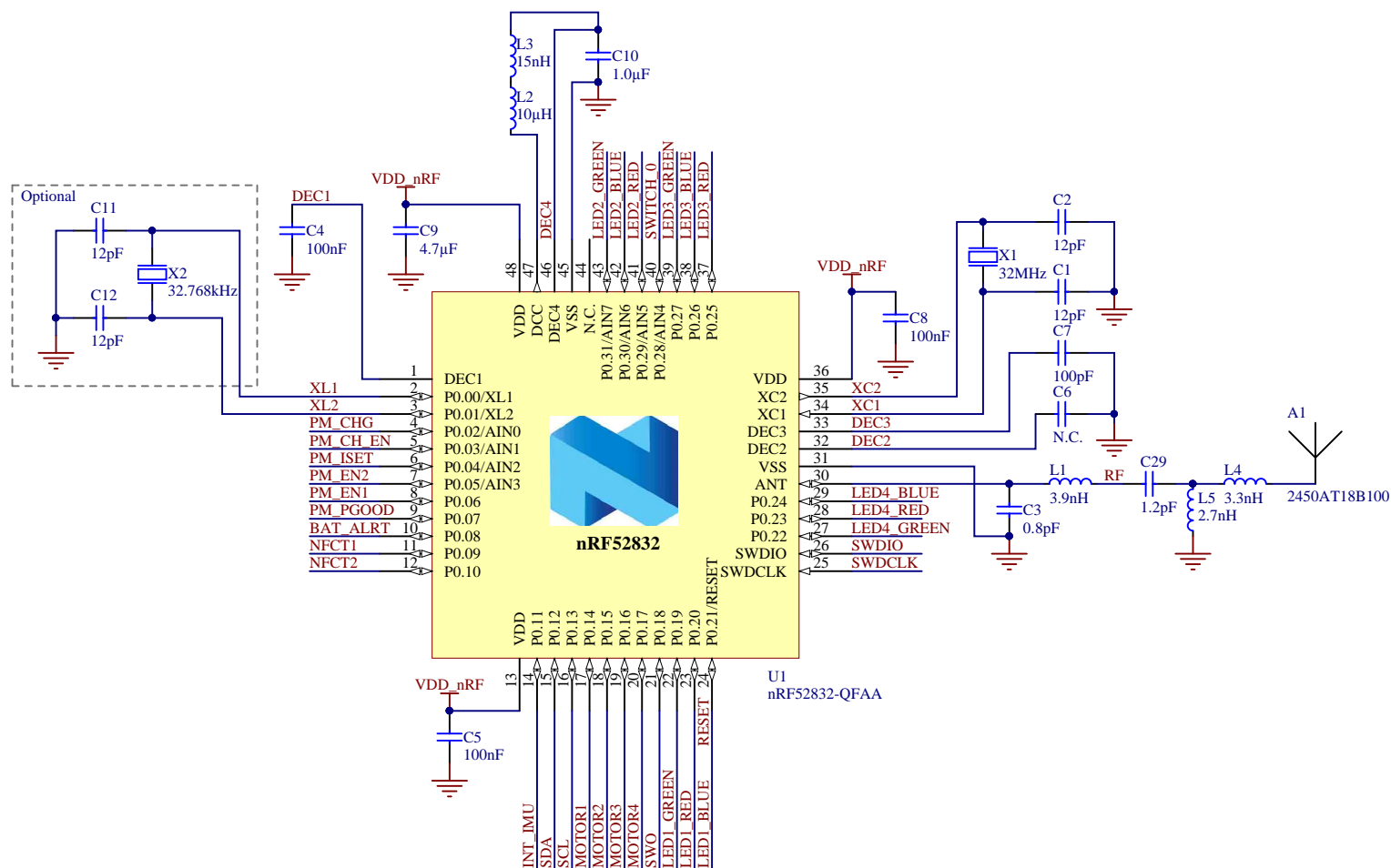

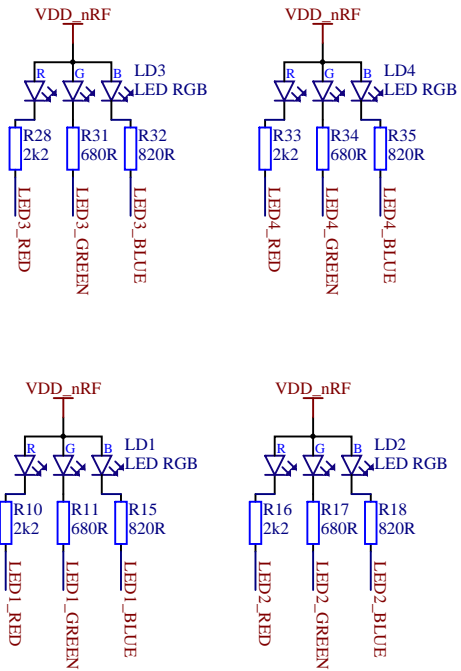


MCU

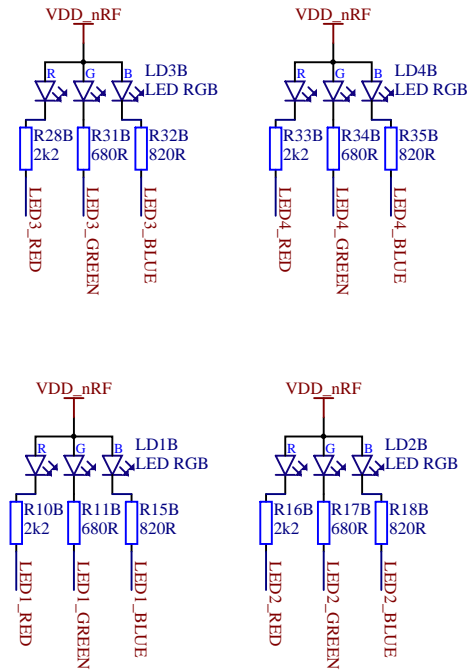


Title <b>nRF52 Quadcopter - MCU</b>			
Size <b>A4</b>	Project Number <b>4425</b>	Revision <b>1.0.0</b>	
Date: <b>12.08.2016</b>			Sheet <b>1</b> of <b>5</b>
File: <b>pca20017_mcu.SchDoc</b>			Drawn By: <b>ERHE</b>

