

SNE3002 Linear Algebra – 2025 Spring

# Introduction to Linear Algebra

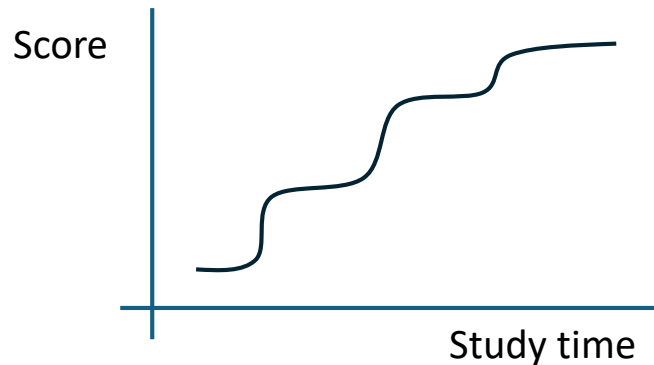


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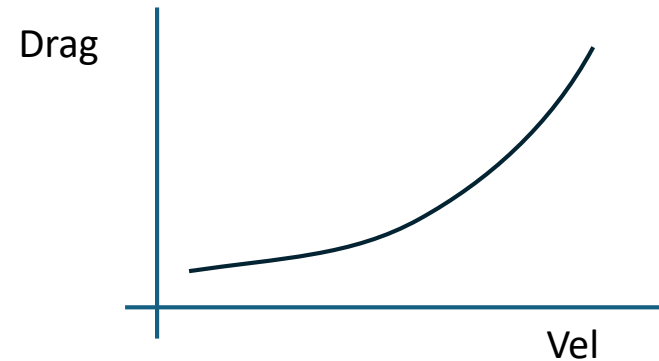
# Why Linear Algebra?

> Many things in real-world is nonlinear

- Ex. 1) Study time vs Grade



2) Velocity vs Drag force



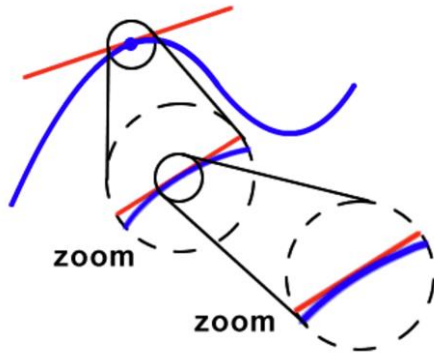
> How to deal with nonlinear system?

- There is no universal rules

> The simplest and easiest method would be linearization!

# Why Linear Algebra?

- > Everything is approximately linear.



- > The most fundamental (understandable) equations of nature appear to be linear.

$$F = ma$$

$$i\hbar \frac{\partial \psi}{\partial t} = -\frac{\hbar^2}{2m} \nabla^2 \psi + V\psi$$

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}, \quad \nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}, \quad \nabla \times \mathbf{B} = \mu_0 \mathbf{J} + \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}.$$

# Why Linear Algebra?

- > Linear Algebra – mathematical base
  - Machine Learning, Linear System, Dynamics, Control, Perception
- > Theoretically solid
  - Safe and reliable
- > Computationally efficient
  - Affordable and practical
- > When our problems are reduced to linear algebra, we can actually solve them (problem formulation is half of the job!)

