

Solving NP-complete problems

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Agenda

- Exact solution (today)
 - Brute force search
 - Branch and bound
 - Dynamic programming, memoization
- Approximation
 - Greedy strategy
 - Heuristics, local search
 - Monte-Carlo
 - Meta-heuristics (genetic alg, annealing, ant colony, etc.)

Branch and Bound

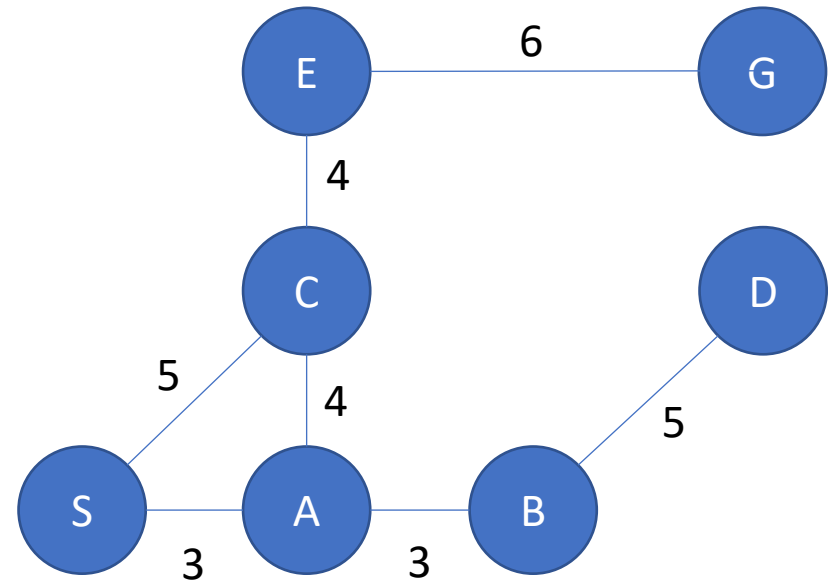
Idea:

- Branching: Assume a set G is split into subsets $G_i \leq G, i = 1 \dots r: \bigcup_r G_i = G$ - recursively = search tree
- Upper bound $UB_i \geq \min_{x \in G_i} f(x)$
- Lower bound $LB_i \leq \min_{x \in G_i} f(x)$

Construct several solutions sequentially and store a target function record. If G_i has lower bound $LB_i > Record$, then G_i doesn't contain optimal solution – do not explore the branch anymore.

Branch and Bound

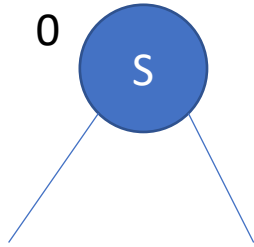
- Short path example for approach demonstration (S to D)



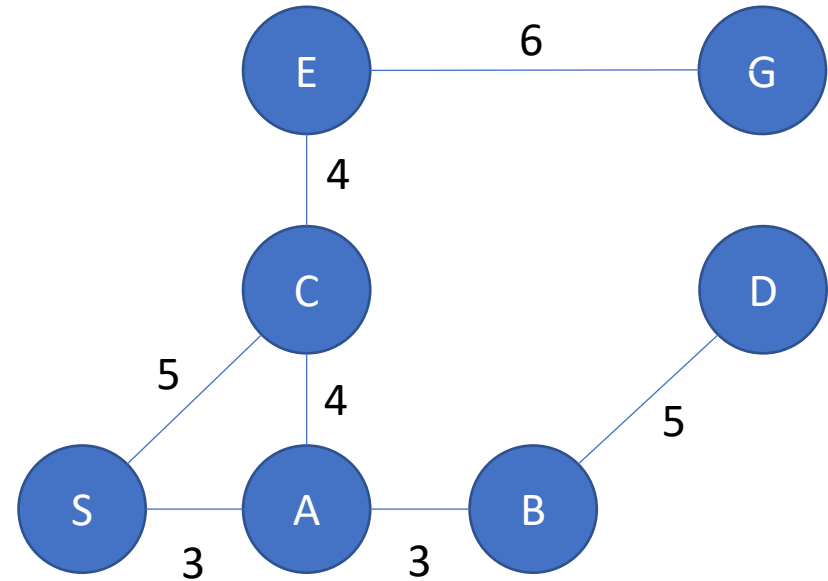
Example source: MIT 6.034

Branch and Bound

- Search tree

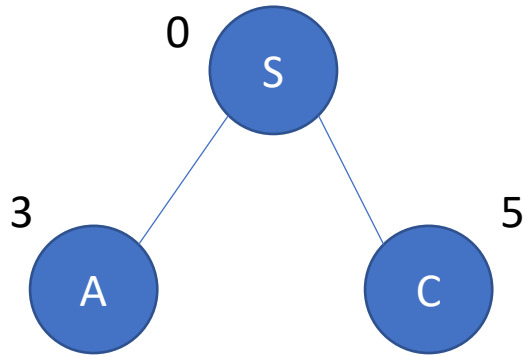


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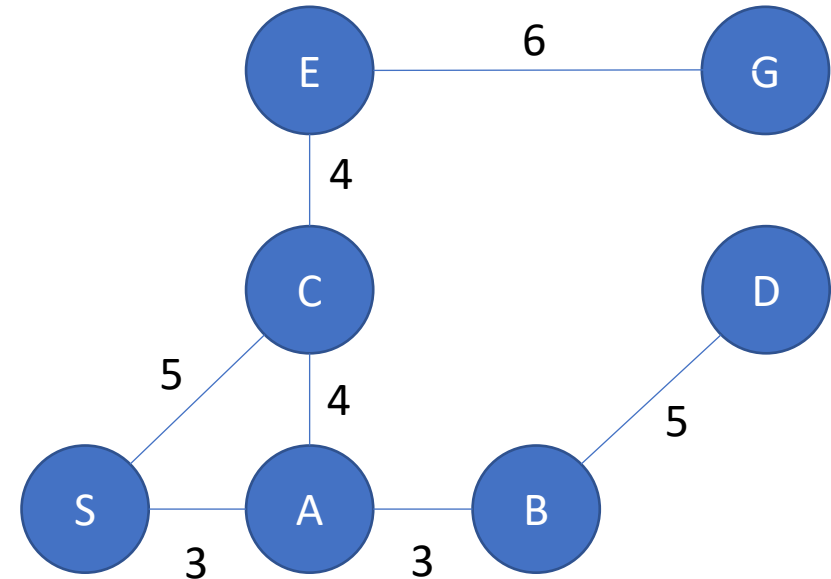
Branch and Bound

- Search tree



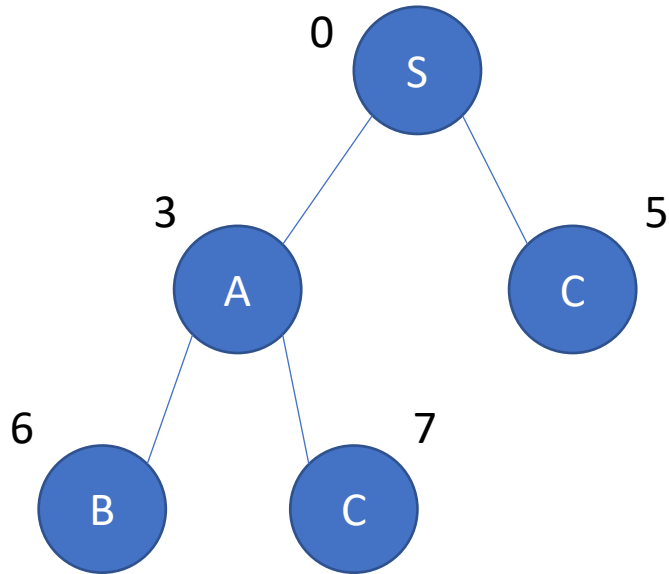
Sort nodes in lexical order

- Short path example for approach demonstration (S to D)

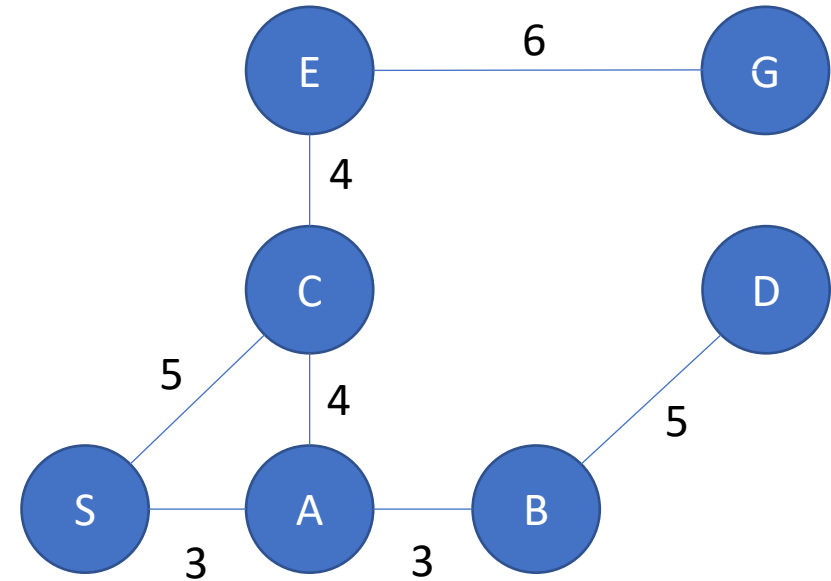


Branch and Bound

- Search tree

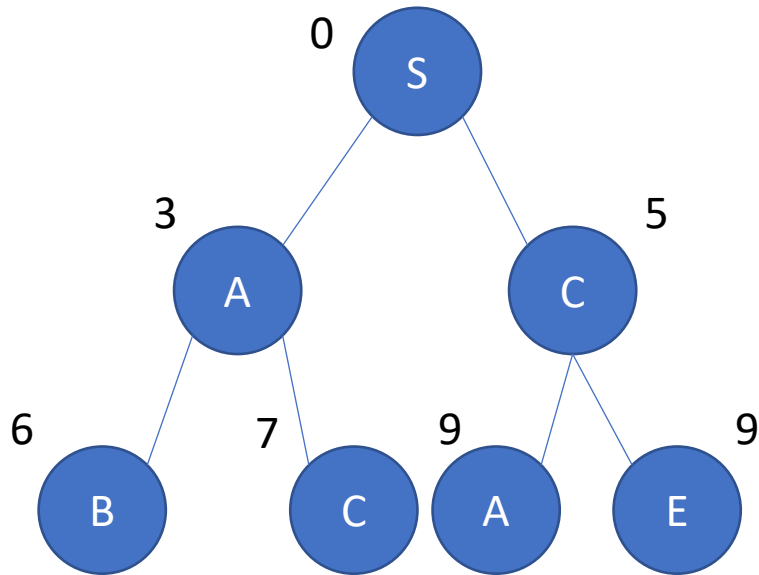


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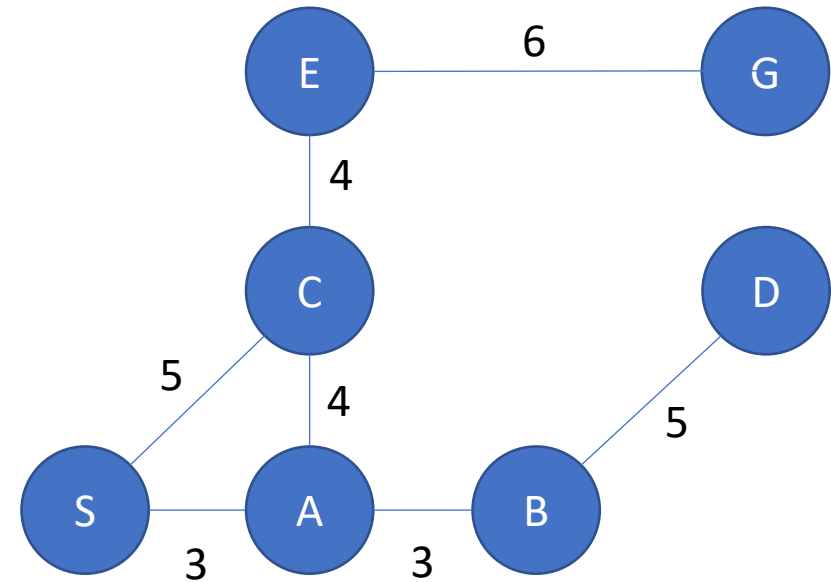


