BAYESIAN STATISTICS - LECTURE 9

LECTURE 9: HMC, STAN, VARIATIONAL.

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LECTURE OVERVIEW

- **Hamiltonian Monte Carlo**
- **Stan**
- Variational Bayes

HAMILTONIAN MONTE CARLO

- Assume $\theta = (\theta_1, ..., \theta_p)$. If p is large, then most of the mass of $p(\theta|\mathbf{y})$ is usually located on some subregion in \mathbb{R}^p with complicated geometry.
- lacksquare MH: hard to find good proposal distribution $q\left(\cdot| heta^{(i-1)}
 ight)$.
- MH: have to use very small step sizes otherwise too many rejections.
- Hamiltonian Monte Carlo (HMC): distant proposals with high acceptance probabilities.
- HMC adds an auxiliary momentum parameter $\phi = (\phi_1, \dots, \phi_p)$ and samples from $p(\theta, \phi | \mathbf{y}) = p(\theta | \mathbf{y}) p(\phi)$.

HAMILTONIAN MONTE CARLO

- Physics: **Hamiltonian** system $H(\theta, \phi) = U(\theta) + K(\phi)$, where U is the **potential energy** and K is the **kinetic energy**.
- **Hamiltonian Dynamics**

$$\frac{d\theta_{i}}{dt} = \frac{\partial H}{\partial \phi_{i}} = \frac{\partial K}{\partial \phi_{i}},$$
$$\frac{d\phi_{i}}{dt} = -\frac{\partial H}{\partial \theta_{i}} = -\frac{\partial U}{\partial \theta_{i}}$$

- Think: Hockey puck sliding over a friction-less surface: illustration.
- Use $U(\theta) = -\log[p(\theta)p(\mathbf{y}|\theta)]$.
- Use $\phi \sim N\left(\mathbf{0},\mathbf{M}\right)$ and $K\left(\phi\right) = -\log\left[p\left(\phi\right)\right] = \frac{1}{2}\phi^{\mathsf{T}}\mathbf{M}^{-1}\phi + \mathrm{const}$, where \mathbf{M} is the mass matrix (often diagonal).
- If we could propose θ in continuous time (spoiler: we can't), the acceptance probability would be one.

HAMILTONIAN MONTE CARLO

Hamiltonian Dynamics

$$\begin{split} \frac{d\theta_{i}}{dt} &= \left[\mathbf{M}^{-1} \boldsymbol{\phi}\right]_{i}, \\ \frac{d\phi_{i}}{dt} &= \frac{\partial \log p\left(\boldsymbol{\theta} | \mathbf{y}\right)}{\partial \theta_{i}} \end{split}$$

which can be simulated using the leapfrog algorithm

$$\begin{split} \phi_{i}\left(t+\frac{\varepsilon}{2}\right) &= \phi_{i}\left(t\right) - \frac{\varepsilon}{2} \frac{\partial \log p\left(\theta(t)|\mathbf{y}\right)}{\partial \theta_{i}}, \\ \theta\left(t+\varepsilon\right) &= \theta\left(t\right) + \varepsilon \mathbf{M}^{-1}\phi(t), \\ \phi_{i}\left(t+\varepsilon\right) &= \phi_{i}\left(t+\frac{\varepsilon}{2}\right) - \frac{\varepsilon}{2} \frac{\partial \log p\left(\theta(t)|\mathbf{y}\right)}{\partial \theta_{i}}, \end{split}$$

where ε is the step size.

■ Discretization \Rightarrow acceptance probability drops with ε .

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THE HAMILTONIAN MONTE CARLO ALGORITHM

- Initialize $\theta^{(0)}$ and iterate for i = 1, 2, ...
 - 1. Sample the starting **momentum** $\phi_{S} \sim N\left(\mathsf{O}, \mathbf{M}\right)$
 - 2. Simulate new values for (θ_p, ϕ_p) by iterating the **leapfrog** algorithm L times, starting in $(\theta^{(i-1)}, \phi_s)$.
 - 3. Compute the acceptance probability

$$\alpha = \min\left(1, \frac{p(\mathbf{y}|\theta_p)p(\theta_p)}{p(\mathbf{y}|\theta^{(i-1)})p(\theta^{(i-1)})} \frac{p(\phi_p)}{p(\phi_s)}\right)$$

- 4. With probability α set $\theta^{(i)} = \theta_p$ and $\theta^{(i)} = \theta^{(i-1)}$ otherwise.
- Tuning parameters: 1. stepsize ε , 2. number of leapfrog iterations L and 3. mass matrix M. No U-turn.