# Why Linear Algebra?

## > Tangible applications

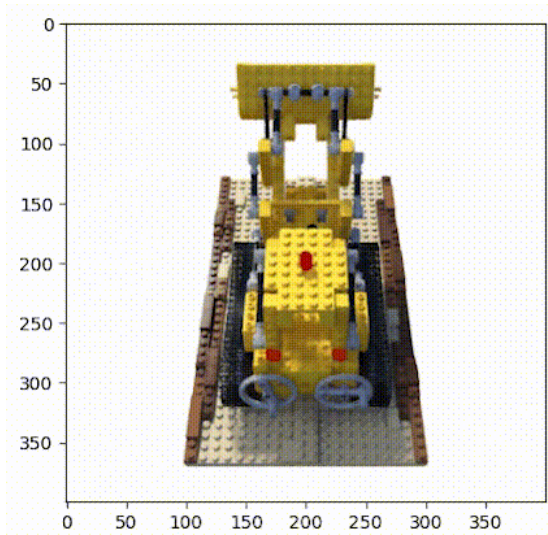
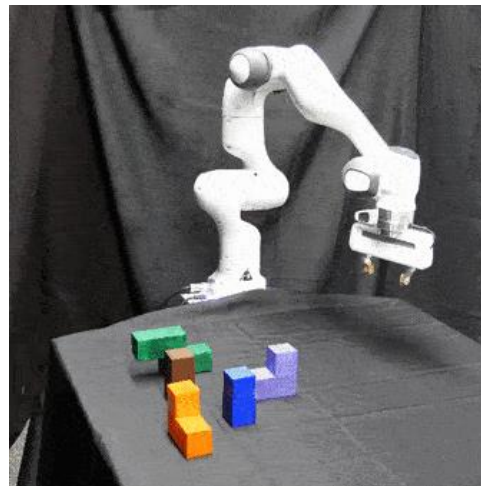
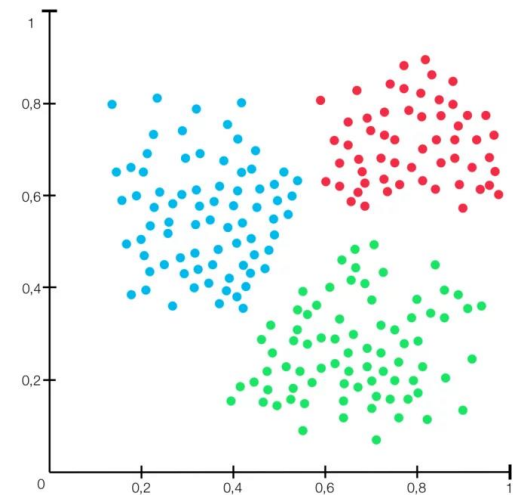


Image Processing



Manipulator Control



Data Clustering

# What is Linear Algebra?

- > Algebra : equations with variables

$$3x^2 + 4y^5 = 1$$

$$\pi e^x + \sqrt{\log(2y)} = 2$$

$$\sin(x) + \cos(2y) = 3$$

- > Linear algebra : each variable appears by itself, not raised to a power, not multiplied by each others, not inside a function (log, sin)

$$3x + 4y = 5$$

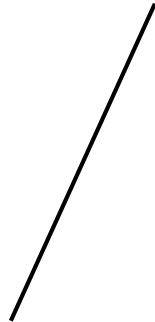
$$2x - 6y + 8z = 15$$

# What is Linear Algebra?

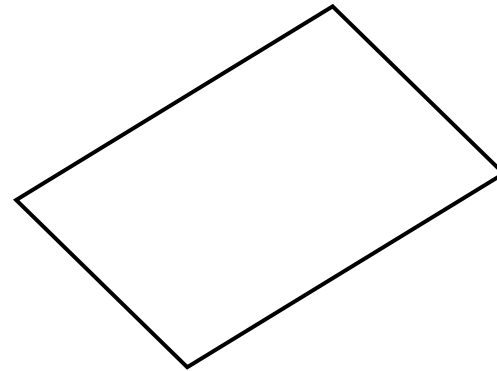
- > Geometrically, the study of 'flat', 'linear' objects like points, lines, and planes.



$$\begin{aligned}x &= \alpha \\y &= \beta \\z &= \gamma\end{aligned}$$



$$\begin{aligned}ax + by + cz &= \alpha \\cx + by + dz &= \beta\end{aligned}$$



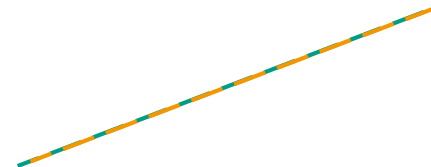
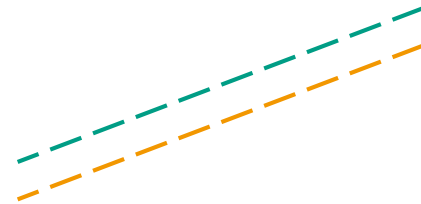
$$ax + by + cz = \alpha$$

where  $(x, y, z) \in \mathbb{R}^3$

# Linear Systems, Solutions

> A system of linear equations can have

- No solution;
- Unique solution (one and only);
- Infinite number of solutions.

