Московский Авиационный Институт (Национальный исследовательский Университет)

Факультет: «Информационные технологии и прикладная математика» Кафедра: 806 «Вычислительная математика и программирование»

Лабораторная работа № 4 по курсу «ООП»

Тема: Основы метапрограммирования.

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```
1. Код:
vertex.h:
#ifndef D_VERTEX_H_
#define D_VERTEX_H_
#include <iostream>
template<class T>
struct vertex {
  T x, y;
};
template<class T>
std::istream& operator>> (std::istream& is, vertex<T>& v){
  is >> v.x >> v.y;
  return is;
}
template<class T>
std::ostream& operator<< (std::ostream& os, const vertex<T>& v){
  os << "(" << v.x << ", " << v.y << ") ";
  return os:
}
template<class T>
vertex<T> operator+(vertex<T> lhs,vertex<T> rhs){
  vertex<T> res;
  res.x = lhs.x + rhs.x;
  res.y = lhs.y + rhs.y;
  return res;
}
template<class T>
vertex<T>& operator/= (vertex<T>& vertex, int number) {
  vertex.x = vertex.x / number;
  vertex.y = vertex.y / number;
  return vertex;
}
#endif
templates.h:
#ifndef D_TEMPLATES_H_
#define D_TEMPLATES_H_ 1
#include <tuple>
#include <type_traits>
```

```
#include "square.h"
#include "rectangle.h"
#include "trapezoid.h"
#include "vertex.h"
template<class T>
struct is_vertex : std::false_type {};
template<class T>
struct is_vertex<vertex<T>> : std::true_type {};
template<class T>
struct is_figurelike_tuple : std::false_type {};
template<class Head, class... Tail>
struct is_figurelike_tuple<std::tuple<Head, Tail...>> :
  std::conjunction<is_vertex<Head>,
   std::is_same<Head, Tail>...> {};
template<class Type, size_t SIZE>
struct is_figurelike_tuple<std::array<Type, SIZE>> :
  is_vertex<Type> {};
template<class T>
inline constexpr bool is_figurelike_tuple_v =
 is_figurelike_tuple<T>::value;
template<class T, class = void>
struct has_print_method : std::false_type {};
template<class T>
struct has_print_method<T,
 std::void_t<decltype(std::declval<const T>().Print())>> :
  std::true_type {};
template<class T>
inline constexpr bool has_print_method_v =
 has_print_method<T>::value;
template<class T>
std::enable_if_t<has_print_method_v<T>, void>
  Print(const T& figure) {
     figure.Print();
}
template<size_t ID, class T>
void single_print(const T& t) {
  std::cout << std::get<ID>(t);
  return;
}
```

```
template<size_t ID, class T>
void RecursivePrint(const T& t) {
  if constexpr (ID < std::tuple size v < T >){
     single_print<ID>(t);
    RecursivePrint<ID+1>(t);
    return;
  }
  return;
}
template<class T>
std::enable_if_t<is_figurelike_tuple_v<T>, void>
  Print(const T& fake) {
  return RecursivePrint<0>(fake);
}
template<class T, class = void>
struct has_center_method : std::false_type {};
template<class T>
struct has_center_method<T,
    std::void_t<decltype(std::declval<const T>().Center())>> :
    std::true_type {};
template<class T>
inline constexpr bool has center method v =
    has_center_method<T>::value;
template<class T>
std::enable_if_t<has_center_method_v<T>, vertex<double>>
Center(const T& figure) {
  return figure.Center();
}
template<class T>
inline constexpr const int tuple_size_v = std::tuple_size<T>::value;
template<size t ID, class T>
vertex<double> single_center(const T& t) {
  vertex<double> v;
  v.x = std::get < ID > (t).x;
  v.y = std::get < ID > (t).y;
  v /= std::tuple_size_v<T>;
  return v;
template<size_t ID, class T>
vertex<double> RecursiveCenter(const T& t) {
  if constexpr (ID < std::tuple_size_v<T>){
```