STAN

- **Stan** is a probabilistic programming language based on HMC.
- Allows for Bayesian inference in many models with automatic implementation of the MCMC sampler.
- Named after Stanislaw Ulam (1909-1984), co-inventor of the Monte Carlo algorithm.
- Written in C++ but can be run from R using the package rstan



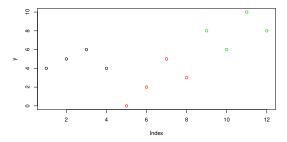
Stan logo



Stanislaw Ulam

STAN - TOY EXAMPLE: THREE PLANTS

■ Three plants were observed for four months, measuring the number of flowers



STAN MODEL 1: IID NORMAL

$$y_i \stackrel{iid}{\sim} N(\mu, \sigma^2)$$

```
library(rstan)
y = c(4,5,6,4,0,2,5,3,8,6,10,8)
N = length(v)
StanModel = '
data {
  int<lower=0> N; // Number of observations
  int<lower=0> v[N]: // Number of flowers
parameters {
  real mu:
  real<lower=o> sigma2;
model {
  mu ~ normal(0,100); // Normal with mean 0, st.dev. 100
  sigma2 ~ scaled_inv_chi_square(1,2); // Scaled-inv-chi2 with nu 1, sigma 2
  for(i in 1:N)
    y[i] ~ normal(mu,sqrt(sigma2));
```

STAN MODEL 2: MULTILEVEL NORMAL

$$y_{i,p} \sim N(\mu_p, \sigma_p^2), \quad \mu_p \sim N(\mu, \sigma^2)$$

```
StanModel = '
data {
 int<lower=0> N; // Number of observations
 int<lower=0> v[N]; // Number of flowers
 int<lower=0> P: // Number of plants
transformed data {
 int<lower=0> M: // Number of months
 M = N / P:
parameters {
 real mu:
 real<lower=o> sigma2;
 real mup[P];
  real sigmap2[P];
model {
 mu ~ normal(0.100): // Normal with mean o. st.dev. 100
 sigma2 ~ scaled inv chi square(1,2); // Scaled-inv-chi2 with nu 1, sigma 2
 for(p in 1:P){
   mup[p] ~ normal(mu.sgrt(sigma2));
   for(m in 1:M)
      y[M*(p-1)+m] ~ normal(mup[p],sqrt(sigmap2[p]));
```

STAN MODEL 3: MULTILEVEL POISSON

$y_{i,p} \sim Poisson(\mu_p)$, $\mu_p \sim logN(\mu, \sigma^2)$

```
StanModel = '
data {
 int<lower=0> N: // Number of observations
 int<lower=0> v[N]; // Number of flowers
 int<lower=0> P; // Number of plants
transformed data {
 int<lower=0> M; // Number of months
 M = N / P:
parameters {
 real mu:
 real<lower=o> sigma2:
 real mup[P]:
model {
 mu ~ normal(0,100); // Normal with mean 0, st.dev. 100
 sigma2 ~ scaled inv chi square(1,2); // Scaled-inv-chi2 with nu 1, sigma 2
 for(p in 1:P){
   mup[p] ~ lognormal(mu,sqrt(sigma2)); // Log-normal
   for(m in 1:M)
      v[M*(p-1)+m] ~ poisson(mup[p]): // Poisson
```

STAN: FIT MODEL AND ANALYZE OUTPUT

```
data = list(N=N, v=v, P=P)
burnin = 1000
niter = 2000
fit = stan(model code=StanModel.data=data.
           warmup=burnin,iter=niter,chains=4)
# Print the fitted model
print(fit, digits summary=3)
# Extract posterior samples
postDraws <- extract(fit)
# Do traceplots of the first chain
par(mfrow = c(1,1))
plot(postDraws$mu[1:(niter-burnin)],type="l",ylab="mu",main="Traceplot")
# Do automatic traceplots of all chains
traceplot(fit)
# Bivariate posterior plots
pairs(fit)
```

