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**Rolling bearings. Tolerances.
Terms and definitions**

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1.25. <i>d</i>	, ,

1.26.

$$d_s(D_s) = \frac{^{\wedge}jfnax^{\wedge}b^{\wedge}smin}{2}$$

1.27.

$$d_m(D_m) = \frac{^{\wedge}smax^{\wedge}P^{\wedge}s'min}{2}$$

1.28.

$$dmp(\& \quad) = \frac{^{\wedge}jfnax^{\wedge}b^{\wedge}smin}{2}$$

1.29

$$B_s(C_s) = \frac{^{\wedge}jfnax^{\wedge}b^{\wedge}smin}{2}$$

1.30.

$$(\quad) = \frac{^{\wedge}jfnax^{\wedge}b^{\wedge}smin}{2}$$

$$\begin{aligned} R &= \frac{^{\wedge}jfnax^{\wedge}b^{\wedge}smin}{2} \\ &= \frac{^{\wedge}jfnax^{\wedge}b^{\wedge}smin}{2} \end{aligned}$$

1.31.

$$T_s(H_s) = \frac{^{\wedge}jfnax^{\wedge}b^{\wedge}smin}{2}$$

1.32.

$$D_{ws} = \frac{^{\wedge}jfnax^{\wedge}b^{\wedge}smin}{2}$$

1.33.	-
1.34.	-
Dwmp	
1.35.	-
Lws	,
1.36,	-
Lwm	
	$\overset{\wedge}{L-wm}-2^{\text{ters}\cdot\text{min}}$
2.	
2.1.	
2.1.1.	
d_s	
2.1.2.	-
$\dot{d}m$	
2 . .	-
2.1.4.	,
	$\sim d_m p \ d$

2.2.

2.2.1.

 D_s $Q \xrightarrow{s} D_s \xrightarrow{s} D$

2.2.2.

 $=D_m \xrightarrow{s} D$

2.2.3.

 $A_D = D_{mp} \xrightarrow{s} D$

2.3.

()

2.3.1.

 $s(\&)$ $\xrightarrow{s} (\xrightarrow{s} C_s \xrightarrow{s})$

2.3.2.

 (\xrightarrow{s}) $\xrightarrow{s} T_s \xrightarrow{s} (\xrightarrow{s} H_s \xrightarrow{s} H)$

2.4.

2.4.1.

 ws $)_{ws}$

2.4.2.

 $)_{wm} \xrightarrow{wm} Dwm$

2.4.3.	-
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2.4.4.	-
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$v^o - l >$	
2.4.5.	-
WS	$= L_{WS} - L_w$
2.4.6.	,

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3.4.

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3,7.

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3.8.

, $V_{q_{ws}} \sim D_{ws \ min}$

vD_{wmp}

$B_{wmpmax} D_{wmpmiw}$

3.9.

3.11.

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$z^I -$

3.12.

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4.

4.1.

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4.4,
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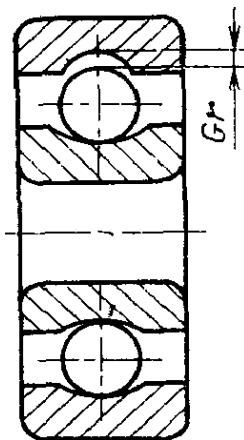
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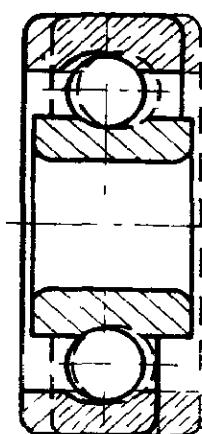
6.

6.1.

