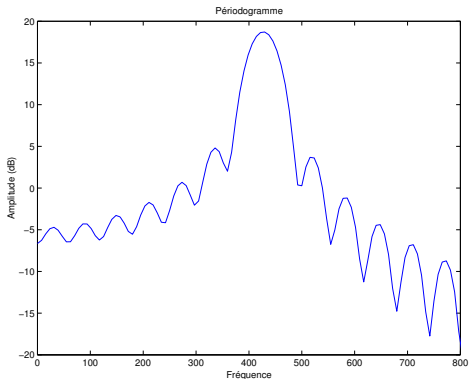


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Part II

Maximum Likelihood Method





Definitions

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- $\mathbf{x}(t) = [x_{t-l+1}, \dots, x_{t+n-1}]^\top = \mathbf{s}(t) + \mathbf{b}(t)$





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- Maximization w.r.t. σ^2 : $\sigma^2 = \frac{1}{N} \left\| \mathbf{x}(t) - \mathbf{V}^N \alpha(t) \right\|^2$





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- This optimization problem has to be solved numerically





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- High resolution parametric estimation methods overcome the limits of Fourier analysis



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- The noise variance is the residual power.





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- If $K \geq 1$, we assume that $N \gg \frac{1}{\min_{k_1 \neq k_2} |f_{k_2} - f_{k_1}|}$





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- Find the K greatest values of the periodogram
- Limit of Fourier analysis : $\min_{k_1 \neq k_2} |f_{k_2} - f_{k_1}| \gg \frac{1}{N}$





Part III

High resolution methods based on linear prediction





Jean-Baptiste Joseph Fourier (1768-1830)





Gaspard-Marie Riche of Prony (1755-1839)





Linear prediction methods

- Principle : any signal such that $s_t - z_0 s_{t-1} = 0$ is of the form $s_t = \alpha_0 z_0^t$





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- Drawback : mediocre performance in presence of noise





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- Then $\mathbf{p}^H \mathbf{X}(t) = \varepsilon(t)^H$ where $\mathbf{p} = [p_K, p_{K-1}, \dots, p_0]^H$, $\varepsilon(t) = [\varepsilon_{t-l+K+1}, \varepsilon_{t-l+K+2}, \dots, \varepsilon_{t+K}]^H$ and

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■ We minimize $\frac{1}{I} \|\varepsilon\|^2$ w.r.t. \mathbf{p} , under the constraint $p_0 = 1$

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■ The solution is $\mathbf{p} = \frac{1}{\mathbf{e}_1^H \hat{\mathbf{R}}_{xx}(t)^{-1} \mathbf{e}_1} \hat{\mathbf{R}}_{xx}(t)^{-1} \mathbf{e}_1$ where $\mathbf{e}_1 \triangleq [1, 0 \dots 0]^T$





Prony and Pisarenko methods

■ Prony method :

- Construct matrix $\mathbf{X}(t)$ and compute $\hat{\mathbf{R}}_{xx}(t)$
- Compute $\mathbf{p} = \frac{1}{\mathbf{e}_1^H \hat{\mathbf{R}}_{xx}(t)^{-1} \mathbf{e}_1} \hat{\mathbf{R}}_{xx}(t)^{-1} \mathbf{e}_1$
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■ Method of Pisarenko

- Minimize $\frac{1}{T} \|\varepsilon\|^2 = \mathbf{p}^H \hat{\mathbf{R}}_{xx}(t) \mathbf{p}$ under the constraint $\|\mathbf{p}\|_2 = 1$





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- Construct matrix $\mathbf{X}(t)$ and compute $\hat{\mathbf{R}}_{xx}(t)$
- Compute $\mathbf{p} = \frac{1}{\mathbf{e}_1^H \hat{\mathbf{R}}_{xx}(t)^{-1} \mathbf{e}_1} \hat{\mathbf{R}}_{xx}(t)^{-1} \mathbf{e}_1$
- Determine the z_k 's as the roots of $P[z] = \sum_{k=0}^K p_k z^{K-k}$

