#Import some libraries to perform some calculations, visualization, plotting, remove warnings and other usage of functions import pandas as pd import matplotlib.pyplot as plt import seaborn as sns from scipy import stats import numpy as np import warnings warnings.filterwarnings("ignore")

#Load the train dataset of CAR and stored in variable called car:

car = pd.read_csv('/content/train_qWM28Y1.csv')

	policy_id	policy_tenure	age_of_car	age_of_policyholder	area_cluster	population_density	make	segment	model	fuel_type	is_brake_assist	is_power
0	ID00001	0.515874	0.05	0.644231	C1	4990	1	А	M1	CNG	 No	
1	ID00002	0.672619	0.02	0.375000	C2	27003	1	А	M1	CNG	 No	
2	ID00003	0.841110	0.02	0.384615	C3	4076	1	А	M1	CNG	 No	
	ID00004	0.900277		0.432692	C4	21622			M2	Petrol		
4	ID00005	0.596403	0.11	0.634615	C5	34738	2	А	МЗ	Petrol	 No	
58587	ID58588	0.355089	0.13	0.644231	C8	8794	2	А	М3	Petrol	 No	
58588	ID58589	1.199642	0.02	0.519231	C14	7788	1	А	M1	CNG	 No	
58589	ID58590	1.162273	0.05	0.451923	C5	34738	1	А	M1	CNG	 No	
58590	ID58591	1.236307	0.14	0.557692	C8	8794	1	B2	M6	Petrol	 Yes	
58591	ID58592	0.124429	0.02	0.442308	C8	8794	3	C2	M4	Diesel	 Yes	

58592 rows × 44 columns

▼ Basic Pandas

 $\# This\ command\ gives\ the\ information\ of\ given\ dataset:$

<class 'pandas.core.frame.DataFrame'>

car.info()

```
RangeIndex: 58592 entries, 0 to 58591
Data columns (total 44 columns):
# Column
                                                      Non-Null Count Dtype
0 policy_id
                                                      58592 non-null object
      policy_tenure
                                                      58592 non-null float64
 2 age_of_car
                                                     58592 non-null float64
      age_of_policyholder
                                         58592 non-null float64
58592 non-null object
58592 non-null int64
58592 non-null int64
58592 non-null object
                                                     58592 non-null float64
     area cluster
5 population_density
     make
      segment
 8 model
      fuel_type
 10 max_torque
 11 max_power
 12 engine_type
 13 airbags

      14
      is_esc
      58592 non-null object

      15
      is_adjustable_steering
      58592 non-null object

      16
      is_tpms
      58592 non-null object

      17
      is_parking_sensors
      58592 non-null object

      18
      is_parking_camera
      58592 non-null object

      19
      rear_brakes_type
      58592 non-null int64

      20
      displacement
      58592 non-null int64

                                          58592 non-null int64
58592 non-null object
58592 non-null int64
 21 cylinder
 22 transmission_type
                                                      58592 non-null object
 23 gear_box
 24 steering_type
                                                     58592 non-null object
      turning_radius
                                                      58592 non-null float64
 26 length
 27 width
                                                      58592 non-null int64
                                                      58592 non-null int64
 28 height
 29 gross_weight
                                                      58592 non-null int64
       is_front_fog_lights
                                                      58592 non-null object
 31 is_rear_window_wiper
                                                      58592 non-null object
 32 is_rear_window_washer
 33 is_rear_window_defogger
                                                     58592 non-null object
                                                      58592 non-null object
 34 is_brake_assist
 35 is_power_door_locks
                                                      58592 non-null object
 36 is_central_locking
                                                      58592 non-null object
 37 is_power_steering
                                                      58592 non-null object
      is_driver_seat_height_adjustable 58592 non-null object
 39 is_day_night_rear_view_mirror
                                                     58592 non-null object
40 is_ecw
                                                      58592 non-null object
 41 is_speed_alert
                                                      58592 non-null object
 42 ncap_rating
                                                      58592 non-null int64
43 is_claim
                                                      58592 non-null int64
dtypes: float64(4), int64(12), object(28)
memory usage: 19.7+ MB
```

