# CodingLab2\_A\_Shlychkov\_E\_Seiffert\_A\_Gittel

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Neural Data Science

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# 1 Coding Lab 2

- Data: Use the saved data nds\_cl\_1\_\*.npy from Coding Lab 1. Or, if needed, download the data files nds\_cl\_1\_\*.npy from ILIAS and save it in the subfolder .../data/.
- Dependencies: You don't have to use the exact versions of all the dependencies in this notebook, as long as they are new enough. But if you run "Run All" in Jupyter and the boilerplate code breaks, you probably need to upgrade them.

```
[]: import numpy as np
     import scipy as sp
     import matplotlib.pyplot as plt
     from sklearn.cluster import KMeans
     from __future__ import annotations
     import matplotlib
     import scipy.stats as stats
     from scipy.stats import multivariate_normal
     import scipy as sp
     # import lda from sklearn
     from sklearn.discriminant_analysis import LinearDiscriminantAnalysis as LDA
     from sklearn.mixture import GaussianMixture
     %load_ext jupyter_black
     %load_ext watermark
     %watermark --time --date --timezone --updated --python --iversions --watermark ⊔
      ⊶-p sklearn
```

The jupyter\_black extension is already loaded. To reload it, use: %reload\_ext\_jupyter\_black

The watermark extension is already loaded. To reload it, use:

%reload\_ext watermark

Last updated: 2024-05-12 21:31:49Mitteleuropäische Sommerzeit

Python implementation: CPython Python version : 3.10.0 IPython version : 8.24.0

sklearn: 1.4.2

matplotlib: 3.8.4 scipy : 1.13.0 numpy : 1.26.4

Watermark: 2.4.3

```
[]: plt.style.use("../matplotlib_style.txt")
```

#### 1.1 Load data

```
[]: # replace by path to your solutions
features = np.load("../data/nds_cl_1_features.npy")
s = np.load("../data/nds_cl_1_spiketimes_s.npy")
w = np.load("../data/nds_cl_1_waveforms.npy")
np.random.seed(0)
```

#### 1.2 Task 1: Generate toy data

Sample 1000 data points from a two dimensional mixture of Gaussian model with three clusters and the following parameters:

$$\mu_{1} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \Sigma_{1} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \pi_{1} = 0.3$$

$$\mu_{2} = \begin{bmatrix} 5 \\ 1 \end{bmatrix}, \Sigma_{2} = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}, \pi_{2} = 0.5$$

$$\mu_{3} = \begin{bmatrix} 0 \\ 4 \end{bmatrix}, \Sigma_{3} = \begin{bmatrix} 1 & -0.5 \\ -0.5 & 1 \end{bmatrix}, \pi_{3} = 0.2$$

Plot the sampled data points and indicate in color the cluster each point came from. Plot the cluster means as well.

