```
import numpy as np
import cv2
from matplotlib import pyplot as plt
def extract points(img, number=25, thickness=10):
 gray = cv2.cvtColor(img,cv2.COLOR BGR2GRAY)
 corners = cv2.goodFeaturesToTrack(gray, number, 0.01, 10)
 corners = np.int0(corners)
 for i in corners:
   x,y = i.ravel()
   cv2.circle(img, (x,y), thickness, 255, -1)
 return img, corners
def map points(img, corners1, corners2, accuracy=30, thickness=10):
 new_img = img.copy()
 counter = 0
 for i in corners1:
   min dist = accuracy**2
   best j = None
   flag = False
    for j in corners2:
     dist = (i[0][0]-j[0][0])**2 + (i[0][1]-j[0][1])**2
      # print(dist)
      if dist <= min dist:
          min dist = dist
          best_j = j[0]
          flag=True
    if flag:
      new img = cv2.line(new img, tuple(i[0]), tuple(best j), (0, 255, 255), thickn
      counter += 1
 return new img, counter
```

Вращение объекта при неподвижной камере

```
img1 = cv2.imread('Mosfilm1.png')
img1 = img1[450:2000, 1000:2750]

img2 = cv2.imread('Mosfilm2.png')
img2 = img2[450:2000, 1000:2750]

img_points1, corners1 = extract_points(img1)
img_points2, corners2 = extract_points(img2)

moving img, counter = map points(img2, corners1, corners2)
```

Движение строго вправо в студийных условиях

Overall points 25, found - 17, accuracy - 68.0%

```
img1 = cv2.imread('left.png')
img2 = cv2.imread('right.png')

img_points1, corners1 = extract_points(img1, thickness=5)
img_points2, corners2 = extract_points(img2, thickness=5)

moving_img, counter = map_points(img2, corners1, corners2, thickness=2)

fig, axes = plt.subplots(1, 3)
```

```
axes[0].imshow(img_points1)
axes[0].set_title('First image')

axes[1].imshow(img_points2)
axes[1].set_title('Second image')

axes[2].imshow(moving_img)
axes[2].set_title('Show moving image')

fig.set_figwidth(24)
fig.set_figheight(12)

plt.show()

print(f'Overall points 25, found - {counter}, accuracy - {counter/25 * 100}%')

Overall points 25, found - 24, accuracy - 96.0%
```

```
def extract_moving_and_show_result(img1, img2):
    img_points1, corners1 = extract_points(img1)
    img_points2, corners2 = extract_points(img2)

moving_img, counter = map_points(img2, corners1, corners2, accuracy=100)

fig, axes = plt.subplots(1, 3)

axes[0].imshow(img_points1)
    axes[0].set_title('First image')

axes[1].imshow(img_points2)
    axes[1].set_title('Second image')

axes[2].imshow(moving_img)
    axes[2].set_title('Show moving image')

fig.set_figwidth(12)
```

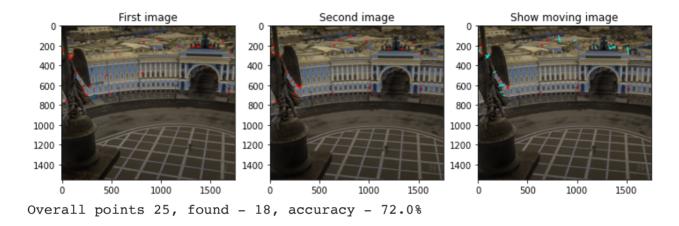
```
fig.set_figheight(6)
plt.show()
print(f'Overall points 25, found - {counter}, accuracy - {counter/min(len(corne))
```

Движение по спирали вниз

```
img1 = cv2.imread('Dvorts1.png')
img1 = img1[450:2000, 1000:2750]

img2 = cv2.imread('Dvorts2.png')
img2 = img2[450:2000, 1000:2750]

extract_moving_and_show_result(img1, img2)
```



Движение вверх

```
img1 = cv2.imread('Adm1.png')
img1 = img1[450:2000, 1000:2750]

img2 = cv2.imread('Adm2.png')
img2 = img2[450:2000, 1000:2750]

extract_moving_and_show_result(img1, img2)
```

Отдаление

```
img1 = cv2.imread('Isaak1.png')
img1 = img1[450:2000, 1000:2750]

img2 = cv2.imread('Isaak2.png')
img2 = img2[450:2000, 1000:2750]
```

extract_moving_and_show_result(img1, img2)