 $\mbox{\em \#This}$ command gives the static information of given dataset:

car.describe()

	policy_tenure	age_of_car	age_of_policyholder	population_density	make	airbags	displacement	cylinder	gear_box	turning_radius
count	58592.000000	58592.000000	58592.000000	58592.000000	58592.000000	58592.000000	58592.000000	58592.000000	58592.000000	58592.000000 5
mean	0.611246	0.069424	0.469420	18826.858667	1.763722	3.137066	1162.355851	3.626963	5.245443	4.852893
std	0.414156	0.056721	0.122886	17660.174792	1.136988	1.832641	266.304786	0.483616	0.430353	0.228061
min	0.002735	0.000000	0.288462	290.000000	1.000000	1.000000	796.000000	3.000000	5.000000	4.500000

#This command shows the first 5 rows of given dataset:

car.head()

0.644231 ID00001 0.515874 0.05 C1 4990 1 Α M1 CNG No ID00003 0.841110 0.02 0.384615 C3 4076 1 Α M1 CNG No 4 0.11 0.634615 C5 2 ID00005 0.596403 34738 Α М3 No Petrol

5 rows × 11 columns

#This command shows the last 5 rows of given dataset:

car.tail()

0.644231 58587 ID58588 0.355089 0.13 C8 8794 2 М3 Petrol No 58589 ID58590 1.162273 0.05 0.451923 C5 34738 1 Α M1 CNG No ID58592 0.02 0.442308 C8 58591 0.124429 8794 3 C2 M4 Diesel Yes

5 rows × 44 columns

#This command shows the columns of given dataset:

car.columns

 $\# This\ command\ shows\ the\ order\ pair\ of\ given\ dataset:$

car.shape

(58592, 44)

 $\hbox{\tt\#This command gives the missing values of given dataset:}\\$

car.isnull().sum()

policy_id policy_tenure age_of_car age_of_policyholder area cluster population_density 0 make segment model fuel_type max_torque max_power engine_type airbags is_esc is_adjustable_steering is_tpms is_parking_sensors is_parking_camera rear_brakes_type displacement cylinder transmission_type gear_box steering_type turning_radius length width height gross_weight is_front_fog_lights is_rear_window_wiper is_rear_window_washer is_rear_window_defogger is_brake_assist is_power_door_locks is_central_locking is_power_steering

#This command gives the duplicated values of given dataset:

car.duplicated().sum()

a

#This command groups the target column ("is_claim") into all other columns. #Following cammand shows the relationship between target and other column:

gp = car.groupby('is_claim').count()

policy_id policy_tenure age_of_car age_of_policyholder area_cluster population_density make segment model fuel_type ... is_rear_window_defog

is claim

0	54844	54844	54844	54844	54844	54844	54844	54844	54844	54844	 548
	3748	3748	3748	3748	3748	3748	3748	3748	3748	3748	37

2 rows × 43 columns

#This command counts the value of target column:

car.is_claim.value_counts()

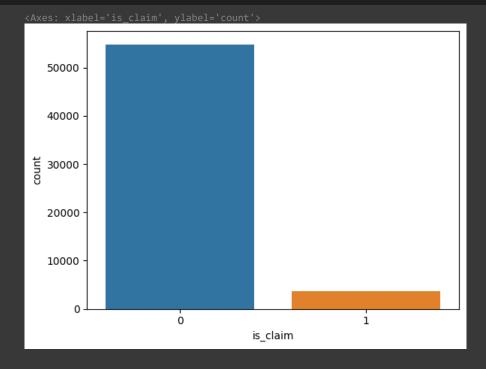
0 54844 1 3748

Name: is_claim, dtype: int64

→ Visualization:

 $\mbox{\tt\#}$ This command shows the value of target column in the form of graph:

