## Practical Machine Learning - Course Project

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## Aim of the project

Predict classe response based on movement predictors.

```
training <- read.csv("pml-training.csv", header = TRUE, row.names = 1)
testing <- read.csv("pml-testing.csv", header = TRUE, row.names = 1)
str(training)</pre>
```

```
## 'data.frame':
                   19622 obs. of 159 variables:
                            : Factor w/ 6 levels "adelmo", "carlitos", ...: 2 2 2 2 2 2 2 2 2 2 ...
## $ user_name
## $ raw timestamp part 1
                            : int 1323084231 1323084231 1323084231 1323084232 1323084232 1323084232
                                   788290 808298 820366 120339 196328 304277 368296 440390 484323 484
## $ raw_timestamp_part_2
                            : int
## $ cvtd_timestamp
                            : Factor w/ 20 levels "02/12/2011 13:32",..: 9 9 9 9 9 9 9 9 9 ...
## $ new_window
                            : Factor w/ 2 levels "no", "yes": 1 1 1 1 1 1 1 1 1 1 ...
## $ num_window
                                   11 11 11 12 12 12 12 12 12 12 ...
## $ roll_belt
                                   1.41 1.41 1.42 1.48 1.48 1.45 1.42 1.42 1.43 1.45 ...
## $ pitch_belt
                            : num 8.07 8.07 8.07 8.05 8.07 8.06 8.09 8.13 8.16 8.17 ...
## $ yaw_belt
                                   -94.4 - 94.4 - 94.4 - 94.4 - 94.4 - 94.4 - 94.4 - 94.4 - 94.4 \dots
## $ total_accel_belt
                                   3 3 3 3 3 3 3 3 3 ...
                            : int
                            : Factor w/ 397 levels "","-0.016850",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis_roll_belt
## $ kurtosis_picth_belt
                            : Factor w/ 317 levels "","-0.021887",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis yaw belt
                            : Factor w/ 2 levels "", "#DIV/0!": 1 1 1 1 1 1 1 1 1 1 ...
                            : Factor w/ 395 levels "","-0.003095",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_roll_belt
                            : Factor w/ 338 levels "","-0.005928",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness roll belt.1
## $ skewness_yaw_belt
                            : Factor w/ 2 levels "", "#DIV/0!": 1 1 1 1 1 1 1 1 1 1 ...
## $ max_roll_belt
                            : num NA NA NA NA NA NA NA NA NA ...
## $ max_picth_belt
                            : int \, NA ...
## $ max_yaw_belt
                            : Factor w/ 68 levels "","-0.1","-0.2",..: 1 1 1 1 1 1 1 1 1 1 ...
                            : num NA NA NA NA NA NA NA NA NA ...
## $ min_roll_belt
## $ min_pitch_belt
                            : int NA NA NA NA NA NA NA NA NA ...
                            : Factor w/ 68 levels "","-0.1","-0.2",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ min_yaw_belt
## $ amplitude_roll_belt
                            : num NA NA NA NA NA NA NA NA NA ...
## $ amplitude_pitch_belt
                            : int NA NA NA NA NA NA NA NA NA ...
                            : Factor w/ 4 levels "","#DIV/0!","0.00",..: 1 1 1 1 1 1 1 1 1 1 1 ...
## $ amplitude_yaw_belt
##
   $ var_total_accel_belt
                            : num
                                   NA NA NA NA NA NA NA NA NA ...
## $ avg_roll_belt
                            : num
                                   NA NA NA NA NA NA NA NA NA ...
## $ stddev_roll_belt
                            : num NA NA NA NA NA NA NA NA NA ...
## $ var_roll_belt
                            : num NA NA NA NA NA NA NA NA NA ...
## $ avg_pitch_belt
                            : num NA NA NA NA NA NA NA NA NA ...
## $ stddev_pitch_belt
                            : num NA NA NA NA NA NA NA NA NA ...
## $ var_pitch_belt
                            : num NA NA NA NA NA NA NA NA NA ...
## $ avg_yaw_belt
                            : num NA NA NA NA NA NA NA NA NA ...
## $ stddev_yaw_belt
                            : num
                                   NA NA NA NA NA NA NA NA NA ...
## $ var_yaw_belt
                            : num NA NA NA NA NA NA NA NA NA ...
## $ gyros_belt_x
                            ## $ gyros_belt_y
                            : num 0 0 0 0 0.02 0 0 0 0 ...
```

```
## $ gyros belt z
                                 -0.02 -0.02 -0.02 -0.03 -0.02 -0.02 -0.02 -0.02 -0.02 0 ...
                           : num
## $ accel_belt_x
                                 -21 -22 -20 -22 -21 -21 -22 -22 -20 -21 ...
                           : int
## $ accel belt y
                           : int
                                 4 4 5 3 2 4 3 4 2 4 ...
## $ accel_belt_z
                                  22 22 23 21 24 21 21 21 24 22 ...
                           : int
## $ magnet_belt_x
                           : int
                                  -3 -7 -2 -6 -6 0 -4 -2 1 -3 ...
## $ magnet_belt_y
                                 599 608 600 604 600 603 599 603 602 609 ...
                           : int
## $ magnet_belt_z
                           : int
                                  -313 -311 -305 -310 -302 -312 -311 -313 -312 -308 ...
##
   $ roll arm
                           : num
                                  ##
