

# ARTEM KULAKEVICH

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## EDUCATION

<b>Master of Science, Electrical Engineering</b> <i>Portland State University</i>	<b>GPA: 4.00 / 4.00</b>	<b>Jun 2019 – Present (Jun 2021)</b> Portland, OR
<b>Bachelor of Science, Electrical Engineering</b> <i>Portland State University</i>	<b>GPA: 3.97 / 4.00</b> <i>Summa cum laude</i>	<b>Sep 2017 – Jun 2020</b> Portland, OR

## WORK EXPERIENCE

<b>Production Specialist III</b> <i>Micro Systems Engineering, Inc.</i>	<b>Dec 2016 – Present</b> Lake Oswego, OR
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- Physically rewired and rebuilt 2 production imaging robot cells. Updated LabVIEW software used for automation of imaging robot.
- Trained an Epson 6-axis robot arm to process 3 new medical devices for production. Used inaccurate documentation for reference and fixed the documentation after gaining experience.
- Perform mechanical and electrical troubleshooting tasks on test fixtures, and production equipment.

## SKILLS

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|-----------------|-------------------------|-----------------|
| • C++ / C       | • LabVIEW 12.0          | • SystemVerilog |
| • Embedded Rust | • ARM / RISC-V Assembly | • Oscilloscopes |
| • LTspice       | • Soldering             | • Git (Github)  |

## PROJECTS

<b>High Assurance Self Balancing Robot - Senior Capstone</b> <i>Project Sponsor: Galois, Inc.</i>	<b>Jan 2020 – Jun 2020</b> Portland, OR
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- Programmed a self-balancing robot to explore complex methods of control and formal verification.
- Altered a compiler in a verification tool called Kind2 to generate embedded **Rust** code from a verifiable language called **Lustre**.
- Used the modified compiler to generate an embedded **Rust** PID controller and Fuzzy logic controller. Found Rust PID to be within 5% of a controller written in **C++** for most characteristics.

<b>RISC-V System-On-Chip Projects</b>	<b>Oct 2020 – Dec 2020</b>
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- Modified a RISC-V Swerve EH1 processor written in **SystemVerilog** and to interact more I/Os, VGA displays, and internal busses. Wrote **assembly** code used by the processor.
- Teacher's assistant used my code to teach other students how to implement the project.

<b>MIPS-lite Simulator</b>	<b>Apr 2020 – Jun 2020</b>
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- Designed a 5-stage MIPS simulator in **C++** with timing analysis, hazard mitigation, and forwarding. Evaluated the simulator with a provided memory image.

<b>Class AB Audio Amplifier</b>	<b>Sep 2019 – Feb 2019</b>
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- Designed a 10-watt audio amplifier circuit to gain experience with design process; used **LTspice** to plan out implementation. Soldered and tested the design using **oscilloscope** and power resistors.
- Amplifier reached 7.94W output with no distortion and 9.8W output with some distortion 0 – 20kHz.

<b>ARM Sitara AM335x 32-bit Processor</b>	<b>Sep 2018 – Dec 2018</b>
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- Utilized ARM **assembly** and **C** to program a BeagleBone Black board to communicate with an RC8660 talker board over UART and a NewHaven LCD over I2C.
- Used datasheets and pseudo code to identify and plan modifications for peripherals. Implemented all necessary features using interrupts.

## RELEVANT COURSEWORK

Computer Architecture • **Microprocessors 1 & 2** • ASIC: Modeling & Synthesis • **Digital IC Design** • Analog IC Design • **Formal Verification** • System-On-Chip