
AT32F422/426 Firmware BSP&Pack User Guide

Introduction

This application note is written to give a brief description of how to use AT32F422/426 BSP (Board Support Package) and install AT32 pack.

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1 Overview

In order to help users make efficient use of Artery MCU, we provide a complete set of BSP & Pack tools to speed up development. They include peripheral driver library, core-related documents and application cases as well as Pack documents supporting a variety of development environments such as Keil_v5, Keil_v4, IAR_v6, IAR_v7 and IAR_v8. The BSP and Pack are available on Artery official website.

This application note is written to present how to use BSP and Pack.

2 How to install Pack

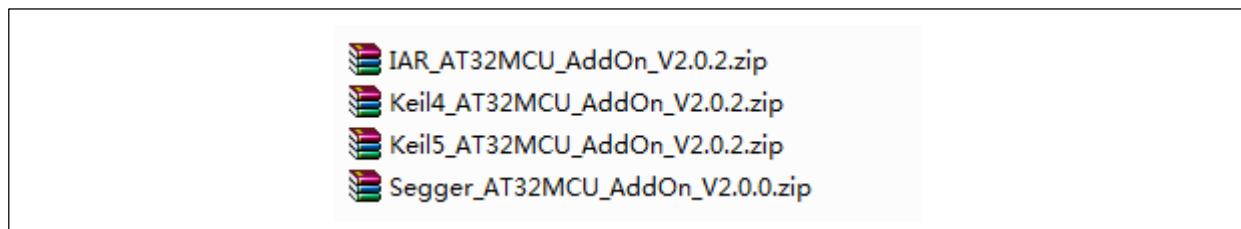
Artery Pack supports various development environment such as Keil_v5, Keil_v4, IAR_v6, IAR_v7 and IAR_v8.

Double click on the corresponding Pack to finish installation.

Note: This section takes AT32F403A as an example, and other AT32 MCUs have similar Pack installation methods.

The installation package is shown in Figure 1 (the specific version information is subject to the actual conditions).

Figure 1. Pack kit

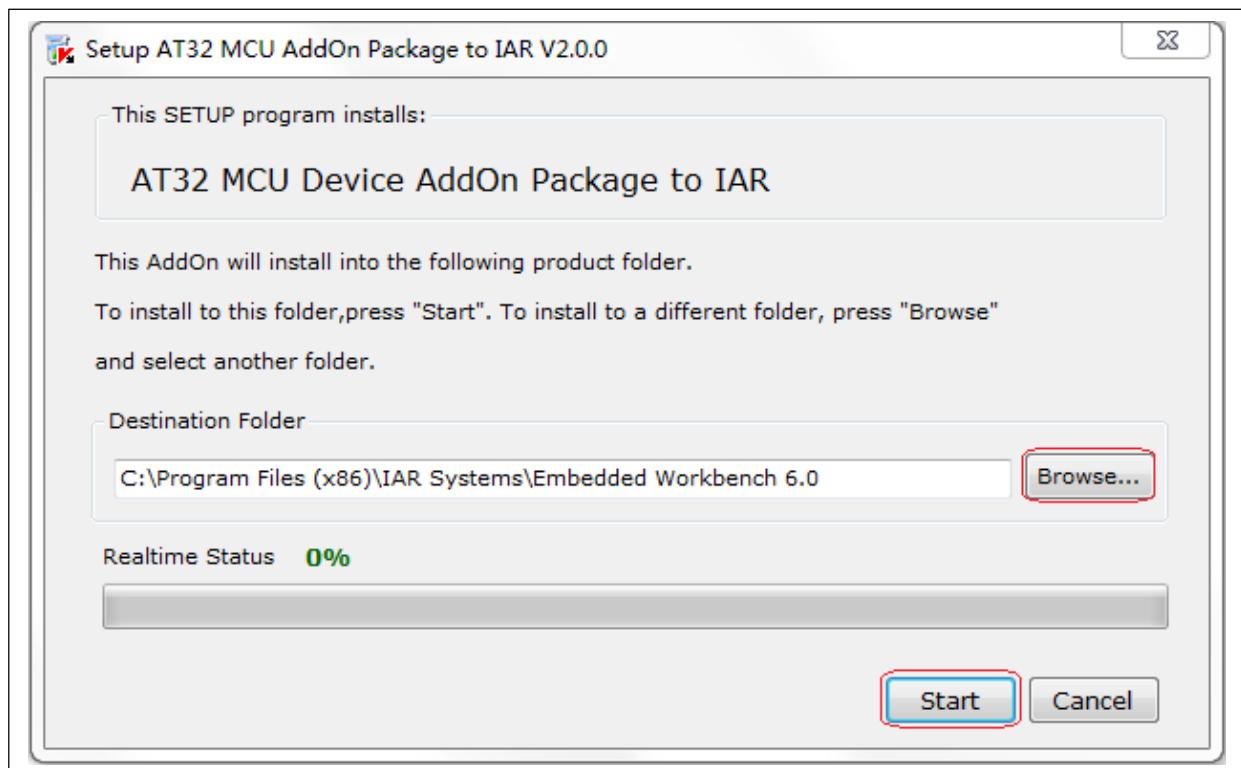


2.1 IAR Pack installation

IAR_AT32MCU_AddOn.zip: This is a zip file supporting IAR_V6, IAR_V7 and IAR_V8. Follow the steps below to install:

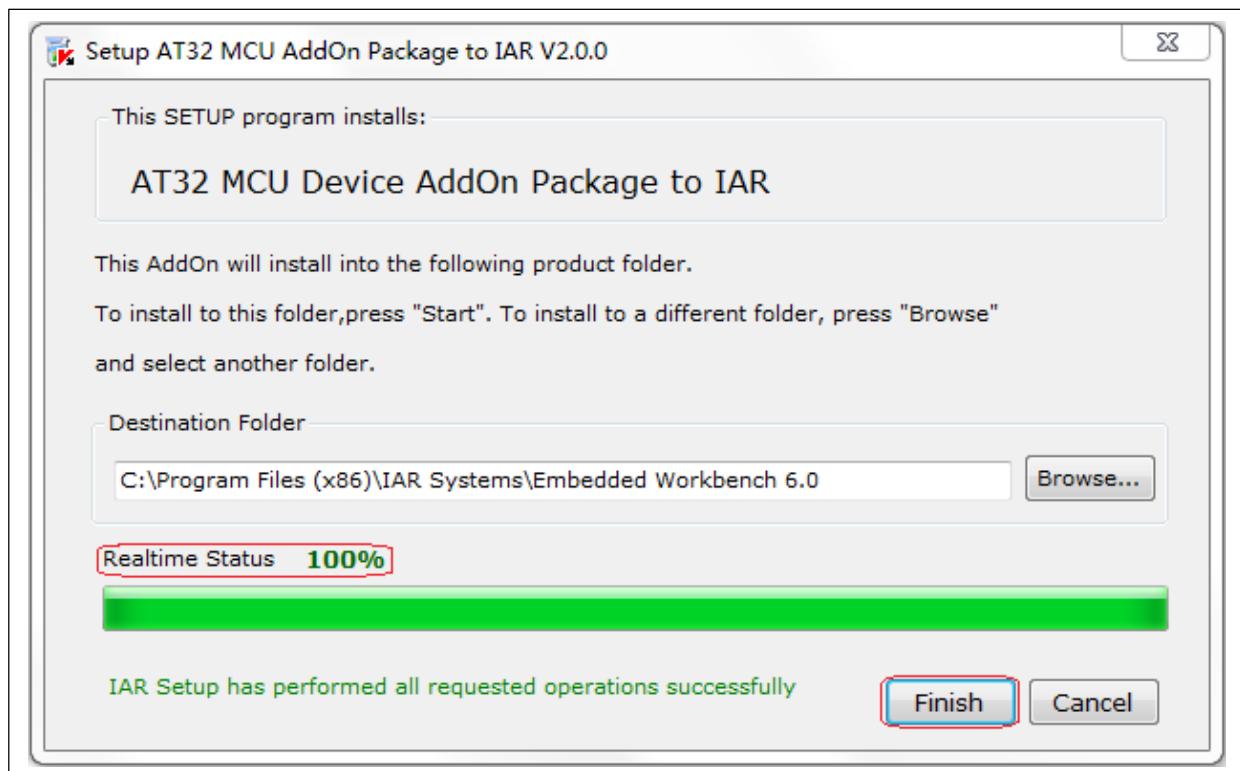
- ① Unzip *IAR_AT32MCU_AddOn.zip*;
- ② Double click on *IAR_AT32MCU_AddOn.exe*, and a dialog box pops up below (the specific version information is subject to the actual conditions).

Figure 2. IAR Pack installation window



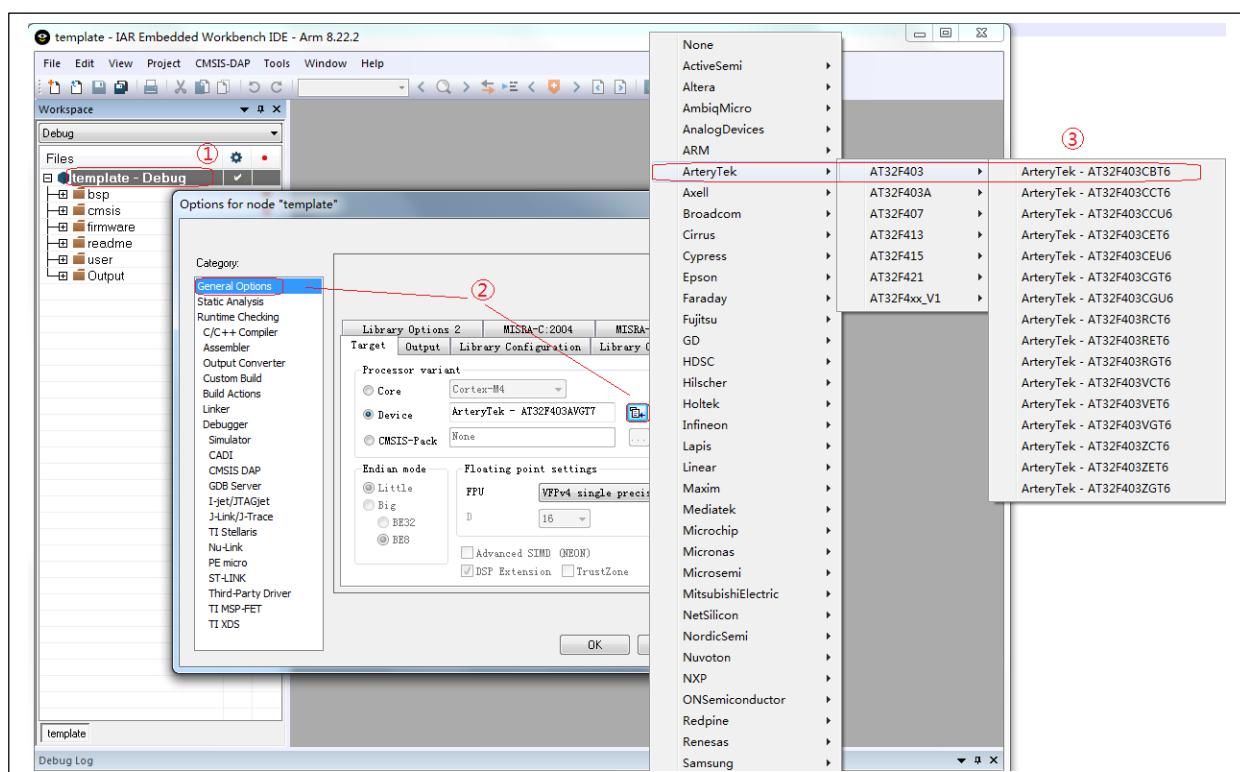
Note: If the installation path of IAR does not match the Destination Folder, click on "Browse" to select a correct path, then click on "Start", as shown below.

Figure 3. IAR Pack installation window



- ③ Click on “Finish”;
- ④ To check whether the IAR Pack is installed successfully or not, open an IAR project and follow the steps below:
 - Right click on a project name, and select “Options...”;
 - Select “General Options”, and click on the check box;
 - Click on “ArteryTek” and view AT32 MCU-related information.

Figure 4. View IAR Pack installation status

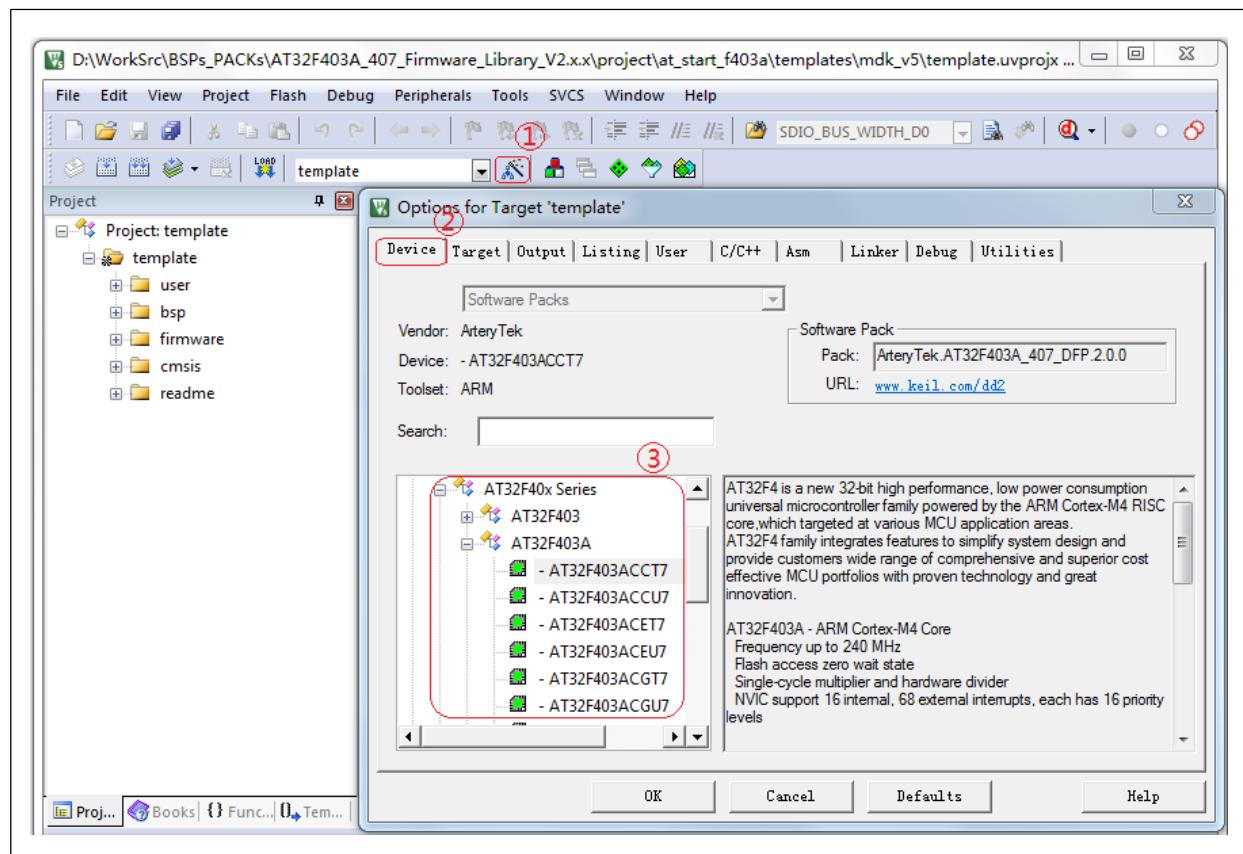


2.2 Keil_v5 Pack installation

Keil5_AT32MCU_AddOn.zip: This is a zip file supporting Keil_v5. Follow the steps below to install:

- ① Unzip *Keil5_AT32MCU_AddOn.zip*. This zip file includes all Keil5 packs supported, all of which are standard Keil_v5 DFP installation files.
- ② Select the desired Pack, and double click on *ArteryTek.AT32xxxx_DFP.2.x.x.pack* to get one-stop installation.
- ⑤ To check whether the Keil_v5 Pack is installed successfully or not, follow the steps below:
 - Click on wand;
 - Select “Device”;
 - View AT32 MCU-related information.

Figure 5. View Keil_v5 Pack installation status

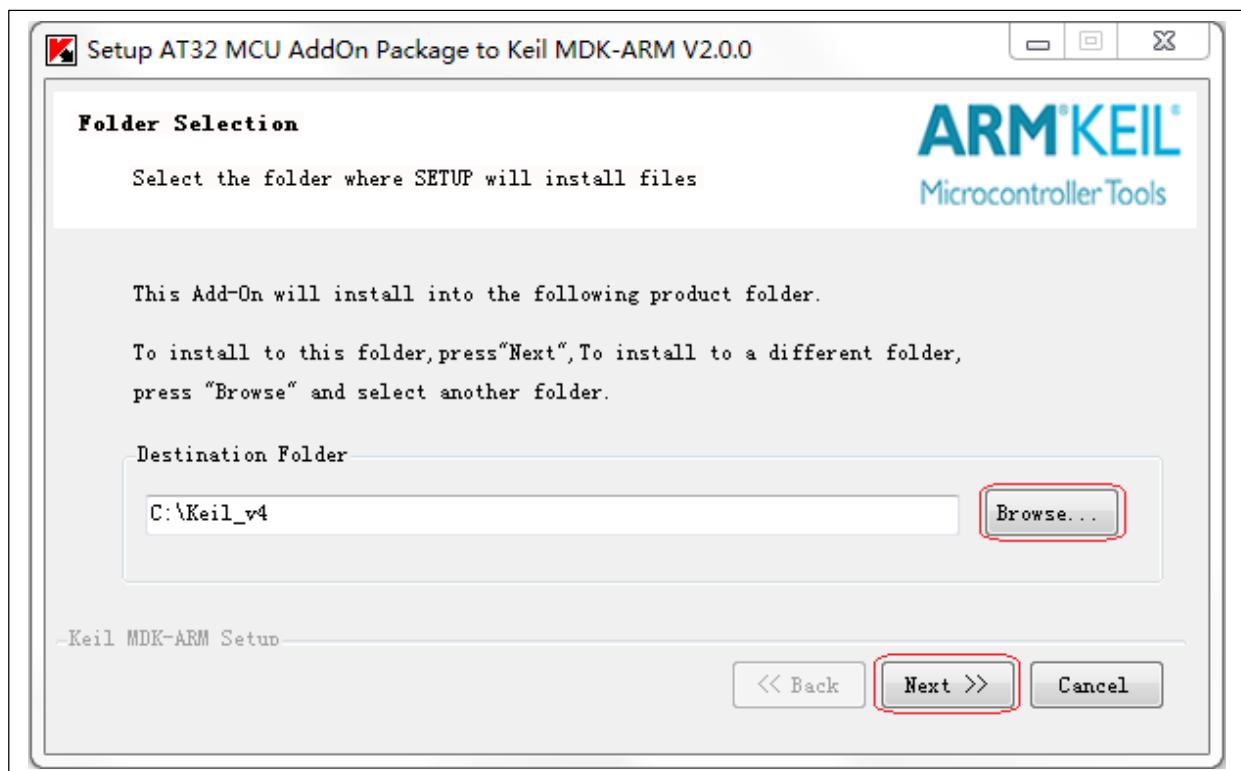


2.3 Keil_v4 Pack installation

Keil4_AT32MCU_AddOn.zip: This is a zip file supporting Keil_v4. Follow the steps below to install:

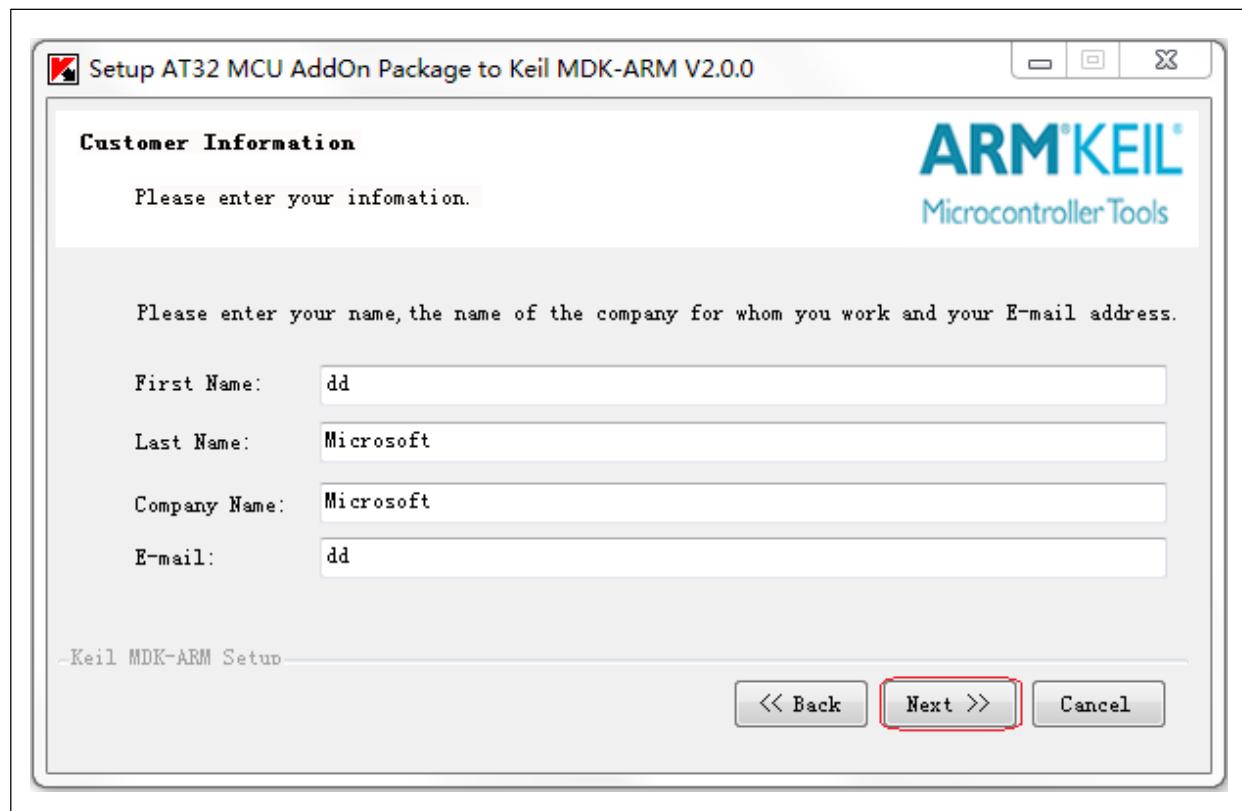
- ① Unzip *Keil4_AT32MCU_AddOn.zip*;
- ② Double click on *Keil4_AT32MCU_AddOn.exe*, and a dialog box pops up below (the specific version information is subject to the actual conditions).

Figure 6. Keil_v4 Pack installation



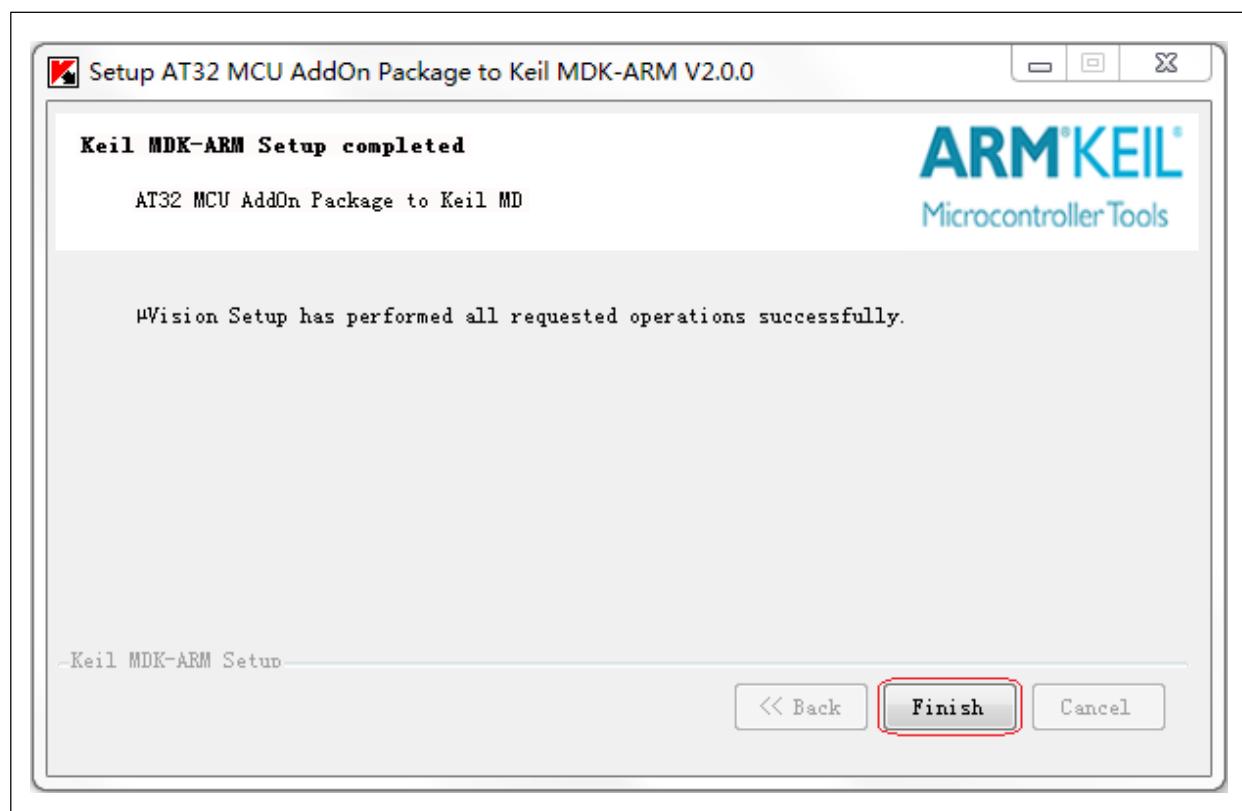
- ③ If the installation path of Keil_v4 does not match the “Destination Folder”, click on “Browse” to select the actual correct path, then click on “Next”, as shown below.

Figure 7. Keil_v4 Pack installation process



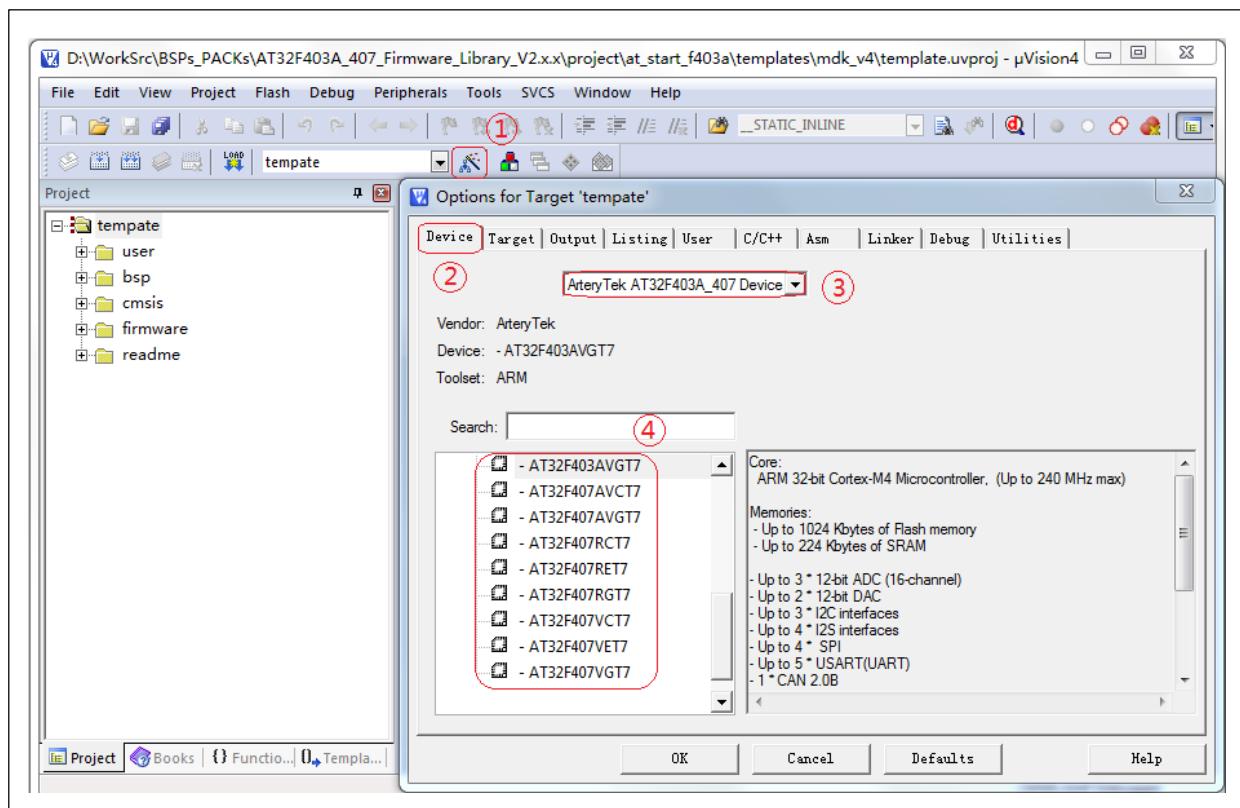
- ④ In the above “Customer Information” window, you can make some changes, but usually it is unnecessary. Then click on “Next” to start installation. The installation result is as follows.

Figure 8. Keil_v4 Pack installation complete



- ⑤ Click on “Finish”. To check whether Keil_v4 Pack is installed successfully or not, follow the below steps:
- Click on wand;
 - Select “Device”;
 - Select the desired pack file;
 - View ArteryTek-related information.

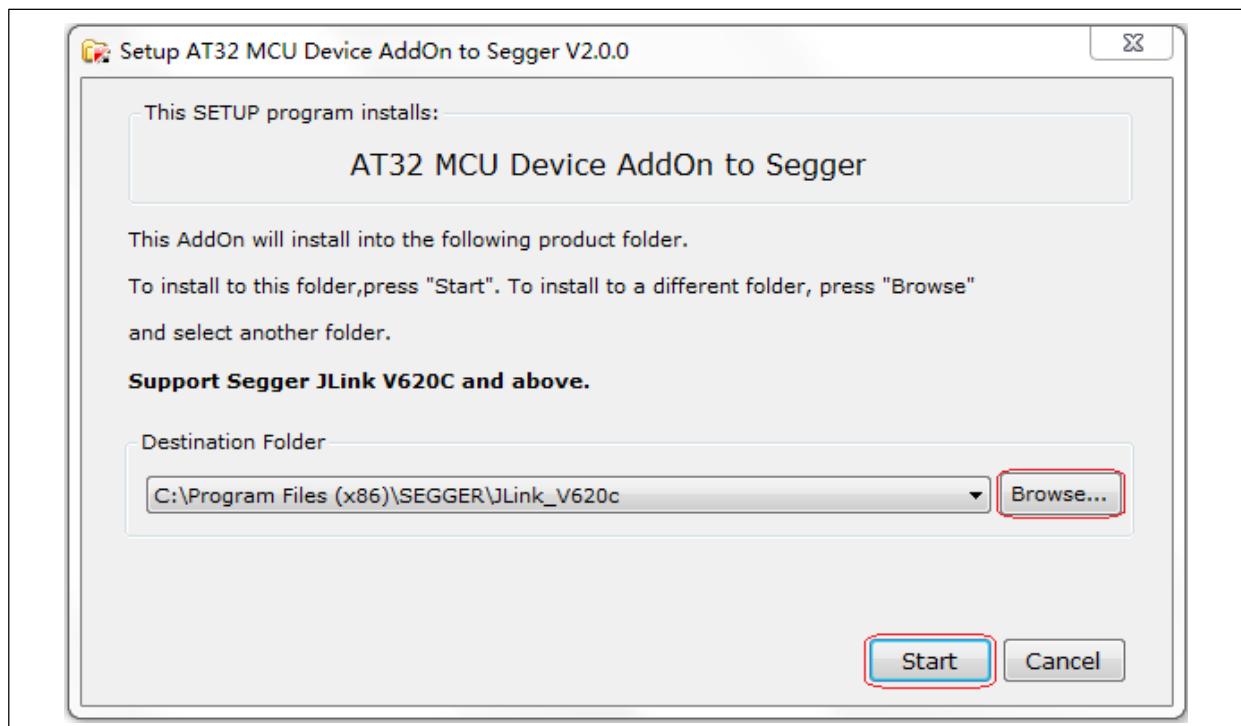
Figure 9. View Keil_v4 Pack installation status



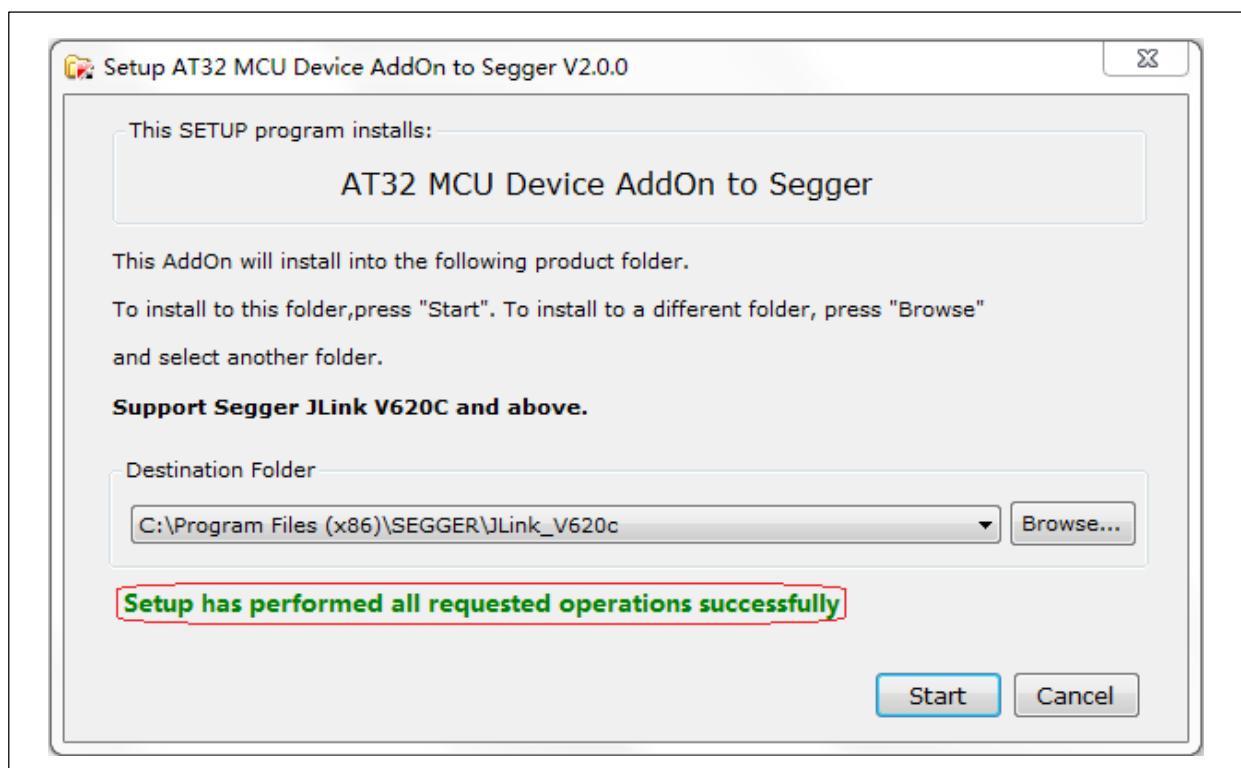
2.4 Segger Pack installation

Segger_AT32MCU_AddOn.zip: This is used to download J-Flash. Follow the steps below to install:

- ① Unzip Segger_AT32MCU_AddOn.zip;
- ② Double click on Segger_AT32MCU_AddOn.exe, and a dialog box pops up below (the specific version information is subject to the actual conditions).

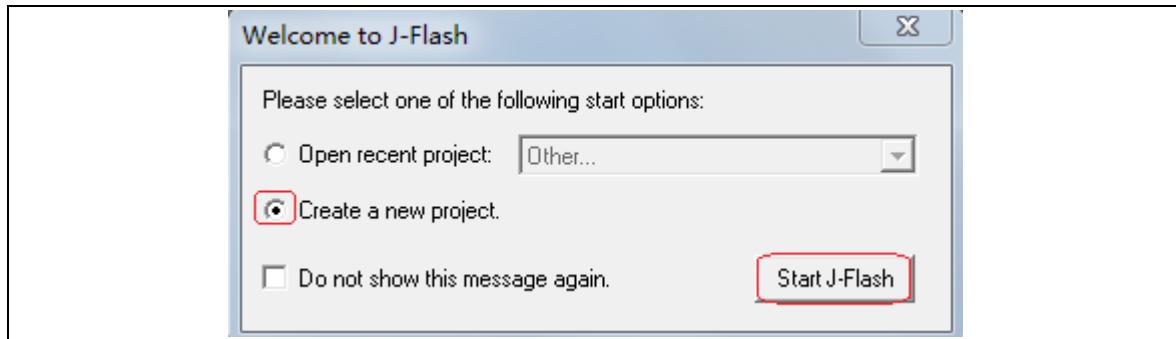
Figure 10. Segger pack installation window

Note: If the installation path of Segger does not match the “Destination Folder”, click on “Browse” to select a correct path, then click on “Start”, as shown below.

Figure 11. Segger pack installation process

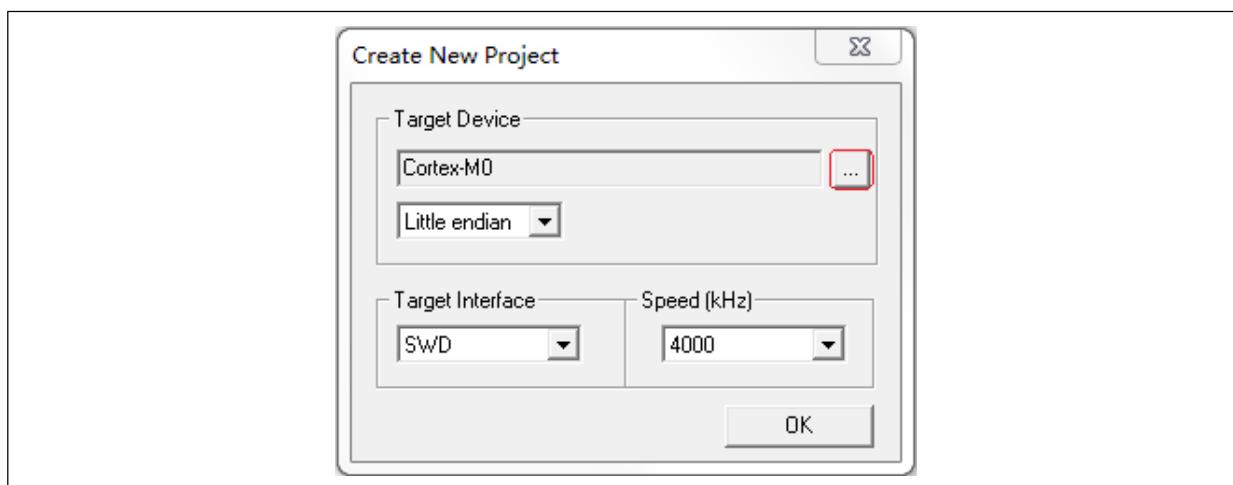
- ③ If the “Setup has performed all requested operations successfully” appears, it indicates successful installation. To check whether the installation is successful or not, follow the steps below:
 - Open J-Flash.exe, a dialog box appears; tick “Create a new project” and click on “Start J-Flash”:

Figure 12. Open J-Flash



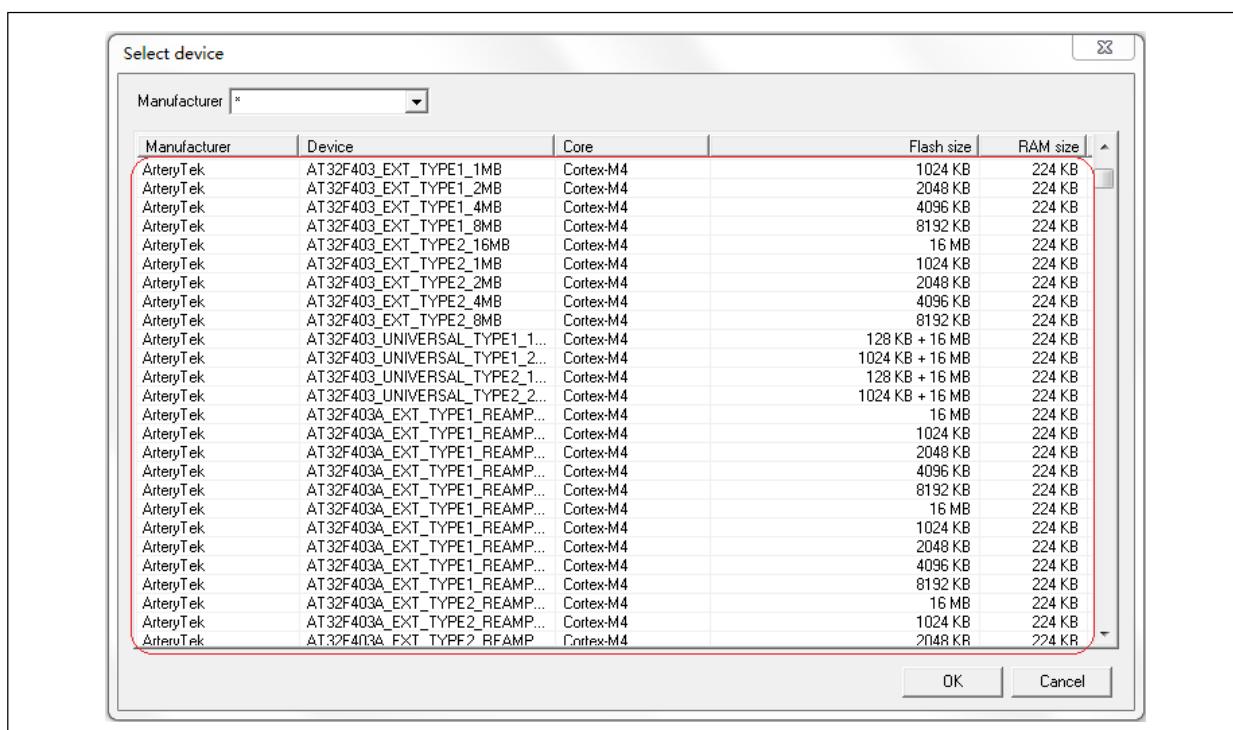
- After “Start J-Flash”, click on the check box under “Target Device”.

Figure 13. Create a new project using J-Flash



- Drag the scroll bar up and down in the check box. If the ArteryTek-related information and algorithm documents can be found, the installation is successful, as shown below:

Figure 14. View Device information



3 Flash algorithm file

Flash algorithm files are included in the Pack for online download through IDE tools such as KEIL/IAR. This section describes how to use Flash algorithm files.

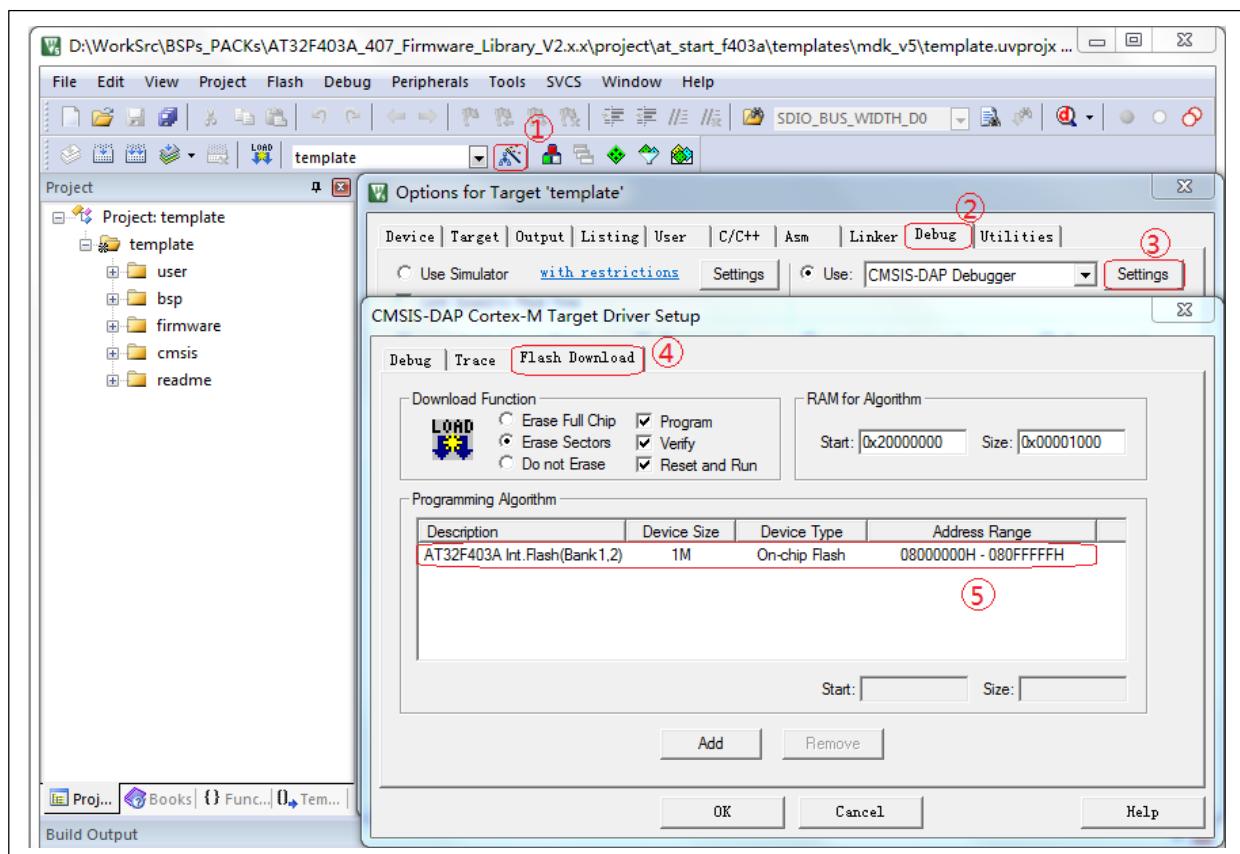
Note: AT32 MCUs have similar Flash algorithms, and this section uses AT32F403A as an example.