Grading: 1 pts

```
[]: def sample_data(
    n_samples: int,
    means: np.ndarray,
    covariances: np.ndarray,
```

```
priors: np.ndarray,
    random_seed: int = 2046,
) -> tuple[np.ndarray, np.ndarray]:
    \hbox{\it """Generate $n\_$ samples samples from a Mixture of Gaussian distribution with}\\
    means m, covariances S and priors p.
    Parameters
    n_samples: int
        Number of samples
    m: np.ndarray, (n_clusters, n_dims)
        Means
    S: np.ndarray, (n_clusters, n_dims, n_dims)
        Covariances
    p: np.ndarray, (n_clusters, )
        Cluster weights / probablities
    random_seed: int
        Random Seed
    Returns
    _____
    labels: np.array, (n_samples, )
        Grund truth labels.
    x: np.array, (n_samples, n_dims)
       Data points
    n n n
    # ensure reproducibility using a random number generator
    # hint: access random functions of this generator
    rng = np.random.default_rng(random_seed)
    # insert your code here
    cluster_ids = np.random.choice(
        [0, 1, 2], n_samples, p=priors
    ) # return a vector of N cluster ids sampled from the given priors
    data = np.array(
            np.random.multivariate_normal(mean=means[id], cov=covariances[id])
            for id in cluster_ids
        ]
```

```
) # create a data point for each entry of the cluster_ids vector by sampling from the multivariate normal distribution with the means and covariances correcponding to the cluster_ids

return data, cluster_ids
```

```
[]: N = 1000  # total number of samples

priors = np.array([0.3, 0.5, 0.2])  # percentage of each cluster
means = np.array([[0.0, 0.0], [5.0, 1.0], [0.0, 4.0]])  # means
g_means = np.array([[0.0, 0.0], [5.0, 1.0], [0.0, 4.0]])

S1 = np.array([[1.0, 0.0], [0.0, 1.0]])
S2 = np.array([[2.0, 1.0], [1.0, 2.0]])
S3 = np.array([[1.0, -0.5], [-0.5, 1.0]])
S = np.stack([S1, S2, S3])  # cov

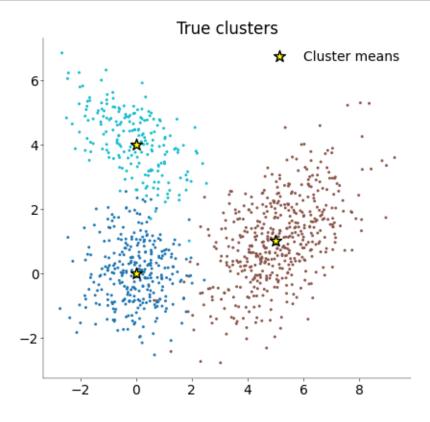
toy_data, toy_cluster_ids_true = sample_data(N, means, S, priors)
```

```
# plot points from mixture of Gaussians (0.5 pt)
def plot_clustering(data, true_cluster_ids, fit_cluster_ids, true_means,_
 →fit means):
    11 11 11
    Plots the (2D) data as scatter plot, with different colors and an extra\Box
 symbol for the mean per cluster.
    Args:
        data: (N, n\_dimensions) - shaped array of data
        cluster_ids: (N,)-shaped array of integers that hold the cluster ⊔
 \neg assignment\ for\ each\ data\ point
        means : (n_cluster, n_dimensions)-shaped array of mean vectors
        title: string that is added as title
    11 11 11
    mosaic = [["True", "MoG"]]
    fig, ax = plt.subplot_mosaic(mosaic=mosaic, figsize=(8, 4),__
 ⇔layout="constrained")
    cmap = matplotlib.colormaps["tab10"]
    colors = cmap(np.linspace(0, 1, len(true_means)))
    for i, k in enumerate(mosaic):
        true = k[0]
        fit = k[1]
```

```
ax[true].scatter(x=data[:, 0], y=data[:, 1],__
⇔c=colors[true_cluster_ids], s=5)
      ax[true].set_title("True clusters")
      for j, mean in enumerate(true_means):
           if j == 0:
               ax[true].scatter(
                   mean[0],
                   mean[1],
                   s=80,
                   c="yellow",
                   marker="*",
                   edgecolor="black",
                   linewidth=1,
                   label="Cluster means",
               )
           else:
               ax[true].scatter(
                   mean[0],
                   mean[1],
                   s=80,
                   c="yellow",
                   marker="*",
                   edgecolor="black",
                   linewidth=1,
               )
      ax[true].legend()
      if fit_cluster_ids is not None:
           ax[fit].scatter(x=data[:, 0], y=data[:, 1],__

¬c=colors[fit_cluster_ids], s=5)
           ax[fit].set_title("Predicted clusters")
           for j, mean in enumerate(fit_means):
               if j == 0:
                   ax[fit].scatter(
                       mean[0],
                       mean[1],
                       s=80,
                       c="yellow",
                       marker="*",
                       edgecolor="black",
                       linewidth=1,
                       label="Cluster means",
                   )
               else:
                   ax[fit].scatter(
```

[]: plot\_clustering(toy\_data, toy\_cluster\_ids\_true, None, means, None)



#### 1.3 Task 2: Implement a Gaussian mixture model

Implement the EM algorithm to fit a Gaussian mixture model in fit\_mog(). Sort the data points by inferring their class labels from your mixture model (by using maximum a-posteriori classification). Fix the seed of the random number generator to ensure deterministic and reproducible behavior. Test it on the toy dataset specifying the correct number of clusters and make sure the code works correctly. Plot the data points from the toy dataset and indicate in color the cluster each point was assigned to by your model. How does the assignment compare to ground truth? If you run

the algorithm multiple times, you will notice that some solutions provide suboptimal clustering solutions - depending on your initialization strategy.

Grading: 4 pts

It is important to initialize the means, covariances and mixing coefficients appropriately. Also, during optimization, covariance matrices can become singular. To prevent this, one can add a small constant (like  $10^{-6}$ ) to the diagonal.

```
[]: def initialize clusters(data, n clusters):
         """Function that initializes the means and covariances for the EM algorithm
         Args:
             data: (N, n_dimensions)-shaped array of data
             n clusters: number of clusters
             means: (n_cluster, n_dimensions)-shaped array of mean vectors
             covariances: (n dimensions, n dimensions, n cluster)-shaped array of \Box
      ⇔covariance matrices
             priors: (n_cluster)-shaped arrays of priors / mixing coefficients
         clusters = []
         k_means = KMeans(n_clusters).fit(data)
         mu_k = k_means.cluster_centers_
         # initialize a dictionary containing means, covariances and probabilities,
      ⇔for each cluster
         for i in range(n_clusters):
             clusters.append(
                 {
                     # the initial weight (or probability) of each cluster.
                     "pi k": 1.0 / n clusters,
                     # corresponding mean from the mu_k array obtained from KMeans
                     "mu k": mu k[i],
                     # the initial covariance matrix of each cluster.
                     "cov k": np.cov(data, rowvar=False),
                 }
             )
         return clusters
```

