

# Acceleration function benchmarks

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Solving the equations of motions for an N-body problem implies solving a (large) system of differential equations. In `DifferentialEquations.jl` these are represented through ODE or SDE problems. To build the problem we need a function that describe the equations. In the case of N-body problems, this function gives the accelerations for the particles in the system.

Here we will test the performance of several acceleration functions used in N-body simulations. The systems that will be used are not necessarily realistic as we are not solving the problem, we just time how fast is an acceleration function call.

```
using BenchmarkTools, NBodySimulator
using NBodySimulator: gather_bodies_initial_coordinates,
gather_accelerations_for_potentials,
gather_simultaneous_acceleration, gather_group_accelerations
using StaticArrays

const SUITE = BenchmarkGroup();

function acceleration(simulation)

    (u0, v0, n) = gather_bodies_initial_coordinates(simulation)

    acceleration_functions = gather_accelerations_for_potentials(simulation)
    simultaneous_acceleration = gather_simultaneous_acceleration(simulation)

    function soode_system!(dv, v, u, p, t)
        @inbounds for i = 1:n
            a = MVector{0.0, 0.0, 0.0}
            for acceleration! in acceleration_functions
                acceleration!(a, u, v, t, i);
            end
            dv[:, i] .= a
        end
        for acceleration! in simultaneous_acceleration
            acceleration!(dv, u, v, t);
        end
    end

    return soode_system!
end
```

```
acceleration (generic function with 1 method)
```

## 0.1 Gravitational potential

```
let SUITE=SUITE
  G = 6.67e-11 # m^3/kg/s^2
  N = 200 # number of bodies/particles
  m = 1.0 # mass of each of them
  v = 10.0 # mean velocity
  L = 20.0 # size of the cell side

  bodies = generate_bodies_in_cell_nodes(N, m, v, L)
  g_parameters = GravitationalParameters(G)
  system = PotentialNBodySystem(bodies, Dict(:gravitational => g_parameters))
  tspan = (0.0, 1.0)
  simulation = NBodySimulation(system, tspan)

  f = acceleration(simulation)
  u0, v0, n = gather_bodies_initial_coordinates(simulation)
  dv = zero(v0)

  b = @benchmarkable $f(dv, $v0, $u0, $g_parameters, 0.) setup=(dv=zero($v0)) evals=1

  SUITE["gravitational"] = b
end
```

```
Benchmark(evals=1, seconds=5.0, samples=10000)
```

## 0.2 Coulomb potential

```
let SUITE=SUITE
  n = 200
  bodies = ChargedParticle[]
  L = 20.0
  m = 1.0
  q = 1.0
  count = 1
  dL = L / (ceil(n^(1 / 3)) + 1)
  for x = dL / 2:dL:L, y = dL / 2:dL:L, z = dL / 2:dL:L
    if count > n
      break
    end
    r = SVector(x, y, z)
    v = SVector(.0, .0, .0)
    body = ChargedParticle(r, v, m, q)
    push!(bodies, body)
    count += 1
  end

  k = 9e9
  τ = 0.01 * dL / sqrt(2 * k * q * q / (dL * m))
  t1 = 0.0
  t2 = 1000 * τ
```

```

potential = ElectrostaticParameters(k, 0.45 * L)
system = PotentialNBodySystem(bodies, Dict(:electrostatic => potential))
pbc = CubicPeriodicBoundaryConditions(L)
simulation = NBodySimulation(system, (t1, t2), pbc)

f = acceleration(simulation)
u0, v0, n = gather_bodies_initial_coordinates(simulation)
dv = zero(v0)

b = @benchmarkable $f(dv, $v0, $u0, $potential, 0.) setup=(dv=zero($v0)) evals=1

SUITE["coulomb"] = b
end

```

```
Benchmark(evals=1, seconds=5.0, samples=10000)
```

### 0.3 Magnetic dipole potential

```

let SUITE=SUITE
n = 200
bodies = MagneticParticle[]
L = 20.0
m = 1.0
count = 1
dL = L / (ceil(n^(1 / 3)) + 1)
for x = dL / 2:dL:L, y = dL / 2:dL:L, z = dL / 2:dL:L
    if count > n
        break
    end
    r = SVector(x, y, z)
    v = SVector(.0, .0, .0)
    mm = rand(SVector{3})
    body = MagneticParticle(r, v, m, mm)
    push!(bodies, body)
    count += 1
end

μ_4π = 1e-7
t1 = 0.0 # s
t2 = 1.0 # s
τ = (t2 - t1) / 100

parameters = MagnetostaticParameters(μ_4π)
system = PotentialNBodySystem(bodies, Dict(:magnetic => parameters))
simulation = NBodySimulation(system, (t1, t2))

f = acceleration(simulation)
u0, v0, n = gather_bodies_initial_coordinates(simulation)
dv = zero(v0)

b = @benchmarkable $f(dv, $v0, $u0, $parameters, 0.) setup=(dv=zero($v0)) evals=1

SUITE["magnetic_dipole"] = b
end