■ Method of Pisarenko

- Minimize $\frac{1}{T} \|\varepsilon\|^2 = \mathbf{p}^H \hat{\mathbf{R}}_{xx}(t) \mathbf{p}$ under the constraint $\|\mathbf{p}\|_2 = 1$
- Solution : \mathbf{p} = eigenvector of $\hat{\mathbf{R}}_{xx}(t)$ of lowest eigenvalue





Prony and Pisarenko methods

■ Prony method :

- Construct matrix $\mathbf{X}(t)$ and compute $\hat{\mathbf{R}}_{xx}(t)$
- Compute $\mathbf{p} = \frac{1}{\mathbf{e}_1^H \hat{\mathbf{R}}_{xx}(t)^{-1} \mathbf{e}_1} \hat{\mathbf{R}}_{xx}(t)^{-1} \mathbf{e}_1$
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- Pisarenko method :
 - Construct the matrix $\mathbf{X}(t)$ and compute $\hat{\mathbf{R}}_{xx}(t)$
 - Diagonalize $\hat{\mathbf{R}}_{xx}(t)$
 - \mathbf{p} = eigenvector of $\hat{\mathbf{R}}_{xx}(t)$ of lowest eigenvalue
 - Determine the z_k 's as the roots of $P[z] = \sum_{k=0}^K p_k z^{K-k}$





Part IV

Subspace-based HR methods





Matrix representation of the signal

- Observation horizon : $t \in \{0 \dots N - 1\}$, where $N > 2K$





Matrix representation of the signal

- Observation horizon : $t \in \{0 \dots N - 1\}$, where $N > 2K$
- Data matrix ($n > K$, $l > K$ and $N = n + l - 1$) :

$$\mathbf{S} = \begin{bmatrix} s_0 & s_1 & \dots & s_{l-1} \\ s_1 & s_2 & \dots & s_l \\ \vdots & \vdots & \vdots & \vdots \\ s_{n-1} & s_n & \dots & s_{N-1} \end{bmatrix}$$





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- Factorization of matrix \mathbf{S} : $\mathbf{S} = \mathbf{V}^n \mathbf{A} \mathbf{V}^l{}^\top$, where
 - \mathbf{V}^n is the **Vandermonde** matrix of dimension $n \times K$,

$$\mathbf{V}^n = \begin{bmatrix} 1 & 1 & \dots & 1 \\ z_0 & z_1 & \dots & z_{K-1} \\ z_0^2 & z_1^2 & \dots & z_{K-1}^2 \\ \vdots & \vdots & \vdots & \vdots \\ z_0^{n-1} & z_1^{n-1} & \dots & z_{K-1}^{n-1} \end{bmatrix}$$





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 - \mathbf{V}^l is the Vandermonde matrix of dimension $l \times K$,
 - $\mathbf{A} = \text{diag}(\alpha_0, \alpha_1 \dots \alpha_{K-1})$ is a diagonal matrix of dimension $K \times K$.





Empirical covariance matrix

- Let us define the empirical covariance matrix $\mathbf{R}_{ss} = \frac{1}{I} \mathbf{S} \mathbf{S}^H$





Empirical covariance matrix

- Let us define the **empirical covariance matrix** $\mathbf{R}_{ss} = \frac{1}{T} \mathbf{S} \mathbf{S}^H$
- Then $\mathbf{R}_{ss} = \mathbf{V}^n \mathbf{P} \mathbf{V}^{nH}$, where $\mathbf{P} = \frac{1}{T} \mathbf{A} \mathbf{V}^{l\top} \mathbf{V}^{l*} \mathbf{A}^H$





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- Matrix \mathbf{R}_{ss} has rank K





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 - $\forall i \in \{0 \dots K-1\}, \lambda_i > 0$;
 - $\forall i \in \{K \dots n-1\}, \lambda_i = 0$.
- Let $\hat{\mathbf{R}}_{bb} = \frac{1}{T} \mathbf{B} \mathbf{B}^H$ and $\mathbf{R}_{bb} = \mathbb{E} [\hat{\mathbf{R}}_{bb}] = \sigma^2 \mathbf{I}_n$.





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- In the same way, let $\hat{\mathbf{R}}_{xx} = \frac{1}{T} \mathbf{X} \mathbf{X}^H$ and $\mathbf{R}_{xx} = \mathbb{E} [\hat{\mathbf{R}}_{xx}]$.