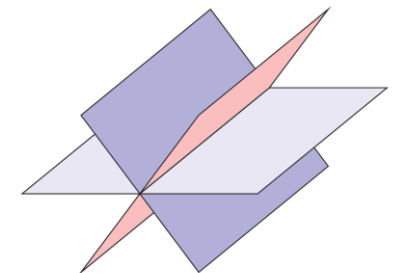
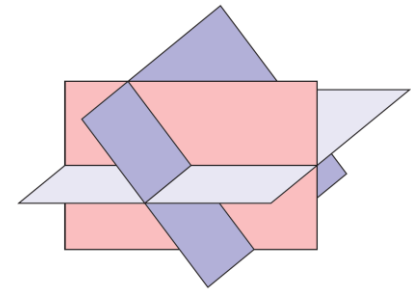
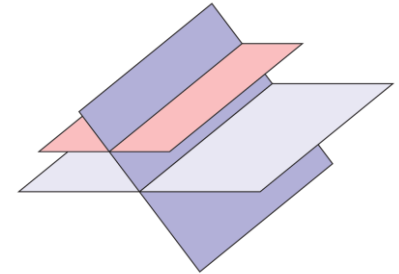




# Linear Systems, Solutions

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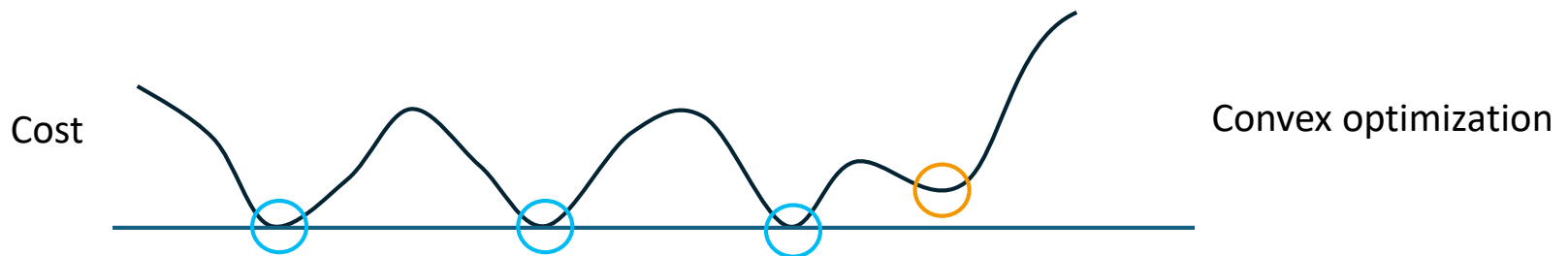


# Linear Systems, Solutions

- > A system of linear equations can have
  - No solution; Unique solution (one and only); Inf. N. of Sols.

# Linear Systems, Solutions

- > We have considered a set of **2** equations with **2** variables  $(x, y)$ .
- > What if we have **n** equations with **m** variables?
  - The same holds true: we could have a unique solution, no solution, or an infinitely many solutions.
  - There is no case we have  $>2$  (multiple) solutions.  
(Very good property for obtaining a solution)



## Row Reduced Echelon Form (RREF)

- > Q. Wanda the witch owns three types of pets – cats, ravens, and snakes. She has 10 pets in total, with a total of 16 legs and 4 wings. How many of each type of pet does she own?



