

~/ros2_ws3/src/talkerlistener/launch/talk_listen_launch.py

```
1 from launch import LaunchDescription
2 from launch_ros.actions import Node
3 from launch.actions import DeclareLaunchArgument
4 from launch.substitutions import LaunchConfiguration
5
6 def generate_launch_description():
7     message_arg = DeclareLaunchArgument(
8         'message',
9         default_value='Hello from launch file!',
10        description='Message to publish'
11    )
12
13    talker_node = Node(
14        package='talkerlistener',
15        executable='talker',
16        name='talker',
17        parameters=[{'message': LaunchConfiguration('message')}]
18    )
19
20    listener_node = Node(
21        package='talkerlistener',
22        executable='listener',
23        name='listener'
24    )
25
26    return LaunchDescription([
27        message_arg,
28        talker_node,
29        listener_node
30    ])
```