

Address	Element	Description
0	partNum	<p>Device ID: uint16_t</p> <p>This ID is used to identify the ADPD4100 sensor device type and do specific tuning.</p> <p>0x00C0 – ADPD4000 device – on DVT1 watch</p> <p>0x01C2 – ADPD4100 device - on DVT2/3 watch</p>
1	targetSlots	<p>Slot selection: uint16_t</p> <p>Determine the slot from the 12 slots available on ADPD4000/ADPD4100</p>
2	targetChs	<p>Target Channel(s) selection and shift: uint8_t</p> <p>The lower nibble (Bit[3:0]) chooses the input channel value to HRM from the slot (selected by targetSlots) while Bit[6:4] chooses the shift value of channel signal in mode 3 and 4. Bit7 is used as Channel2 packetization control in modes 1,3,4.</p> <p>Bit[3:0]: channel mode</p> <p>Bit[6:4]: shift (for mode 3 and 4)</p> <p>Bit[7]: Channel2 packetization control (for mode 1,3 and 4). Setting this bit will disable the Channel2 packetization.</p> <p>1 - Channel 1 (default)</p> <p>2 - Channel 2</p> <p>3 – Channel1 will be fed as PD1+PD2 and shifted by value in [6:4]</p> <p>4 – Channel1 and Channel2 shifted by value in [6:4] and sum.</p> <p>Eg: - 0x23 → (Channel1>>2), 0x13 → (Channel1>>1), 0x24 → (Channel1>>2+Channel2>>2), 0x14 → (Channel1>>1+Channel2>>1),</p>
3	deviceMode	Not used
4	featureSelect	<p>Enable pre-process features: uint16_t</p> <p>Used to enable/disable some of the pre-process states of the ADPD State Machine. This should not be used unless the user is fully aware of what they are doing.</p> <p>Bit is 1: feature enabled; 0: feature disabled</p> <p>Bit 0 → Detect On</p> <p>Bit 1 → Detect Off</p>

		Bit 4 → Not used Bit 6 → Not used Bit 8 → Dynamic AGC Bit 9 → Static AGC Bit 12 → HRM algorithm
5	drTime	Data Rate Time: uint16_t Sets the time used to determine the data rate adjustment factor. To account for the fact that clock calibration does not align exactly on the rate needed. The data rate is determined during the running of the algorithm; this factor is then used to adjust the heart rate value determined by the algorithm. The input is a time in milliseconds. The default is 0ms.
6	DutyCycle	Not used (uint32_t)
7	hrmInputRate	Used to check the sampling rate to be used for the algorithm. ADI HRM Algorithm used in this package will support only 50Hz: uint16_t To support a higher sample rate of ADPD and ADXL, both data should be decimated to 50Hz.
8	syncMode	Not used
9	proximityRate	Not used
10	proximityTimeout	Not used
11	proximityOnLevel	Not used
12	staticAgcRecalTime	Time in minutes for static AGC recalibration. Set this value to 0x00 to disable this feature.
13	Res16_1	Reserved(uint16_t)
14	Res8_1	Reserved(uint8_t)
15	Res16_2	Reserved(uint16_t)
16	Res16_3	Reserved(uint16_t)
17	Res32_2	Reserved(uint32_t)
18	initialLedPulse	Initial Pulse for Static AGC in PPG application: uint16_t When static AGC is not enabled, this will be the pulse for the session.
19	Res8_2	Reserved(uint8_t)
20	Res8_3	Reserved(uint8_t)
21	Res32_3	Reserved(uint32_t)

22	rmssdSampleWindow	RMSSD calculation window size: uint16_t This is used during RMSSD calculation of HRV data.
23	Res8_4	Reserved (uint8_t)
24	Res16_4	Reserved(uint16_t)
25	Res16_5	Reserved(uint16_t)
26	maxSamplingRate	Maximum sampling rate used for Dynamic AGC: uint16_t
27	targetDcPercent	Target DC level in percentage: uint8_t Used in dynamic AGC to set the target current percentage during AFE saturation. It is also used for checking DC level during pulse adjust
28	maxLedCurrent	Set Maximum Current for dynamic AGC: uint16_t
29	maxPulseNum	Set Maximum LED pulses dynamic AGC: uint8_t
30	satAdjustPercentForStaticAgc	Saturation adjust in percentage: uint8_t Used in Static AGC to set the target current percentage during AFE saturation. (It is also used by ppg application when static AGC is disabled)
31	Res8_5	Reserved(uint8_t)
32	InitialCurrentTiaGain	LED current & TIA gain when static AGC is disabled: uint16_t Eg:- 0000BF24 -> current(bit[15:8]) and Initial TIA Gain channel2 [5:3] channel1[2:0]) where, current is the actual LED current Initial TIA Gain setting is 000: 200 kΩ. 001: 100 kΩ. 010: 50 kΩ. 011: 25 kΩ. 100: 12.5 kΩ
33	motionThreshold	Low Motion activity threshold(For dynamic AGC): uint32_t
34	motionCheckPeriod	Upper = check period, Lower = rest time(dynamic AGC): uint32_t Default set to Upper=2min and Lower=3sec

35	motionThresholdHigh	High motion activity threshold (dynamic AGC): uint32_t
36	motionCheckPeriodHigh	Low & High motion activity period check (dynamic AGC): uint32_t Default set to 6sec for low and high activity
37	Res8_6	Reserved (uint8_t)
38	Res16_6	Reserved(uint16_t)
39	Res16_7	Reserved(uint16_t)
40	sqiLowPowerThreshold	SQI low power threshold: uint16_t If SQI is greater than this threshold, then dynamic AGC will decrease the power. This means the signal is good. Default: (0.25*1024)
41	sqiHighPowerThreshold	SQI high power threshold: uint16_t If SQI is less than or equal to this threshold, then dynamic AGC will increase the power. This means the signal is poor. Default: (0.15*1024)