

TASK-1

With Understanding Identify The Scope, Advantages And Disadvantages Of The Given Searching Algorithm .

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Searching Technique	Scope	Constraints	Application
Linear Search	<ul style="list-style-type: none"> • Works on unsorted or sorted data. • Suitable for small datasets. • Useful when data structure does not support random access (e.g., linked lists). 	<ul style="list-style-type: none"> • Time complexity is $O(n)$ → slow for large datasets. • Cannot exploit sorted structure efficiently. • Not suitable for performance-critical applications. 	<ul style="list-style-type: none"> • Searching small unsorted lists. • Lookup in linked lists. • When the dataset is very small or rarely searched.
Binary Search	<ul style="list-style-type: none"> • Works only on sorted arrays/lists. • Efficient on static datasets with random access. 	<ul style="list-style-type: none"> • Requires sorted input. • Not suitable for linked lists unless modified. • Updates (insert/delete) are costly because sorting must be maintained. 	<ul style="list-style-type: none"> • Search in databases, dictionaries. • Finding elements in sorted arrays. • Used in libraries like <code>bisect()</code> in Python.
Depth-First Search (DFS)	<p>DFS goes deep along one path before backtracking.</p> <p>Used on:</p> <ul style="list-style-type: none"> • Graphs and Trees • Both directed and undirected graphs 	<ul style="list-style-type: none"> • Can get stuck in cycles without “visited” tracking • Recursive DFS may cause stack overflow for deep graphs • Takes longer to find shortest paths 	<ul style="list-style-type: none"> • Pathfinding in puzzles (mazes) • Detecting cycles in graphs • Topological sorting • Solving tree-based problems

Breadth-First Search (BFS)	<ul style="list-style-type: none"> Explores nodes level by level, making it perfect for finding the shortest path. Useful in real-world graphs like social networks and maps. Works for finite graphs and trees 	<ul style="list-style-type: none"> Requires large memory because all neighbors must be stored in a queue. Slower when the branching factor is very high. Not ideal for very deep graph 	<ul style="list-style-type: none"> Finding shortest path in unweighted graphs GPS navigation Social networks (friend recommendations) Web crawling
Hash-Based Search	<ul style="list-style-type: none"> Allows very fast searches ($O(1)$ average time). Used when you need instant lookup, such as dictionaries or symbol tables. Works best with unique keys and well-distributed hash functions. 	<ul style="list-style-type: none"> Hash collisions can reduce speed. Requires more memory (extra buckets and overhead). Performance depends heavily on quality of hash function. 	<ul style="list-style-type: none"> Databases indexing Language compilers (symbol tables) Password hashing and validation Implementing dictionaries/maps
Jump Search	<ul style="list-style-type: none"> A middle-ground between linear and binary search for sorted arrays. Uses fixed jumps to reduce search time in large datasets. Helpful in systems where jumping is faster than random access. 	<ul style="list-style-type: none"> Only works for sorted arrays. Slower compared to binary search in most cases. Choosing optimal jump size is required for best performance. 	<ul style="list-style-type: none"> Searching in large sorted lists Used where binary search overhead is expensive

Interpolation Search	<ul style="list-style-type: none"> Estimates the position of the target based on value distribution. Very fast when data is evenly spread (e.g., student roll numbers). Works only on sorted data with numeric or uniform keys. 	<ul style="list-style-type: none"> Performs poorly when values are clustered or unevenly distributed. Cannot be used with strings or unsorted data. Worst-case complexity becomes O(n) if distribution is bad. 	<ul style="list-style-type: none"> Searching in uniform numeric datasets Databases with evenly distributed keys Statistical lookup tables
Exponential Search	<ul style="list-style-type: none"> Useful when the array size is unknown or very large. Quickly finds a range using exponential jumps before applying binary search. Works for sorted lists, especially streaming or unbounded data sources. 	<ul style="list-style-type: none"> Needs random access (array). Inefficient for small datasets. Only works for sorted data. 	<ul style="list-style-type: none"> Searching in unbounded or infinite lists Used in online data streams Useful in exponentially growing data structures
Fibonacci Search	<ul style="list-style-type: none"> Similar to binary search but uses Fibonacci sequence to divide search range. Reduces comparisons in systems where memory access is costly. Best for sorted arrays stored in slow memory (e.g., old tapes). 	<ul style="list-style-type: none"> More complex to implement than binary search. Slightly slower in practice due to Fibonacci calculations. Only works on sorted lists. 	<ul style="list-style-type: none"> Searching when memory access is expensive Embedded systems Systems using sequential memory blocks (tapes)

Ternary Search	<ul style="list-style-type: none"> Splits data into three parts instead of two. Primarily used to find peak/minimum in unimodal functions. Works well in optimization problems. 	<ul style="list-style-type: none"> Not useful for regular array searching. Slower than binary search for discrete datasets. Requires the function to have only one peak or valley (unimodal). 	<ul style="list-style-type: none"> Optimization problems Finding minimum/maximum of mathematical functions AI algorithms requiring optimization
Sublist Search (KMP Algorithm)	<ul style="list-style-type: none"> Efficient for pattern matching in text (string search). Uses preprocessing to avoid re-checking characters. Works on very large texts. 	<ul style="list-style-type: none"> Needs preprocessing of pattern (computing lps table). Only applicable to sequential data like strings or lists. Higher initial setup cost for short searches. 	<ul style="list-style-type: none"> Text editors (Find/Replace) DNA/protein sequence analysis Search engines Plagiarism detection
A* Search Algorithm	<ul style="list-style-type: none"> Combines cost so far (g) + heuristic estimate (h) to find best path. Works on weighted graphs and maps. Finds shortest optimal paths if heuristic is correct. 	<ul style="list-style-type: none"> Requires a good heuristic; bad heuristic slows it down. Can use large amounts of memory (open/closed lists). Not ideal for extremely large graphs. 	<ul style="list-style-type: none"> Google Maps, GPS navigation Video game AI for pathfinding Robotics movement and planning Network routing protocols
Beam Search	<ul style="list-style-type: none"> Heuristic search that keeps only a limited number of best candidates. Useful in huge search problems where full exploration is impossible. Trades accuracy for speed. 	<ul style="list-style-type: none"> May miss the optimal solution due to limited beam width. Depends heavily on heuristics. Not guaranteed to find the best or even correct result. 	<ul style="list-style-type: none"> Speech recognition Machine Translation (NLP) Optimization problems Large decision-tree searches

Grover's Search Algorithm	<ul style="list-style-type: none"> • A quantum search algorithm that finds a target in \sqrt{n} time. • Works on unsorted databases better than classical methods. • Useful in fields needing massive search optimization. 	<ul style="list-style-type: none"> • Requires quantum computing hardware (not widely available). • Only gives quadratic speedup, not exponential. • Sensitive to quantum noise and decoherence. 	<ul style="list-style-type: none"> • Cryptography (breaking symmetric keys faster) • Searching quantum databases • Quantum AI and optimization
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