E - step

```
[]: def expectation_step(data, clusters):
    """Function that performs the E-step of the EM algorithm
    Args:
        data: (N,n_dimensions)-shaped array of data
        clusters: list of dictionaries, each containing the parameters for a
    ⇔cluster
    Returns:
```

```
expectation: N,n_clusters)-shaped array of expected cluster assignments
      totals: (N,1)-shaped array of total probabilities
   11 11 11
  N = data.shape[0] # number of data points
  K = len(clusters) # number of clusters
  totals = np.zeros((N, 1), dtype=np.float64) # initialize totals array
  # initialize expectation array
  expectation = np.zeros((N, K), dtype=np.float64)
  for k, cluster in enumerate(clusters):
      pi_k = cluster["pi_k"]
      mu k = cluster["mu k"]
      cov_k = cluster["cov_k"]
      # add a small value to the diagonal of the covariance matrix to avoid
⇔singular matrices
      cov_k += 1e-6 * np.identity(data.shape[1], dtype=np.float64)
      expectation[:, k] = pi_k * (
          stats.multivariate normal(mean=mu k, cov=cov k).pdf(data)
      )
  totals = np.sum(expectation, 1)
  expectation /= np.expand_dims(totals, 1)
  return expectation
```

#### M - step

```
[]: def maximization_step(data, clusters):
    """Function that performs the M-step of the EM algorithm
    Args:
        data: (N,n_dimensions)-shaped array of data
        clusters: list of dictionaries, each containing the parameters for a_
        cluster
        Returns:
            updated cluster parameters
        """

        expectation = expectation_step(data, clusters)

        N = float(data.shape[0]) # number of data points

        for k, cluster in enumerate(clusters):

        # Extract the expectation values for cluster k
```

```
expectation_k = expectation[:, k]

# Calculate N_k (total responsibility for cluster k)
N_k = np.sum(expectation_k)

# Update cluster parameters
pi_k = N_k / N
mu_k = np.sum(expectation_k.reshape(-1, 1) * data, axis=0) / N_k
cov_k = (expectation_k.reshape(-1, 1) * (data - mu_k)).T @ (data - mu_k) / N_k

# Update cluster parameters in the cluster dictionary
cluster["pi_k"] = pi_k
cluster["mu_k"] = mu_k
cluster["cov_k"] = cov_k
```

Combining the E-step and the M-step together

```
[]: def fit_mog(
        data: np.ndarray, n_clusters: int, n_iters: int = 10, random_seed: int = __
      →2046
     ) -> tuple[np.ndarray]:
         """Fit Mixture of Gaussian model using EM algo.
        Parameters
         _____
         data: np.array, (n_samples, n_dims)
             Input data
         n_clusters: int
             Number of clusters
         n_iters: int
             Maximal number of iterations.
        random_seed: int
            Random Seed
         Returns
         _____
         labels: np.array, (n_samples)
             Cluster labels
        m: list or np.array, (n_clusters, n_dims)
```

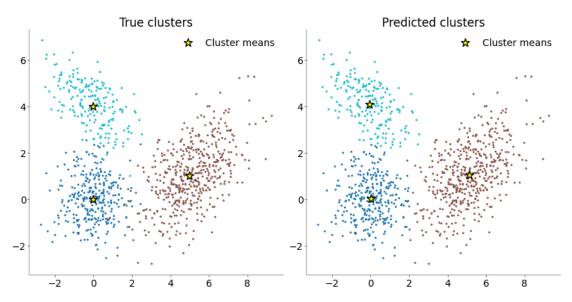
```
Means
S: list or np.array, (n_clusters, n_dims, n_dims)
    Covariances
p: list or np.array, (n_clusters, )
    Cluster weights / probablities
.....
# ensure reproducibility using a random number generator
rng = np.random.default rng(random seed)
# fill in your code here
# -----
# init (1 pt)
# -----
clusters = initialize_clusters(data, n_clusters) # initialize clusters
scores = np.zeros((data.shape[0], n_clusters)) # initialize scores array
# -----
# EM maximisation (2.5 pts)
# -----
for step in range(n_iters):
   expectation_step(data, clusters) # E-step
   maximization_step(data, clusters) # M-step
expectation = expectation_step(data, clusters)
scores = np.log(expectation)
# extract the means from the cluster dictionary
cluster_means = np.array([cluster["mu_k"] for cluster in clusters])
# assign each data point to the cluster with the highest score
cluster_ids = np.argmax(scores, axis=1)
covariances = np.array([cluster["cov_k"] for cluster in clusters])
priors = np.array([cluster["pi_k"] for cluster in clusters])
return cluster_ids, cluster_means, covariances, priors
```

