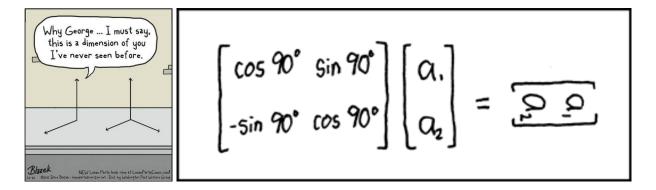
Notes: Computational Linear Algebra



1 Introduction

These notes review the background material from linear algebra and data structures needed to understand data mining. They focus on runtime concepts that you may not have covered in your previous classes, but should hopefully be easy to grasp. You are not required to complete and submit the problems in this packet, but the problems on the midterm will be very similar, so I strongly recommend you complete all of these problems.

NOTE: If you find any errors in these notes (or any other class material), you can get extra credit by submitting a pull request to github fixing the error.

2 Linear Algebra Basics

Many students struggle in this course with basic linear algebra concepts like the rank of a matrix and eigenvalues. If you would like more background on these topics, I recommend watching the 3blue1brown videos on linear algebra:

https://www.3blue1brown.com/essence-of-linear-algebra-page

The eigenvalue video is the most important:

https://www.youtube.com/watch?v=PFDu9oVAE-g

3 Big-O/ Θ/Ω Notation

You are likely familiar with asymptotic notation from your data structures class, where you used it to measure the time and space complexity of algorithms. In this class, we will also be measuring statistical complexity of algorithms. The statistical complexity will result in formulas a bit more complex than you have likely seen before, and so you will need to be intimately familiar with the formal definitions of asymptotic notation. There are many equivalent definitions, but in this class, we will use the following.

Definition 1. Let f, g be (possibly multivariate) functions from $(\mathbb{R}^+)^d \to \mathbb{R}^+$, where d > 0 is an integer that specifies the number of input variables. Then,

1. If
$$\lim_{\mathbf{x}\to\infty}\frac{f(\mathbf{x})}{g(\mathbf{x})}<\infty$$
, then we say $f=O(g)$.

2. If
$$\lim_{\mathbf{x}\to\infty} \frac{f(\mathbf{x})}{g(\mathbf{x})} > 0$$
, then we say $f = \Omega(g)$.

3. We say that $f = \Theta(g)$ if both f = O(g) and $f = \Omega(g)$.

Intuitively, you should think of O as \leq , Ω as \geq , and Θ as =.

Problem 1. Complete each equation below by adding the symbol O if f = O(g), Ω if $f = \Omega(g)$, or Θ if $f = \Theta(g)$. The first row is completed for you as an example.

f(n)		g(n)
1	=	O(n)
$3n\log n$	=	n^2
1	=	1/n
$\log_2 n$	=	$\log_3 n$
$\log n$	=	$\frac{1}{\log n}$
$5 \cdot 10^{30}$	=	$\log n$
$\log n$	=	$\log(n^2)$
2 ⁿ	=	3 ⁿ
$\frac{1}{n}$	=	$\sqrt{\frac{1}{n}}$
$\log n$	=	$(\log n)^2$

Problem 2. Complete each equation below by adding the symbol O if f = O(g), Ω if $f = \Omega(g)$, or Θ if $f = \Theta(g)$. If f cannot be related to g using asymptotic notation, draw a slash through the equals sign. The first row is completed for you as an example.

f(a,b,c)		g(a,b,c)
ab	=	$\Omega(b)$
a^2b	=	ab^2
$a \log b$	=	a^b
a^2bc^3	=	$a^2b^2c^3$
$rac{a}{b}$	=	$rac{a}{b^2}$
$rac{a}{b}$	=	$(rac{a}{b})^2$
a^b	=	b^a
a^b	=	$(\log a)^c$
a^b	=	$(1+c)^a$

The main advantage of asymptotic notation is that it lets us write complex formulas in simpler forms, focusing only on the "most important" parts.

 $\bf Problem~3.$ Simplify the following expressions:

1.
$$O\left(n^3 + 5n^2 \log n + \log n\right)$$

2.
$$O\left(ab^2 + 3a^2b + ab + 10b\right)$$

3.
$$O\left(a+b+c+ab+bc+abc\right)$$

$$4. \ O\left(\frac{1}{n} + \frac{1}{n^2}\right)$$

$$5. \ O\left(\frac{1}{n} + \frac{1}{nm} + \frac{1}{m}\right)$$

4 BLAS

The Basic Linear Algebra Subprogram (BLAS) is a standard interface for simple vector and matrix operations. BLAS libraries are written in low-level languages like Assembly, C, Fortran, and CUDA. PyTorch provides an "easy to use" interface to these BLAS operations. We will gloss over many technical details in these notes and focus on high-level asymptotic runtimes.