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- In the same way, let $\hat{\mathbf{R}}_{xx} = \frac{1}{T} \mathbf{X} \mathbf{X}^H$ and $\mathbf{R}_{xx} = \mathbb{E} [\hat{\mathbf{R}}_{xx}]$.
- Then $\mathbf{R}_{xx} = \mathbf{R}_{ss} + \sigma^2 \mathbf{I}_n$





Signal subspace and noise subspace

- For all $i \in \{0 \dots n-1\}$, \mathbf{w}_i is also an eigenvector of \mathbf{R}_{xx} corresponding to the eigenvalue $\lambda'_i = \lambda_i + \sigma^2$. Therefore,





Signal subspace and noise subspace

- For all $i \in \{0 \dots n-1\}$, \mathbf{w}_i is also an eigenvector of \mathbf{R}_{xx} corresponding to the eigenvalue $\lambda'_i = \lambda_i + \sigma^2$. Therefore,
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- The poles $\{z_k\}_{k \in \{0 \dots K-1\}}$ are the solutions of equation
$$\|\mathbf{W}_\perp^H \mathbf{v}(z)\|^2 = 0, \text{ where } \mathbf{v}(z) = [1, z, \dots, z^{n-1}]$$





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- The **MUSIC** method consists in solving this equation





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$$\|\mathbf{W}_\perp^H \mathbf{v}(z)\|^2 = 0, \text{ where } \mathbf{v}(z) = [1, z, \dots, z^{n-1}]$$
- The **MUSIC** method consists in solving this equation
- The **Spectral-MUSIC** method consists in detecting the K highest peaks in function $z \mapsto \frac{1}{\|\mathbf{W}_\perp^H \mathbf{v}(z)\|^2}$.





Spectral MUSIC method

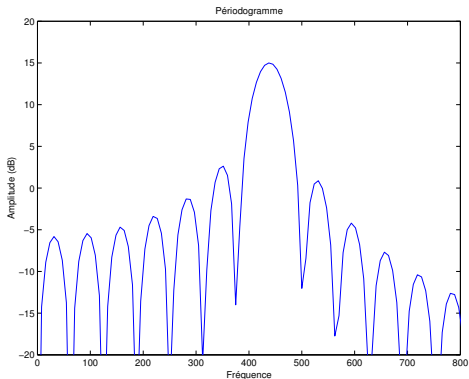
Test signal :

- Sampling frequency : 8000 Hz
- First sinusoid : 440 Hz (A)
- Second sinusoid : 415,3 Hz (G#)
- No damping, all amplitudes equal to 1
- Length of the rectangular window : $N = 128$ (16 ms)
- Length of the transform : 1024 samples



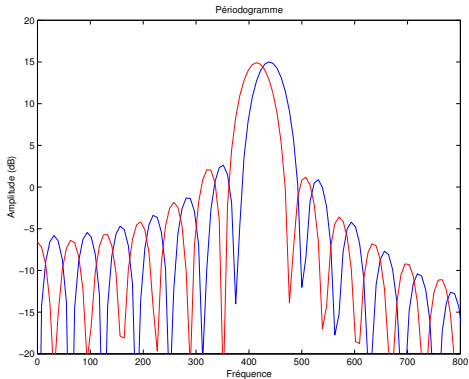


Spectral MUSIC method



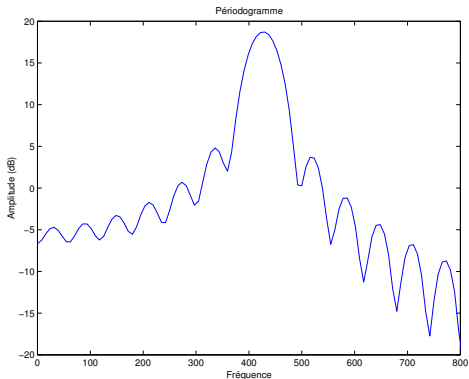


Spectral MUSIC method



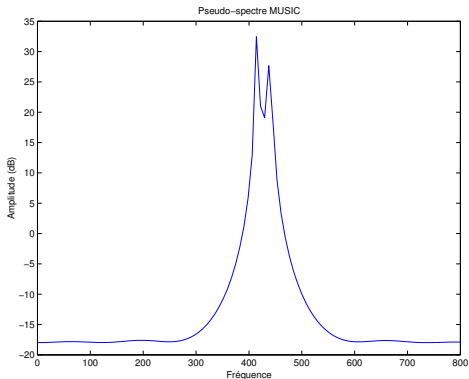


Spectral MUSIC method





Spectral MUSIC method





ESPRIT method

- Rotational invariance property of \mathbf{V}^n :

