

### TASK-1

With Understanding Identify The Scope, Advantages And Disadvantages Of The Given Searching Algorithm .

Name: Kaushal Dahal

Reg No. : 2023006226

Searching Technique	Scope	Constraints	Application
Linear Search	<ul style="list-style-type: none"><li>• Works on <b>unsorted or sorted</b> data.</li><li>• Suitable for <b>small datasets</b>.</li><li>• Useful when data structure does not support random access (e.g., linked lists).</li></ul>	<ul style="list-style-type: none"><li>• <b>Time complexity is <math>O(n)</math></b> → slow for large datasets.</li><li>• Cannot exploit sorted structure efficiently.</li><li>• Not suitable for performance-critical applications.</li></ul>	<ul style="list-style-type: none"><li>• Searching small unsorted lists.</li><li>• Lookup in <b>linked lists</b>.</li><li>• When the dataset is very small or rarely searched.</li></ul>
Binary Search	<ul style="list-style-type: none"><li>• Works only on <b>sorted arrays/lists</b>.</li><li>• Efficient on static datasets with random access.</li></ul>	<ul style="list-style-type: none"><li>• Requires <b>sorted input</b>.</li><li>• <b>Not suitable</b> for linked lists unless modified.</li><li>• Updates (insert/delete) are costly because sorting must be maintained.</li></ul>	<ul style="list-style-type: none"><li>• Search in <b>databases, dictionaries</b>.</li><li>• Finding elements in sorted arrays.</li><li>• Used in libraries like <code>bisect()</code> in Python.</li></ul>
Depth-First Search (DFS)	DFS goes <b>deep along one path</b> before backtracking. Used on: <ul style="list-style-type: none"><li>• <b>Graphs and Trees</b></li><li>• Both directed and undirected graphs</li></ul>	<ul style="list-style-type: none"><li>• Can get stuck in cycles without “visited” tracking</li><li>• Recursive DFS may cause <b>stack overflow</b> for deep graphs</li><li>• Takes longer to find shortest paths</li></ul>	<ul style="list-style-type: none"><li>• Pathfinding in puzzles (mazes)</li><li>• Detecting cycles in graphs</li><li>• Topological sorting</li><li>• Solving tree-based problems</li></ul>

<b>Breadth-First Search (BFS)</b>	<ul style="list-style-type: none"> <li>• Explores nodes <b>level by level</b>, making it perfect for finding the <b>shortest path</b>.</li> <li>• Useful in real-world graphs like social networks and maps.</li> <li>• Works for finite graphs and trees</li> </ul>	<ul style="list-style-type: none"> <li>• Requires <b>large memory</b> because all neighbors must be stored in a queue.</li> <li>• Slower when the branching factor is very high.</li> <li>• Not ideal for very deep graph</li> </ul>	<ul style="list-style-type: none"> <li>• Finding <b>shortest path in unweighted graphs</b></li> <li>• GPS navigation</li> <li>• Social networks (friend recommendations)</li> <li>• Web crawling</li> </ul>
<b>Hash-Based Search</b>	<ul style="list-style-type: none"> <li>• Allows <b>very fast searches</b> (<math>O(1)</math> average time).</li> <li>• Used when you need instant lookup, such as dictionaries or symbol tables.</li> <li>• Works best with <b>unique keys</b> and well-distributed hash functions.</li> </ul>	<ul style="list-style-type: none"> <li>• Hash collisions can reduce speed.</li> <li>• Requires more memory (extra buckets and overhead).</li> <li>• Performance depends heavily on quality of hash function.</li> </ul>	<ul style="list-style-type: none"> <li>• Databases indexing</li> <li>• Language compilers (symbol tables)</li> <li>• Password hashing and validation</li> <li>• Implementing dictionaries/maps</li> </ul>
<b>Jump Search</b>	<ul style="list-style-type: none"> <li>• A middle-ground between linear and binary search for <b>sorted arrays</b>.</li> <li>• Uses fixed jumps to reduce search time in large datasets.</li> <li>• Helpful in systems where jumping is faster than random access.</li> </ul>	<ul style="list-style-type: none"> <li>• Only works for <b>sorted</b> arrays.</li> <li>• Slower compared to binary search in most cases.</li> <li>• Choosing optimal jump size is required for best performance.</li> </ul>	<ul style="list-style-type: none"> <li>• Searching in large sorted lists</li> <li>• Used where binary search overhead is expensive</li> </ul>