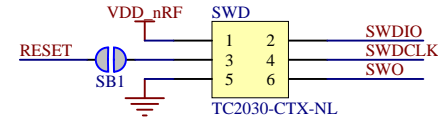
## LEDs Top



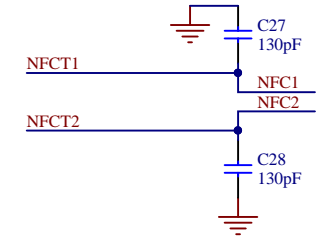
## LEDs Bottom



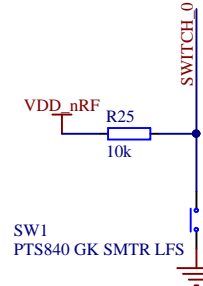
## Debug In



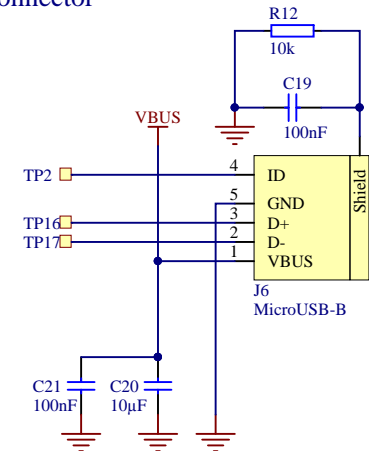
## NFCT Antenna



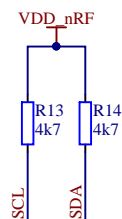
## User Switch



## USB Connector



## I2C Pull-ups



Title  
nRF52 Quadcopter - Misc

Size  
A4

Date: 12.08.2016

File: pca20017\_misc.SchDoc

Project Number  
4425

Revision  
1.0.0

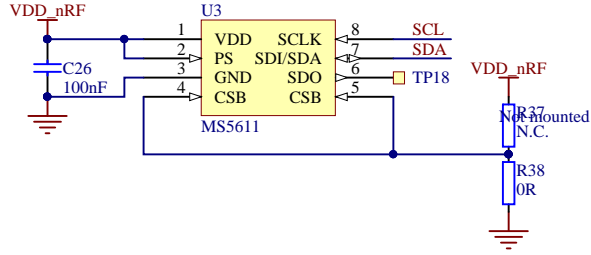
Sheet 2 of 5

Drawn By: ERHE



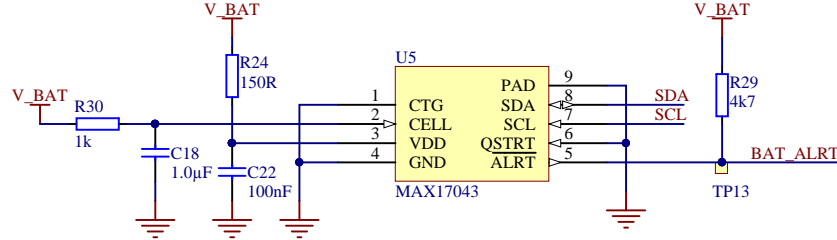