3.1 How to use Keil algorithm file

Common IDE tools such as Keil_v4 and Keil_v5 adopt a similar method to select and use the algorithm files. Here we take Keil_v5 as an example.

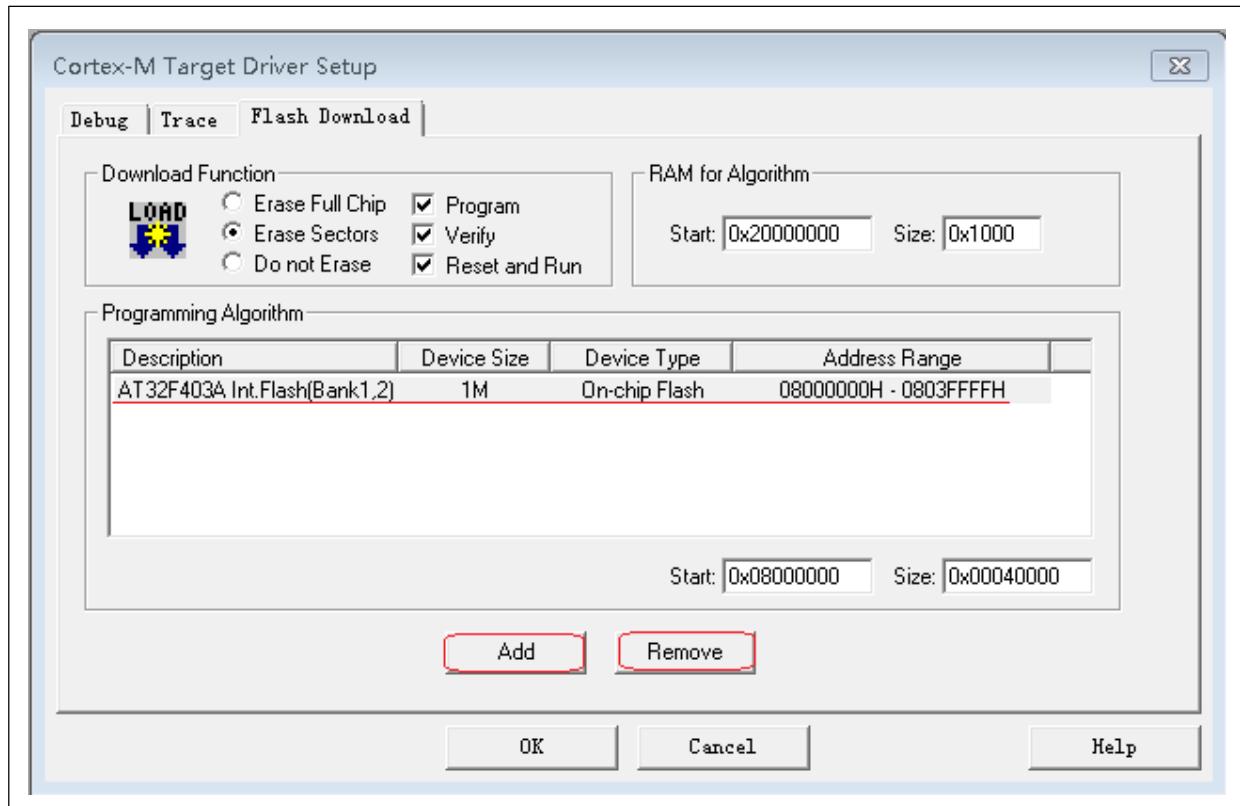
After creating a Keil IDE development tool project, the user can start Debug configuration and select the Flash algorithms. Go to *wand*—>*Debug*—>*Settings*—>*Flash Download*, as shown below:

Figure 15. Keil algorithm file settings



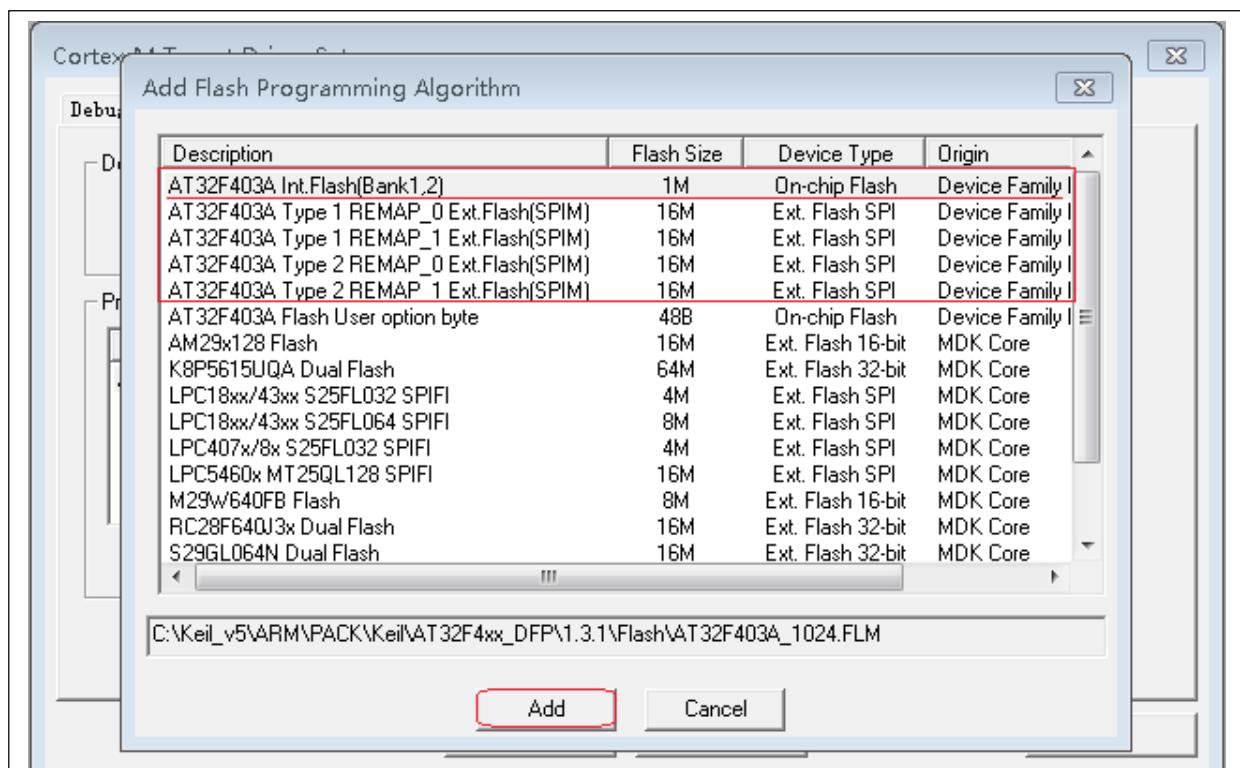
In this example, the selected Flash algorithm file is the default one. To change or remove it, click on this algorithm file, then click on *Add* or *Remove*. If the selected algorithm does not match the MCU, please follow the method below to modify.

Figure 16. Keil algorithm file configuration



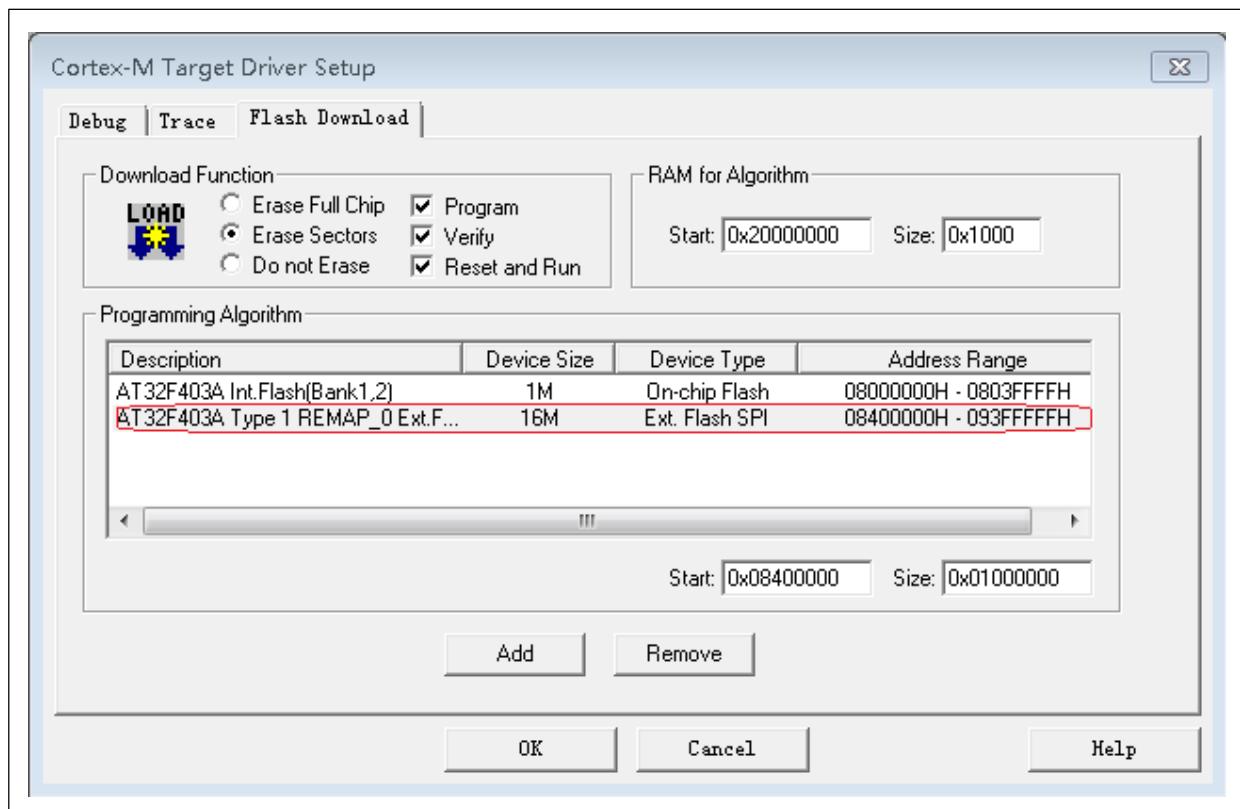
Click on *Remove* to remove the existing algorithm from the configuration, then click on *Add* to view the algorithm files associated with a MCU model and select them, as shown below:

Figure 17. Select algorithm files using Keil



After selection, click on *Add* to add the selected algorithm files into the current configuration. For example, a new SPIFI algorithm is added into the project.

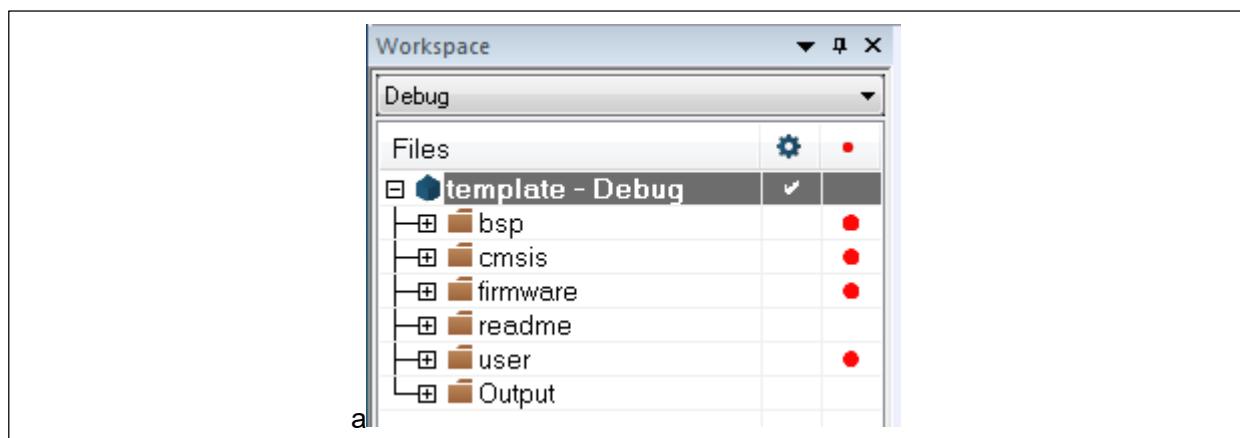
Figure 18. Add algorithm files using Keil



3.2 How to use IAR algorithm files

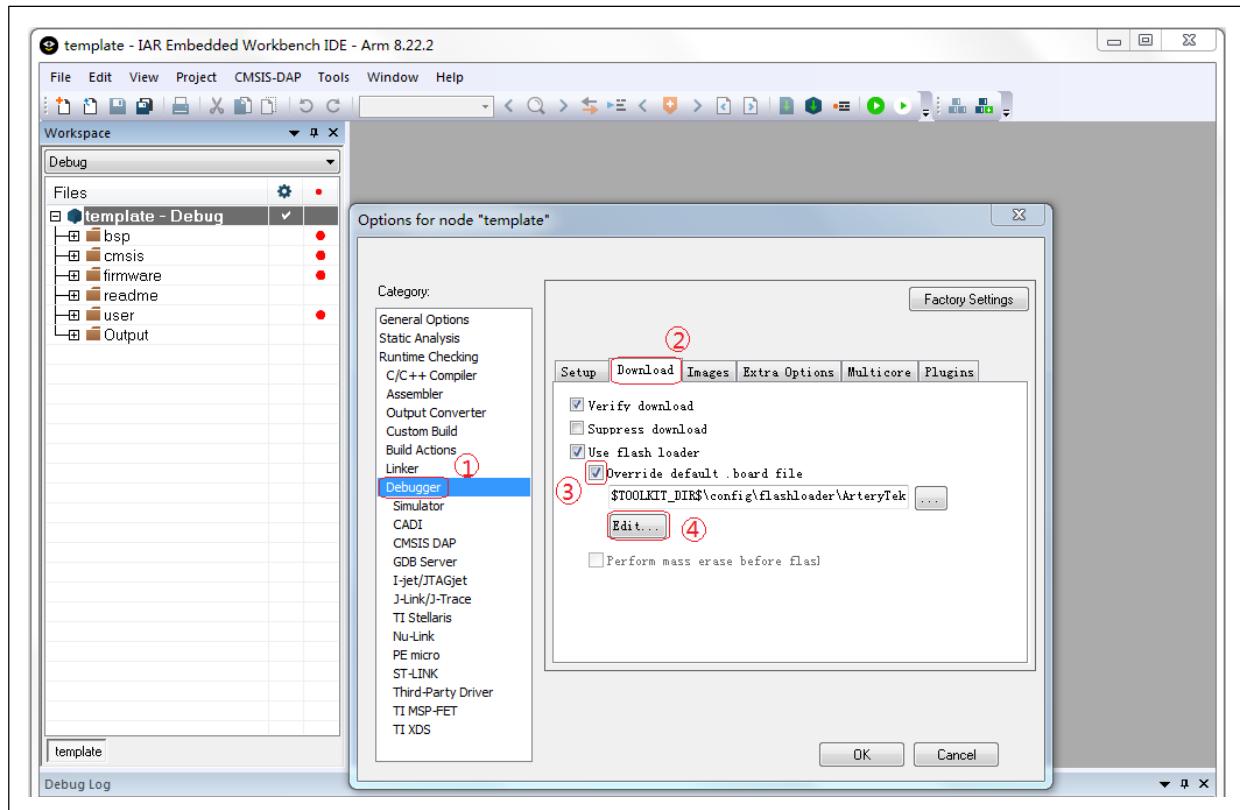
In IAR environment, the Flash algorithm files are automatically selected according to the selected MCU model during a new project configuration. To configure/modify an algorithm file manually, right-click on the file name (after an IAR project is created) in the following gray box:

Figure 19. IAR project name



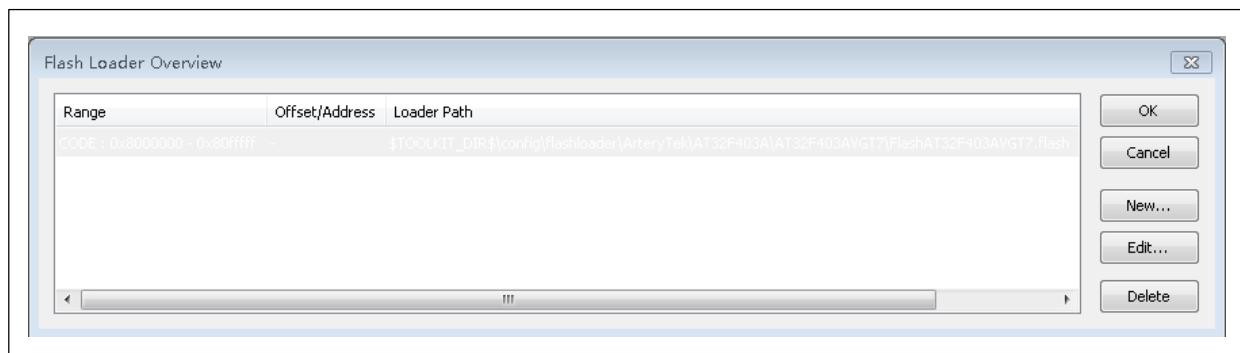
Go to Options—>Debugger—>Download—>Tick Override default .board file—>Click on Edit, as shown below:

Figure 20. IAR algorithm file configuration



Then the following window will be displayed.

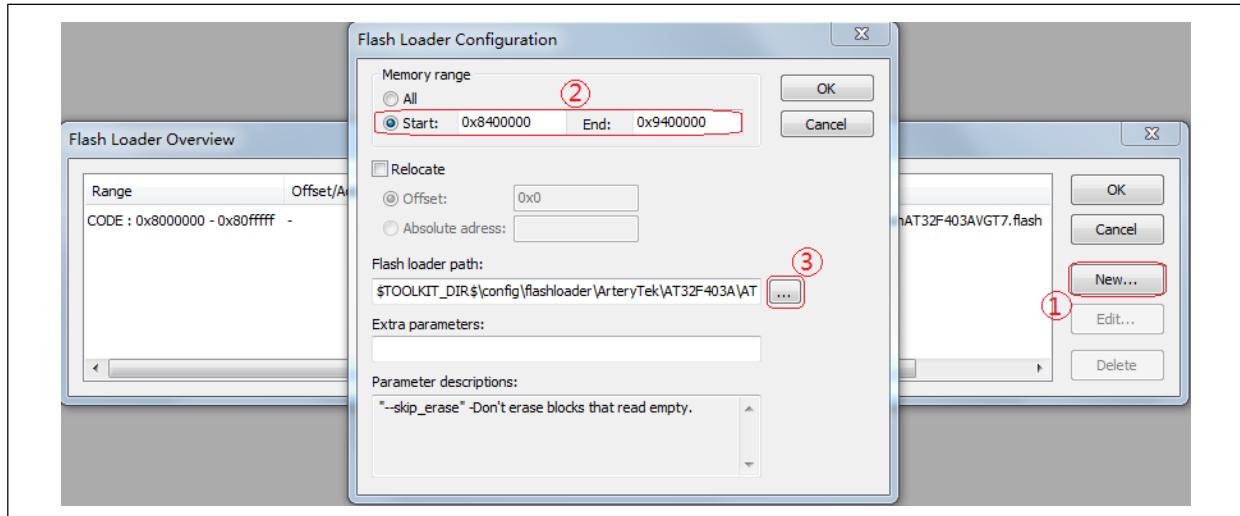
Figure 21. IAR Flash Loader overview



Flash algorithm configuration is designated by default after selecting a MCU part number. To modify it, click on *New/Edit/Delete*.

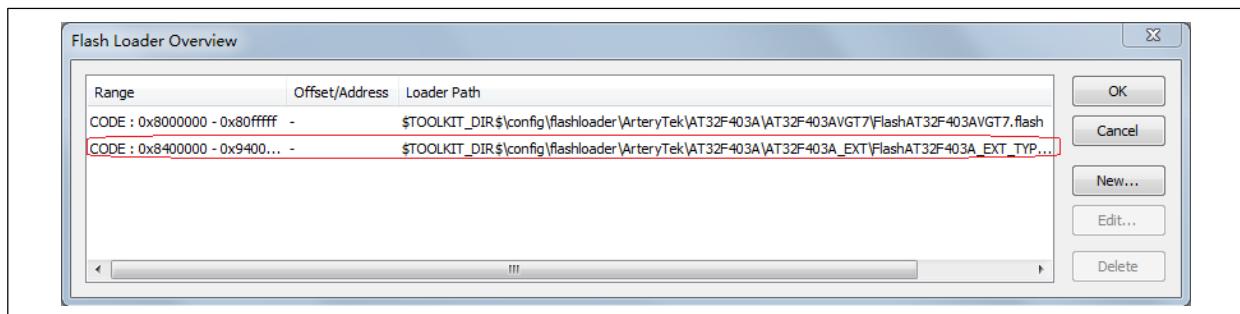
For example, click on *New*—>*Memory range*—> Select a Flash algorithm file, as shown below:

Figure 22. IAR Flash Loader configuration



This example shows how to add a SPIM Flash algorithm file. The user needs to select the corresponding MCU part number and a correct Flash algorithm file. The selected Flash algorithm configuration file is installed into IAR development environment using IAR_AT32MCU_AddOn tool. After a successful configuration, a new SPIM Flash algorithm is shown below:

Figure 23. IAR Flash Loader configuration success



1. Description of SPIM algorithms

Some Artery MCUs support Bank3 (refer to the Reference Manual or Datasheet on Artery official website for details), which can be used as an expansion of Flash memory in case of insufficient internal Flash or special application requirements. When the compiling addresses of some code or data are stored in the SPIM, these algorithm files are used for external Flash programming during online IDE tool download.

Naming rules of Artery SPIM algorithm file: AT32F4xxTypeNREMAP_P Ext.Flash.

N=1,2

P=0,1

TYPEN: External SPI Flash. Select it according to the external Flash type and part number. Refer to the FLASH_SELECT register section of the corresponding MCU Reference Manual.

REMAP_P: Select multiplex-function MCU SPIM PIN. Select it according to the connection method of pins connected to external Flash. Refer to the external SPIF remapping section in the corresponding MCU reference manual.

REMAP0: EXT_SPIF_GRMP=000

REMAP1: EXT_SPIF_GRMP=001

4 BSP introduction

4.1 Quick start

4.1.1 Template project

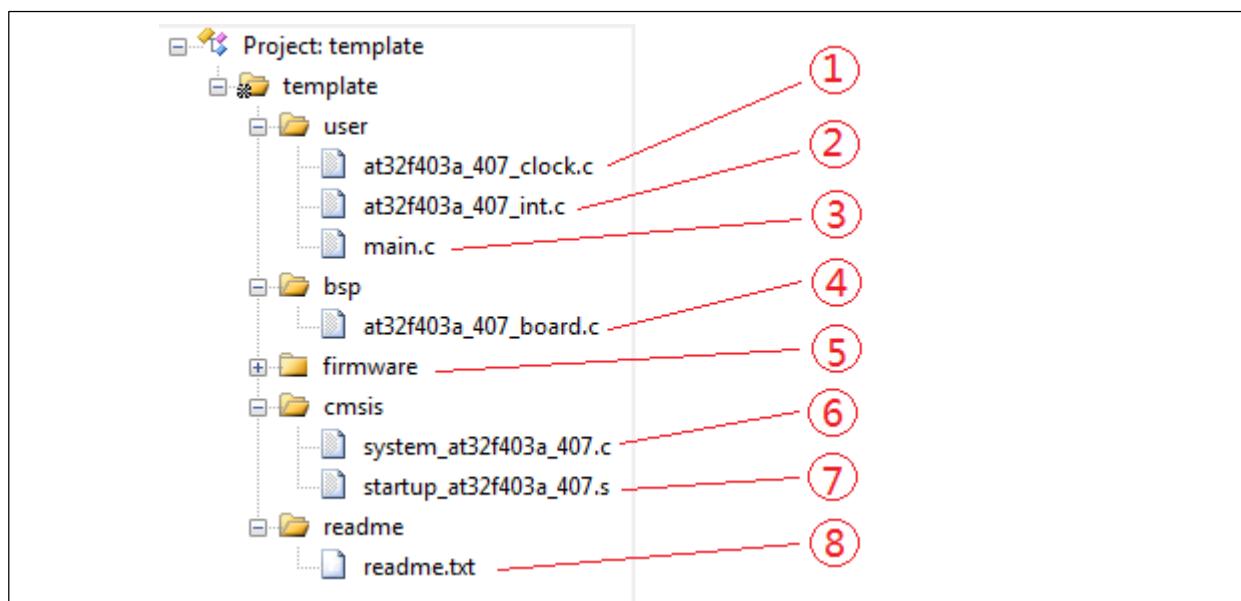
Artery firmware library BSP comes with a series of template projects built around Keil and IAR. For example, the template project of AT32F403A/407 is located in `AT32F403A_407_Firmware_Library_V2.x.x/project/at_start_xxx/templates`.

Figure 24. Template content

iar_v6.10	21/05/24 16:03	文件夹
iar_v7.4	21/05/24 16:03	文件夹
iar_v8.2	21/05/24 16:03	文件夹
inc	21/05/24 16:03	文件夹
mdk_v4	21/05/24 16:03	文件夹
mdk_v5	21/05/24 16:03	文件夹
src	21/05/24 16:03	文件夹
readme.txt	21/05/21 11:15	TXT 文件

The above template project includes various versions such as Keil_v5, Keil_v4, IAR_6.10, IAR_7.4 and IAR_8.2. Of those, “inc” and “src” folders contain header files and source code files, respectively. Open a corresponding folder and click on the corresponding file to open an IDE project. Figure 25 presents an example of Keil_v5 template project (its details and version are subject to the actual firmware library).

Figure 25. Keil_v5 template project example



The contents in a project include: (using AT32F403A/407 as an example, other products are similar)

- ① `at32f403a_407_clock.c` (clock configuration file) defines the default clock frequency and clock paths.
- ② `at32f403a_407_int.c` (interrupt file) contains some interrupt handling codes.
- ③ `main.c` contains the main code files.

- ④ at32f403a_407_board.c (board configuration file) contains common hardware configurations such as buttons and LEDs on the AT-START-Evaluation Board.
- ⑤ at32f403a_407_xx.c under firmware folder contains driver files of on-chip peripherals.
- ⑥ system_at32f403a_407.c is the system initialization file.
- ⑦ startup_at32f403a_407.s is a startup file.
- ⑧ readme.txt is a readme file, containing functional description and configuration information.

Note: AT32 MUCs share similar BSP usage method, and this section uses AT32F403A as an example.

4.1.2 BSP macro definitions

- ① To create a project, it is necessary to enable a startup code (startup_at32f403a_407.s) and open the appropriate macro definitions according to MCU part number before compiling code. Table 1 presents the correspondence between the MCU and their macro definitions.

Table 1. Summary of macro definitions

MCU part numbers	Macro definitions	PINs	Flash size (KB)
AT32F403ACCT7	AT32F403ACCT7	48	256
AT32F403ACET7	AT32F403ACET7	48	512
AT32F403ACGT7	AT32F403ACGT7	48	1024
AT32F403ACCU7	AT32F403ACCU7	48	256
AT32F403ACEU7	AT32F403ACEU7	48	512
AT32F403ACGU7	AT32F403ACGU7	48	1024
AT32F403ARCT7	AT32F403ARCT7	64	256
AT32F403ARET7	AT32F403ARET7	64	512
AT32F403ARGT7	AT32F403ARGT7	64	1024
AT32F403AVCT7	AT32F403AVCT7	100	256
AT32F403AVET7	AT32F403AVET7	100	512
AT32F403AVGT7	AT32F403AVGT7	100	1024
AT32F407RCT7	AT32F407RCT7	64	256
AT32F407RET7	AT32F407RET7	64	512
AT32F407RGT7	AT32F407RGT7	64	1024
AT32F407VCT7	AT32F407VCT7	100	256
AT32F407VET7	AT32F407VET7	100	512
AT32F407VGT7	AT32F407VGT7	100	1024
AT32F407AVCT7	AT32F407AVCT7	100	256
AT32F407AVGT7	AT32F407AVGT7	100	1024

- ② In the header file (at32f403a_407.h), USE_STDPERIPH_DRIVER (macro definition) is used to determine whether the Keil RTE feature is used or not. Enabling this definition while Keil RTE is unused can prevent some versions of Keil-MDK from opening _RTE_ accidentally.
- ③ The configuration header file (at32f403a_407_conf.h) defines macro definitions that enable peripherals. The file can be used to control the use of peripherals. The peripherals can be disabled simply by masking _MODULE_ENABLED pertaining to peripherals, as shown below:

Figure 26. Peripheral enable macro definitions

```
#define CRM_MODULE_ENABLED  
#define TMR_MODULE_ENABLED  
#define RTC_MODULE_ENABLED  
#define BPR_MODULE_ENABLED  
#define GPIO_MODULE_ENABLED  
#define I2C_MODULE_ENABLED  
#define USART_MODULE_ENABLED  
#define PWC_MODULE_ENABLED  
#define CAN_MODULE_ENABLED  
#define ADC_MODULE_ENABLED  
#define DAC_MODULE_ENABLED  
#define SPI_MODULE_ENABLED  
#define DMA_MODULE_ENABLED  
#define DEBUG_MODULE_ENABLED  
#define FLASH_MODULE_ENABLED  
#define CRC_MODULE_ENABLED  
#define WWDT_MODULE_ENABLED  
#define WDT_MODULE_ENABLED  
#define EXINT_MODULE_ENABLED  
#define SDIO_MODULE_ENABLED  
#define XMC_MODULE_ENABLED  
#define USB_MODULE_ENABLED  
#define ACC_MODULE_ENABLED  
#define MISC_MODULE_ENABLED  
#define EMAC_MODULE_ENABLED
```

at32f403a_407_conf.h also defines the HEXT_VALUE (high-speed external clock value), which should be modified accordingly when changing an external high-speed crystal oscillator.

- ④ The system clock configuration file (*at32f403a_407_clock.c/.h*) defines the default system clock frequency and clock paths. The user, if needed, can customize the frequency multiplication process and factors, or generate corresponding clock configuration files using the clock configuration host of ArteryTek.

4.2 BSP specifications

The subsequent sections give a description of BSP specifications.

4.2.1 List of abbreviations for peripherals

Table 2. List of abbreviations for peripherals

Abbreviations	Description
ADC	Analog-to-digital converter
BPR	Battery powered register
CAN	Controller area network
CRC	CRC calculation unit
CRM	Clock and reset manage
DAC	Digital-to-analog converter
DMA	Direct memory access
DEBUG	Debug
EXINT	External interrupt/event controller
GPIO	General-purpose I/Os
IOMUX	Multiplexed I/Os
I2C	Inter-integrated circuit interface
NVIC	Nested vectored interrupt controller
PWC	Power controller
RTC	Real-time clock
SPI	Serial peripheral interface
I2S	Inter-IC Sound
SysTick	System tick timer
TMR	Timer
USART	Universal synchronous/asynchronous receiver transmitter
WDT	Watchdog timer
WWDT	Window watchdog timer
XMC	External memory controller

4.2.2 Naming rules

The naming rules for BSP are described as follows:

“ip” indicates an abbreviation of a peripheral, for example, ADC, TMR, GPIO, etc., regardless of upper and lower case letters, such as, adc, tmr, gpio...

- **Source code file**
The file name starts with “at32fxxx_ip.c”, for example, at32f403a_407_adc.c
- **Header file**
The file name starts with “at32fxxx_ip.h”, such as, at32f403a_407_adc.h
- **Constant**
If it is used in a single one file, the constant is then defined in this file; if it is used in multiple files, the constant is defined in corresponding header file.
All constants are in written in English capital letters.
- **Variable**
If it is used in a single one file, the variable is then defined in this file; if it is used in multiple files, the variable is declared with extern in the corresponding header file.

- **Naming rules for functions**

The peripheral functions are named based on the rule of “**peripheral abbreviatio_attribute_action**” or “**peripheral abbreviation_attribute_action**”.

The commonly used functions are as follows:

Function type	Naming rule	Example
Peripheral reset	ip_reset	adc_reset
Peripheral enable	ip_enable	adc_enable
Peripheral structure parameter initialize	ip_default_para_init	spi_default_para_init
Peripheral initialize	ip_init	spi_init
Peripheral interrupt enable	ip_interrupt_enable	adc_interrupt_enable
Peripheral flag get	ip_flag_get	adc_flag_get
Peripheral flag clear	ip_flag_clear	adc_flag_clear

4.2.3 Encoding rules

This section describes the encoding rules related to firmware function library.

Type of variables:

```

typedef int32_t INT32;
typedef int16_t INT16;
typedef int8_t INT8;
typedef uint32_t UINT32;
typedef uint16_t UINT16;
typedef uint8_t UINT8;

typedef int32_t s32;
typedef int16_t s16;
typedef int8_t s8;

typedef const int32_t sc32; /*!< read only */
typedef const int16_t sc16; /*!< read only */
typedef const int8_t sc8; /*!< read only */

typedef __IO int32_t vs32;
typedef __IO int16_t vs16;
typedef __IO int8_t vs8;

typedef __I int32_t vsc32; /*!< read only */
typedef __I int16_t vsc16; /*!< read only */
typedef __I int8_t vsc8; /*!< read only */

typedef uint32_t u32;
typedef uint16_t u16;
typedef uint8_t u8;

typedef const uint32_t uc32; /*!< read only */
typedef const uint16_t uc16; /*!< read only */
typedef const uint8_t uc8; /*!< read only */

```

```
typedef __IO uint32_t vu32;
typedef __IO uint16_t vu16;
typedef __IO uint8_t vu8;

typedef __I uint32_t vuc32; /*!< read only */
typedef __I uint16_t vuc16; /*!< read only */
typedef __I uint8_t vuc8; /*!< read only */
```

4.2.3.1 Flag type

```
typedef enum {RESET = 0, SET = !RESET} flag_status;
```

4.2.3.2 Function status type

```
typedef enum {FALSE = 0, TRUE = !FALSE} confirm_state;
```

4.2.3.3 Error status type

```
typedef enum {ERROR = 0, SUCCESS = !ERROR} error_status;
```

4.2.3.4 Peripheral type

① Peripherals

Define the base address of peripheral in the at32fxxx_ip.h, for example, in the at32f403a_407.h:

```
#define ADC1_BASE (APB2PERIPH_BASE + 0x2400)
#define ADC2_BASE (APB2PERIPH_BASE + 0x2800)
```

Define the type of a peripheral in the at32fxxx_ip.h, for example, in the at32f403a_407_adc.h:

```
#define ADC1 ((adc_type *)ADC1_BASE)
#define ADC2 ((adc_type *)ADC2_BASE)
```

② Peripheral registers and bits

Define the type of a peripheral in the at32fxxx_ip.h, for example, in the at32f403a_407_adc.h

```
/**
 * @brief type define adc register all
 */
typedef struct
{

    /**
     * @brief adc sts register, offset:0x00
     */
    union
    {
        __IO uint32_t sts;
        struct
    }
}
```

```

    __IO uint32_t vmor      : 1; /* [0] */
    __IO uint32_t cce      : 1; /* [1] */
    __IO uint32_t pcce     : 1; /* [2] */
    __IO uint32_t pccs     : 1; /* [3] */
    __IO uint32_t occs     : 1; /* [4] */
    __IO uint32_t reserved1 : 27; /* [31:5] */

} sts_bit;

};

...
...
...
/** 
 * @brief adc odt register, offset:0x4C
 */
union
{
    __IO uint32_t odt;
    struct
    {
        __IO uint32_t odt      : 16; /* [15:0] */
        __IO uint32_t adc2odt  : 16; /* [31:16] */
    } odt_bit;
};

} adc_type;

```

③ Examples of peripheral register access

Read peripheral	i = ADC1->ctrl1;
Write peripheral	ADC1->ctrl1 = i;
Read bit 5 in bit-field mode	i = ADC1->ctrl1.cceien;
Write 1 to bit 5 in bit-field mode	ADC1->ctrl1.cceien= TRUE;
Write 1 to bit 5	ADC1->ctrl1 = 1<<5;
Write 0 to bit 5	ADC1->ctrl1&= ~(1<<5);

4.3 BSP structure

4.3.1 BSP folder structure

BSP (Board Support Package) structure is shown in Figure 27.

Figure 27. BSP folder structure

document	21/05/18 10:32	文件夹
libraries	21/05/18 10:32	文件夹
middlewares	21/05/18 10:32	文件夹
project	21/05/18 10:32	文件夹
utilities	21/05/14 11:35	文件夹

Document:

- AT32Fxxx firmware library BSP&Pack user guide.pdf: refer to BSP/Pack user manual
- ReleaseNotes_AT32F403A_407_Firmware_Library.pdf: document revision history

Libraries:

- **Drivers:** driver library for peripherals
Src folder: low-level driver source file for peripherals, such as, at32fxxx_ip.c
inc folder: low-level driver header file for peripherals, such as, at32fxxx_ip.h
- **Cmsis:** Core-related files
cm4 folder: core-related files, including cortex-m4 library, system initialization file, startup file, etc.
dsp folder: dsp-related files

Middlewares:

Third-party software or public protocols, including USB protocol layer driver, network protocol driver, operating system source code, etc.

Project:

Examples: demo

Templates: template projects, including Keil4, keil5, IAR6, IAR7, IAR8 and eclipse_gcc

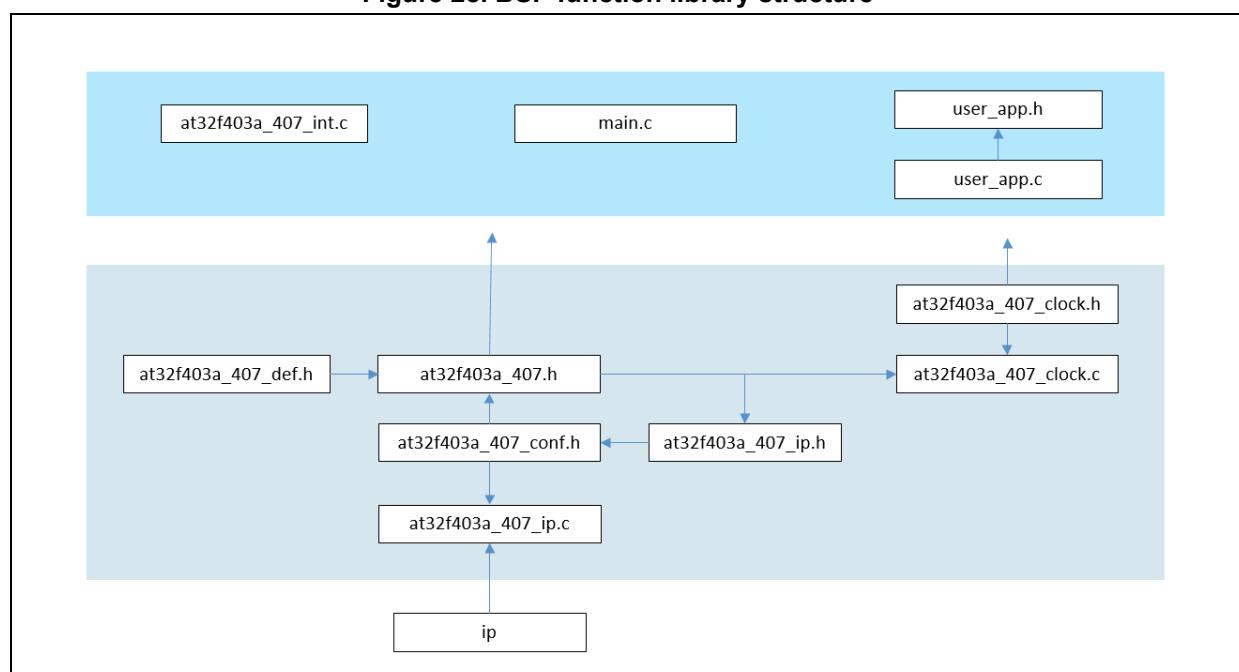
Utilities:

Store application cases

4.3.2 BSP function library structure

Figure 28 shows the architecture of BSP function library.

Figure 28. BSP function library structure



BSP function library files are described in Table 3.

Table 3. Summary of BSP function library files

File name	Description
at32f403a_407_conf.h	Macro definition for peripheral enable, and external high-speed clock HEXT_VALUE
main.c	Main function
at32f403a_407_ip.c	Driver source file for a peripheral, for example, at32f403a_407_adc.c
at32f403a_407_ip.h	Driver header file for a peripheral, for example, at32f403a_407_adc.h
at32f403a_407.h	In the header file (at32f403a_407.h), the definition USE_STDPERIPH_DRIVER is used to determine whether the Keil RTE is used or not. Enabling the definition while Keil RTE is unused can prevent Keil-MDK from enabling _RTE_ accidentally.
at32f403a_407_clock.c	This is a clock configuration file used to configure default clock frequency and clock path.
at32f403a_407_clock.h	This is a clock configure header file.
at32f403a_407_int.c	This is a source file for interrupt functions that programs interrupt handling code.
at32f403a_407_int.h	This is a header file for interrupt functions.
at32f403a_407_misc.c	This is a source file for other configurations, such as, nvic configuration function, systick clock source selection.
at32f403a_407_misc.h	This is a header file for other configurations.
startup_at32f403a_407.s	This is a startup file.

4.3.3 Initialization and configuration for peripherals

This section describes how to initialize and configure peripherals using GPIO as an example.

GPIO initialization

- Step 1: Define the gpio_init_type, for example, gpio_init_type gpio_init_struct;
- Step 2: Enable GPIO clock using the function crm_periph_clock_enable;
- Step 3: De-initialize the structure gpio_init_struct to allow the values of other members (mostly default values) to be correctly written, for example, gpio_default_para_init(&gpio_init_struct);
- Step 4: Configure member of the structure, and write structure parameters into GPIO registers through the gpio_init, for example,

```
gpio_init_struct.gpio_pins = GPIO_PINS_2 | GPIO_PINS_3;
gpio_init_struct.gpio_mode = GPIO_MODE_OUTPUT;
gpio_init_struct.gpio_out_type = GPIO_OUTPUT_PUSH_PULL;
gpio_init_struct.gpio_pull = GPIO_PULL_NONE;
gpio_init_struct.gpio_drive_strength = GPIO_DRIVE_STRENGTH_STRONGER;
gpio_init(GPIOA, &gpio_init_struct);
```

For more information on peripheral initialization procedure, refer to the section of peripherals of the reference manual, and the section of peripherals of the

AT32Fxxx_Firmware_Library_V2.x.x.zip\project\at_start_fxxx\examples.

4.3.4 Peripheral functions format description

Table 4. Function format description for peripherals

Name	Description
Function name	The name of a peripheral function
Function prototype	Prototype declaration
Function description	Brief description of how the function is executed
Input parameter (n)	Description of the input parameters
Output parameter (n)	Description of the output parameters
Return value	Value returned by the function
Required preconditions	Requirements before calling the function
Called functions	Other library functions called

5 AT32F422/426 peripheral library functions

5.1 Analog-to-digital converter (ADC)

ADC register structure adc_type is defined in the “at32f422_426_adc.h”.

```
/*
 * @brief type define adc register all
 */
typedef struct
{
    .....
} adc_type;
```

The table below gives a list of the ADC registers.

Table 5. Summary of ADC registers

Register	Description
sts	ADC status register
ctrl1	ADC control register 1
ctrl2	ADC control register 2
spt1	ADC sample time register 1
spt2	ADC sample time register 2
pcdto1	ADC preempted channel data offset register 1
pcdto2	ADC preempted channel data offset register 2
pcdto3	ADC preempted channel data offset register 3
pcdto4	ADC preempted channel data offset register 4
vmb	ADC voltage monitor high boundary register
vmlb	ADC voltage monitor low boundary register
osq1	ADC ordinary sequence register 1
osq2	ADC ordinary sequence register 2
osq3	ADC ordinary sequence register 3
psq	ADC preempted sequence register
pdt1	ADC preempted data register 1
pdt2	ADC preempted data register 2
pdt3	ADC preempted data register 3
pdt4	ADC preempted data register 4
odt	ADC ordinary data register
misc1	ADC additional register 1
misc2	ADC additional register 2

The table below gives a list of ADC library functions.