```
return single_center<ID>(t) + RecursiveCenter<ID+1>(t);
  } else {
    vertex<double> v;
    v.x = 0;
    v.y = 0;
    return v;
  }
}
template<class T>
std::enable_if_t<is_figurelike_tuple_v<T>, vertex<double>>
Center(const T& fake) {
  return RecursiveCenter<0>(fake);
template<class T, class = void>
struct has_area_method : std::false_type {};
template<class T>
struct has_area_method<T,
     std::void_t<decltype(std::declval<const T>().Area())>> :
    std::true_type {};
template<class T>
inline constexpr bool has_area_method_v =
    has_area_method<T>::value;
template<class T>
std::enable_if_t<has_area_method_v<T>, double>
Area(const T& figure) {
  return figure.Area();
}
template<size_t ID, class T>
double single_area(const T& t) {
  const auto& a = std::get<0>(t);
  const auto& b = std::get < ID - 1 > (t);
  const auto& c = std::get < ID > (t);
  const double dx1 = b.x - a.x;
  const double dy1 = b.y - a.y;
  const double dx2 = c.x - a.x;
  const double dy2 = c.y - a.y;
  return std::abs(dx1 * dy2 - dy1 * dx2) * 0.5;
}
template<size_t ID, class T>
double RecursiveArea(const T& t) {
  if constexpr (ID < std::tuple_size_v<T>){
    return single_area<ID>(t) + RecursiveArea<ID + 1>(t);
  }
```

```
return 0;
}
template<class T>
std::enable_if_t<is_figurelike_tuple_v<T>, double>
Area(const T& fake) {
  return RecursiveArea<2>(fake);
}
#endif // D_TEMPLATES_H_
trapezoid.h
#ifndef D_TRAPEZOID_H_
#define D_TRAPEZOID_H_
#include <iostream>
#include <assert.h>
#include "vertex.h"
template<class T>
struct Trapezoid {
  Trapezoid(std::istream &is);
  int IsCorrect() const;
  vertex<double> Center() const;
  void Print() const;
  double Area() const;
private:
  vertex<T> one,two,three,four;
};
template<class T>
Trapezoid<T>::Trapezoid(std::istream &is){
  is >> one >> two >> three >> four;
  assert(IsCorrect());
}
template<class T>
int Trapezoid<T>::IsCorrect() const {
  T \text{ vec1}_x = \text{four.x - one.x};
  T \text{ vec1}_y = \text{four.y - one.y};
  T \text{ vec2}_x = \text{three.x - two.x};
  T \text{ vec2}_y = \text{three.y - two.y};
  T vec3_x = two.x - one.x;
  T \text{ vec3}_y = \text{two.y} - \text{one.y};
```

```
T vec4_x = three.x - four.x;
  T \text{ vec4\_y} = \text{three.y} - \text{four.y};
  if ((\text{vec1}_x / \text{vec2}_x == \text{vec1}_y / \text{vec2}_y) \| (\text{vec3}_x / \text{vec4}_x == \text{vec3}_y / \text{vec4}_y) \|
//отношение соответствующих координат
        (\text{vec1}_x == 0 \&\& \text{vec2}_x == 0) \parallel (\text{vec1}_y == 0 \&\& \text{vec2}_y == 0) \parallel (\text{vec3}_x == 0 \&\&
vec4_x == 0 || (vec3_y == 0 \&\& vec4_y == 0)) {
     return 1;
  return 0;
}
template<class T>
vertex<double> Trapezoid<T>::Center() const {
  vertex<double> center;
  center = one + two + three + four;
  center /= 4;
  return center;
}
template<class T>
void Trapezoid<T>::Print() const {
  std::cout << one << " " << two << " " << three << " " << four << '\n';
}
template<class T>
double Trapezoid<T>::Area() const {
  const T area1 = 0.5 * abs((three.x - two.x) * (four.y - two.y) - (four.x - two.x) * (three.y -
two.y));
  const T area2 = 0.5 * abs((one.x - two.x) * (four.y - two.y) - (four.x - two.x) * (one.y - two.y));
  return area1 + area2;
}
#endif
square.h
#ifndef D_SQUARE_H_
#define D_SQUARE_H_
#include <iostream>
#include <assert.h>
#include <math.h>
#include "vertex.h"
```