# Barometer 1

CSB | I2C Address  
0 | 0x77  
1 | 0x78



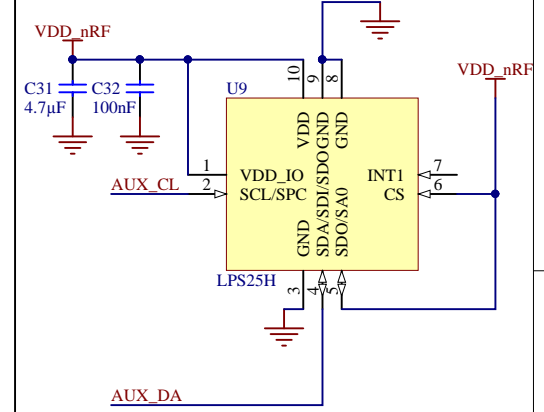
# Fuel Guage

I2C Address - 0x34



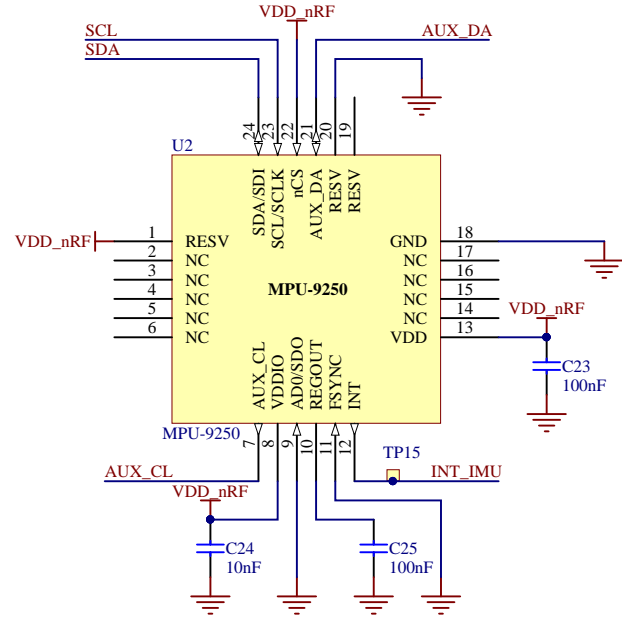
# Barometer 2

I2C Address - 0xB8



# IMU 9-DOF

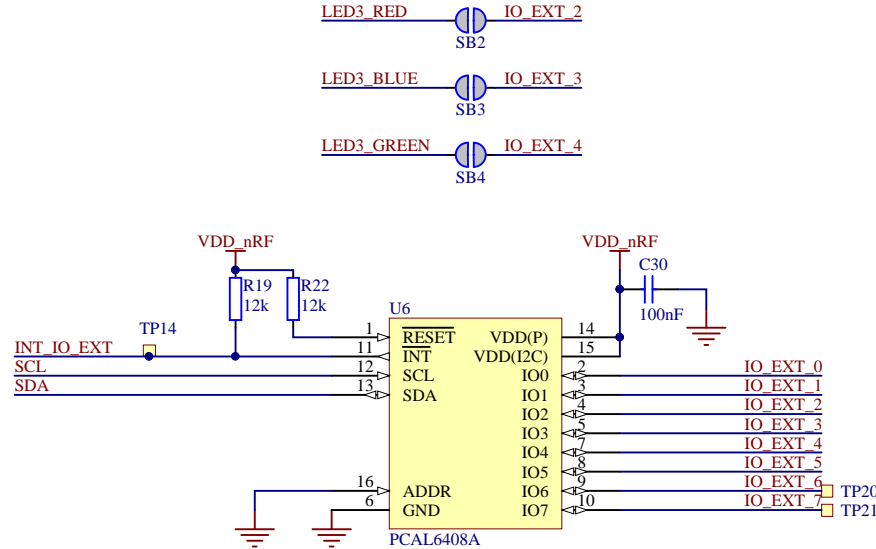
I2C Address - 0x68



# IO Extender

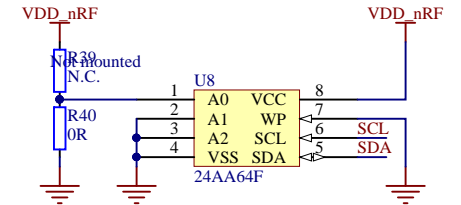
I2C Address - 0x20

Disable LEDs to give access to nRF52 GPIO



# EEPROM

A[2:0] | I2C Address  
000 | 0x50  
001 | 0x51



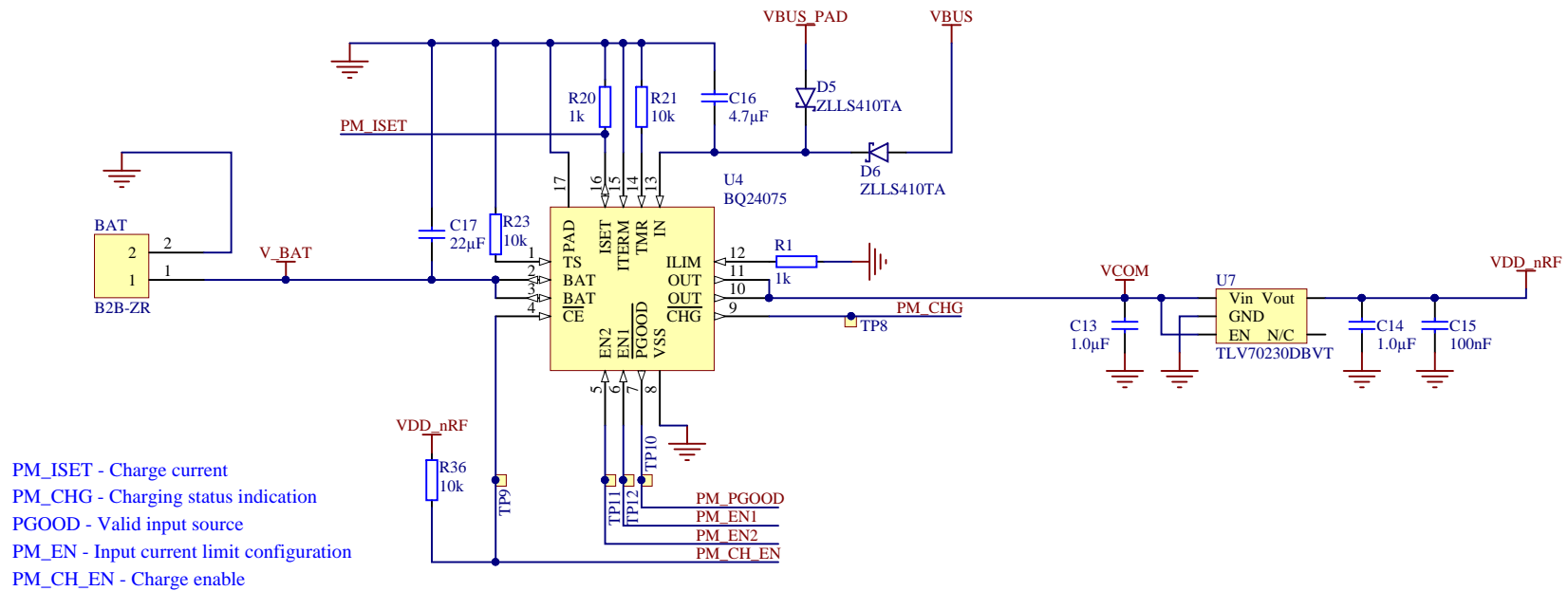
Title  
nRF52 Quadcopter - Sensors