Branch and Bound

- Search tree

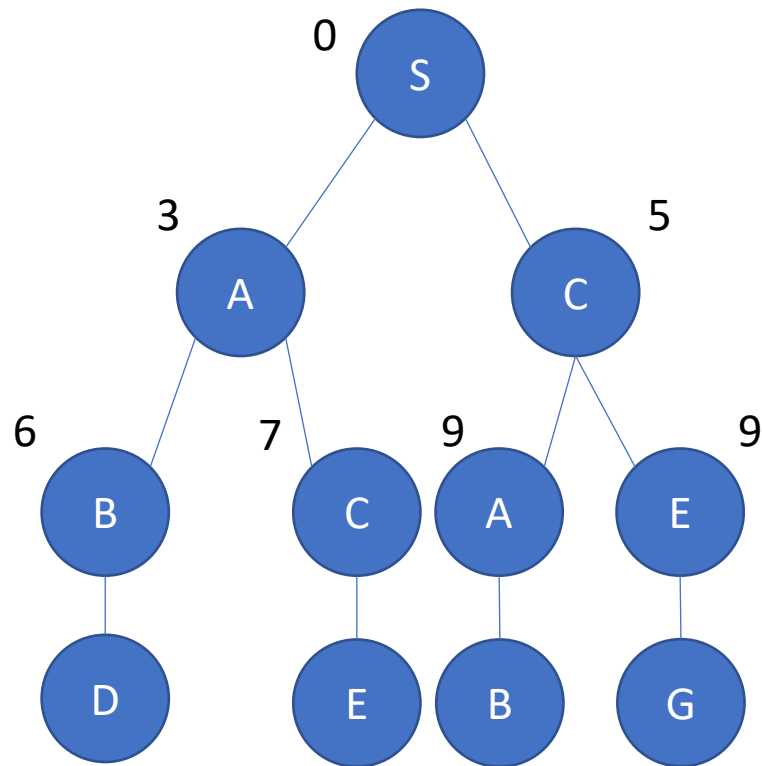


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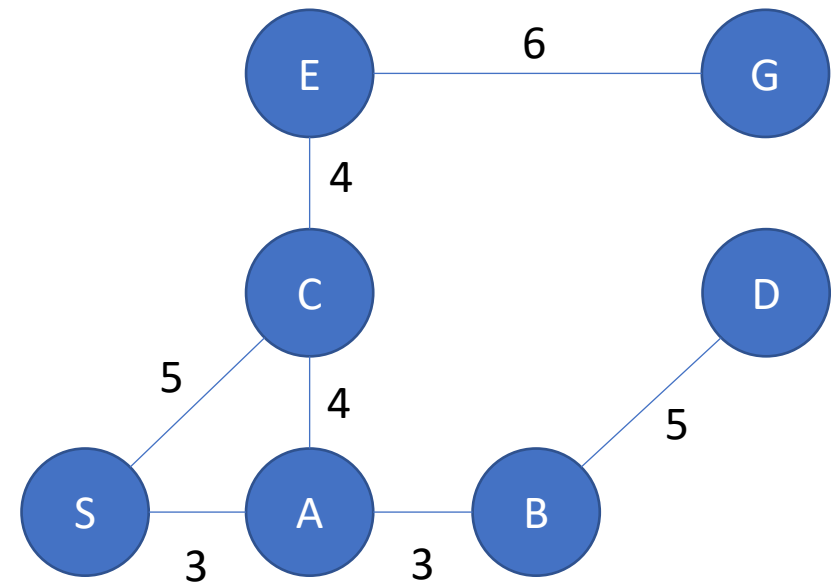
Branch and Bound

- Search tree



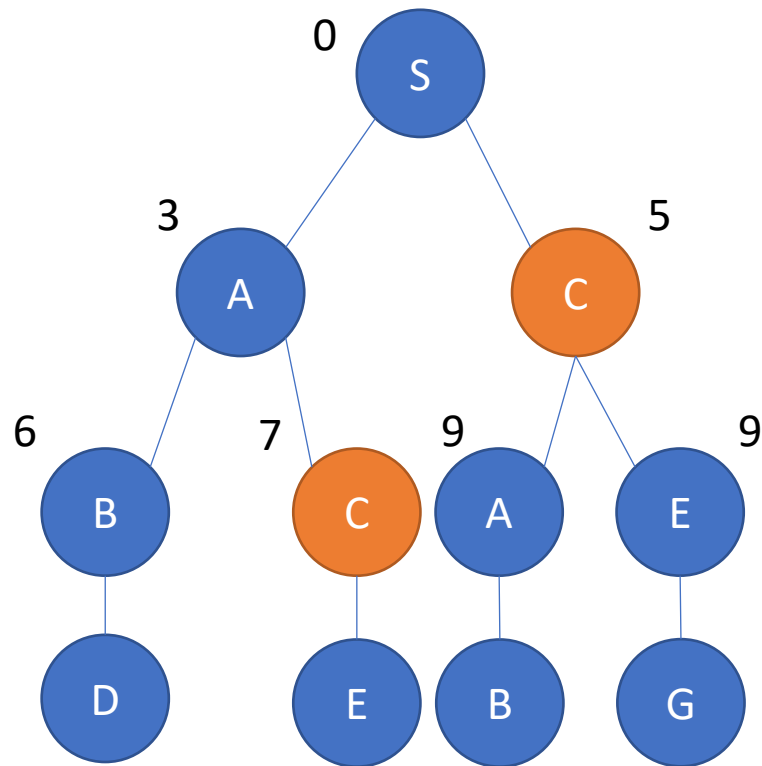
- Complete search tree
- Back tracking

- Short path example for approach demonstration (S to D)



Branch and Bound

- Search tree

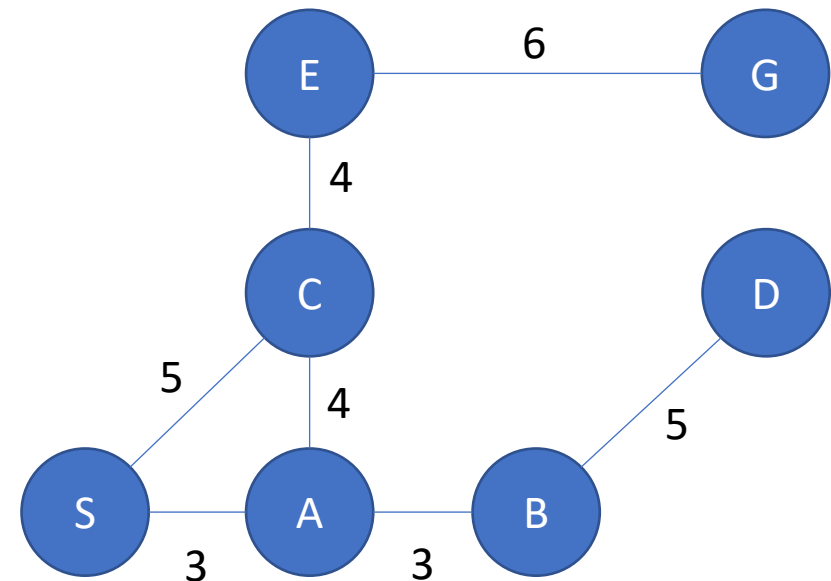


- Complete search tree
- Back tracking

Extremely stupid:

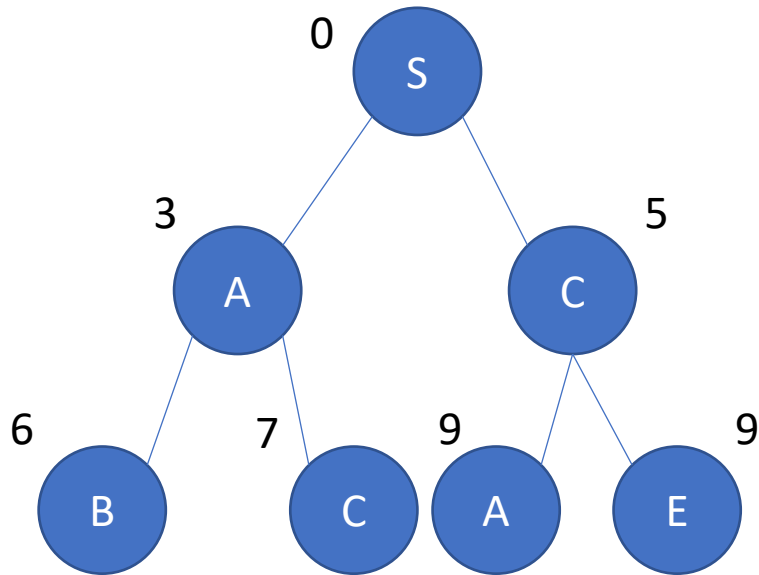
- Visiting the same nodes
- Can't tell if the solution gets better or not

- Short path example for approach demonstration (S to D)

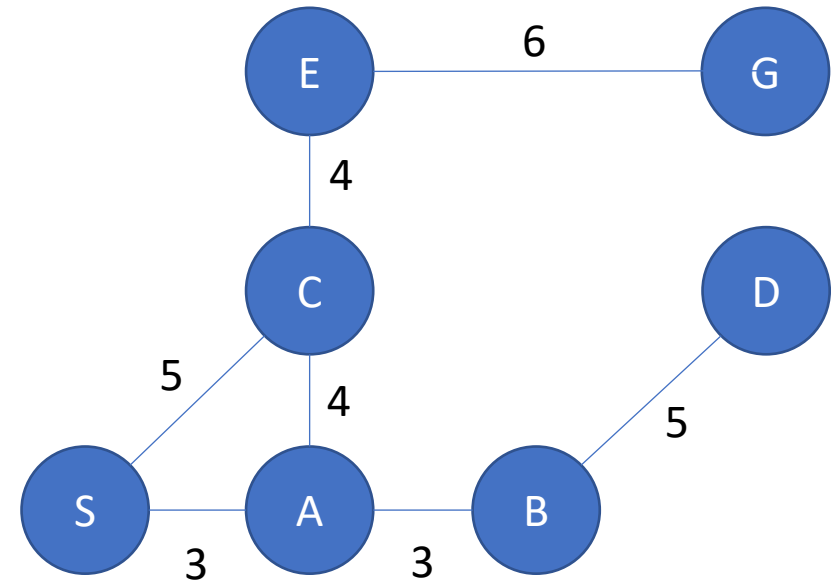


Branch and Bound

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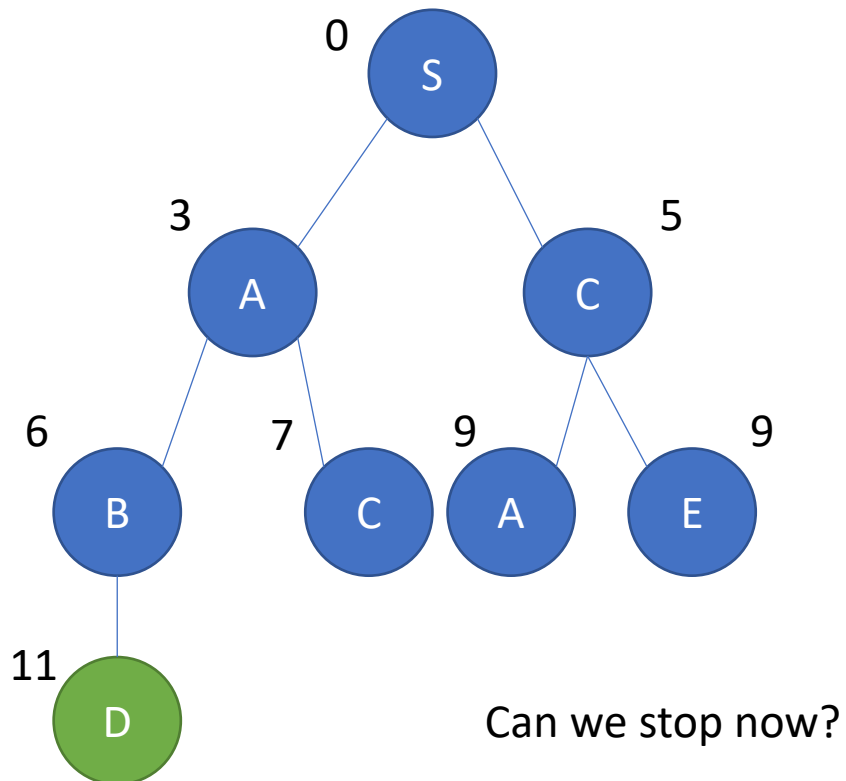