```
template<class T>
struct Square {
  Square(std::istream &is);
  int IsCorrect() const;
  vertex<double> Center() const;
  void Print() const;
  double Area() const;
private:
  vertex<T> one,two,three,four;
};
template<class T>
Square<T>::Square(std::istream &is){
  is >> one >> two >> three >> four;
  assert(IsCorrect());
}
template<class T>
int Square<T>::IsCorrect() const {
  const T \text{ vec1}_x = \text{two.x} - \text{one.x};
  const T vec1_y = two.y - one.y;
  const T vec2_x = three.x - two.x;
  const T vec2_y = three.y - two.y;
  const T vec3_x = four.x - one.x;
  const T vec3_y = four.y - one.y;
  const T vec4_x = four.x - three.x;
  const T vec4_y = four.y - three.y;
  const T dotProduct1 = vec1_x * vec2_x + vec1_y * vec2_y;
  const T dotProduct2 = vec3_x * vec1_x + vec3_y * vec1_y;
  const T dotProduct3 = vec3_x * vec4_x + vec3_y * vec4_y;
  const T vec1_length = sqrt(vec1_x * vec1_x + vec1_y * vec1_y);
  const T vec2_length = sqrt(vec2_x * vec2_x + vec2_y * vec2_y);
  if (dotProduct1 == 0 && dotProduct2 == 0 && dotProduct3 == 0 && vec1_length ==
vec2_length) {
    return 1;
  return 0;
template<class T>
vertex<double> Square<T>::Center() const {
  vertex<double> center;
```

```
center.x = (one.x + three.x) / 2;
  center.y = (one.y + three.y) / 2;
  return center;
}
template<class T>
void Square<T>::Print() const {
  std::cout << one << " " << two << " " << three << " " << four << '\n';
template<class T>
double Square<T>::Area() const {
  const T vecX = two.x - one.x;
  const T vecY = two.y - one.y;
  return vecX * vecX + vecY * vecY;
}
#endif
rectangle.h
#ifndef D_RECTANGLE_H_
#define D_RECTANGLE_H_
#include <iostream>
#include <assert.h>
#include <math.h>
#include "vertex.h"
template<class T>
struct Rectangle {
  Rectangle(std::istream &is);
  int IsCorrect() const;
  vertex<double> Center() const;
  void Print() const;
  double Area() const;
private:
  vertex<T> one,two,three,four;
};
template<class T>
Rectangle<T>::Rectangle(std::istream &is){
  is >> one >> two >> three >> four;
  assert(IsCorrect());
```

```
template<class T>
int Rectangle<T>::IsCorrect() const {
  const T vec1_x = two.x - one.x;
  const T vec1_y = two.y - one.y;
  const T vec2_x = three.x - two.x;
  const T vec2_y = three.y - two.y;
  const T vec3_x = four.x - one.x;
  const T vec3_y = four.y - one.y;
  const T vec4 x = four.x - three.x;
  const T vec4_y = four.y - three.y;
  const T dotProduct1 = vec1_x * vec2_x + vec1_y * vec2_y;
  const T dotProduct2 = vec3_x * vec1_x + vec3_y * vec1_y;
  const T dotProduct3 = vec3_x * vec4_x + vec3_y * vec4_y;
  if (dotProduct1 == 0 \&\& dotProduct2 == 0 \&\& dotProduct3 == 0) 
    return 1;
  }
  return 0;
}
template<class T>
vertex<double> Rectangle<T>::Center() const {
  vertex<double> center;
  center.x = (one.x + three.x) / 2;
  center.y = (one.y + three.y) / 2;
  return center;
}
template<class T>
void Rectangle<T>::Print() const {
  std::cout << one << " " << two << " " << three << " " << four << '\n';
}
template<class T>
double Rectangle<T>::Area() const {
  const T xHeight = two.x - one.x;
  const T yHeight = two.y - one.y;
  const T xWidth = three.x - two.x;
  const T yWidth = three.y - two.y;
  return sqrt(xHeight * xHeight + yHeight * yHeight) * sqrt(xWidth * xWidth + yWidth *
yWidth);
#endif
```

main.cpp

