# **Report for Matrix Operations**

### Introduction

This project involves the implementation of a VHDL program that performs matrix operations on a 2x2 matrix derived from a std\_logic\_vector input. The operations include finding the greatest and least numbers in the matrix, rotating the matrix 90 degrees clockwise, and computing the sum of the original and rotated matrices. The project consists of three files: the main entity and architecture, a custom package for matrix types, and a testbench.

### File 1: MatrixOps.vhd

**Entity Declaration** 

```
library IEEE;
 2
    use IEEE.STD_LOGIC_1164.ALL;
 3
    use IEEE.STD LOGIC ARITH.ALL;
 4
    use IEEE.STD_LOGIC_UNSIGNED.ALL;
 5
    use IEEE.std logic_arith.all;
 78
    -- Import the custom package
    use work.MatrixTypes.all;
 9
10
    entity MatrixOps is
11
        Port (
12
                             : in std logic vector(31 downto 0);
             input_vector
13
             max val
                             : out integer;
14
             min val
                            : out integer;
15
             rotated matrix : out integer matrix;
16
             sum matrix
                             : out integer_matrix
17
        ):
    end MatrixOps;
18
```

The entity **MatrixOps** defines the input and output ports:

- **input\_vector**: A 32-bit **std\_logic\_vector** representing the input matrix.
- max\_val and min\_val: Integers representing the maximum and minimum values in the matrix.
- rotated\_matrix: A 2x2 integer matrix representing the 90-degree clockwise rotated matrix.
- sum matrix: A 2x2 integer matrix representing the sum of the original and rotated matrices.

### **Architecture Implementation**

```
architecture Behavioral of MatrixOps is
21
         -- Define the original 2x2 matrix signal
22
         signal matrix : integer_matrix;
23
         signal rotated : integer_matrix;
24
         signal sum_result : integer_matrix;
25
   begin
26
         -- Extract the 8-bit segments of input vector and convert them to integers for matrix elements
27
        matrix(0,0) \le conv integer((signed(input vector(31 downto 24))));
28
        matrix(0,1) <= conv_integer((signed(input_vector(23 downto 16))));</pre>
29
        matrix(1,0) <= conv_integer((signed(input_vector(15 downto 8))));</pre>
30
         matrix(1,1) <= conv_integer((signed(input_vector(7 downto 0))));</pre>
```

The architecture **Behavioral** of **MatrixOps** defines signals for the original matrix, the rotated matrix, and the sum matrix. The input vector is divided into 8-bit segments, which are converted to integers and assigned to the matrix elements.

### **Finding Maximum and Minimum Values**

```
-- Determine the maximum and minimum values in the matrix

max_val <= matrix(0,0) when (matrix(0,0) >= matrix(0,1) and matrix(0,0) >= matrix(1,0) and matrix(0,0) >= matrix(1,1)) else

matrix(1,0) when (matrix(0,1) >= matrix(1,0) and matrix(0,1) >= matrix(1,1)) else

matrix(1,0) when (matrix(1,0) >= matrix(1,1)) else

matrix(1,1);

min_val <= matrix(0,0) when (matrix(0,0) <= matrix(0,1) and matrix(0,0) <= matrix(1,0) and matrix(0,0) <= matrix(1,1)) else

matrix(1,0) when (matrix(0,1) <= matrix(1,0) and matrix(0,1) <= matrix(1,1)) else

matrix(1,1);
```

The maximum and minimum values in the matrix are determined using a series of **when else** statements to compare the matrix elements.

### **Rotating the Matrix**

```
-- Rotate the matrix 90 degrees clockwise and assign to rotated signal rotated(0,0) <= matrix(1,0); rotated(0,1) <= matrix(0,0); rotated(1,0) <= matrix(1,1); rotated(1,1) <= matrix(0,1);
```

The matrix is rotated 90 degrees clockwise by reassigning the elements to their new positions in the **rotated** signal. The rotated matrix is then assigned to the **rotated\_matrix** output.

### **Computing the Sum of Matrices**

```
-- Compute the sum of the original matrix and the rotated matrix, assigning to sum_result signal sum_result(0,0) <= matrix(0,0) + rotated(0,0); sum_result(0,1) <= matrix(0,1) + rotated(0,1); sum_result(1,0) <= matrix(1,0) + rotated(1,0); sum_result(1,1) <= matrix(1,1) + rotated(1,1); -- Assign sum matrix to output sum_matrix <= sum_result;
```

The sum of the original matrix and the rotated matrix is computed elementwise and assigned to the **sum\_result** signal. The sum matrix is then assigned to the **sum\_matrix** output.

### File 2: MatrixTypes.vhd

```
library IEEE;
use IEEE.STD_LOGIC_1164.ALL;

package MatrixTypes is
    -- Define a custom 2D array type for integer matrices
    type integer_matrix is array (0 to 1, 0 to 1) of integer;
end MatrixTypes;
```

This file defines a custom package **MatrixTypes** that includes a type definition for a 2x2 integer matrix. This package is used in the main entity and testbench to handle matrix operations.