Run Mixture of Gaussian on toy data

```
[]: toy_cluster_ids_fit, toy_means_fit, covariances, priors = fit_mog(toy_data, 3) print(toy_means_fit.shape)
```

(3, 2)

Plot toy data with cluster assignments and compare to original labels



## 1.4 Task 3: Model complexity

A priori we do not know how many neurons we recorded. Extend your algorithm with an automatic procedure to select the appropriate number of mixture components (clusters). Base your decision on the Bayesian Information Criterion:

$$BIC = -2L + P \log N$$
,

where L is the log-likelihood of the data under the best model, P is the number of parameters of the model and N is the number of data points. You want to minimize the quantity. Plot the BIC as a function of mixture components. What is the optimal number of clusters on the toy dataset?

You can also use the BIC to make your algorithm robust against suboptimal solutions due to local minima. Start the algorithm multiple times and pick the best solutions for extra points. You will notice that this depends a lot on which initialization strategy you use.

Grading: 3 pts

```
[]: def mog_bic(
        x: np.ndarray, m: np.ndarray, S: np.ndarray, p: np.ndarray
    ) -> tuple[float, float]:
        Parameters
        -----
        x: np.array, (n_samples, n_dims)
            Input data
        m: np.array, (n_clusters, n_dims)
            Means
        S: np.array, (n_clusters, n_dims, n_dims)
            Covariances
        p: np.array, (n_clusters, )
            Cluster weights / probablities
        Return
        bic: float
           BIC
        LL: float
            Log Likelihood
        n_clusters = len(m) # number of clusters
        n_dims = x.shape[1] # number of dimensions
        n_samples = x.shape[0] # number of samples
        # LL = data_likelihood # log likelihood of the data given the model
        # Calculate the log likelihood of the data given the model
        expectation = np.zeros((n_samples, n_clusters), dtype=np.float64)
        for i, k in enumerate(range(n_clusters)):
            pi_k = p[k]
            mu_k = m[k]
            cov k = S[k]
            expectation[:, k] = pi_k * stats.multivariate_normal(mean=mu_k,__
     ⇒cov=cov_k).pdf(
               X
            totals = np.sum(expectation, 1)
```

```
[]: bic, LL = mog_bic(toy_data, toy_means_fit, S, priors) # compute BIC
```

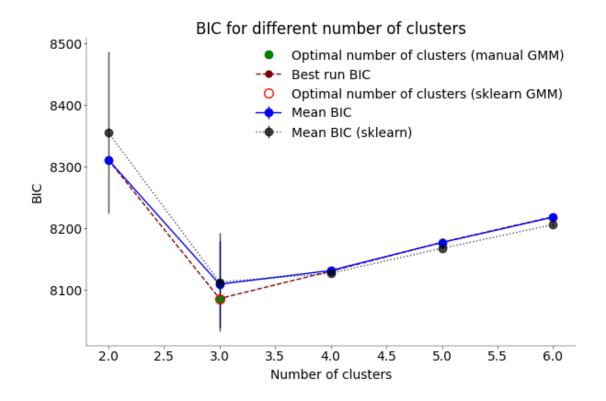
Below we will additionally compare our GMM implementation to the scikit learn GMM

