Gradient Operator (∇)

In Cartesian Coordinate

$$\vec{\nabla} = \left(\frac{\partial}{\partial x}\right)\hat{i} + \left(\frac{\partial}{\partial y}\right)\hat{j} + \left(\frac{\partial}{\partial z}\right)\hat{k}$$

Find out gradient of the following function

$$T(x,y) = -(\cos^2 x + \cos^2 y)^2$$

$$T=T(x,y,z)$$

$$dT = \left(\frac{\partial T}{\partial x}\right) dx + \left(\frac{\partial T}{\partial y}\right) dy + \left(\frac{\partial T}{\partial z}\right) dz.$$

$$dT = \left(\frac{\partial T}{\partial x}\hat{\mathbf{x}} + \frac{\partial T}{\partial y}\hat{\mathbf{y}} + \frac{\partial T}{\partial z}\hat{\mathbf{z}}\right) \cdot (dx\,\hat{\mathbf{x}} + dy\,\hat{\mathbf{y}} + dz\,\hat{\mathbf{z}})$$
$$= (\nabla T) \cdot (d\mathbf{l}),$$

$$\nabla T \equiv \frac{\partial T}{\partial x}\hat{\mathbf{x}} + \frac{\partial T}{\partial y}\hat{\mathbf{y}} + \frac{\partial T}{\partial z}\hat{\mathbf{z}}$$

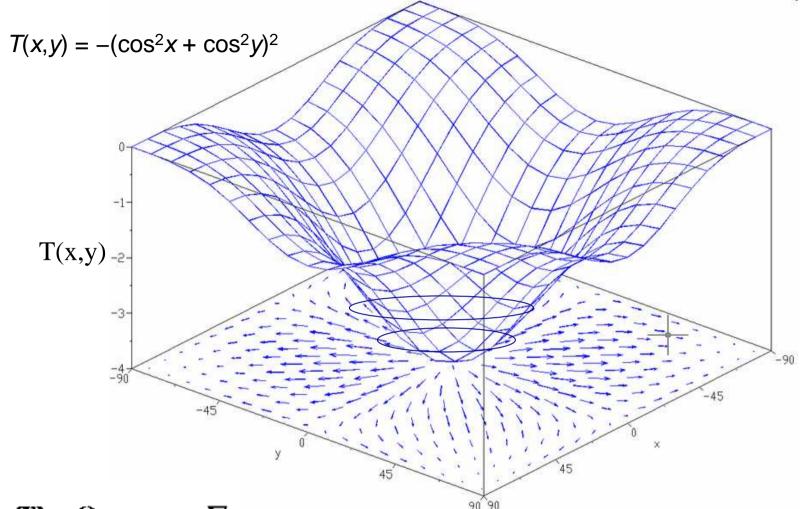
Geometrical Interpretation of the Gradient

$$dT = \nabla T \cdot d\mathbf{l} = |\nabla T| |d\mathbf{l}| \cos \theta$$

when
$$\theta = 0$$
 (for then $\cos \theta = 1$)

The gradient ∇T points in the direction of maximum increase of the function T.

The magnitude $|\nabla T|$ gives the slope (rate of increase) along this maximal direction.



The Operator ∇

$$\nabla = \hat{\mathbf{x}} \frac{\partial}{\partial x} + \hat{\mathbf{y}} \frac{\partial}{\partial y} + \hat{\mathbf{z}} \frac{\partial}{\partial z}.$$

http://en.wikipedia.org/wiki/Gradient

$$\nabla T = \left(\hat{\mathbf{x}} \frac{\partial}{\partial x} + \hat{\mathbf{y}} \frac{\partial}{\partial y} + \hat{\mathbf{z}} \frac{\partial}{\partial z}\right) T$$
Vector Field

Scalar Field

The Divergence

$$\nabla \cdot \mathbf{v} = \left(\hat{\mathbf{x}} \frac{\partial}{\partial x} + \hat{\mathbf{y}} \frac{\partial}{\partial y} + \hat{\mathbf{z}} \frac{\partial}{\partial z}\right) \cdot (v_x \hat{\mathbf{x}} + v_y \hat{\mathbf{y}} + v_z \hat{\mathbf{z}})$$

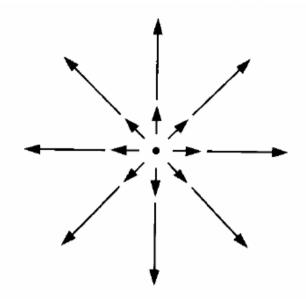
$$= \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \qquad \nabla \cdot \vec{V} \neq \vec{V} \cdot \nabla$$

(a)
$$\mathbf{v}_a = x^2 \,\hat{\mathbf{x}} + 3xz^2 \,\hat{\mathbf{y}} - 2xz \,\hat{\mathbf{z}}$$
.