$$\underbrace{\begin{bmatrix} 1 & \dots & 1 \\ z_0 & \dots & z_{K-1} \\ \vdots & \dots & \vdots \\ z_0^{n-2} & \dots & z_{K-1}^{n-2} \\ z_0^{n-1} & \dots & z_{K-1}^{n-1} \end{bmatrix}}_{\mathbf{V}^n}$$

\mathbf{V}^n
 $n \times K$





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$(n-1) \times K$





ESPRIT method

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- Rotational invariance property of \mathbf{V}^n : $\mathbf{V}_{\uparrow}^n = \mathbf{V}_{\downarrow}^n \mathbf{D}$



ESPRIT method

- Rotational invariance property of \mathbf{V}^n : $\mathbf{V}_{\uparrow}^n = \mathbf{V}_{\downarrow}^n \mathbf{D}$
- Change of basis : $\mathbf{V}^n = \mathbf{W} \mathbf{G}$



ESPRIT method

- Rotational invariance property of \mathbf{V}^n : $\mathbf{V}_{\uparrow}^n = \mathbf{V}_{\downarrow}^n \mathbf{D}$
- Change of basis : $\mathbf{V}^n = \mathbf{W} \mathbf{G}$
- Rotational invariance of \mathbf{W} : $\mathbf{W}_{\uparrow} = \mathbf{W}_{\downarrow} \mathbf{\Phi}$
where $\mathbf{\Phi} = \mathbf{G} \mathbf{D} \mathbf{G}^{-1}$ is referred to as the **spectral matrix**



ESPRIT method

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- The eigenvalues of $\mathbf{\Phi}$ are the poles $\{z_k\}_{k \in \{0 \dots K-1\}}$



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- Change of basis : $\mathbf{V}^n = \mathbf{W} \mathbf{G}$
- Rotational invariance of \mathbf{W} : $\mathbf{W}_{\uparrow} = \mathbf{W}_{\downarrow} \mathbf{\Phi}$
where $\mathbf{\Phi} = \mathbf{G} \mathbf{D} \mathbf{G}^{-1}$ is referred to as the **spectral matrix**
- The eigenvalues of $\mathbf{\Phi}$ are the poles $\{z_k\}_{k \in \{0 \dots K-1\}}$
- Matrix $\mathbf{\Phi}$ is such that $\mathbf{\Phi} = \left(\mathbf{W}_{\downarrow}^H \mathbf{W}_{\downarrow} \right)^{-1} \mathbf{W}_{\downarrow}^H \mathbf{W}_{\uparrow}$





ESPRIT method

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Part V

Estimation of the other parameters





Estimation of the modeling order

- Information Theoretic Criteria (ITC) : we minimize

$$\text{ITC}(p) = -(n-p) \ln \left(\frac{\left(\prod_{q=p+1}^n \sigma_q^2 \right)^{\frac{1}{n-p}}}{\sum_{q=p+1}^n \sigma_q^2} \right) + p(2n-p) C(l)$$

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- The penalty term $C(l)$ avoids over-estimating p .





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- We finally get $\hat{a}_k = |\hat{\alpha}_k|$ and $\hat{\phi}_k = \arg(\hat{\alpha}_k)$





Part VI

Performance of the estimators





Cramér-Rao bounds

■ Regular statistical model

- Consider a statistical model $p(\mathbf{x}; \theta)$ parameterized by θ
- Score function : $l(\mathbf{x}; \theta) \triangleq \nabla_{\theta} \ln p(\mathbf{x}; \theta) \mathbf{1}_{p(\mathbf{x}; \theta) > 0}$
- The parameterization is said *regular* if :
 1. $p(\mathbf{x}; \theta)$ is continuously differentiable w.r.t. θ .
 2. $\mathbf{F}(\theta) \triangleq \int_H l(\mathbf{x}; \theta) l(\mathbf{x}; \theta)^{\top} p(\mathbf{x}; \theta) d\mathbf{x}$ (Fisher information matrix) is positive definite for all θ and continuous w.r.t. θ