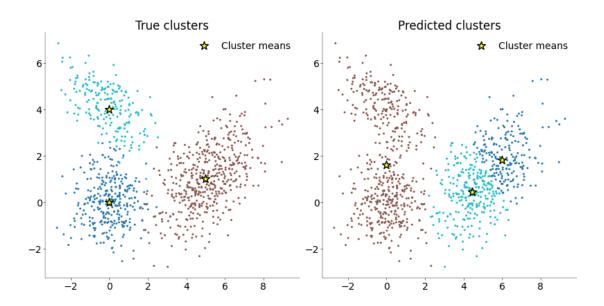
```
[]: #__
     # Compute and plot the BIC for mixture models with different numbers of \Box
     \hookrightarrow clusters (e.g., 2 - 6). (0.5 pts)
     # Make your algorithm robust against local minima. (0.5 pts) and plot the
     \hookrightarrow result (0.5 pts)
     #__
     possible_clusters = range(2, 7)
     num_seeds = 10
     BIC = np.zeros((num_seeds, len(possible_clusters)))
     LL = np.zeros((num_seeds, len(possible_clusters)))
     sklearn_BIC = np.zeros((num_seeds, len(possible_clusters)))
     sklearn_LL = np.zeros((num_seeds, len(possible_clusters)))
     # Running manual GMM
     for i, k in enumerate(possible_clusters):
         for j in range(num_seeds):
             (cluster_ids, means, covariances, priors) = fit_mog(toy_data, k)
             BIC[j, i], LL[j, i] = mog_bic(toy_data, means, covariances, priors)
     # Running sklearn GMM
     for i, k in enumerate(possible_clusters):
         for j in range(num_seeds):
```

```
sklearn_gmm = GaussianMixture(
                 n_components=k, covariance_type="full", init_params="k-means++"
             sklearn_gmm.fit(toy_data)
             sklearn_BIC[j, i], sklearn_LL[j, i] = mog_bic(
                 toy_data, sklearn_gmm.means_, sklearn_gmm.covariances_, sklearn_gmm.
      →weights_
             )
[]: # Get the optimal number of clusters for the manual GMM
     model_index, cluster_index = np.where(BIC == BIC.min())
     optimal_cluster_number = possible_clusters[cluster_index[0]]
     lowest_bic = BIC[model_index[0], :]
     print(f"Optimal number of clusters: {optimal_cluster_number}")
     # Get the optimal number of clusters for the sklearn GMM
     sklearn model index, sklearn cluster index = np.where(sklearn BIC ==___
     ⇒sklearn_BIC.min())
     sklearn_optimal_cluster_number = possible_clusters[sklearn_cluster_index[0]]
     sklearn_lowest_bic = sklearn_BIC[sklearn_model_index[0], :]
     print(f"Optimal number of clusters: {sklearn_optimal_cluster_number}")
    Optimal number of clusters: 3
    Optimal number of clusters: 3
[]: fig, ax = plt.subplots(figsize=(6, 4))
     ax.errorbar(
         possible_clusters,
         np.mean(BIC, axis=0),
         yerr=np.std(BIC, axis=0),
         fmt="o-",
         label="Mean BIC",
         color="blue",
     ax.plot(
         optimal_cluster_number,
         BIC[model_index[0], cluster_index[0]],
         color="green",
         label="Optimal number of clusters (manual GMM)",
         linestyle="",
         marker="o",
         zorder=10,
     ax.plot(
         possible_clusters,
         lowest_bic,
         color="maroon",
```

```
label="Best run BIC",
    linestyle="--",
    marker="o",
    markersize=5,
ax.errorbar(
   possible_clusters,
    np.mean(sklearn_BIC, axis=0),
    yerr=np.std(sklearn_BIC, axis=0),
    fmt="o:",
    label="Mean BIC (sklearn GMM)",
    color="black",
    alpha=0.7,
)
ax.plot(
    sklearn_optimal_cluster_number,
    sklearn_BIC[sklearn_model_index[0], sklearn_cluster_index[0]],
    color="red",
    label="Optimal number of clusters (sklearn GMM)",
    linestyle="",
    marker="o",
    mfc="none",
    markersize=7,
    zorder=10,
ax.set_xlabel("Number of clusters")
ax.set_ylabel("BIC")
ax.legend()
ax.set_title("BIC for different number of clusters")
# plot BIC
```

[]: Text(0.5, 1.0, 'BIC for different number of clusters')





# 1.5 Task 4: Spike sorting using Mixture of Gaussian

Run the full algorithm on your set of extracted features (including model complexity selection). Plot the BIC as a function of the number of mixture components on the real data. For the best model, make scatter plots of the first PCs on all four channels (6 plots). Color-code each data point according to its class label in the model with the optimal number of clusters. In addition, indicate the position (mean) of the clusters in your plot.