Table 6. Summary of ADC library functions

Function name	Description
adc_reset	Reset all ADC registers to their reset values
adc_enable	Enable A/D converter
adc_base_default_para_init	Define an initial value for adc_base_struct
adc_base_config	Configure ADC registers with the initialized parameters of the adc_base_struct
adc_dma_mode_enable	Enable DMA transfer for ordinary group
adc_interrupt_enable	Enable the selected ADC event interrupt
adc_calibration_init	Initialization calibration
adc_calibration_init_status_get	Get initialization calibration status
adc_calibration_start	Start calibration
adc_calibration_status_get	Get calibration status
adc_voltage_monitor_enable	Enable voltage monitoring for ordinary/preempted channels and a single channel
adc_voltage_monitor_threshold_value_set	Set the threshold of voltage monitoring
adc_voltage_monitor_single_channel_select	Select a single channel for voltage monitoring
adc_ordinary_channel_set	Configure ordinary channels, including channel selection, conversion sequence number and sampling time
adc_preempt_channel_length_set	Configure the length of preempted group conversion sequence
adc_preempt_channel_set	Configure preempted channels, including channel selection, conversion sequence number and sampling time
adc_ordinary_conversion_trigger_set	Enable trigger mode and trigger event selection for ordinary conversion
adc_preempt_conversion_trigger_set	Enable trigger mode and trigger event selection for preempted conversion
adc_preempt_offset_value_set	Set data offset for preempted conversion
adc_ordinary_part_count_set	Set the number of ordinary channels for each triggered conversion in partition mode
adc_ordinary_part_mode_enable	Enable partition mode for ordinary channels
adc_preempt_part_mode_enable	Enable partition mode for preempted channels
adc_preempt_auto_mode_enable	Enable auto conversion of preempted group at the end of ordinary conversion
adc_tempersensor_vintrv_enable	Enable internal temperature sensor and VINTRV
adc_ordinary_software_trigger_enable	Software trigger ordinary group conversion
adc_ordinary_software_trigger_status_get	Get the status of ordinary group conversion triggered by software
adc_preempt_software_trigger_enable	Software trigger preempted group conversion
adc_preempt_software_trigger_status_get	Get the status of preempted group conversion triggered by software
adc_ordinary_conversion_data_get	Get data of ordinary group conversion in non-master-slave mode
adc_preempt_conversion_data_get	Get the converted data of preempted group
adc_flag_get	Get the status of flag bits
adc_flag_clear	Clear flag bits

Function name	Description
adc_conversion_stop	Stop on-going ADC conversion
adc_conversion_stop_status_get	Get the status of stop conversion command
adc_convert_fail_auto_abort_enable	Enable ADC auto abort after conversion failure
adc_xeoc_sync_mode_set	Set XEOC synchronization mode
adc_fail_auto_processing_enable	Enable auto processing after trigger conversion failure
adc_fail_auto_processing_mode_set	Set auto processing mode after trigger conversion failure
adc_conversion_fail_sequence_number_get	Get the sequence number of trigger conversion failure
adc_conversion_fail_sequence_number_clear	Clear the sequence number of trigger conversion failure

5.1.1 adc_reset function

The table below describes the function adc_reset.

Table 7. adc_reset function

Name	Description
Function name	adc_reset
Function prototype	void adc_reset(adc_type *adc_x)
Function description	Reset all ADC registers to their reset values
Input parameter	adc_x: indicates the selected ADC This parameter can be ADC1.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	crm_periph_reset()

Example:

```
/* Deinitialize adc1 */
adc_reset(ADC1);
```

5.1.2 adc_enable function

The table below describes the function adc_enable.

Table 8. adc_enable function

Name	Description
Function name	adc_enable
Function prototype	void adc_enable(adc_type *adc_x, confirm_state new_state)
Function description	Enable/disable A/D converter
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	new_state: indicates the pre-configured status of A/D converter This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable adc1 */
adc_enable(ADC1, TRUE);
```

Note: Calling the function adc_enable while the ADC is enabled triggers the conversion of ordinary channels.

5.1.3 adc_base_default_para_init function

The table below describes the function adc_base_default_para_init

Table 9. adc_base_default_para_init function

Name	Description
Function name	adc_base_default_para_init
Function prototype	void adc_base_default_para_init(adc_base_config_type *adc_base_struct)
Function description	Set the initial value for the adc_base_struct.
Input parameter	adc_base_struct: adc_base_config_type pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

The default values of members in the adc_base_struct:

sequence_mode:	FALSE
repeat_mode:	FALSE
data_align:	ADC_RIGHT_ALIGNMENT
ordinary_channel_length:	1

Example:

```
/* initialize a adc_base_config_type structure */
adc_base_config_type adc_base_struct;
adc_base_default_para_init(&adc_base_struct);
```

5.1.4 adc_base_config function

The table below describes the function adc_base_config.

Table 10. adc_base_config function

Name	Description
Function name	adc_base_config
Function prototype	void adc_base_config(adc_type *adc_x, adc_base_config_type *adc_base_struct);
Function description	Initialize ADC registers with the specified parameters in the adc_base_struct.
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_base_struct: adc_base_config_type structure pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

adc_base_config_type structure

The adc_base_config_type is defined in the at32f422_426_adc.h.

typedef struct

```
{
    confirm_state          sequence_mode;
    confirm_state          repeat_mode;
    adc_data_align_type   data_align;
    uint8_t                ordinary_channel_length;
}
```

adc_base_config_type; the member parameters are described as follows.

sequence_mode

Set ADC sequence mode.

FALSE: Select a single channel for conversion

TRUE: Select multiple channels for conversion

repeat_mode

Set ADC repeat mode.

FALSE: when SQEN=0, trigger a single channel conversion each time; when SQEN=1, trigger the conversion of a group of channels each time

TRUE: when SQEN =0, repeatedly convert a single channel at each trigger; when SQEN=1, repeatedly convert a group of channels at each trigger until the ADCEN bit is cleared.

data_align

Set data alignment of ADC.

ADC_RIGHT_ALIGNMENT: right-aligned

ADC_LEFT_ALIGNMENT: left-aligned

ordinary_channel_length

Set the length of ordinary group ADC conversion.

Example:

```
adc_base_config_type adc_base_struct;
adc_base_struct.sequence_mode = TRUE;
adc_base_struct.repeat_mode = FALSE;
adc_base_struct.data_align = ADC_RIGHT_ALIGNMENT;
adc_base_struct.ordinary_channel_length = 3;
adc_base_config(ADC1, &adc_base_struct);
```

5.1.5 adc_dma_mode_enable function

The table below describes the function adc_dma_mode_enable.

Table 11. adc_dma_mode_enable function

Name	Description
Function name	adc_dma_mode_enable
Function prototype	void adc_dma_mode_enable(adc_type *adc_x, confirm_state new_state)
Function description	Enable DMA transfer for ordinary group conversion
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	new_state: pre-configured status of ordinary group in DMA transfer mode This parameter can be TRUE or FALSE.
Output parameter	NA

Name	Description
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable dma transfer adc ordinary conversion data */
adc_dma_mode_enable(ADC1, TRUE);
```

5.1.6 adc_interrupt_enable function

The table below describes the function adc_interrupt_enable.

Table 12. adc_interrupt_enable function

Name	Description
Function name	adc_interrupt_enable
Function prototype	void adc_interrupt_enable(adc_type *adc_x, uint32_t adc_int, confirm_state new_state)
Function description	Enable the selected ADC event interrupt
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_int: ADC event interrupt selection This parameter is used to select any event interrupt supported by ADC.
Input parameter 3	new_state: indicates the pre-configured status of ADC event interrupts This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

adc_int

The adc_int is used to select and set event interrupts, with the following parameters:

ADC_CCE_INT: Interrupt enabled at the end of channel conversion

ADC_VMOR_INT: Interrupt enabled when voltage monitor is outside a threshold

ADC_PCCE_INT: Interrupt enabled at the end of preempted group conversion

ADC_OCCO_INT: Overflow interrupt for ordinary group conversion

ADC_TCF_INT: Trigger conversion fail interrupt

Example:

```
/* enable voltage monitoring out of range interrupt */
adc_interrupt_enable(ADC1, ADC_VMOR_INT, TRUE);
```

5.1.7 adc_calibration_init function

The table below describes the function adc_calibration_init.

Table 13. adc_calibration_init function

Name	Description
Function name	adc_calibration_init
Function prototype	void adc_calibration_init(adc_type *adc_x)
Function description	Initialization calibration
Input parameter	adc_x: indicates the selected ADC This parameter can be ADC1.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* initialize A/D calibration */
adc_calibration_init(ADC1);
```

5.1.8 adc_calibration_init_status_get function

The table below describes the function adc_calibration_init_status_get.

Table 14. adc_calibration_init_status_get function

Name	Description
Function name	adc_calibration_init_status_get
Function prototype	flag_status adc_calibration_init_status_get(adc_type *adc_x)
Function description	Get the status of initialization calibration
Input parameter	adc_x: indicates the selected ADC This parameter can be ADC1.
Output parameter	NA
Return value	flag_status: indicates the status of calibration initialization Return SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```
/* wait initialize A/D calibration success */
while(adc_calibration_init_status_get(ADC1));
```

5.1.9 adc_calibration_start function

The table below describes the function adc_calibration_start.

Table 15. adc_calibration_start function

Name	Description
Function name	adc_calibration_start
Function prototype	void adc_calibration_start(adc_type *adc_x)
Function description	Start calibration
Input parameter	adc_x: indicates the selected ADC This parameter can be ADC1.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* start calibration process */  
adc_calibration_start(ADC1);
```

5.1.10 adc_calibration_status_get function

The table below describes the function adc_calibration_status_get.

Table 16. adc_calibration_status_get function

Name	Description
Function name	adc_calibration_status_get
Function prototype	flag_status adc_calibration_status_get(adc_type *adc_x)
Function description	Get the status of calibration
Input parameter	adc_x: indicates the selected ADC This parameter can be ADC1.
Output parameter	NA
Return value	flag_status: indicates the status of calibration Return SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```
/* wait calibration success */  
while(adc_calibration_status_get(ADC1));
```

5.1.11 adc_voltage_monitor_enable function

The table below describes the function adc_voltage_monitor_enable.

Table 17. adc_voltage_monitor_enable function

Name	Description
Function name	adc_voltage_monitor_enable
Function prototype	void adc_voltage_monitor_enable(adc_type *adc_x, adc_voltage_monitoring_type adc_voltage_monitoring)
Function description	Enable voltage monitor for ordinary/preempted group and a single channel
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_voltage_monitoring: select ordinary group, preempted group or a single channel for voltage monitoring This parameter can be any enumerated value in the adc_voltage_monitoring_type.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

adc_voltage_monitoring

The adc_voltage_monitoring is used to select one or more channels of ordinary group/preempted group for voltage monitoring, including:

ADC_VMONITOR_SINGLE_ORDINARY:

Select a single ordinary channel for voltage monitoring

ADC_VMONITOR_SINGLE_PREEMPT:

Select a single preempted channel for voltage monitoring

ADC_VMONITOR_SINGLE_ORDINARY_PREEMPT:

Select a single channel from ordinary or preempted group for voltage monitoring

ADC_VMONITOR_ALL_ORDINARY:

Select all ordinary channels for voltage monitoring

ADC_VMONITOR_ALL_PREEMPT:

Select all preempted channels for voltage monitoring

ADC_VMONITOR_ALL_ORDINARY_PREEMPT:

Select all ordinary and preempted channels for voltage monitoring

ADC_VMONITOR_NONE:

No channels need voltage monitoring

Example:

```
/* enable the voltage monitoring on all ordinary and preempt channels */
adc_voltage_monitor_enable(ADC1, ADC_VMONITOR_ALL_ORDINARY_PREEMPT);
```

5.1.12 adc_voltage_monitor_threshold_value_set function

The table below describes the function adc_voltage_monitor_threshold_value_set.

Table 18. adc_voltage_monitor_threshold_value_set function

Name	Description
Function name	adc_voltage_monitor_threshold_value_set
Function prototype	void adc_voltage_monitor_threshold_value_set(adc_type *adc_x, uint16_t adc_high_threshold, uint16_t adc_low_threshold)
Function description	Configure the threshold of voltage monitoring
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_high_threshold: indicates the upper limit for voltage monitoring This parameter can be any value between 0x000 and 0xFFFF.
Input parameter 3	adc_low_threshold: indicates the lower limit for voltage monitoring This parameter can be any value lower than that of adc_high_threshold in the range of 0x000~0xFFFF.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* set voltage monitoring's high and low thresholds value */
adc_voltage_monitor_threshold_value_set(ADC1, 0xBBB, 0xAAA);
```

5.1.13 adc_voltage_monitor_single_channel_select function

The table below describes the function adc_voltage_monitor_single_channel_select.

Table 19. adc_voltage_monitor_single_channel_select function

Name	Description
Function name	adc_voltage_monitor_single_channel_select
Function prototype	void adc_voltage_monitor_single_channel_select(adc_type *adc_x, adc_channel_select_type adc_channel)
Function description	Select a single channel for voltage monitoring
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_channel: select a single channel for voltage monitoring Refer to adc_channel for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

adc_channel

The adc_channel is used to select a single channel for voltage monitoring, including:

ADC_CHANNEL_0: ADC channel 0

ADC_CHANNEL_1: ADC channel 1

.....

ADC_CHANNEL_16: ADC channel 16

ADC_CHANNEL_17: ADC channel 17

Example:

```
/* select the voltage monitoring's channel */
adc_voltage_monitor_single_channel_select(ADC1, ADC_CHANNEL_5);
```

5.1.14 adc_ordinary_channel_set function

The table below describes the function adc_ordinary_channel_set.

Table 20. adc_ordinary_channel_set function

Name	Description
Function name	adc_ordinary_channel_set
Function prototype	void adc_ordinary_channel_set(adc_type *adc_x, adc_channel_select_type adc_channel, uint8_t adc_sequence, adc_sampletime_select_type adc_sampletime)
Function description	Configure ordinary channels, including parameters such as channel selection, conversion sequence number and sampling time
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_channel: indicates the selected channel Refer to adc_channel for details.
Input parameter 3	adc_sequence: defines the sequence of channel conversion This parameter can be any value from 1 to 16.
Input parameter 4	adc_sampletime: defines the sampling time for channel Refer to adc_sampletime for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

adc_sampletime

The adc_sampletime is used to configure the sampling time of channels, including:

ADC_SAMPLETIME_1_5: sampling time is 1.5 ADCCLK cycles

ADC_SAMPLETIME_7_5: sampling time is 7.5 ADCCLK cycles

ADC_SAMPLETIME_13_5: sampling time is 13.5 ADCCLK cycles

ADC_SAMPLETIME_28_5: sampling time is 28.5 ADCCLK cycles

ADC_SAMPLETIME_41_5: sampling time is 41.5 ADCCLK cycles

ADC_SAMPLETIME_55_5: sampling time is 55.5 ADCCLK cycles

ADC_SAMPLETIME_71_5: sampling time is 71.5 ADCCLK cycles

ADC_SAMPLETIME_239_5: sampling time is 239.5 ADCCLK cycles

Example:

```
/* set ordinary channel's corresponding rank in the sequencer and sample time */
adc_ordinary_channel_set(ADC1, ADC_CHANNEL_4, 1, ADC_SAMPLETIME_239_5);
adc_ordinary_channel_set(ADC1, ADC_CHANNEL_5, 2, ADC_SAMPLETIME_239_5);
```

5.1.15 adc_preempt_channel_length_set function

The table below describes the function adc_preempt_channel_length_set.

Table 21. adc_preempt_channel_length_set function

Name	Description
Function name	adc_preempt_channel_length_set
Function prototype	void adc_preempt_channel_length_set(adc_type *adc_x, uint8_t adc_channel_lenght)
Function description	Set the length of preempted channel conversion
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_channel_lenght: set the length of preempted channel conversion This parameter can be any value from 0x1 to 0x4.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* set preempt channel lenght */
adc_preempt_channel_length_set(ADC1, 3);
```

5.1.16 adc_preempt_channel_set function

The table below describes the function adc_preempt_channel_set.

Table 22. adc_preempt_channel_set function

Name	Description
Function name	adc_preempt_channel_set
Function prototype	void adc_preempt_channel_set(adc_type *adc_x, adc_channel_select_type adc_channel, uint8_t adc_sequence, adc_sampletime_select_type adc_sampletime)
Function description	Configure preempted group, including parameters such as channel selection, conversion sequence number and sampling time
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_channel: indicates the selected channel Refer to adc_channel for details.
Input parameter 3	adc_sequence: set the sequence number for channel conversion This parameter can be any value from 1 to 4.
Input parameter 4	adc_sampletime: set the sampling time for channels Refer to adc_sampletime for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* set ordinary channel's corresponding rank in the sequencer and sample time */
adc_preempt_channel_set(ADC1, ADC_CHANNEL_7, 1, ADC_SAMPLETIME_239_5);
adc_preempt_channel_set(ADC1, ADC_CHANNEL_8, 2, ADC_SAMPLETIME_239_5);
```

5.1.17 adc_ordinary_conversion_trigger_set function

The table below describes the function adc_ordinary_conversion_trigger_set.

Table 23. adc_ordinary_conversion_trigger_set function

Name	Description
Function name	adc_ordinary_conversion_trigger_set
Function prototype	void adc_ordinary_conversion_trigger_set(adc_type *adc_x, adc_ordinary_trig_select_type adc_ordinary_trig, confirm_state new_state)
Function description	Enable trigger mode and select trigger events for ordinary group conversion
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_ordinary_trig: indicates the selected trigger event for ordinary group This parameter can be any enumerated value in the adc_ordinary_trig_select_type.
Input parameter 3	new_state: indicates the pre-configured status of trigger mode This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

adc_ordinary_trig

The adc_ordinary_trig is used to select a trigger event for ordinary group conversion, including:

ADC_ORDINARY_TRIG_TMR1CH1:	TMR1 CH1 event
ADC_ORDINARY_TRIG_TMR1CH2:	TMR1 CH2 event
ADC_ORDINARY_TRIG_TMR1CH3:	TMR1 CH3 event
ADC_ORDINARY_TRIG_TMR3CH3:	TMR3 CH3 event
ADC_ORDINARY_TRIG_TMR3TRGOUT:	TMR3 TRGOUT event
ADC_ORDINARY_TRIG_TMR15CH1:	TMR15 CH1 event
ADC_ORDINARY_TRIG_EXINT11:	EXINT line11 event
ADC_ORDINARY_TRIG_SOFTWARE:	Software trigger event

Example:

```
/* set ordinary external trigger event */
adc_ordinary_conversion_trigger_set(ADC1, ADC_ORDINARY_TRIG_TMR1CH1, TRUE);
```

5.1.18 adc_preempt_conversion_trigger_set function

The table below describes the function adc_preempt_conversion_trigger_set.

Table 24. adc_preempt_conversion_trigger_set function

Name	Description
Function name	adc_preempt_conversion_trigger_set
Function prototype	void adc_preempt_conversion_trigger_set(adc_type *adc_x, adc_preempt_trig_select_type adc_preempt_trig, confirm_state new_state)
Function description	Enable trigger mode and trigger events for preempted group conversion
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_preempt_trig: indicates the selected trigger event for preempted group This parameter can be any enumerated value in the adc_preempt_trig_select_type.
Input parameter 3	new_state: indicates the pre-configured status of trigger mode This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

adc_preempt_trig

The adc_preempt_trig is used to select a trigger event for preempted group conversion, including:

ADC_PREEMPT_TRIG_TMR1TRGOUT:	TMR1 TRGOUT event
ADC_PREEMPT_TRIG_TMR1CH4:	TMR1 CH4 event
ADC_PREEMPT_TRIG_TMR4CH4:	TMR4 CH4 event
ADC_PREEMPT_TRIG_TMR15CH2:	TMR3 CH4 event
ADC_PREEMPT_TRIG_TMR3CH4:	TMR3 CH4 event
ADC_PREEMPT_TRIG_TMR15TRGOUT:	TMR15 TRGOUT event
ADC_PREEMPT_TRIG_EXINT15:	EXINT line15 event
ADC_PREEMPT_TRIG_SOFTWARE:	Software trigger event

Example:

```
/* set preempt external trigger event */
adc_preempt_conversion_trigger_set(ADC1, ADC_PREEMPT_TRIG_SOFTWARE, TRUE);
```

5.1.19 adc_preempt_offset_value_set function

The table below describes the function adc_preempt_offset_value_set.

Table 25. adc_preempt_offset_value_set function

Name	Description
Function name	adc_preempt_offset_value_set
Function prototype	void adc_preempt_offset_value_set(adc_type *adc_x, adc_preempt_channel_type adc_preempt_channel, uint16_t adc_offset_value)
Function description	Set the offset value of preempted group conversion
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_preempt_channel: indicates the selected channel Refer to adc_preempt_channel for details.
Input parameter 3	adc_offset_value: set the offset value for the selected channel This parameter can be any value from 0x000 to 0xFFFF.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

adc_preempt_channel

The adc_preempt_channel is used to set an offset value for the selected channel, including:

ADC_PREEMPT_CHANNEL_1:	Preempted channel 1
ADC_PREEMPT_CHANNEL_2:	Preempted channel 2
ADC_PREEMPT_CHANNEL_3:	Preempted channel 3
ADC_PREEMPT_CHANNEL_4:	Preempted channel 4

Example:

```
/* set preempt channel's conversion value offset */
adc_preempt_offset_value_set(ADC1, ADC_PREEMPT_CHANNEL_1, 0x111);
adc_preempt_offset_value_set(ADC1, ADC_PREEMPT_CHANNEL_2, 0x222);
adc_preempt_offset_value_set(ADC1, ADC_PREEMPT_CHANNEL_3, 0x333);
```

5.1.20 adc_ordinary_part_count_set function

The table below describes the function adc_ordinary_part_count_set.

Table 26. adc_ordinary_part_count_set function

Name	Description
Function name	adc_ordinary_part_count_set
Function prototype	void adc_ordinary_part_count_set(adc_type *adc_x, uint8_t adc_channel_count)
Function description	Set the number of ordinary channels at each triggered conversion in partition mode
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_channel_count: indicates the number of ordinary group in partition mode This parameter can be any value from 0x1 to 0x8.
Output parameter	NA

Name	Description
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* set partitioned mode channel count */
adc_ordinary_part_count_set(ADC1, 2);
```

Note: In partition mode, only the number of ordinary group is settable, and that of preempted group is fixed 1.

5.1.21 adc_ordinary_part_mode_enable function

The table below describes the function adc_ordinary_part_mode_enable.

Table 27. adc_ordinary_part_mode_enable function

Name	Description
Function name	adc_ordinary_part_mode_enable
Function prototype	void adc_ordinary_part_mode_enable(adc_type *adc_x, confirm_state new_state)
Function description	Enable partition mode for ordinary channels
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	new_state: indicates the pre-configured status for partition mode of ordinary channels This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable the partitioned mode on ordinary channel */
adc_ordinary_part_mode_enable(ADC1, TRUE);
```

5.1.22 adc_preempt_part_mode_enable function

The table below describes the function adc_preempt_part_mode_enable.

Table 28. adc_preempt_part_mode_enable function

Name	Description
Function name	adc_preempt_part_mode_enable
Function prototype	void adc_preempt_part_mode_enable(adc_type *adc_x, confirm_state new_state)
Function description	Enable partition mode for preempted channels
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	new_state: indicates the pre-configured status for partition mode of preempted channels This parameter can be TRUE or FALSE.
Output parameter	NA

Name	Description
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable the partitioned mode on preempt channel */
adc_preempt_part_mode_enable(ADC1, TRUE);
```

5.1.23 adc_preempt_auto_mode_enable function

The table below describes the function adc_preempt_auto_mode_enable.

Table 29. adc_preempt_auto_mode_enable function

Name	Description
Function name	adc_preempt_auto_mode_enable
Function prototype	void adc_preempt_auto_mode_enable(adc_type *adc_x, confirm_state,new_state)
Function description	Enable auto preempted group conversion at the end of ordinary group conversion
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	new_state: indicates the pre-configured status for auto preempted group conversion This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable automatic preempt group conversion */
adc_preempt_auto_mode_enable(ADC1, TRUE);
```

5.1.24 adc_tempersensor_vintrv_enable function

The table below describes the function adc_tempersensor_vintrv_enable.

Table 30. adc_tempersensor_vintrv_enable function

Name	Description
Function name	adc_tempersensor_vintrv_enable
Function prototype	void adc_tempersensor_vintrv_enable(confirm_state new_state)
Function description	Enable internal temperature sensor and V _{INTRV}
Input parameter	new_state: indicates the pre-configured status for internal temperature sensor and V _{INTRV} This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable the temperature sensor and vintrv channel */
adc_tempersensor_vintrv_enable(TRUE);
```

5.1.25 adc_ordinary_software_trigger_enable function

The table below describes the function adc_ordinary_software_trigger_enable.

Table 31. adc_ordinary_software_trigger_enable function

Name	Description
Function name	adc_ordinary_software_trigger_enable
Function prototype	void adc_ordinary_software_trigger_enable(adc_type *adc_x, confirm_state new_state)
Function description	Trigger ordinary group conversion by software
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	new_state: indicates the pre-configured status for software-triggered ordinary group conversion This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable ordinary software start conversion */
adc_ordinary_software_trigger_enable(ADC1, TRUE);
```

5.1.26 adc_ordinary_software_trigger_status_get function

The table below describes the function adc_ordinary_software_trigger_status_get.

Table 32. adc_ordinary_software_trigger_status_get function

Name	Description
Function name	adc_ordinary_software_trigger_status_get
Function prototype	flag_status adc_ordinary_software_trigger_status_get(adc_type *adc_x)
Function description	Get the status of software-triggered ordinary group conversion
Input parameter	adc_x: indicates the selected ADC This parameter can be ADC1.
Output parameter	NA
Return value	flag_status: indicates the status of software-triggered ordinary group conversion Return SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```
/* wait ordinary software start conversion */
while(adc_ordinary_software_trigger_status_get(ADC1));
```

5.1.27 adc_preempt_software_trigger_enable function

The table below describes the function adc_preempt_software_trigger_enable.

Table 33. adc_preempt_software_trigger_enable function

Name	Description
Function name	adc_preempt_software_trigger_enable
Function prototype	void adc_preempt_software_trigger_enable(adc_type *adc_x, confirm_state new_state)
Function description	Preempted group conversion triggered by software
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	new_state: indicates the pre-configured status of software-triggered preempted group conversion This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable preempt software start conversion */
adc_preempt_software_trigger_enable(ADC1, TRUE);
```

5.1.28 adc_preempt_software_trigger_status_get function

The table below describes the function adc_preempt_software_trigger_status_get.

Table 34. adc_preempt_software_trigger_status_get function

Name	Description
Function name	adc_preempt_software_trigger_status_get
Function prototype	flag_status adc_preempt_software_trigger_status_get(adc_type *adc_x)
Function description	Get the status of software-triggered preempted group conversion
Input parameter	adc_x: indicates the selected ADC This parameter can be ADC1.
Output parameter	NA
Return value	flag_status: indicates the status of software-triggered preempted group conversion Return SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```
/* wait preempt software start conversion */
while(adc_preempt_software_trigger_status_get(ADC1));
```

5.1.29 adc_ordinary_conversion_data_get function

The table below describes the function adc_ordinary_conversion_data_get.

Table 35. adc_ordinary_conversion_data_get function

Name	Description
Function name	adc_ordinary_conversion_data_get
Function prototype	uint16_t adc_ordinary_conversion_data_get(adc_type *adc_x)
Function description	Get the converted data of ordinary group in non-master/slave mode
Input parameter	adc_x: indicates the selected ADC This parameter can be ADC1.
Output parameter	NA
Return value	16-bit converted data by ordinary group
Required preconditions	NA
Called functions	NA

Example:

```
uint16_t adc1_ordinary_index = 0;
adc1_ordinary_index = adc_ordinary_conversion_data_get(ADC1);
```

Note: This function can be used only when the ADC is configured with a single channel.

5.1.30 adc_preempt_conversion_data_get function

The table below describes the function adc_preempt_conversion_data_get.

Table 36. adc_preempt_conversion_data_get function

Name	Description
Function name	adc_preempt_conversion_data_get
Function prototype	uint16_t adc_preempt_conversion_data_get(adc_type *adc_x, adc_preempt_channel_type adc_preempt_channel)
Function description	Get the converted data of preempted group
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_preempt_channel: the selected preempted channel Refer to adc_preempt_channel for details.
Output parameter	NA
Return value	16-bit converted data by preempted group
Required preconditions	NA
Called functions	NA

Example:

```
uint16_t adc1_preempt_valuetab[3] = {0};
adc1_preempt_valuetab[0] = adc_preempt_conversion_data_get(ADC1, ADC_PREEMPT_CHANNEL_1);
adc1_preempt_valuetab[1] = adc_preempt_conversion_data_get(ADC1, ADC_PREEMPT_CHANNEL_2);
adc1_preempt_valuetab[2] = adc_preempt_conversion_data_get(ADC1, ADC_PREEMPT_CHANNEL_3);
```

5.1.31 adc_flag_get function

The table below describes the function adc_flag_get.

Table 37. adc_flag_get function

Name	Description
Function name	adc_flag_get
Function prototype	flag_status adc_flag_get(adc_type *adc_x, uint8_t adc_flag)
Function description	Get the status of the flag bit
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_flag: indicates the selected flag Refer to adc_flag for details.
Output parameter	NA
Return value	flag_status: the status for the selected flag bit Return SET or RESET.
Required preconditions	NA
Called functions	NA

adc_flag

The adc_flag is used to select a flag to get its status, including:

ADC_VMOR_FLAG:	Voltage monitor outside threshold
ADC_CCE_FLAG:	End of channel conversion
ADC_PCCE_FLAG:	End of preempted group conversion
ADC_PCCS_FLAG:	Start of preempted channel conversion
ADC_OCCS_FLAG:	Start of ordinary channel conversion
ADC_OCCO_FLAG:	Overflow flag for ordinary channel conversion
ADC_RDY_FLAG:	ADC ready to conversion flag
ADC_TCF_FLAG:	ADC trigger conversion fail flag
ADC_OTCF_FLAG:	ADC ordinary channel trigger conversion fail flag
ADC_PTDF_FLAG:	ADC preempted channel trigger conversion fail flag

Example:

```
/* check if wakeup preempted channelsconversion end flag is set */
if(adc_flag_get(ADC1, ADC_PCCE_FLAG) != RESET)
```

5.1.32 adc_interrupt_flag_get function

The table below describes the function adc_interrupt_flag_get.

Table 38. adc_interrupt_flag_get function

Name	Description
Function name	adc_interrupt_flag_get
Function prototype	flag_status adc_interrupt_flag_get(adc_type *adc_x, uint8_t adc_flag)
Function description	Get ADC interrupt flag status
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_flag: select a flag to be clear Refer to adc_flag for details.
Output parameter	NA
Return value	flag_status: SET or RESET.
Required preconditions	NA
Called functions	NA

adc_flag

The adc_flag is used to select a flag to get its status, including:

- ADC_VMOR_FLAG: Voltage monitor outside threshold
- ADC_CCE_FLAG: End of channel conversion
- ADC_PCCE_FLAG: End of preempted group conversion
- ADC_OCCO_FLAG: Overflow flag for ordinary channel conversion
- ADC_TCF_FLAG: ADC trigger conversion fail flag

Example:

```
/* check if wakeup preempted channelsconversion end flag is set */
if(adc_interrupt_flag_get(ADC1, ADC_PCCE_FLAG) != RESET)
```

5.1.33 adc_flag_clear function

The table below describes the function adc_flag_clear.

Table 39. adc_flag_clear function

Name	Description
Function name	adc_flag_clear
Function prototype	void adc_flag_clear(adc_type *adc_x, uint32_t adc_flag)
Function description	Clear the flag bits that have been set.
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_flag: select a flag to be clear. Refer to adc_flag for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* preempted channels conversion end flag clear */
adc_flag_clear(ADC1, ADC_PCCE_FLAG);
```

5.1.34 adc_conversion_stop function

The table below describes the function adc_conversion_stop.

Table 40. adc_conversion_stop function

Name	Description
Function name	adc_conversion_stop
Function prototype	void adc_conversion_stop(adc_type *adc_x)
Function description	Stop on-going ADC conversion
Input parameter	adc_x: indicates the selected ADC This parameter can be ADC1.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* stop the ongoing conversion */
adc_conversion_stop(ADC1);
```

5.1.35 adc_conversion_stop_status_get function

The table below describes the function adc_conversion_stop_status_get.

Table 41. adc_conversion_stop_status_get function

Name	Description
Function name	adc_conversion_stop_status_get
Function prototype	flag_status adc_conversion_stop_status_get(adc_type *adc_x)
Function description	Get the status of stop conversion command
Input parameter	adc_x: indicates the selected ADC This parameter can be ADC1.
Output parameter	NA
Return value	flag_status: get the operational status of stop conversion command Return SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```
/* wait stop conversion's */
while(adc_conversion_stop_status_get(ADC1));
```

5.1.36 adc_convert_fail_auto_abort_enable

The table below describes the function adc_convert_fail_auto_abort_enable.

Table 42. adc_convert_fail_auto_abort_enable function

Name	Description
Function name	adc_convert_fail_auto_abort_enable
Function prototype	void adc_convert_fail_auto_abort_enable(adc_type *adc_x, confirm_state new_state)
Function description	Enable ADC auto abort after conversion failure
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	new_state: indicates the pre-configured status for ADC auto abort after conversion failure This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable adc trigger conversion fail auto conversion abort */
adc_convert_fail_auto_abort_enable(ADC1, TRUE);
```

5.1.37 adc_xeoc_sync_mode_set function

The table below describes the function adc_xeoc_sync_mode_set.

Table 43. adc_xeoc_sync_mode_set function

Name	Description
Function name	adc_xeoc_sync_mode_set
Function prototype	void adc_xeoc_sync_mode_set(adc_type *adc_x, adc_xeoc_sync_type xeoc_sync_mode)
Function description	Set XEOC synchronization mode
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	xeoc_sync_mode: XEOC synchronization mode See xeoc_sync_mode for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

xeoc_sync_mode

The xeoc_sync_mode is used to select the synchronization mode for XEOC signal, including:

ADC_XEOC_SYNC_RISING_EDGE: Synchronized with rising edge

ADC_XEOC_SYNC_HIGH_LEVEL: Synchronized with high level

Example:

```
/* set XEOC sync rising edge */
```

```
adc_xeoc_sync_mode_set(ADC1, ADC_XEOC_SYNC_RISING_EDGE);
```

5.1.38 adc_fail_auto_processing_enale function

The table below describes the function adc_fail_auto_processing_enale.

Table 44. adc_fail_auto_processing_enale function

Name	Description
Function name	adc_fail_auto_processing_enale
Function prototype	void adc_fail_auto_processing_enale(adc_type *adc_x, confirm_state new_state)
Function description	Enable auto processing after ADC conversion trigger failure
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	new_state: indicates the pre-configured status for auto processing after ADC conversion trigger failure This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable the adc trigger conversion fail auto processing mode */
adc_fail_auto_processing_enale (ADC1, TRUE);
```

5.1.39 adc_fail_auto_processing_mode_set.

The table below describes the function adc_fail_auto_processing_mode_set.

Table 45. adc_xeoc_sync_mode_set function

Name	Description
Function name	adc_fail_auto_processing_mode_set
Function prototype	void adc_fail_auto_processing_mode_set(adc_type *adc_x, adc_fail_auto_processing_mode_type fail_auto_processing_mode)
Function description	Set the auto processing mode after ADC conversion trigger failure
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	fail_auto_processing_mode: the auto processing mode after ADC conversion trigger failure Refer to fail_auto_processing_mode for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

fail_auto_processing_mode

The fail_auto_processing_mode is used to select the auto processing mode after ADC conversion trigger failure, including:

ADC_AUTO_STORAGE_TEMPORARY_DATA: Store XD value automatically

ADC_AUTO_CONVERSION_FAIL_CHANNEL: Converted the failed channel automatically

Example:

```
/* set adc fail auto processing mode */
adc_fail_auto_processing_mode_set(ADC1, ADC_AUTO_STORAGE_TEMPORARY_DATA);
```

5.1.40 adc_conversion_fail_sequence_number_get function

The table below describes the function adc_conversion_fail_sequence_number_get.

Table 46. adc_conversion_fail_sequence_number_get function

Name	Description
Function name	adc_conversion_fail_sequence_number_get
Function prototype	uint16_t adc_conversion_fail_sequence_number_get(adc_type *adc_x, uint32_t adc_group_number)
Function description	Get the sequence number of ADC conversion trigger failure
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_group_number: the selected ADC channel group Refer to adc_group_number for details.
Output parameter	NA
Return value	16-bit channel number
Required preconditions	NA
Called functions	NA

adc_group_number

The adc_group_number is used to select the channel group, including:

ADC_OSNF_NUMBER: sequence number of the failed ordinary channel group

ADC_PSNF_NUMBER: sequence number of the failed preempted channel group

Example:

```
__IO uint16_t count_tcf_ord_sequence_number = 0;
count_tcf_ord_sequence_number = adc_conversion_fail_sequence_number_get(ADC1,
ADC_OSNF_NUMBER);
```

5.1.41 adc_conversion_fail_sequence_number_clear function

The table below describes the function adc_conversion_fail_sequence_number_clear.

Table 47. adc_conversion_fail_sequence_number_clear function

Name	Description
Function name	adc_conversion_fail_sequence_number_clear
Function prototype	void adc_conversion_fail_sequence_number_clear(adc_type *adc_x, uint32_t adc_group_number)
Function description	Clear the sequence number of ADC conversion trigger failure
Input parameter 1	adc_x: indicates the selected ADC This parameter can be ADC1.
Input parameter 2	adc_group_number: the selected ADC channel group Refer to adc_group_number for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* ordinary conversion_fail_sequence_number_clear */  
adc_conversion_fail_sequence_number_clear (ADC1, ADC_OSNF_NUMBER);
```

5.2 Controller area network (CAN)

CAN register structure can_type is defined in the “AT32F422_426_can.h”.

```
/*
 * @brief type define can register all
 */
typedef struct
{
    ...
} can_type;
```

The table below gives a list of the CAN registers.

Table 48. Summary of CAN registers

Register	Description
tncfg	Timestamp and node control register
actime	Classic-CAN bit timing register
fdtime	CAN-FD bit timing register
lbtcfg	Limit and bit timing configuration register
sts	Interrupt status register
tstat	Transmit status register
tts	Transmit timestamp register
ctrlstat	Control and status register
err	Error configuration and status register
refmsg	TTCAN reference message register
ttcfg	TTCAN trigger configuration register
tttrig	TTCAN trigger timing configuration register
acfctrl	Acceptance filter control register
fcid	Filter identifier ID area
fcfmt	Filter identifier format area
fctyp	Filter identifier type area
fcacf	Filter identifier acceptance field
fmid	Filter mask ID area
fmfmt	Filter mask format area
fmtyp	Filter mask type area
fmacf	Filter mask acceptance field
rbid	Receive buffer ID area
rbfmt	Receive buffer format area
rbtyp	Receive buffer type area
rbacf	Receive buffer acceptance field
rbdat[0..18]	Receive buffer data area
tbid	Trasmit buffer ID area
tbfmt	Trasmit buffer format area
tbtyp	Trasmit buffer type area
tbacf	Trasmit buffer acceptance field
tbdat[0..15]	Trasmit buffer data area

Register	Description
llcformat	LLC frame calculation input register
llcsize	LLC frame calculation output register
inten	Interrupt enable register

The table below gives a list of CAN library functions.

Table 49. Summary of CAN library functions

Function name	Description
can_reset	Reset all CAN registers to their reset values
can_software_reset	CAN software reset
can_fd_iso_mode_enable	Enable CAN-FD ISO mode (for CAN-FD only)
can_mode_set	Set CAN operating mode
can_standby_mode_enable	Enable transceiver standby mode
can_restricted_operation_enable	Enable CAN restricted operation mode
can_bittime_default_para_init	Set initial default value for the can_bittime_struct
can_bittime_set	Set CAN bittime and baud rate
can_retransmission_limit_set	Set CAN retransmission limit
can_rearbitration_limit_set	Set CAN rearbitration limit
can_timestamp_enable	Enable CAN timestamp
can_timestamp_position_set	Set CAN timestamp position
can_transmit_timestamp_get	Get CAN transmit timestamp
can_txbuf_write	Write CAN transmit buffer
can_txbuf_transmit	Transmit data from transmit buffer
can_transmit_abort	Abort CAN data transmission
can_stb_transmit_mode_set	Set transmit mode of secondary transmission buffer
can_stb_status_get	Get secondary transmit buffer status
can_transmit_status_get	Get transmit status
can_stb_clear	Clear secondary transmit buffer data
can_rxbuf_overflow_mode_set	Set overflow mode of receive buffer
can_receive_all_enable	Enable receive all
can_rxbuf_read	Read data of receive buffer
can_rxbuf_release	Release receiver buffer
can_rxbuf_status_get	Get receive buffer status
can_filter_default_para_init	Set initial default value for the filter_config_struct
can_filter_set	Set CAN receive filter
can_filter_enable	Enable receiver filter
can_arbitration_lost_capture_get	Get arbitration lost position
can_rxbuf_warning_set	Set receive buffer almost full warning level value
can_error_warning_set	Set error count warning level value
can_kind_error_get	Get error type
can_receive_error_counter_get	Get receive error count
can_transmit_error_counter_get	Get transmit error count
can_busoff_get	Get bus-off status
can_busoff_reset	Reset bus-off status

can_ttcn_ref_message_set	Set TTCAN reference message
can_ttcn_timer_div_set	Set TTCAN clock timer division
can_ttcn_enable	Enable TTCAN
can_ttcn_trigger_type_set	Set TTCAN trigger type
can_ttcn_trigger_set	Set TTCAN trigger time
can_ttcn_watch_trigger_set	Set TTCAN window trigger time
can_ttcn_transmit_window_set	Set TTCAN transmit enable widow
can_ttcn_txbuf_enable	Enable TTCAN transmit buffer slot mode
can_ttcn_txbuf_status_set	Set TTCAN transmit buffer slot state
can_ttcn_txbuf_status_get	Get TTCAN transmit buffer slot status
can_ttcn_txbuf_transmit_set	Set TTCAN transmit buffer slot to be sent
can_ttcn_txbuf_write	Write TTCAN transmit buffer slot
can_interrupt_enable	Enable CAN interrupts
can_flag_get	Get CAN flags
can_interrupt_flag_get	Get CAN interrupt flags
can_flag_clear	Clear CAN interrupt flags

5.2.1 can_reset function

The table below describes the function can_reset.

Table 50. can_reset function

Name	Description
Function name	can_reset
Function prototype	void can_reset(can_type* can_x);
Function description	Reset all CAN registers to their default values.
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
can_reset(CAN1);
```

5.2.2 can_software_reset function

The table below describes the function can_software_reset.

Table 51. can_software_reset function

Name	Description
Function name	can_software_reset
Function prototype	void can_software_reset(can_type* can_x, confirm_state new_state);
Function description	Reset partial CAN registers to their default values and these register can be configurable only when software resets
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	new_state: enable or disable This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
can_software_reset(CAN1);
```

5.2.3 can_fd_iso_mode_enable function

The table below describes the function can_fd_iso_mode_enable.

Table 52. can_fd_iso_mode_enable function

Name	Description
Function name	can_fd_iso_mode_enable
Function prototype	void can_fd_iso_mode_enable(can_type* can_x, confirm_state new_state);
Function description	Enale CAN-FD ISO mode (for CAN-FD only)
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	new_state: enable or disable This parameter can be FALSE or TRUE
Output parameter	NA
Return value	NA
Required preconditions	This mode can be used only when software resets.
Called functions	NA

Example:

```
can_software_reset(CAN1, TRUE);
can_fd_iso_mode_enable(CAN1, TRUE);
can_software_reset(CAN1, FALSE);
```

5.2.4 can_mode_set function

The table below describes the function can_mode_set.

Table 53. can_mode_set function

Name	Description
Function name	can_mode_set
Function prototype	void can_mode_set(can_type* can_x, can_mode_type mode_selection);
Function description	Set CAN communication mode
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	mode_selection: operating mode selection
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

mode_selection

CAN_MODE_COMMUNICATE:	Communication mode
CAN_MODE_EXT_LOOPBACK:	External loopback mode
CAN_MODE_EXT_LOOPBACK_ACK:	External loopback + acknowledge mode
CAN_MODE_INT_LOOPBACK:	Internal loopback mode
CAN_MODE_LISTENONLY:	Listen-only mode
CAN_MODE_LISTENONLY_EXT:	Listen-only + external loopback mode
CAN_MODE_LISTENONLY_EXT_ACK:	Listen-only + external loopback + acknowledge mode

Example:

```
can_mode_set(CAN1, CAN_MODE_COMMUNICATE);
```

5.2.5 can_standby_mode_enable function

The table below describes the function can_standby_mode_enable.

Table 54. can_standby_mode_enable function

Name	Description
Function name	can_standby_mode_enable
Function prototype	error_status can_standby_mode_enable(can_type* can_x, confirm_state new_state);
Function description	Enable CAN transceiver standby mode
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	new_state: enable or disable This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	error_status: setting success or setting failure
Required preconditions	NA
Called functions	NA

Example:

```
can_standby_mode_enable (CAN1, TRUE);
```

5.2.6 can_restricted_operation_enable function

The table below describes the function can_restricted_operation_enable.

