Problem 0.1. (2 points) Find the reduced row-echelon form of the matrix

$$A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 4 & 5 & 6 & 2 \\ 7 & 8 & 9 & 3 \end{bmatrix}$$

$$\operatorname{rref}(A) =$$

Problem 0.2. (2 points) Find the solution set of the linear system below in parametric vector form.

$$\begin{cases} x + 2y + 3z = 1 \\ 4x + 5y + 6z = 2 \\ 7x + 8y + 9z = 3 \end{cases}$$

solution			
Solution			
set			

Problem 0.3. (2 points) Simplify the following matrix expression:

$$\begin{bmatrix} 0 & 0 & 1 \end{bmatrix} \left(\begin{bmatrix} a \\ b \\ c \end{bmatrix} \begin{bmatrix} a & b \end{bmatrix} + \begin{bmatrix} e \\ f \\ g \end{bmatrix} \begin{bmatrix} e & f \end{bmatrix} \right) \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

simplified expression

Problem 0.4. (2 points) Find and simplify the inverse of the matrix

$$A = \begin{bmatrix} 1 & 0 & 0 \\ a & 1 & 0 \\ 0 & a & 1 \end{bmatrix}$$

$$A^{-1} =$$

Problem 0.5. (2 points) Find the LU-factorization of the matrix

$$A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 4 & 5 & 6 & 2 \\ 7 & 8 & 9 & 3 \end{bmatrix}$$

$$L=oxed{U=}$$

Problem 0.6. (2 points) Find the CR-factorization of the matrix

$$A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 4 & 5 & 6 & 2 \\ 7 & 8 & 9 & 3 \end{bmatrix}$$

$$C =$$
 $R =$

Problem 0.7. (2 points) Showing/explaining your work, find the determinant of the matrix

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & -1 \\ 1 & 0 & 1 \end{bmatrix}$$

$$\det A =$$

Problem 0.8. (2 points) If possible, diagonalize the matrix below.

$$A = \begin{bmatrix} 5 & -1 \\ 9 & -1 \end{bmatrix}$$

$$A = SDS^{-1}$$
 where $S =$ and $D =$

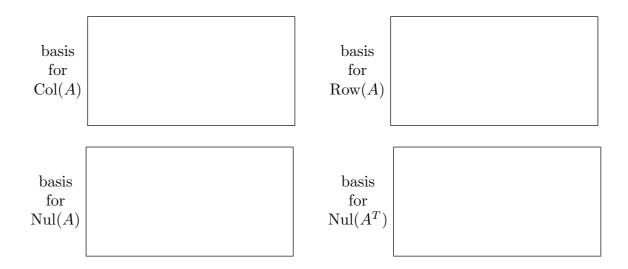
Problem 0.9. (2 points) Showing your work, deterimine if the following set is linearly dependent or linearly independent.

$$\left\{ \begin{bmatrix} 1\\2\\3 \end{bmatrix}, \begin{bmatrix} 4\\5\\6 \end{bmatrix}, \begin{bmatrix} 7\\8\\9 \end{bmatrix} \right\}$$

Circle one: Linearly dependent Linearly independent

Problem 0.10. (4 points) Find bases for the four fundamental subspaces of the matrix

$$A = \begin{bmatrix} 1 & 2 & 1 \\ 3 & 7 & 4 \end{bmatrix}$$



Problem 0.11. (4 points) Diagonalize, if possible.

$$A = \begin{bmatrix} 2 & -1 & -1 \\ 1 & 0 & -1 \\ 3 & -1 & -2 \end{bmatrix}$$

$$A = SDS^{-1}$$
 where $S =$

and
$$D =$$

Problem 0.12. (2 points) Find the least squares solutions of $\begin{bmatrix} 1 & -1 \\ 1 & -1 \\ 1 & -1 \end{bmatrix} \mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$.

$$\mathbf{x} =$$

Problem 1.1. (10 points) Find the QR-factorization of the matrix

$$A = \begin{bmatrix} 6 & -5 & 0 \\ 8 & 10 & 0 \\ 0 & 0 & 7 \end{bmatrix}$$

$$Q =$$

$$R =$$

Problem 1.2. (10 points) Find an orthogonal diagonalization of the following matrix:

$$A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

$$A = UDU^T$$
 where $U =$

and D =

Problem 1.2. (10 points) Find the singular value decomposition (SVD) of the matrix:

$$A = \begin{bmatrix} 1 & 4 \\ 2 & -2 \\ 2 & 0 \end{bmatrix}$$

$$A = U\Sigma V^T$$
 where $U =$

$$\Sigma =$$

$$V =$$

(a)	The set of pivot columns of a matrix is linearly independent.
(b)	If $det(A) = 1$, then A is invertible.
(c)	If $1 \in \sigma(A)$, then $A - I$ is singular.
(d)	For an $n \times n$ matrix A with n signular values, $ A\mathbf{x} \ge \sigma_n \mathbf{x} $.
(e)	The normal equations $A^T A \mathbf{x} = A^T \mathbf{b}$ always have at least one solution.

Problem 2. (10 points) Evaluate the truth of each statement below. If the statement is

true write T in the box preceding the statement. Otherwise, write F.

Problem 3. (10 points) The built-in MATLAB function null returns a matrix having columns that form an orthonormal basis for the null space of the input matrix. For example,

Provide the output expected from MATLAB for the given commands in the answer boxes:

```
>> A = [1 1 1 0; 1 1 1 0 ; 1 1 1 0; 0 0 0 0];
>> rref(A)
ans =
          1
                  0
               0
                  0
          0
               0
       0
          0
                  0
       0
          0
               0
                  0
>> N=null(A);
>> A*N
```



>> transpose(N)*N % transpose outputs the transpose of the input matrix