```
#include "square.h"
#include "rectangle.h"
#include "trapezoid.h"
#include "templates.h"
int main() {
  int input;
  while (true) {
     std::cout << "0: Exit" << std::endl;
     std::cout << "1: Fake figure demonstration" << std::endl;</pre>
     std::cout << "2: Array figure demonstration" << std::endl;</pre>
     std::cout << "3: Real figure demonstration" << std::endl;</pre>
     std::cin >> input;
     if (input == 0) {
       break;
     if (input > 3) {
       std::cout << "Invalid input" << std::endl;</pre>
    switch (input) {
       case 1: {
          std::cout << "Fake Square (float):" << std::endl;</pre>
          std::tuple<vertex<float>, vertex<float>, vertex<float>, vertex<float>>
               fakeSquare{{0, 0}, {0, 0.5}, {0.5, 0.5}, {0.5, 0}};
          std::cout << "Coordinates: ";</pre>
          Print(fakeSquare);
          std::cout << std::endl;</pre>
          std::cout << "Center: " << Center(fakeSquare) << std::endl;</pre>
          std::cout << "Area: " << Area(fakeSquare) << std::endl << std::endl;
          std::cout << "Fake Rectangle (int):" << std::endl;</pre>
          std::tuple<vertex<int>, vertex<int>, vertex<int>, vertex<int>>
               fakeRectangle{{0, 0}, {0, 2}, {10, 2}, {10, 0}};
          std::cout << "Coordinates: ";</pre>
          Print(fakeRectangle);
          std::cout << std::endl;</pre>
          std::cout << "Center: " << Center(fakeRectangle) << std::endl;</pre>
          std::cout << "Area: " << Area(fakeRectangle) << std::endl << std::endl;
          std::cout << "Fake Trapezoid (double):" << std::endl;</pre>
          std::tuple<vertex<double>, vertex<double>, vertex<double>,
```

```
fakeTrapezoid{{0, 0}, {0.5, 2}, {2, 2}, {15.5, 0}};
  std::cout << "Coordinates: ";</pre>
  Print(fakeTrapezoid);
  std::cout << std::endl;</pre>
  std::cout << "Center: " << Center(fakeTrapezoid) << std::endl;</pre>
  std::cout << "Area: " << Area(fakeTrapezoid) << std::endl << std::endl;</pre>
break;
}
case 2: {
  std::cout << "Array Square (double):" << std::endl;</pre>
  std::array<vertex<double>, 4>
        array_Square{{{0, 0}, {0, 2}, {2, 2}, {2, 0}}};
  std::cout << "Coordinates: ";</pre>
  Print(array_Square);
  std::cout << std::endl;</pre>
  std::cout << "Center: " << Center(array_Square) << std::endl;</pre>
  std::cout << "Area: " << Area(array_Square) << std::endl << std::endl;</pre>
  std::cout << "Array Trapezoid (float):" << std::endl;</pre>
  std::array<vertex<float>, 4>
        array_Trapezoid{{{0, 0}, {1, 2}, {2, 2}, {3, 0}}};
  std::cout << "Coordinates: ";</pre>
  Print(array_Trapezoid);
  std::cout << std::endl;</pre>
  std::cout << "Center: " << Center(array_Trapezoid) << std::endl;</pre>
  std::cout << "Area: " << Area(array Trapezoid) << std::endl << std::endl;
break:
}
case 3: {
  int realID;
  std::cout << "Input real figure id:" << std::endl;
  std::cout << "1: Square" << std::endl;
  std::cout << "2: Rectangle" << std::endl;</pre>
  std::cout << "3: Trapezoid" << std::endl;</pre>
  std::cin >> realID;
  switch (realID) {
     case 1: {
        std::cout << "Input 4 coordinates in a sequence" << std::endl;
        Square<double> realSquare(std::cin);
        std::cout << "Coordinates: ";</pre>
        Print(realSquare);
        std::cout << std::endl;</pre>
        std::cout << "Center: " << Center(realSquare) << std::endl;</pre>
        std::cout << "Area: " << Area(realSquare) << std::endl << std::endl;
     break;
```