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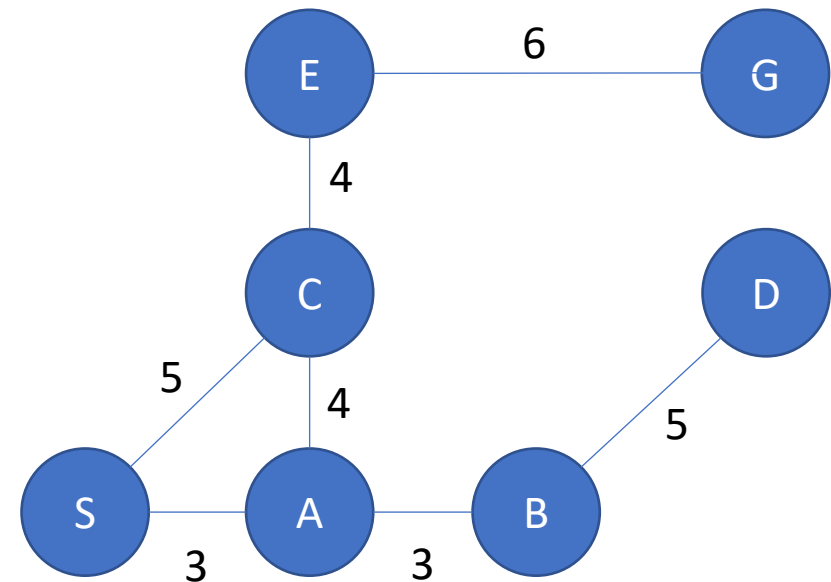


Branch and Bound

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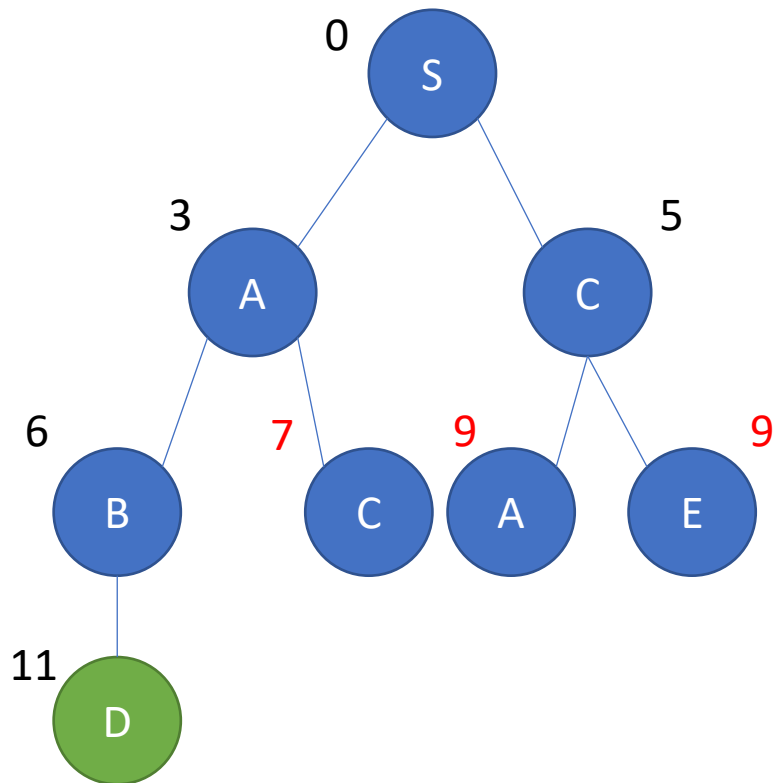


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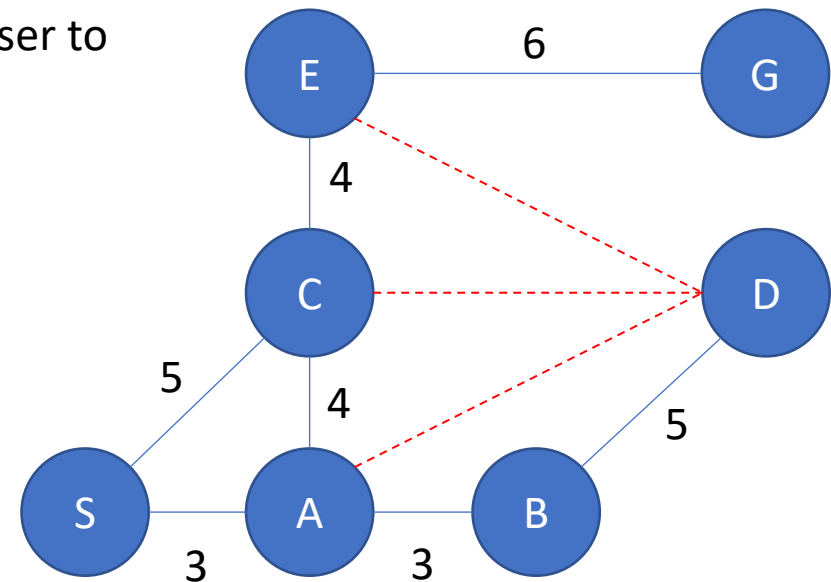
Branch and Bound

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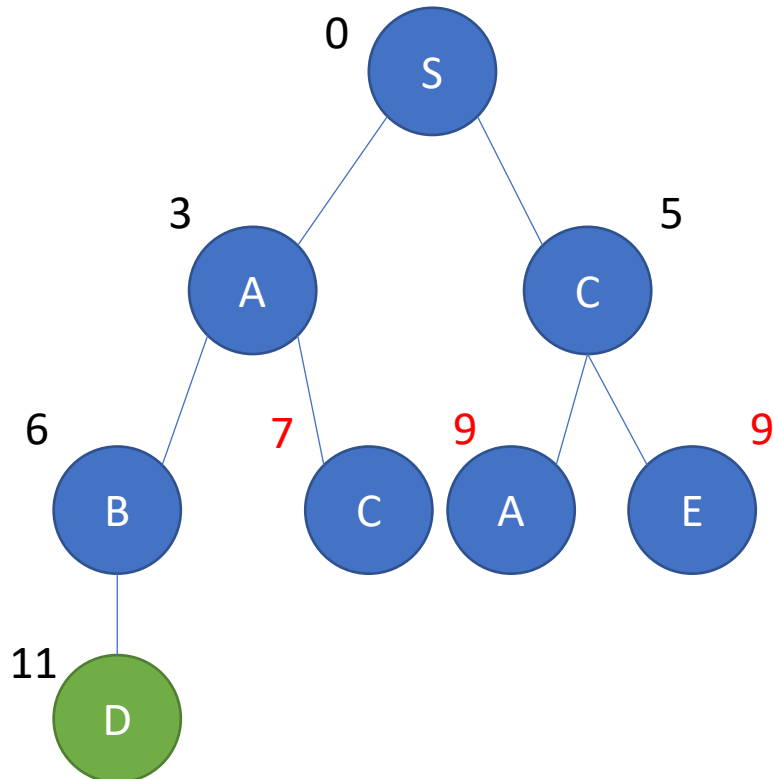
- Short path example for approach demonstration (S to D)

Heuristic: being closer to the goal is better?



Branch and Bound

- Search tree

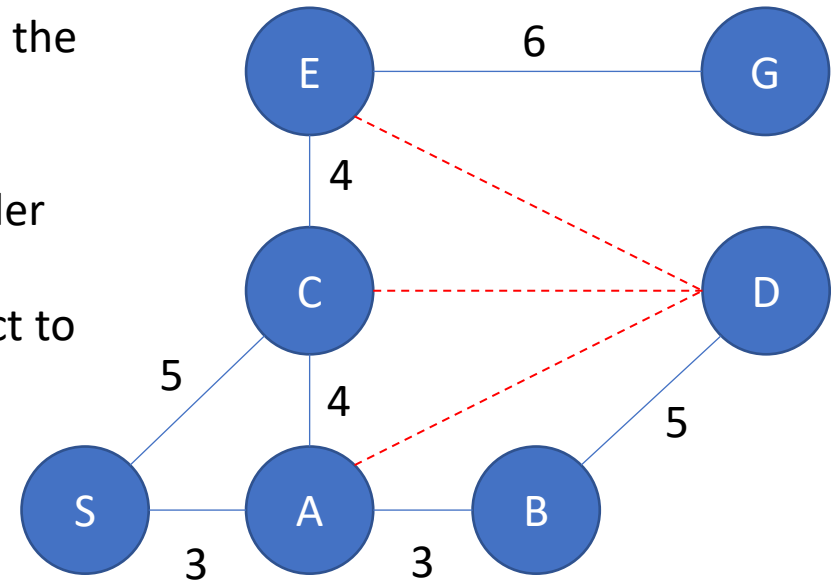


Heuristic: being closer to the goal is better?

DFS: heuristic guided order instead of lexical

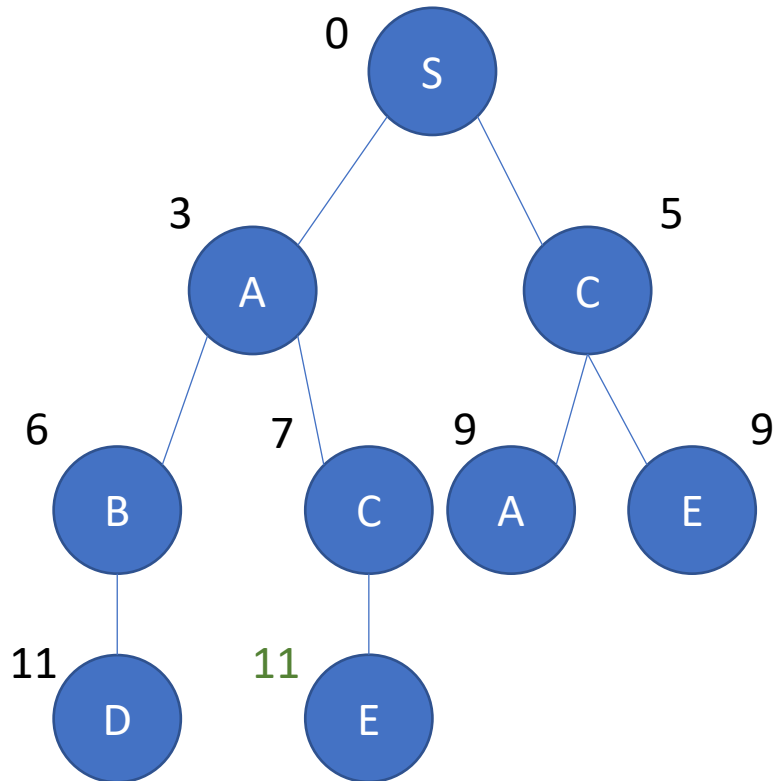
BFS: beam search (restrict to beam width)

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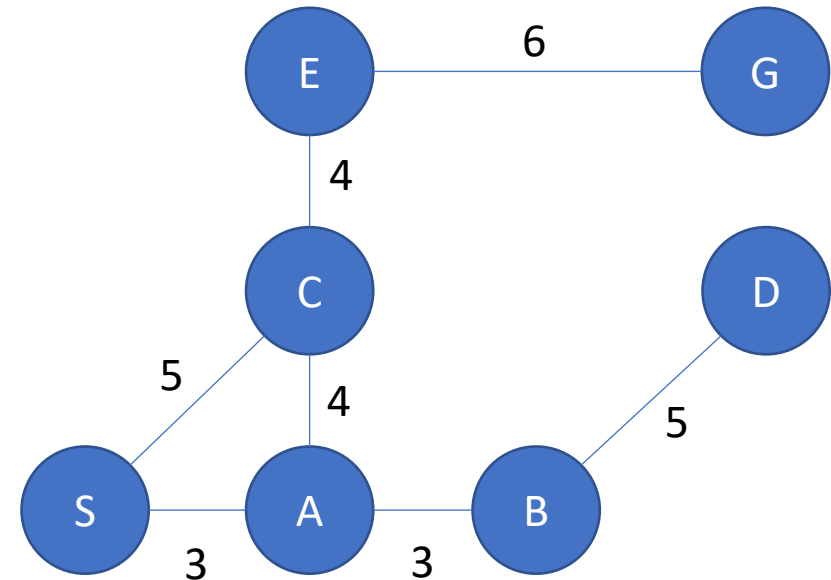