STAN - USEFUL LINKS

- Getting started with RStan
- RStan vignette
- Stan Modeling Language User's Guide and Reference Manual
- Stan Case Studies

VARIATIONAL INFERENCE

- Let $\theta = (\theta_1, ..., \theta_p)$. Approximate the posterior $p(\theta|y)$ with a (simpler) distribution $q(\theta)$.
- Before: **Normal approximation** from optimation: $q(\theta) = N \left[\tilde{\theta}, J_{\mathbf{v}}^{-1}(\tilde{\theta}) \right].$
- Mean field Variational Bayes (VB)

$$q(\theta) = \prod_{i=1}^{p} q_i(\theta_i)$$

■ Find the $q(\theta)$ that **minimizes the Kullback-Leibler distance** between the true posterior p and the approximation q:

$$\mathit{KL}(q,p) = \int q(\theta) \ln \frac{q(\theta)}{p(\theta|y)} d\theta = \mathit{E}_q \left[\ln \frac{q(\theta)}{p(\theta|y)} \right].$$

MEAN FIELD APPROXIMATION

■ Mean field VB is based on factorized approximation:

$$q(\theta) = \prod_{i=1}^{p} q_i(\theta_i)$$

- No specific functional forms are assumed for the $q_i(\theta)$.
- Optimal densities can be shown to satisfy:

$$q_i(\theta) \propto \exp\left(E_{-\theta_i} \ln p(\mathbf{y}, \theta)\right)$$

where $E_{-\theta_i}(\cdot)$ is the expectation with respect to $\prod_{i\neq j}q_j(\theta_j)$.

■ **Structured mean field approximation**. Group subset of parameters in tractable blocks. Similar to Gibbs sampling.

MEAN FIELD APPROXIMATION - ALGORITHM

- Initialize: $q_2^*(\theta_2), ..., q_M^*(\theta_p)$
- Repeat until convergence:

•
$$q_1^*(\theta_1) \leftarrow \frac{\exp[E_{-\theta_1} \ln p(\mathbf{y}, \theta)]}{\int \exp[E_{-\theta_1} \ln p(\mathbf{y}, \theta)] d\theta_1}$$

• :

• $q_p^*(\theta_p) \leftarrow \frac{\exp\left[\mathbf{E}_{-\theta_p} \ln p(\mathbf{y}, \theta)\right]}{\int \exp\left[\mathbf{E}_{-\theta_p} \ln p(\mathbf{y}, \theta)\right] d\theta_p}$

- Note: no assumptions about parametric form of the $q_i(\theta)$.
- Optimal $q_i(\theta)$ often **turn out** to be parametric (normal etc).
- Just update hyperparameters in the optimal densities.

MEAN FIELD APPROXIMATION - NORMAL MODEL

- Model: $X_i | \theta, \sigma^2 \stackrel{iid}{\sim} N(\theta, \sigma^2)$.
- Prior: $\theta \sim N(\mu_0, \tau_0^2)$ independent of $\sigma^2 \sim Inv \chi^2(\nu_0, \sigma_0^2)$.
- Mean-field approximation: $q(\theta, \sigma^2) = q_{\theta}(\theta) \cdot q_{\sigma^2}(\sigma^2)$.
- Optimal densities

$$\begin{split} q_{\theta}^*(\theta) &\propto \exp\left[E_{q(\sigma^2)} \ln p(\theta, \sigma^2, \mathbf{x})\right] \\ q_{\sigma^2}^*(\sigma^2) &\propto \exp\left[E_{q(\theta)} \ln p(\theta, \sigma^2, \mathbf{x})\right] \end{split}$$

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NORMAL MODEL - VB ALGORITHM

■ Variational density for σ^2

$$\sigma^2 \sim \text{Inv} - \chi^2 \left(\tilde{v}_n, \tilde{\sigma}_n^2 \right)$$

where
$$\tilde{\nu}_n = \nu_0 + n$$
 and $\tilde{\sigma}_n = \frac{\nu_0 \sigma_0^2 + \sum_{i=1}^n (x_i - \tilde{\mu}_n)^2 + n \cdot \tilde{\tau}_n^2}{\nu_0 + n}$