Table 55. can_restricted_operation_enable function

Name	Description
Function name	can_restricted_operation_enable
Function prototype	void can_restricted_operation_enable(can_type* can_x, confirm_state new_state);
Function description	Enable CAN restricted operation mode
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	new_state: enable or disable This parameter can be FALSE or TRUE
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
can_restricted_operation_enable(CAN1, TRUE);
```

5.2.7 can_bittime_default_para_init function

The table below describes the function can_bittime_default_para_init.

Table 56. can_bittime_default_para_init function

Name	Description
Function name	can_bittime_default_para_init
Function prototype	void can_bittime_default_para_init(can_bittime_type* can_bittime_struct);
Function description	Set an initial default value for the can_bittime_struct
Input parameter 1	can_bittime_struct: pointer to the can_bittime_type
Output parameter	NA
Return value	NA
Required preconditions	It is necessary to define a variable of the can_bittime_type before starting.
Called functions	NA

can_bittime_type is defined in the AT32F422_426_can.h:

typedef struct

```
{
    uint8_t bittime_div;
    uint8_t ac_rsaw_size;
    uint16_t ac_bts1_size;
    uint8_t ac_bts2_size;
```

```
#ifdef SUPPORT_CAN_FD
    uint8_t fd_rsaw_size;
    uint16_t fd_bts1_size;
    uint8_t fd_bts2_size;
    uint8_t fd_ssp_offset;
#endif
} can_bittime_type;
bittime_div
CAN clock division factor
Value range: 0x01~0x20
ac_rsaw_size
classic-can resynchronization jump width: the maximum limit for shortening or lengthening the bit time for resynchronization
Value range: 0x01~0x80
ac_bts1_size
classic-can segment1 time
Value range: 0x02~0x201
ac_bts2_size
classic-can segment2 time
Value range: 0x01~0x80
fd_rsaw_size
can-fd resynchronization jump width: the maximum limit for shortening or lengthening the bit time for resynchronization
Value range: 0x01~0x80
fd_bts1_size
can-fd segment1 time
Value range: 0x02~0x101
fd_bts2_size
can-fd segment2 time
Value range: 0x01~0x80
fd_ssp_offset
can-fd secondary sample point offset
Value range: 0x00~0xFF
```

Example:

```
/* initialize a can_bittime_type structure */
can_bittime_type can_bittime_struct;
can_bittime_default_para_init(&can_bittime_struct);
```

5.2.8 can_bittime_set function

The table below describes the function can_bittime_set.

Table 57. can_bittime_set function

Name	Description
Function name	can_bittime_set
Function prototype	void can_bittime_set(can_type* can_x, can_bittime_type* can_bittime_struct);
Function description	Set CAN baud rate
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	can_bittime_struct: pointer to the can_bittime_type
Output parameter	NA
Return value	NA
Required preconditions	1. It is necessary to define the can_bittime_type variable 2. This feature can be used only when software resets
Called functions	NA

can_bittime_type is defined in the AT32F422_426_can.h:

typedef struct

```
{
    uint8_t bittime_div;
    uint8_t ac_rsaw_size;
    uint16_t ac_bts1_size;
    uint8_t ac_bts2_size;
#define SUPPORT_CAN_FD
    uint8_t fd_rsaw_size;
    uint16_t fd_bts1_size;
    uint8_t fd_bts2_size;
    uint8_t fd_ssp_offset;
#endif
```

} can_bittime_type;

bittime_div

CAN clock division factor

Value range: 0x01~0x20

ac_rsaw_size

classic-can resynchronization jump width: the maximum limit for shortening or lengthening the bit time for resynchronization

Value range: 0x01~0x80

ac_bts1_size

classic-can segment1 time

Value range: 0x02~0x201

ac_bts2_size

classic-can segment2 time

Value range: 0x01~0x80

fd_rsaw_size

can-fd resynchronization jump width: the maximum limit for shortening or lengthening the bit time for

resynchronization

Value range: 0x01~0x80

fd_bts1_size

can-fd segment1 time

Value range: 0x02~0x101

fd_bts2_size

can-fd segment2 time

Value range: 0x01~0x80

fd_ssp_offset

can-fd secondary sample point offset

Value range: 0x00~0xFF

Example:

```
can_software_reset(CAN1, TRUE);
/* set can bit time */
can_bittime_struct.bittime_div = 1;
can_bittime_struct.ac_bts1_size = 96;
can_bittime_struct.ac_bts2_size = 24;
can_bittime_struct.ac_rsaw_size = 24;
can_bittime_struct.fd_bts1_size = 19;
can_bittime_struct.fd_bts2_size = 5;
can_bittime_struct.fd_rsaw_size = 5;
can_bittime_struct.fd_ssp_offset = 20;
can_bittime_set(CAN1, &can_bittime_struct);
can_software_reset(CAN1, FALSE);
```

5.2.9 can_retransmission_limit_set function

The table below describes the function can_retransmission_limit_set.

Table 58. can_retransmission_limit_set function

Name	Description
Function name	can_retransmission_limit_set
Function prototype	void can_retransmission_limit_set(can_type* can_x, can_retransmission_times_type re_trans_times);
Function description	Set CAN retransmission limit
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	re_trans_times: retransmission times
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

re_trans_times

CAN_RE_TRANS_TIMES_0: No retransmission

CAN_RE_TRANS_TIMES_1: Retransmission 1 time

.....
 CAN_RE_TRANS_TIMES_6: Retransmission 6 times
 CAN_RE_TRANS_TIMES_UNLIMIT: Retransmission unlimited

Example:

```
can_retransmission_limit_set(CAN1, CAN_RE_TRANS_TIMES_UNLIMIT);
```

5.2.10 can_rearbitration_limit_set function

The table below describes the function can_rearbitration_limit_set.

Table 59. can_rearbitration_limit_set function

Name	Description
Function name	can_rearbitration_limit_set
Function prototype	void can_rearbitration_limit_set(can_type* can_x, can_rearbitration_times_type re_arbi_times);
Function description	Set rearbitration limit
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	re_arbi_times: rearbitration times
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

re_arbi_times

CAN_RE_ARBI_TIMES_0: No retransmission
 CAN_RE_ARBI_TIMES_1: Retransmission 1 time

 CAN_RE_ARBI_TIMES_6: Retransmission 6 times
 CAN_RE_ARBI_TIMES_UNLIMIT: Retransmission unlimited

Example:

```
can_rearbitration_limit_set(CAN1, CAN_RE_ARBI_TIMES_UNLIMIT);
```

5.2.11 can_timestamp_enable function

The table below describes the function can_timestamp_enable.

Table 60. can_timestamp_enable function

Name	Description
Function name	can_timestamp_enable
Function prototype	void can_timestamp_enable(can_type* can_x, confirm_state new_state);
Function description	Enable timestamp
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	new_state: enable or disable This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
can_timestamp_enable(CAN1, TRUE);
```

5.2.12 can_timestamp_position_set function

The table below describes the function can_timestamp_position_set.

Table 61. can_timestamp_position_set function

Name	Description
Function name	can_timestamp_position_set
Function prototype	void can_timestamp_position_set(can_type* can_x, can_timestamp_position_type timestamp_position);
Function description	Set timestamp position
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	timestamp_position: timestamp position
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

timestamp_position

CAN_TIMESTAMP_AT_SOF: Timestamp at SOF

CAN_TIMESTAMP_AT_EOF: Timestamp at EOF

Example:

```
can_timestamp_position_set(CAN1, CAN_TIMESTAMP_AT_SOF);
```

5.2.13 can_transmit_timestamp_get function

The table below describes the function can_transmit_timestamp_get.

Table 62. can_transmit_timestamp_get function

Name	Description
Function name	can_transmit_timestamp_get
Function prototype	uint32_t can_transmit_timestamp_get(can_type* can_x);
Function description	Get transmit timestamp
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Output parameter	NA
Return value	Transmit timestamp Range: depends on TMR counter
Required preconditions	NA
Called functions	NA

Example:

```
uint32_t transmit_timestamp;
transmit_timestamp = can_transmit_timestamp_get (CAN1);
```

5.2.14 can_txbuf_write function

The table below describes the function can_txbuf_write.

Table 63. can_txbuf_write function

Name	Description
Function name	can_txbuf_write
Function prototype	error_status can_txbuf_write(can_type* can_x, can_txbuf_select_type txbuf_type, can_txbuf_type* can_txbuf_struct);
Function description	Write transmit buffer
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	txbuf_type: transmit buffer selection
Input parameter 3	can_txbuf_struct: write data, refere to the pointer of can_txbuf_type
Output parameter	NA
Return value	error_status: success or failure
Required preconditions	NA
Called functions	NA

txbuf_type

Select a transmit buffer type.

CAN_TXBUF_PTB: Primary transmit buffer

CAN_TXBUF_STB: Secondary transmit buffer

can_txbuf_type is defined in the AT32F422_426_can.h:

typedef struct

```
{  
    uint32_t id;  
    can_identifier_type      id_type;  
    can_frame_type          frame_type;  
#ifdef SUPPORT_CAN_FD  
    can_format_type         fd_format;  
    can_rate_switch_type    fd_rate_switch;  
    uint8_t data[64];  
#else  
    uint8_t data[8];  
#endif  
    confirm_state   tx_timestamp;  
    uint8_t        handle;  
} can_txbuf_type;
```

id
Standard identifier (11bit) or extended identifier (29bit)
Value range: 0x000~0x7FF or 0x000~0x1FFFFFF

id_type
Identifier type
CAN_ID_STANDARD: Standard identifier
CAN_ID_EXTENDED: Extended identifier

frame_type
Frame type
CAN_FRAME_DATA: Data frame
CAN_FRAME_REMOTE: Remote frame

fd_format
Version format
CAN_FORMAT_CLASSIC: Classic CAN2.0A/B
CAN_FORMAT_FD: CAN-FD

fd_rate_switch
Baud rate switch type
CAN_BRS_OFF: Baud rate switch OFF
CAN_BRS_ON: Baud rate switch ON

tx_timestamp
Enable or disable transmit timestamp
FALSE: Disable transmit timestamp
TRUE: Enable transmit timestamp

data_length
Data field length
CAN_DLC_BYTES_0: 0 byte
.....
CAN_DLC_BYTES_8: 8 bytes
CAN_DLC_BYTES_12: 12 bytes (for CAN-FD only)
CAN_DLC_BYTES_16: 16 bytes (for CAN-FD only)
CAN_DLC_BYTES_20: 20 bytes (for CAN-FD only)
CAN_DLC_BYTES_24: 24 bytes (for CAN-FD only)

CAN_DLC_BYTES_32: 32 bytes (for CAN-FD only)
CAN_DLC_BYTES_48: 48 bytes (for CAN-FD only)
CAN_DLC_BYTES_64: 64 bytes (for CAN-FD only)

data[64]

Data to write transmit buffer (for CAN-FD only)

Value range: 0x00~0xFF

data[8]

Data to write transmit buffer

Value range: 0x00~0xFF

handle

Handle that is used to identify frames

Value range: 0x00~0xFF

Example:

```
can_txbuf_type can_txbuf_struct;

/* write the primary transmit buffer */
can_txbuf_struct.id = 0x400;
can_txbuf_struct.id_type = CAN_ID_STANDARD;
can_txbuf_struct.frame_type = CAN_FRAME_DATA;
can_txbuf_struct.format_type = CAN_FORMAT_FD;
can_txbuf_struct.switch_type = CAN_BRS_ON;
can_txbuf_struct.data_length = CAN_DLC_BYTES_64;
can_txbuf_struct.data[0] = 0x00;
can_txbuf_struct.data[1] = 0x11;
can_txbuf_struct.data[2] = 0x22;
can_txbuf_struct.data[3] = 0x33;
can_txbuf_struct.data[4] = 0x44;
can_txbuf_struct.data[5] = 0x55;
can_txbuf_struct.data[6] = 0x66;
can_txbuf_struct.data[7] = 0x77;
can_txbuf_struct.data[63] = 0x63;
can_txbuf_struct.tx_timestamp = TRUE;
while(can_txbuf_write(CAN1, CAN_TXBUF_PTB, &can_txbuf_struct) != SUCCESS);
```

5.2.15 can_txbuf_transmit function

The table below describes the function can_txbuf_transmit.

Table 64. can_txbuf_transmit function

Name	Description
Function name	can_txbuf_transmit
Function prototype	error_status can_txbuf_transmit(can_type* can_x, can_transmit_txbuf_type transmit_type);
Function description	Transmit data of transmit buffer
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	transmit_type: transmit type
Output parameter	NA
Return value	error_status: transmit enable is successful or not
Required preconditions	NA
Called functions	NA

transmit_type

Transmit type

CAN_TRANSMIT_PTB:	Transmit data of primary transmit buffer
CAN_TRANSMIT_STB_ONE:	Transmit one frame data of secondary transmit buffer
CAN_TRANSMIT_STB_ALL:	Transmit all data of primary transmit buffer

Example:

```
/* transmit the primary transmit buffer */
can_txbuf_transmit(CAN1, CAN_TRANSMIT_PTB);
```

5.2.16 can_transmit_abort function

The table below describes the function can_transmit_abort.

Table 65. can_transmit_abort function

Name	Description
Function name	can_transmit_abort
Function prototype	void can_transmit_abort(can_type* can_x, can_abort_transmit_type abort_type);
Function description	Transmit abort
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	abort_type: abort type
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

abort_type

Abort type

CAN_ABORT_TRANSMIT_PTB:	Abort primary transmit buffer
CAN_ABORT_TRANSMIT_STB:	Abort secondary transmit buffer

Example:

```
can_transmit_abort(CAN1, CAN_ABORT_TRANSMIT_PTB);
```

5.2.17 can_stb_transmit_mode_set function

The table below describes the function can_stb_transmit_mode_set.

Table 66. can_stb_transmit_mode_set function

Name	Description
Function name	can_stb_transmit_mode_set
Function prototype	void can_stb_transmit_mode_set(can_type* can_x, can_stb_transmit_mode_type stb_transmit_mode);
Function description	Set secondary transmit buffer transmit mode
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	stb_transmit_mode: select secondary transmit buffer transmit mode
Output parameter	NA
Return value	NA
Required preconditions	This function is configured only when software resets.
Called functions	NA

stb_transmit_mode

Secondary transmit buffer transmit mode

CAN_STB_TRANSMIT_BY_FIFO:	Transmit secondary transmit buffer by FIFO
CAN_STB_TRANSMIT_BY_ID:	Transmit secondary transmit buffer by ID

Example:

```
can_software_reset(CAN1, TRUE);
can_stb_transmit_mode_set(CAN1, CAN_STB_TRANSMIT_BY_FIFO);
can_software_reset(CAN1, FALSE);
```

5.2.18 can_stb_status_get function

The table below describes the function can_stb_status_get.

Table 67. can_stb_status_get function

Name	Description
Function name	can_stb_status_get
Function prototype	can_stb_status_type can_stb_status_get(can_type* can_x);
Function description	Get secondary transmit buffer status
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Output parameter	NA
Return value	can_stb_status: secondary transmit buffer status
Required preconditions	NA
Called functions	NA

can_stb_status

Select secondary transmit buffer status

CAN_STB_STATUS_EMPTY:	Secondary transmit buffer is empty
CAN_STB_STATUS_LESS:	Secondary transmit buffer is less than or equal to half full
CAN_STB_STATUS_MORE:	Secondary transmit buffer is more than half full
CAN_STB_STATUS_FULL:	Secondary transmit buffer is full

Example:

```
can_stb_status_type stb_status;
stb_status = can_stb_status_get(CAN1);
```

5.2.19 can_transmit_status_get function

The table below describes the function can_transmit_status_get.

Table 68. can_transmit_status_get function

Name	Description
Function name	can_transmit_status_get
Function prototype	void can_transmit_status_get(can_type* can_x, can_transmit_status_type* transmit_status_struct);
Function description	Get transmit status
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Output parameter 1	transmit_status_struct: to-be-written data, see the pointer of the can_transmit_status_type
Return value	NA
Required preconditions	NA
Called functions	NA

can_transmit_status_type is defined in the AT32F422_426_can.h:
typedef struct

```
{  
    uint8_t current_handle;  
    can_tstat_encoding_type current_tstat;  
    uint8_t final_handle;  
    can_tstat_encoding_type final_tstat;  
} can_transmit_status_type;
```

current_handle

The handle (identifier) of the current transmit frame

Value range: 0x00~0xFF

current_tstat

The status of the current transmit frame

CAN_TSTAT_IDLE:	Transmit is in idle state
CAN_TSTAT_ONGOING:	Transmit is ongoing
CAN_TSTAT_LOST_ARBITRATION:	Transmit lost arbitration (retransmission limit is reached)
CAN_TSTAT_TRANSMITTED:	Transmit is complete
CAN_TSTAT_ABORTED:	Transmit is aborted
CAN_TSTAT_DISTURBED:	Transmit is disturbed (retransmission limit is reached)
CAN_TSTAT_REJECTED:	Transmit data configuration is rejected

final_handle

The handle (identifier) of the transmit frame that is complete

Value range: 0x00~0xFF

final_tstat

The status of the transmit frame that is complete

CAN_TSTAT_IDLE:	Transmit is in idle state
CAN_TSTAT_ONGOING:	Transmit is ongoing
CAN_TSTAT_LOST_ARBITRATION:	Transmit lost arbitration (retransmission limit is reached)
CAN_TSTAT_TRANSMITTED:	Transmit is complete
CAN_TSTAT_ABORTED:	Transmit is aborted
CAN_TSTAT_DISTURBED:	Transmit is disturbed (retransmission limit is reached)
CAN_TSTAT_REJECTED:	Transmit data configuration is rejected

Example:

```
can_transmit_status_type transmit_status;  
can_transmit_status_get(CAN1, &transmit_status);
```

5.2.20 can_stb_clear function

The table below describes the function can_stb_clear.

Table 69. can_stb_clear function

Name	Description
Function name	can_stb_clear
Function prototype	error_status can_stb_clear(can_type* can_x, can_clear_stb_type clear_type);
Function description	Clear secondary transmit buffer
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	clear_type: clear type
Output parameter	NA
Return value	error_status: clear operation is successful or not
Required preconditions	NA
Called functions	NA

clear_type

clear type

CAN_CLEAR_STB_ONE: Clear one frame of secondary transmit buffer

CAN_CLEAR_STB_ALL: Clear all data of secondary transmit buffer

Example:

```
can_stb_clear(CAN1, CAN_CLEAR_STB_ALL);
```

5.2.21 can_rxbuf_overflow_mode_set function

The table below describes the function can_rxbuf_overflow_mode_set.

Table 70. can_rxbuf_overflow_mode_set function

Name	Description
Function name	can_rxbuf_overflow_mode_set
Function prototype	void can_rxbuf_overflow_mode_set(can_type* can_x, can_rxbuf_overflow_mode_type rxbuf_overflow_mode);
Function description	Set receive buffer overflow mode
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	rxbuf_overflow_mode: select receive buffer overflow mode
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

rxbuf_overflow_mode

Select receive buffer overflow mode

CAN_RXBUF_OVERFLOW_BE_OVERWRITTEN: the oldest frame will be overwritten

CAN_RXBUF_OVERFLOW_BE_LOSE: the new frame is not restored

Example:

```
can_rdbuf_overflow_mode_set(CAN1,CAN_RXBUF_OVERFLOW_BE_LOSE);
```

5.2.22 can_receive_all_enable function

The table below describes the function can_receive_all_enable.

Table 71. can_receive_all_enable function

Name	Description
Function name	can_receive_all_enable
Function prototype	void can_receive_all_enable(can_type* can_x, confirm_state new_state);
Function description	Enable receive all data (including error data)
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	new_state: enable or disable This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
can_receive_all_enable(CAN1, TRUE);
```

5.2.23 can_rdbuf_read function

The table below describes the function can_rdbuf_read.

Table 72. can_rdbuf_read function

Name	Description
Function name	can_rdbuf_read
Function prototype	error_status can_rdbuf_read(can_type* can_x, can_rdbuf_type* can_rdbuf_struct);
Function description	Read receive buffer
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	can_rdbuf_struct: data to read, see the pointer of the can_rdbuf_type
Output parameter	NA
Return value	error_status: operation is successful or not
Required preconditions	NA
Called functions	NA

can_rdbuf_type is defined in the AT32F422_426_can.h:

```
typedef struct
{
    uint32_t id;
    can_identifier_type id_type;
    can_frame_type frame_type;
```

```
    can_data_length_type      data_length;
#endif SUPPORT_CAN_FD
    can_format_type          fd_format;
    can_rate_switch_type     fd_rate_switch;
    can_error_state_type     fd_error_state;
    uint8_t  data[64];
#else
    uint8_t  data[8];
#endif
    can_recv_frame_type      recv_frame;
    can_error_type           kind_error;
    uint32_t  rx_timestamp;
    uint16_t  cycle_time;
} can_rdbuf_type;
```

id

Standard identifier (11 bits) or extended identifier (29 bits)

Value range: 0x000~0x7FF or 0x000~0x1FFFFFF

id_type

Identifier type

CAN_ID_STANDARD: Standard identifier

CAN_ID_EXTENDED: Extended identifier

frame_type

Frame type

CAN_FRAME_DATA: Data frame

CAN_FRAME_REMOTE: Remote frame

fd_format

Frame format

CAN_FORMAT_CLASSIC: Classic CAN2.0A/B

CAN_FORMAT_FD: CAN-FD

fd_rate_switch

Baud rate switch type

CAN_BRS_OFF: Baud rate switch OFF

CAN_BRS_ON: Baud rate switch ON

data_length

Data field length

CAN_DLC_BYTES_0: 0 byte

.....

CAN_DLC_BYTES_8: 8 bytes

CAN_DLC_BYTES_12: 12 bytes (for CAN-FD only)

CAN_DLC_BYTES_16: 16 bytes (for CAN-FD only)

CAN_DLC_BYTES_20: 20 bytes (for CAN-FD only)

CAN_DLC_BYTES_24: 24 bytes (for CAN-FD only)

CAN_DLC_BYTES_32: 32 bytes (for CAN-FD only)

CAN_DLC_BYTES_48: 48 bytes (for CAN-FD only)

CAN_DLC_BYTES_64: 64 bytes (for CAN-FD only)

fd_error_state

Error state

CAN_ESI_ACTIVE:	Active error
CAN_ESI_PASSIVE:	Passive error

kind_error

Error type

CAN_KOER_NOERR:	No error
CAN_KOER_BIT:	Bit error
CAN_KOER_FORM:	Format error
CAN_KOER_STUFF:	Bit stuffing error
CAN_KOER_ACK:	Acknowledge error
CAN_KOER_CRC:	CRC error
CAN_KOER_OTHER:	Other errors

recv_frame

Receive frame type

CAN_RECV_NORMAL	Normal receive frame
CAN_RECV_LOOPBACK	Loopback receive frame

data[64]

Data to write transmit buffer (for CAN-FD only)

Value range: 0x00~0xFF

data[8]

Data to write transmit buffer

Value range: 0x00~0xFF

rx_timestamp

Receive frame timestamp

Value range: depends on the TMR counter

cycle_time

Receive frame cycle time (for TTCAN)

Value range: 0x0000~0xFFFF

Example:

```
can_rdbuf_type can_rdbuf_struct;
while(ERROR != can_rdbuf_read(CAN1, &can_rdbuf_struct))
{
    if(can_rdbuf_struct.id_type == CAN_ID_STANDARD)
        at32_led_toggle(LED2);
    else
        at32_led_toggle(LED3);
    printf("receive timestamp = %u\r\n", can_rdbuf_struct.rx_timestamp);
}
```

5.2.24 can_rdbuf_release function

The table below describes the function can_rdbuf_release.

Table 73. can_rdbuf_release function

Name	Description
Function name	can_rdbuf_release
Function prototype	error_status can_rdbuf_release(can_type* can_x);
Function description	Release one frame data of receive buffer
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Output parameter	NA
Return value	error_status: operation is successful or not
Required preconditions	NA
Called functions	NA

Example:

```
can_rdbuf_release (CAN1);
```

5.2.25 can_rdbuf_status_get function

The table below describes the function can_rdbuf_status_get.

Table 74. can_rdbuf_status_get function

Name	Description
Function name	can_rdbuf_status_get
Function prototype	can_rdbuf_status_type can_rdbuf_status_get(can_type* can_x);
Function description	Get receive buffer status
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Output parameter	NA
Return value	can_rdbuf_status: receive buffer status
Required preconditions	NA
Called functions	NA

can_rdbuf_status

Receive buffer status

CAN_RXBUF_STATUS_EMPTY:	Receive buffer is empty
CAN_RXBUF_STATUS_LESS:	Receive buffer is less than almost full
CAN_RXBUF_STATUS_ALMOST:	Receive buffer is more than or equal to almost full
CAN_RXBUF_STATUS_FULL:	Receive buffer is full
CAN_RXBUF_STATUS_OVERFLOW:	Receive buffer is overflow

Example:

```
can_rdbuf_status_type rdbuf_status;  
rdbuf_status = can_rdbuf_status_get(CAN1);
```

5.2.26 can_filter_default_para_init function

The table below describes the function can_filter_default_para_init.

Table 75. can_filter_default_para_init function

Name	Description
Function name	can_filter_default_para_init
Function prototype	void can_filter_default_para_init(can_filter_config_type* filter_config_struct);
Function description	Set an initial default value for the filter_config_struct
Input parameter 1	filter_config_struct: pointer to the can_filter_config_type
Output parameter	NA
Return value	NA
Required preconditions	It is necessary to define the can_filter_config_type, can_filter_code_type and can_filter_mask_type first before starting.
Called functions	NA

can_filter_config_type is defined in the AT32F422_426_can.h:

```
typedef struct
{
    can_filter_code_type    code_para;
    can_filter_mask_type   mask_para;
} can_filter_config_type;
```

can_filter_code_type is defined in the AT32F422_426_can.h:

```
typedef struct
{
    uint32_t id;
    can_identifier_type id_type;
    can_frame_type frame_type;
    uint8_t data_length;
#endif SUPPORT_CAN_FD
    can_format_type fd_format;
    can_rate_switch_type fd_rate_switch;
    can_error_state_type fd_error_state;
#endif
    can_recv_frame_type recv_frame;
} can_filter_code_type;
```

id

Filter standard identifier (11 bits) or extended identifier (29 bits)

Value range: 0x000~0x7FF or 0x000~0x1FFFFFFF

id_type

Filter identifier type

CAN_ID_STANDARD: Standard identifier

CAN_ID_EXTENDED: Extended identifier

frame_type

Filter frame type

CAN_FRAME_DATA: Data frame

CAN_FRAME_REMOTE: Remote frame
fd_format
Filter format type
CAN_FORMAT_CLASSIC: Classic CAN2.0A/B
CAN_FORMAT_FD: CAN-FD
fd_rate_switch
Baud rate switch on/off
CAN_BRS_OFF: Baud rate switch OFF
CAN_BRS_ON: Baud rate switch ON
data_length
Data field length
Value range: 0x00~0xFF
fd_error_state
Filter error state
CAN_ESI_ACTIVE: Active error
CAN_ESI_PASSIVE: Passive error
recv_frame
Filter receive frame type
CAN_RECV_NORMAL Normal receive frame
CAN_RECV_LOOPBACK Loopback receive frame

can_filter_mask_type is defined in the AT32F422_426_can.h:

```
typedef struct
{
    uint32_t id;
    confirm_state id_type;
    confirm_state frame_type;
    uint8_t data_length;
#ifndef SUPPORT_CAN_FD
    confirm_state fd_format;
    confirm_state fd_rate_switch;
    confirm_state fd_error_state;
#endif
    confirm_state recv_frame;
} can_filter_mask_type;
```

id

Filter mask (standard identifier (11 bits) or extended identifier (29 bits))
Value range: 0x000~0x7FF or 0x000~0x1FFFFFFF (0: filter, 1: ignore)

id_type

Filter identifier mask

FALSE: Filter

TRUE: Ignore

frame_type

Filter frame type mask

FALSE: Filter

TRUE: Ignore

fd_format

Filter format mask

FALSE: Filter

TRUE: Ignore

fd_rate_switch

Baud rate switch type mask

FALSE: Filter

TRUE: Ignore

data_length

Filter data length mask

Value range: 0x00~0xFF (0: Filter, 1: Ignore)

fd_error_state

Filter error state mask

FALSE: Filter

TRUE: Ignore

recv_frame

Filter receive frame type mask

FALSE: Filter

TRUE: Ignore

Example:

```
can_filter_config_type can_filter_struct;
can_filter_default_para_init(&can_filter_struct);
```

5.2.27 can_filter_set function

The table below describes the function can_filter_set.

Table 76. can_filter_set function

Name	Description
Function name	can_filter_set
Function prototype	void can_filter_set(can_type* can_x, can_filter_type filter_number, can_filter_config_type* filter_config_struct);
Function description	Set filter
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	filter_number: filter number
Input parameter 3	filter_config_struct: pointer to the can_filter_config_type
Output parameter	NA
Return value	NA
Required preconditions	1. It is necessary to first define the can_filter_config_type, can_filter_code_type and can_filter_mask_type. 2. This function can be configured only when software resets.
Called functions	NA

filter_number

CAN_FILTER_NUM_0: Filter 0

CAN_FILTER_NUM_1: Filter 1
.....
CAN_FILTER_NUM_15: Filter 15

can_filter_config_type is defined in the AT32F422_426_can.h:

```
typedef struct
{
    can_filter_code_type    code_para;
    can_filter_mask_type   mask_para;
} can_filter_config_type;
```

can_filter_code_type is defined in the AT32F422_426_can.h:

```
typedef struct
{
    uint32_t id;
    can_identifier_type id_type;
    can_frame_type frame_type;
    uint8_t data_length;
#define SUPPORT_CAN_FD
    can_format_type fd_format;
    can_rate_switch_type fd_rate_switch;
    can_error_state_type fd_error_state;
#endif
    can_recv_frame_type recv_frame;
} can_filter_code_type;
```

id

Standard identifier (11 bits) or extended identifier (29 bits)

Value range: 0x000~0x7FF or 0x000~0x1FFFFFF

id_type

Filter identifier type

CAN_ID_STANDARD: Standard identifier

CAN_ID_EXTENDED: Extended identifier

frame_type

Frame type

CAN_FRAME_DATA: Data frame

CAN_FRAME_REMOTE: Remote frame

fd_format

Frame format

CAN_FORMAT_CLASSIC: Classic CAN2.0A/B

CAN_FORMAT_FD: CAN-FD

fd_rate_switch

Baud rate switch on/off

CAN_BRS_OFF: Baud rate switch OFF

CAN_BRS_ON: Baud rate switch ON

data_length

Filter data length

Value range: 0x00~0xFF

fd_error_state

Filter error state

CAN_ESI_ACTIVE: Active error

CAN_ESI_PASSIVE: Passive error

recv_frame

Filter receive type

CAN_RECV_NORMAL Normal receive frame

CAN_RECV_LOOPBACK Loopback receive frame

can_filter_mask_type is defined in the AT32F422_426_can.h:

typedef struct

{

 uint32_t id;

 confirm_state id_type;

 confirm_state frame_type;

 uint8_t data_length;

#ifdef SUPPORT_CAN_FD

 confirm_state fd_format;

 confirm_state fd_rate_switch;

 confirm_state fd_error_state;

#endif

 confirm_state recv_frame;

} can_filter_mask_type;

id

Filter standard identifier (11 bits) or extended identifier (29 bits)

Value range: 0x000~0x7FF or 0x000~0x1FFFFFF (0: Filter, 1: Ignored)

id_type

Filter identifier mask

FALSE: Filter

TRUE: Ignored

frame_type

Filter frame type mask

FALSE: Filter

TRUE: Ignored

fd_format

Filter format type mask

FALSE: Filter

TRUE: Ignored

fd_rate_switch

Baud rate switch type mask

FALSE: Filter

TRUE: Ignored

data_length

Filter data length mask

Value range: 0x00~0xFF (0: Filter, 1: Ignored)

fd_error_state

Filter error state mask

FALSE: Filter

TRUE: Ignored

recv_frame

Filter receive frame type mask

FALSE: Filter

TRUE: Ignored

Example:

```

can_software_reset(CAN1, TRUE);

/* can filter 0 config */

can_filter_struct.code_para.id = FILTER_CODE_EXT_ID;
can_filter_struct.code_para.id_type = CAN_ID_EXTENDED;
can_filter_struct.mask_para.id = FILTER_MASK_EXT_ID;
can_filter_struct.mask_para.id_type = FALSE;           /* not mask, filter id_type. */
can_filter_struct.mask_para.data_length = 0xF;        /* mask data_length, not filter. */
can_filter_struct.mask_para.frame_type = TRUE;        /* mask frame_type, not filter. */
can_filter_struct.mask_para.fd_error_state = TRUE;    /* mask error_state, not filter. */
can_filter_struct.mask_para.fd_format = TRUE;         /* mask format_type, not filter. */
can_filter_struct.mask_para.fd_rate_switch = TRUE;    /* mask switch_type, not filter. */
can_filter_struct.mask_para.recv_frame = TRUE;        /* mask recv_type, not filter. */
can_filter_set(CAN1, CAN_FILTER_NUM_0, &can_filter_struct);
can_software_reset(CAN1, FALSE);

```

5.2.28 can_filter_enable function

The table below describes the function can_filter_enable.

Table 77. can_filter_enable function

Name	Description
Function name	can_filter_enable
Function prototype	void can_filter_enable(can_type* can_x, can_filter_type filter_number, confirm_state new_state);
Function description	Enable receive filter
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	filter_number: filter number
Input parameter 3	new_state: enable or disable This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

filter_number

CAN_FILTER_NUM_0: Filter 0

CAN_FILTER_NUM_1: Filter 1

 CAN_FILTER_NUM_15: Filter 15

Example:

```
can_filter_enable(CAN1, CAN_FILTER_NUM_0, TRUE);
```

5.2.29 can_arbitration_lost_position_get function

The table below describes the function can_arbitration_lost_position_get.

Table 78. can_arbitration_lost_position_get function

Name	Description
Function name	can_arbitration_lost_position_get
Function prototype	uint8_t can_arbitration_lost_position_get(can_type* can_x);
Function description	Get arbitration lost position
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Output parameter	NA
Return value	Arbitration lost position (the position in the arbitration field) Parameter range:0~31
Required preconditions	NA
Called functions	NA

Example:

```
uint8_t arbitration_lost_position;  

transmit_timestamp = can_arbitration_lost_position_get (CAN1);
```

5.2.30 can_rxbuf_warning_set function

The table below describes the function can_rxbuf_warning_set.

Table 79. can_rxbuf_warning_set function

Name	Description
Function name	can_rxbuf_warning_set
Function prototype	void can_rxbuf_warning_set(can_type* can_x, uint8_t warning_value);
Function description	Set a warning value indicating the receive buffer is almost full
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	warning_value: warning value to indicate that the receive buffer is almost full Value range: 1~6
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
can_rxbuf_warning_set(CAN1, 3);
```

5.2.31 can_error_warning_set function

The table below describes the function can_error_warning_set.

Table 80. can_error_warning_set function

Name	Description
Function name	can_error_warning_set
Function prototype	void can_error_warning_set(can_type* can_x, uint8_t warning_value);
Function description	Set a warning value indicating an error
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	warning_value: error warning value Value range: 0~15 Programmable error warning value = (warning_value + 1)*8.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* programmable error warning limit = (10+1)*8 = 88. */
can_error_warning_set(CAN1, 10);
```

5.2.32 can_kind_error_get function

The table below describes the function can_kind_error_get.

Table 81. can_kind_error_get function

Name	Description
Function name	can_kind_error_get
Function prototype	can_error_type can_kind_error_get(can_type* can_x);
Function description	Get CAN error type
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Output parameter	NA
Return value	error_type: error type
Required preconditions	NA
Called functions	NA

error_type

Error type

CAN_KOER_NOERR:	No error
CAN_KOER_BIT:	Bit error
CAN_KOER_FORM:	Format error
CAN_KOER_STUFF:	Bit stuffing error
CAN_KOER_ACK:	Acknowledge error
CAN_KOER_CRC:	CRC error

CAN_KOER_OTHER: Other errors

Example:

```
/* get the error type */
can_error_type error_type;
error_type = can_kind_error_get(CAN1);
```

5.2.33 can_receive_error_counter_get function

The table below describes the function can_receive_error_counter_get.

Table 82. can_receive_error_counter_get function

Name	Description
Function name	can_receive_error_counter_get
Function prototype	uint8_t can_receive_error_counter_get(can_type* can_x);
Function description	Read CAN receive error counter
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Output parameter	NA
Return value	receive_error_counter: receive error counter Value range: 0x00~0xFF
Required preconditions	NA
Called functions	NA

Example:

```
/* get the receive error counter */
uint8_t receive_error_counter;
receive_error_counter = can_receive_error_counter_get (CAN1);
```

5.2.34 can_transmit_error_counter_get function

The table below describes the function can_transmit_error_counter_get.

Table 83. can_transmit_error_counter_get function

Name	Description
Function name	can_transmit_error_counter_get
Function prototype	uint8_t can_transmit_error_counter_get(can_type* can_x);
Function description	Read CAN transmit error counter
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Output parameter	NA
Return value	transmit_error_counter: transmit error counter Value range: 0x00~0xFF
Required preconditions	NA
Called functions	NA

Example:

```
/* get the transmit error counter */
uint8_t transmit_error_counter;
transmit_error_counter = can_transmit_error_counter_get (CAN1);
```

5.2.35 can_busoff_get function

The table below describes the function can_busoff_get.

Table 84. can_busoff_get function

Name	Description
Function name	can_busoff_get
Function prototype	flag_status can_busoff_get(can_type* can_x);
Function description	Get bus off status
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	NA
Output parameter	NA
Return value	flag_status: bus state This parameter can be SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```
/* get bus-off status */
flag_status bit_status = RESET;
bit_status = can_busoff_get (CAN1);
```

5.2.36 can_busoff_reset function

The table below describes the function can_busoff_reset.

Table 85. can_busoff_reset function

Name	Description
Function name	can_busoff_reset
Function prototype	void can_busoff_reset(can_type* can_x);
Function description	Bus-off reset
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* resets the error counters and therefore forces the node to leave the bus off state. */
can_busoff_reset (CAN1);
```

5.2.37 can_ttcanc_ref_message_set function

The table below describes the function can_ttcanc_ref_message_set.

Table 86. can_ttcanc_ref_message_set function

Name	Description
Function name	can_ttcanc_ref_message_set
Function prototype	void can_ttcanc_ref_message_set(can_type* can_x, can_identifier_type id_type, uint32_t id);
Function description	Set TTCAN reference message
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	id_type: identifier type
Input parameter 3	id: standard identifier (11-bit) or extended identifier (29-bit) Parameter range: 0x000~0x7FF or 0x000~0x1FFFFFF
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

id_type

Identifier type

CAN_ID_STANDARD: Standard identifier

CAN_ID_EXTENDED: Extended identifier

Example:

```
/* set the reference message identifier for ttcanc */
can_ttcanc_ref_message_set(CAN1, CAN_ID_EXTENDED, 0x1F543210);
```

5.2.38 can_ttcanc_timer_div_set function

The table below describes the function can_ttcanc_timer_div_set.

Table 87. can_ttcanc_timer_div_set function

Name	Description
Function name	can_ttcanc_timer_div_set
Function prototype	void can_ttcanc_timer_div_set(can_type* can_x, can_ttcanc_timer_div_type div_value);
Function description	Set TTCAN clock division
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	div_value: TTCAN clock division value
Output parameter	NA
Return value	NA
Required preconditions	This function can be called only when the TTCAN is not enabled.
Called functions	NA

div_value

CAN_TTCAN_TIMER_DIV_1:	TTCAN/1
CAN_TTCAN_TIMER_DIV_2:	TTCAN/2
CAN_TTCAN_TIMER_DIV_4:	TTCAN/4
CAN_TTCAN_TIMER_DIV_8:	TTCAN/8

Example:

```
/* 1 tick of the cycle time = 8/ac_baudrate = 8/1M = 8us */
can_ttcancan_timer_div_set(CAN1, CAN_TTCAN_TIMER_DIV_8);
```

5.2.39 can_ttcancan_enable function

The table below describes the function can_ttcancan_enable.

Table 88. can_ttcancan_enable function

Name	Description
Function name	can_ttcancan_enable
Function prototype	void can_ttcancan_enable(can_type* can_x, confirm_state new_state);
Function description	Enable TTCAN
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	new_state: enable or disable This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* ttcancan enabled, timer is running */
can_ttcancan_enable(CAN1, TRUE);
```

5.2.40 can_ttcancan_trigger_type_set function

The table below describes the function can_ttcancan_trigger_type_set,

Table 89. can_stb_transmit_mode_set function

Name	Description
Function name	can_ttcancan_trigger_type_set
Function prototype	void can_ttcancan_trigger_type_set(can_type* can_x, can_ttcancan_trigger_type trigger_type);
Function description	Set TTCAN trigger type
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	trigger_type: TTCAN trigger type
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

trigger_type

TTCAN trigger type

CAN_TTCAN_TRIGGER_IMMEDIATE:	Trigger immediately
CAN_TTCAN_TRIGGER_TIME:	Time trigger
CAN_TTCAN_TRIGGER_SINGLE_TRANSMIT:	Trigger single transmit
CAN_TTCAN_TRIGGER_TRANSMIT_START:	Trigger transmit start
CAN_TTCAN_TRIGGER_TRANSMIT_STOP:	Trigger transmit stop

Example:

```
/* set the time trigger type be single shot transmit trigger */
can_ttcancan_trigger_type_set(CAN1, CAN_TTCAN_TRIGGER_SINGLE_TRANSMIT);
```

5.2.41 can_ttcancan_trigger_set function

The table below describes the function can_ttcancan_trigger_set.

Table 90. can_ttcancan_trigger_set function

Name	Description
Function name	can_ttcancan_trigger_set
Function prototype	void can_ttcancan_trigger_set(can_type* can_x, uint16_t trigger_time);
Function description	Set TTCAN trigger time
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	trigger_time: TTCAN trigger time Parameter range: 0x0000~0xFFFF
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* trigger transmit time = 40000*1 tick = 40000*8us = 320ms */
can_ttcn_trigger_set(CAN1, 40000);
```

5.2.42 can_ttcn_watch_trigger_set function

The table below describes the function can_ttcn_watch_trigger_set.

Table 91. can_ttcn_watch_trigger_set function

Name	Description
Function name	can_ttcn_watch_trigger_set
Function prototype	void can_ttcn_watch_trigger_set(can_type* can_x, uint16_t watch_trigger_time);
Function description	Set TTCAN watch trigger time
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	watch_trigger_time: TTCAN watch trigger time Parameter range: 0x0000~0xFFFF
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* the cycle time for a watch trigger = 8us * 10000 = 80ms */
can_ttcn_watch_trigger_set(CAN1, 10000);
```

5.2.43 can_ttcn_transmit_window_set function

The table below describes the function can_ttcn_transmit_window_set.

Table 92. can_ttcn_transmit_window_set function

Name	Description
Function name	can_ttcn_transmit_window_set
Function prototype	void can_ttcn_transmit_window_set(can_type* can_x, uint8_t window_ticks);
Function description	Set TTCAN transmit enable window (for single transmit trigger type)
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	window_ticks: TTCAN transmit enable window Parameter range: 0~15
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* transmit enable window = (15+1)*1 tick = (15+1)*8us = 128us */
can_ttcn_transmit_window_set(CAN1, 15);
```

5.2.44 can_ttcancan_txbuf_enable function

The table below describes the function can_ttcancan_txbuf_enable.

Table 93. can_ttcancan_txbuf_enable function

Name	Description
Function name	can_ttcancan_txbuf_enable
Function prototype	void can_ttcancan_txbuf_enable(can_type* can_x, confirm_state new_state);
Function description	Enable TTCAN transmit buffer slot mode
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	new_state: enable or disable This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable transmit buffer support for ttcancan mode */
can_ttcancan_txbuf_enable(CAN1, TRUE);
```

5.2.45 can_ttcancan_txbuf_status_set function

The table below describes the function can_ttcancan_txbuf_status_set.

Table 94. can_ttcancan_txbuf_status_set function

Name	Description
Function name	can_ttcancan_txbuf_status_set
Function prototype	void can_ttcancan_txbuf_status_set(can_type* can_x, can_ttcancan_txbuf_type txbuf_number, can_ttcancan_txbuf_status_type status_type);
Function description	Set TTCAN transmit buffer status
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	txbuf_number: TTCAN transmit buffer number
Input parameter 3	status_type: TTCAN transmit buffer status
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

txbuf_number

- CAN_TTCAN_TXBUF_NUM_0: TTCAN transmit buffer 0
- CAN_TTCAN_TXBUF_NUM_1: TTCAN transmit buffer 1
- CAN_TTCAN_TXBUF_NUM_2: TTCAN transmit buffer 2
- CAN_TTCAN_TXBUF_NUM_3: TTCAN transmit buffer 3

status_type

CAN_TTCAN_TXBUF_EMPTY	TTCAN transmit buffer is empty
CAN_TTCAN_TXBUF_FILLED	TTCAN transmit buffer is full

Example:

```
can_ttcancan_txbuff_status_set(CAN1, CAN_TTCAN_TXBUF_NUM_1, CAN_TTCAN_TXBUF_EMPTY);
```

5.2.46 can_ttcancan_txbuff_status_get function

The table below describes the function can_ttcancan_txbuff_status_get.

Table 95. can_ttcancan_txbuff_status_get function

Name	Description
Function name	can_ttcancan_txbuff_status_get
Function prototype	can_ttcancan_txbuff_status_type can_ttcancan_txbuff_status_get(can_type* can_x, can_ttcancan_txbuff_type txbuff_number);
Function description	Get TTCAN transmit buffer status
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	txbuff_number: TTCAN transmit buffer number
Output parameter	NA
Return value	status_type: TTCAN transmit buffer status
Required preconditions	NA
Called functions	NA

txbuff_number

CAN_TTCAN_TXBUF_NUM_0: TTCAN transmit buffer 0

CAN_TTCAN_TXBUF_NUM_1: TTCAN transmit buffer 1

CAN_TTCAN_TXBUF_NUM_2: TTCAN transmit buffer 2

CAN_TTCAN_TXBUF_NUM_3: TTCAN transmit buffer 3

status_type

CAN_TTCAN_TXBUF_EMPTY TTCAN transmit buffer is empty

CAN_TTCAN_TXBUF_FILLED TTCAN transmit buffer is full

Example:

```
if(can_ttcancan_txbuff_status_get(CAN1, CAN_TTCAN_TXBUF_NUM_1) != CAN_TTCAN_TXBUF_FILLED)
{
    /* write the transmission buffer 0 for ttcancan*/
    can_ttcancan_txbuff_write(CAN1, CAN_TTCAN_TXBUF_NUM_1, &can_txbuff_struct);
}
```

5.2.47 can_ttcanc_txbuf_transmit_set function

The table below describes the function can_ttcanc_txbuf_transmit_set.