```

```
Benchmark(evals=1, seconds=5.0, samples=10000)
```

## 0.4 Lennard Jones potential

```
let SUITE=SUITE
  T = 120.0 # K
  T0 = 90.0 # K
  kb = 8.3144598e-3 # kJ/(K*mol)
   $\epsilon$  = T * kb
   $\sigma$  = 0.34 # nm
   $\rho$  = 1374/1.6747 # Da/nm3
  N = 200
  m = 39.95 # Da = 216 # number of bodies/particles
  L = (m*N/ $\rho$ )^(1/3) # 10.229 $\sigma$ 
  R = 0.5*L
  v_dev = sqrt(kb * T / m)
  bodies = generate_bodies_in_cell_nodes(N, m, v_dev, L)

   $\tau$  = 0.5e-3 # ps or 1e-12 s
  t1 = 0.0
  t2 = 2000 $\tau$ 

  lj_parameters = LennardJonesParameters( $\epsilon$ ,  $\sigma$ , R)
  lj_system = PotentialNBodySystem(bodies, Dict{:lennard_jones => lj_parameters});

  pbc = CubicPeriodicBoundaryConditions(L)
  simulation = NBodySimulation(lj_system, (t1, t2), pbc, kb)

  f = acceleration(simulation)
  u0, v0, n = gather_bodies_initial_coordinates(simulation)
  dv = zero(v0)

  b = @benchmarkable $f(dv, $v0, $u0, $lj_parameters, 0.) setup=(dv=zero($v0)) evals=1

  SUITE["lennard_jones"] = b
end
```

```
Benchmark(evals=1, seconds=5.0, samples=10000)
```

## 0.5 WaterSPCFw model

```
function acceleration(simulation::NBodySimulation{<:WaterSPCFw})

  (u0, v0, n) = gather_bodies_initial_coordinates(simulation)

  (o_accelerations, h_accelerations) = gather_accelerations_for_potentials(simulation)
  group_accelerations = gather_group_accelerations(simulation)
  simultaneous_acceleration = gather_simultaneous_acceleration(simulation)

  function soode_system!(dv, v, u, p, t)
    @inbounds for i = 1:n
```

```

        a = MVector(0.0, 0.0, 0.0)
        for acceleration! in o_accelerations
            acceleration!(a, u, v, t, 3 * (i - 1) + 1);
        end
        dv[:, 3 * (i - 1) + 1] .= a
    end
    @inbounds for i in 1:n, j in (2, 3)
        a = MVector(0.0, 0.0, 0.0)
        for acceleration! in h_accelerations
            acceleration!(a, u, v, t, 3 * (i - 1) + j);
        end
        dv[:, 3 * (i - 1) + j] .= a
    end
    @inbounds for i = 1:n
        for acceleration! in group_accelerations
            acceleration!(dv, u, v, t, i);
        end
    end
    for acceleration! in simultaneous_acceleration
        acceleration!(dv, u, v, t);
    end
end

return soode_system!
end

let SUITE=SUITE
T = 370 # K
T0 = 275 # K
kb = 8.3144598e-3 # kJ/(K*mol)
ϵ00 = 0.1554253*4.184 # kJ
σ00 = 0.3165492 # nm
ρ = 997/1.6747 # Da/nm3
mO = 15.999 # Da
mH = 1.00794 # Da
mH2O = mO+2*mH
N = 200
L = (mH2O*N/ρ)^(1/3)
R = 0.9 # ~3*σ00
Rel = 0.49*L
v_dev = sqrt(kb * T / mH2O)
τ = 0.5e-3 # ps
t1 = 0τ
t2 = 5τ # ps
k_bond = 1059.162*4.184*1e2 # kJ/(mol*nm2)
k_angle = 75.90*4.184 # kJ/(mol*rad2)
rOH = 0.1012 # nm
∠HOH = 113.24*pi/180 # rad
qH = 0.41
qO = -0.82
k = 138.935458 #
bodies = generate_bodies_in_cell_nodes(N, mH2O, v_dev, L)
jl_parameters = LennardJonesParameters(ϵ00, σ00, R)
e_parameters = ElectrostaticParameters(k, Rel)
spc_parameters = SPCFwParameters(rOH, ∠HOH, k_bond, k_angle)
pbc = CubicPeriodicBoundaryConditions(L)
water = WaterSPCFw(bodies, mH, mO, qH, qO, jl_parameters, e_parameters,
spc_parameters);
simulation = NBodySimulation(water, (t1, t2), pbc, kb);

```

```

f = acceleration(simulation)
u0, v0, n = gather_bodies_initial_coordinates(simulation)
dv = zero(v0)

b = @benchmarkable $f(dv, $v0, $u0, $spc_parameters, 0.) setup=(dv=zero($v0)) evals=1

SUITE["water_spcfw"] = b
end

```

```
Benchmark(evals=1, seconds=5.0, samples=10000)
```

Here are the results of the benchmarks

```

r = run(SUITE)

minimum(r)

```

```

5-element BenchmarkTools.BenchmarkGroup:
 tags: []
 "gravitational" => TrialEstimate(4.838 ms)
 "coulomb" => TrialEstimate(719.181 μs)
 "lennard_jones" => TrialEstimate(529.330 μs)
 "water_spcfw" => TrialEstimate(9.000 ms)
 "magnetic_dipole" => TrialEstimate(28.116 ms)

```

and

```
memory(r)
```

```

5-element BenchmarkTools.BenchmarkGroup:
 tags: []
 "gravitational" => 7664000
 "coulomb" => 9600
 "lennard_jones" => 9600
 "water_spcfw" => 124912
 "magnetic_dipole" => 25555200

```