Grading: 3 pts

```
[]: # features = np.load(".../data/example_features.npy")

[]: #____
# Select the model that best represents the data according to the BIC (include____
aplot) (1 pt)
#___

possible_clusters = np.arange(2, 16)
num_seeds = 5

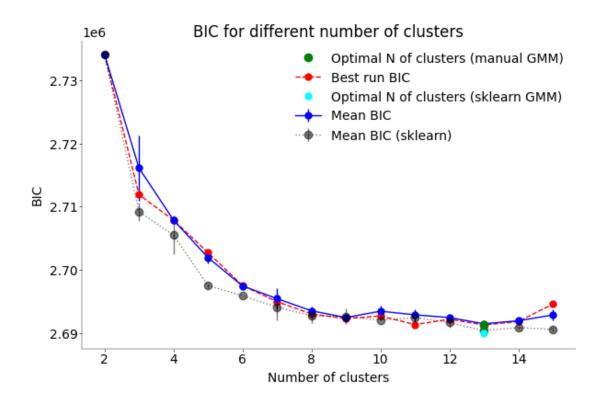
BIC = np.zeros((num_seeds, len(possible_clusters)))
LL = np.zeros((num_seeds, len(possible_clusters)))
sklearn_BIC = np.zeros((num_seeds, len(possible_clusters)))
sklearn_LL = np.zeros((num_seeds, len(possible_clusters)))
for i, k in enumerate(possible_clusters):
    for j in range(num_seeds):
```

```
cluster_ids, means, covariances, priors = fit_mog(features, k)
             BIC[j, i], LL[j, i] = mog_bic(features, means, covariances, priors)
     for i, k in enumerate(possible_clusters):
         for j in range(num_seeds):
             sklearn_gmm = GaussianMixture(
                 n_components=k, covariance_type="full", max_iter=1000
             sklearn gmm.fit(features)
             sklearn_BIC[j, i], sklearn_LL[j, i] = mog_bic(
                 features, sklearn_gmm.means_, sklearn_gmm.covariances_, sklearn_gmm.
      →weights_
[]: # Find the optimal number of clusters according to the BIC in all model runs
      ⇔and possible cluster numbers
     # Get the optimal number of clusters for the manual GMM
     model_index, cluster_index = np.where(BIC == BIC.min())
     optimal_cluster_number = possible_clusters[cluster_index[0]]
     lowest_bic = BIC[model_index[0], :]
     print(f"lowest BIC: # cluster = {optimal_cluster_number}")
     # Get the optimal number of clusters for the sklearn GMM
     sklearn_model_index, sklearn_cluster_index = np.where(sklearn_BIC ==__

¬sklearn_BIC.min())
     sklearn optimal cluster number = possible clusters[sklearn cluster index[0]]
     sklearn_lowest_bic = sklearn_BIC[sklearn_model_index[0], :]
     print(f"Optimal number of clusters: {sklearn_optimal_cluster_number}")
    lowest BIC: # cluster = 13
    Optimal number of clusters: 13
[]: fig, ax = plt.subplots(figsize=(6, 4))
     ax.errorbar(
         possible_clusters,
         np.mean(BIC, axis=0),
         yerr=np.std(BIC, axis=0),
         fmt="o-",
         label="Mean BIC",
         color="blue",
         markersize=5,
     ax.plot(
         optimal_cluster_number,
         BIC[model_index, cluster_index][0],
```

```
color="green",
    label="Optimal N of clusters (manual GMM)",
    marker="o",
    markersize=6,
    zorder=10,
    linestyle="",
)
ax.plot(
    possible_clusters,
    lowest_bic,
    color="red",
    label="Best run BIC",
    linestyle="--",
    marker="o",
    markersize=5,
)
ax.errorbar(
   possible_clusters,
    np.mean(sklearn_BIC, axis=0),
    yerr=np.std(sklearn_BIC, axis=0),
    fmt="o:",
    label="Mean BIC (sklearn GMM)",
    color="black",
    alpha=0.5,
)
ax.plot(
    sklearn_optimal_cluster_number,
    sklearn_BIC[sklearn_model_index[0], sklearn_cluster_index[0]],
    color="cyan",
    label="Optimal N of clusters (sklearn GMM)",
    linestyle="",
    marker="o",
    markersize=5,
    zorder=10,
)
ax.set_xlabel("Number of clusters")
ax.set_ylabel("BIC")
ax.legend()
ax.set_title("BIC for different number of clusters")
```

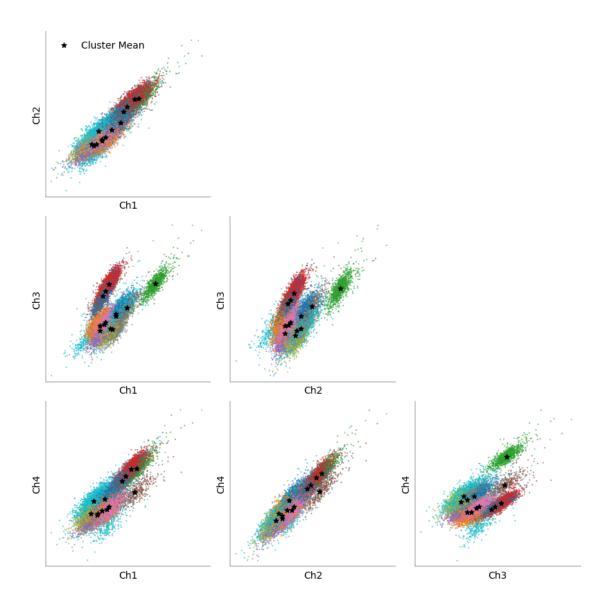
[]: Text(0.5, 1.0, 'BIC for different number of clusters')