4.1 Notation

We will typically use capital letters (A, B, C) to denote matrices, bold lower case letters $(\mathbf{x}, \mathbf{y}, \mathbf{z})$ to denote vectors, and lower case italics letters (n, m, o) to denote scalars.

4.2 Dense vs Sparse Matrices

Mathematicians define a sparse matrix to be any matrix with a large number of zero entries relative to the total number of entries, and a dense matrix to be any matrix with few zeros. There is no strict cut-off here, but it's typical for a sparse matrix to have < 1% of its entries be zero. We will use the function nnz(A) to represent the total Number of Non Zero values of the matrix $A : \mathbb{R}^{m \times n}$.

Problem 4. What is the nnz of the following matrices?

$$A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix}$$
 nnz(A) =

$$B = \begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix} \qquad \text{nnz}(B) =$$

$$C = \begin{pmatrix} 0.0 & 0.1 & 0.2 \\ 0.3 & 0.4 & 0.5 \end{pmatrix}$$
 nnz(C) =

Problem 5. Describe data structures optimized for sparse and dense matrices.

4.3 Memory Usage

If A is stored as a sparse matrix, the memory usage is $\Theta(\text{nnz}(A))$. If A is stored as a dense matrix, the memory usage is $\Theta(mn)$.

Problem 6. Prove or provide a counter example. For both sparse and dense matrices, the storage requirements are O(mn).



4.4 BLAS Level 1

BLAS Level 1 routines are for linear algebra operations that only involve vectors. These include the dot product, vector norms, addition, and scalar multiplication.

These are fully implemented in PyTorch for both sparse and dense vectors. For dense vectors of length n, the runtime of all operations is $\Theta(n)$. For sparse vectors, all operations of a single vector \mathbf{x} take time $\Theta(\operatorname{nnz}(\mathbf{x}))$ and all operations of two vectors \mathbf{x} and \mathbf{y} take time $\Theta(\operatorname{nnz}(\mathbf{x}) + \operatorname{nnz}(\mathbf{y}))$.

Problem 9. What is the runtime of the following expressions?

1. $5 \cdot \mathbf{x}$

2. $0 \cdot \mathbf{x}$

3. $\mathbf{x}^T \mathbf{y}$

4. $\|\mathbf{x}\|_1$

Problem 10. What is the formula for the following vector norms? What is the runtime for computing these formula in both the sparse and dense case?

$$1. \ \left\| \mathbf{x} \right\|_1 =$$

$$2.\ \left\| \mathbf{x} \right\|_2 =$$

3.
$$\|\mathbf{x}\|_{\infty} =$$

4.5 BLAS Level 2

BLAS Level 2 routines are for vector-matrix operations. The main examples are the products $A\mathbf{x}$ and $\mathbf{x}A$. Up to constant factors, these operations have the same run times as the BLAS level 3 operations, so we will only discuss the level 3 operations below.

4.6 BLAS Level 3

BLAS Level 3 routines are for matrix-matrix operations. Let $A : \mathbb{R}^{m \times n}$ and $B : \mathbb{R}^{n \times o}$. Note that when o = 1, then B is a vector, and so BLAS Level 3 operations can be used to implement BLAS Level 2 operations.

For dense matrices, matrix multiplication AB takes time O(mno). This is often referred to as a "cubic" runtime because when the multiplied matrices are square, and thus m=n=o, the runtime is $O(n^3)$. There are good algorithms that take potentially much less time than this, with the best known taking time $O(n^{2\cdot2\cdot371552})$. No BLAS implementation that I know of actually implements this algorithm due to the very high constant factor, and Strassen's algorithm with runtime $\Theta(n^{\log_2 7}) \approx \Theta(n^{2\cdot807})$ is the most commonly used algorithm. Currently, we know that matrix multiplication takes at least time $\Omega(n^2 \log n)$, and it is an open problem what the optimal runtime for matrix multiplication is. The following wikipedia link has more details:

https://en.wikipedia.org/wiki/Computational_complexity_of_matrix_multiplication

For sparse matrices, PyTorch has only limited support for BLAS Level 2/3. In particular, PyTorch allows the first matrix to be either sparse or dense, but the second matrix must be dense. The runtime in the sparse case is $\Theta(\text{nnz}(A)o)$. The output is always a dense tensor.

For both sparse and dense matrices, the runtime of computing the transpose is $\Theta(1)$. The runtime of addition is linear in the memory usage of the vectors.