Branch and Bound

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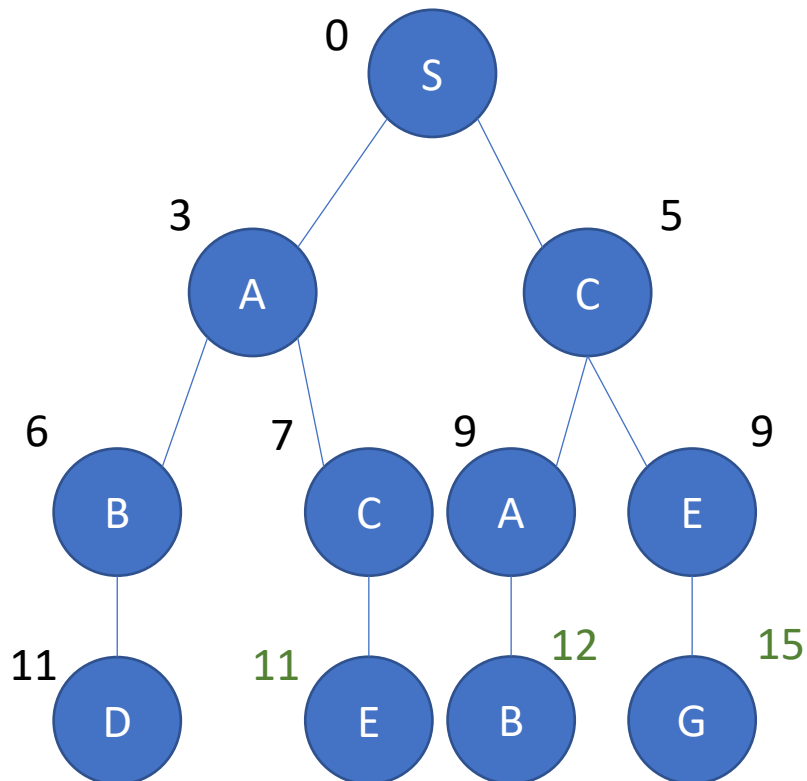


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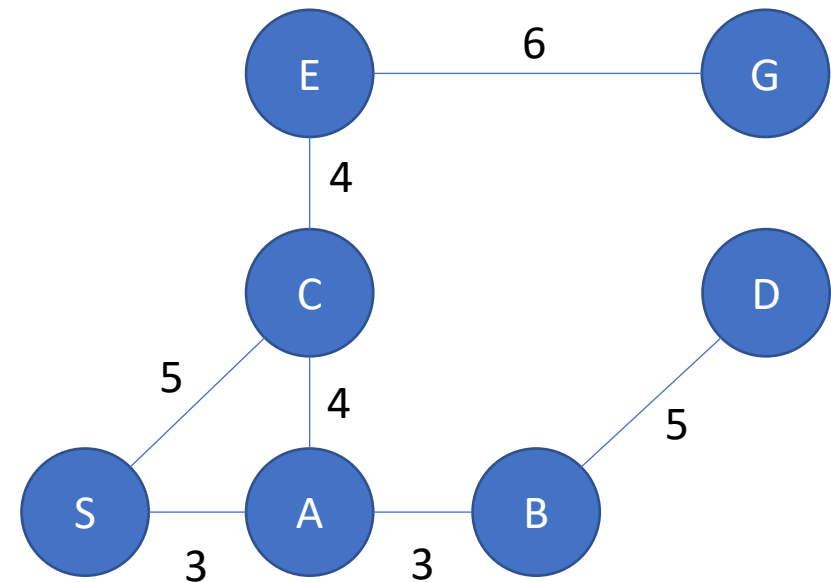


Branch and Bound

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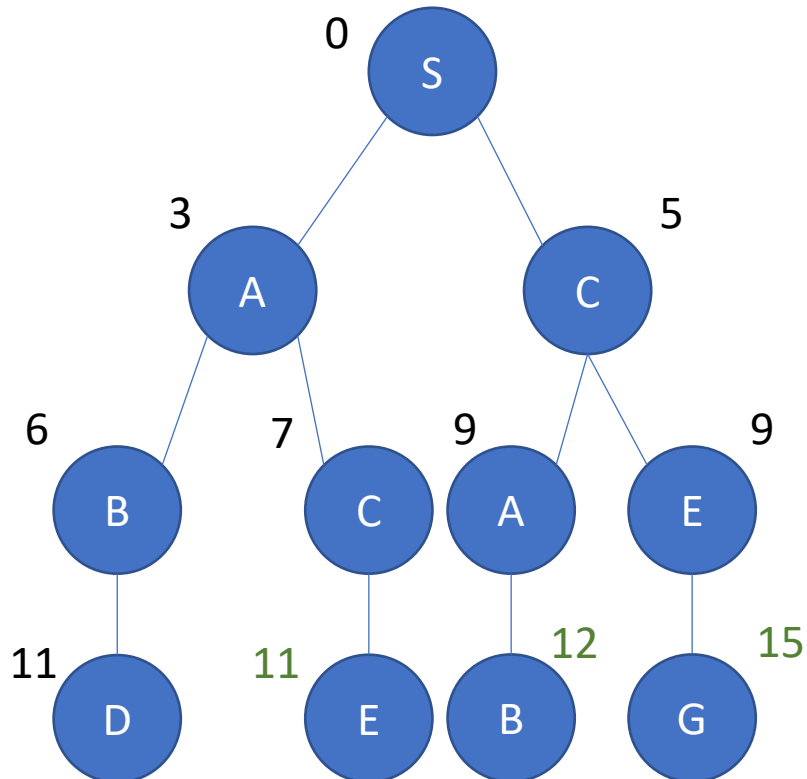


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Branch and Bound

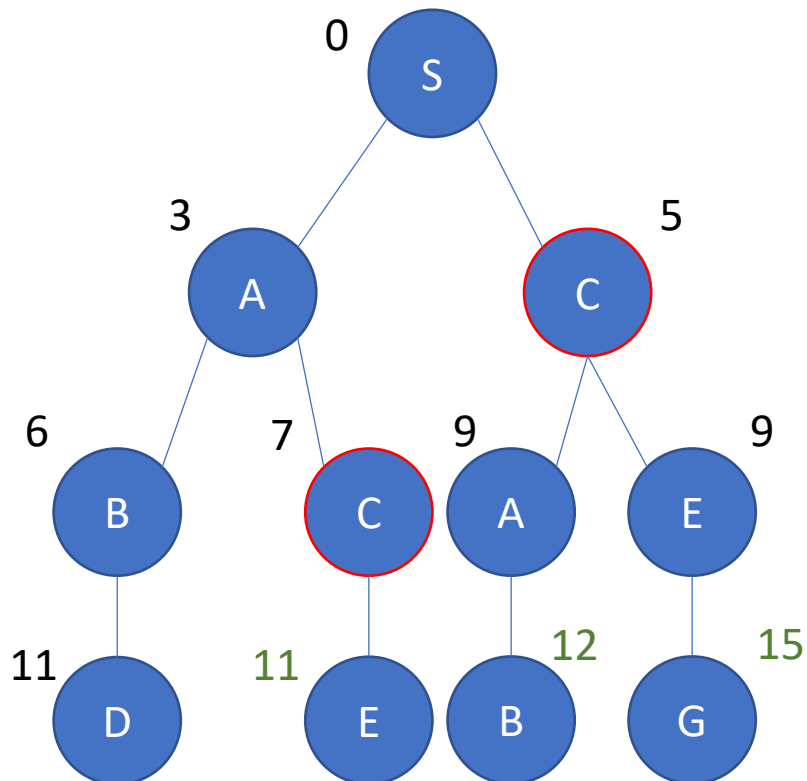
- Search tree



- Create a queue
 - LIFO
 - FIFO
 - Cost based
- Test a path
 - Done if found*
- Extend the path & sort* new queue items

Branch and Bound

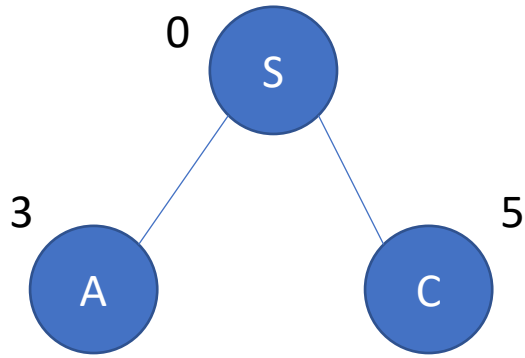
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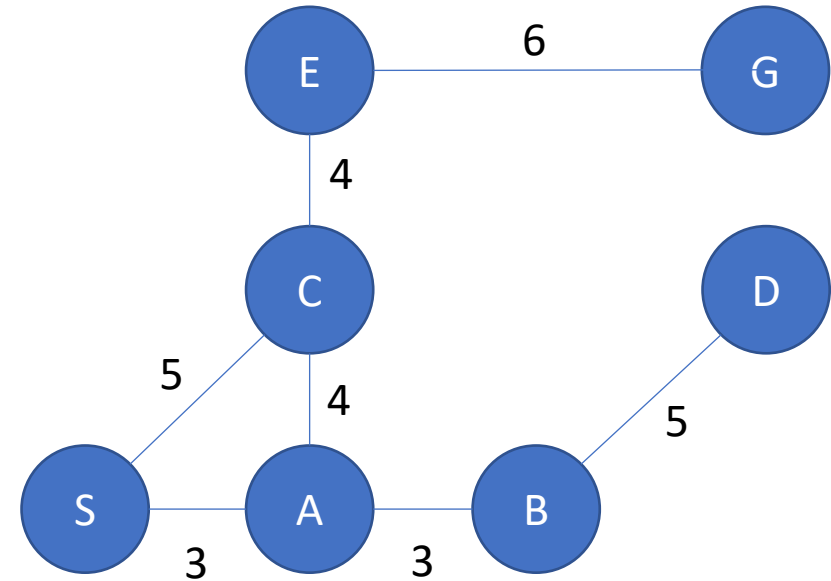
- Create a queue
 - LIFO
 - FIFO
 - Cost based
- Test a path
 - Done if found*
- Extend the path & sort* new queue items
 - Don't extend nodes that have been extended

Branch and Bound

- Search tree

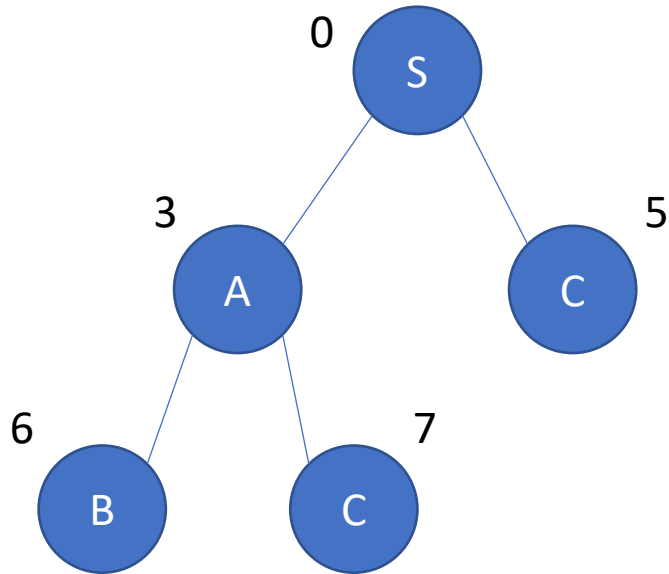


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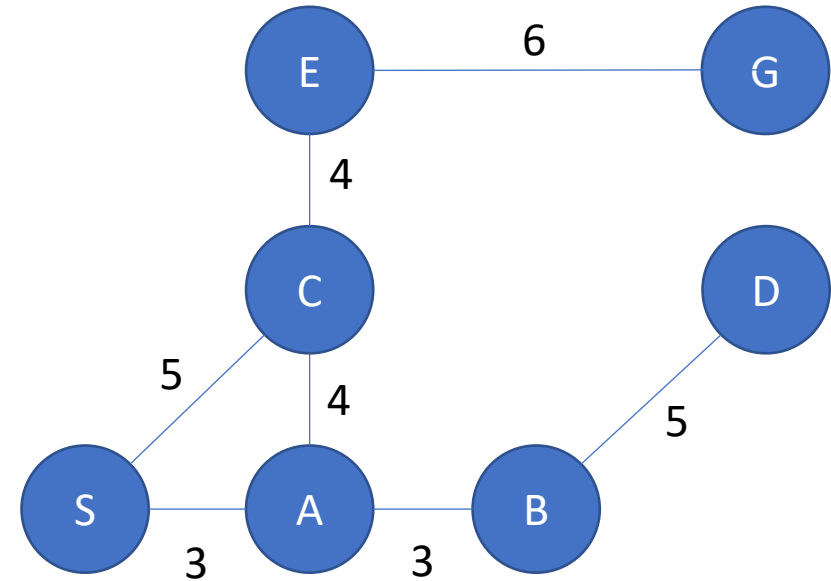