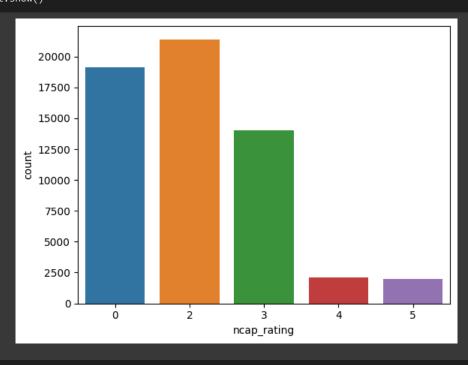
sns.countplot(x= car['is_claim'], data=car)



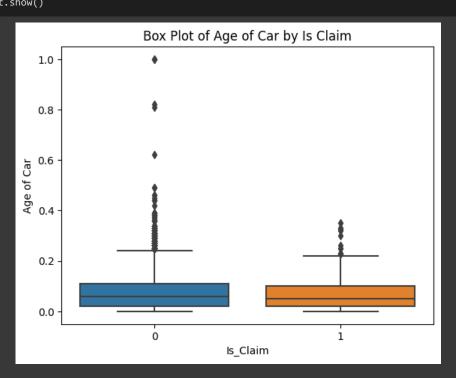
The difference between 0 and 1 is huge, due to class Im-Balancing problem: After some codes this problem will we solved:

#This command shows the ncap_rating in the form of graph:

sns.countplot(x = 'ncap_rating', data = car)
plt.xlabel('ncap_rating')
plt.show()

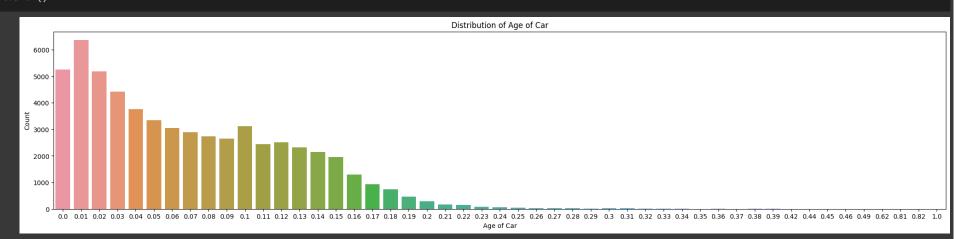


#This commad is used to show the outliers in target column:
sns.boxplot(x='is_claim', y='age_of_car', data=car)
plt.xlabel('Is_Claim')
plt.ylabel('Age of Car')
plt.title('Box Plot of Age of Car by Is Claim')
plt.show()



#This command shows the age_of_car column in graphical view:

plt.figure(figsize = (25,5))
sns.countplot(x='age_of_car', data=car)
plt.xlabel('Age of Car')
plt.ylabel('Count')
plt.title('Distribution of Age of Car')
plt.show()



 $\hbox{\tt\#This command is used to identify the co-relation of entire dataset:}\\$

car.corr()