Size  
A4  
Project Number  
4425  
Date: 12.08.2016  
File: pca20017\_sensors.SchDoc

Revision  
1.0.0  
Sheet 3 of 5  
Drawn By: ERHE



## Power System



Title  
**nRF52 Quadcopter - Power**

Size  
 A4

Project Number  
 4425

Revision  
 1.0.0

Date: 12.08.2016

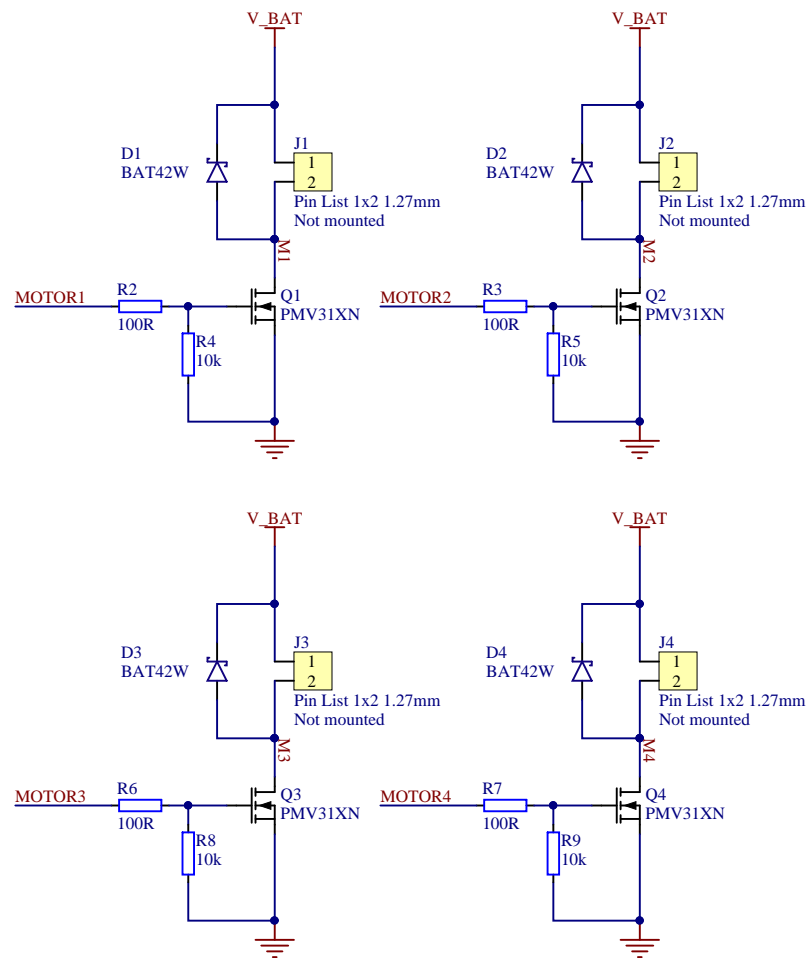
Sheet 4 of 5

File: pca20017\_power.SchDoc

Drawn By: ERHE



## Motor System



Title  
nRF52 Quadcopter - Motors

Size  
A4

Project Number  
4425

Revision  
1.0.0

Date: 12.08.2016

Sheet 5 of 5

File: pca20017\_motors.SchDoc

Drawn By: ERHE