Note 1. For the following problems, always assume that the dimensions match so that the expressions are well defined. You will have to specify the dimensions.

Problem 11. What is the runtime of the following expressions? You should report the answer for every possible combination of sparse/dense matrices.

1. 3*A*

2. A + B

3. *AB*

4. Ax

5. $\mathbf{x}A$

Problem 12. Many systems that implement sparse matrices offer only limited support in the same way that PyTorch does. The reason is that the sparsity of the matrix product AB is impossible to predict from the sparsity of just A and B. In this problem, you will prove this fact by example. Your task is to construct a family of $m \times m$ matrices A and B such that

$$nnz(AB) = O(1) \quad and \quad nnz(BA) = \Omega(m^2). \tag{1}$$

4.7 Matrix Chain Ordering Problem (MCOP)

Matrix multiplication is famously not commutative, but it is associative. That is, no matter where you place the parentheses, you will get the same answer. Computationally, however, some choices of parentheses can be much better than others.

Problem 13. Let $A : \mathbb{R}^{m \times n}$, $B : \mathbb{R}^{n \times o}$, $C : \mathbb{R}^{o \times p}$.

1. What is the runtime of computing (AB)C?

2. What is the runtime of computing A(BC)?

3. Under what conditions would you choose the former parenthesization over the latter?

Problem 14. Recall that in PyTorch, only the first matrix in a matrix multiplication can be sparse, and the second must be dense. It is still possible to compute the product ABC if any one of the matrices is dense and the other two are sparse. For example, if A and B are sparse, then the parenthesization A(BC) can be computed in PyTorch. How should you rewrite the multiplication ABC so that it can be computed when both A and C are sparse?

Hint: You can swap the order of matrix multiplications by using the fact that for any two matrices X and Y, $XY = (Y^TX^T)^T$.

The Matrix Chain Ordering Problem (MCOP) is the problem of finding the optimal ordering of parentheses for a given sequence of n matrices. There is a classic dynamic programming solution to this problem that takes time $\Theta(n^3)$. (It's important to note that the n here refers to the number of matrices, not the dimensions of any given matrices.) Many more complicated algorithms exist for solving MCOP, the best of which currently takes time $\Theta(n \log n)$. The best known lower bound for MCOP is $\Omega(n)$, and it is therefore an open problem whether MCOP can be solved in linear time.

Note: The Θ and Ω notation above is correct. It should be "obvious" why these values are consistent with each other and do not contradict the definitions of Θ and Ω .

Problem 15. Parenthesization becomes critical when the matrices are vectors. What is the optimal way to parenthesize the expressions:

1.
$$\mathbf{x}^T \mathbf{x} \mathbf{x}^T \mathbf{x}$$
?

2.
$$\mathbf{x}\mathbf{x}^T\mathbf{x}\mathbf{x}^T$$
?

¹In mathematics, the word *obvious* has a different meaning than ordinary English. In mathematics, it means that the claim follows directly from the definitions. It still might take you 20-30 minutes of thinking about the definitions to verify the claim, however.

Problem 16. Based on your solution to Problem above, what is the asymptotically fastest way to compute the following expression

$$\prod_{i=1}^{n} (\mathbf{x}\mathbf{x}^{T}) \tag{2}$$

5 Beyond BLAS

Let $A : \mathbb{R}^{n \times n}$. The matrix inverse A^{-1} and matrix determinant $\det(A)$ can both be computed in time $O(n^3)$. There are asymptotically faster algorithms for computing these runtimes, but they are less important than the matrix multiplication algorithms. The runtime of computing the top-k eigenvectors and eigenvalues is $O(kn^2)$.

For each of these operations, PyTorch has full support for dense matrices, but no support for sparse matrices.

Problem 17. Let $A : \mathbb{R}^{m \times n}$, $\mathbf{x} : \mathbb{R}^n$, and $\lambda : \mathbb{R}$. Assume that A and \mathbf{x} are dense. What is the runtime for computing the following expressions?

1. A^{-1} **x**

²In the next set of notes, we will see that the pagerank technique is equivalent to computing the top eigenvalue of a matrix. We will then explore several algorithms for computing eigenvalues that have faster but more complex runtime expressions. For this set of notes, however, just assume that computing the top-k eigenvectors takes time $O(kn^2)$ as stated above.

$$2. \ (AA^T)^{-1}A\mathbf{x}$$

3. $A(A^TA)^{-1}$

4. $\|AA^TA\mathbf{x}\|_F^2$

5. $\|(\lambda I + A)\mathbf{x}\mathbf{x}^T\|_F$

Note that I is the identity matrix. For the expression above to be well defined, m must be equal to n.