<b>Interpolation Search</b>	<ul style="list-style-type: none"> <li>Estimates the position of the target based on <b>value distribution</b>.</li> <li>Very fast when data is <b>evenly spread</b> (e.g., student roll numbers).</li> <li>Works only on sorted data with numeric or uniform keys.</li> </ul>	<ul style="list-style-type: none"> <li>Performs poorly when values are <b>clustered</b> or unevenly distributed.</li> <li>Cannot be used with strings or unsorted data.</li> <li>Worst-case complexity becomes <math>O(n)</math> if distribution is bad.</li> </ul>	<ul style="list-style-type: none"> <li>Searching in uniform numeric datasets</li> <li>Databases with evenly distributed keys</li> <li>Statistical lookup tables</li> </ul>
<b>Exponential Search</b>	<ul style="list-style-type: none"> <li>Useful when the array size is <b>unknown</b> or very large.</li> <li>Quickly finds a range using exponential jumps before applying binary search.</li> <li>Works for sorted lists, especially streaming or unbounded data sources.</li> </ul>	<ul style="list-style-type: none"> <li>Needs random access (array).</li> <li>Inefficient for small datasets.</li> <li>Only works for <b>sorted</b> data.</li> </ul>	<ul style="list-style-type: none"> <li>Searching in <b>unbounded</b> or <b>infinite lists</b></li> <li>Used in online data streams</li> <li>Useful in exponentially growing data structures</li> </ul>
<b>Fibonacci Search</b>	<ul style="list-style-type: none"> <li>Similar to binary search but uses Fibonacci sequence to divide search range.</li> <li>Reduces comparisons in systems where memory access is costly.</li> <li>Best for sorted arrays stored in slow memory (e.g., old tapes).</li> </ul>	<ul style="list-style-type: none"> <li>More complex to implement than binary search.</li> <li>Slightly slower in practice due to Fibonacci calculations.</li> <li>Only works on sorted lists.</li> </ul>	<ul style="list-style-type: none"> <li>Searching when memory access is expensive</li> <li>Embedded systems</li> <li>Systems using sequential memory blocks (tapes)</li> </ul>

<b>Ternary Search</b>	<ul style="list-style-type: none"> <li>• Splits data into three parts instead of two.</li> <li>• Primarily used to find peak/minimum in <b>unimodal</b> functions.</li> <li>• Works well in optimization problems.</li> </ul>	<ul style="list-style-type: none"> <li>• Not useful for regular array searching.</li> <li>• Slower than binary search for discrete datasets.</li> <li>• Requires the function to have only <b>one peak or valley</b> (unimodal).</li> </ul>	<ul style="list-style-type: none"> <li>• Optimization problems</li> <li>• Finding minimum/maximum of mathematical functions</li> <li>• AI algorithms requiring optimization</li> </ul>
<b>Sublist Search (KMP Algorithm)</b>	<ul style="list-style-type: none"> <li>• Efficient for <b>pattern matching</b> in text (string search).</li> <li>• Uses preprocessing to avoid re-checking characters.</li> <li>• Works on very large texts.</li> </ul>	<ul style="list-style-type: none"> <li>• Needs preprocessing of pattern (computing lps table).</li> <li>• Only applicable to sequential data like strings or lists.</li> <li>• Higher initial setup cost for short searches.</li> </ul>	<ul style="list-style-type: none"> <li>• Text editors (Find/Replace)</li> <li>• DNA/protein sequence analysis</li> <li>• Search engines</li> <li>• Plagiarism detection</li> </ul>
<b>A* Search Algorithm</b>	<ul style="list-style-type: none"> <li>• Combines cost so far (<b>g</b>) + heuristic estimate (<b>h</b>) to find best path.</li> <li>• Works on weighted graphs and maps.</li> <li>• Finds <b>shortest optimal paths</b> if heuristic is correct.</li> </ul>	<ul style="list-style-type: none"> <li>• Requires a <b>good heuristic</b>; bad heuristic slows it down.</li> <li>• Can use large amounts of memory (open/closed lists).</li> <li>• Not ideal for extremely large graphs.</li> </ul>	<ul style="list-style-type: none"> <li>• Google Maps, GPS navigation</li> <li>• Video game AI for pathfinding</li> <li>• Robotics movement and planning</li> <li>• Network routing protocols</li> </ul>
<b>Beam Search</b>	<ul style="list-style-type: none"> <li>• Heuristic search that keeps only a limited number of best candidates.</li> <li>• Useful in huge search problems where full exploration is impossible.</li> <li>• Trades accuracy for speed.</li> </ul>	<ul style="list-style-type: none"> <li>• May miss the optimal solution due to limited beam width.</li> <li>• Depends heavily on heuristics.</li> <li>• Not guaranteed to find the best or even correct result.</li> </ul>	<ul style="list-style-type: none"> <li>• Speech recognition</li> <li>• Machine Translation (NLP)</li> <li>• Optimization problems</li> <li>• Large decision-tree searches</li> </ul>

<b>Grover's Search Algorithm</b>	<ul style="list-style-type: none"><li>• A quantum search algorithm that finds a target in <math>\sqrt{n}</math> time.</li><li>• Works on unsorted databases better than classical methods.</li><li>• Useful in fields needing massive search optimization.</li></ul>	<ul style="list-style-type: none"><li>• Requires quantum computing hardware (not widely available).</li><li>• Only gives quadratic speedup, not exponential.</li><li>• Sensitive to quantum noise and decoherence.</li></ul>	<ul style="list-style-type: none"><li>• Cryptography (breaking symmetric keys faster)</li><li>• Searching quantum databases</li><li>• Quantum AI and optimization</li></ul>
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