Refit model with lowest BIC and plot data points

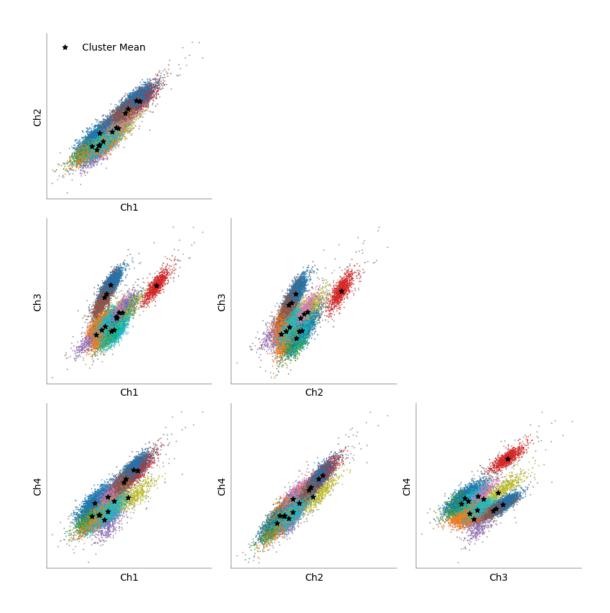
[]: GaussianMixture(n\_components=13)

```
mosaic = [
    ["Ch2 vs Ch1", ".", "."],
    ["Ch3 vs Ch1", "Ch3 vs Ch2", "."],
    ["Ch4 vs Ch1", "Ch4 vs Ch2", "Ch4 vs Ch3"],
fig, ax = plt.subplot_mosaic(mosaic=mosaic, figsize=(8, 8),__
→layout="constrained")
cmap = matplotlib.colormaps["tab10"]
colors = cmap(np.linspace(0, 1, len(means)))
i = {"Ch1": 0, "Ch2": 3, "Ch3": 6, "Ch4": 9}
for m in np.ravel(mosaic):
    if m == ".":
        continue
    y, x = m.split(" vs ")
    a = i[y]
    b = i[x]
    ax[m].scatter(features[:, a], features[:, b], s=0.5, c=colors[cluster_ids])
    # plot means of clusters
    ax[m].scatter(
        means[:, a], means[:, b], s=25, c="black", marker="*", label="Cluster_u"
 ⊶Mean"
    )
    ax["Ch2 vs Ch1"].legend()
    ax[m].set_xlabel(x)
    ax[m].set_ylabel(y)
    x_min, x_max = np.min(features[:, a]), np.max(features[:, a])
    y_min, y_max = np.min(features[:, b]), np.max(features[:, b])
    ax[m].set_xlim(1.1 * x_min, 1.1 * x_max)
    ax[m].set_ylim(1.1 * y_min, 1.1 * y_max)
    ax[m].set_xticks([])
    ax[m].set_yticks([])
```



```
len(
            sklearn_gmm.means_,
        ),
print(colors[0], colors[1])
i = {"Ch1": 0, "Ch2": 3, "Ch3": 6, "Ch4": 9}
for m in np.ravel(mosaic):
    if m == ".":
        continue
    y, x = m.split(" vs ")
    a = i[y]
    b = i[x]
    ax[m].scatter(
        features[:, a],
        features[:, b],
        s=0.5,
        c=colors[sklearn_gmm.predict(features)],
    )
    # plot means of clusters
    ax[m].scatter(
        sklearn_gmm.means_[:, a],
        sklearn_gmm.means_[:, b],
        s = 25,
        c="black",
        marker="*",
        label="Cluster Mean",
    ax["Ch2 vs Ch1"].legend()
    ax[m].set_xlabel(x)
    ax[m].set_ylabel(y)
    x_min, x_max = np.min(features[:, a]), np.max(features[:, a])
    y_min, y_max = np.min(features[:, b]), np.max(features[:, b])
    ax[m].set_xlim(1.1 * x_min, 1.1 * x_max)
    ax[m].set_ylim(1.1 * y_min, 1.1 * y_max)
    ax[m].set_xticks([])
    ax[m].set_yticks([])
```

```
[0.12156863 0.46666667 0.70588235 1. ] [0.12156863 0.46666667 0.70588235 1. ]
```



## 1.5.1 Task 5: Cluster separation

Implement linear discriminant analysis to visualize how well each cluster is separated from its neighbors in the high-dimensional space in the function **separation()**. Project the spikes of each pair of clusters onto the axis that optimally separates those two clusters.

Plot a matrix with pairwise separation plots, showing the histogram of the points in both clusters projected on the axis best separating the clusters (as shown in the lecture). *Hint:* Since Python 3.5+, matrix multiplications can be compactely written as x@y.