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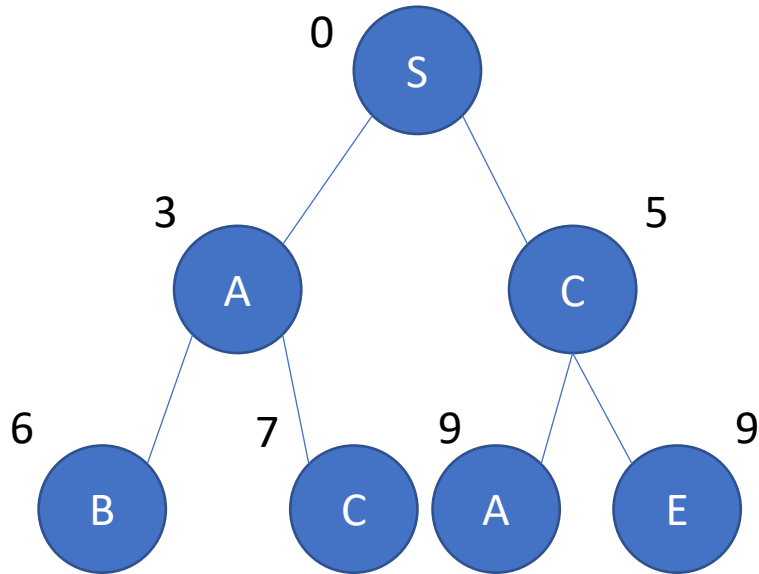


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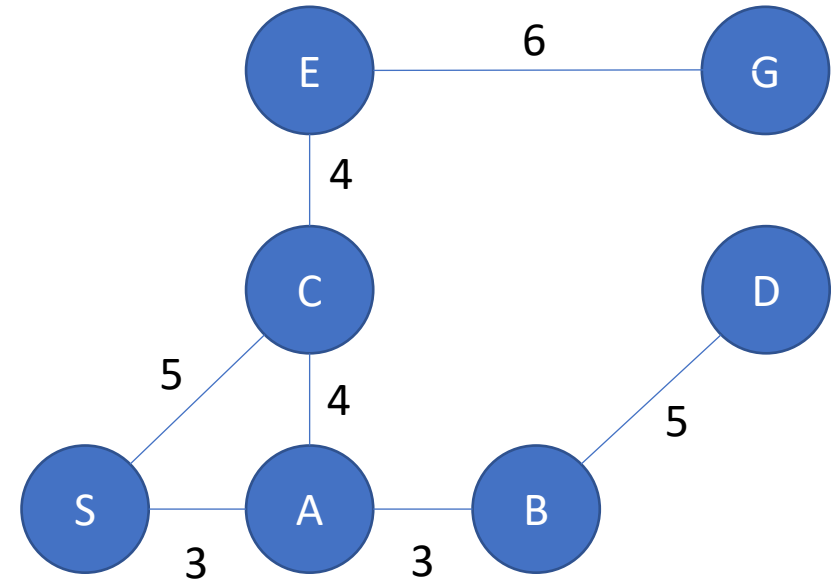


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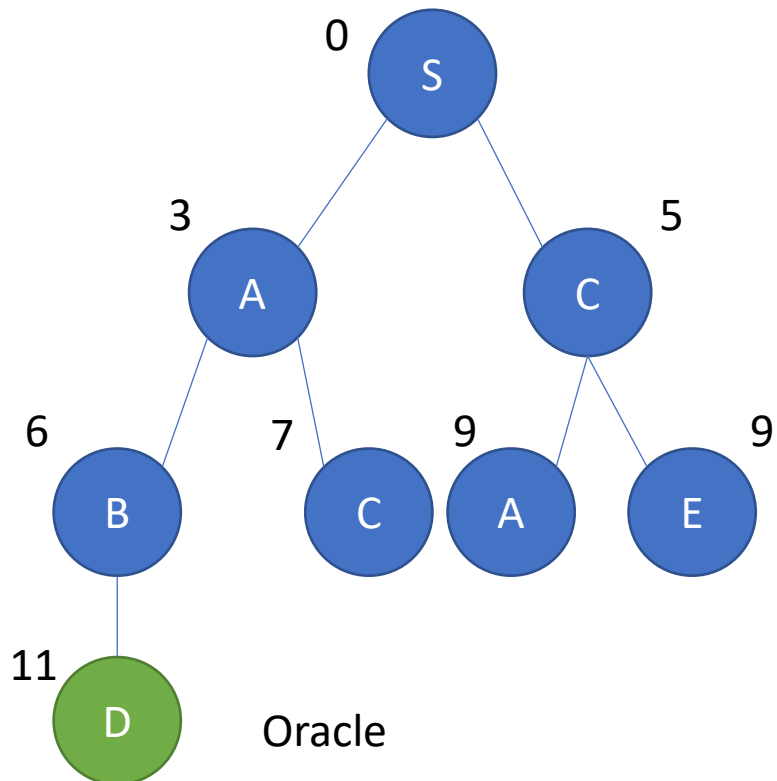


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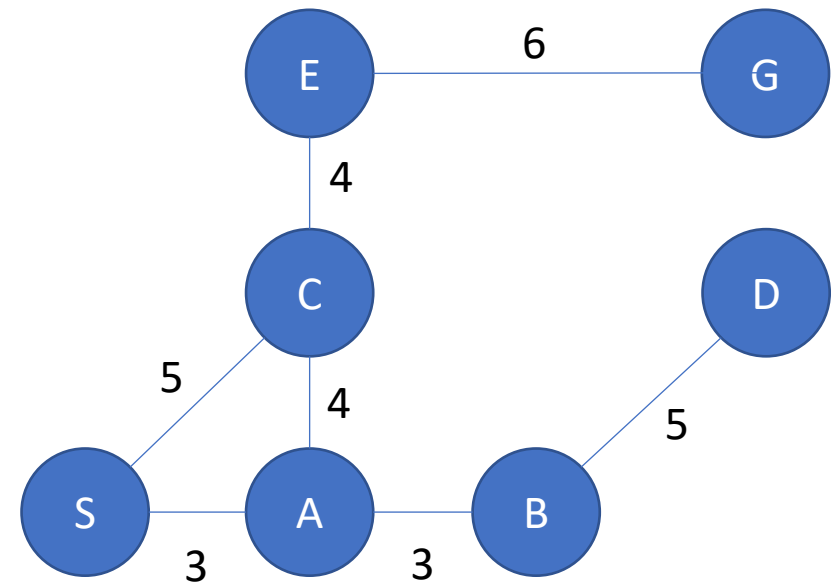


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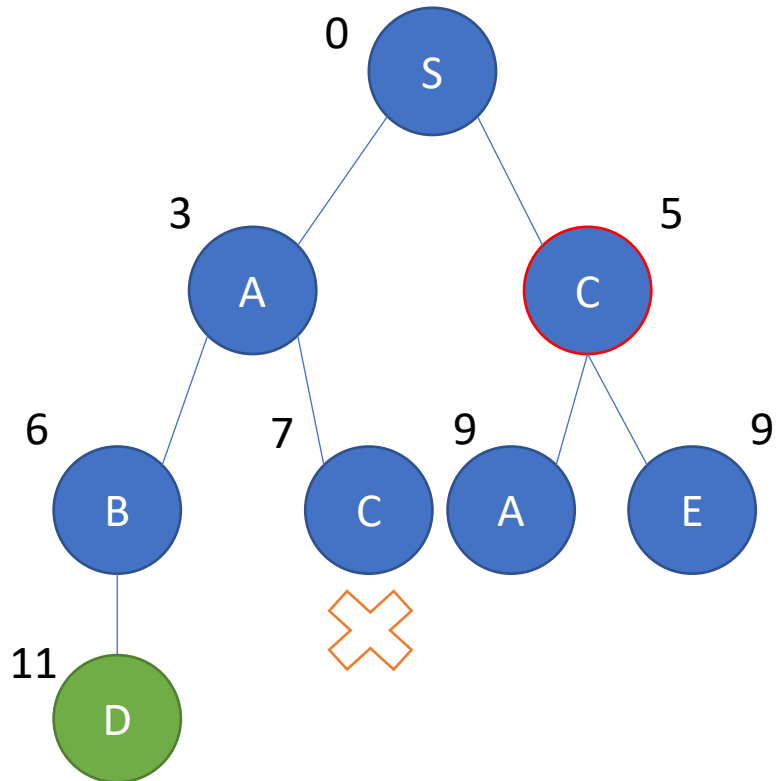


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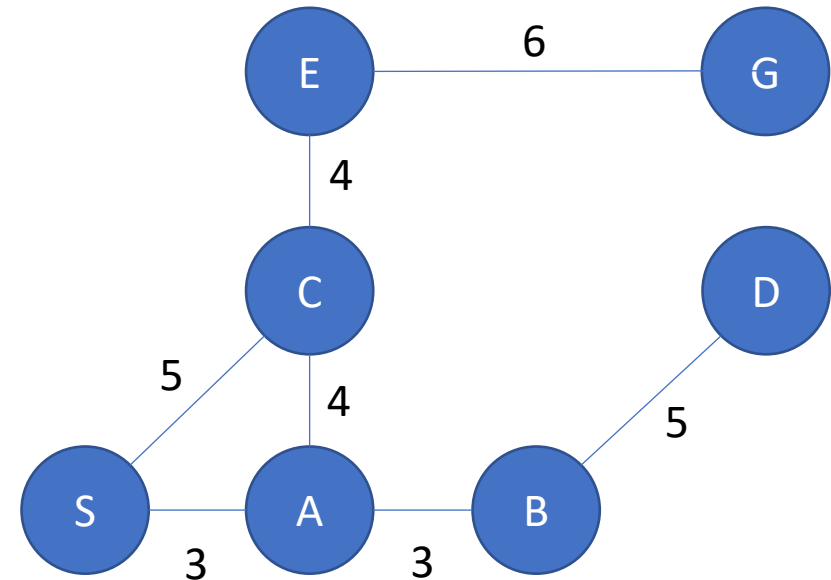


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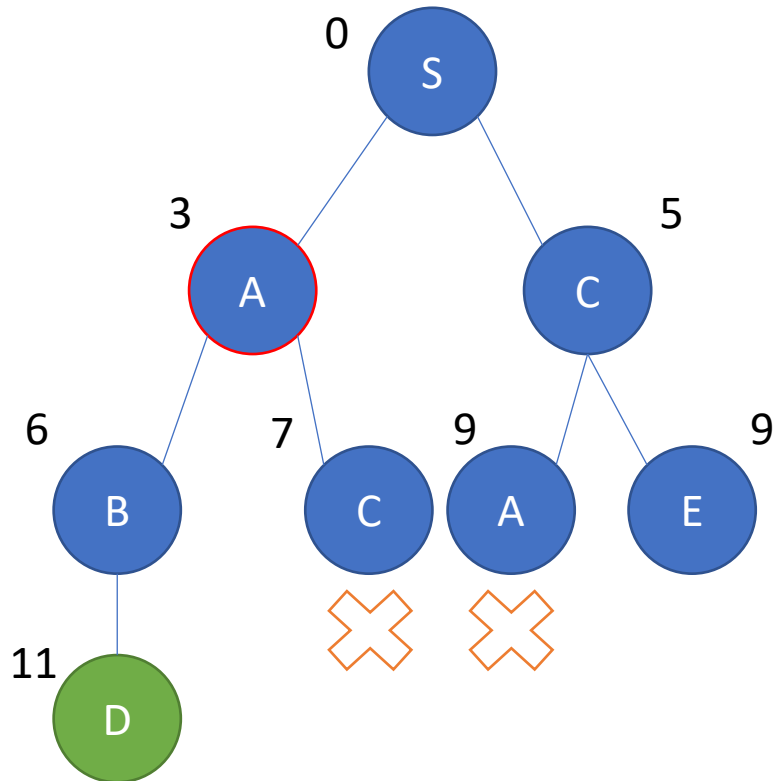


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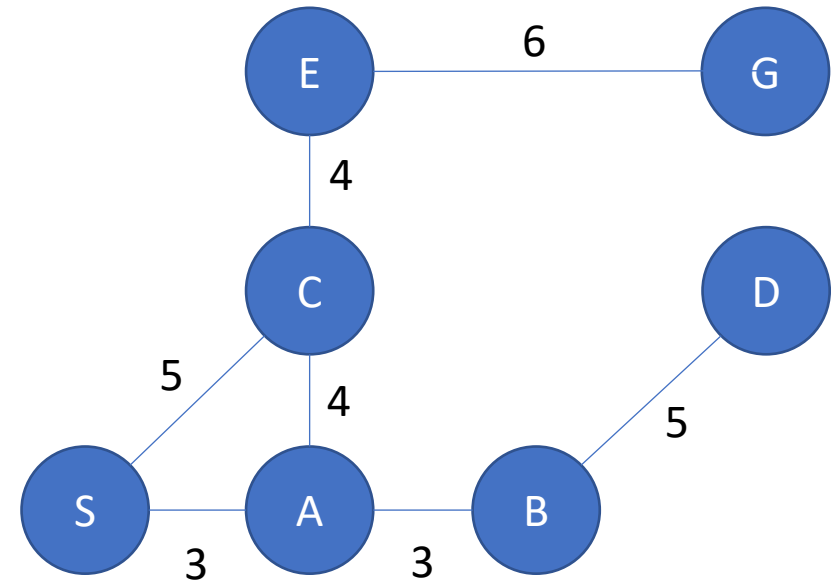