Table 96. can_ttcanc_txbuf_transmit_set function

Name	Description
Function name	can_ttcanc_txbuf_transmit_set
Function prototype	void can_ttcanc_txbuf_transmit_set(can_type* can_x, can_ttcanc_txbuf_type txbuf_number);
Function description	Get TTCAN transmit buffer status
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	txbuf_number: TTCAN transmit buffer number
Output parameter	NA
Return value	status_type: TTCAN transmit buffer status
Required preconditions	NA
Called functions	NA

txbuf_number

- CAN_TTCAN_TXBUF_NUM_0: TTCAN transmit buffer 0
- CAN_TTCAN_TXBUF_NUM_1: TTCAN transmit buffer 1
- CAN_TTCAN_TXBUF_NUM_2: TTCAN transmit buffer 2
- CAN_TTCAN_TXBUF_NUM_3: TTCAN transmit buffer 3

status_type

- CAN_TTCAN_TXBUF_EMPTY TTCAN transmit buffer is empty
- CAN_TTCAN_TXBUF_FILLED TTCAN transmit buffer is full

Example:

```
if(can_ttcanc_txbuf_status_get(CAN1, CAN_TTCAN_TXBUF_NUM_1) != CAN_TTCAN_TXBUF_FILLED)
{
    /* write the transmission buffer 0 for ttcanc*/
    can_ttcanc_txbuf_write(CAN1, CAN_TTCAN_TXBUF_NUM_1, &can_txbuf_struct);
}
```

5.2.48 can_ttcanc_txbuf_write function

The table below describes the function can_ttcanc_txbuf_write.

Table 97. can_ttcanc_txbuf_write function

Name	Description
Function name	can_ttcanc_txbuf_write
Function prototype	error_status can_ttcanc_txbuf_write(can_type* can_x, can_ttcanc_txbuf_type txbuf_number, can_txbuf_type* can_txbuf_struct);
Function description	Write TTCAN transmit buffer
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	txbuf_number: TTCAN transmit buffer number
Input parameter 3	can_txbuf_struct: data to write, referto the pointer of the can_txbuf_type
Output parameter	NA
Return value	error_status: write operation is successful or not
Required preconditions	NA
Called functions	NA

txbuf_number

CAN_TTCAN_TXBUF_NUM_0: TTCAN transmit buffer 0
 CAN_TTCAN_TXBUF_NUM_1: TTCAN transmit buffer 1
 CAN_TTCAN_TXBUF_NUM_2: TTCAN transmit buffer 2
 CAN_TTCAN_TXBUF_NUM_3: TTCAN transmit buffer 3

can_txbuf_type is defined in the AT32F422_426_can.h:

```
typedef struct
{
    uint32_t id;
    can_identifier_type id_type;
    can_frame_type frame_type;
#define SUPPORT_CAN_FD
    can_format_type fd_format;
    can_rate_switch_type fd_rate_switch;
    uint8_t data[64];
#else
    uint8_t data[8];
#endif
    confirm_state tx_timestamp;
    uint8_t handle;
} can_txbuf_type;
```

id

Standard identifier (11 bits) or extended identifier (29 bits)

Value range: 0x000~0x7FF or 0x000~0x1FFFFFF

id_type

Identifier type

CAN_ID_STANDARD: Standard identifier

CAN_ID_EXTENDED: Extended identifier

frame_type

Frame type

CAN_FRAME_DATA: Data frame

CAN_FRAME_REMOTE: Remote frame

fd_format

Format type

CAN_FORMAT_CLASSIC: Classic CAN2.0A/B

CAN_FORMAT_FD: CAN-FD

fd_rate_switch

Baud rate switch type

CAN_BRS_OFF: Baud rate switch OFF

CAN_BRS_ON: Baud rate switch ON

tx_timestamp

Enable or disable transmit timestamp

FALSE: Disable transmit timestamp

TRUE: Enable transmit timestamp

data_length

Data field length

CAN_DLC_BYTES_0: 0 byte

.....

CAN_DLC_BYTES_8: 8 bytes

CAN_DLC_BYTES_12: 12 bytes (for CAN-FD only)

CAN_DLC_BYTES_16: 16 bytes (for CAN-FD only)

CAN_DLC_BYTES_20: 20 bytes (for CAN-FD only)

CAN_DLC_BYTES_24: 24 bytes (for CAN-FD only)

CAN_DLC_BYTES_32: 32 bytes (for CAN-FD only)

CAN_DLC_BYTES_48: 48 bytes (for CAN-FD only)

CAN_DLC_BYTES_64: 64 bytes (for CAN-FD only)

data[64]

Data to write transmit buffer (for CAN-FD only)

Value range: 0x00~0xFF

data[8]

Data to write transmit buffer

Value range: 0x00~0xFF

handle

Handle that is used to identify frames.

Value range: 0x00~0xFF

Example:

```
can_txbuf_type can_txbuf_struct;
can_txbuf_struct.id = 0x400;
can_txbuf_struct.id_type = CAN_ID_STANDARD;
can_txbuf_struct.frame_type = CAN_FRAME_DATA;
can_txbuf_struct.format_type = CAN_FORMAT_FD;
can_txbuf_struct.switch_type = CAN_BRS_ON;
```

```

can_txbuf_struct.data_length = CAN_DLC_BYTES_8;
can_txbuf_struct.data[0] = 0x00;
can_txbuf_struct.data[1] = 0x11;
can_txbuf_struct.data[2] = 0x22;
can_txbuf_struct.data[3] = 0x33;
can_txbuf_struct.data[4] = 0x44;
can_txbuf_struct.data[5] = 0x55;
can_txbuf_struct.data[6] = 0x66;
can_txbuf_struct.data[7] = 0x77;
if(can_ttcancan_txbuf_status_get(CAN1, CAN_TTCAN_TXBUF_NUM_1) != CAN_TTCAN_TXBUF_FILLED)
{
    /* write the transmission buffer 0 for ttcancan*/
    can_ttcancan_txbuf_write(CAN1, CAN_TTCAN_TXBUF_NUM_1, &can_txbuf_struct);
}

```

5.2.49 can_interrupt_enable function

The table below describes the function can_interrupt_enable.

Table 98. can_interrupt_enable function

Name	Description
Function name	can_interrupt_enable
Function prototype	void can_interrupt_enable(can_type* can_x, uint32_t can_int, confirm_state new_state);
Function description	Enable the selected CAN interrupt
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	can_int: the selected CAN interrupt
Input parameter 3	new_state: Enable or disable This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

can_int

CAN interrupt selection includes:

- CAN_AIE_INT: Abort transmit interrupt enable
- CAN_EIE_INT: Error interrupt enable (including error warning and disconnection)
- CAN_TSIE_INT: Secondary transmit buffer transmit complete interrupt enable
- CAN_TPIE_INT: Primary transmit buffer transmit complete interrupt enable
- CAN_RAFIE_INT: Receive buffer almost full interrupt enable
- CAN_RFIE_INT: Receive buffer full interrupt enable
- CAN_ROIE_INT: Receive buffer overflow interrupt enable
- CAN_RIE_INT: Receive interrupt enable
- CAN_BEIE_INT: Bus error interrupt enable
- CAN_ALIE_INT: Arbitration lost interrupt enable

- CAN_EPIE_INT: Error passive interrupt enable
- CAN_TTIE_INT: Time-triggered interrupt enable
- CAN_TEIE_INT: Trigger error interrupt enable
- CAN_WTIE_INT: Window trigger interrupt enable

Example:

```
/* can interrupt config */
nvic_irq_enable(CAN1_TX_IRQn, 0x00, 0x00);
nvic_irq_enable(CAN1_RX_IRQn, 0x00, 0x00);
nvic_irq_enable(CAN1_ERR_IRQn, 0x00, 0x00);
nvic_irq_enable(CAN1_STAT_IRQn, 0x00, 0x00);
can_interrupt_enable(CAN1, CAN_TSIE_INT, TRUE);
can_interrupt_enable(CAN1, CAN_RIE_INT, TRUE);
can_interrupt_enable(CAN1, CAN_TEIE_INT|CAN_TTIE_INT|CAN_WTIE_INT, TRUE);
can_interrupt_enable(CAN1, CAN_BEIE_INT, TRUE);
```

5.2.50 can_flag_get function

The table below describes the function can_flag_get.

Table 99. can_flag_get function

Name	Description
Function name	can_flag_get
Function prototype	flag_status can_flag_get(can_type* can_x, uint32_t can_flag);
Function description	Get the status of the selected CAN flag
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	can_flag: indicates the selected flag Refer to the "can_flag" description below for details
Output parameter	NA
Return value	flag_status: SET or RESET.
Required preconditions	NA
Called functions	NA

can_flag

This is used to select a flag and get its status, including:

- CAN_AIF_FLAG: Aborted transmit interrupt flag
- CAN{EIF}_FLAG: Error interrupt flag
- CAN_TSIF_FLAG: Secondary transmit buffer transmit complete interrupt flag
- CAN_TPIF_FLAG: Primary transmit buffer transmit complete interrupt flag
- CAN_RAFIF_FLAG: Receive buffer almost full interrupt flag
- CAN_RFIF_FLAG: Receive buffer full interrupt flag
- CAN_ROIF_FLAG: Receive buffer overflow interrupt flag
- CAN_RIF_FLAG: Receive interrupt flag
- CAN_BEIF_FLAG: Bus error interrupt flag
- CAN_ALIF_FLAG: Arbitration lost interrupt flag
- CAN_EPIF_FLAG: Error passive interrupt flag

CAN_TTIF_FLAG:	Time-triggered interrupt flag
CAN_TEIF_FLAG:	Trigger error interrupt flag
CAN_WTIF_FLAG:	Window trigger interrupt flag
CAN_EPASS_FLAG:	Error passive status flag
CAN_EWARN_FLAG:	Error warning flag

Example:

```
/* transmit the primary transmit buffer */
can_txbuf_transmit(CAN1, CAN_TRANSMIT_PTB);
/* wait transmit be completed */
while(can_flag_get(CAN1, CAN_TPIF_FLAG) != SET);
can_flag_clear(CAN1, CAN_TPIF_FLAG);
```

5.2.51 can_interrupt_flag_get function

The table below describes the function can_interrupt_flag_get.

Table 100. can_interrupt_flag_get function

Name	Description
Function name	can_interrupt_flag_get
Function prototype	flag_status can_interrupt_flag_get(can_type* can_x, uint32_t can_flag);
Function description	Get CAN interrupt flag status
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	can_flag: indicates the selected flag. Refer to “can_flag” below for details.
Output parameter	NA
Return value	flag_status: SET or RESET
Required preconditions	NA
Called functions	NA

can_flag

This is used to clear the selected flag, including:

CAN_AIF_FLAG:	Aborted transmit interrupt flag
CAN{EIF}_FLAG:	Error interrupt flag
CAN_TSIF_FLAG:	Secondary transmit buffer transmit complete interrupt flag
CAN_TPIF_FLAG:	Primary transmit buffer transmit complete interrupt flag
CAN_RAFIF_FLAG:	Receive buffer almost full interrupt flag
CAN_RFIF_FLAG:	Receive buffer full interrupt flag
CAN_ROIF_FLAG:	Receive buffer overflow interrupt flag
CAN_RIF_FLAG:	Receive interrupt flag
CAN_BEIF_FLAG:	Bus error interrupt flag
CAN_ALIF_FLAG:	Arbitration lost interrupt flag
CAN_EPIF_FLAG:	Error passive interrupt flag
CAN_TTIF_FLAG:	Time-triggered interrupt flag
CAN_TEIF_FLAG:	Trigger error interrupt flag
CAN_WTIF_FLAG:	Window trigger interrupt flag

Example:

```
can_rdbuf_type can_rdbuf_struct;
/* rx_buffer had data be received */
if(can_interrupt_flag_get(CAN1, CAN_RIF_FLAG) != RESET)
{
    can_flag_clear(CAN1, CAN_RIF_FLAG);
    while(ERROR != can_rdbuf_read(CAN1, &can_rdbuf_struct))
    {
    }
}
```

5.2.52 can_flag_clear function

The table below describes the function can_flag_clear.

Table 101. can_flag_clear function

Name	Description
Function name	can_flag_clear
Function prototype	void can_flag_clear(can_type* can_x, uint32_t can_flag);
Function description	Clear the selected CAN flag
Input parameter 1	can_x: indicates the selected CAN This parameter can be CAN1.
Input parameter 2	can_flag: indicates the selected flag. Refer to "can_flag" below for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

can_flag

This is used to clear the selected flag, including:

CAN_AIF_FLAG:	Aborted transmit interrupt flag
CAN{EIF}_FLAG:	Error interrupt flag
CAN_TSIF_FLAG:	Secondary transmit buffer transmit complete interrupt flag
CAN_TPIF_FLAG:	Primary transmit buffer transmit complete interrupt flag
CAN_RAFIF_FLAG:	Receive buffer almost full interrupt flag
CAN_RFIF_FLAG:	Receive buffer full interrupt flag
CAN_ROIF_FLAG:	Receive buffer overflow interrupt flag
CAN_RIF_FLAG:	Receive interrupt flag
CAN_BEIF_FLAG:	Bus error interrupt flag
CAN_ALIF_FLAG:	Arbitration lost interrupt flag
CAN_EPIF_FLAG:	Error passive interrupt flag
CAN_TTIF_FLAG:	Time-triggered interrupt flag
CAN_TEIF_FLAG:	Trigger error interrupt flag
CAN_WTIF_FLAG:	Window trigger interrupt flag

Example:

```
/* clear receive flag */
can_flag_clear(CAN1, CAN_RIF_FLAG);
```

5.3 CRC calculation unit (CRC)

The CRC register structure `crc_type` is defined in the “`at32f422_426_crc.h`”.

```
/*
 * @brief type define crc register all
 */
typedef struct
{
    ...
} crc_type;
```

The table below gives a list of the CRC registers.

Table 102. Summary of CRC registers

Register	Description
dt	Data register
cdt	Common data register
ctrl	Control register
idt	Initialization register
poly	Polynomial generator register

The table below gives a list of CRC library functions.

Table 103. Summary of CRC library functions

Function name	Description
<code>crc_data_reset</code>	Data register reset
<code>crc_one_word_calculate</code>	Calculate the CRC value using combination of a new 32-bit data and the previous CRC value
<code>crc_block_calculate</code>	Write a data block in order into CRC check and return the calculated result
<code>crc_data_get</code>	Get the currently calculated CRC result
<code>crc_common_data_set</code>	Configure common registers
<code>crc_common_date_get</code>	Get the value of common registers
<code>crc_init_data_set</code>	Set the CRC initialization register
<code>crc_reverse_input_data_set</code>	Set CRC input data bit reverse type
<code>crc_reverse_output_data_set</code>	Set CRC output data reverse type
<code>crc_poly_value_set</code>	Set polynomial value
<code>crc_poly_value_get</code>	Get polynomial value
<code>crc_poly_size_set</code>	Set polynomial valid width
<code>crc_poly_size_get</code>	Get polynomial valid width

5.3.1 crc_data_reset function

The table below describes the function crc_data_reset.

Table 104. crc_data_reset function

Name	Description
Function name	crc_data_reset
Function prototype	void crc_data_reset(void);
Function description	When the data register is reset, the value of the initialization register is added into the data register as an initial value. The default reset value is 0xFFFFFFFF.
Input parameter 1	NA
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* reset crc data register */
crc_data_reset();
```

5.3.2 crc_one_word_calculate function

The table below describes the function crc_one_word_calculate.

Table 105. crc_one_word_calculate function

Name	Description
Function name	crc_one_word_calculate
Function prototype	uint32_t crc_one_word_calculate(uint32_t data);
Function description	Calculate the CRC value using a combination of a new 32-bit data and the previous CRC value.
Input parameter 1	data: input a 32-bit data
Input parameter 2	NA
Output parameter	NA
Return value	uint32_t: return CRC calculation result
Required preconditions	NA
Called functions	NA

Example:

```
/* calculate and return result */
uint32_t data = 0x12345678, result = 0;
result = crc_one_word_calculate (data);
```

5.3.3 crc_block_calculate function

The table below describes the function crc_block_calculate.

Table 106. crc_block_calculate function

Name	Description
Function name	crc_block_calculate
Function prototype	uint32_t crc_block_calculate(uint32_t *pbuffer, uint32_t length);
Function description	Input a data block in sequence to go through CRC calculation and return a result
Input parameter 1	pbuffer: pointer to the data block pending for CRC check
Input parameter 2	length: data block length pending for CRC check, in terms of 32-bit
Output parameter	NA
Return value	uint32_t: return CRC calculation result
Required preconditions	NA
Called functions	NA

Example:

```
/* calculate and return result */
uint32_t pbuffer[2] = {0x12345678, 0x87654321};
uint32_t result = 0;
result = crc_block_calculate (pbuffer, 2);
```

5.3.4 crc_data_get function

The table below describes the function crc_data_get.

Table 107. crc_data_get function

Name	Description
Function name	crc_data_get
Function prototype	uint32_t crc_data_get(void);
Function description	Return the current CRC calculation result
Input parameter 1	NA
Input parameter 2	NA
Output parameter	NA
Return value	uint32_t: return CRC calculation result
Required preconditions	NA
Called functions	NA

Example:

```
/* get result */
uint32_t result = 0;
result = crc_data_get();
```

5.3.5 crc_common_data_set function

The table below describes the function crc_common_data_set.

Table 108. crc_common_data_set function

Name	Description
Function name	crc_common_data_set
Function prototype	void crc_common_data_set(uint8_t cdt_value);
Function description	Configure common data register
Input parameter 1	cdt_value: 8-bit common data that can be used as temporary storage data
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* set common data */  
crc_common_data_set (0x88);
```

5.3.6 crc_common_data_get function

The table below describes the function crc_common_data_get.

Table 109. crc_common_data_get function

Name	Description
Function name	crc_common_data_get
Function prototype	uint8_t crc_common_data_get(void);
Function description	Return the value of the command data register
Input parameter 1	NA
Input parameter 2	NA
Output parameter	NA
Return value	uint8_t: return the value of the previously programmed common data register
Required preconditions	NA
Called functions	NA

Example:

```
/* get common data */  
uint8_t cdt_value = 0;  
cdt_value = crc_common_data_get();
```

5.3.7 crc_init_data_set function

The table below describes the function `crc_init_data_set`.

Table 110. `crc_init_data_set` function

Name	Description
Function name	<code>crc_init_data_set</code>
Function prototype	<code>void crc_init_data_set(uint32_t value);</code>
Function description	Set the value of the CRC initialization register
Input parameter 1	value: the value of the CRC initialization register
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

After the value of the CRC initialization register is programmed, the CRC data register is updated with this value whenever the `crc_data_reset` function is called.

Example:

```
/* set initial data */
uint32_t init_value = 0x11223344;
crc_init_data_set (init_value);
```

5.3.8 crc_reverse_input_data_set function

The table below describes the function `crc_reverse_input_data_set`.

Table 111. `crc_reverse_input_data_set` function

Name	Description
Function name	<code>crc_reverse_input_data_set</code>
Function prototype	<code>void crc_reverse_input_data_set(crc_reverse_input_type value);</code>
Function description	Define the CRC input data bit reverse type
Input parameter 1	value: input data bit reverse type. Refer to “value” below for details.
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

Define the reverse type of input data bit.

`CRC_REVERSE_INPUT_NO_AFFECTE`: No effect

`CRC_REVERSE_INPUT_BY_BYTE`: Byte reverse

`CRC_REVERSE_INPUT_BY_HALFWORD`: Half-word reverse

`CRC_REVERSE_INPUT_BY_WORD`: Word reverse

Example:

```
/* set input data reversing type */
crc_reverse_input_data_set(CRC_REVERSE_INPUT_BY_WORD);
```

5.3.9 crc_reverse_output_data_set function

The table below describes the function crc_reverse_output_data_set.

Table 112. crc_reverse_output_data_set function

Name	Description
Function name	crc_reverse_output_data_set
Function prototype	void crc_reverse_output_data_set(crc_reverse_output_type value);
Function description	Define the CRC output data reverse type
Input parameter 1	value: output data bit reverse type. Refer to “value” below for details.
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

Define the reverse type of output data bit.

CRC_REVERSE_OUTPUT_NO_AFFECTE: No effect

CRC_REVERSE_OUTPUT_DATA: Word reverse

Example:

```
/* set output data reversing type */
crc_reverse_output_data_set(CRC_REVERSE_OUTPUT_DATA);
```

5.3.10 crc_poly_value_set function

The table below describes the function crc_poly_value_set.

Table 113. crc_poly_value_set function

Name	Description
Function name	crc_poly_value_set
Function prototype	void crc_poly_value_set(uint32_t value);
Function description	Set CRC polynomial value
Input parameter 1	value: polynomial value
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* set poly value */
crc_poly_value_set(0x12345671);
```

5.3.11 crc_poly_value_get function

The table below describes the function crc_poly_value_get.

Table 114. crc_poly_value_get function

Name	Description
Function name	crc_poly_value_get
Function prototype	uint32_t crc_poly_value_get(void);
Function description	Get CRC polynomial value
Input parameter 1	NA
Input parameter 2	NA
Output parameter	NA
Return value	uint32_t: return polynomial value
Required preconditions	NA
Called functions	NA

Example:

```
/* get poly value */
uint32_t poly = 0;
poly = crc_poly_value_get();
```

5.3.12 crc_poly_size_set function

The table below describes the function crc_poly_size_set.

Table 115. crc_poly_size_set function

Name	Description
Function name	crc_poly_size_set
Function prototype	void crc_poly_size_set(crc_poly_size_type size);
Function description	Set CRC polynomial valid width
Input parameter 1	size: polynomial valid width
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

size

Define the valid width of polynomial.

- CRC_POLY_SIZE_32B: 32-bit
- CRC_POLY_SIZE_16B: 16-bit
- CRC_POLY_SIZE_8B: 8-bit
- CRC_POLY_SIZE_7B: 7-bit

Example:

```
/* set poly size 32-bit */
crc_poly_size_set(CRC_POLY_SIZE_32B);
```

5.3.13 crc_poly_size_get function

The table below describes the function crc_poly_size_get.

Table 116. crc_poly_size_get function

Name	Description
Function name	crc_poly_size_get
Function prototype	crc_poly_size_type crc_poly_size_get(void);
Function description	Get CRC polynomial valid width
Input parameter 1	NA
Input parameter 2	NA
Output parameter	NA
Return value	crc_poly_size_type: polynomial valid width
Required preconditions	NA
Called functions	NA

crc_poly_size_type

Define the valid width of polynomial.

CRC_POLY_SIZE_32B: 32-bit
CRC_POLY_SIZE_16B: 16-bit
CRC_POLY_SIZE_8B: 8-bit
CRC_POLY_SIZE_7B: 7-bit

Example:

```
/* get poly size */  
crc_poly_size_type size;  
size = crc_poly_size_get();
```

5.4 Clock and reset management (CRM)

The CRM register structure `crm_type` is defined in the “`at32f422_426_crm.h`”.

```
/*
 * @brief type define crm register all
 */
typedef struct
{
    ...
} crm_type;
```

The table below gives a list of the CRM registers.

Table 117. Summary of CRM registers

Register	Description
ctrl	Clock control register
cfg	Clock configuration register
clkint	Clock interrupt register
apb2rst	APB2 peripheral reset register
apb1rst	APB1 peripheral reset register
ahben	AHB peripheral clock enable register
apb2en	APB2 peripheral clock enable register
apb1en	APB1 peripheral clock enable register
bpdc	Battery powered domain control register
ctrlsts	Control/status register
ahbrst	AHB peripheral reset register
pll	PLL configuration register
misc1	Extra register 1
misc2	Extra register 2

The table below gives a list of CRM library functions.

Table 118. Summary of CRM library functions

Function name	Description
crm_reset	Reset clock reset management register and control status
crm_lext_bypass	Configure low-speed external clock bypass
crm_hext_bypass	Configure high-speed external clock bypass
crm_flag_get	Check if the selected flag is set or not
crm_hext_stable_wait	Wait for HEXT to get stable
crm_hick_clock_trimming_set	High speed internal clock trimming
crm_hick_clock_calibration_set	High speed internal clock calibration
crm_periph_clock_enable	Peripheral clock enable
crm_periph_reset	Peripheral reset
crm_periph_sleep_mode_clock_enable	Peripheral clock enable in Sleep mode
crm_clock_source_enable	Clock source enable

crm_flag_clear	Clear flag
crm_ertc_clock_select	ERTC clock source selection
crm_ertc_clock_enable	ERTC clock enable
crm_ahb_div_set	AHB clock division
crm_apb1_div_set	APB1 clock division
crm_apb2_div_set	APB2 clock division
crm_adc_clock_div_set	ADC clock division
crm_clock_failure_detection_enable	Clock failure detection enable
crm_batteryPowered_domain_reset	Battery powered domain reset
crm_pll_config	PLL clock source and frequency multiplication factor
crm_pll_config2	PLL clock source and frequency multiplication factor 2
crm_sysclk_switch	System clock source switch
crm_sysclk_switch_status_get	Get the status of system clock source
crm_clocks_freq_get	Get clock frequency
crm_clock_out_set	Clock source output on clkout pin
crm_interrupt_enable	Interrupt enable
crm_auto_step_mode_enable	Auto step-by-step mode enable
crm_hick_sclk_frequency_select	Set system clock frequency as 8M or 48M when HICK is used as system clock
crm_clkout_div_set	clkout output clock division
crm_pll_parameter_calculate	Calculate PLL parameters automatically

5.4.1 crm_reset function

The table below describes the function crm_reset.

Table 119. crm_reset function

Name	Description
Function name	crm_reset
Function prototype	void crm_reset(void);
Function description	Reset the clock reset management register and control status
Input parameter 1	NA
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

- This function does not change the HICKTRIM[5:0] in the CRM_CTRL register.
- Modifying the function does not reset the CRM_BPDC and CRM_CTRLSTS registers.

Example:

```
/* reset crm */
crm_reset();
```

5.4.2 crm_lext_bypass function

The table below describes the function crm_lext_bypass.

Table 120. crm_lext_bypass function

Name	Description
Function name	crm_lext_bypass
Function prototype	void crm_lext_bypass(confirm_state new_state);
Function description	Configure low-speed external clock bypass
Input parameter 1	new_state: Enable bypass (TRUE), disable bypass (FALSE)
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	The LEXT configuration must be done before being enabled.
Called functions	NA

Example:

```
/* enable lext bypass mode */  
crm_lext_bypass(TRUE);
```

5.4.3 crm_hext_bypass function

The table below describes the function crm_hext_bypass.

Table 121. crm_hext_bypass function

Name	Description
Function name	crm_hext_bypass
Function prototype	void crm_hext_bypass(confirm_state new_state);
Function description	Configure high-speed external clock bypass
Input parameter 1	new_state: Enable bypass (TRUE), disable bypass (FALSE)
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	The HEXT configuration must be done before being enabled.
Called functions	NA

Example:

```
/* enable hext bypass mode */  
crm_hext_bypass(TRUE);
```

5.4.4 crm_flag_get function

The table below describes the function crm_flag_get.

Table 122. crm_flag_get function

Name	Description
Function name	crm_flag_get
Function prototype	flag_status crm_flag_get(uint32_t flag);
Function description	Check if the selected flag has been set.
Input parameter 1	flag: flag selection
Input parameter 2	NA
Output parameter	NA
Return value	flag_status: check the status of the selected flag (SET or RESET).
Required preconditions	NA
Called functions	NA

flag

Select a flag to read, including:

CRM_HICK_STABLE_FLAG:	HICK clock stable flag
CRM_HEXT_STABLE_FLAG:	HEXT clock stable flag
CRM_PLL_STABLE_FLAG:	PLL clock stable flag
CRM_LEXT_STABLE_FLAG:	LEXT clock stable flag
CRM_LICK_STABLE_FLAG:	LICK clock stable flag
CRM_NRST_RESET_FLAG:	NRST pin reset flag
CRM_POR_RESET_FLAG:	Power-on/low voltage reset flag
CRM_SW_RESET_FLAG:	Software reset flag
CRM_WDT_RESET_FLAG:	Watchdog reset flag
CRM_WWDT_RESET_FLAG:	Window watchdog reset flag
CRM_LOWPOWER_RESET_FLAG:	Low-power consumption reset flag
CRM_LICK_READY_INT_FLAG:	LICK clock ready interrupt flag
CRM_LEXT_READY_INT_FLAG:	LEXT clock ready interrupt flag
CRM_HICK_READY_INT_FLAG:	HICK clock ready interrupt flag
CRM_HEXT_READY_INT_FLAG:	HEXT clock ready interrupt flag
CRM_PLL_READY_INT_FLAG:	PLL clock ready interrupt flag
CRM_CLOCK_FAILURE_INT_FLAG:	Clock failure interrupt flag

Example:

```
/* wait till pll is ready */
while(crm_flag_get(CRM_PLL_STABLE_FLAG) != SET)
{
}
```

5.4.5 crm_interrupt_flag_get function

The table below describes the function crm_interrupt_flag_get.

Table 123. crm_interrupt_flag_get function

Name	Description
Function name	crm_interrupt_flag_get
Function prototype	flag_status crm_interrupt_flag_get(uint32_t flag);
Function description	Get interrupt flag status
Input parameter 1	flag: select a flag Refer to the “flag” below for details.
Input parameter 2	NA
Output parameter	NA
Return value	flag_status: check the status of the selected flag (SET or RESET).
Required preconditions	NA
Called functions	NA

flag

Select a flag to read, including:

CRM_LICK_READY_INT_FLAG:	LICK clock ready interrupt flag
CRM_LEXT_READY_INT_FLAG:	LEXT clock ready interrupt flag
CRM_HICK_READY_INT_FLAG:	HICK clock ready interrupt flag
CRM_HEXT_READY_INT_FLAG:	HEXT clock ready interrupt flag
CRM_PLL_READY_INT_FLAG:	PLL clock ready interrupt flag
CRM_CLOCK_FAILURE_INT_FLAG:	Clock failure interrupt flag

Example:

```
/* check pll ready interrupt flag */
if(crm_interrupt_flag_get(CRM_PLL_READY_INT_FLAG) != RESET)
{
}
```

5.4.6 crm_hext_stable_wait function

The table below describes the function crm_hext_stable_wait.

Table 124. crm_hext_stable_wait function

Name	Description
Function name	crm_hext_stable_wait
Function prototype	error_status crm_hext_stable_wait(void);
Function description	Wait for HEXT to activate and become stable
Input parameter 1	NA
Input parameter 2	NA
Output parameter	NA
Return value	error_status: Return the status of HEXT (SUCCESS or ERROR).
Required preconditions	NA
Called functions	NA

Example:

```
/* wait till hext is ready */
```

```

while(crm_hext_stable_wait() == ERROR)
{
}

```

5.4.7 crm_hick_clock_trimming_set function

The table below describes the function crm_hick_clock_trimming_set.

Table 125. crm_hick_clock_trimming_set function

Name	Description
Function name	crm_hick_clock_trimming_set
Function prototype	void crm_hick_clock_trimming_set(uint8_t trim_value);
Function description	Trim HICK clock
Input parameter 1	trim_value: trimming value. Default value is 0x20, configurable range is from 0 to 0x3F.
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```

/* set trimming value */
crm_hick_clock_trimming_set(0x1F);

```

5.4.8 crm_hick_clock_calibration_set function

The table below describes the function crm_hick_clock_calibration_set.

Table 126. crm_hick_clock_calibration_set function

Name	Description
Function name	crm_hick_clock_calibration_set
Function prototype	void crm_hick_clock_calibration_set(uint8_t cali_value);
Function description	Set HICK clock calibration value
Input parameter 1	cali_value: calibration compensation value. The factory gate value is the default value. Its configurable range is from 0 to 0xFF.
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```

/* set trimming value */
crm_hick_clock_trimming_set(0x80);

```

5.4.9 crm_periph_clock_enable function

The table below describes the function crm_periph_clock_enable.

Table 127. crm_periph_clock_enable function

Name	Description
Function name	crm_periph_clock_enable
Function prototype	void crm_periph_clock_enable(crm_periph_clock_type value, confirm_state new_state);
Function description	Enable peripheral clock
Input parameter 1	value: defines peripheral clock type
Input parameter 2	new_state: enabled (TRUE) or disabled (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

It indicates the selected peripheral. The crm_periph_clock_type is defined in the “at32f422_426_crm.h”.

The naming rule of this parameter is: CRM_peripheral name_PERIPH_CLOCK.

CRM_DMA1_PERIPH_CLOCK: DMA1 peripheral clock enable

...

CRM_PWC_PERIPH_CLOCK: PWC peripheral clock enable

Example:

```
/* enable gpioa periph clock */
crm_periph_clock_enable(CRM_GPIOA_PERIPH_CLOCK, TRUE);
```

5.4.10 crm_periph_reset function

The table below describes the function crm_periph_reset.

Table 128. crm_periph_reset function

Name	Description
Function name	crm_periph_reset
Function prototype	void crm_periph_reset(crm_periph_reset_type value, confirm_state new_state);
Function description	Reset peripherals
Input parameter 1	value: Peripheral reset type
Input parameter 2	new_state: TRUE or FALSE
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

It indicates the selected peripheral. The crm_periph_reset_type is defined in the “at32f422_426_crm.h”.

The naming rule of this parameter is: CRM_peripheral name_PERIPH_RESET.

CRM_DMA1_PERIPH_RESET: DMA1 peripheral reset

...

CRM_PWC_PERIPH_RESET: PWC peripheral reset

Example:

```
/* reset gpioa periph */
crm_periph_reset(CRM_GPIOA_PERIPH_RESET, TRUE);
```

5.4.11 `crm_periph_sleep_mode_clock_enable` function

The table below describes the function `crm_periph_sleep_mode_clock_enable`.

Table 129. `crm_periph_sleep_mode_clock_enable` function

Name	Description
Function name	<code>crm_periph_sleep_mode_clock_enable</code>
Function prototype	<code>void crm_periph_sleep_mode_clock_enable(crm_periph_clock_sleepmd_type value, confirm_state new_state);</code>
Function description	Enable peripheral clock in Sleep mode
Input parameter 1	value: indicates peripheral clock type in Sleep mode
Input parameter 2	new_state: enabled (TRUE) or disabled (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

It indicates the selected peripheral. The `crm_periph_clock_sleepmd_type` is defined in the "at32f422_426_crm.h".

The naming rule of this parameter is: CRM_peripheral name _PERIPH_CLOCK_SLEEP_MODE.

CRM_SRAM_PERIPH_RESET: SRAM clock reset in Sleep mode

CRM_FLASH_PERIPH_RESET: FLASH clock reset in Sleep mode

Example:

```
/* disable flash clock when entry sleep mode */
crm_periph_sleep_mode_clock_enable (CRM_FLASH_PERIPH_CLOCK_SLEEP_MODE, FALSE);
```

5.4.12 `crm_clock_source_enable` function

The table below describes the function `crm_clock_source_enable`.

Table 130. `crm_clock_source_enable` function

Name	Description
Function name	<code>crm_clock_source_enable</code>
Function prototype	<code>void crm_clock_source_enable(crm_clock_source_type source, confirm_state new_state);</code>
Function description	Enable clock source
Input parameter 1	source: Clock type
Input parameter 2	new_state: enabled (TRUE) or disabled (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA

Name	Description
Called functions	NA

source

Clock source selection.

CRM_CLOCK_SOURCE_HICK:	HICK
CRM_CLOCK_SOURCE_HEXT:	HEXT
CRM_CLOCK_SOURCE_PLL:	PLL
CRM_CLOCK_SOURCE_LEXT:	LEXT
CRM_CLOCK_SOURCE_LICK:	LICK

Example:

```
/* enable hext */
crm_clock_source_enable(CRM_CLOCK_SOURCE_HEXT, FALSE);
```

5.4.13 crm_flag_clear function

The table below describes the function crm_flag_clear.

Table 131. crm_flag_clear function

Name	Description
Function name	crm_flag_clear
Function prototype	void crm_flag_clear(uint32_t flag);
Function description	Clear the selected flags
Input parameter 1	flag: indicates the flag to clear
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

flag

Select a flag to clear.

CRM_NRST_RESET_FLAG:	NRST pin reset flag
CRM_POR_RESET_FLAG:	Power-on/low voltage reset flag
CRM_SW_RESET_FLAG:	Software reset flag
CRM_WDT_RESET_FLAG:	Watchdog reset flag
CRM_WWDAT_RESET_FLAG:	Window watchdog reset flag
CRM_LOWPOWER_RESET_FLAG:	Low-power reset flag
CRM_ALL_RESET_FLAG:	All reset flags
CRM_LICK_READY_INT_FLAG:	LICK clock ready interrupt flag
CRM_LEXT_READY_INT_FLAG:	LEXT clock ready interrupt flag
CRM_HICK_READY_INT_FLAG:	HICK clock ready interrupt flag
CRM_HEXT_READY_INT_FLAG:	HEXT clock ready interrupt flag
CRM_PLL_READY_INT_FLAG:	PLL clock ready interrupt flag
CRM_CLOCK_FAILURE_INT_FLAG:	Clock failure interrupt flag

Example:

```
/* clear clock failure detection flag */
crm_flag_clear(CRM_CLOCK_FAILURE_INT_FLAG);
```

5.4.14 crm_ertc_clock_select function

The table below describes the function crm_ertc_clock_select.

Table 132. crm_ertc_clock_select function

Name	Description
Function name	crm_ertc_clock_select
Function prototype	void crm_ertc_clock_select(crm_ertc_clock_type value);
Function description	Select ERTC clock source
Input parameter 1	value: indicates ertc clock source type
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

ERTC clock source selection.

CRM_ERTC_CLOCK_NOCLK: No clock source for ERTC

CRM_ERTC_CLOCK_LEXT: LEXT selected as ERTC clock

CRM_ERTC_CLOCK_LICK: LICK selected as ERTC clock

CRM_ERTC_CLOCK_HEXT_DIV: HEXT/128 selected as ERTC clock

Example:

```
/* config lext as ertc clock */
crm_ertc_clock_select(CRM_ERTC_CLOCK_LEXT);
```

5.4.15 crm_ertc_clock_enable function

The table below describes the function crm_ertc_clock_enable.

Table 133. crm_ertc_clock_enable function

Name	Description
Function name	crm_ertc_clock_enable
Function prototype	void crm_ertc_clock_enable(confirm_state new_state);
Function description	Enable ERTC clock
Input parameter 1	new_state: enabled (TRUE) or disabled (FALSE)
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable ertc clock */
crm_ertc_clock_enable (TRUE);
```

5.4.16 crm_ahb_div_set function

The table below describes the function crm_ahb_div_set.

Table 134. crm_ahb_div_set function

Name	Description
Function name	crm_ahb_div_set
Function prototype	void crm_ahb_div_set(crm_ahb_div_type value);
Function description	Configure AHB clock division
Input parameter 1	value: indicates the division factor
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

- CRM_AHB_DIV_1: SCLK/1 used as AHB clock
- CRM_AHB_DIV_2: SCLK/2 used as AHB clock
- CRM_AHB_DIV_4: SCLK/4 used as AHB clock
- CRM_AHB_DIV_8: SCLK/8 used as AHB clock
- CRM_AHB_DIV_16: SCLK/16 used as AHB clock
- CRM_AHB_DIV_64: SCLK/64 used as AHB clock
- CRM_AHB_DIV_128: SCLK/128 used as AHB clock
- CRM_AHB_DIV_256: SCLK/256 used as AHB clock
- CRM_AHB_DIV_512: SCLK/512 used as AHB clock

Example:

```
/* config ahbclk */
crm_ahb_div_set(CRM_AHB_DIV_1);
```

5.4.17 crm_apb1_div_set function

The table below describes the function crm_apb1_div_set.

Table 135. crm_apb1_div_set function

Name	Description
Function name	crm_apb1_div_set
Function prototype	void crm_apb1_div_set(crm_apb1_div_type value);
Function description	Configure APB1 clock division
Input parameter 1	value: indicates the division factor
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

- CRM_APB1_DIV_1: APB1/1 used as APB1 clock
- CRM_APB1_DIV_2: APB1/2 used as APB1 clock

- CRM_APB1_DIV_4: AHB/4 used as APB1 clock
 CRM_APB1_DIV_8: AHB/8 used as APB1 clock
 CRM_APB1_DIV_16: AHB/16 used as APB1 clock

Example:

```
/* config apb1clk */
crm_apb1_div_set(CRM_APB1_DIV_2);
```

5.4.18 crm_apb2_div_set function

The table below describes the function crm_apb2_div_set.

Table 136. crm_apb2_div_set function

Name	Description
Function name	crm_apb2_div_set
Function prototype	void crm_apb2_div_set(crm_apb2_div_type value);
Function description	Configure APB2 clock division
Input parameter 1	value: indicates the division factor
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

- CRM_APB2_DIV_1: AHB/1 used as APB2 clock
 CRM_APB2_DIV_2: AHB/2 used as APB2 clock
 CRM_APB2_DIV_4: AHB/4 used as APB2 clock
 CRM_APB2_DIV_8: AHB/8 used as APB2 clock
 CRM_APB2_DIV_16: AHB/16 used as APB2 clock

Example:

```
/* config apb2clk */
crm_apb2_div_set(CRM_APB2_DIV_2);
```

5.4.19 crm_adc_clock_div_set function

The table below describes the function crm_adc_clock_div_set.

Table 137. crm_adc_clock_div_set function

Name	Description
Function name	crm_adc_clock_div_set
Function prototype	void crm_adc_clock_div_set(crm_adc_div_type div_value);
Function description	Configure ADC clock division
Input parameter 1	div_value: indicate the division factor
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

div_value

CRM_ADC_DIV_2:	APB/2 used as ADC clock
CRM_ADC_DIV_4:	APB/4 used as ADC clock
CRM_ADC_DIV_6:	APB/6 used as ADC clock
CRM_ADC_DIV_8:	APB/8 used as ADC clock
CRM_ADC_DIV_12:	APB/12 used as ADC clock
CRM_ADC_DIV_16:	APB/16 used as ADC clock

Example:

```
/* config adc div 4 */
crm_adc_clock_div_set(CRM_ADC_DIV_4);
```

5.4.20 crm_clock_failure_detection_enable function

The table below describes the function crm_clock_failure_detection_enable.

