Three Body Work-Precision Diagrams

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May 9, 2021

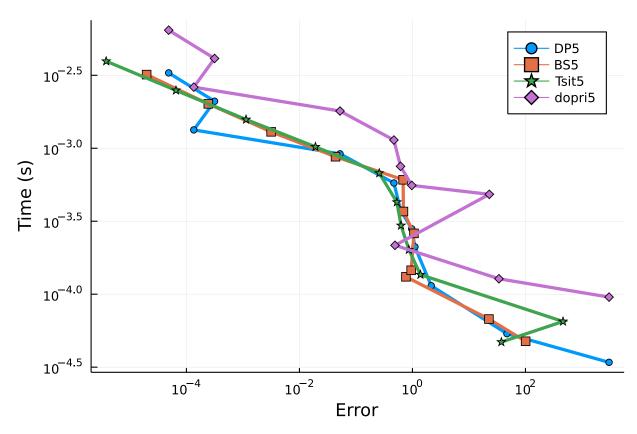
```
using OrdinaryDiffEq, ODE, ODEInterfaceDiffEq, LSODA, Sundials, DiffEqDevTools, Plots;
gr()
## Define the ThreeBody Problem
const threebody \mu = parse(Float64, "0.012277471")
const threebody_\mu/ = 1 - threebody_\mu
f = (du,u,p,t) \rightarrow begin
 @inbounds begin
  # 1 = y_1
  \# 2 = y_2
  \# 3 = y_1'
  \# 4 = y_2'
 D_1 = ((u[1] + threebody_{\mu})^2 + u[2]^2)^(3/2)
 D_2 = ((u[1]-threebody_{\mu})^2 + u[2]^2)^(3/2)
  du[1] = u[3]
  du[2] = u[4]
  du[3] = u[1] + 2u[4] - threebody_{\mu}*(u[1]+threebody_{\mu})/D_1 -
threebody_\mu*(u[1]-threebody_\mu)/D_2
  du[4] = u[2] - 2u[3] - threebody_\(\mu/*u[2]/D_1 - threebody_\(\mu*u[2]/D_2)
end
t_0 = 0.0; T = parse(Float64, "17.0652165601579625588917206249")
tspan = (t_0, 2T)
prob = ODEProblem(f,[0.994, 0.0, 0.0,
parse(Float64, "-2.00158510637908252240537862224")], tspan)
test_sol = TestSolution(T,[prob.u0])
abstols = 1.0 ./ 10.0 .^ (3:13); reltols = 1.0 ./ 10.0 .^ (0:10);
See that it's periodic in the chosen timespan:
sol = solve(prob, Vern9(), abstol=1e-14, reltol=1e-14)
@show sol[1] - sol[end]
@show sol[end] - prob.u0;
sol[1] - sol[end] = [-1.063673593648673e-10, -3.162927231499068e-10, -5.160]
479797103475e-8, -1.6555705695253664e-8]
sol[end] - prob.u0 = [1.063673593648673e-10, 3.162927231499068e-10, 5.16047
9797103475e-8, 1.6555705695253664e-8]
apr = appxtrue(sol,test_sol)
@show sol[end]
@show apr.u[end]
```

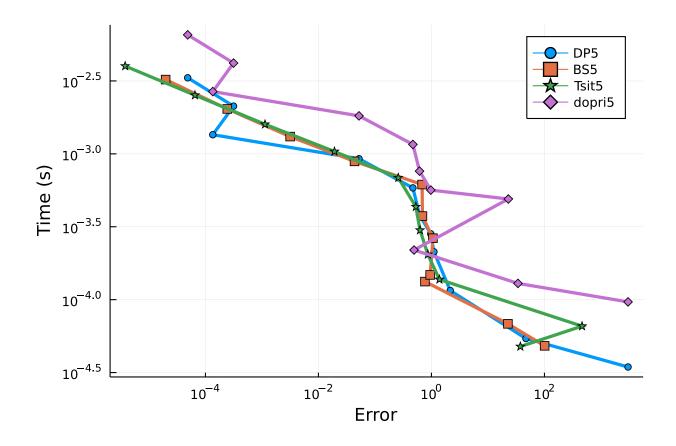
```
@show apr.errors
```

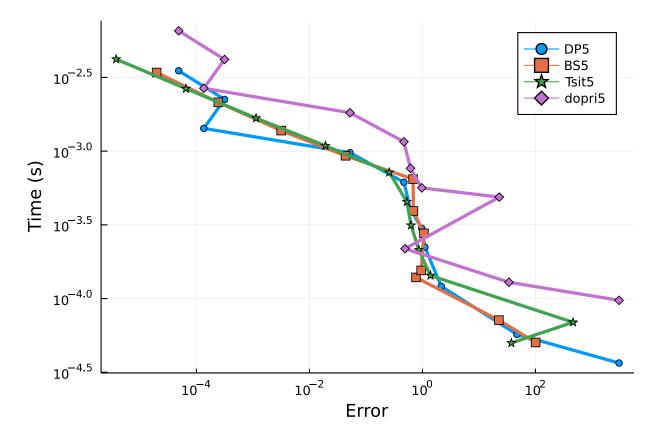
```
sol[end] = [0.9940000001063674, 3.162927231499068e-10, 5.160479797103475e-8
, -2.0015850898233767]
apr.u[end] = [0.9940000001063674, 3.162927231499068e-10, 5.160479797103475e
-8, -2.0015850898233767]
apr.errors = Dict(:final => 1.7145790937200795e-8)
Dict{Symbol, Float64} with 1 entry:
    :final => 1.71458e-8
```

This three-body problem is known to be a tough problem. Let's see how the algorithms fair at standard tolerances.