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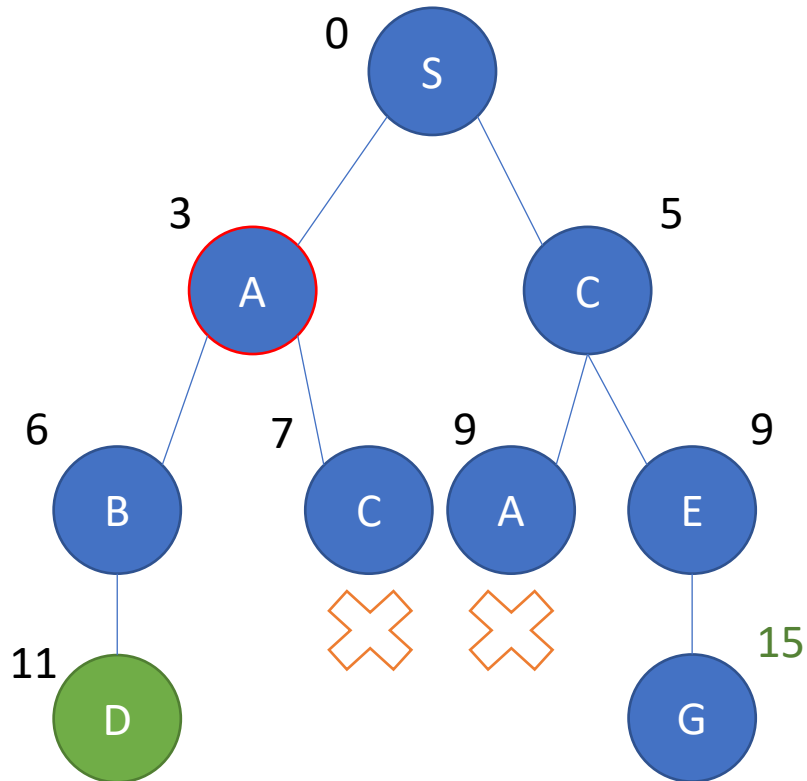


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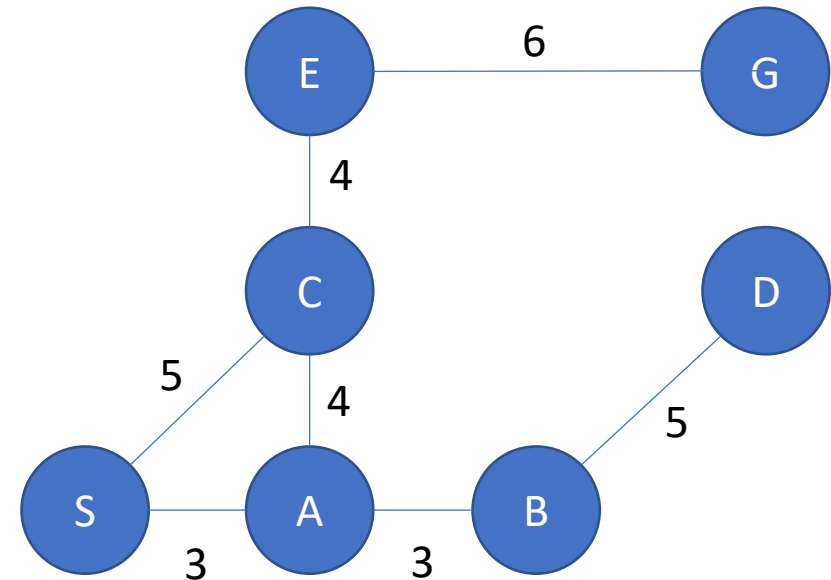


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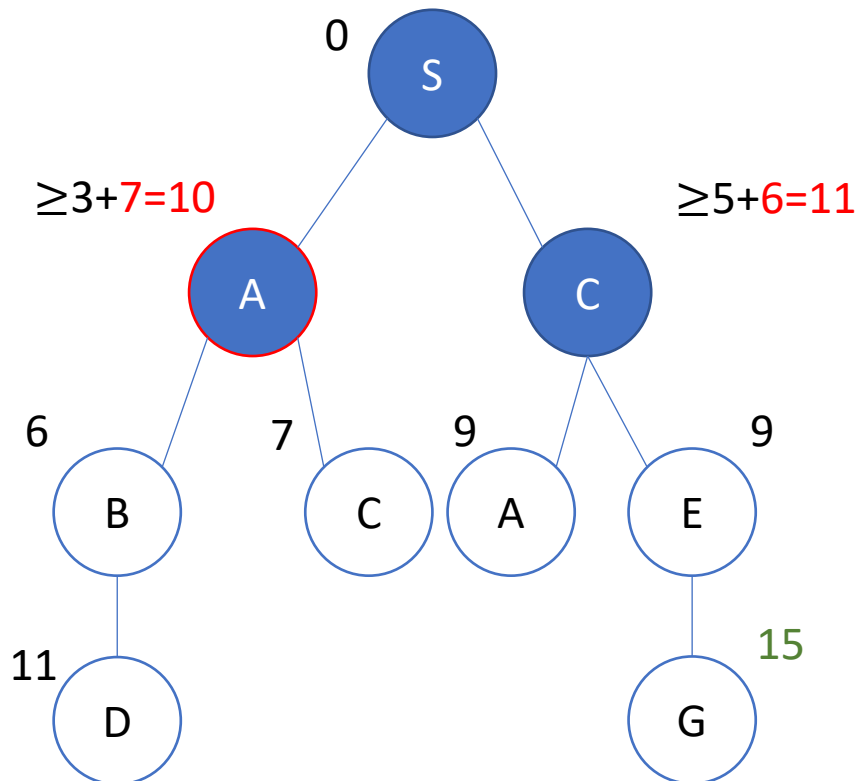
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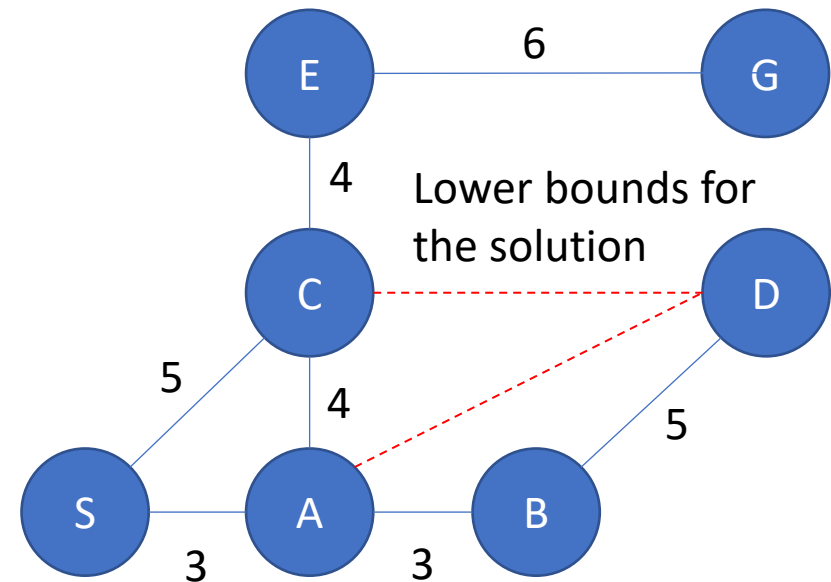
Dead horse principle

Branch and Bound

- Search tree



- Short path example for approach demonstration (S to D)



Dynamic programming

- Divide and concur vs DP
- Optimization problems
- Optimal solution structure description
- Initialization values
- Transition function
- Order

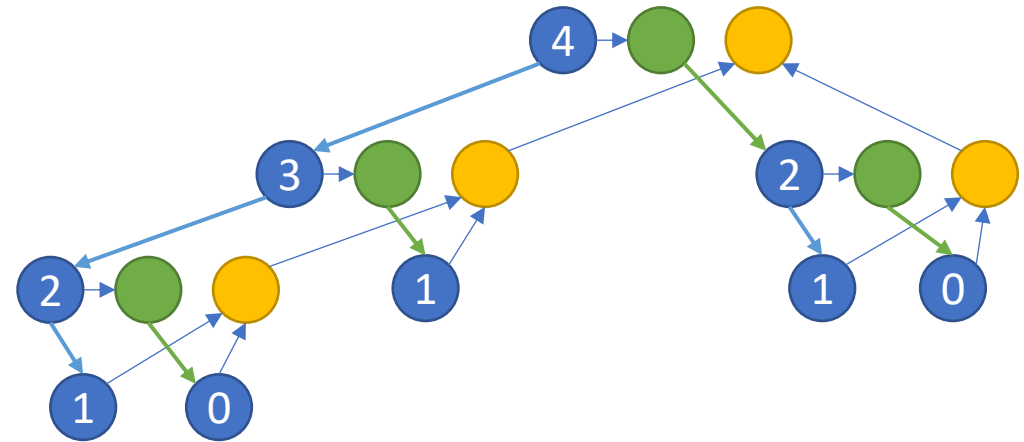
Idea: given a problem we don't know how to solve – split it into subproblems (we don't know how to solve either)

Dynamic programming

Fibonacci example:

```
def fib(n):  
    if (n <= 2):  
        return n  
    return fib(n-1)+fib(n-2)
```

- Fib(4)

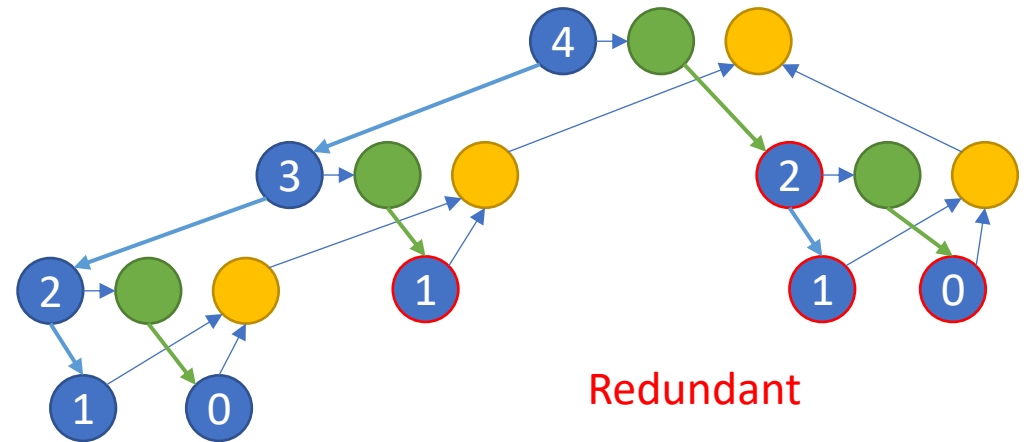


Dynamic programming

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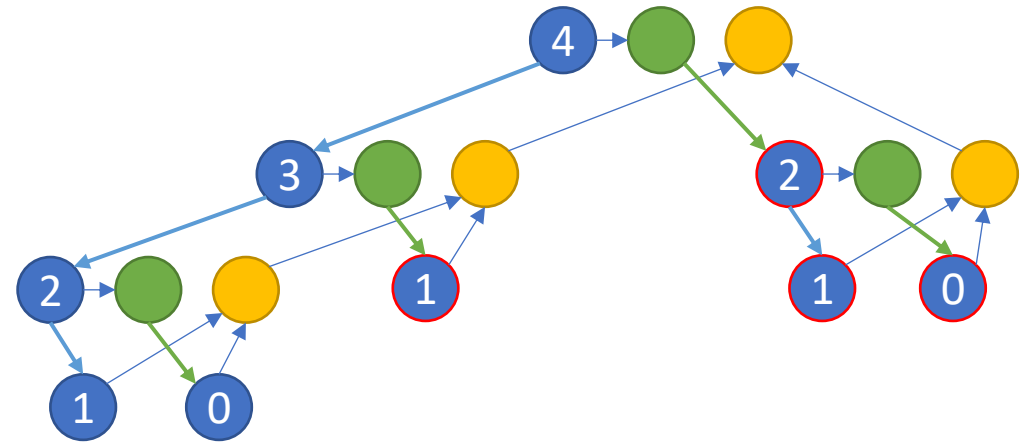


Dynamic programming

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Dynamic programming

- Forward order
- Backward order
- Lazy dynamic



Dynamic programming

- **Forward order**
- Backward order
- Lazy dynamic

```
fib[0] = fib[1] = 1
```

```
for (2..n):
```

```
    fib[i] = fib[i-1]+fib[i-2]
```