	policy_tenure	age_of_car	age_of_policyholder	population_density	make	airbags	displacement	cylinder	gear_box	turning_radius	16
policy_tenure	1.000000	0.166312	0.143676	-0.100307	0.086101	0.103981	0.194361	0.191185	0.095305	0.166426	0.19
age_of_car	0.166312	1.000000	-0.035427	-0.062255	0.188122	0.209073	0.393208	0.379522	0.201579	0.332716	0.38
age_of_policyholder	0.143676	-0.035427	1.000000	0.009669	-0.031989	-0.008041	-0.023764	0.004183	-0.003115	-0.016764	-0.02
population_density	-0.100307	-0.062255	0.009669	1.000000	-0.035125	-0.060359	-0.090983	-0.091591	-0.056640	-0.077501	-0.09
make	0.086101	0.188122	-0.031989	-0.035125	1.000000	0.501800	0.753344	0.410672	0.632807	0.753861	0.69
airbags	0.103981	0.209073	-0.008041	-0.060359	0.501800	1.000000	0.661190	0.478594	0.859556	0.810820	0.80
displacement	0.194361	0.393208	-0.023764	-0.090983	0.753344	0.661190	1.000000	0.866231	0.692240	0.875407	0.96
cylinder	0.191185	0.379522	0.004183	-0.091591	0.410672	0.478594	0.866231	1.000000	0.410163	0.615806	0.80
gear_box	0.095305	0.201579	-0.003115	-0.056640	0.632807	0.859556	0.692240	0.410163	1.000000	0.861740	0.80
turning_radius	0.166426	0.332716	-0.016764	-0.077501	0.753861	0.810820	0.875407	0.615806	0.861740	1.000000	0.94
length	0.190869	0.383177	-0.020138	-0.091968	0.692365	0.809094	0.961655	0.805476	0.808975	0.944899	1.00
width	0.213228	0.414104	-0.006135	-0.098156	0.511695	0.639562	0.899302	0.862430	0.601923	0.825603	0.91
height	0.119055	0.259156	-0.053930	-0.065583	0.303274	0.423816	0.554591	0.352118	0.579725	0.460436	0.55
gross_weight	0.141027	0.302127	-0.007758	-0.077816	0.481408	0.828988	0.776210	0.602978	0.894639	0.823097	0.86
ncap_rating	0.173280	0.348853	-0.031628	-0.071150	0.792254	0.341557	0.847065	0.598364	0.529688	0.779302	0.76
is_claim	0.078747	-0.028172	0.022435	-0.017808	-0.000456	0.002789	0.007678	0.013434	-0.000635	0.002724	0.00

#This command convert the co-relation into heatmap:
#Graphical view of co-relation from heatmap:

#Graphical view of co-relation from heatmap

correlation_matrix = car.corr()
plt.figure(figsize = (15,9))

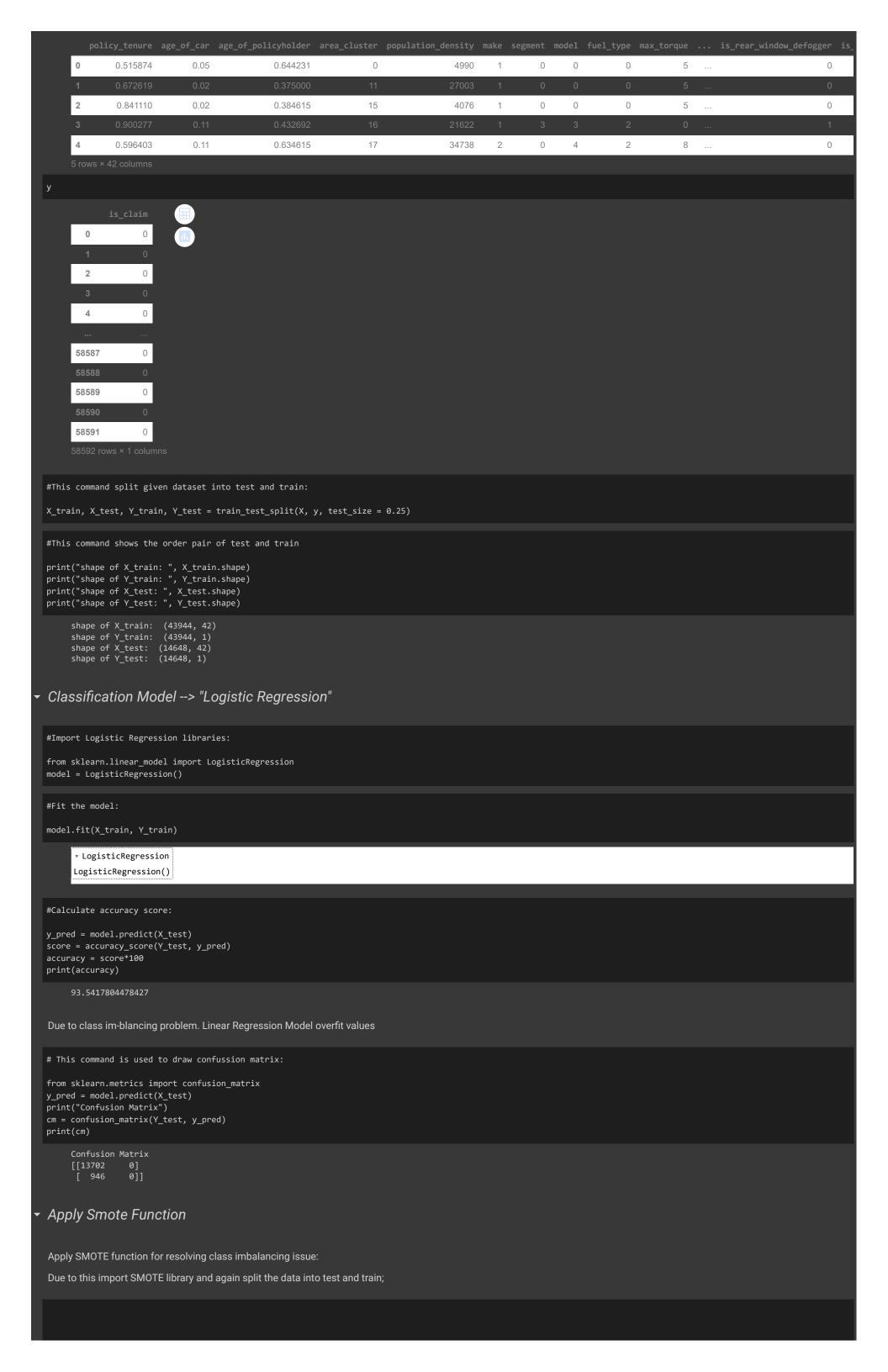
sns.heatmap(correlation_matrix, annot=True, cmap='Pastel1')