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■ Cramér-Rao bounds

- Consider a regular statistic model parameterized by θ
- Let $\hat{\theta}$ be an unbiased estimator of θ ($\forall \theta \in \Theta, \mathbb{E}_{\theta}[\hat{\theta}] = \theta$)
- Then the dispersion matrix $\mathbf{D}(\theta, \hat{\theta}) \triangleq \mathbb{E}_{\theta} \left[(\hat{\theta} - \theta) (\hat{\theta} - \theta)^{\top} \right]$ is such that matrix $\mathbf{D}(\theta, \hat{\theta}) - \mathbf{F}(\theta)^{-1}$ is positive semidefinite.





Cramér-Rao bounds

- For a family of complex Gaussian distributions of covariance $\mathbf{R}_{bb}(\boldsymbol{\theta}) \in \mathcal{C}^1(\Theta, \mathbb{C}^{N \times N})$ and of mean $\mathbf{s}(\boldsymbol{\theta}) \in \mathcal{C}^1(\Theta, \mathbb{C}^N)$,

$$F_{(i,j)}(\boldsymbol{\theta}) = \text{trace} \left(\mathbf{R}_{bb}^{-1} \frac{\partial \mathbf{R}_{bb}(\boldsymbol{\theta})}{\partial \theta_i} \mathbf{R}_{bb}^{-1} \frac{\partial \mathbf{R}_{bb}(\boldsymbol{\theta})}{\partial \theta_j} \right) + 2 \text{Re} \left(\frac{\partial \mathbf{s}(\boldsymbol{\theta})}{\partial \theta_i}^H \mathbf{R}_{bb}^{-1} \frac{\partial \mathbf{s}(\boldsymbol{\theta})}{\partial \theta_j} \right)$$





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- All bounds are independent of the phases ϕ_k and are unchanged by any translation of the set of frequencies f_k
- If $\forall k, \delta_k = 0$ and if $N \rightarrow +\infty$, then :
 - $\text{CRB}\{\sigma\} = \frac{\sigma^2}{4N} + O\left(\frac{1}{N^2}\right)$
 - $\text{CRB}\{f_k\} = \frac{6\sigma^2}{4\pi^2 N^3 a_k^2} + O\left(\frac{1}{N^4}\right)$
 - $\text{CRB}\{a_k\} = \frac{2\sigma^2}{N} + O\left(\frac{1}{N^2}\right)$
 - $\text{CRB}\{\phi_k\} = \frac{2\sigma^2}{Na_k^2} + O\left(\frac{1}{N^2}\right)$





Performance of HR methods

■ Performance of an estimator

- Performance expressed in terms of bias and variance
- Efficiency : ratio between variance and Cramér-Rao bound
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- Maximum likelihood : unbiased and asymptotically efficient ($N \rightarrow +\infty$)
- HR methods : results based on the perturbation theory
 - Assumptions : $N \rightarrow +\infty$ or $\text{SNR} \rightarrow +\infty$
 - All the HR methods are asymptotically unbiased
 - The Prony and Pisarenko methods are very inefficient : their variances are significantly greater than the Cramér-Rao bounds.
 - MUSIC and ESPRIT have an asymptotic efficiency close to 1





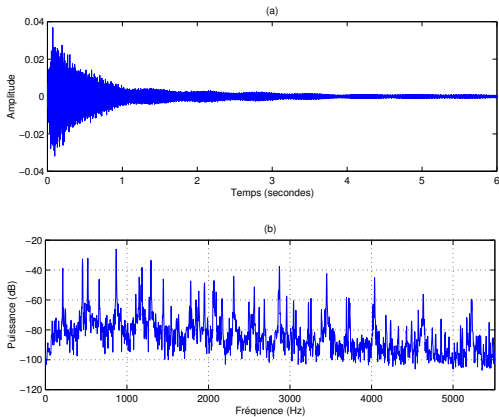
Part VII

Signals to be processed





Bell sound



(a) Signal waveform

(b) Power spectral density