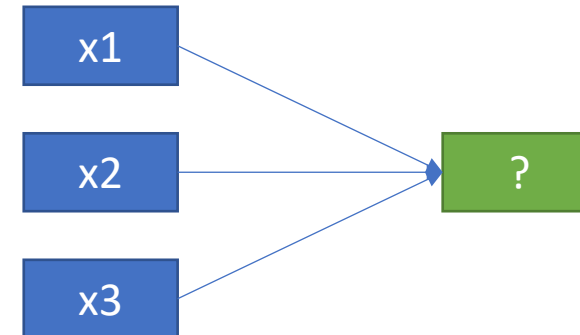
Dynamic programming

- **Forward order**
- Backward order
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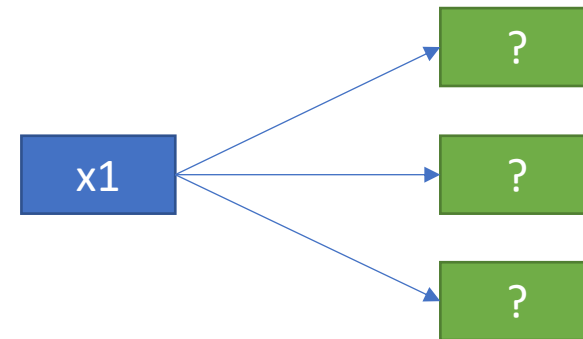
```
    fib[i] = fib[i-1]+fib[i-2]
```



Dynamic programming

- Forward order
- **Backward order**
- Lazy dynamic

```
fib[0] = 1
for (0..n):
    fib[i+1] += fib[i]
    fib[i+2] += fib[i]
```



Dynamic programming

- Forward order
- Backward order
- **Lazy dynamic**

```
def fib(i):  
    if i <= 2: return 1  
    if fib[i] == -1:  
        fib[i] =  
            fib(i-1)+fib(i-2)  
    return fib[i]
```



Example: numbers

Problem:

- Given positive N , calculate the number of permutations of length N that do not contain consequent ones (1 immediately followed by 1)

- 010010100

- 001101011

For $N = 2$: 00, 01, 10, 11 – the number of legal permutations is 3

Example: numbers

Problem:

- Given positive N, calculate the number of permutations of length N that do not contain consequent ones (1 immediately followed by 1)

$$\begin{cases} x_1 x_2 \dots x_{n-1} 0, -2 \text{ options } \{1, 0\} \\ x_1 x_2 \dots x_{n-1} 1, -1 \text{ option } \{0\} \end{cases}$$

Example: numbers

Problem:

- Given positive N, calculate the number of permutations of length N that do not contain consequent ones (1 immediately followed by 1)

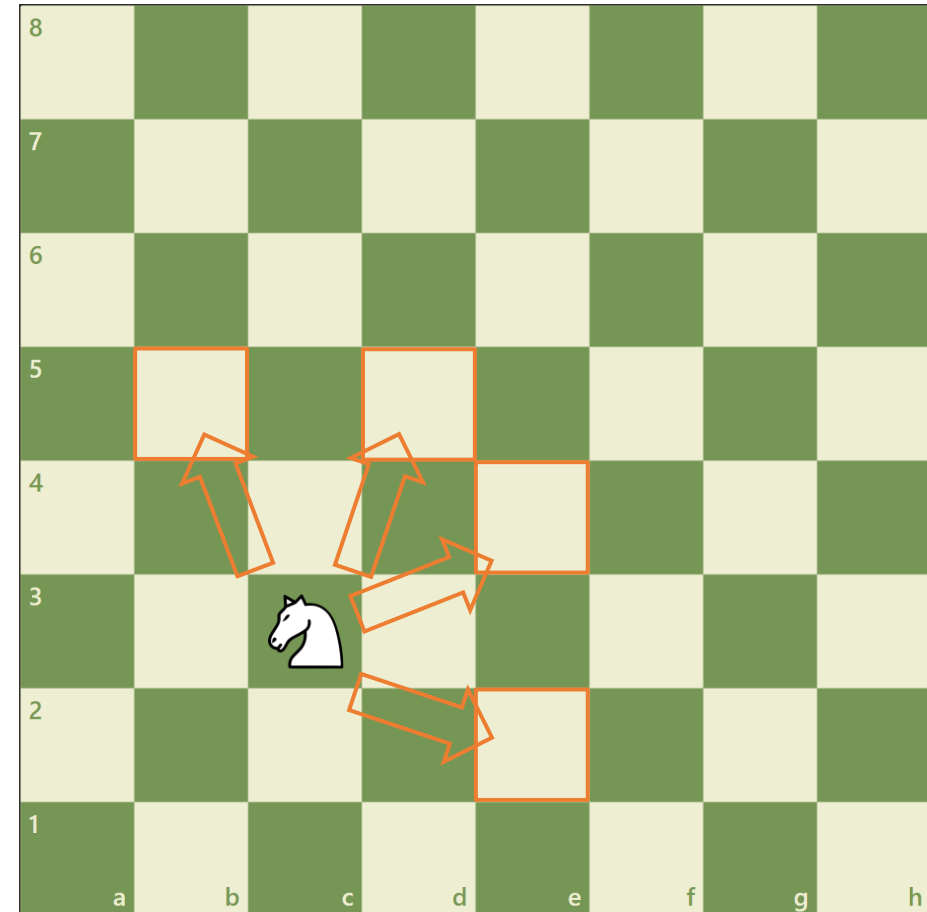
$$\begin{cases} x_1 x_2 \dots x_{n-1} 0, -2 \text{ options } \{1, 0\} \\ x_1 x_2 \dots x_{n-1} 1, -1 \text{ option } \{0\} \end{cases}$$

$$f(n) = f(n - 1) + f(n - 2)$$

Example: knight

Problem:

- How many possible ways to get from a1 to h8 when the knight moves as shown?

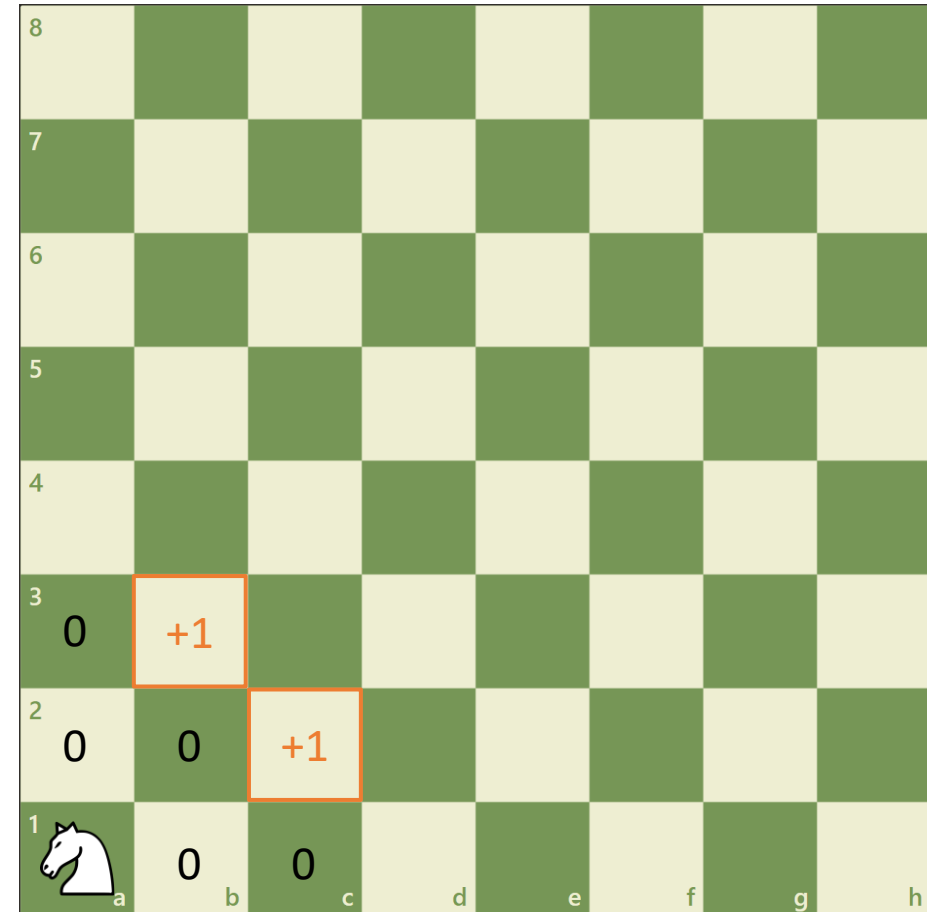


Board source: <https://www.chess.com/>

Example: knight

Problem:

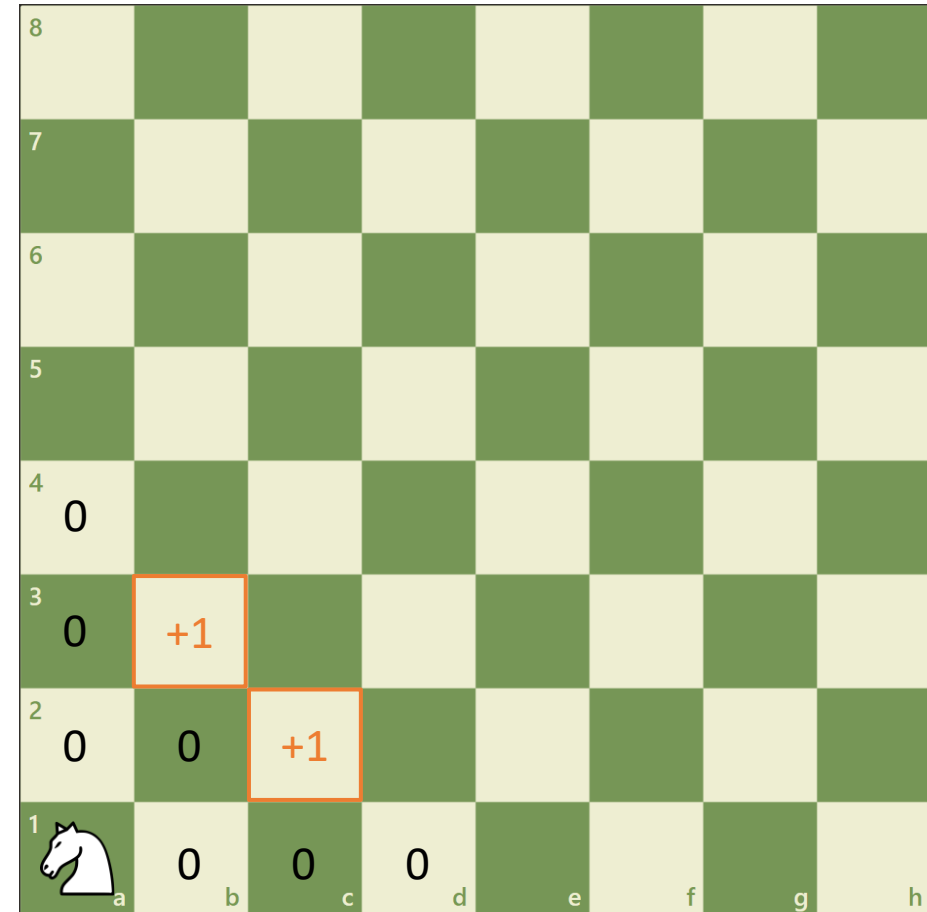
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Example: knight