Table 138. crm_clock_failure_detection_enable function

Name	Description
Function name	crm_clock_failure_detection_enable
Function prototype	void crm_clock_failure_detection_enable(confirm_state new_state);
Function description	Enable clock failure detection
Input parameter 1	new_state: enabled (TRUE) or disabled (FALSE)
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable clock failure detection */
crm_clock_failure_detection_enable(TRUE);
```

5.4.21 crm_batteryPoweredDomainReset function

The table below describes the function crm_batteryPoweredDomainReset.

Table 139. crm_batteryPoweredDomainReset function

Name	Description
Function name	crm_batteryPoweredDomainReset
Function prototype	void crm_batteryPoweredDomainReset(confirm_state new_state);
Function description	Reset battery powered domain
Input parameter 1	new_state: reset (TRUE) or not reset (FALSE)
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

When it comes to resetting battery powered domain, it is usually necessary to reset battery powered domain through TRUE operation and then disable battery powered domain reset through FALSE

operation after the completion of reset.

Example:

```
/* reset battery powered domain */
crm_batteryPoweredDomainReset (TRUE);
```

5.4.22 crm_can_clock_select function

The table below describes the function crm_can_clock_select.

Table 140. crm_can_clock_select function

Name	Description
Function name	crm_can_clock_select
Function prototype	void crm_can_clock_select(crm_can_type can_index, crm_can_clock_source_type value);
Function description	Select CAN clock
Input parameter 1	can_index: selected CAN peripheral
Input parameter 2	value: clock source type
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

can_index

CRM_CAN1: used for CAN1 clock configuration

value

CRM_CAN_CLOCK_SOURCE_HEXT: HEXT used as CAN clock source

CRM_CAN_CLOCK_SOURCE_PLL: PLL used as CAN clock source

CRM_CAN_CLOCK_SOURCE_PCLK: Peripheral bus clock used as CAN clock source

Example:

```
/* select hext as can clock */
crm_can_clock_select ( CRM_CAN1, CRM_CAN_CLOCK_SOURCE_HEXT);
```

5.4.23 crm_can_clock_get function

The table below describes the function crm_can_clock_get.

Table 141. crm_can_clock_get function

Name	Description
Function name	crm_can_clock_get
Function prototype	crm_can_clock_source_type crm_can_clock_get(crm_can_type can_index);
Function description	Get CAN clock
Input parameter 1	can_index: selected CAN peripheral
Input parameter 2	NA
Output parameter	NA
Return value	crm_can_clock_source_type: return the current CAN peripheral clock
Required preconditions	NA
Called functions	NA

can_index

CRM_CAN1: used to get CAN1 clock

Example:

```
/* get can1 clock source */
crm_can_clock_source_type can_clock;
can_clock =.crm_can_clock_get ( CRM_CAN1);
```

5.4.24 crm_pll_config function

The table below describes the function crm_pll_config.

Table 142. crm_pll_config function

Name	Description
Function name	crm_pll_config
Function prototype	void crm_pll_config(crm_pll_clock_source_type clock_source, crm_pll_mult_type mult_value);
Function description	Configure PLL clock source and frequency multiplication factor
Input parameter 1	clock_source: the clock source for PLL frequency multiplication
Input parameter 2	mult_value: frequency multiplication factor
Output parameter	NA
Return value	NA
Required preconditions	PLL clock source must be enabled and stabilized before configuring and enabling PLL.
Called functions	NA

clock_source

CRM_PLL_SOURCE_HICK: HICK is selected as PLL clock source

CRM_PLL_SOURCE_HEXT: HEXT is selected as PLL clock source

CRM_PLL_SOURCE_HEXT_DIV: HEXT is selected as PLL clock source

mult_value

CRM_PLL_MULT_2: PLL input clock *2

CRM_PLL_MULT_3: PLL input clock *3

...

CRM_PLL_MULT_63: PLL input clock *63

CRM_PLL_MULT_64: PLL input clock *64

Example:

```
/* config pll clock resource */
crm_pll_config(CRM_PLL_SOURCE_HEXT_DIV, CRM_PLL_MULT_30);
```

5.4.25 crm_pll_config2 function

The table below describes the function crm_pll_config2.

Table 143. crm_pll_config2 function

Name	Description
Function name	crm_pll_config2
Function prototype	void crm_pll_config2(crm_pll_clock_source_type clock_source, uint16_t pll_ns, uint16_t pll_ms, crm_pll_fr_type pll_fr);
Function description	Configure PLL clock source and frequency multiplication and division factor
Input parameter 1	clock_source: the clock source for PLL frequency multiplication
Input parameter 2	pll_ns: frequency multiplication factor from 31 to 500
Input parameter 3	pll_ms: pre-division frequency factor from 1 to 15
Input parameter 4	pll_fr: the post-division frequency factor
Output parameter	NA
Return value	NA
Required preconditions	PLL clock source must be enabled and stabilized before configuring and enabling PLL.
Called functions	NA

Frequency multiplication formula: $\text{PLLCLK} = \text{PLL input clock} / \text{PLL_MS} * \text{PLL_NS} / \text{PLL_FR}$

Requirements:

$2\text{MHz} \leq \text{PLL input clock} / \text{PLL_MS} \leq 16\text{MHz}$

$500\text{MHz} \leq \text{PLL input clock} / \text{PLL_MS} * \text{PLL_NS} \leq 1000\text{MHz}$

clock_source

CRM_PLL_SOURCE_HICK: HICK is selected as PLL clock source

CRM_PLL_SOURCE_HEXT: HEXT is selected as PLL clock source

CRM_PLL_SOURCE_HEXT_DIV: Divided HEXT is selected as PLL clock source

pll_fr

CRM_PLL_FR_1: PLL/1

CRM_PLL_FR_2: PLL/2

CRM_PLL_FR_4: PLL/4

CRM_PLL_FR_8: PLL/8

CRM_PLL_FR_16: PLL/16

CRM_PLL_FR_32: PLL/32

Example:

```
/* config pll clock resource */
crm_pll_config2(CRM_PLL_SOURCE_HEXT_DIV, 96, 1, CRM_PLL_FR_8);
```

5.4.26 crm_sysclk_switch function

The table below describes the function crm_sysclk_switch.

Table 144. crm_sysclk_switch function

Name	Description
Function name	crm_sysclk_switch
Function prototype	void crm_sysclk_switch(crm_sclk_type value);
Function description	Switch system clock source
Input parameter 1	value: indicates the clock source for system clock
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

CRM_SCLK_HICK: HICK used as system clock

CRM_SCLK_HEXT: HEXT used as system clock

CRM_SCLK_PLL: PLL used as system clock

Example:

```
/* select pll as system clock source */
crm_sysclk_switch(CRM_SCLK_PLL);
```

5.4.27 crm_sysclk_switch_status_get function

The table below describes the function crm_sysclk_switch_status_get.

Table 145. crm_sysclk_switch_status_get function

Name	Description
Function name	crm_sysclk_switch_status_get
Function prototype	crm_sclk_type crm_sysclk_switch_status_get(void);
Function description	Get the clock source of system clock
Input parameter 1	NA
Input parameter 2	NA
Output parameter	NA
Return value	crm_sclk_type: return value is the clock source of system clock
Required preconditions	NA
Called functions	NA

Example:

```
/* wait till pll is used as system clock source */
while(crm_sysclk_switch_status_get() != CRM_SCLK_PLL)
{
}
```

5.4.28 crm_clocks_freq_get function

The table below describes the function crm_clocks_freq_get.

Table 146. crm_clocks_freq_get function

Name	Description
Function name	crm_clocks_freq_get
Function prototype	void crm_clocks_freq_get(crm_clocks_freq_type *clocks_struct);
Function description	Get clock frequency
Input parameter 1	clocks_struct: crm_clocks_freq_type pointer, including clock frequency
Input parameter 2	NA
Output parameter	NA
Return value	crm_sclk_type: return the clock source for system clock
Required preconditions	NA
Called functions	NA

crm_clocks_freq_type

The crm_clocks_freq_type is defined in the “at32f422_426_crm.h”.

typedef struct

```
{
    uint32_t    sclk_freq;
    uint32_t    ahb_freq;
    uint32_t    apb2_freq;
    uint32_t    apb1_freq;
    uint32_t    adc_freq;
}
```

crm_clocks_freq_type;

sclk_freq

Get the system clock frequency, in Hz

ahb_freq

Get the clock frequency of AHB, in Hz

apb2_freq

Get the clock frequency of APB2, in Hz

apb1_freq

Get the clock frequency of APB1, in Hz

adc_freq

Get the clock frequency of ADC, in Hz

Example:

```
/* get frequency */
crm_clocks_freq_type clocks_struct;
crm_clocks_freq_get(&clocks_struct);
```

5.4.29 crm_clock_out_set function

The table below describes the function crm_clock_out_set.

Table 147. crm_clock_out_set function

Name	Description
Function name	crm_clock_out_set
Function prototype	void crm_clock_out_set(crm_clkout_select_type clkout);
Function description	Select clock source output on clkout pin
Input parameter 1	clkout: clock source output on clkout pin
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* config PA8 output pll/4 */
crm_clock_out_set(CRM_CLKOUT_PLL_DIV_4);
```

5.4.30 crm_interrupt_enable function

The table below describes the function crm_interrupt_enable.

Table 148. crm_interrupt_enable function

Name	Description
Function name	crm_interrupt_enable
Function prototype	void crm_interrupt_enable(uint32_t crm_int, confirm_state new_state);
Function description	Enable interrupts
Input parameter 1	crm_int: indicates the selected interrupt
Input parameter 2	new_state: enable (TRUE) or disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

crm_int

CRM_LICK_STABLE_INT:	LICK stable interrupt
CRM_LEXT_STABLE_INT:	LEXT stable interrupt
CRM_HICK_STABLE_INT:	HICK stable interrupt
CRM_HEXT_STABLE_INT:	HEXT stable interrupt
CRM_PLL_STABLE_INT:	PLL stable interrupt
CRM_CLOCK_FAILURE_INT:	Clock failure interrupt

Example:

```
/* enable pll stable interrupt */
crm_interrupt_enable (CRM_PLL_STABLE_INT);
```

5.4.31 crm_auto_step_mode_enable function

The table below describes the function crm_auto_step_mode_enable.

Table 149. crm_auto_step_mode_enable function

Name	Description
Function name	crm_auto_step_mode_enable
Function prototype	void crm_auto_step_mode_enable(confirm_state new_state);
Function description	Enable auto step-by-step mode
Input parameter 1	new_state: enable (TRUE) or disable (FALSE)
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable auto step mode */
crm_auto_step_mode_enable(TRUE);
```

5.4.32 crm_hick_sclk_frequency_select function

The table below describes the function crm_hick_sclk_frequency_select.

Table 150. crm_hick_sclk_frequency_select function

Name	Description
Function name	crm_hick_sclk_frequency_select
Function prototype	void crm_hick_sclk_frequency_select(crm_hick_sclk_frequency_type value);
Function description	Select 8M or 48M system clock frequency when HICK is used as system clock
Input parameter 1	value: 8M or 48M HICK
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

CRM_HICK_SCLK_8MHZ: 8 MHz HICK used as system clock

CRM_HICK_SCLK_48MHZ: 48 MHz HICK used as system clock

Example:

```
/* config sysclk with hick 48mhz */
crm_hick_sclk_frequency_select (CRM_HICK_SCLK_48MHZ);
```

5.4.33 crm_clkout_div_set function

The table below describes the function crm_clkout_div_set.

Table 151. crm_clkout_div_set function

Name	Description
Function name	crm_clkout_div_set
Function prototype	void crm_clkout_div_set(crm_clkout_div_type clkout_div);
Function description	Configure clkout output clock division
Input parameter 1	clkout_div: indicates the clkout output frequency division factor
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

- CRM_CLKOUT_DIV_1: CLKOUT divided by 1
- CRM_CLKOUT_DIV_2: CLKOUT divided by 2
- CRM_CLKOUT_DIV_4: CLKOUT divided by 4
- CRM_CLKOUT_DIV_8: CLKOUT divided by 8
- CRM_CLKOUT_DIV_16: CLKOUT divided by 16
- CRM_CLKOUT_DIV_64: CLKOUT divided by 64
- CRM_CLKOUT_DIV_128: CLKOUT divided by 128
- CRM_CLKOUT_DIV_256: CLKOUT divided by 256
- CRM_CLKOUT_DIV_512: CLKOUT divided by 512

Example:

```
/* config clkout division */
crm_clkout_div_set(CRM_CLKOUT_DIV_1);
```

5.4.34 crm_pll_parameter_calculate function

The table below describes the function crm_pll_parameter_calculate.

Table 152. crm_pll_parameter_calculate function

Name	Description
Function name	crm_pll_parameter_calculate
Function prototype	error_status crm_pll_parameter_calculate(crm_pll_clock_source_type pll_rcs, uint32_t target_sclk_freq, uint16_t *ret_ms, uint16_t *ret_ns, uint16_t *ret_fr);
Function description	PLL parameter auto calculation
Input parameter 1	pll_rcs: pll input clock source
Input parameter 2	target_sclk_freq: target clock frequency multiplication, for example, for 200 MHz, this parameter can be target_sclk_freq=200000000
Output parameter 1	ret_ms: return pll_ms parameter
Output parameter 2	ret_ns: return pll_ns parameter
Output parameter 3	ret_fr: return pll_fr parameter
Return value	error_status: Calculation status. SUCCESS: the calculated result equals the target clock PLL parameter

Name	Description
	ERROR: the calculated result is close to the target clock PLL parameter
Required preconditions	NA
Called functions	NA

Example:

```
/* pll parameter calculate automatic */
uint16_t pll_ms = 0, pll_ns = 0, pll_fr = 0;
crm_pll_parameter_calculate(CRM_PLL_SOURCE_HEXT, 200000000, &pll_ms, &pll_ns, &pll_fr);
```

5.4.35 crm_apb3_div_set function

The table below describes the function crm_apb3_div_set.

Table 153. crm_apb3_div_set function

Name	Description
Function name	crm_apb3_div_set
Function prototype	void crm_apb3_div_set(crm_apb3_div_type value);
Function description	Configure APB3 clock division
Input parameter 1	value: division value
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

- CRM_APB3_DIV_1: AHB/1 used as APB3 clock
- CRM_APB3_DIV_2: AHB/2 used as APB3 clock
- CRM_APB3_DIV_4: AHB/4 used as APB3 clock
- CRM_APB3_DIV_8: AHB/8 used as APB3 clock
- CRM_APB3_DIV_16: AHB/16 used as APB3 clock

Example:

```
/* config apb3clk */
crm_apb3_div_set(CRM_APB3_DIV_2);
```

5.4.36 crm_vbath_div_set function

The table below describes the function crm_vbath_div_set.

Table 154. crm_vbath_div_set function

Name	Description
Function name	crm_vbath_div_set
Function prototype	void crm_vbath_div_set(crm_vbath_div_type value);
Function description	Set clock division from AHB to vbat
Input parameter 1	value: division value
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

CRM_VBATH_DIV_1: AHB/1 used as VBAT clock

CRM_VBATH_DIV_2: AHB/2 used as VBAT clock

CRM_VBATH_DIV_4: AHB/4 used as VBAT clock

Example:

```
/* config vbathclk */
crm_vbath_div_set(CRM_VBATH_DIV_2);
```

5.4.37 crm_lextdrv_set function

The table below describes the function crm_lextdrv_set.

Table 155. crm_lextdrv_set function

Name	Description
Function name	crm_lextdrv_set
Function prototype	void crm_lextdrv_set(crm_drv_strength_type value);
Function description	Set LEXT drive strength
Input parameter 1	value: LEXT drive strength
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

CRM_DRV_STRENGTH_LOW: Low drive strength

CRM_DRV_STRENGTH_MEDIUM_LOW: Medium low drive strength

CRM_DRV_STRENGTH_MEDIUM_HIGH: Medium high drive strength

CRM_DRV_STRENGTH_HIGH: High drive strength

Example:

```
/* config lext high driving strength */
crm_lextdrv_set ( CRM_DRV_STRENGTH_HIGH);
```

5.4.38 crm_hexdrv_set function

The table below describes the function crm_hexdrv_set.

Table 156. crm_hexdrv_set function

Name	Description
Function name	crm_hexdrv_set
Function prototype	void crm_hexdrv_set(crm_drv_strength_type value);
Function description	Set HEXT drive strength
Input parameter 1	value: HEXT drive strength
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

value

CRM_DRV_STRENGTH_LOW:	Low drive strength
CRM_DRV_STRENGTH_MEDIUM_LOW:	Medium low drive strength
CRM_DRV_STRENGTH_MEDIUM_HIGH:	Medium high drive strength
CRM_DRV_STRENGTH_HIGH:	High drive strength

Example:

```
/* config hext high driving strength */
crm_hexdrv_set ( CRM_DRV_STRENGTH_HIGH);
```

5.5 Comparator (CMP)

The CMP register structure cmp_type is defined in the “at32f422_426_cmp.h”.

```
/*
 * @brief type define cmp register all
 */
typedef struct
{

} cmp_type;
```

The table below gives a list of the CMP registers.

Table 157. Summary of CMP registers

Register	Description
ctrlsts	Comparator control and status register
g_filter_en	Glitch filter enable register
high_pulse	Glitch filter high pulse count
low_pulse	Glitch filter low pulse count

The table below gives a list of the CMP library functions.

Table 158. Summary of CMP library functions

Function name	Description
cmp_reset	Reset CMP through CRM reset register
cmp_init	Initialize CMP peripheral
cmp_default_para_init	Initialize CMP default parameters
cmp_enable	Enable/disable CMP
cmp_input_shift_enable	Enable/disable CMP input shift
cmp_output_value_get	Get CMP output value
cmp_write_protect_enable	Enable CMP write protection
cmp_filter_config	Configure CMP glitch filter
cmp_blinking_config	Configure CMP blanking window source
cmp_scal_brg_config	Configure CMP voltage scaling

5.5.1 cmp_reset function

The table below describes the function cmp_reset.

Table 159. cmp_reset function

Name	Description
Function name	cmp_reset
Function prototype	void cmp_reset(void);
Function description	Reset CMP by CRM reset register
Input parameter	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	crm_periph_reset();

Example:

```
cmp_reset();
```

5.5.2 cmp_init function

The table below describes the function cmp_init.

Table 160. cmp_init function

Name	Description
Function name	cmp_init
Function prototype	void cmp_init(cmp_sel_type cmp_sel, cmp_init_type* cmp_init_struct);
Function description	Initialize CMP peripheral
Input parameter 1	cmp_sel: select a comparator to initialize
Input parameter 2	cmp_init_struct: cmp_init_type pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

cmp_sel

Select a comparator for initialization.

CMP1_SELECTION: CMP1

cmp_init_type structure

The cmp_init_type is defined in the “at32f422_426_cmp.h”.

typedef struct

```
{
    cmp_non_inverting_type      cmp_non_inverting;
    cmp_inverting_type          cmp_inverting;
    cmp_speed_type              cmp_speed;
    cmp_output_type              cmp_output;
    cmp_polarity_type           cmp_polarity;
    cmp_hysteresis_type         cmp_hysteresis;
}cmp_init_type;
```

cmp_non_inverting

Set CMP non-inverting input port.

CMP_NON_INVERTING_PA5:	PA5
CMP_NON_INVERTING_PA1:	PA1
CMP_NON_INVERTING_PA0:	PA0
CMP_NON_INVERTING_VSSA:	VSSA

cmp_inverting

Set CMP inverting input port.

CMP_INVERTING_1_4VREFINT:	1/4 VREFINT
CMP_INVERTING_1_2VREFINT:	1/2 VREFINT
CMP_INVERTING_3_4VREFINT:	3/4 VREFINT
CMP_INVERTING_VREFINT:	VREFINT
CMP_INVERTING_PA4:	PA4
CMP_INVERTING_PA5:	PA5
CMP_INVERTING_PA0:	PA0
CMP_INVERTING_PA2:	PA2

cmp_speed

Set CMP speed

CMP_SPEED_FAST:	High-speed/maximum power consumption
CMP_SPEED_MEDIUM:	Medium-speed/medium power consumption
CMP_SPEED_SLOW:	Low-speed/minimum power consumption
CMP_SPEED_ULTRALOW:	Ultra-low speed/ultra-low power consumption

cmp_output

Set CMP output mapping.

CMP_OUTPUT_NONE:	No effect
CMP_OUTPUT_TMR1BRK:	TMR1BRK
CMP_OUTPUT_TMR1CH1:	TMR1CH1
CMP_OUTPUT_TMR1CXORAW_OFF:	TMR1CXORAW_OFF
CMP_OUTPUT_TMR3CH1:	TMR3CH1
CMP_OUTPUT_TMR3CXORAW_OFF:	TMR3CXORAW_OFF

cmp_polarity

Set CMP output polarity.

CMP_POL_NON_INVERTING:	CMP output value is not inverted
CMP_POL_INVERTING:	CMP output value is inverted

cmp_hysteresis

Set CMP hysteresis mode

CMP_HYSTERESIS_NONE:	No hysteresis
CMP_HYSTERESIS_LOW:	Low hysteresis
CMP_HYSTERESIS_MEDIUM:	Medium hysteresis
CMP_HYSTERESIS_HIGH:	High hysteresis

Example:

```
cmp_init_type cmp_init_struct;
cmp_init_struct.cmp_non_inverting = CMP_NON_INVERTING_PA1;
cmp_init_struct.cmp_inverting = CMP_INVERTING_1_4VREFINT;
cmp_init_struct.cmp_output = CMP_OUTPUT_TMR1CH1;
cmp_init_struct.cmp_polarity = CMP_POL_NON_INVERTING;
```

```
cmp_init_struct.cmp_speed = CMP_SPEED_FAST;  
cmp_init_struct.cmp_hysteresis = CMP_HYSTESIS_NONE;  
cmp_init(CMP1_SELECTION, &cmp_init_struct);
```

5.5.3 cmp_default_para_init function

The table below describes the function cmp_default_para_init.

Table 161. cmp_default_para_init function

Name	Description
Function name	cmp_default_para_init
Function prototype	void cmp_default_para_init(cmp_init_type *cmp_init_struct);
Function description	Initialize CMP default parameters
Input parameter	cmp_init_type: cmp_init_type pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

The table below describes the default values of the members of the cmp_init_type.

Table 162. cmp_init_type default values

Member	Default value
cmp_non_inverting	CMP_NON_INVERTING_PA1
cmp_inverting	CMP_INVERTING_1_4VREFINT
cmp_speed	CMP_SPEED_FAST
cmp_output	CMP_OUTPUT_NONE
cmp_polarity	CMP_POL_NON_INVERTING
cmp_hysteresis	CMP_HYSTESIS_NONE

Example:

```
cmp_init_type cmp_init_struct;  
cmp_default_para_init(&cmp_init_struct);
```

5.5.4 cmp_enable function

The table below describes the function cmp_enable.

Table 163. cmp_enable function

Name	Description
Function name	cmp_enable
Function prototype	void cmp_enable(cmp_sel_type cmp_sel, confirm_state new_state);
Function description	Enable/disable CMP
Input parameter 1	cmp_sel: select a comparator. Refer to cmp_sel for details.
Input parameter 2	new_state: indicates the status of the selected comparator; enable (TRUE) or disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
cmp_enable(CMP1_SELECTION, TRUE);
```

5.5.5 cmp_input_shift_enable function

The table below describes the function cmp_input_shift_enable.

Table 164. cmp_input_shift_enable function

Name	Description
Function name	cmp_input_shift_enable
Function prototype	void cmp_input_shift_enable(confirm_state new_state);
Function description	Enable/disable CMP input shift
Input parameter	new_state: indicates the status of the CMP input shift, enable (TRUE) or disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
cmp_input_shift_enable(TRUE);
```

5.5.6 cmp_output_value_get function

The table below describes the function cmp_output_value_get.

Table 165. cmp_output_value_get function

Name	Description
Function name	cmp_output_value_get
Function prototype	uint32_t cmp_output_value_get(cmp_sel_type cmp_sel);
Function description	Get CMP output value
Input parameter	cmp_sel: select a comparator; refer to cmp_sel for details.
Output parameter	NA
Return value	Return CMP output value
Required preconditions	NA
Called functions	NA

Example:

```
uint32_t cmp_value;  
cmp_value = cmp_output_value_get(CMP1_SELECTION);
```

5.5.7 cmp_write_protect_enable function

The table below describes the function cmp_write_protect_enable.

Table 166. cmp_write_protect_enable function

Name	Description
Function name	cmp_write_protect_enable
Function prototype	void cmp_write_protect_enable(cmp_sel_type cmp_sel);
Function description	Enable CMP write protection
Input parameter	cmp_sel: select a comparator, refer to cmp_sel for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
cmp_write_protect_enable(CMP1_SELECTION);
```

5.5.8 cmp_filter_config function

The table below describes the function cmp_filter_config.

Table 167. cmp_filter_config function

Name	Description
Function name	cmp_filter_config
Function prototype	void cmp_filter_config(uint16_t high_pulse_cnt, uint16_t low_pulse_cnt, confirm_state new_state);
Function description	Configure CMP glitch filter
Input parameter 1	high_pulse_cnt: glitch filter high pulse count from 0x00 to 0x3F
Input parameter 2	low_pulse_cnt: glitch filter low pulse count from 0x00 to 0x3F
Input parameter 3	new_state: indicates the status of CMP glitch filter Enable (TRUE) or disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
cmp_filter_config(0x3F, 0x3F, TRUE);
```

5.5.9 cmp_blanketing_config function

The table below describes the function cmp_blanketing_config.

Table 168. cmp_blanketing_config function

Name	Description
Function name	cmp_blanketing_config
Function prototype	void cmp_blanketing_config(cmp_blanketing_type blank_sel);
Function description	Configure CMP blanking source
Input parameter	blank_sel: blanking source selection
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

blank_sel

Blanking source selection.

- | | |
|-------------------------|-----------|
| CMP_BLANKING_NONE: | No effect |
| CMP_BLANKING_TMR1_CH4: | TMR1 CH4 |
| CMP_BLANKING_TMR3_CH3: | TMR3 CH3 |
| CMP_BLANKING_TMR15_CH2: | TMR15 CH2 |
| CMP_BLANKING_TMR15_CH1: | TMR15 CH1 |
| CMP_BLANKING_TMR4_CH4: | TMR4 CH4 |

Example:

```
cmp_blanketing_config(CMP_BLANKING_TMR1_CH4);
```

5.5.10 cmp_scal_brg_config function

The table below describes the function cmp_scal_brg_config.

Table 169. cmp_scal_brg_config function

Name	Description
Function name	cmp_scal_brg_config
Function prototype	void cmp_scal_brg_config(uint32_t scal_brg);
Function description	Enable CMP voltage bridge
Input parameter	scal_brg: voltage bridge selection
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

blank_sel

Enable voltage bridge.

CMP_SCAL_BRG_00: vrefint = 3/4 vrefint = 1/2 vrefint = 1/4 vrefint = 0v

CMP_SCAL_BRG_10: vrefint = 3/4 vrefint = 1/2 vrefint = 1/4 vrefint = 1.2v

CMP_SCAL_BRG_11: vrefint = 1.2v, 3/4 vrefint = 0.9v, 1/2 vrefint = 0.6v, 1/4 vrefint = 0.3v

Example:

```
cmp_scal_brg_config(CMP_SCAL_BRG_11);
```

5.6 Debug

The DEBUG register structure debug_type is defined in the “at32f422_426_debug.h”.

```
/*
 * @brief type define debug register all
 */
typedef struct
{
    ...
} debug_type;
```

The table below gives a list of the DEBUG registers.

Table 170. Summary of DEBUG registers

Register	Description
idcode	Device ID
ctrl	Control register

The table below gives a list of DEBUG library functions.

Table 171. Summary of DEBUG library functions

Function name	Description
debug_device_id_get	Read device idcode
debug_periph_mode_set	Peripheral debug mode configuration

5.6.1 debug_device_id_get function

The table below describes the function debug_device_id_get.

Table 172. debug_device_id_get function

Name	Description
Function name	debug_device_id_get
Function prototype	uint32_t debug_device_id_get(void);
Function description	Read device idcode
Input parameter 1	NA
Input parameter 2	NA
Output parameter	NA
Return value	Return 32-bit idcode
Required preconditions	NA
Called functions	NA

Example:

```
/* get idcode */
uint32_t idcode = 0;
idcode = debug_device_id_get();
```

5.6.2 debug_periph_mode_set function

The table below describes the function debug_periph_mode_set.

Table 173. debug_periph_mode_set function

Name	Description
Function name	debug_periph_mode_set
Function prototype	void debug_periph_mode_set(uint32_t periph_debug_mode, confirm_state new_state);
Function description	Set debug mode for the selected peripheral or mode
Input parameter 1	periph_debug_mode: select a peripheral or mode
Input parameter 2	new_state: enable (TRUE) or disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

periph_debug_mode

Set debug mode for the selected peripheral or mode.

DEBUG_SLEEP:	DEBUG in SLEEP mode
DEBUG_DEEPSLEEP:	DEBUG in DEEPSLEEP mode
DEBUG_STANDBY:	DEBUG in STANDBY mode
DEBUG_WDT_PAUSE:	Watchdog pause control bit
DEBUG_WWDT_PAUSE:	Window watchdog pause control bit
DEBUG_TMR1_PAUSE:	TMR1 pause control bit
DEBUG_TMR3_PAUSE:	TMR3 pause control bit
DEBUG_TMR6_PAUSE:	TMR6 pause control bit
DEBUG_TMR4_PAUSE:	TMR4 pause control bit
DEBUG_TMR15_PAUSE:	TMR15 pause control bit
DEBUG_TMR16_PAUSE:	TMR16 pause control bit
DEBUG_TMR17_PAUSE:	TMR17 pause control bit
DEBUG_I2C1_SMBUS_TIMEOUT:	I ² C1 SMBUS TIMEOUT pause control bit
DEBUG_I2C2_SMBUS_TIMEOUT:	I ² C2 SMBUS TIMEOUT pause control bit
DEBUG_ERTC_PAUSE:	ERTC pause control bit
DEBUG_ERTC_512_PAUSE:	ERTC 512Hz pulse output pause control bit

Example:

```
/* enable tmr1 debug mode */
debug_periph_mode_set(DEBUG_TMR1_PAUSE, TRUE);
```

5.7 DMA controller

The DMA register structure dma_type is defined in the “at32f422_426_dma.h”.

```
/*
 * @brief type define dma register
 */
typedef struct
{
    ...
}
```

} dma_type;

DMA channel register structure dma_channel_type is defined in the “at32f422_426_dma.h”.

```
/*
 * @brief type define dma channel register all
 */
typedef struct
{
    ...
}
```

} dma_channel_type;

The table below gives a list of the DMA registers.

Table 174. Summary of DMA registers

Register	Description
dma_sts	DMA status register
dma_clr	DMA status clear register
dma_c1ctrl	DMA channel 1 configuration register
dma_c1dtcnt	DMA channel 1 number of data register
dma_c1paddr	DMA channel 1 peripheral address register
dma_c1maddr	DMA channel 1 memory address register
dma_c2ctrl	DMA channel 2 configuration register
dma_c2dtcnt	DMA channel 2 number of data register
dma_c2paddr	DMA channel 2 peripheral address register
dma_c2maddr	DMA channel 2 memory address register
dma_c3ctrl	DMA channel 3 configuration register
dma_c3dtcnt	DMA channel 3 number of data register
dma_c3paddr	DMA channel 3 peripheral address register
dma_c3maddr	DMA channel 3 memory address register
dma_c4ctrl	DMA channel 4 configuration register
dma_c4dtcnt	DMA channel 4 number of data register
dma_c4paddr	DMA channel 4 peripheral address register
dma_c4maddr	DMA channel 4 memory address register
dma_c5ctrl	DMA channel 5 configuration register
dma_c5dtcnt	DMA channel 5 number of data register

Register	Description
dma_c5paddr	DMA channel 5 peripheral address register
dma_c5maddr	DMA channel 5 memory address register
dma_c6ctrl	DMA channel 6 configuration register
dma_c6dtcnt	DMA channel 6 number of data register
dma_c6paddr	DMA channel 6 peripheral address register
dma_c6maddr	DMA channel 6 memory address register
dma_c7ctrl	DMA channel 7 configuration register
dma_c7dtcnt	DMA channel 7 number of data register
dma_c7paddr	DMA channel 7 peripheral address register
dma_c7maddr	DMA channel 7 memory address register
dma_src_sel0	Channel source register 0
dma_src_sel1	Channel source register 1

The table below gives a list of DMA library functions.

Table 175. Summary of DMA library functions

Function name	Description
dma_default_para_init	Initialize the parameters of the dma_init_struct
dma_init	Initialize the selected DMA channel
dma_reset	Reset the selected DMA channel
dma_data_number_set	Set the number of data transfer of a given channel
dma_data_number_get	Get the number of data transfer of a given channel
dma_interrupt_enable	Enable DMA channel interrupt
dma_channel_enable	Enable DMA channel
dma_flexible_config	Configure flexible DMA request mapping
dma_flag_get	Get the flag of DMA channels
dma_flag_clear	Clear the flag of DMA channels

5.7.1 dma_default_para_init function

The table below describes the function dma_default_para_init.

Table 176. dma_default_para_init function

Name	Description
Function name	dma_default_para_init
Function prototype	void dma_default_para_init(dma_init_type* dma_init_struct);
Function description	Initialize the parameters of the dma_init_struct
Input parameter 1	dma_init_struct: dma_init_type pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

The table below describes the default values of the dma_init_struct members.

Table 177. dma_init_struct default values

Member	Default value
peripheral_base_addr	0x0
memory_base_addr	0x0
direction	DMA_DIR_PERIPHERAL_TO_MEMORY
buffer_size	0x0
peripheral_inc_enable	FALSE
memory_inc_enable	FALSE
peripheral_data_width	DMA_PERIPHERAL_DATA_WIDTH_BYTE
memory_data_width	DMA_MEMORY_DATA_WIDTH_BYTE
loop_mode_enable	FALSE
priority	DMA_PRIORITY_LOW

Example:

```
/* dma init config with its default value */
dma_init_type dma_init_struct = {0};
dma_default_para_init(&dma_init_struct);
```

5.7.2 dma_init function

The table below describes the function `dma_init`.

Table 178. dma_init function

Name	Description
Function name	<code>dma_init</code>
Function prototype	<code>void dma_init(dma_channel_type* dmax_channely, dma_init_type* dma_init_struct)</code>
Function description	Initialize the selected DMA channel
Input parameter 1	<code>dmax_channely</code> : DMAx_CHANNELy defines a DMA channel number, x=1, y=1...5
Input parameter 2	<code>dma_init_struct</code> : <code>dma_init_type</code> pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

dma_init_type structure

The `dma_init_type` is defined in the “at32f422_426_dma.h”

typedef struct

```
{
    uint32_t peripheral_base_addr;
    uint32_t memory_base_addr;
    dma_dir_type direction;
    uint16_t buffer_size;
    confirm_state peripheral_inc_enable;
    confirm_state memory_inc_enable;
    dma_peripheral_data_size_type peripheral_data_width;
    dma_memory_data_size_type memory_data_width;
```

```
        confirm_state           loop_mode_enable;  
        dma_priority_level_type priority;  
    } dma_init_type;  
peripheral_base_addr  
Set the peripheral address of a DMA channel  
memory_base_addr  
Set the memory address of a DMA channel  
direction  
Set the transfer direction of a DMA channel  
DMA_DIR_PERIPHERAL_TO_MEMORY: Peripheral to memory  
DMA_DIR_MEMORY_TO_PERIPHERAL: Memory to peripheral  
DMA_DIR_MEMORY_TO_MEMORY: Memory to memory  
buffer_size  
Set the number of data transfer of a DMA channel  
peripheral_inc_enable  
Enable/disable DMA channel peripheral address auto increment  
FALSE: Peripheral address is not incremented  
TRUE: Peripheral address is incremented  
memory_inc_enable  
Enable/disable DMA channel memory address auto increment  
FALSE: Memory address is not incremented  
TRUE: Memory address is incremented  
peripheral_data_width  
Set DMA peripheral data width.  
DMA_PERIPHERAL_DATA_WIDTH_BYTE: Byte  
DMA_PERIPHERAL_DATA_WIDTH_HALFWORD: Half-word  
DMA_PERIPHERAL_DATA_WIDTH_WORD: Word  
memory_data_width  
Set DMA memory data width  
DMA_MEMORY_DATA_WIDTH_BYTE: Byte  
DMA_MEMORY_DATA_WIDTH_HALFWORD: Half-word  
DMA_MEMORY_DATA_WIDTH_WORD: Word  
loop_mode_enable  
Set DMA loop mode  
FALSE: DMA single mode  
TRUE: DMA loop mode  
priority  
Set DMA channel priority.  
DMA_PRIORITY_LOW: Low  
DMA_PRIORITY_MEDIUM: Medium  
DMA_PRIORITY_HIGH: High  
DMA_PRIORITY VERY_HIGH: Very high
```

Example:

```
dma_init_type dma_init_struct = {0};  
/* dma1 channel1 configuration */
```

```

dma_init_struct.buffer_size = BUFFER_SIZE;
dma_init_struct.direction = DMA_DIR_MEMORY_TO_PERIPHERAL;
dma_init_struct.memory_base_addr = (uint32_t)src_buffer;
dma_init_struct.memory_data_width = DMA_MEMORY_DATA_WIDTH_HALFWORD;
dma_init_struct.memory_inc_enable = TRUE;
dma_init_struct.peripheral_base_addr = (uint32_t)0x4001100C;
dma_init_struct.peripheral_data_width = DMA_PERIPHERAL_DATA_WIDTH_HALFWORD;
dma_init_struct.peripheral_inc_enable = FALSE;
dma_init_struct.priority = DMA_PRIORITY_MEDIUM;
dma_init_struct.loop_mode_enable = FALSE;
dma_init(DMA1_CHANNEL1, &dma_init_struct);

```

5.7.3 dma_reset function

The table below describes the function dma_reset.

Table 179. dma_reset function

Name	Description
Function name	dma_reset
Function prototype	void dma_reset(dma_channel_type* dmax_channel);
Function description	Reset the selected DMA channel
Input parameter 1	dmax_channel: DMAx_CHANNELy defines a DMA channel number, x=1, y=1...5
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```

/* reset dma1 channel1 */
dma_reset(DMA1_CHANNEL1);

```

5.7.4 dma_data_number_set function

The table below describes the function dma_data_number_set.

Table 180. dma_data_number_set function

Name	Description
Function name	dma_data_number_set
Function prototype	void dma_data_number_set(dma_channel_type* dmax_channel, uint16_t data_number);
Function description	Set the number of data transfer of the selected DMA channel
Input parameter 1	dmax_channel: DMAx_CHANNELy defines a DMA channel number, x=1, y=1...5
Input parameter 2	data_number: indicates the number of data transfer, up to 65535
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* set dma1 channel1 data count is 0x100*/
dma_data_number_set(DMA1_CHANNEL1, 0x100);
```

5.7.5 dma_data_number_get function

The table below describes the function dma_data_number_get.

Table 181. dma_data_number_get function

Name	Description
Function name	dma_data_number_get
Function prototype	uint16_t dma_data_number_get(dma_channel_type* dmax_channel);
Function description	Get the number of data transfer of the selected DMA channel
Input parameter 1	dmax_channel: DMAx CHANNELy defines a DMA channel number, x=1, y=1...5
Output parameter	NA
Return value	Get the number of data transfer of a DMA channel
Required preconditions	NA
Called functions	NA

Example:

```
/* get dma1 channel1 data count/
uint16_t data_counter;
data_counter = dma_data_number_get(DMA1_CHANNEL1);
```

5.7.6 dma_interrupt_enable function

The table below describes the function dma_interrupt_enable.

Table 182. dma_interrupt_enable function

Name	Description
Function name	dma_interrupt_enable
Function prototype	void dma_interrupt_enable(dma_channel_type* dmax_channel, uint32_t dma_int, confirm_state new_state);
Function description	Enable DMA channels interrupt
Input parameter 1	dmax_channel: DMAx CHANNELy defines a DMA channel number, x=1, y=1...5
Input parameter 2	dma_int: interrupt source selection
Input parameter 3	new_state: interrupt enable/disable
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

dma_int

Select DMA interrupt source

DMA_FDT_INT: Transfer complete interrupt

DMA_HDT_INT: Half transfer complete interrupt

DMA_DTERR_INT: Transfer error interrupt

new_state

Enable or disable DMA channel interrupt

FALSE: Disabled

TRUE: Enabled

Example:

```
/* enable dma1 channel1 transfer full data interrupt */
dma_interrupt_enable(DMA1_CHANNEL1, DMA_FDT_INT, TRUE);
```

5.7.7 dma_channel_enable function

The table below describes the function `dma_channel_enable`.

Table 183. `dma_channel_enable` function

Name	Description
Function name	<code>dma_channel_enable</code>
Function prototype	<code>void dma_channel_enable(dma_channel_type* dmax_channel, confirm_state new_state);</code>
Function description	Enable the selected DMA channel
Input parameter 1	<code>dmax_channel</code> : DMAx_CHANNELy defines a DMA channel number, x=1, y=1...5
Input parameter 2	<code>new_state</code> : enable or disable the selected DMA channel
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

new_state

Enable or disable DMA channels.

FALSE: Disabled

TRUE: Enabled

Example:

```
/* enable dma channel */
dma_channel_enable(DMA1_CHANNEL1, TRUE);
```

5.7.8 dma_interrupt_flag_get function

The table below describes the function `dma_interrupt_flag_get`.

Table 184. `dma_interrupt_flag_get` function

Name	Description
Function name	<code>dma_interrupt_flag_get</code>
Function prototype	<code>flag_status dma_interrupt_flag_get(uint32_t dmax_flag);</code>
Function description	Get the flag of the selected DMA channel and check the corresponding interrupt enable bit
Input parameter 1	<code>dmax_flag</code> : select the desired flag
Output parameter	NA
Return value	<code>flag_status</code> : indicates whether the desired flag is set or not
Required preconditions	NA
Called functions	NA

dmax_flag

The dmax_flag is used for flag section, including:

DMA1_GL1_FLAG:	DMA1 channel 1 global flag
DMA1_FDT1_FLAG:	DMA1 channel 1 transfer complete flag
DMA1_HDT1_FLAG:	DMA1 channel 1 half transfer complete flag
DMA1_DTERR1_FLAG:	DMA1 channel 1 transfer error flag
DMA1_GL2_FLAG:	DMA1 channel 2 global flag
DMA1_FDT2_FLAG:	DMA1 channel 2 transfer complete flag
DMA1_HDT2_FLAG:	DMA1 channel 2 half transfer complete flag
DMA1_DTERR2_FLAG:	DMA1 channel 2 transfer error flag
DMA1_GL3_FLAG:	DMA1 channel 3 global flag
DMA1_FDT3_FLAG:	DMA1 channel 3 transfer complete flag
DMA1_HDT3_FLAG:	DMA1 channel 3 half transfer complete flag
DMA1_DTERR3_FLAG:	DMA1 channel 3 transfer error flag
DMA1_GL4_FLAG:	DMA1 channel 4 global flag
DMA1_FDT4_FLAG:	DMA1 channel 4 transfer complete flag
DMA1_HDT4_FLAG:	DMA1 channel 4 half transfer complete flag
DMA1_DTERR4_FLAG:	DMA1 channel 4 transfer error flag
DMA1_GL5_FLAG:	DMA1 channel 5 global flag
DMA1_FDT5_FLAG:	DMA1 channel 5 transfer complete flag
DMA1_HDT5_FLAG:	DMA1 channel 5 half transfer complete flag
DMA1_DTERR5_FLAG:	DMA1 channel 5 transfer error flag
DMA1_FDT6_FLAG:	DMA1 channel 6 transfer complete flag
DMA1_HDT6_FLAG:	DMA1 channel 6 half transfer complete flag
DMA1_DTERR6_FLAG:	DMA1 channel 6 transfer error flag
DMA1_GL7_FLAG:	DMA1 channel 7 global flag
DMA1_FDT7_FLAG:	DMA1 channel 7 transfer complete flag
DMA1_HDT7_FLAG:	DMA1 channel 7 half transfer complete flag
DMA1_DTERR7_FLAG:	DMA1 channel 7 transfer error flag

flag_status

RESET: Flag is reset

SET: Flag is set

Example:

```
if(dma_interrupt_flag_get(DMA1_FDT1_FLAG) != RESET)
{
    /* turn led2/led3/led4 on */
    at32_led_on(LED2);
    at32_led_on(LED3);
    at32_led_on(LED4);
}
```

5.7.9 dma_flag_get function

The table below describes the function `dma_flag_get`.

Table 185. `dma_flag_get` function

Name	Description
Function name	<code>dma_flag_get</code>
Function prototype	<code>flag_status dma_flag_get(uint32_t dmax_flag);</code>
Function description	Get the flag of the selected DMA channel
Input parameter 1	<i>dmax_flag</i> : select the desired flag
Output parameter	NA
Return value	<code>flag_status</code> : indicates whether the desired flag is set or not
Required preconditions	NA
Called functions	NA

dmax_flag

The `dmax_flag` is used for flag section, including:

DMA1_GL1_FLAG:	DMA1 channel 1 global flag
DMA1_FDT1_FLAG:	DMA1 channel 1 transfer complete flag
DMA1_HDT1_FLAG:	DMA1 channel 1 half transfer complete flag
DMA1_DTERR1_FLAG:	DMA1 channel 1 transfer error flag
DMA1_GL2_FLAG:	DMA1 channel 2 global flag
DMA1_FDT2_FLAG:	DMA1 channel 2 transfer complete flag
DMA1_HDT2_FLAG:	DMA1 channel 2 half transfer complete flag
DMA1_DTERR2_FLAG:	DMA1 channel 2 transfer error flag
DMA1_GL3_FLAG:	DMA1 channel 3 global flag
DMA1_FDT3_FLAG:	DMA1 channel 3 transfer complete flag
DMA1_HDT3_FLAG:	DMA1 channel 3 half transfer complete flag
DMA1_DTERR3_FLAG:	DMA1 channel 3 transfer error flag
DMA1_GL4_FLAG:	DMA1 channel 4 global flag
DMA1_FDT4_FLAG:	DMA1 channel 4 transfer complete flag
DMA1_HDT4_FLAG:	DMA1 channel 4 half transfer complete flag
DMA1_DTERR4_FLAG:	DMA1 channel 4 transfer error flag
DMA1_GL5_FLAG:	DMA1 channel 5 global flag
DMA1_FDT5_FLAG:	DMA1 channel 5 transfer complete flag
DMA1_HDT5_FLAG:	DMA1 channel 5 half transfer complete flag
DMA1_DTERR5_FLAG:	DMA1 channel 5 transfer error flag
DMA1_FDT6_FLAG:	DMA1 channel 6 transfer complete flag
DMA1_HDT6_FLAG:	DMA1 channel 6 half transfer complete flag
DMA1_DTERR6_FLAG:	DMA1 channel 6 transfer error flag
DMA1_GL7_FLAG:	DMA1 channel 7 global flag
DMA1_FDT7_FLAG:	DMA1 channel 7 transfer complete flag
DMA1_HDT7_FLAG:	DMA1 channel 7 half transfer complete flag
DMA1_DTERR7_FLAG:	DMA1 channel 7 transfer error flag

flag_status

RESET: Flag is reset

SET: Flag is set

Example:

```
if(dma_flag_get(DMA1_FDT1_FLAG) != RESET)
{
    /* turn led2/led3/led4 on */
    at32_led_on(LED2);
    at32_led_on(LED3);
    at32_led_on(LED4);
}
```

5.7.10 dma_flag_clear function

The table below describes the function `dma_flag_clear`.

Table 186. `dma_flag_clear` function function

Name	Description
Function name	<code>dma_flag_clear</code>
Function prototype	<code>void dma_flag_clear(uint32_t dmax_flag);</code>
Function description	Clear the selected flag
Input parameter 1	<code>dmax_flag</code> : a flag that needs to be cleared
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

dmax_flag

The `dmax_flag` is used to select the desired flag, including:

DMA1_GL1_FLAG:	DMA1 channel 1 global flag
DMA1_FDT1_FLAG:	DMA1 channel 1 transfer complete flag
DMA1_HDT1_FLAG:	DMA1 channel 1 half transfer complete flag
DMA1_DTERR1_FLAG:	DMA1 channel 1 transfer error flag
DMA1_GL2_FLAG:	DMA1 channel 2 global flag
DMA1_FDT2_FLAG:	DMA1 channel 2 transfer complete flag
DMA1_HDT2_FLAG:	DMA1 channel 2 half transfer complete flag
DMA1_DTERR2_FLAG:	DMA1 channel 2 transfer error flag
DMA1_GL3_FLAG:	DMA1 channel 3 global flag
DMA1_FDT3_FLAG:	DMA1 channel 3 transfer complete flag
DMA1_HDT3_FLAG:	DMA1 channel 3 half transfer complete flag
DMA1_DTERR3_FLAG:	DMA1 channel 3 transfer error flag
DMA1_GL4_FLAG:	DMA1 channel 4 global flag
DMA1_FDT4_FLAG:	DMA1 channel 4 transfer complete flag
DMA1_HDT4_FLAG:	DMA1 channel 4 half transfer complete flag
DMA1_DTERR4_FLAG:	DMA1 channel 4 transfer error flag
DMA1_GL5_FLAG:	DMA1 channel 5 global flag
DMA1_FDT5_FLAG:	DMA1 channel 5 transfer complete flag
DMA1_HDT5_FLAG:	DMA1 channel 5 half transfer complete flag
DMA1_DTERR5_FLAG:	DMA1 channel 5 transfer error flag
DMA1_FDT6_FLAG:	DMA1 channel 6 transfer complete flag
DMA1_HDT6_FLAG:	DMA1 channel 6 half transfer complete flag

DMA1_DTERR6_FLAG:	DMA1 channel 6 transfer error flag
DMA1_GL7_FLAG:	DMA1 channel 7 global flag
DMA1_FDT7_FLAG:	DMA1 channel 7 transfer complete flag
DMA1_HDT7_FLAG:	DMA1 channel 7 half transfer complete flag
DMA1_DTERR7_FLAG:	DMA1 channel 7 transfer error flag

Example:

```
if(dma_flag_get(DMA1_FDT1_FLAG) != RESET)
{
    /* turn led2/led3/led4 on */
    at32_led_on(LED2);
    at32_led_on(LED3);
    at32_led_on(LED4);
    dma_flag_clear(DMA1_FDT1_FLAG);
}
```

5.8 Real-time clock (ERTC)

The ERTC register structure ertc_type is defined in the “at32f422_426_ertc.h”.

