

ARTEM KULAKEVICH

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EDUCATION

Master of Science, Electrical Engineering <i>Portland State University</i>	GPA: 4.00	Jun 2019 – Jun 2021
Bachelor of Science, Electrical Engineering <i>Portland State University</i>	GPA: 3.97	Sep 2017 – Jun 2020

WORK EXPERIENCE

Design & Dev. Engineer, Micro Systems Engineering, Inc.	Dec 2020 – Present
<ul style="list-style-type: none">Equipment owner for 2 laser PCB depaneling systems that process all circuits in production. (1000+ medical implants per day)Led projects to replace \$180K UV laser source and \$80K automated conveyance on laser system.Leading equipment purchasing and integration project for 2 additional laser systems. (\$770K investment)	
Production Specialist, Micro Systems Engineering, Inc.	Dec 2016 – Dec 2020
<ul style="list-style-type: none">Performed LabVIEW software updates for multiple automated imaging robots used to image the majority of production circuits. (1000+ medical implants per day)Rebuilt and rewired multiple automated imaging robots currently used in production.Programmed Epson 6-axis robot pick and place positions to introduce new products into the production line.	

SKILLS

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| • C++ / C | • LabVIEW 13.0 | • SystemVerilog |
| • Embedded Rust | • ARM / RISC-V Assembly | • Soldering |

RELEVANT PROJECTS

High Assurance Self Balancing Robot	Jan 2020 – Jun 2020
<ul style="list-style-type: none">Programmed a self-balancing robot to explore complex methods of control and formal verification.Altered Kind2 compiler to generate embedded Rust from Lustre; generated working PID and Fuzzy controller.Created a website with an SQL database to provide a live feed of robot sensor data.	
RISC-V SoC FPGA Project	Oct 2020 – Dec 2020
<ul style="list-style-type: none">Modified a RISC-V processor written in SystemVerilog to introduce VGA, I/O, and a microcontroller.Wrote assembly code used by the modified RISC-V processor.	
ARM 32-bit Programming Project	Sep 2018 – Dec 2018
<ul style="list-style-type: none">Utilized ARM assembly and C to program dev board to communicate with peripherals over UART and I2C.Used datasheets and pseudo code to identify and plan modifications for peripheral settings.	