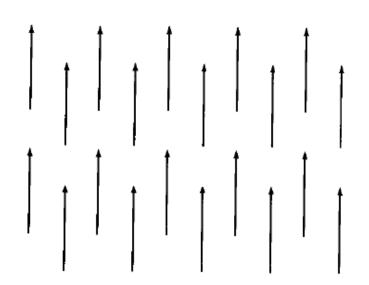
(b)
$$\mathbf{v}_b = xy\,\hat{\mathbf{x}} + 2yz\,\hat{\mathbf{y}} + 3zx\,\hat{\mathbf{z}}.$$

(c)
$$\mathbf{v}_c = y^2 \,\hat{\mathbf{x}} + (2xy + z^2) \,\hat{\mathbf{y}} + 2yz \,\hat{\mathbf{z}}.$$

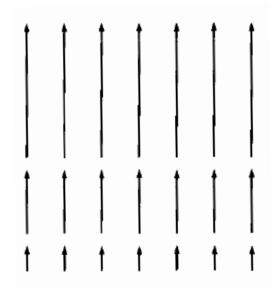
$$\mathbf{v}_a = \mathbf{r} = x\,\hat{\mathbf{x}} + y\,\hat{\mathbf{y}} + z\,\hat{\mathbf{z}}$$



$$\mathbf{v}_b = \hat{\mathbf{z}}$$

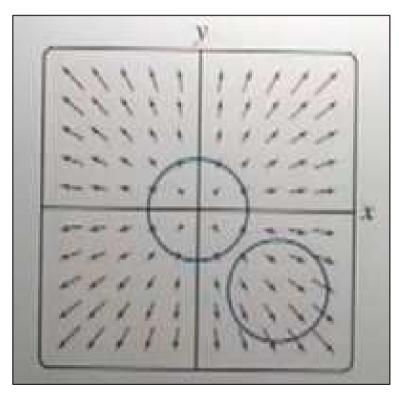


$$\mathbf{v}_c = z\,\hat{\mathbf{z}}$$



In many cases, the divergence of a vector function at point P may be predicted by considering a closed surface surrounding P and analyzing the flow over the boundary, keeping in mind that at P:

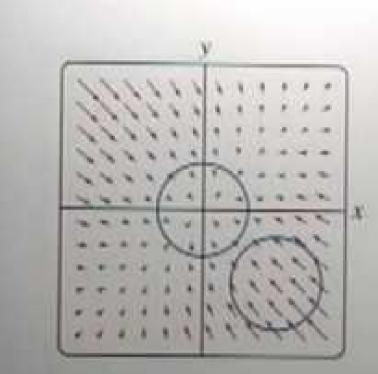
$$\nabla \cdot \vec{F} = \text{outflow} - \text{inflow}$$



$$\vec{V} = x\hat{i} + y\hat{j}$$

$$\vec{\nabla} \cdot \vec{V} = 2$$

In 3-D, divergence is a measure of Change of flux per unit volume

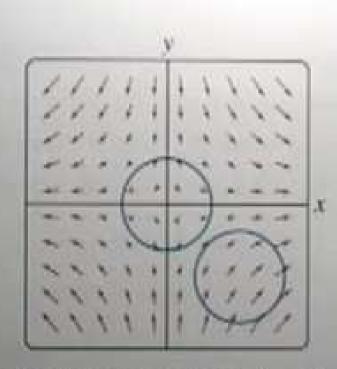


(B) The force field

F = (y - 2x, x - 2y)

with div(F) = -4.

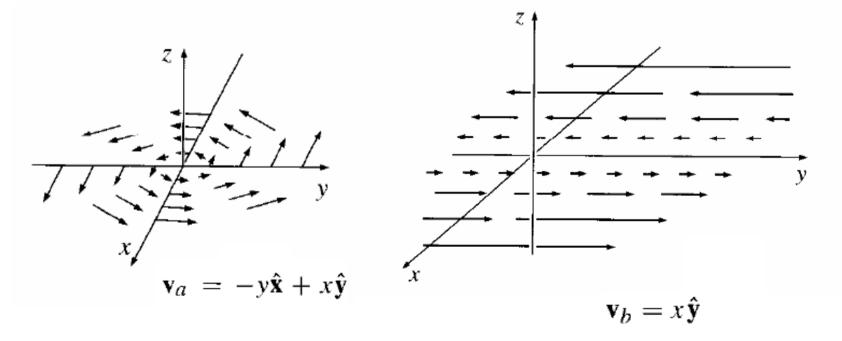
There is a net inflow into every circle.