Grading: 4 pts

```
[]: def separation(
    b: np.ndarray,
```

```
m: np.ndarray,
   S: np.ndarray,
   assignment: np.ndarray,
   n_bins: int = 50,
):
    """Calculate cluster separation by LDA.
   proj, bins = separation(b, m, S, p, assignment)
   projects the data on the LDA axis for all pairs of clusters. The result
    is normalized such that the left (i.e. first) cluster has
    zero mean and unit variances. The LDA axis is estimated from the model.
   Parameters
    b: np.array, (n_spikes, n_features)
       Features.
   m: np.array, (n_clusters, n_features)
       Means.
   S: np.array, (n_clusters, n_features, n_features)
        Covariance.
    assignment: np.array, (n_spikes, )
        Cluster assignments / labels for each spike
    n_bins: int
       Number of bins in a lda histogram.
   Returns
    _____
   proj: np.array, (n_bins, n_clusters, n_clusters)
        computed lda histo# Comparing the cells in particular
    bins: np.array, (n_bins)
        bin times relative to center #bins x 1
    n n n
   n_clusters = len(m)
   n_features = b.shape[1]
    # initialize the lda object
   lda = LDA()
```

```
lda_results_list = []
  # lda_results_array = np.zeros((n_bins, n_clusters, n_clusters))
  for i in range(n_clusters):
      for j in range(n_clusters):
           if i == j:
              lda_results_list.append(None)
              continue
           cluster_1 = b[assignment == i] # get the data points corresponding⊔
⇔to the first cluster
           cluster_2 = b[assignment == j] # qet the data points corresponding_
→to the second cluster
           data_matrix = np.vstack([cluster_1, cluster_2]) # stack the data_
⇒points of the two clusters
           labels = np.hstack([np.zeros(len(cluster_1)), np.
→ones(len(cluster_2))]) # create a label vector for the two clusters
           lda.fit(data_matrix, labels) # fit the lda model to the data
           cluster_1_proj = lda.transform(cluster_1) # project the data points_
⇔of the first cluster
           cluster_2_proj = lda.transform(cluster_2) # project the data points_
→of the second cluster
           # normalize the data
           cluster_1_proj_mean = np.mean(cluster_1_proj)
           cluster_1_proj_std = np.std(cluster_1_proj)
           cluster_1_proj_normalized = (
              cluster_1_proj - cluster_1_proj_mean
           ) / cluster_1_proj_std
           # Normalize the second cluster using the same parameters
           cluster_2_proj_normalized = (
              cluster_2_proj - cluster_1_proj_mean
           ) / cluster_1_proj_std
           # add label to the current cluster
           label_cluster_1 = np.full_like(cluster_1_proj_normalized, i)
           label_cluster_2 = np.full_like(cluster_2_proj_normalized, j)
           cluster_1_proj_normalized = np.hstack(
               [cluster_1_proj_normalized, label_cluster_1]
           ) # add the labels to the projected data
           cluster 2 proj normalized = np.hstack(
               [cluster_2_proj_normalized, label_cluster_2]
           ) # add the labels to the projected data
```

```
lda_results_list.append(
                      (cluster_1_proj_normalized, cluster_2_proj_normalized)
                 ) # append the projected data to the lda_results_list
         return lda_results_list
[]: lda_results_list = separation(features, means, covariances, cluster_ids) #__
      \hookrightarrow compute lda
[]: print(len(lda_results_list))
    156
[]: fig, ax = plt.subplots(13, 13, figsize=(20, 20))
     cmap = matplotlib.colormaps["tab20"]
     for i in range(13):
         for j in range(13):
             if i == j:
                 # plt.delaxes(ax[i, j])
                 # ax[i, j].axis("off")
                 if i == 0 and j == 0:
                     ax[i, j].set_ylabel("Cluster 1")
                     ax[i, j].yaxis.label.set_visible(True)
                     ax[i, j].yaxis.set_visible(False)
                     ax[i, j].set_title("Cluster 1")
                     ax[i, j].xaxis.set_visible(False)
                 continue
             ax[i, j].hist(
                 lda_results_list[i * 13 + j][0][:, 0],
                 bins=50,
                 alpha=0.5,
                 label=f"Cluster {int(lda_results_list[i * 13 + j][0][0, 1])}",
                 color=cmap(i),
             )
             ax[i, j].hist(
                 lda_results_list[i * 13 + j][1][:, 0],
                 bins=50,
                 alpha=0.5,
                 label=f"Cluster {int(lda_results_list[i * 13 + j][1][0, 1])}",
                 color=cmap(j),
             )
             # ax[i, j].legend()
             if i == 0:
                 ax[i, j].set_title(f"Cluster {j+1}")
             if j == 0:
```