## File 3: MatrixOps\_tb.vhd

### **Testbench Entity**

```
library IEEE;
2
    use IEEE.STD LOGIC 1164.ALL;
3
    use IEEE.STD LOGIC ARITH.ALL;
4
    use IEEE.STD LOGIC UNSIGNED.ALL;
5
6
    -- Import the custom package to use integer matrix
7
    use work.MatrixTypes.all;
8
9
    entity MatrixOps tb is
    end MatrixOps tb;
10
```

The testbench entity **MatrixOps\_tb** is defined to test the **MatrixOps** entity.

### **Testbench Architecture**

```
12
    architecture Behavioral of MatrixOps tb is
13
        -- Component declaration for the Unit Under Test (UUT)
14
        component MatrixOps
15
            Port (
                input_vector : in std_logic_vector(31 downto 0);
16
17
                max val
                               : out integer;
                min val : out integer;
18
19
                rotated_matrix : out integer_matrix;
20
                sum_matrix : out integer_matrix
21
            );
22
        end component;
23
        -- Signals for input and output ports
24
25
        signal input_vector : std_logic_vector(31 downto 0) := (others => '0');
        signal max val
                              : integer;
26
27
        signal min val
                              : integer;
28
        signal rotated_matrix : integer_matrix;
        signal sum matrix
                              : integer_matrix;
```

The testbench architecture **Behavioral** declares the **MatrixOps** component and signals for the input and output ports.

#### **Stimulus Process**

```
32
          -- Instantiate the Unit Under Test (UUT)
33
          uut: MatrixOps
              Port map (
35
                   input vector
                                    => input vector,
                                     => max_val,
                   max_val
37
                                    => min val,
                   min val
38
                   rotated_matrix => rotated_matrix,
                                    => sum_matrix
                   sum matrix
40
              ):
41
42
          -- Stimulus process to apply test cases
43
          stimulus: process
              -- Test Case 1: input_vector with values {4, 2, -1, 3} (represented in 8-bit signed integers) input_vector <= x"04" & x"02" & x"FF" & x"03"; -- 0x04, 0x02, 0xFF (-1), 0x03 in matrix
48
49
               -- Assert statements for Test Case 1
              assert (max_val = 4) report "Test Case 1 Failed: max_val is incorrect" severity error;
assert (min_val = -1) report "Test Case 1 Failed: min_val is incorrect" severity error;
50
              assert (rotated_matrix(0,0) = -1 and rotated_matrix(0,1) = 4 and rotated_matrix(1,0) = 3 and rotated_matrix(1,1) = 2)
    report "Test Case 1 Failed: rotated_matrix is incorrect" severity error;
52
53
               report "Test Case 1 Failed: sum_matrix is incorrect" severity error;
```

The stimulus process applies test cases to the **MatrixOps** entity and uses assert statements to verify the correctness of the outputs.

### **Additional Test Cases**

```
-- Assert statements for Test Case 2
                                                       assert (max_val = 7) report "Test Case 2 Failed: max_val is incorrect" severity error;
assert (min_val = -8) report "Test Case 2 Failed: min_val is incorrect" severity error;
assert (rotated_matrix(0,0) = 5 and rotated_matrix(0,1) = -8 and rotated_matrix(1,0) = -6 and rotated_matrix(1,1) = 7)
62
 63
                                                       report "Test Case 2 Failed: rotated_matrix is incorrect" severity error; assert (sum_matrix(0,0) = -3 and sum_matrix(0,1) = -1 and sum_matrix(1,0) = -1 and sum_matrix(1,1) = 1)
                                                                                                              Test Case 2 Failed: sum_matrix is incorrect" severity error;
 68
                                                      -- Test Case 3: input_vector with values {0, -1, 1, 0} input_vector <= x"00" & x"FF" & x"01" & x"00"; -- 0x00, 0xFF (-1), 0x01, 0x00
 69
70
71
72
73
74
75
                                                       wait for 10 ns;
                                                       -- Assert statements for Test Case 3
                                                      assert (max_val = 1) report "Test Case 3 Failed: max_val is incorrect" severity error;
assert (min_val = -1) report "Test Case 3 Failed: min_val is incorrect" severity error;
                                                       assert (rotated matrix(\theta, \theta) = 1 and rotated matrix(\theta, \overline{1}) = \theta and rotated matrix(\overline{1}, \theta) = \theta and rotated matrix(\theta, \overline{1}) 
                                                                          report "Test Case 3 Failed: rotated_matrix is incorrect" severity error;
  78
                                                       assert (sum_matrix(0,0) = 1 \text{ and } sum_matrix(0,1) = -1 \text{ and } sum_matrix(1,0) = 1 \text{ and } sum_matrix(1,1) = -1)
 79
                                                                                                           "Test Case 3 Failed: sum_matrix is incorrect" severity error;
```

Additional test cases are applied to ensure the correctness of the matrix operations. The testbench uses assert statements to verify the expected outputs for each test case.

#### Conclusion

This project successfully implements matrix operations in VHDL, including finding the maximum and minimum values, rotating the matrix, and computing the sum of matrices. The testbench verifies the correctness of the implementation through various test cases. The detailed report provides an overview of the project structure, code explanations, and the testing process.