```
}
            case 2: {
               std::cout << "Input 4 coordinates in a sequence" << std::endl;
               Rectangle<double> realRectangle(std::cin);
               std::cout << "Coordinates: ";</pre>
               Print(realRectangle);
               std::cout << std::endl;</pre>
               std::cout << "Center: " << Center(realRectangle) << std::endl;</pre>
               std::cout << "Area: " << Area(realRectangle) << std::endl << std::endl;</pre>
            break;
            }
            case 3: {
               std::cout << "Input 4 coordinates in a sequence" << std::endl;
              Trapezoid<double> realTrapezoid(std::cin);
               std::cout << "Coordinates: ";</pre>
               Print(realTrapezoid);
               std::cout << std::endl;</pre>
               std::cout << "Center: " << Center(realTrapezoid) << std::endl;</pre>
               std::cout << "Area: " << Area(realTrapezoid) << std::endl << std::endl;</pre>
            break;
            }
          }
       break;
     }
  }
  return 0;
Makefile:
all: oop_exercise_04
oop_exercise_04: main.cpp rectangle.h square.h trapezoid.h vertex.h templates.h
    g++ -std=c++17 -Wall main.cpp -o oop_exercise_04
clean:
    rm -rf *.o oop_exercise_04
2. Ссылка на репозиторий на GitHub.
https://github.com/ArtemKD/oop_exercise_04
```

```
3. Haбop testcases.
test 01.test:
```

1 2

test_03.test:

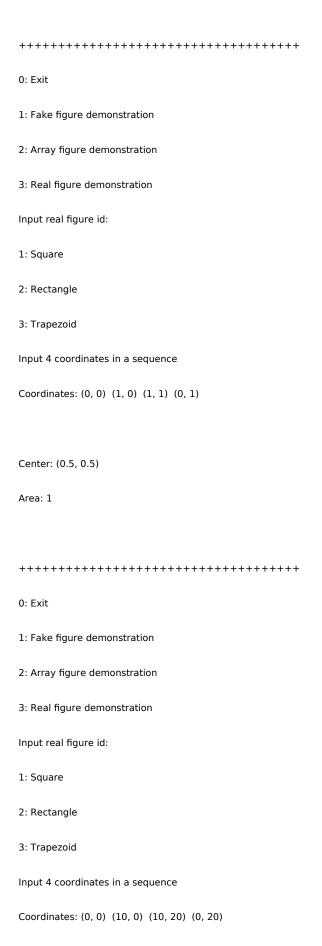
3

1
0 100
100 100
100 0
0 0
3
2
0 0
0.4 0
0.4 1000
0 1000
3
3
0 0
50 50
150 50
100 0
0
4. Результаты выполнения тестов test_01.test:
+++++++++++++++++++++++++++++++++++++++
0: Exit
1: Fake figure demonstration
2: Array figure demonstration
3: Real figure demonstration
Fake Square (float):

Coordinates: (0, 0) (0, 0.5) (0.5, 0.5) (0.5, 0)