   $ pitch arm
                                  22.5 22.5 22.5 22.1 22.1 22 21.9 21.8 21.7 21.6 ...
                           : num
## $ yaw_arm
                           : num
                                 $ total_accel_arm
                                  34 34 34 34 34 34 34 34 34 ...
                           : int
##
   $ var_accel_arm
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ avg_roll_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
## $ stddev_roll_arm
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ var_roll_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
##
   $ avg_pitch_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
## $ stddev_pitch_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
## $ var_pitch_arm
                                 NA NA NA NA NA NA NA NA NA . . .
                           : num
                           : num NA NA NA NA NA NA NA NA NA ...
## $ avg_yaw_arm
## $ stddev_yaw_arm
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ var_yaw_arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ gyros_arm_x
                                 : num
## $ gyros_arm_y
                           : num
                                 0 -0.02 -0.02 -0.03 -0.03 -0.03 -0.03 -0.02 -0.03 -0.03 ...
## $ gyros_arm_z
                           : num
                                 -0.02 -0.02 -0.02 0.02 0 0 0 0 -0.02 -0.02 ...
## $ accel_arm_x
                           : int
                                 ## $ accel_arm_y
                           : int
                                 109 110 110 111 111 111 111 111 109 110 ...
## $ accel_arm_z
                                 -123 -125 -126 -123 -123 -122 -125 -124 -122 -124 ...
                           : int
                           : int
## $ magnet_arm_x
                                 -368 -369 -368 -372 -374 -369 -373 -372 -369 -376 ...
## $ magnet_arm_y
                           : int 337 337 344 344 337 342 336 338 341 334 ...
## $ magnet_arm_z
                           : int 516 513 513 512 506 513 509 510 518 516 ...
## $ kurtosis_roll_arm
                           : Factor w/ 330 levels "","-0.02438",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis_picth_arm
                           : Factor w/ 328 levels "","-0.00484",..: 1 1 1 1 1 1 1 1 1 1 ...
                           : Factor w/ 395 levels "","-0.01548",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis_yaw_arm
                           : Factor w/ 331 levels "","-0.00051",...: 1 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_roll_arm
                           : Factor w/ 328 levels "","-0.00184",...: 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_pitch_arm
## $ skewness_yaw_arm
                           : Factor w/ 395 levels "","-0.00311",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ max roll arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ max_picth_arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ max_yaw_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : int
## $ min_roll_arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ min_pitch_arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ min_yaw_arm
                           : int NA NA NA NA NA NA NA NA NA ...
## $ amplitude_roll_arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ amplitude_pitch_arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ amplitude_yaw_arm
                           : int
                                 NA NA NA NA NA NA NA NA NA ...
##
   $ roll_dumbbell
                           : num
                                 13.1 13.1 12.9 13.4 13.4 ...
## $ pitch_dumbbell
                           : num -70.5 -70.6 -70.3 -70.4 -70.4 ...
## $ yaw_dumbbell
                           : num -84.9 -84.7 -85.1 -84.9 -84.9 ...
## $ kurtosis_roll_dumbbell : Factor w/ 398 levels "","-0.0035","-0.0073",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis_picth_dumbbell : Factor w/ 401 levels "","-0.0163","-0.0233",..: 1 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis_yaw_dumbbell : Factor w/ 2 levels "","#DIV/0!": 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness roll dumbbell : Factor w/ 401 levels "","-0.0082","-0.0096",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_pitch_dumbbell : Factor w/ 402 levels "","-0.0053","-0.0084",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_yaw_dumbbell : Factor w/ 2 levels "","#DIV/0!": 1 1 1 1 1 1 1 1 1 1 ...
```

```
## $ max roll dumbbell
                             : num NA NA NA NA NA NA NA NA NA ...
## $ max_picth_dumbbell
                             : num NA NA NA NA NA NA NA NA NA ...
                             : Factor w/ 73 levels "","-0.1","-0.2",..: 1 1 1 1 1 1 1 1 1 1 1 ...
## $ max yaw dumbbell
## $ min_roll_dumbbell
                             : num NA NA NA NA NA NA NA NA NA ...
## $ min_pitch_dumbbell
                             : num NA NA NA NA NA NA NA NA NA ...
## $ min yaw dumbbell
                             : Factor w/ 73 levels "","-0.1","-0.2",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ amplitude roll dumbbell : num NA ...
   $ amplitude_pitch_dumbbell: num    NA ...
##
##
     [list output truncated]
```