plt.title('Correlation Matrix of Iris Dataset')
plt show()

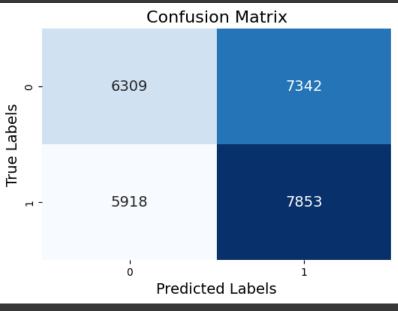
plt.show()

Drop Poilcy_ID Column, Label Encoding at different columns, Split data into train-test model

```
#Import some libraries for label encoding, accurarcy and other:
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import StandardScaler
from sklearn.metrics import accuracy_score
from sklearn.preprocessing import LabelEncoder
#This command is used to drop the policy_id column:
car1 = car
car1= car1.drop('policy_id', axis=1)
# This command extract the categorical columns:
catFeatures= [col for col in car1.columns if col in
               car1.select_dtypes(include=object).columns]
# # Extracting All Features:
features = [col for col in car1.columns if col not in ['is_claim']]
print(features)
print(catFeatures)
      ['policy_tenure', 'age_of_car', 'age_of_policyholder', 'area_cluster', 'population_density', 'make', 'segment', 'model', 'fuel_type', 'max_torque', 'max_power', ['area_cluster', 'segment', 'model', 'fuel_type', 'max_torque', 'max_power', 'engine_type', 'is_esc', 'is_adjustable_steering', 'is_tpms', 'is_parking_sensors',
# This command is used to Split Features and Target Variable:
X = car1.loc[:, features]
# Checking Dataset Shape (Features):
print(X.shape)
      (58592, 42)
# This command is used to Split Features and Target Variable:
y=car[['is_claim']]
# Checking Dataset Shape (Features):
print(y.shape)
      (58592, 1)
# This command is used to put label_Encoding into Categorical columns:
labelEncode = LabelEncoder()
# Iterating Over each categorial features:
for col in catFeatures:
    # storing its numerical value:
    X[col] = labelEncode.fit_transform(car1[col])
#After apply label_Encoding all categorical columns is converted into numerical columns:
X.head()
```



```
X_re, y_re = sm.fit_resample(X, y)
X_train, X_test, Y_train, Y_test = train_test_split(X_re, y_re, test_size = 0.25)
#This command shows the order pair of test and train after SMOTE function:
print("shape of X_train: ", X_train.shape)
print("shape of Y_train: ", Y_train.shape)
print("shape of X_test: ", X_test.shape)
print("shape of Y_test: ", Y_test.shape)
     shape of X_train: (82266, 42)
     shape of Y_train: (82266, 1)
     shape of X_test: (27422, 42)
shape of Y_test: (27422, 1)
Classification Model --> "Logistic Regression"
#Import Logistic Regression libraries:
from sklearn.linear_model import LogisticRegression
model = LogisticRegression()
# Fit the Model:
model.fit(X_train, Y_train)
      ▼ LogisticRegression
      LogisticRegression()
#Calculate accuracy score:
y_pred = model.predict(X_test)
score = accuracy_score(Y_test, y_pred)
accuracy = score*100
print(accuracy)
     51.644664867624535
# This command is used to draw confussion matrix:
from sklearn.metrics import confusion_matrix
y_pred = model.predict(X_test)
print("Confusion Matrix")
cm = confusion_matrix(Y_test, y_pred)
print(cm)
     Confusion Matrix
     [[6309 7342]
      [5918 7853]]
\mbox{\tt\#} This command is used to draw a heatmap of confussion matrix:
plt.figure(figsize = (6, 4))
sns.heatmap(cm, annot = True, fmt = 'd', cmap = 'Blues', cbar = False, annot_kws = {'size' : 14})
plt.xlabel('Predicted Labels', fontsize = 14)
plt.ylabel('True Labels', fontsize = 14)
plt.title('Confusion Matrix', fontsize = 16)
plt.show()
                                Confusion Matrix
```