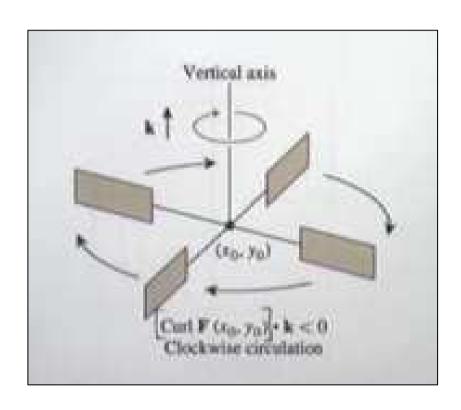
(C) The force field $F = \langle x, -y \rangle$ with div(F) = 0. The flux through every circle is zero.

The Curl

$$\nabla \times \mathbf{v} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}$$
$$= \hat{\mathbf{x}} \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) + \hat{\mathbf{y}} \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) + \hat{\mathbf{z}} \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right)$$

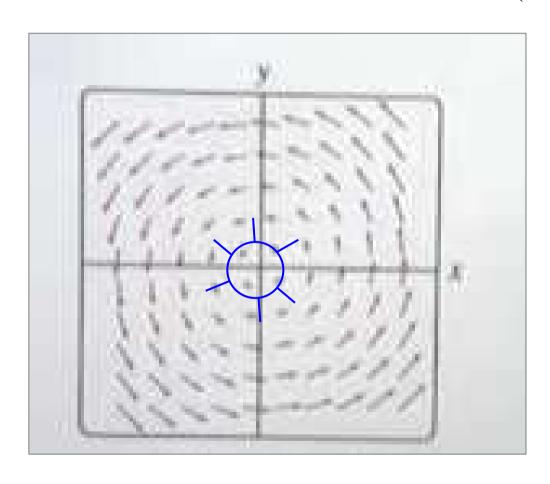


Paddle wheel analysis

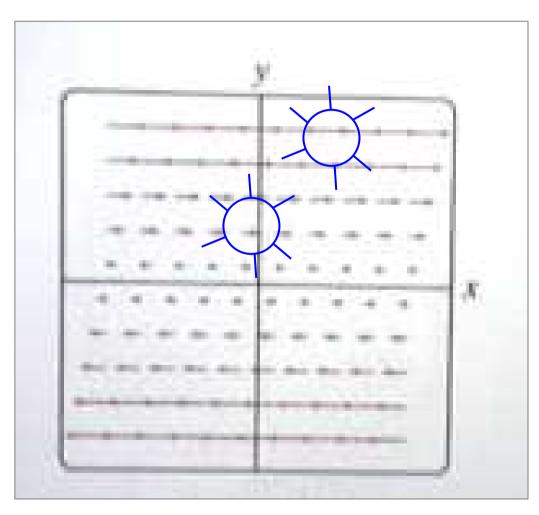


$$[\nabla \times \vec{F}(x_0, y_0)] \cdot \hat{k} < 0$$

$$\vec{F}(x,y) = -y\hat{i} + x\hat{j} \qquad (\vec{\nabla} \times \vec{F}) \cdot \hat{k} = 2$$



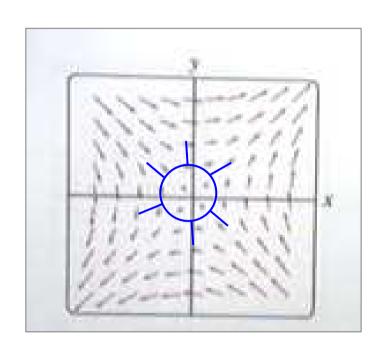
$$\vec{F}(x,y) = y\hat{i}$$

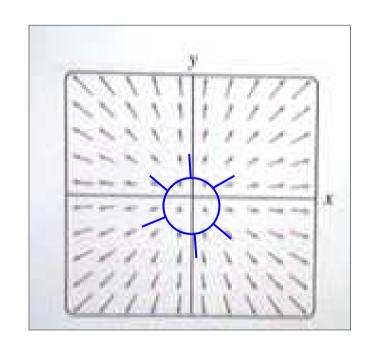


$$(\nabla \times \vec{F}) \cdot \hat{k} = -1$$

$$\vec{F}(x,y) = y\hat{i} + x\hat{j}$$

$$\vec{F}(x,y) = x\hat{i} + y\hat{j}$$





$$\nabla \times \vec{F} = 0$$

Summary

Gradient of a Scalar Field

$$\nabla T = \left(\hat{\mathbf{x}} \frac{\partial}{\partial x} + \hat{\mathbf{y}} \frac{\partial}{\partial y} + \hat{\mathbf{z}} \frac{\partial}{\partial z}\right) T$$
Scalar Field