Some of the predictors appear to exhibit a large number of NA-values. Which predictors have more than 50% NA-observations and/or blank values?

```
index_na <- vector()
counter <- 1

for(i in 1:ncol(training)){
   ratio_na <- as.data.frame(prop.table(table(is.na(training[,i]))))

if(ratio_na$Freq[ratio_na$Var1 == FALSE] < 0.5 | sum(training[,i] == "") > 1){
   index_na[counter] <- i
   counter <- counter+1
   }
}</pre>
```

In a more elaborate walkthrough, you could try to impute the missing values for the "NA-rich" predictors. For now, I will discard respective predictors. Note that there are no more NA-values in the training dataset. Therefore, there is no need for imputation later on. If imputation was needed, I would probably use a proximity matrix to do so, since I will classify the data based on the random Forest method.

I will also remove the timestamp-columns.

```
# does the testing data have the same column order as the training data?
check_col <- colnames(training) == colnames(testing)
which(check_col == FALSE)

## [1] 159
# the last column holds different variables in training and testing data, the others are the same
# delete na-rich or blank-rich predictors
training <- training[,-index_na]
testing <- testing[,-index_na]

# delete time stamp columns
training <- training[,-(2:4)]
testing <- testing[,-(2:4)]</pre>
```

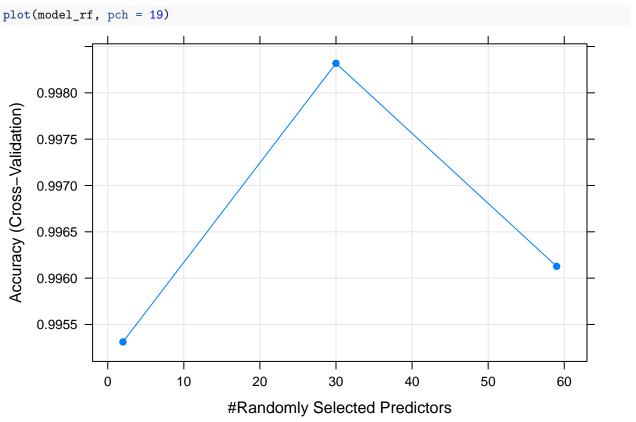
Let's try to classify the data using the randomForest method. First, we split the data to allow for cross-validation.

