

## Formula Sheet

### Definition 1.1: Mean (p.9)

The mean of a sample of  $n$  measured responses  $y_1, y_2, \dots, y_n$  is given by

$$\bar{y} = \frac{1}{n} \sum_{i=1}^n y_i$$

The corresponding population mean is denoted  $\mu$ .

### Definition 1.2: Variance (p.10)

The variance of a sample of measurements  $y_1, y_2, \dots, y_n$  is the sum of the square of the differences between the measurements and their mean, divided by  $n - 1$ . Symbolically, the sample variance is

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (y_i - \bar{y})^2$$

### Definition 1.3: Standard Deviation (p.10)

The standard deviation of a sample of measurements is the positive square root of the variance; that is,

$$s = \sqrt{s^2}$$

### Definition 2.7 And Theorem 2.2 : Permutation (p.43)

An ordered arrangement of  $r$  distinct objects is called a permutation. The number of ways of ordering  $n$  distinct objects taken  $r$  at a time will be designated by the symbol  $P_n r$

$$P_r^n = n(n-1)(n-2) \dots (n-r+1) = \frac{n!}{(n-r)!}$$

**Theorem 2.3:**

The number of ways of partitioning  $n$  distinct objects into  $k$  distinct groups containing  $n_1, n_2, \dots, n_k$  objects, respectively

$$N = \binom{n}{n_1 n_2 \dots n_k} = \frac{n!}{n_1! n_2! \dots n_k!}$$

**Definition 2.8 (p.46) Combinations**

The number of combinations of  $n$  objects taken  $r$  at a time is the number of subsets, each of size  $r$ , that can be formed from the  $n$  objects. This number will be denoted by  $C_n^r$

$$\binom{n}{r} = C_n^r = \frac{P_r^n}{r!} = \frac{n!}{r! (n-r)!}$$

**Definition 2.9 (p.52) :**

The conditional probability of an event  $A$ , given that event  $B$  has occurred, is equal to

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

provided  $P(B) > 0$ , the symbol  $P(A|B)$  means probability of  $A$  given  $B$

**Definition 2.10 (p.53)**

Two events  $A$  and  $B$  are said to be independent if any one of the following holds:

$$P(A|B) = P(A)$$

$$P(B|A) = P(B)$$

$$P(A \cap B) = P(A)P(B)$$

Otherwise, the events are said to be *dependent*

**Theorem 2.9: Bayes Theorem (p.71)**

For 2 events A and B in sample space S, with  $P(A) > 0$  and  $P(B) > 0$

$$P(B|A) = \frac{P(A|B) P(B)}{P(A)}$$

**Definition 3.4: Expected Value (p.91)**

Let Y be a discrete random variable with the probability function  $p(y)$ . Then the expected value of Y,  $E(Y)$ , is defined to be

$$E(Y) = \sum_y yp(y)$$

**Definition 3.7: Binomial Distribution (p.103)**

A random variable Y is said to have a binomial distribution based on n trials with success probability p if and only if

$$p(y) = \binom{n}{y} p^y q^{n-y}$$

Where:  $y = 0, 1, 2, \dots, n$  and  $0 \leq p \leq 1$

**Definition 3.8: Geometric Distribution (p.115)**

A random variable Y is said to have a geometric probability distribution if and only if

$$p(y) = q^{y-1}p$$

Where:  $y = 1, 2, 3, \dots$   $0 \leq p \leq 1$