```
Center: (0.25, 0.25)
Area: 0.25
Fake Rectangle (int):
Coordinates: (0, 0) (0, 2) (10, 2) (10, 0)
Center: (5, 1)
Area: 20
Fake Trapezoid (double):
Coordinates: (0, 0) (0.5, 2) (2, 2) (15.5, 0)
Center: (4.5, 1)
Area: 17
0: Exit
1: Fake figure demonstration
2: Array figure demonstration
3: Real figure demonstration
Array Square (double):
Coordinates: (0, 0) (0, 2) (2, 2) (2, 0)
Center: (1, 1)
Area: 4
Array Trapezoid (float):
Coordinates: (0, 0) (1, 2) (2, 2) (3, 0)
Center: (1.5, 1)
```

Area: 4



Center: (5, 10)
Area: 200
+++++++++++++++++++++++++++++++++++++++
0: Exit
1: Fake figure demonstration
2: Array figure demonstration
3: Real figure demonstration
Input real figure id:
1: Square
2: Rectangle
3: Trapezoid
Input 4 coordinates in a sequence
Coordinates: (0, 0) (1, 2) (2, 2) (3, 0)
Center: (1.5, 1)
Area: 4
+++++++++++++++++++++++++++++++++++++++
0: Exit
1: Fake figure demonstration
2: Array figure demonstration
3: Real figure demonstration
test_02.test: ++++++++++++++++++++++++++++++++++++

2: Rectangle 2: Rectangle
3: Trapezoid
Input 4 coordinates in a sequence
oop_exercise_04: /home/vladislav/Pa6oчий стол/prog_3_sem/oop_labs/lab_04/square.h:26: Square<T>::Square(std::istream&) [with
T = double; std::istream = std::basic_istream<char>]: Assertion `lsCorrect()' failed.
[1] 25916 abort (core dumped) ./oop_exercise_04 < test_02.test > test_02.result test_03.test: 0: Exit 1: Fake figure demonstration 2: Array figure demonstration 3: Real figure demonstration Input real figure id: 1: Square 2: Rectangle 3: Trapezoid Input 4 coordinates in a sequence Coordinates: (0, 100) (100, 100) (100, 0) (0, 0)

Center: (50, 50)

Area: 10000

- 0: Exit
- 1: Fake figure demonstration
- 2: Array figure demonstration
- 3: Real figure demonstration

Input real figure id:

- 1: Square
- 2: Rectangle
- 3: Trapezoid

Input 4 coordinates in a sequence
Coordinates: (0, 0) (0.4, 0) (0.4, 1000) (0, 1000)
Center: (0.2, 500) Area: 400
Area: 400
+++++++++++++++++++++++++++++++++++++++
0: Exit
1: Fake figure demonstration
2: Array figure demonstration
3: Real figure demonstration
Input real figure id:
1: Square
2: Rectangle
3: Trapezoid
Input 4 coordinates in a sequence
Coordinates: (0, 0) (50, 50) (150, 50) (100, 0)
Center: (75, 25)
Area: 5000
+++++++++++++++++++++++++++++++++++++++
0: Exit
1: Fake figure demonstration
2: Array figure demonstration
3: Real figure demonstration

5. Объяснение результатов работы программы.

Пользователь выбирает демонстрацию работы программы с использованием массива точек, tuple или заданных классов. При нажатии 1 выводятся координаты вершин, геометрический центр и площадь трёх фигур: квадрата с вершинами типа float, прямоугольника с вершинами типа int и трапеции с вершинами типа double. При нажатии 2 выводятся координаты вершин, геометрический центр и площадь квадрата и трапеции, заданных в виде массива. При нажатии 3 пользователь сам выбирает одну из трёх фигур и вводит координаты их вершин. После этого выводятся координаты вершин и геометрического центра и площадь введённой фигуры.

6. Вывод.

Выполняя данную лабораторную я изучил основы метапрограммирования, применения шаблонов класса в рамках реализации классов фигур с вершинами с переменным типом данных, причём методы данных классов могут работать с tuple.