0.0.1 5th Order Runge-Kutta Methods

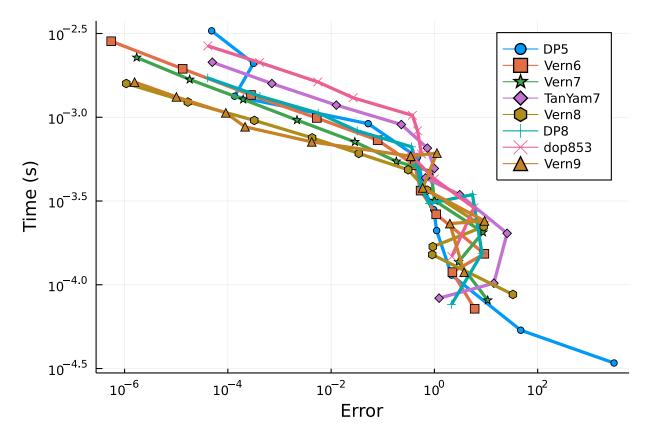




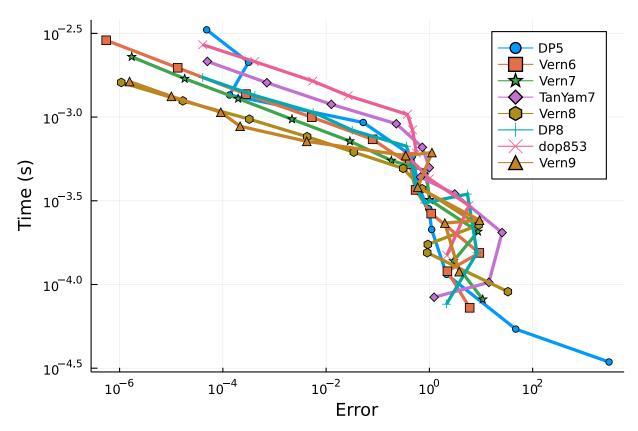


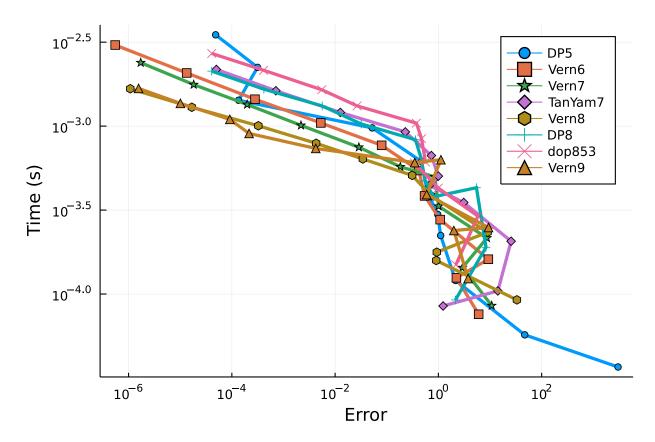
In these tests we see that most of the algorithms are close, with BS5 and DP5 showing much better than Tsit5. ode45 errors.

0.0.2 Higher Order Algorithms



 $\label{local_prob_abstols_reltols_setups;appxsol=test_sol,dense=} false, numruns=100, verbose=\\ false) \\ plot(wp)$

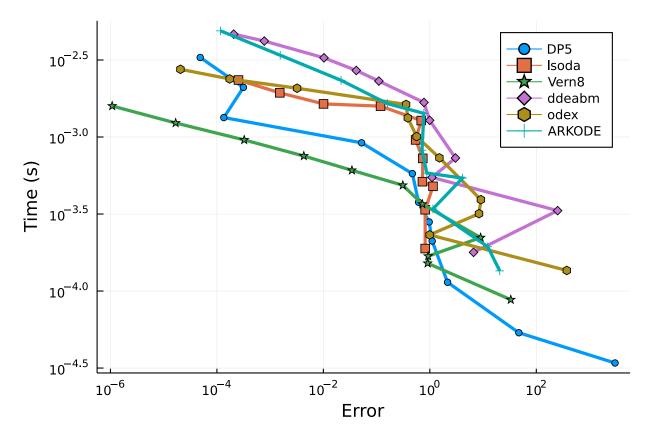




In this test we see Vern7 and Vern8 shine.