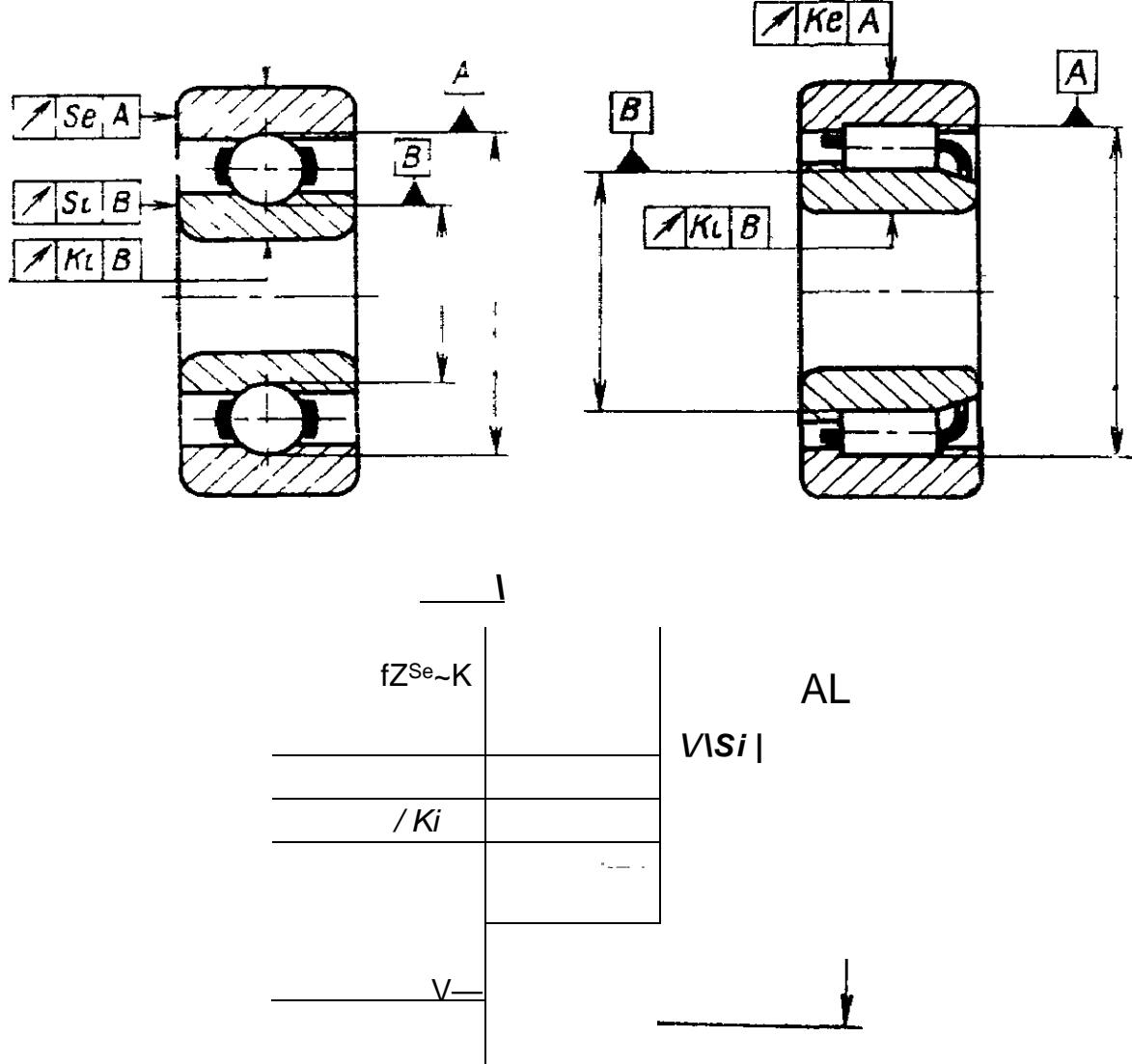
8.2.

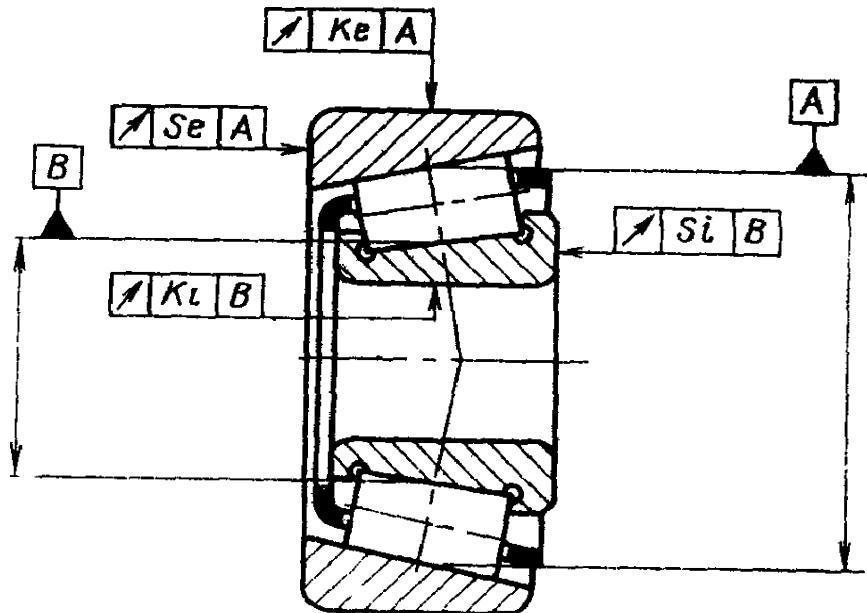
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-	-	(-	5.4
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				3.8
				3.1

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)				3.5
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				1.5
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			-	2.2.3
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				2.1.2
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				2.1.4
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				1.8
				1.29
				1.30

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