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$$c + r + s = 10$$

$$4c + 2r = 16$$

$$2r = 4$$

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### Def. Augmented Matrix of a System of Linear Equations

The **augmented matrix** of the system of linear equations

$$\begin{array}{l} a_{11}x_1 + \dots + a_{1n}x_n = b_1 \\ \dots \\ a_{m1}x_1 + \dots + a_{mn}x_n = b_m \end{array} \quad \text{is} \quad \left[ \begin{array}{ccc|c} a_{11} & \cdots & a_{1n} & b_1 \\ \vdots & & \vdots & \vdots \\ a_{m1} & \cdots & a_{mn} & b_m \end{array} \right]$$

### Def. Elementary Row Operations

1. Switch two rows.
2. Multiply a row by a non-zero number.
3. Add a multiple of one row to another row.

## Row Reduced Echelon Form (RREF)

- > Q. Wanda the witch owns three types of pets – cats, ravens, and snakes. She has 10 pets in total, with a total of 16 legs and 4 wings. How many of each type of pet does she own?

$$\left[ \begin{array}{ccc|c} 1 & 1 & 1 & 10 \\ 4 & 2 & 0 & 16 \\ 0 & 2 & 0 & 4 \end{array} \right]$$

# Row Reduced Echelon Form (RREF)

## Def. Row Echelon Form

An entry of an augmented matrix is called a **leading entry** or **pivot entry** if it is the leftmost non-zero entry of a row. An augmented matrix is in **row echelon form** if

1. All rows of zeros are below all non-zero rows.
2. Each leading entry of a row is in a column to the right of the leading entry of any row above it.

$$\left[ \begin{array}{ccccc|c} 0 & 5 & 2 & 1 & 3 & 5 \\ 0 & 0 & 0 & 0 & 1 & 6 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right], \quad \left[ \begin{array}{ccccc|c} 1 & 4 & 0 & 0 & 5 & 0 \\ 0 & 0 & 1 & 0 & 2 & 0 \\ 0 & 0 & 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{array} \right], \quad \left[ \begin{array}{ccc|c} 3 & 0 & 6 & 2 \\ 0 & 1 & 4 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

✗

$$\left[ \begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ 1 & 2 & 3 & 3 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right], \quad \left[ \begin{array}{c|c} 1 & 2 \\ 2 & 4 \\ 4 & 0 \end{array} \middle| \begin{array}{c} 3 \\ -6 \\ 7 \end{array} \right], \quad \left[ \begin{array}{ccc|c} 0 & 2 & 3 & 3 \\ 1 & 5 & 0 & 2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$



# Row Reduced Echelon Form (RREF)

## Def. Row Reduced Echelon Form

An augmented matrix is in **row reduced echelon form** if

1. Each leading entry is equal to 1.
2. All entries above a leading entry are zero.

$$\left[ \begin{array}{ccccc|c} 1 & 2 & 0 & 5 & 0 & 3 \\ 0 & 0 & 1 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right], \quad \left[ \begin{array}{cccc|c} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right], \quad \left[ \begin{array}{ccc|c} 1 & 0 & 0 & 4 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 2 \end{array} \right]$$

- > The number of pivots is called the **rank**. This will be very useful later
- > The algorithm to put a matrix into RREF is Gauss-Jordan algorithm
- > RREF is unique

# Lecture Plan

- > First half semester: mathematics
- > Second half semester: mathematics + programming
- > 5 Assignments (scheduled 2<sup>rd</sup>, 4<sup>th</sup>, 5<sup>th</sup>, 10<sup>th</sup>, 11<sup>th</sup> week)
  - TA: 이민호 (mhlee00@inha.edu)
- > 1 Project? 14<sup>th</sup> week
- > Grade
  - Attendance 5% (No grade if absences reach one-quarter of total class days.)
  - Assignment 30%
  - Mid-term 30%
  - Final-term 35%

# Reference

## > Book

- Matrix Theory and Linear Algebra, Peter Selinger
- Introduction to Linear Algebra, Janis Lazovskis
- Introduction to Applied Linear Algebra, Stephen Boyd

## > Lecture

- <https://dept.math.lsa.umich.edu/~speyer/LinearAlgebraVideos/>
- <https://github.com/michiganrobotics/rob101>