```
/*
 * @brief type define ertc register all
 */
typedef struct
{

} ertc_type;
```

The table below gives a list of the ERTC registers.

Table 187. Summary of ERTC registers

Register	Description
time	ERTC time register
date	ERTC date register
ctrl	ERTC control register
sts	ERTC initialization and status register
div	ERTC divider register
ala	ERTC alarm clock A register
wp	ERTC write protection register
sbs	ERTC subsecond register
tadj	ERTC time adjustment register
tstm	ERTC timestamp time register
tsdt	ERTC timestamp date register
tssbs	ERTC timestamp subsecond register
scal	ERTC smooth calibration register
tamp	ERTC tamper configuration register
alasbs	ERTC alarm clock A subsecond register
bpx	ERTC battery powered domain data register

The table below gives a list of ERTC library functions.

Table 188. Summary of ERTC library functions

Function name	Description
ertc_num_to_bcd	Convert number to BCD code
ertc_bcd_to_num	Convert BCD code to number
ertc_write_protect_enable	Enable write protection
ertc_write_protect_disable	Disable write protection
ertc_wait_update	Wait for register update complete
ertc_wait_flag	Wait flag
ertc_init_mode_enter	Enter initialization mode
ertc_init_mode_exit	Exit initialization mode
ertc_reset	Reset ERTC registers

ertc_divider_set	Divider setting
ertc_hour_mode_set	Hour mode setting
ertc_date_set	Date setting
ertc_time_set	Time setting
ertc_calendar_get	Get calendar
ertc_sub_second_get	Get the current subsecond
ertc_alarm_mask_set	Set alarm mask
ertc_alarm_week_date_select	Alarm time format selection (week/date)
ertc_alarm_set	Set alarm
ertc_alarm_sub_second_set	Set alarm subsecond
ertc_alarm_enable	Enable alarm
ertc_alarm_get	Get alarm value
ertc_alarm_sub_second_get	Get alarm subsecond
ertc_smooth_calibration_config	Configure smooth calibration
ertc_cal_output_select	Calibration output source selection
ertc_cal_output_enable	Enable calibration output
ertc_time_adjust	Time adjustment
ertc_daylight_set	Set daylight saving time
ertc_daylight_bpr_get	Get daylight saving time battery powered domain data register value (BPR)
ertc_refer_clock_detect_enable	Enable reference clock detection
ertc_direct_read_enable	Enable direct read mode
ertc_output_set	Set event output
ertc_timestamp_valid_edge_set	Set timestamp detection valid edge
ertc_timestamp_enable	Enable timestamp
ertc_timestamp_get	Get timestamp
ertc_timestamp_sub_second_get	Get timestamp subsecond
ertc_tamper_pull_up_enable	Enable tamper pin pull-up resistor
ertc_tamper_precharge_set	Set tamper pin precharge time
ertc_tamper_filter_set	Set tamper filter time
ertc_tamper_detect_freq_set	Set tamper detection frequency
ertc_tamper_valid_edge_set	Set tamper detection valid edge
ertc_tamper_timestamp_enable	Enable timestamp upon a tamper event
ertc_tamper_enable	Enable tamper detection
ertc_interrupt_enable	Enable interrupts
ertc_interrupt_get	Get the status of interrupt enable
ertc_flag_get	Get flag status
ertc_flag_clear	Clear flag
ertc_bpr_data_write	Write data to battery powered data register (BPR)
ertc_bpr_data_read	Read data from battery powered data register (BPR)

5.8.1 ertc_num_to_bcd function

The table below describes the function ertc_num_to_bcd.

Table 189. ertc_num_to_bcd function

Name	Description
Function name	ertc_num_to_bcd
Function prototype	uint8_t ertc_num_to_bcd(uint8_t num);
Function description	Convert number into BCD format
Input parameter 1	num: number to be converted
Output parameter	NA
Return value	BCD code
Required preconditions	NA
Called functions	NA

Example:

```
ertc_num_to_bcd(12);
```

5.8.2 ertc_bcd_to_num function

The table below describes the function ertc_bcd_to_num.

Table 190. ertc_bcd_to_num function

Name	Description
Function name	ertc_bcd_to_num
Function prototype	uint8_t ertc_bcd_to_num(uint8_t bcd);
Function description	Convert BCD code into number
Input parameter 1	bcd: BCD code to be converted
Output parameter	NA
Return value	Return the number corresponding to BCD code
Required preconditions	NA
Called functions	NA

Example:

```
ertc_bcd_to_num(0x12);
```

5.8.3 ertc_write_protect_enable function

The table below describes the function ertc_write_protect_enable.

Table 191. ertc_write_protect_enable function

Name	Description
Function name	ertc_write_protect_enable
Function prototype	void ertc_write_protect_enable(void);
Function description	Write protection enable
Input parameter 1	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
ertc_write_protect_enable();
```

5.8.4 ertc_write_protect_disable function

The table below describes the function ertc_write_protect_disable.

Table 192. ertc_write_protect_disable function

Name	Description
Function name	ertc_write_protect_disable
Function prototype	void ertc_write_protect_disable(void);
Function description	Write protection disable
Input parameter 1	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
ertc_write_protect_disable();
```

5.8.5 ertc_wait_update function

The table below describes the function ertc_wait_update.

Table 193. ertc_wait_update function

Name	Description
Function name	ertc_wait_update
Function prototype	error_status ertc_wait_update(void);
Function description	Wait for register to finish update
Input parameter 1	NA
Output parameter	NA
Return value	SUCCESS: register update complete ERROR: flag wait timeout
Required preconditions	NA
Called functions	NA

Example:

ertc_wait_update();

5.8.6 ertc_wait_flag function

The table below describes the function ertc_wait_flag.

Table 194. ertc_wait_flag function

Name	Description
Function name	ertc_wait_flag
Function prototype	error_status ertc_wait_flag(uint32_t flag, flag_status status);
Function description	Wait flag
Input parameter 1	flag: flag selection Refer to the "flag" description below for details.
Input parameter 1	status: flag status. After the flag status is set, the function remains stuck here until flag status changes. This parameter can be SET or RESET.
Output parameter	NA
Return value	SUCCESS: flag state changed ERROR: flag wait timeout
Required preconditions	NA
Called functions	NA

flag

Flag selection

ERTC_ALAWF_FLAG: Alarm A write enable flag

ERTC_TADJF_FLAG: Time adjustment flag

ERTC_CALUPDF_FLAG: Calibration value update complete flag

Example:

ertc_wait_flag(ERTC_ALAWF_FLAG, RESET);

5.8.7 ertc_init_mode_enter function

The table below describes the function ertc_init_mode_enter.

Table 195. ertc_init_mode_enter function

Name	Description
Function name	ertc_init_mode_enter
Function prototype	error_status ertc_init_mode_enter(void);
Function description	Enter initialization mode
Input parameter 1	NA
Output parameter	NA
Return value	SUCCESS: Initialization mode is entered successfully ERROR: Timeout
Required preconditions	NA
Called functions	NA

Example:

```
ertc_init_mode_enter();
```

5.8.8 ertc_init_mode_exit function

The table below describes the function ertc_init_mode_exit.

Table 196. ertc_init_mode_exit function

Name	Description
Function name	ertc_init_mode_exit
Function prototype	void ertc_init_mode_exit(void);
Function description	Exit initialization mode
Input parameter 1	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
ertc_init_mode_exit();
```

5.8.9 ertc_reset function

The table below describes the function ertc_reset.

Table 197. ertc_reset function

Name	Description
Function name	ertc_reset
Function prototype	error_status ertc_reset(void);
Function description	Reset all ERTC registers
Input parameter 1	NA
Output parameter	NA
Return value	SUCCESS: Reset successful ERROR: Reset failed
Required preconditions	NA
Called functions	NA

Example:

```
ertc_reset();
```

5.8.10 ertc_divider_set function

The table below describes the function ertc_divider_set.

Table 198. ertc_divider_set function

Name	Description
Function name	ertc_divider_set
Function prototype	error_status ertc_divider_set(uint16_t div_a, uint16_t div_b);
Function description	Divider settings, frequency division value $(div_a + 1) * (div_b + 1) = ERTC_CLK$ frequency For example, if 32768Hz is used, the frequency division should be diva = 127, div_b = 255
Input parameter 1	div_a: divider A, range: 0~0x7F
Input parameter 2	div_b: divider B, range: 0~0x7FFF
Output parameter	NA
Return value	SUCCESS: Reset successful ERROR: Reset failed
Required preconditions	NA
Called functions	NA

Example:

```
ertc_divider_set(127, 255);
```

5.8.11 ertc_hour_mode_set function

The table below describes the function ertc_hour_mode_set.

Table 199. ertc_hour_mode_set function

Name	Description
Function name	ertc_hour_mode_set
Function prototype	error_status ertc_hour_mode_set(ertc_hour_mode_set_type mode);
Function description	Hour mode settings
Input parameter 1	mode: hour mode Refer to the following description “mode” for details.
Output parameter	NA
Return value	SUCCESS: Setting success ERROR: Setting error
Required preconditions	NA
Called functions	NA

mode

ERTC_HOUR_MODE_24: 24-hour format

ERTC_HOUR_MODE_12: 12-hour format

Example:

```
ertc_hour_mode_set(ERTC_HOUR_MODE_24);
```

5.8.12 ertc_date_set function

The table below describes the function ertc_date_set.

Table 200. ertc_date_set function

Name	Description
Function name	ertc_date_set
Function prototype	error_status ertc_date_set(uint8_t year, uint8_t month, uint8_t date, uint8_t week);
Function description	Set date: year, month, date, weekday
Input parameter 1	year: range 0~99
Input parameter 2	month: range 1~12
Input parameter 3	date: range 1~31
Input parameter 4	week: range 1~7
Output parameter	NA
Return value	SUCCESS: Setting success ERROR: Setting error
Required preconditions	NA
Called functions	NA

Example:

```
ertc_date_set(22, 5, 26, 4);
```

5.8.13 ertc_time_set function

The table below describes the function ertc_time_set.

Table 201. ertc_time_set function

Name	Description
Function name	ertc_time_set
Function prototype	error_status ertc_time_set(uint8_t hour, uint8_t min, uint8_t sec, ertc_am_pm_type ampm);
Function description	Set time: hour, minute, second, AM/PM (for 12-hour format only)
Input parameter 1	hour: range 0~23
Input parameter 2	min: range 0~59
Input parameter 3	sec: range 0~59
Input parameter 4	ampm: AM/PM in 12-hour format (for 12-hour format only, don't care in 24-hour format) Refer to the following description "ampm" for details.
Output parameter	NA
Return value	SUCCESS: Setting success ERROR: Setting error
Required preconditions	NA
Called functions	NA

ampm

AM/PM in 12-hour format (for 12-hour format only, don't care in 24-hour format)

ERTC_24H: 24-hour format (for 24-hour format)

ERTC_AM: AM in 12-hour format

ERTC_PM: PM in 12-hour format

Example:

```
ertc_time_set(12, 1, 20, ERTC_24H);
```

5.8.14 ertc_calendar_get function

The table below describes the function ertc_calendar_get.

Table 202. ertc_calendar_get function

Name	Description
Function name	ertc_calendar_get
Function prototype	void ertc_calendar_get(ertc_time_type* time);
Function description	Get calendar, including year, month, date, weekday, hour, minute, second, AM/PM
Input parameter 1	time: ertc_time_type pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

ertc_time_type* time

The ertc_time_type is defined in the "at32f422_426_ertc.h".

typedef struct

{

```

    uint8_t          year;
    uint8_t          month;
    uint8_t          day;
    uint8_t          hour;
    uint8_t          min;
    uint8_t          sec;
    uint8_t          week;
    ertc_am_pm_type ampm;
} ertc_time_type;
year
Range 0~99
month
Range 1~12
day
Range 1~31
week
Range 1~7
hour
Range 0~23
min
Range 0~59
sec
Range 0~59
ampm
AM/PM in 12-hour format (for 12-hour format only, doesn't care in 24 hour), including:  

ERTC_AM: AM in 12 hour format  

ERTC_PM: PM in 12 hour format

```

Example:

```
ertc_calendar_get(&time);
```

5.8.15 ertc_sub_second_get function

The table below describes the function ertc_sub_second_get.

Table 203. ertc_sub_second_get function

Name	Description
Function name	ertc_sub_second_get
Function prototype	uint32_t ertc_sub_second_get(void);
Function description	Get current subsecond (the current value of divider B)
Input parameter 1	NA
Output parameter	NA
Return value	Current subsecond
Required preconditions	NA
Called functions	NA

Example:

```
ertc_sub_second_get();
```

5.8.16 ertc_alarm_mask_set function

The table below describes the function ertc_alarm_mask_set.

Table 204. ertc_alarm_mask_set function

Name	Description
Function name	ertc_alarm_mask_set
Function prototype	void ertc_alarm_mask_set(ertc_alarm_type alarm_x, uint32_t mask);
Function description	Set alarm mask
	alarm_x: alarm selection Refer to the following description "alarm_x" for details.
Input parameter 1	mask: Set alarm mask Refer to the following description "mask" for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

alarm_x

Alarm selection

ERTC_ALA: Alarm A

mask

Set alarm mask

ERTC_ALARM_MASK_NONE:	No mask, alarm is relevant to all fields
ERTC_ALARM_MASK_SEC:	Mask second, alarm is not relevant to second
ERTC_ALARM_MASK_MIN:	Mask minute, alarm is not relevant to minute
ERTC_ALARM_MASK_HOUR:	Mask hour, alarm is not relevant to hour
ERTC_ALARM_MASK_DATE_WEEK:	Mask date, alarm is not relevant to date
ERTC_ALARM_MASK_ALL:	Mask all. Generate an alarm per one second

Example:

```
ertc_alarm_mask_set(ERTC_ALA, ERTC_ALARM_MASK_NONE);
```

5.8.17 ertc_alarm_week_date_select function

The table below describes the function ertc_alarm_week_date_select.

Table 205. ertc_alarm_week_date_select function

Name	Description
Function name	ertc_alarm_week_date_select
Function prototype	void ertc_alarm_week_date_select(ertc_alarm_type alarm_x, ertc_week_date_select_type wk);
Function description	Alarm time format selection: week/date
Input parameter 1	alarm_x: alarm selection Refer to the following description “alarm_x” for details.
Input parameter 2	wk: alarm week/date format selection Refer to the following description “wk” for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

alarm_x

Alarm selection

ERTC_ALA: Alarm A

wk

Alarm week/date format selection

ERTC_SELECT_DATE: Date mode

ERTC_SELECT_WEEK: Week mode

Example:

```
ertc_alarm_week_date_select(ERTC_ALA, ERTC_SELECT_DATE);
```

5.8.18 ertc_alarm_set function

The table below describes the function ertc_alarm_set.

Table 206. ertc_alarm_set function

Name	Description
Function name	ertc_alarm_set
Function prototype	void ertc_alarm_set(ertc_alarm_type alarm_x, uint8_t week_date, uint8_t hour, uint8_t min, uint8_t sec, ertc_am_pm_type ampm);
Function description	Set alarm
Input parameter 1	alarm_x: alarm selection Refer to the following description “alarm_x” for details.
Input parameter 2	week_date: date or week, depending on the ertc_alarm_week_date_select() Date: range 1~31 Week: range 1~7
Input parameter 3	hour: range 0~23
Input parameter 4	min: range 0~59
Input parameter 5	sec: range 0~59
Input parameter 6	ampm: AM/PM in 12-hour format (12 hour format only, doesn’t care in 24-hour format) Refer to the following description “ampm” for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

alarm_x

Alarm selection

ERTC_ALA: Alarm A

ampm

AM/PM in 12-hour format (for 12 hour format only, doesn’t care in 24 hour)

ERTC_24H: 24-hour format (for 24 hour format)

ERTC_AM: AM in 12-hour format

ERTC_PM: PM in 12-hour format

Example:

```
ertc_alarm_set(ERTC_ALA, 15, 8, 0, 0, ERTC_24H);
```

5.8.19 ertc_alarm_sub_second_set function

The table below describes the function ertc_alarm_sub_second_set.

Table 207. ertc_alarm_sub_second_set function

Name	Description
Function name	ertc_alarm_sub_second_set
Function prototype	void ertc_alarm_sub_second_set(ertc_alarm_type alarm_x, uint32_t value, ertc_alarm_sbs_mask_type mask);
Function description	Set alarm subsecond
Input parameter 1	alarm_x: alarm selection Refer to the following description “alarm_x” for details.
Input parameter 2	value: subsecond value, range 0~0x7FFF
Input parameter 3	mask: alarm mask settings Refer to the following description “mask” for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

alarm_x

Alarm selection

ERTC_ALA: Alarm A

mask

Subsecond mask

ERTC_ALARM_SBS_MASK_ALL:	Mask all
ERTC_ALARM_SBS_MASK_14_1:	Only match SBS bit [0]
ERTC_ALARM_SBS_MASK_14_2:	Only match SBS bit [1:0]
ERTC_ALARM_SBS_MASK_14_3:	Only match SBS bit [2:0]
ERTC_ALARM_SBS_MASK_14_4:	Only match SBS bit [3:0]
ERTC_ALARM_SBS_MASK_14_5:	Only match SBS bit [4:0]
ERTC_ALARM_SBS_MASK_14_6:	Only match SBS bit [5:0]
ERTC_ALARM_SBS_MASK_14_7:	Only match SBS bit [6:0]
ERTC_ALARM_SBS_MASK_14_8:	Only match SBS bit [7:0]
ERTC_ALARM_SBS_MASK_14_9:	Only match SBS bit [8:0]
ERTC_ALARM_SBS_MASK_14_10:	Only match SBS bit [9:0]
ERTC_ALARM_SBS_MASK_14_11:	Only match SBS bit [10:0]
ERTC_ALARM_SBS_MASK_14_12:	Only match SBS bit [11:0]
ERTC_ALARM_SBS_MASK_14_13:	Only match SBS bit [12:0]
ERTC_ALARM_SBS_MASK_14:	Only match SBS bit [13:0]
ERTC_ALARM_SBS_MASK_NONE:	Only match SBS bit [14:0]

Example:

```
ertc_alarm_sub_second_set(ERTC_ALA, 200, ERTC_ALARM_SBS_MASK_NONE);
```

5.8.20 ertc_alarm_enable function

The table below describes the function ertc_alarm_enable.

Table 208. ertc_alarm_enable function

Name	Description
Function name	ertc_alarm_enable
Function prototype	error_status ertc_alarm_enable(ertc_alarm_type alarm_x, confirm_state new_state);
Function description	Alarm enable
Input parameter 1	alarm_x: alarm selection Refer to the following description “alarm_x” for details.
Input parameter 2	new_state: alarm enable status This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	SUCCESS: Setting success ERROR: Setting error
Required preconditions	NA
Called functions	NA

alarm_x

Alarm selection

ERTC_ALA: Alarm A

Example:

```
ertc_alarm_enable(ERTC_ALA, TRUE);
```

5.8.21 ertc_alarm_get function

The table below describes the function ertc_alarm_get.

Table 209. ertc_alarm_get function

Name	Description
Function name	ertc_alarm_get
Function prototype	void ertc_alarm_get(ertc_alarm_type alarm_x, ertc_alarm_value_type* alarm);
Function description	Get alarm value
Input parameter 1	alarm_x: alarm selection Refer to the following description “alarm_x” for details.
Input parameter 2	alarm: ertc_alarm_value_type pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

alarm_x

Alarm selection

ERTC_ALA: Alarm A

ertc_alarm_value_type* alarm

The ertc_alarm_value_type is defined in the “at32f422_426_ertc.h”.

typedef struct

```
{  
    uint8_t          day;  
    uint8_t          hour;  
    uint8_t          min;  
    uint8_t          sec;  
    ertc_am_pm_type ampm;  
    uint32_t         mask;  
    uint8_t          week_date_sel;  
    uint8_t          week;  
} ertc_alarm_value_type;
```

day

Range 1~31

hour

Range 0~23

min

Range 0~59

sec

Range 0~59

ampm

AM/PM in 12-hour format (for 12-hour format only, doesn't care in 24 hour), including:

ERTC_AM: AM in 12 hour format

ERTC_PM: PM in 12 hour format

mask

Alarm mask value, including:

ERTC_ALARM_MASK_NONE: No mask

ERTC_ALARM_MASK_SEC: Mask second

ERTC_ALARM_MASK_MIN: Mask minute

ERTC_ALARM_MASK_HOUR: Mask hour

ERTC_ALARM_MASK_DATE_WEEK: Mask date

ERTC_ALARM_MASK_ALL: Mask all. Generate an alarm per one second

week_date_sel

Alarm week/date format, including:

ERTC_SELECT_DATE: Date mode

ERTC_SELECT_WEEK: Week mode

week

Range 1~7

Example:

```
ertc_alarm_get(ERTC_ALA, &alarm);
```

5.8.22 ertc_alarm_sub_second_get function

The table below describes the function ertc_alarm_sub_second_get.

Table 210. ertc_alarm_sub_second_get function

Name	Description
Function name	ertc_alarm_sub_second_get
Function prototype	uint32_t ertc_alarm_sub_second_get(ertc_alarm_type alarm_x);
Function description	Get alarm subsecond value
Input parameter 1	alarm_x: alarm selection Refer to the following description “alarm_x” for details.
Output parameter	NA
Return value	Alarm subsecond value
Required preconditions	NA
Called functions	NA

alarm_x

Alarm selection

ERTC_ALA: Alarm A

Example:

```
ertc_alarm_sub_second_get(ERTC_ALA);
```

5.8.23 ertc_smooth_calibration_config function

The table below describes the function ertc_smooth_calibration_config.

Table 211. ertc_smooth_calibration_config function

Name	Description
Function name	ertc_smooth_calibration_config
Function prototype	error_status ertc_smooth_calibration_config(ertc_smooth_cal_period_type period, ertc_smooth_cal_clk_add_type clk_add, uint32_t clk_dec);
Function description	Set smooth digital calibration
Input parameter 1	period: calibration period Refer to the following “period” descriptions for details.
Input parameter 2	clk_add: add ERTC CLK cycles Refer to the following “clk_add” descriptions for details.
Input parameter 3	clk_dec: reduce ERTC CLK cycles, range 0~511
Output parameter	NA
Return value	SUCCESS: Setting success ERROR: Setting error
Required preconditions	NA
Called functions	NA

period

Calibration periods

ERTC_SMOOTH_CAL_PERIOD_32: 32 seconds

ERTC_SMOOTH_CAL_PERIOD_16: 16 seconds

ERTC_SMOOTH_CAL_PERIOD_8: 8 seconds

clk_add

Add ERTC CLK cycles

ERTC_SMOOTH_CAL_CLK_ADD_0: No effect

ERTC_SMOOTH_CAL_CLK_ADD_512: Add 512 ERTC_CLK cycles

Example:

```
ertc_smooth_calibration_config(ERTC_SMOOTH_CAL_PERIOD_32, ERTC_SMOOTH_CAL_CLK_ADD_0, 511);
```

5.8.24 ertc_cal_output_select function

The table below describes the function ertc_cal_output_select.

Table 212. ertc_cal_output_select function

Name	Description
Function name	ertc_cal_output_select
Function prototype	void ertc_cal_output_select(ertc_cal_output_select_type output);
Function description	Calibration output source selection
Input parameter 1	output: Calibration output source Refer to the following "output" descriptions for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

output

Calibration output source

ERTC_CAL_OUTPUT_512HZ: 512 Hz output

ERTC_CAL_OUTPUT_1HZ: 1 Hz output

Example:

```
ertc_cal_output_select(ERTC_CAL_OUTPUT_1HZ);
```

5.8.25 ertc_cal_output_enable function

The table below describes the function ertc_cal_output_enable.

Table 213. ertc_cal_output_enable function

Name	Description
Function name	ertc_cal_output_enable
Function prototype	void ertc_cal_output_enable(confirm_state new_state);
Function description	Calibration output enable
Input parameter 1	new_state: calibration output enable state This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
ertc_cal_output_enable(TRUE);
```

5.8.26 ertc_time_adjust function

The table below describes the function ertc_time_adjust.

Table 214. ertc_time_adjust function

Name	Description
Function name	ertc_time_adjust
Function prototype	error_status ertc_time_adjust(ertc_time_adjust_type add1s, uint32_t decsbs);
Function description	Adjust time
Input parameter 1	add1s: add seconds Refer to the following “add1s” descriptions for details.
Input parameter 2	decsbs: reduce subseconds, range 0~0x7FFF
Output parameter	NA
Return value	SUCCESS: setting success ERROR: setting error
Required preconditions	NA
Called functions	NA

add1s

This bit is used to add seconds.

ERTC_TIME_ADD_NONE: No effect

ERTC_TIME_ADD_1S: Add 1 second

Example:

```
ertc_time_adjust(ERTC_TIME_ADD_1S, 254);
```

5.8.27 ertc_daylight_set function

The table below describes the function ertc_daylight_set.

Table 215. ertc_daylight_set function

Name	Description
Function name	ertc_daylight_set
Function prototype	void ertc_daylight_set(ertc_dst_operation_type operation, ertc_dst_save_type save);
Function description	Set daylight-saving time
Input parameter 1	operation: daylight-saving time settings Refer to the following “operation” descriptions for details.
Input parameter 2	save: save daylight time Refer to the following “save” descriptions for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

operation

Daylight-saving time settings

ERTC_DST_ADD_1H: Add 1 hour

ERTC_DST_DEC_1H: Decrease 1 hour

save

Save daylight time

ERTC_DST_SAVE_0: set BPR bit =0 in the CTRL register

ERTC_DST_SAVE_1: set BPR bit =1 in the CTRL register

Example:

```
ertc_daylight_set(ERTC_DST_ADD_1H, ERTC_DST_SAVE_1);
```

5.8.28 ertc_daylight_bpr_get function

The table below describes the function ertc_daylight_bpr_get.

Table 216. ertc_daylight_bpr_get function

Name	Description
Function name	ertc_daylight_bpr_get
Function prototype	uint8_t ertc_daylight_bpr_get(void);
Function description	Get the value of daylight-saving time battery powered register (BPR bit in the CTRL register)
Input parameter 1	NA
Output parameter	NA
Return value	Return the value of daylight-saving time battery powered register (BPR bit in the CTRL register)
Required preconditions	NA
Called functions	NA

Example:

```
ertc_daylight_bpr_get();
```

5.8.29 ertc_refer_clock_detect_enable function

The table below describes the function ertc_refer_clock_detect_enable.

Table 217. ertc_refer_clock_detect_enable function

Name	Description
Function name	ertc_refer_clock_detect_enable
Function prototype	error_status ertc_refer_clock_detect_enable(confirm_state new_state);
Function description	Enable reference clock detection
Input parameter 1	new_state: reference clock detection enable state This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	SUCCESS: setting success ERROR: setting error
Required preconditions	NA
Called functions	NA

Example:

```
ertc_refer_clock_detect_enable(TRUE);
```

5.8.30 ertc_direct_read_enable function

The table below describes the function ertc_direct_read_enable.

Table 218. ertc_direct_read_enable function

Name	Description
Function name	ertc_direct_read_enable
Function prototype	void ertc_direct_read_enable(confirm_state new_state);
Function description	Enable direct read mode
Input parameter 1	new_state: direct read mode enable state This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
ertc_direct_read_enable(TRUE);
```

5.8.31 ertc_output_set function

The table below describes the function ertc_output_set.

Table 219. ertc_output_set function

Name	Description
Function name	ertc_output_set
Function prototype	void ertc_output_set(ertc_output_source_type source, ertc_output_polarity_type polarity, ertc_output_type type);
Function description	Set event output on PC13
Input parameter 1	source: output source selection Refer to the following "source" descriptions for details.
Input parameter 2	polarity: output polarity Refer to the following "polarity" descriptions for details.
Input parameter 3	type: output type Refer to the following "type" descriptions for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

source

Output source selection

- | | |
|----------------------|----------------------|
| ERTC_OUTPUT_DISABLE: | Output disabled |
| ERTC_OUTPUT_ALARM_A: | Output alarm A event |
| ERTC_OUTPUT_ALARM_B: | Output alarm B event |
| ERTC_OUTPUT_WAKEUP: | Output wakeup event |

polarity

Output polarity

- | | |
|----------------------------|------------------------------------|
| ERTC_OUTPUT_POLARITY_HIGH: | Output high when an event occurred |
|----------------------------|------------------------------------|

ERTC_OUTPUT_POLARITY_LOW: Output low when an event occurred

type

Output type

ERTC_OUTPUT_TYPE_OPEN_DRAIN: Open-drain output

ERTC_OUTPUT_TYPE_PUSH_PULL: Push-pull output

Example:

```
ertc_output_set(ERTC_OUTPUT_ALARM_A, ERTC_OUTPUT_POLARITY_HIGH,
ERTC_OUTPUT_TYPE_PUSH_PULL);
```

5.8.32 ertc_timestamp_valid_edge_set function

The table below describes the function ertc_timestamp_valid_edge_set.

Table 220. ertc_timestamp_valid_edge_set function

Name	Description
Function name	ertc_timestamp_valid_edge_set
Function prototype	void ertc_timestamp_valid_edge_set(ertc_timestamp_valid_edge_type edge);
Function description	Set timestampe detection valid edge
Input parameter 1	edge: timestampe detection valid edge Refer to the following "edge" descriptions for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

edge

Timestampe detection valid edge

ERTC_TIMESTAMP_EDGE_RISING: Rising edge

ERTC_TIMESTAMP_EDGE_FALLING: Falling edge

Example:

```
ertc_timestamp_valid_edge_set(ERTC_TIMESTAMP_EDGE_RISING);
```

5.8.33 ertc_timestamp_enable function

The table below describes the function ertc_timestamp_enable.

Table 221. ertc_timestamp_enable function

Name	Description
Function name	ertc_timestamp_enable
Function prototype	void ertc_timestamp_enable(confirm_state new_state);
Function description	Enable timestamp
Input parameter 1	new_state: timestamp enable state This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
ertc_timestamp_enable(TRUE);
```

5.8.34 ertc_timestamp_get function

The table below describes the function ertc_timestamp_get.

Table 222. ertc_timestamp_get function

Name	Description
Function name	ertc_timestamp_get
Function prototype	void ertc_timestamp_get(ertc_time_type* time);
Function description	Get timestamp
Input parameter 1	time: ertc_time_type pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

ertc_time_type* time

The ertc_time_type is defined in the "at32f422_426_ertc.h".

typedef struct

```
{
    uint8_t          year;
    uint8_t          month;
    uint8_t          day;
    uint8_t          hour;
    uint8_t          min;
    uint8_t          sec;
    uint8_t          week;
    ertc_am_pm_type ampm;
}
```

} ertc_time_type;

year

Range 0~99

month

Range 1~12

day

Range 1~31

week

Range 1~7

hour

Range 0~23

min

Range 0~59

sec

Range 0~59

ampm

AM/PM in 12-hour format (only for 12-hour format, doesn't care in 24-hour format), including:

ERTC_AM: AM in 12-hour format

ERTC_PM: PM in 12-hour format

Example:

```
ertc_timestamp_get(&time);
```

5.8.35 ertc_timestamp_sub_second_get function

The table below describes the function ertc_timestamp_sub_second_get.

Table 223. ertc_timestamp_sub_second_get function

Name	Description
Function name	ertc_timestamp_sub_second_get
Function prototype	uint32_t ertc_timestamp_sub_second_get(void);
Function description	Get timestamp subsecond
Input parameter 1	NA
Output parameter	NA
Return value	Return timestamp subsecond
Required preconditions	NA
Called functions	NA

Example:

```
ertc_timestamp_sub_second_get();
```

5.8.36 ertc_tamper_pull_up_enable function

The table below describes the function ertc_tamper_pull_up_enable.

Table 224. ertc_tamper_pull_up_enable function

Name	Description
Function name	ertc_tamper_pull_up_enable
Function prototype	void ertc_tamper_pull_up_enable(confirm_state new_state);
Function description	Enable tamper pin pull-up resistor
Input parameter 1	new_state: tamper pin pull-up resistor enable state This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
ertc_tamper_pull_up_enable(TRUE);
```

5.8.37 ertc_tamper_purge_set function

The table below describes the function ertc_tamper_purge_set.

Table 225. ertc_tamper_purge_set function

Name	Description
Function name	ertc_tamper_purge_set
Function prototype	void ertc_tamper_purge_set(ertc_tamper_purge_type purge);
Function description	Set tamper pin purge time. This setting is needed only when the tamper pull-up resistor is enabled through the function ertc_tamper_pull_up_enable.
Input parameter 1	purge: tamper pin purge time Refer to the following “purge” descriptions for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

purge

Tamper pin purge time

- ERTC_TAMPER_PR_1_ERTCCLK: 1 ERTC_CLK cycle
- ERTC_TAMPER_PR_2_ERTCCLK: 2 ERTC_CLK cycles
- ERTC_TAMPER_PR_4_ERTCCLK: 4 ERTC_CLK cycles
- ERTC_TAMPER_PR_8_ERTCCLK: 8 ERTC_CLK cycles

Example:

```
ertc_tamper_purge_set(ERTC_TAMPER_PR_2_ERTCCLK);
```

5.8.38 ertc_tamper_filter_set function

The table below describes the function ertc_tamper_filter_set.

Table 226. ertc_tamper_filter_set function

Name	Description
Function name	ertc_tamper_filter_set
Function prototype	void ertc_tamper_filter_set(ertc_tamper_filter_type filter);
Function description	Set tamper filtering time
Input parameter 1	filter: tamper filtering time Refer to the following “filter” descriptions for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

filter

Set tamper filtering time

ERTC_TAMPER_FILTER_DISABLE: No filtering

ERTC_TAMPER_FILTER_2:

Tamper event is considered to have occur after two valid consecutive sampling

ERTC_TAMPER_FILTER_4:

Tamper event is considered to have occur after four valid consecutive sampling

ERTC_TAMPER_FILTER_8:

Tamper event is considered to have occur after eight valid consecutive sampling

Example:

```
ertc_tamper_filter_set(ERTC_TAMPER_FILTER_2);
```

5.8.39 ertc_tamper_detect_freq_set function

The table below describes the function ertc_tamper_detect_freq_set.

Table 227. ertc_tamper_detect_freq_set function

Name	Description
Function name	ertc_tamper_detect_freq_set
Function prototype	void ertc_tamper_detect_freq_set(ertc_tamper_detect_freq_type freq);
Function description	Set tamper detection frequency
Input parameter 1	freq: tamper detection frequency Refer to the following "freq" descriptions for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

freq

Select tamper detection frequency

ERTC_TAMPER_FREQ_DIV_32768:	ERTC_CLK / 32768
ERTC_TAMPER_FREQ_DIV_16384:	ERTC_CLK / 16384
ERTC_TAMPER_FREQ_DIV_8192:	ERTC_CLK / 8192
ERTC_TAMPER_FREQ_DIV_4096:	ERTC_CLK / 4096
ERTC_TAMPER_FREQ_DIV_2048:	ERTC_CLK / 2048
ERTC_TAMPER_FREQ_DIV_1024:	ERTC_CLK / 1024
ERTC_TAMPER_FREQ_DIV_512:	ERTC_CLK / 512
ERTC_TAMPER_FREQ_DIV_256:	ERTC_CLK / 256

Example:

```
ertc_tamper_detect_freq_set(ERTC_TAMPER_FREQ_DIV_512);
```

5.8.40 ertc_tamper_valid_edge_set function

The table below describes the function ertc_tamper_valid_edge_set.

Table 228. ertc_tamper_valid_edge_set function

Name	Description
Function name	ertc_tamper_valid_edge_set
Function prototype	void ertc_tamper_valid_edge_set(ertc_tamper_select_type tamper_x, ertc_tamper_valid_edge_type trigger);
Function description	Set tamper detection valid edge
Input parameter 1	tamper_x: tamper selection Refer to the following "tamper_x" descriptions for details.
Input parameter 2	trigger: tamper detection valid edge Refer to the following "trigger" descriptions for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tamper_x

Tamper selection

ERTC_TAMPER_1: Tamper detection 1

trigger

Tamper detection valid edge selection

ERTC_TAMPER_EDGE_RISING: Rising edge

ERTC_TAMPER_EDGE_FALLING: Falling edge

ERTC_TAMPER_EDGE_LOW: Low level

ERTC_TAMPER_EDGE_HIGH: High level

Example:

```
ertc_tamper_valid_edge_set(ERTC_TAMPER_1, ERTC_TAMPER_EDGE_RISING);
```

5.8.41 ertc_tamper_timestamp_enable function

The table below describes the function ertc_tamper_timestamp_enable.

Table 229. ertc_tamper_timestamp_enable function

Name	Description
Function name	ertc_tamper_timestamp_enable
Function prototype	void ertc_tamper_timestamp_enable(confirm_state new_state);
Function description	Enable timestamp when a tamper event occurs
Input parameter 1	new_state: timestamp feature enable state when a tamper event occurs This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
ertc_tamper_timestamp_enable(TRUE);
```

5.8.42 ertc_tamper_enable function

The table below describes the function ertc_tamper_enable.

Table 230. ertc_tamper_enable function

Name	Description
Function name	ertc_tamper_enable
Function prototype	void ertc_tamper_enable(ertc_tamper_select_type tamper_x, confirm_state new_state);
Function description	Enable tamper detection
Input parameter 1	tamper_x: tamper selection Refer to the following “tamper_x” descriptions for details.
Input parameter 2	new_state: tamper detection enable state This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tamper_x

Tamper selection

ERTC_TAMPER_1: Tamper detection 1

Example:

```
ertc_tamper_enable(ERTC_TAMPER_1, TRUE);
```

5.8.43 ertc_interrupt_enable function

The table below describes the function ertc_interrupt_enable.

Table 231. ertc_interrupt_enable function

Name	Description
Function name	ertc_interrupt_enable
Function prototype	void ertc_interrupt_enable(uint32_t source, confirm_state new_state);
Function description	Interrupt enable
	source: interrupt source to be enabled Refer to the following “source” descriptions for details.
Input parameter 1	new_state: interrupt enable state This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

source

Interrupt source to be enabled

ERTC_TP_INT: Tamper detection interrupt

ERTC_ALA_INT: Alarm A interrupt

ERTC_TS_INT: Timestamp interrupt

Example:

```
ertc_interrupt_enable(ERTC_TP_INT, TRUE);
```

5.8.44 ertc_interrupt_get function

The table below describes the function ertc_interrupt_get.

Table 232. ertc_interrupt_get function

Name	Description
Function name	ertc_interrupt_get
Function prototype	flag_status ertc_interrupt_get(uint32_t source);
Function description	Get interrupt enable state
Input parameter 1	source: interrupt source Refer to the following "source" descriptions for details.
Output parameter	NA
Return value	flag_status: flag status This parameter can be SET or RESET.
Required preconditions	NA
Called functions	NA

source

Interrupt source

ERTC_TP_INT: Tamper detection interrupt

ERTC_ALA_INT: Alarm A interrupt

ERTC_TS_INT: Timestamp interrupt

Example:

```
ertc_interrupt_get(ERTC_TP_INT);
```

5.8.45 ertc_flag_get function

The table below describes the function ertc_flag_get.

Table 233. ertc_flag_get function

Name	Description
Function name	ertc_flag_get
Function prototype	flag_status ertc_flag_get(uint32_t flag);
Function description	Get flag status
Input parameter 1	flag: flag selection Refer to the following "flag" descriptions for details.
Output parameter	NA
Return value	flag_status: flag status This parameter can be SET or RESET.
Required preconditions	NA
Called functions	NA

flag

This bit is used to select a flag. Optional parameters are as follows:

ERTC_ALAWF_FLAG: Alarm A write enable flag

ERTC_TADJF_FLAG: Time adjust flag

ERTC_INITF_FLAG:	Calendar initialization flag
ERTC_UPDF_FLAG:	Calendar update flag
ERTC_IMF_FLAG:	Initialization mode entry flag
ERTC_ALAF_FLAG:	Alarm A flag
ERTC_TSF_FLAG:	Timestamp flag
ERTC_TSOF_FLAG:	Timestamp overflow flag
ERTC_TP1F_FLAG:	Tamper detection 1 flag
ERTC_CALUPDF_FLAG:	Calibration value update complete flag

Example:

```
ertc_flag_get(ERTC_TP1F_FLAG);
```

5.8.46 ertc_interrupt_flag_get function

The table below describes the function ertc_interrupt_flag_get.

Table 234. ertc_interrupt_flag_get function

Name	Description
Function name	ertc_interrupt_flag_get
Function prototype	flag_status ertc_interrupt_flag_get(uint32_t flag);
Function description	Get interrupt flag status, and check the corresponding interrupt enable bit
Input parameter 1	flag: flag selection Refer to the following “flag” descriptions for details.
Output parameter	NA
Return value	flag_status: flag status This parameter can be SET or RESET.
Required preconditions	NA
Called functions	NA

flag

This bit is used to select a flag. Optional parameters are as follows:

ERTC_ALAF_FLAG:	Alarm A flag
ERTC_TSF_FLAG:	Timestamp flag
ERTC_TP1F_FLAG:	Tamper detection 1 flag

Example:

```
ertc_interrupt_flag_get(ERTC_TP1F_FLAG);
```

5.8.47 ertc_flag_clear function

The table below describes the function ertc_flag_clear.

Table 235. ertc_flag_clear function

Name	Description
Function name	ertc_flag_clear
Function prototype	void ertc_flag_clear(uint32_t flag);
Function description	Clear flag
Input parameter 1	flag: flag selection Refer to the following "flag" descriptions for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

flag

This bit is used to select a flag. Optional parameters are as follows:

ERTC_ALAWF_FLAG:	Alarm A write enable flag
ERTC_TADJF_FLAG:	Time adjust flag
ERTC_INITF_FLAG:	Calendar initialization flag
ERTC_UPDF_FLAG:	Calendar update flag
ERTC_IMF_FLAG:	Initialization mode entry flag
ERTC_ALAF_FLAG:	Alarm A flag
ERTC_TSFLAG:	Timestamp flag
ERTC_TSOF_FLAG:	Timestamp overflow flag
ERTC_TP1F_FLAG:	Tamper detection 1 flag
ERTC_CALUPDF_FLAG:	Calibration value update complete flag

Example:

```
ertc_flag_clear(ERTC_TP1F_FLAG);
```

5.8.48 ertc_bpr_data_write function

The table below describes the function ertc_bpr_data_write.

Table 236. ertc_bpr_data_write function

Name	Description
Function name	ertc_bpr_data_write
Function prototype	void ertc_bpr_data_write(ertc_dt_type dt, uint32_t data);
Function description	Write data to BPR register (battery powered data register)
Input parameter 1	dt: data register Refer to the following "dt" descriptions for details.
Input parameter 1	data: 32-bit data
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

dt

Data register

ERTC_DT1: Data register 1

ERTC_DT2: Data register 2

ERTC_DT3: Data register 3

ERTC_DT4: Data register 4

ERTC_DT5: Data register 5

Example:

```
ertc_bpr_data_write(ERTC_DT1, 0x12345678);
```

5.8.49 ertc_bpr_data_read function

The table below describes the function ertc_bpr_data_read.

Table 237. ertc_bpr_data_read function

Name	Description
Function name	ertc_bpr_data_read
Function prototype	uint32_t ertc_bpr_data_read(ertc_dt_type dt);
Function description	Read data from BPR register (battery powered data register)
Input parameter 1	dt: data register Refer to the following "dt" descriptions for details.
Output parameter	NA
Return value	Data from BPR register
Required preconditions	NA
Called functions	NA

dt

Data register

ERTC_DT1: Data register 1

ERTC_DT2: Data register 2

ERTC_DT3: Data register 3

ERTC_DT4: Data register 4

ERTC_DT5: Data register 5

Example:

```
ertc_bpr_data_read(ERTC_DT1);
```

5.9 External interrupt/event controller (EXINT)

The EXINT register structure exint_type is defined in the “at32f422_426_exint.h”.