Random forest computation takes a long time without parallelization. Hence, I will use the parallel and doParallel package to reduce time expenses.

```
library(caret)
## Loading required package: lattice
## Loading required package: ggplot2
```

```
library(parallel)
library(doParallel)
## Loading required package: foreach
## Loading required package: iterators
library(ggplot2)
set.seed(42)
# define cluster
cluster <- makeCluster(detectCores() - 1)</pre>
registerDoParallel(cluster)
# define 5-fold cross-validation
trControl <- trainControl(method="cv", number=5, allowParallel = TRUE)</pre>
# create random forest model
model_rf <- train(classe~., data=training, method="rf", trControl=trControl, verbose=FALSE)
# shutting down cluster after successful computation
stopCluster(cluster)
registerDoSEQ()
```

The random forest has one major hyperparameter, mtry, i.e. the number of randomly selected predictors per node. Since I applied cross-validation, I can estimate an optimal mtry-value based on cross-validation accuracy.



abline

```
## function (a = NULL, b = NULL, h = NULL, v = NULL, reg = NULL,
       coef = NULL, untf = FALSE, ...)
##
## {
##
       int_abline <- function(a, b, h, v, untf, col = par("col"),</pre>
           lty = par("lty"), lwd = par("lwd"), ...) .External.graphics(C_abline,
##
           a, b, h, v, untf, col, lty, lwd, ...)
##
##
       if (!is.null(reg)) {
##
            if (!is.null(a))
##
                warning("'a' is overridden by 'reg'")
##
           a <- reg
       }
##
       if (is.object(a) || is.list(a)) {
##
##
           p <- length(coefa <- as.vector(coef(a)))</pre>
##
            if (p > 2)
                warning(gettextf("only using the first two of %d regression coefficients",
##
                    p), domain = NA)
##
##
           islm <- inherits(a, "lm")</pre>
           noInt <- if (islm)</pre>
##
##
                !as.logical(attr(stats::terms(a), "intercept"))
##
           else p == 1
            if (noInt) {
##
                a <- 0
##
                b <- coefa[1L]
##
##
           }
##
           else {
                a <- coefa[1L]
##
##
                b \leftarrow if (p >= 2)
##
                    coefa[2L]
##
                else 0
##
           }
##
       }
##
       if (!is.null(coef)) {
##
            if (!is.null(a))
##
                warning("'a' and 'b' are overridden by 'coef'")
##
           a \leftarrow coef[1L]
##
           b <- coef[2L]
##
##
       int_abline(a = a, b = b, h = h, v = v, untf = untf, ...)
       invisible()
##
## }
## <bytecode: 0x7fdf9bd068b0>
## <environment: namespace:graphics>
```

If I had more computational power and more time, I would scan more than three mtry-values. For now, I will build my final model with mtry=30 since it provided the best accuracy.

Note that cross-validation can also provide a good estimate of the out of sample error.

## model\_rf\$resample

```
## Accuracy Kappa Resample
## 1 0.9974529 0.9967783 Fold1
## 2 0.9979613 0.9974213 Fold3
## 3 0.9992355 0.9990330 Fold2
```

```
## 4 0.9987258 0.9983882 Fold5
## 5 0.9982161 0.9977437 Fold4
```

The accuracy in each fold is very high. Less than 1% of the observations were incorrectly classified. I assume that the model will perform similarly well on similar data.

Let's predict classe for the 20 test observations.

```
predictions <- predict(model_rf, newdata = testing[,-56])</pre>
```

Finally, let's save the predictions in an appropriate format.

```
results <- data.frame(problem_id = testing$problem_id, predictions = predictions)
write.csv(results, "Predictions_ArneSchoch.csv")</pre>
```