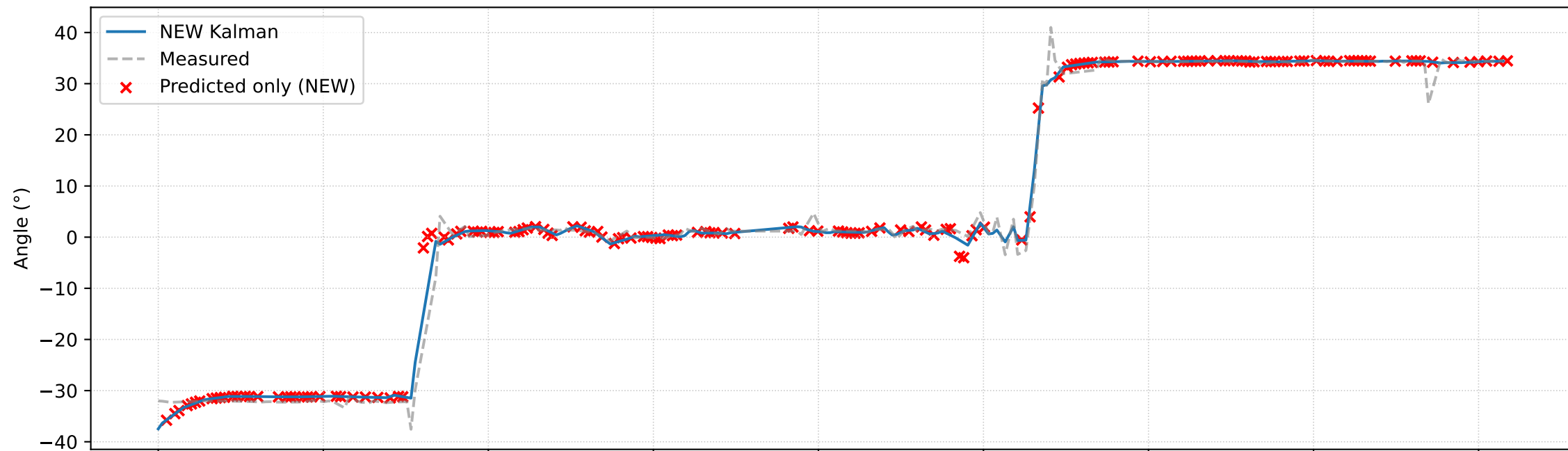


NEW Kalman vs Measured



OLD Kalman vs Measured