Vector Field

Divergence of a Vector Field — Measure of Change of flux per unit volume

Curl of a Vector Field ———— Measure of degree of rotation of the field

Identities related to Gradient

$$\nabla (f + g) = \nabla f + \nabla g, \qquad \nabla \cdot (\mathbf{A} + \mathbf{B}) = (\nabla \cdot \mathbf{A}) + (\nabla \cdot \mathbf{B}),$$

$$\nabla \times (\mathbf{A} + \mathbf{B}) = (\nabla \times \mathbf{A}) + (\nabla \times \mathbf{B}),$$

$$\nabla(kf) = k\nabla f, \quad \nabla \cdot (k\mathbf{A}) = k(\nabla \cdot \mathbf{A}), \quad \nabla \times (k\mathbf{A}) = k(\nabla \times \mathbf{A}),$$

fg (product of two scalar functions),

 $\mathbf{A} \cdot \mathbf{B}$ (dot product of two vector functions)

$$\nabla(fg) = f\nabla g + g\nabla f$$

$$\nabla (\mathbf{A} \cdot \mathbf{B}) = \mathbf{A} \times (\nabla \times \mathbf{B}) + \mathbf{B} \times (\nabla \times \mathbf{A}) + (\mathbf{A} \cdot \nabla)\mathbf{B} + (\mathbf{B} \cdot \nabla)\mathbf{A}$$

Identities related to Divergence & Curl

$$f$$
 A (scalar times vector),
A × B (cross product of two vectors)

$$\nabla \cdot (f\mathbf{A}) = f(\nabla \cdot \mathbf{A}) + \mathbf{A} \cdot (\nabla f)$$

$$\nabla \cdot (\mathbf{A} \times \mathbf{B}) = \mathbf{B} \cdot (\nabla \times \mathbf{A}) - \mathbf{A} \cdot (\nabla \times \mathbf{B})$$

$$\nabla \times (f\mathbf{A}) = f(\nabla \times \mathbf{A}) - \mathbf{A} \times (\nabla f)$$

$$\nabla \times (\mathbf{A} \times \mathbf{B}) = (\mathbf{B} \cdot \nabla)\mathbf{A} - (\mathbf{A} \cdot \nabla)\mathbf{B} + \mathbf{A}(\nabla \cdot \mathbf{B}) - \mathbf{B}(\nabla \cdot \mathbf{A})$$

Second Derivatives

 ∇T is a vector

- (1) Divergence of gradient: $\nabla \cdot (\nabla T)$
- (2) Curl of gradient: $\nabla \times (\nabla T)$.

 $\nabla \cdot \mathbf{v}$ is a *scalar* Gradient of divergence: $\nabla (\nabla \cdot \mathbf{v})$

 $\nabla \times \mathbf{v}$ is a *vector*. Divergence of curl: $\nabla \cdot (\nabla \times \mathbf{v})$. Curl of curl: $\nabla \times (\nabla \times \mathbf{v})$.

 $\nabla \cdot (\nabla T) = \left(\hat{\mathbf{x}} \frac{\partial}{\partial x} + \hat{\mathbf{y}} \frac{\partial}{\partial y} + \hat{\mathbf{z}} \frac{\partial}{\partial z}\right) \cdot \left(\frac{\partial T}{\partial x} \hat{\mathbf{x}} + \frac{\partial T}{\partial y} \hat{\mathbf{y}} + \frac{\partial T}{\partial z} \hat{\mathbf{z}}\right)$

$$= \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2}$$

$$= \nabla^2 T$$
Laplacian oparator

Laplacian of a vector,

$$\nabla^2 \mathbf{v} \equiv (\nabla^2 v_x) \hat{\mathbf{x}} + (\nabla^2 v_y) \hat{\mathbf{y}} + (\nabla^2 v_z) \hat{\mathbf{z}}$$

The curl of a gradient is always zero.

$$\nabla \times (\nabla T) = 0$$

$$\nabla^2 \mathbf{v} = (\nabla \cdot \nabla) \mathbf{v} \neq \nabla (\nabla \cdot \mathbf{v})$$

The divergence of a curl, like the curl of a gradient, is always zero $\nabla \cdot (\nabla \times \mathbf{v}) = 0$

$$\nabla \cdot (\nabla \times \mathbf{v}) = 0$$

$$\nabla \times (\nabla \times \mathbf{v}) = \nabla (\nabla \cdot \mathbf{v}) - \nabla^2 \mathbf{v}$$