ADI HRM Algorithm LCFG Guide Version 1.0.0



Revision History

Date	Notes
(YYYY-MM-DD)	
2021-05-12	Initial Document

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Library Configuration (LCFG) for ADI HRM Algorithm

These parameters are already tuned for best performance of the ADI HRM algorithm

Element	Description
spotalgosamplerate	Sampling rate: int16_t
	This is the data sampling rate used for the
	spot algorithm. This is fixed at 50Hz and
	should not be changed.
	This parameter is not used currently.
spotalgodecimation	Decimation factor: int16_t
	The internal decimation factor used by
	algorithm for the incoming data. The value is
	fixed at 6 and should not be changed.
	This parameter is not used currently.
mindifftrackSpot	Minimum difference between Track and Spot
	HR output: int16_t
	This value is to determine the closeness of
	the tracking HR to the spotHR. If the
	difference is lesser than this value, the value
	of the HR from tracking algorithm is output.
	The value set in this release is 4.
	This parameter is not used currently.
initialconfidencethreshold	Confidence Threshold: int16_t
	The tracking algorithm returns a measure of
	the correctness of the HR estimation after
	each sample is processed. If the returned
	confidence is beyond this initial value, the
	system switches the spot algorithm and uses
	the tracking algorithm for further HR
	estimation. The value used now is 70%
	(equivalent to 716 in 6.10 fixed point format)
ppgscale	Scaling value of PPG signal: uint32_t
	This is scaling value used for the incoming
	PPG signal. It is fixed at 3200 and should not
	be changed.
accelscale	Scaling value of accelerometer: int16_t
	This is scaling value used for the incoming
	accelerometer signal. It is fixed at 4194 and
	should not be changed.



Stability count for spot algorithm: int16_t When the spot algorithm HR output is close to the tracking algorithm, this value is used to measure its stability over a range of samples, before switching to the tracking HR output. This parameter is set to 5 seconds.
to the tracking algorithm, this value is used to measure its stability over a range of samples, before switching to the tracking HR output. This parameter is set to 5 seconds.
measure its stability over a range of samples, before switching to the tracking HR output. This parameter is set to 5 seconds.
before switching to the tracking HR output. This parameter is set to 5 seconds.
This parameter is set to 5 seconds.
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This parameter is not used currently.
spothrtimeoutsecs Timeout for spot algorithm: int16_t
This is the maximum amount of time that
the spot algorithm is run initially before
switching to only tracking algorithm. The value
is set to 15 seconds.
This parameter is not used currently.
zeroorderholdnumsamples Number of hold samples for tracking
algorithm: int16_t
This is an internal parameter to determine
the iterations for algorithm for each sample.
This value is fixed to 1 and should not be
changed.
trackalgosamplerate Tracking algorithm sampling rate: int16_t
This parameter is not used currently.
trackhrtimeoutsecs Timeout for tracking algorithm: int16_t
This parameter is not used currently.
spotwindowlength Amount of data analysed by algorithm for
heart rate estimation: uint32_t
This is set to 5000ms
This parameter is not used currently.
trackerminheartratebpm Minimum heart rate tracked: uint32_t
This set to 30
This parameter is not used currently.
hrvEnable Whether hrv is enabled: uint8_t
Enabled by default