■ Variational density for θ

$$\theta \sim N\left(\tilde{\mu}_n, \tilde{\tau}_n^2\right)$$

where

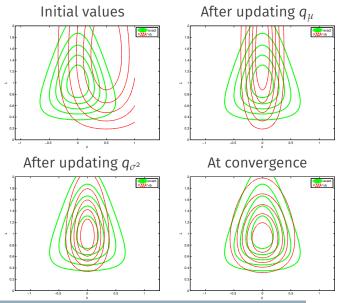
$$\tilde{\tau}_n^2 = \frac{1}{\frac{n}{\tilde{\sigma}_n^2} + \frac{1}{\tau_0^2}}$$

$$\tilde{\mu}_{\mathsf{n}} = \tilde{\mathsf{w}}\bar{\mathsf{x}} + (\mathsf{1} - \tilde{\mathsf{w}})\mu_{\mathsf{o}},$$

where

$$\tilde{W} = \frac{\frac{n}{\tilde{\sigma}_n^2}}{\frac{n}{\tilde{\sigma}_n^2} + \frac{1}{\tau_0^2}}$$

Normal example from Murphy ($\lambda = 1/\sigma^2$)



PROBIT REGRESSION

■ Model:

$$\Pr\left(y_i = 1 | \mathbf{x}_i\right) = \Phi(\mathbf{x}_i^\mathsf{T} \boldsymbol{\beta})$$

- **Prior**: $\beta \sim N(0, \Sigma_{\beta})$. For example: $\Sigma_{\beta} = \tau^2 I$.
- Latent variable formulation with $u = (u_1, ..., u_n)'$

$$\mathbf{u}|\beta \sim N(\mathbf{X}\beta,\mathbf{1})$$

and

$$y_i = \begin{cases} 0 & \text{if } u_i \le 0 \\ 1 & \text{if } u_i > 0 \end{cases}$$

■ Factorized variational approximation

$$q(\mathbf{u}, \beta) = q_{\mathbf{u}}(\mathbf{u})q_{\beta}(\beta)$$

VB FOR PROBIT REGRESSION

■ VB posterior

$$eta \sim N\left(ilde{\mu}_{eta}, \left(extbf{X}^{\mathsf{T}} extbf{X} + \Sigma_{eta}^{-1}
ight)^{-1}
ight)$$

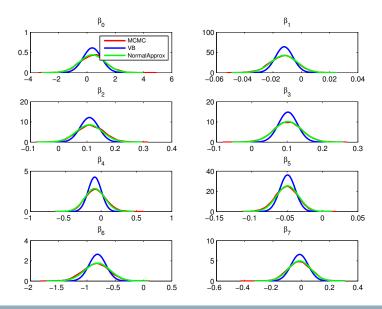
where

$$\tilde{\mu}_{\beta} = \left(\mathbf{X}^{\mathsf{T}}\mathbf{X} + \boldsymbol{\Sigma}_{\beta}^{-1}\right)^{-1}\mathbf{X}^{\mathsf{T}}\tilde{\boldsymbol{\mu}}_{\mathbf{u}}$$

and

$$\tilde{\mu}_{\mathbf{u}} = \mathbf{X} \tilde{\boldsymbol{\mu}}_{\boldsymbol{\beta}} + \frac{\phi \left(\mathbf{X} \tilde{\boldsymbol{\mu}}_{\boldsymbol{\beta}} \right)}{\Phi \left(\mathbf{X} \tilde{\boldsymbol{\mu}}_{\boldsymbol{\beta}} \right)^{\mathbf{y}} \left[\Phi \left(\mathbf{X} \tilde{\boldsymbol{\mu}}_{\boldsymbol{\beta}} \right) - \mathbf{1}_{n} \right]^{\mathbf{1}_{n} - \mathbf{y}}}.$$

PROBIT EXAMPLE (N=200 OBSERVATIONS)



PROBIT EXAMPLE