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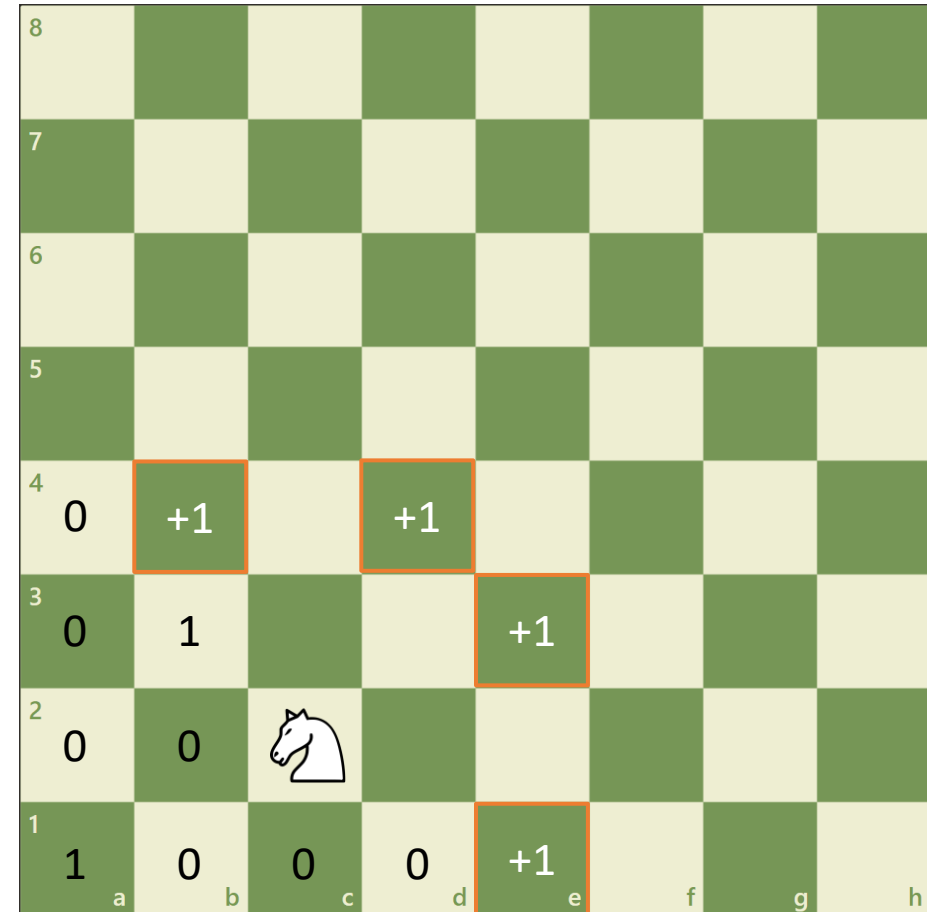
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Example: knight

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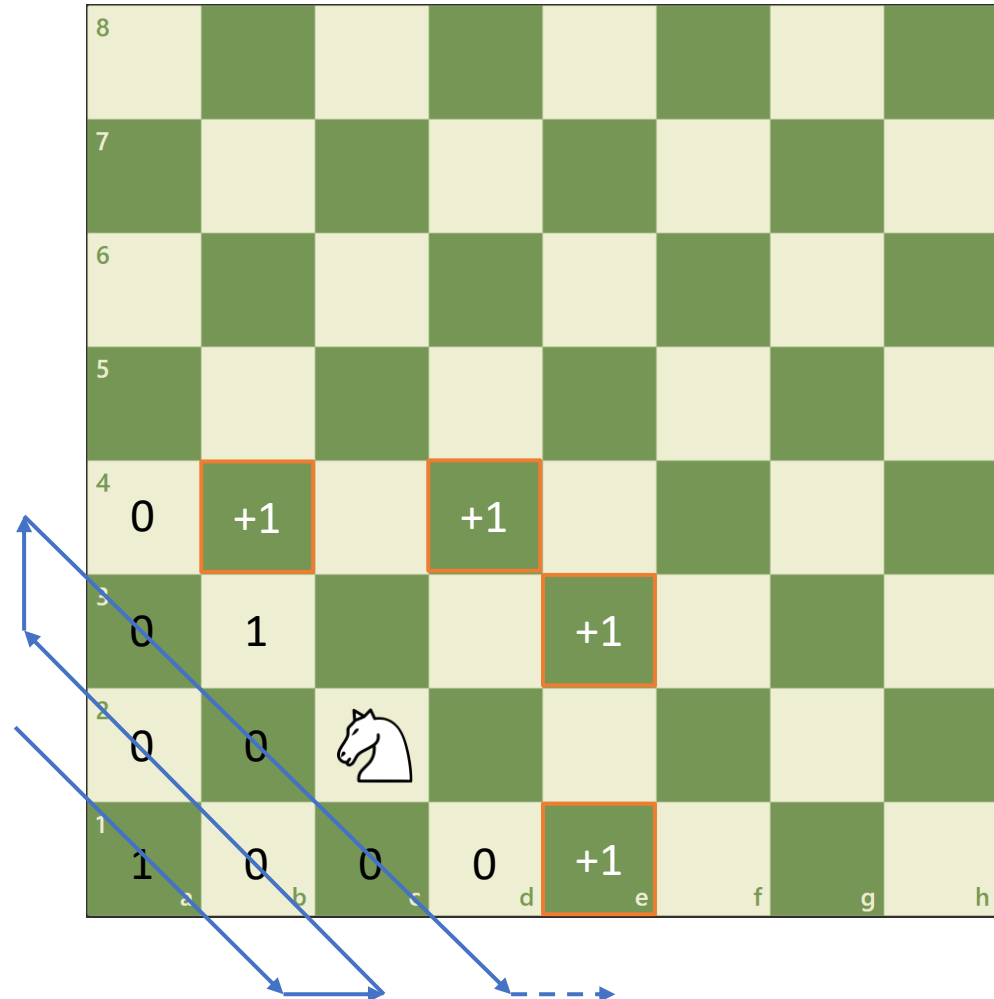
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Example: knight

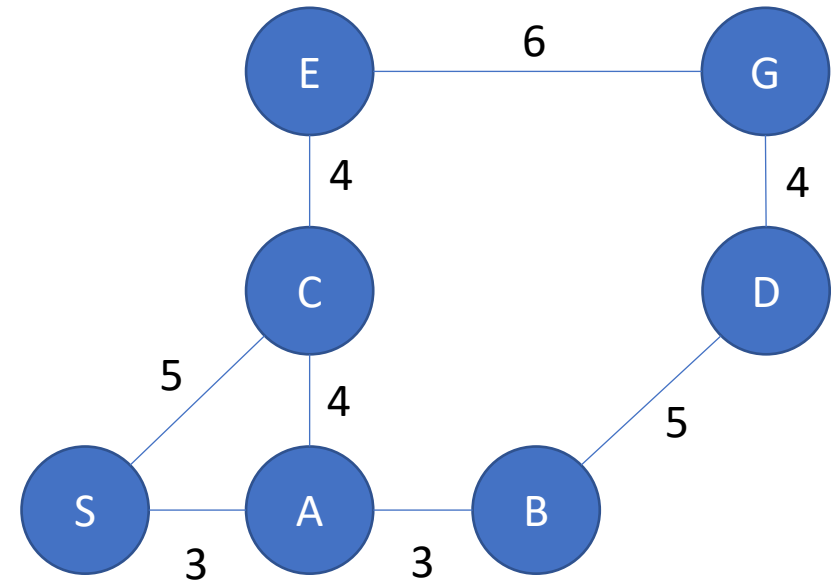
Problem:

- How many possible ways to get from a1 to h8 when the knight moves as shown?
- Backward order: take current position and update dependents
- Traverse order is important



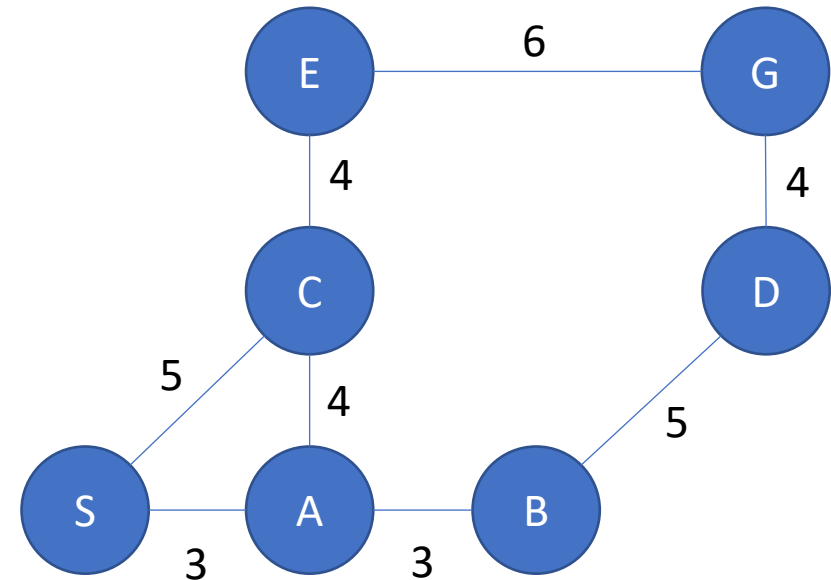
Example: Hamiltonian path (TSP)

- Hamiltonian path – graph that visits each vertex exactly once (example from [3])



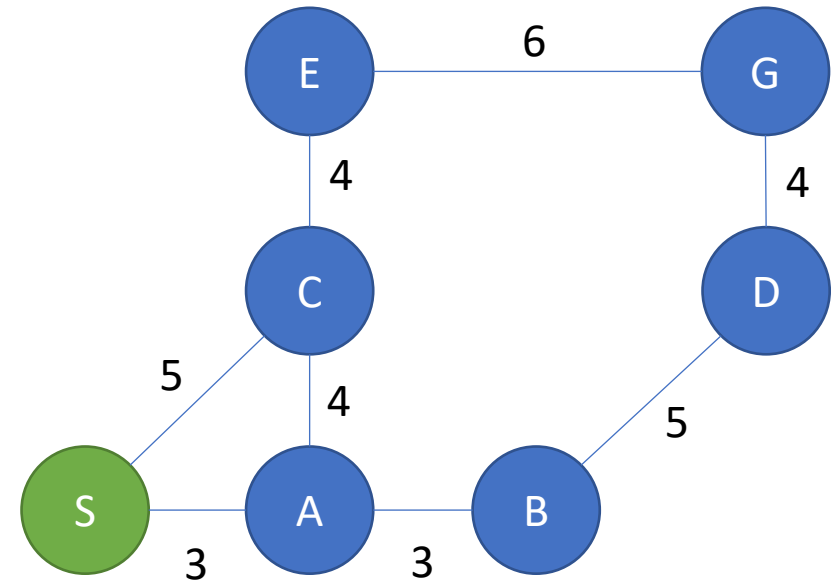
Example: Hamiltonian path (TSP)

- Hamiltonian path – graph that visits each vertex exactly once
- Idea: solve it for subgraphs



Example: Hamiltonian path (TSP)

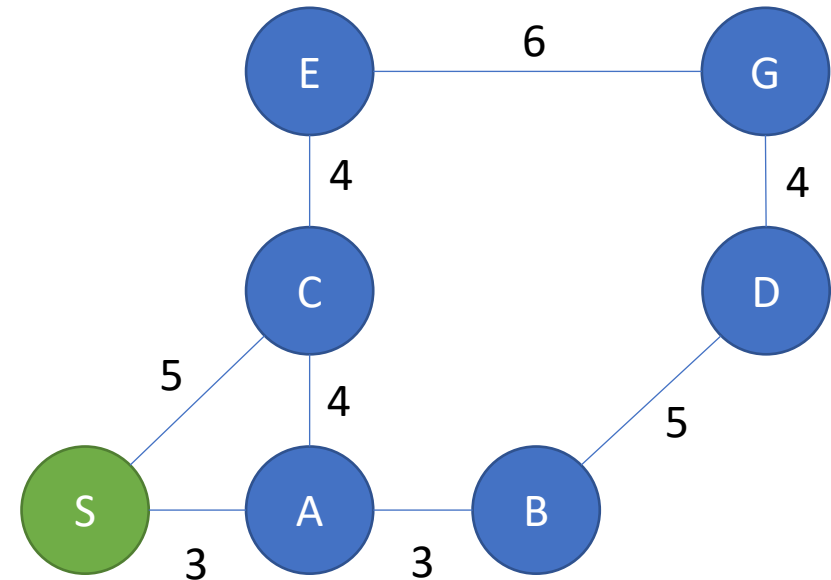
- Hamiltonian path – graph that visits each vertex exactly once
- Idea: solve it for subgraphs
- $res[mask, v] = \begin{cases} 0, & \text{for } S \\ \text{inf} & \end{cases}$,
mask describes whether a vertex is in the path or not.
- Result is in $res[111 \dots 1, 0]$



Example: Hamiltonian path (TSP)

- Hamiltonian path – graph that visits each vertex exactly once
- Idea: solve it for subgraphs
- $res[mask, v] = \begin{cases} 0, & \text{for } S \\ \infty & \end{cases}$
- Result in $res[111 \dots 1, 0]$
- $res[m, v] = \min(res[m, v], res[11\underbrace{0}_{\uparrow} \dots 1, i] + w(i, v))$

\uparrow
i'th mask
element



Resources

- [1] Introduction to Algorithms, Thomas H. Cormen, chapter 15
- [2] Universal sequential search problems
<http://www.cs.bu.edu/fac/Ind/dvi/ppi9-115.pdf>
- [3] Nice article on dynamic programming (rus)
<https://habr.com/ru/post/191498/>
- [4] MIT open courseware on DP: [course](#)
- [5] More on DP on mccme:
<https://informatics.mccme.ru/course/view.php?id=9>

BACKUP