0.0.3 Other Algorithms

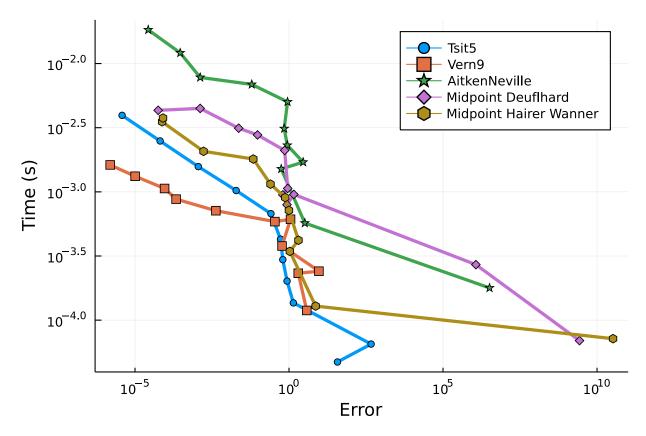
Once again we separate ODE.jl because it fails. We also separate Sundials' CVODE_Adams since it fails at high tolerances.

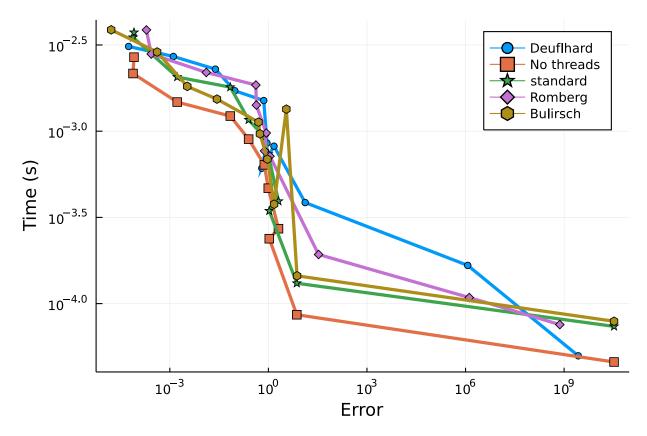


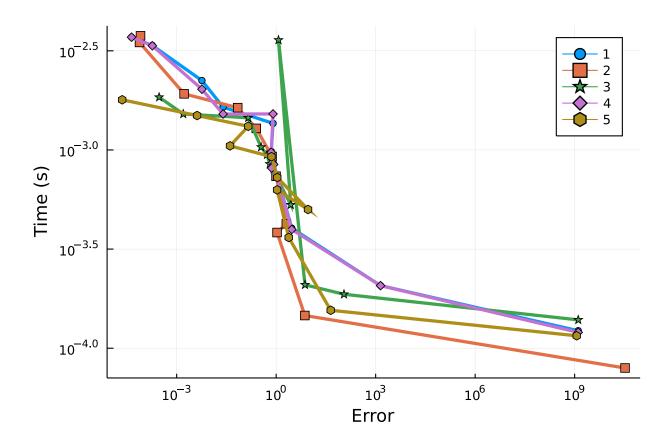
Again, on cheap function calculations the Adams methods are shown to not be efficient once the error is sufficiently small. Also, as seen in other places, the extrapolation methods do not fare as well as the Runge-Kutta methods.

0.1 Comparison with Non-RK methods

Now let's test Tsit5 and Vern9 against parallel extrapolation methods and an Adams-Bashforth-Moulton:







0.1.1 Conclusion

As in the other tests, the OrdinaryDiffEq.jl algorithms with the Verner Efficient methods are the most efficient solvers at stringent tolerances for most of the tests, while the order 5 methods do well at cruder tolerances. ODE.jl fails to run the test problems without erroring.

0.2 Appendix

These benchmarks are a part of the SciMLBenchmarks.jl repository, found at: https://github.com/SciML/For more information on high-performance scientific machine learning, check out the SciML Open Source Software Organization https://sciml.ai.

To locally run this benchmark, do the following commands:

```
using SciMLBenchmarks
SciMLBenchmarks.weave_file("benchmarks/NonStiffODE","ThreeBody_wpd.jmd")
```

Computer Information:

Julia Version 1.6.1

```
Platform Info:
       OS: Linux (x86_64-pc-linux-gnu)
       CPU: Intel(R) Core(TM) i7-9700K CPU @ 3.60GHz
       WORD SIZE: 64
       LIBM: libopenlibm
       LLVM: libLLVM-11.0.1 (ORCJIT, skylake)
        JULIA_DEPOT_PATH = /root/.cache/julia-buildkite-plugin/depots/5b300254-1738-4989-ae0a
        JULIA_NUM_THREADS = 3
Package Information:
                        Status \( \tau \rangle / \tau \rangl
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         [7f56f5a3] LSODA v0.7.0
        [c030b06c] ODE v2.13.0
         [54ca160b] ODEInterface v0.5.0
         [09606e27] ODEInterfaceDiffEq v3.10.0
         [1dea7af3] OrdinaryDiffEq v5.53.0
         [65888b18] ParameterizedFunctions v5.10.0
         [91a5bcdd] Plots v1.13.2
         [31c91b34] SciMLBenchmarks v0.1.0 `../..`
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And the full manifest:
                        Status \( \tau \rangle / \tau \rangl
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