Class Im-balancing problem is vanish but model accuracy is very low, for raising the model accuracy we can tune it's parameter by using "HYPERPARAMETER TUNNING".

```
# This command is used to store parameters for hyper parameter tunning:

param_g = {
    'C': [0.001, 0.01, 0.1, 1, 10, 100],
    'penalty': ['ll', 'l2']
}
```

#Import library:

from sklearn.model_selection import GridSearchCV

from imblearn.over_sampling import SMOTE

sm = SMOTE(random_state=42)

```
# This command is used to develop the model:
clf = GridSearchCV(model, param_grid = param_g, cv = 10, verbose = True, n_jobs = -1)
#Fit the model:
LR_grid = clf.fit(X, y)
     Fitting 10 folds for each of 12 candidates, totalling 120 fits
# This command is used to show best parameter and best index:
print('Best hyperparameters are: '+str(LR_grid.best_params_))
print('Best index is: '+str(LR_grid.best_index_))
     Best hyperparameters are: {'C': 0.001, 'penalty': '12'}
     Best index is: 1
# This command is used to calculate accurary:
score = (LR_grid.best_score_)
accuracy = score*100
print(accuracy)
     93.60322236959911
Classification Model --> "Decision Tree"
#Import decesion tree classifier library and develop the model:
from sklearn.tree import DecisionTreeClassifier
dtc = DecisionTreeClassifier()
# Fit model:
dtc.fit(X_train, Y_train)
     ▼ DecisionTreeClassifier
     DecisionTreeClassifier()
#This command is used to calculate accuracy of the model:
y_pred = dtc.predict(X_test)
score = accuracy_score(Y_test, y_pred)
accuracy = score*100
print(accuracy)
     91.5031726351105
# This command is used to draw confussion matrix:
from sklearn.metrics import confusion_matrix
y_pred = dtc.predict(X_test)
print("Confusion Matrix")
cm_dtc = confusion_matrix(Y_test, y_pred)
print(cm_dtc)
     Confusion Matrix
     [[12397 1254]
[ 1076 12695]]
# This command is used to draw a heatmap of confussion matrix:
plt.figure(figsize = (6, 4))
sns.heatmap(cm_dtc, annot = True, fmt = 'd', cmap = 'Blues', cbar = False, annot_kws = {'size' : 14})
plt.xlabel('Predicted Labels', fontsize = 14)
plt.ylabel('True Labels', fontsize = 14)
plt.title('Confusion Matrix', fontsize = 16)
plt.show()
                              Confusion Matrix
```