```
/*
 * @brief type define exint register all
 */
typedef struct
{
    ...
} exint_type;
```

The table below gives a list of the EXINT registers.

Table 238. Summary of EXINT registers

Registers	Description
inten	Interrupt enable register
evten	Event enable register
polcfg1	Polarity configuration register 1
polcfg2	Polarity configuration register 2
swtrg	Software trigger register
intsts	Interrupt status register

The table below gives a list of EXINT library functions.

Table 239. Summary of EXINT library functions

Function name	Description
exint_reset	Reset all EXINT registers to their reset values
exint_default_para_init	Configure the EXINT initial structure with the initial value
exint_init	Initialize EXINT
exint_flag_clear	Clear the selected EXINT interrupt flag
exint_flag_get	Get the selected EXINT interrupt flag
exint_interrupt_flag_get	Read the selected EXINT interrupt flag
exint_software_interrupt_event_generate	Software interrupt event generation
exint_interrupt_enable	Enable the selected EXINT interrupt
exint_event_enable	Enable the selected EXINT event

5.9.1 exint_reset function

The table below describes the function exint_reset.

Table 240. exint_reset function

Name	Description
Function name	exint_reset
Function prototype	void exint_reset(void);
Function description	Reset all EXINT registers to their reset values.
Input parameter	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	crm_periph_reset();

Example:

```
exint_reset();
```

5.9.2 exint_default_para_init function

The table below describes the function exint_default_para_init.

Table 241. exint_default_para_init function

Name	Description
Function name	exint_default_para_init
Function prototype	void exint_default_para_init(exint_init_type *exint_struct);
Function description	Configure the EXINT initial structure with the initiali value
Input parameter 1	exint_struct: exint_init_type pointer
Output parameter	NA
Return value	NA
Required preconditions	It is necessary to define a variable of exint_init_type before starting.
Called functions	NA

Example:

```
exint_init_type exint_init_struct;  
exint_default_para_init(&exint_init_struct);
```

5.9.3 exint_init function

The table below describes the function exint_init.

Table 242. exint_init function

Name	Description
Function name	exint_init
Function prototype	void exint_init(exint_init_type *exint_struct);
Function description	Initialize EXINT
Input parameter 1	exint_init_type : exint_struct pointer
Output parameter	NA
Return value	NA
Required preconditions	It is necessary to define a variable of exint_init_type before starting.
Called functions	NA

The exint_init_type is defined in the “at32f422_426_exint.h”.

typedef struct

```
{
    exint_line_mode_type          line_mode;
    uint32_t                      line_select;
    exint_polarity_config_type   line_polarity;
    confirm_state                 line_enable;
} exint_init_type;
```

line_mode

Select event mode or interrupt mode

EXINT_LINE_INTERRUPT: Interrupt mode

EXINT_LINE_EVENT: Event mode

line_select

Line selection

EXINT_LINE_NONE: No line

EXINT_LINE_0: line0

EXINT_LINE_1: line1

...

EXINT_LINE_20: line20

EXINT_LINE_21: line21

line_polarity

Trigger edge selection

EXINT_TRIGGER_RISING_EDGE: Rising edge

EXINT_TRIGGER_FALLING_EDGE: Falling edge

EXINT_TRIGGER_BOTH_EDGE: Rising/falling edge

line_enable

Enable/disable line

FALSE: Disable line

TRUE: Enable line

Example:

```
exint_init_type exint_init_struct;
```

```

exint_default_para_init(&exint_init_struct);
exint_init_struct.line_enable = TRUE;
exint_init_struct.line_mode = EXINT_LINE_INTERRUPT;
exint_init_struct.line_select = EXINT_LINE_0;
exint_init_struct.line_polarity = EXINT_TRIGGER_RISING_EDGE;
exint_init(&exint_init_struct);

```

5.9.4 exint_flag_clear function

The table below describes the function exint_flag_clear.

Table 243. exint_flag_clear function

Name	Description
Function name	exint_flag_clear
Function prototype	void exint_flag_clear(uint32_t exint_line);
Function description	Clear the selected EXINT interrupt flag
Input parameter	exint_line: line selection Refer to the line_select for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
exint_flag_clear(EXINT_LINE_0);
```

5.9.5 exint_flag_get function

The table below describes the function exint_flag_get.

Table 244. exint_flag_get function

Name	Description
Function name	exint_flag_get
Function prototype	flag_status exint_flag_get(uint32_t exint_line);
Function description	Get the selected EXINT interrupt flag
Input parameter	exint_line: line selection Refer to line_select for details.
Output parameter	NA
Return value	flag_status: status of the selected flag This parameter can be SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```

flag_status status = RESET;
status = exint_flag_get(EXINT_LINE_0);

```

5.9.6 exint_interrupt_flag_get function

The table below describes the function exint_interrupt_flag_get.

Table 245. exint_interrupt_flag_get function

Name	Description
Function name	exint_interrupt_flag_get
Function prototype	flag_status exint_interrupt_flag_get(uint32_t exint_line)
Function description	Get EXINT interrupt flag status
Input parameter	exint_line: line selection Refer to line_select for details.
Output parameter	NA
Return value	flag_status: status of the selected flag This parameter can be SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```
flag_status status = RESET;
status = exint_interrupt_flag_get (EXINT_LINE_0);
```

5.9.7 exint_software_interrupt_event_generate function

The table below describes the function exint_software_interrupt_event_generate.

Table 246. exint_software_interrupt_event_generate function

Name	Description
Function name	exint_software_interrupt_event_generate
Function prototype	void exint_software_interrupt_event_generate(uint32_t exint_line);
Function description	Generate software interrupt event
Input parameter	exint_line: line selection Refer to line_select for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
exint_software_interrupt_event_generate (EXINT_LINE_0);
```

5.9.8 exint_interrupt_enable function

The table below describes the function exint_interrupt_enable.

Table 247. exint_interrupt_enable function

Name	Description
Function name	exint_interrupt_enable
Function prototype	void exint_interrupt_enable(uint32_t exint_line, confirm_state new_state);
Function description	Enable the selected EXINT interrupt
Input parameter 1	exint_line: line selection Refer to line_select for details.
Input parameter 2	new_state: Enable or disable This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
exint_interrupt_enable (EXINT_LINE_0);
```

5.9.9 exint_event_enable function

The table below describes the function exint_event_enable.

Table 248. exint_event_enable function

Name	Description
Function name	exint_event_enable
Function prototype	void exint_event_enable(uint32_t exint_line, confirm_state new_state);
Function description	Enable the selected EXINT event
Input parameter 1	exint_line: line selection Refer to line_select for details.
Input parameter 2	new_state: Enable or disable This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
exint_event_enable (EXINT_LINE_0);
```

5.10 Flash memory controller (FLASH)

The FLASH register structure flash_type is defined in the “at32f422_426_flash.h”.

```
/*
 * @brief type define flash register all
 */
typedef struct
{
    ...
} flash_type;
```

The table below gives a list of the FLASH registers.

Table 249. Summary of FLASH registers

Register	Description
flash_psr	Flash performance select register
flash_unlock	Flash unlock register
flash_usd_unlock	Flash user system data unlock register
flash_sts	Flash status register
flash_ctrl	Flash control register
flash_addr	Flash address register
flash_usd	User system data register
flash_epps	Erase/program protection status register
slib_sts0	Flash security library status register 0
slib_sts1	Flash security library status register 1
slib_pwd_clr	Flash security library password clear register
slib_misc_sts	Flash security library extra status register
flash_crc_addr	Flash CRC check address register
flash_crc_ctrl	Flash CRC check control register
flash_crc_chkr	Flash CRC check result register
slib_set_pwd	Flash security library password setting register
slib_set_range	Flash security library address setting register
em_slib_set	Extended memory security library setting register
btm_mode_set	Boot memory mode setting register
slib_unlock	Flash security library unlock register

The table below gives a list of FLASH library functions.

Table 250. Summary of FLASH library functions

Function name	Description
flash_flag_get	Get flag status
flash_flag_clear	Clear flag
flash_operation_status_get	Get operation status (Flash memory bank 1)
flash_operation_wait_for	Wait for operation complete (Flash memory bank 1)
flash_unlock	Unlock Flash (Flash memory bank 1 and 2)
flash_lock	Lock Flash (Flash memory bank 1 and 2)
flash_sector_erase	Erase Flash sector
flash_internal_all_erase	Erase internal Flash
flash_user_system_data_erase	Erase user system data
flash_word_program	Flash word programming
flash_halfword_program	Flash half-word programming
flash_byte_program	Flash byte programming
flash_user_system_data_program	User system data programming
flash_epp_set	Erase/programming protection configuration
flash_epp_status_get	Get erase/programming protection status
flash_fap_enable	Flash access protection enable
flash_fap_status_get	Get Flash access protection status
flash_fap_high_level_enable	Flash high level access protection enable
flash_fap_high_level_status_get	Get Flash high level access protection status
flash(ssb)_set	System configuration byte configuration
flash(ssb)_status_get	Get system configuration byte configuration status
flash_interrupt_enable	Flash interrupt configuration
flash_slib_enable	sLib enable
flash_slib_disable	sLib disable
flash_slib_state_get	Get sLib states
flash_slib_start_sector_get	Get sLib start sector
flash_slib_inststart_sector_get	Get sLib instruction area start sector
flash_slib_end_sector_get	Get sLib end sector
flash_crc_calibrate	Flash CRC verify
flash_boot_memory_extension_mode_enable	Boot memory is used as an extended Flash memory
flash_extension_memory_slib_enable	Extended Flash memory is used as a security library
flash_extension_memory_slib_state_get	Get the status of the security library in the extended Flash memory
flash_em_slib_inststart_sector_get	Get the start sector of instruction area of security library in the extended memory
flash_low_power_mode_enable	Enable Flash low-power mode

5.10.1 flash_flag_get function

The table below describes the function flash_flag_get.

Table 251. flash_flag_get function

Name	Description
Function name	flash_flag_get
Function prototype	flag_status flash_flag_get(uint32_t flash_flag);
Function description	Get flag status
Input parameter	flash_flag: flag selection
Output parameter	NA
Return value	flag_status: indicates the flag status Return RESET or SET.
Required preconditions	NA
Called functions	NA

flash_flag

Flag selection.

- FLASH_OBF_FLAG: Flash operation busy
- FLASH_ODF_FLAG: Flash operation complete
- FLASH_PGMERR_FLAG: Flash programming error
- FLASH_EPPERR_FLAG: Flash erase error
- FLASH_USDERR_FLAG: User system data area error

Example:

```
flag_status status;
status = flash_flag_get (FLASH_ODF_FLAG);
```

5.10.2 flash_flag_clear function

The table below describes the function flash_flag_clear.

Table 252. flash_flag_clear function

Name	Description
Function name	flash_flag_clear
Function prototype	void flash_flag_clear(uint32_t flash_flag);
Function description	Clear flag
Input parameter	flash_flag: flag selection
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

flash_flag

Flash status flag selection

- FLASH_ODF_FLAG: Flash operation complete
- FLASH_PGMERR_FLAG: Flash programming error
- FLASH_EPPERR_FLAG: Flash error error

Example:

```
flash_flag_clear(FLASH_ODF_FLAG);
```

5.10.3 flash_operation_status_get function

The table below describes the function flash_operation_status_get.

Table 253. flash_operation_status_get function

Name	Description
Function name	flash_operation_status_get
Function prototype	flash_status_type flash_operation_status_get(void);
Function description	Get operation status
Input parameter	NA
Output parameter	NA
Return value	Refer to the flash_status_type for details.
Required preconditions	NA
Called functions	NA

flash_status_type

FLASH_OPERATE_BUSY:	Operate busy
FLASH_PROGRAM_ERROR:	Programming error
FLASH_EPP_ERROR:	Erase/program protection error
FLASH_OPERATE_DONE:	Operation complete
FLASH_OPERATE_TIMEOUT:	Operation timeout

Example:

```
flash_status_type status = FLASH_OPERATE_DONE;
/* check for the flash status */
status = flash_operation_status_get();
```

5.10.4 flash_operation_wait_for function

The table below describes the function flash_operation_wait_for.

Table 254. flash_operation_wait_for function

Name	Description
Function name	flash_operation_wait_for
Function prototype	flash_status_type flash_operation_wait_for(uint32_t time_out);
Function description	Wait for Flash operation
Input parameter	time_out: wait timeout The timeout value is defined in the flash.h file.
Output parameter	NA
Return value	Refer to flash_status_type for details.
Required preconditions	NA
Called functions	NA

flash_time_out

ERASE_TIMEOUT:	Erase timeout
PROGRAMMING_TIMEOUT:	Programming timeout
OPERATION_TIMEOUT:	Operation timeout

Example:

```
/* wait for operation to be completed */
status = flash_operation_wait_for(PROGRAMMING_TIMEOUT);
```

5.10.5 flash_unlock function

The table below describes the function flash_unlock.

Table 255. flash_unlock function

Name	Description
Function name	flash_unlock
Function prototype	void flash_unlock(void);
Function description	Unlock Flash memory controller
Input parameter	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
flash_unlock();
```

5.10.6 flash_lock function

The table below describes the function flash_lock.

Table 256. flash_lock function

Name	Description
Function name	flash_lock
Function prototype	void flash_lock(void);
Function description	Lock Flash memory controller
Input parameter	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
flash_lock();
```

5.10.7 flash_sector_erase function

The table below describes the function flash_sector_erase.

Table 257. flash_sector_erase function

Name	Description
Function name	flash_sector_erase
Function prototype	flash_status_type flash_sector_erase(uint32_t sector_address);
Function description	Erase data in the selected Flash sector address
Input parameter	sector_address: select the Flash sector address to be erased, usually Flash sector start address
Output parameter	NA
Return value	Refer to flash_status_type for details.
Required preconditions	NA
Called functions	NA

Example:

```
flash_status_type status = FLASH_OPERATE_DONE;
flash_unlock();
status = flash_sector_erase(0x08001000);
```

5.10.8 flash_internal_all_erase function

The table below describes the function flash_internal_all_erase.

Table 258. flash_internal_all_erase function

Name	Description
Function name	flash_internal_all_erase
Function prototype	flash_status_type flash_internal_all_erase(void);
Function description	Erase internal Flash data
Input parameter	NA
Output parameter	NA
Return value	Refer to flash_status_type for details.
Required preconditions	NA
Called functions	NA

Example:

```
flash_status_type status = FLASH_OPERATE_DONE;
flash_unlock();
status = flash_internal_all_erase();
```

5.10.9 flash_user_system_data_erase function

The table below describes the function `flash_user_system_data_erase`.

Table 259. `flash_user_system_data_erase` function

Name	Description
Function name	<code>flash_user_system_data_erase</code>
Function prototype	<code>flash_status_type flash_user_system_data_erase(void);</code>
Function description	Erase user system data
Input parameter	NA
Output parameter	NA
Return value	Refer to flash_status_type for details.
Required preconditions	NA
Called functions	NA

Note: As this function remains in FAP state, it only erases data except FAP in the user system data area.

Example:

```
flash_status_type status = FLASH_OPERATE_DONE;
flash_unlock();
status = flash_user_system_data_erase();
```

5.10.10 `flash_word_program` function

The table below describes the function `flash_word_program`.

Table 260. `flash_word_program` function

Name	Description
Function name	<code>flash_word_program</code>
Function prototype	<code>flash_status_type flash_word_program(uint32_t address, uint32_t data);</code>
Function description	Write one word data to a given address
Input parameter 1	address: programmed address, word-aligned
Input parameter 2	data: programmed data
Output parameter	NA
Return value	Refer to flash_status_type for details.
Required preconditions	The programming operation can be allowed only when data in the address are all 0xFF.
Called functions	NA

Example:

```
flash_status_type status = FLASH_OPERATE_DONE;
uint32_t i;
flash_unlock();
status = flash_sector_erase(0x08001000);
if(status = FLASH_OPERATE_DONE)
{
    /* program 256 words */
    for(i = 0; i < 256; i++)
    {
        status = flash_word_program(0x08001000 + i*4, i);
```

{
}

5.10.11 flash_halfword_program function

The table below describes the function flash_halfword_program.

Table 261. flash_halfword_program function

Name	Description
Function name	flash_halfword_program
Function prototype	flash_status_type flash_halfword_program(uint32_t address, uint16_t data);
Function description	Write a half-word data to a given address
Input parameter 1	address: programmed address, half-word-aligned
Input parameter 2	data: programmed data
Output parameter	NA
Return value	Refer to flash_status_type for details.
Required preconditions	The programming operation can be allowed only when data in the address are all 0xFF.
Called functions	NA

Example:

```
flash_status_type status = FLASH_OPERATE_DONE;  
uint32_t i;  
flash_unlock();  
status = flash_sector_erase(0x08001000);  
if(status = FLASH_OPERATE_DONE)  
{  
    /* program 256 halfwords */  
    for(l = 0; l < 256; i++)  
    {  
        status = flash_halfword_program(0x08001000 + i*2, (uint16_t)i);  
    }  
}
```

5.10.12 flash_byte_program function

The table below describes the function flash_byte_program.

Table 262. flash_byte_program function

Name	Description
Function name	flash_byte_program
Function prototype	flash_status_type flash_byte_program(uint32_t address, uint8_t data);
Function description	Program a byte data to a given address
Input parameter 1	address: programmed address
Input parameter 2	data: programmed data
Output parameter	NA
Return value	Refer to flash_status_type for details.
Required preconditions	The programming operation can be allowed only when data in the address are all 0xFF.
Called functions	NA

Example:

```
flash_status_type status = FLASH_OPERATE_DONE;
uint32_t i;
flash_unlock();
status = flash_sector_erase(0x08001000);
if(status = FLASH_OPERATE_DONE)
{
    /* program 256 bytes */
    for(i = 0; i < 256; i++)
    {
        status = flash_byte_program(0x08001000 + i*2, (uint8_t)i);
    }
}
```

5.10.13 flash_user_system_data_program function

The table below describes the function flash_user_system_data_program

Table 263. flash_user_system_data_program function

Name	Description
Function name	flash_user_system_data_program
Function prototype	flash_status_type flash_user_system_data_program (uint32_t address, uint8_t data);
Function description	Program a byte data to a given address in the user system data area
Input parameter 1	address: programmed address
Input parameter 2	data: programmed data
Output parameter	NA
Return value	Refer to flash_status_type for details.
Required preconditions	The programming operation can be allowed only when data and its inverse data in the user system data area are all 0xFF.
Called functions	NA

Example:

```

flash_status_type status = FLASH_OPERATE_DONE;
flash_unlock();
status = flash_user_system_data_erase();
if(status = FLASH_OPERATE_DONE)
{
    /* program user system data */
    status = flash_user_system_data_program(0x1FFF804, 0x55);
}

```

5.10.14 flash_epp_set function

The table below describes the function `flash_epp_set`.

Table 264. `flash_epp_set` function

Name	Description
Function name	<code>flash_epp_set</code>
Function prototype	<code>flash_status_type flash_epp_set(uint32_t *sector_bits);</code>
Function description	Enable erase/ programming protection
Input parameter	*sector_bits: Erase/ programming protection sector address pointer. Each of bits 15~0 protects 4KB sectors, and the bit31 guards Flash extension area. When this bit is set to 1, it indicates that the corresponding sector is protected.
Output parameter	NA
Return value	Refer to flash_status_type for details.
Required preconditions	NA
Called functions	NA

Example:

```

flash_status_type status = FLASH_OPERATE_DONE;
uint32_t epp_val[2];
flash_unlock();
status = flash_user_system_data_erase();
if(status = FLASH_OPERATE_DONE)
{
    epp_val[0] = 0x00000001;
    epp_val[1] = 0x00000001;
    /* program epp */
    status = flash_epp_set(epp_val);
}

```

5.10.15 flash_epp_status_get function

The table below describes the function flash_epp_status_get.

Table 265. flash_epp_status_get function

Name	Description
Function name	flash_epp_status_get
Function prototype	void flash_epp_status_get(uint32_t *sector_bits);
Function description	Get the status of erase/ programming protection
Input parameter	NA
Output parameter	*sector_bits: Erase/ programming protection sector address pointer. Each of bits 15~0 protects 4KB sectors, and the bit31 guards Flash extension area. When this bit is set to 1, it indicates that the corresponding sector is protected.
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
uint32_t epp_val[2];
/* get epp status */
flash_epp_status_get(epp_val);
```

5.10.16 flash_fap_enable function

The table below describes the function flash_fap_enable.

Table 266. flash_fap_enable function

Name	Description
Function name	flash_fap_enable
Function prototype	flash_status_type flash_fap_enable(confirm_state new_state);
Function description	Enable Flash access protection
Input parameter	new_state: Flash access protection status This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	Refer to flash_status_type for details.
Required preconditions	NA
Called functions	NA

Note: This function will erase the whole user system data area. If there were data programmed in the user system data area before calling this function, they have to be re-programmed after calling this function.

Example:

```
flash_status_type status = FLASH_OPERATE_DONE;
flash_unlock();
status = flash_fap_enable(TRUE);
```

5.10.17 flash_fap_status_get function

The table below describes the function flash_fap_status_get.

Table 267. flash_fap_status_get function

Name	Description
Function name	flash_fap_status_get
Function prototype	flag_status flash_fap_status_get(void);
Function description	Get the status of Flash access protection
Input parameter	NA
Output parameter	NA
Return value	flag_status: flag status This parameter can be SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```
flag_status status;
status = flash_fap_status_get();
```

5.10.18 flash_fap_high_level_enable function

The table below describes the function flash_fap_high_level_enable.

Table 268. flash_fap_high_level_enable function

Name	Description
Function name	flash_fap_high_level_enable
Function prototype	flash_status_type flash_fap_high_level_enable(confirm_state new_state);
Function description	Enable Flash high level access protection
Input parameter	new_state: Flash access protection status This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	Refer to flash_status_type for details.
Required preconditions	NA
Called functions	NA

Example:

```
flash_status_type status = FLASH_OPERATE_DONE;
flash_unlock();
status = flash_fap_high_level_enable(TRUE);
```

5.10.19 flash_fap_high_level_status_get function

The table below describes the function flash_fap_high_level_status_get.

Table 269. flash_fap_high_level_status_get function

Name	Description
Function name	flash_fap_high_level_status_get
Function prototype	flag_status flash_fap_high_level_status_get(void);
Function description	Get Flash high level access protection status
Input parameter	NA
Output parameter	NA
Return value	flag_status: flag status This parameter can be SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```
flag_status status;
status = flash_fap_high_level_status_get();
```

5.10.20 flash(ssb) set function

The table below describes the function flash(ssb) set.

Table 270. flash(ssb) set function

Name	Description
Function name	flash_ssbs_set
Function prototype	flash_status_type flash_ssbs_set(uint8_t usd_ssbs);
Function description	Configure system setting bytes
Input parameter	usd_ssbs: system setting byte value is a combination of the selected data from all data group. Refer to ssb_data_define for details.
Output parameter	NA
Return value	Refer to flash_status_type for details.
Required preconditions	NA
Called functions	NA

ssb_data_define

type 1:

USD_WDT_ATO_DISABLE: Watchdog auto-start disabled

USD_WDT_ATO_ENABLE: Watchdog auto-start enabled

type 2:

USD_DEPSLP_NO_RST: No reset occurred when entering Deepsleep mode

USD_DEPSLP_RST: Reset occurred when entering Deepsleep mode

type 3:

USD_STDBY_NO_RST: No reset occurred when entering Standby mode

USD_STDBY_RST: Reset occurred when entering Standby mode

type 4:

USD_BOOT1_LOW: Boot from boot memory when BOOT0 high

USD_BOOT1_HIGH: Boot from internal Flash memory when BOOT0 high

Example:

```

flash_status_type status = FLASH_OPERATE_DONE;
flash_unlock();
status = flash_user_system_data_erase();
if(status == FLASH_OPERATE_DONE)
{
    status = flash(ssb_set(USD_WDT_ATO_DISABLE | USD_DEPSLP_NO_RST | USD_STDBY_RST |
FLASH_BOOT_FROM_BANK1);
}

```

5.10.21 flash_ss_b_status_get function

The table below describes the function flash_ss_b_status_get.

Table 271. flash_ss_b_status_get function

Name	Description
Function name	flash_ss _b _status_get
Function prototype	uint8_t flash_ss _b _status_get(void);
Function description	Get the status of system setting bytes
Input parameter	NA
Output parameter	NA
Return value	Refer to ss_b_data_define for details.
Required preconditions	NA
Called functions	NA

Example:

```

uint8_t ssb_val;
ssb_val = flash_ssb_status_get();

```

5.10.22 flash_interrupt_enable function

The table below describes the function flash_interrupt_enable.

Table 272. flash_interrupt_enable function

Name	Description
Function name	flash_interrupt_enable
Function prototype	void flash_interrupt_enable(uint32_t flash_int, confirm_state new_state);
Function description	Enable Flash interrupts
Input parameter 1	flash_int: Flash interrupt type. Refer to flash_interrupt_type for details.
Input parameter 2	new_state: interrupt status This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

flash_interrupt_type

- | | |
|----------------|------------------------------------|
| FLASH_ERR_INT: | Flash error interrupt |
| FLASH_ODF_INT: | Flash operation complete interrupt |

Example:

```
flash_interrupt_enable(FLASH_BANK1_ERR_INT | FLASH_BANK1_ODF_INT, TRUE);
```

5.10.23 flash_slib_enable function

The table below describes the function flash_slib_enable.

Table 273. flash_slib_enable function

Name	Description
Function name	flash_slib_enable
Function prototype	flash_status_type flash_slib_enable(uint32_t pwd, uint16_t start_sector, uint16_t inst_start_sector, uint16_t end_sector);
Function description	Enable security library (sLib) and its address range
Input parameter 1	pwd: sLib password. The sLib data are saved as ciphertext, associated with encrypted computing. A correct password is entered in order to unlock encryption.
Input parameter 2	start_sector: sLib start sector number
Input parameter 3	inst_start_sector: sLib data area instruction start sector number
Input parameter 4	end_sector: sLib end sector number
Output parameter	NA
Return value	Refer to flash_status_type for details.
Required preconditions	NA
Called functions	NA

Example:

```
flash_status_type status = FLASH_OPERATE_DONE;
status = flash_slib_enable(0x12345678, 0x04, 0x05, 0x06);
```

5.10.24 flash_slib_disable function

The table below describes the function flash_slib_disable.

Table 274. flash_slib_disable function

Name	Description
Function name	flash_slib_disable
Function prototype	error_status flash_slib_disable(uint32_t pwd);
Function description	Disable security library (sLib)
Input parameter	pwd: sLib password. it must be entered correctly, otherwise it is not allowed to enter until reset.
Output parameter	NA
Return value	Return error status This parameter can be ERROE or SUCCESS.
Required preconditions	NA
Called functions	NA

Note: Successful calling of this function will erase the whole internal Flash memory.

Example:

```
error_status status;
status = flash_slib_disable(0x12345678);
```

5.10.25 flash_slib_state_get function

The table below describes the function flash_slib_state_get.

Table 275. flash_slib_state_get function

Name	Description
Function name	flash_slib_state_get
Function prototype	flag_status flash_slib_state_get(void);
Function description	Get the status of sLib
Input parameter	NA
Output parameter	NA
Return value	flag_status: flag status This parameter can be SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```
flag_status status;  
status = flash_slib_state_get();
```

5.10.26 flash_slib_start_sector_get function

The table below describes the function flash_slib_start_sector_get.

Table 276. flash_slib_start_sector_get function

Name	Description
Function name	flash_slib_start_sector_get
Function prototype	uint16_t flash_slib_start_sector_get(void);
Function description	Get the start sector number of sLib
Input parameter	NA
Output parameter	NA
Return value	Return the start sector number of sLib
Required preconditions	NA
Called functions	NA

Example:

```
uint16_t num;  
num = flash_slib_start_sector_get();
```

5.10.27 flash_slib_inststart_sector_get function

The table below describes the function flash_slib_inststart_sector_get.

Table 277. flash_slib_inststart_sector_get function

Name	Description
Function name	flash_slib_inststart_sector_get
Function prototype	uint16_t flash_slib_inststart_sector_get(void);
Function description	Get the start sector number of sLib instruction area
Input parameter	NA
Output parameter	NA
Return value	Return the start sector number of sLib instruction area
Required preconditions	NA
Called functions	NA

Example:

```
uint16_t num;  
num = flash_slib_inststart_sector_get();
```

5.10.28 flash_slib_end_sector_get function

The table below describes the function flash_slib_end_sector_get.

Table 278. flash_slib_end_sector_get function

Name	Description
Function name	flash_slib_end_sector_get
Function prototype	uint16_t flash_slib_end_sector_get(void);
Function description	Get the end sector number of sLib
Input parameter	NA
Output parameter	NA
Return value	Return the end sector number of sLib
Required preconditions	NA
Called functions	NA

Example:

```
uint16_t num;  
num = flash_slib_end_sector_get();
```

5.10.29 flash_crc_calibrate function

The table below describes the function flash_crc_calibrate.

Table 279. flash_crc_calibrate function

Name	Description
Function name	flash_crc_calibrate
Function prototype	uint32_t flash_crc_calibrate(uint32_t start_sector, uint32_t sector_cnt);
Function description	Enable Flash CRC check
Input parameter 1	start_sector: CRC check start address
Input parameter 2	sector_cnt: CRC check sector count
Output parameter	NA
Return value	Return CRC calculation result
Required preconditions	NA
Called functions	NA

Note: The sector set to go through CRC check is only allowed to be on a single area, rather than on both security library and common area.

Example:

```
uint32_t crc_val;
crc_val = flash_crc_calibrate(0, 10);
```

5.10.30 flash_boot_memory_extension_mode_enable function

The table below describes the function flash_boot_memory_extension_mode_enable.

Table 280. flash_boot_memory_extension_mode_enable function

Name	Description
Function name	flash_boot_memory_extension_mode_enable
Function prototype	void flash_boot_memory_extension_mode_enable(void);
Function description	Boot memory is used as extended Flash memory. This settings becomes effective after a system reset.
Input parameter	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Note: This feature can be enabled once and is irreversible, which makes it impossible to return to boot memory after successful configuration.

Example:

```
flash_boot_memory_extension_mode_enable();
nvic_system_reset();
```

5.10.31 flash_extension_memory_slib_enable function

The table below describes the function flash_extension_memory_slib_enable.

Table 281. flash_extension_memory_slib_enable function

Name	Description
Function name	flash_extension_memory_slib_enable
Function prototype	flash_status_type flash_extension_memory_slib_enable(uint32_t pwd, uint16_t inst_start_sector);
Function description	Enable Flash memory extension area sLib and its data area start sector
Input parameter 1	pwd: Flash extension area sLib password. The sLib data are saved in ciphertext, associated with encrypted computing. A correct password is entered in order to unlock encryption.
Input parameter 2	inst_start_sector: the start sector number of sLib instruction area in the Flash extension area
Output parameter	NA
Return value	Refer to flash_status_type for details.
Required preconditions	NA
Called functions	NA

Note: Flash memory and its extension area cannot be configured with security library at the same time. Select either one of both is permitted.

Example:

```
flash_status_type status = FLASH_OPERATE_DONE;
status = flash_extension_memory_slib_enable(0x123456, 0x01);
```

5.10.32 flash_extension_memory_slib_state_get function

The table below describes the function flash_extension_memory_slib_state_get.

Table 282. flash_extension_memory_slib_state_get function

Name	Description
Function name	flash_extension_memory_slib_state_get
Function prototype	flag_status flash_extension_memory_slib_state_get(void);
Function description	Get the status of security library in the extended Flash memory
Input parameter	NA
Output parameter	NA
Return value	flag_status: flag status This value can be SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```
flag_status status;
status = flash_extension_memory_slib_state_get();
```

5.10.33 flash_em_slib_inststart_sector_get function

The table below describes the function flash_em_slib_inststart_sector_get.

Table 283. flash_em_slib_inststart_sector_get function

Name	Description
Function name	flash_em_slib_inststart_sector_get
Function prototype	uint16_t flash_em_slib_inststart_sector_get(void);
Function description	Get the start sector of security library instruction area in the extended Flash memory
Input parameter	NA
Output parameter	NA
Return value	Return the start sector of security library instruction area in the extended Flash memory
Required preconditions	NA
Called functions	NA

Example:

```
uint16_t num;
num = flash_em_slib_datastart_sector_get();
```

5.10.34 flash_low_power_mode_enable function

The table below describes the function flash_low_power_mode_enable.

Table 284. flash_low_power_mode_enable function

Name	Description
Function name	flash_low_power_mode_enable
Function prototype	void flash_low_power_mode_enable(confirm_state new_state);
Function description	Enable Flash low-power mode
Input parameter	new_state: indicates the status of Flash low-power mode This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
flash_low_power_mode_enable(TRUE);
```

5.11 General-purpose I/Os and multiplexed I/Os (GPIO/IOMUX)

The GPIO register structure gpio_type is defined in the “at32f422_426_gpio.h”.

```
/*
 * @brief type define gpio register all
 */
typedef struct
{
    } gpio_type;
```

The table below gives a list of the GPIO registers.

Table 285. Summary of GPIO registers

Register	Description
cfg	GPIO configuration register
omode	GPIO output mode register
odrvr	GPIO drive capability switch control register
pull	GPIO pull-up/pull-down register
idt	GPIO input data register
odt	GPIO output data register
scr	GPIO set/clear register
wpr	GPIO write protection register
muxl	GPIO multiplexed function low register
muxh	GPIO multiplexed function high register
clr	GPIO port bit clear register
hdrv	GPIO huge current control register

The table below gives a list of GPIO and IOMUX library functions.

Table 286. Summary of GPIO and IOMUX library functions

Function name	Description
gpio_reset	Reset GPIO by CRM reset register
gpio_init	Initialize GPIO peripherals
gpio_default_para_init	Initialize GPIO default parameters
gpio_input_data_bit_read	Read GPIO input data bit
gpio_input_data_read	Read GPIO input data
gpio_output_data_bit_read	Read GPIO output data bit
gpio_output_data_read	Read GPIO output data
gpio_bits_set	Set GPIO bits
gpio_bits_reset	Reset GPIO bits
gpio_bits_toggle	Toggle GPIO bits
gpio_bits_write	Write GPIO bits
gpio_port_write	Write GPIO ports
gpio_pin_wp_config	Configure GPIO pin write protection

gpio_pins_huge_driven_config	Configure GPIO huge drive capability
gpio_pin_mux_config	Configure GPIO pin multiplexed function

5.11.1 gpio_reset function

The table below describes the function gpio_reset.

Table 287. gpio_reset function

Name	Description
Function name	gpio_reset
Function prototype	void gpio_reset(gpio_type *gpio_x);
Function description	GPIO is reset by CRM reset register
Input parameter	gpio_x: the selected GPIO peripheral This parameter can be GPIOA, GPIOB, GPIOC, GPIOF.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	crm_periph_reset();

Example:

```
gpio_reset(GPIOA);
```

5.11.2 gpio_init function

The table below describes the function gpio_init.

Table 288. gpio_init function

Name	Description
Function name	gpio_init
Function prototype	void gpio_init(gpio_type *gpio_x, gpio_init_type *gpio_init_struct);
Function description	Initialize GPIO peripherals
Input parameter 1	gpio_x: the selected GPIO peripheral This parameter can be GPIOA, GPIOB, GPIOC, GPIOF.
Input parameter 2	gpio_init_struct: gpio_init_type pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

gpio_init_type structure

The gpio_init_type is defined in the “at32f422_426_gpio.h”.

typedef struct

```
{
    uint32_t          gpio_pins;
    gpio_output_type gpio_out_type;
    gpio_pull_type   gpio_pull;
    gpio_mode_type   gpio_mode;
    gpio_drive_type  gpio_drive_strength;
} gpio_init_type;
```

gpio_pins

Select a GPIO pin.

- GPIO_PINS_0: GPIO pin 0
- GPIO_PINS_1: GPIO pin 1
- GPIO_PINS_2: GPIO pin 2
- GPIO_PINS_3: GPIO pin 3
- GPIO_PINS_4: GPIO pin 4
- GPIO_PINS_5: GPIO pin 5
- GPIO_PINS_6: GPIO pin 6
- GPIO_PINS_7: GPIO pin 7
- GPIO_PINS_8: GPIO pin 8
- GPIO_PINS_9: GPIO pin 9
- GPIO_PINS_10: GPIO pin 10
- GPIO_PINS_11: GPIO pin 11
- GPIO_PINS_12: GPIO pin 12
- GPIO_PINS_13: GPIO pin 13
- GPIO_PINS_14: GPIO pin 14
- GPIO_PINS_15: GPIO pin 15

gpio_out_type

Set GPIO output type.

- GPIO_OUTPUT_PUSH_PULL: GPIO push-pull
- GPIO_OUTPUT_OPEN_DRAIN: GPIO open drain

gpio_pull

Set GPIO pull-up or pull-down.

- GPIO_PULL_NONE: No GPIO pull-up/pull-down
- GPIO_PULL_UP: GPIO pull-up
- GPIO_PULL_DOWN: GPIO pull-down

gpio_mode

Set GPIO mode

- GPIO_MODE_INPUT: GPIO input mode
- GPIO_MODE_OUTPUT: GPIO output mode
- GPIO_MODE_MUX: GPIO multiplexed mode
- GPIO_MODE_ANALOG: GPIO analog mode

gpio_drive_strength

Set GPIO drive capability.

- GPIO_DRIVE_STRENGTH_STRONGER: Strong drive strength
- GPIO_DRIVE_STRENGTH_MODERATE: Moderate drive strength

Example:

```
gpio_init_type gpio_init_struct;
gpio_init_struct gpio_pins = GPIO_PINS_0;
gpio_init_struct gpio_mode = GPIO_MODE_MUX;
gpio_init_struct gpio_out_type = GPIO_OUTPUT_PUSH_PULL;
gpio_init_struct gpio_pull = GPIO_PULL_NONE;
gpio_init_struct gpio_drive_strength = GPIO_DRIVE_STRENGTH_STRONGER;
gpio_init(GPIOA, &gpio_init_struct);
```

5.11.3 gpio_default_para_init function

The table below describes the function gpio_default_para_init.

Table 289. gpio_default_para_init function

Name	Description
Function name	gpio_default_para_init
Function prototype	void gpio_default_para_init(gpio_init_type *gpio_init_struct);
Function description	Initialize GPIO default parameters
Input parameter	gpio_init_struct: gpio_init_type pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

The table below describes the default values of members of the gpio_init_struct.

Table 290. gpio_init_struct default values

Member	Default value
gpio_pins	GPIO_PINS_ALL
gpio_mode	GPIO_MODE_INPUT
gpio_out_type	GPIO_OUTPUT_PUSH_PULL
gpio_pull	GPIO_PULL_NONE
gpio_drive_strength	GPIO_DRIVE_STRENGTH_STRONGER

Example:

```
gpio_init_type gpio_init_struct;
gpio_default_para_init(&gpio_init_struct);
```

5.11.4 gpio_input_data_bit_read function

The table below describes the function gpio_input_data_bit_read.

Table 291. gpio_input_data_bit_read function

Name	Description
Function name	gpio_input_data_bit_read
Function prototype	flag_status gpio_input_data_bit_read(gpio_type *gpio_x, uint16_t pins);
Function description	Read GPIO input port pins
Input parameter 1	gpio_x: the selected GPIO peripheral This parameter can be GPIOA, GPIOB, GPIOC, GPIOF.
Input parameter 2	pins: indicates the GPIO pins; refer to gpio_pins for details.
Output parameter	NA
Return value	Return GPIO input pin status
Required preconditions	NA
Called functions	NA

Example:

```
gpio_input_data_bit_read(GPIOA, GPIO_PINS_0);
```

5.11.5 gpio_input_data_read function

The table below describes the function gpio_input_data_read.

Table 292. gpio_input_data_read function

Name	Description
Function name	gpio_input_data_read
Function prototype	uint16_t gpio_input_data_read(gpio_type *gpio_x);
Function description	Read GPIO input ports
Input parameter	gpio_x: the selected GPIO peripheral This parameter can be GPIOA, GPIOB, GPIOC, GPIOF.
Output parameter	NA
Return value	Return GPIO input port status
Required preconditions	NA
Called functions	NA

Example:

```
gpio_input_data_read(GPIOA);
```

5.11.6 gpio_output_data_bit_read function

The table below describes the function gpio_output_data_bit_read.

Table 293. gpio_output_data_bit_read function

Name	Description
Function name	gpio_output_data_bit_read
Function prototype	uint16_t gpio_output_data_bit_read(gpio_type *gpio_x);
Function description	Read GPIO output port pin
Input parameter 1	gpio_x: the selected GPIO peripheral This parameter can be GPIOA, GPIOB, GPIOC, GPIOF.
Input parameter 2	pins: indicates the GPIO pins; refer to gpio_pins for details.
Output parameter	NA
Return value	Return GPIO output pin status
Required preconditions	NA
Called functions	NA

Example:

```
gpio_output_data_bit_read(GPIOA, GPIO_PINS_0);
```

5.11.7 gpio_output_data_read function

The table below describes the function gpio_output_data_read.

Table 294. gpio_output_data_read function

Name	Description
Function name	gpio_output_data_read
Function prototype	uint16_t gpio_output_data_read(gpio_type *gpio_x);
Function description	Read GPIO output port
Input parameter	gpio_x: the selected GPIO peripheral This parameter can be GPIOA, GPIOB, GPIOC, GPIOF.
Output parameter	NA
Return value	Read GPIO output port status
Required preconditions	NA
Called functions	NA

Example:

```
gpio_output_data_read(GPIOA);
```

5.11.8 gpio_bits_set function

The table below describes the function gpio_bits_set.

Table 295. gpio_bits_set function

Name	Description
Function name	gpio_bits_set
Function prototype	void gpio_bits_set(gpio_type *gpio_x, uint16_t pins);
Function description	Set GPIO pins
Input parameter 1	gpio_x: the selected GPIO peripheral This parameter can be GPIOA, GPIOB, GPIOC, GPIOF.
Input parameter 2	pins: indicates the GPIO pins; refer to gpio_pins for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
gpio_bits_set(GPIOA, GPIO_PINS_0);
```

5.11.9 gpio_bits_reset function

The table below describes the function gpio_bits_reset.

Table 296. gpio_bits_reset function

Name	Description
Function name	gpio_bits_reset
Function prototype	void gpio_bits_reset(gpio_type *gpio_x, uint16_t pins);
Function description	Reset GPIO pins
Input parameter 1	gpio_x: the selected GPIO peripheral This parameter can be GPIOA, GPIOB, GPIOC, GPIOF.
Input parameter 2	pins: indicates the GPIO pins; refer to gpio_pins for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
gpio_bits_reset(GPIOA, GPIO_PINS_0);
```

5.11.10 gpio_bits_toggle function

The table below describes the function gpio_bits_toggle

Table 297. gpio_bits_toggle function

Name	Description
Function name	gpio_bits_toggle
Function prototype	void gpio_bits_toggle(gpio_type *gpio_x, uint16_t pins);
Function description	Toggle GPIO bits
Input parameter 1	gpio_x: the selected GPIO peripheral This parameter can be GPIOA, GPIOB, GPIOC, GPIOF.
Input parameter 2	pins: indicates the GPIO pins; refer to gpio_pins for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
gpio_bits_toggle (GPIOA, GPIO_PINS_0);
```

5.11.11 gpio_bits_write function

The table below describes the function gpio_bits_write.

Table 298. gpio_bits_write function

Name	Description
Function name	gpio_bits_write
Function prototype	void gpio_bits_write(gpio_type *gpio_x, uint16_t pins, confirm_state bit_state);
Function description	Write GPIO pins
Input parameter 1	gpio_x: the selected GPIO peripheral This parameter can be GPIOA, GPIOB, GPIOC, GPIOF.
Input parameter 2	pins: indicates the GPIO pins; refer to gpio_pins for details.
Input parameter 3	bit_state: indicates GPIO pin value to write This parameter can be 1 (TRUE) or 0 (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
gpio_bits_write(GPIOA, GPIO_PINS_0, TRUE);
```

5.11.12 gpio_port_write function

The table below describes the function gpio_port_write.

Table 299. gpio_port_write function

Name	Description
Function name	gpio_port_write
Function prototype	void gpio_port_write(gpio_type *gpio_x, uint16_t port_value);
Function description	Write GPIO ports
Input parameter 1	gpio_x: the selected GPIO peripheral This parameter can be GPIOA, GPIOB, GPIOC, GPIOF.
Input parameter 2	port_value: indicates the port value to write This parameter can be 0x0000~0xFFFF.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
gpio_port_write(GPIOA, 0xFFFF);
```

5.11.13 gpio_pin_wp_config function

The table below describes the function gpio_pin_wp_config.

Table 300. gpio_pin_wp_config function

Name	Description
Function name	gpio_pin_wp_config
Function prototype	void gpio_pin_wp_config(gpio_type *gpio_x, uint16_t pins);
Function description	Configure GPIO pin write protection
Input parameter 1	gpio_x: the selected GPIO peripheral This parameter can be GPIOA, GPIOB, GPIOC, GPIOF.
Input parameter 2	pins: indicates the GPIO pins; refer to gpio_pins for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
gpio_pin_wp_config(GPIOA, GPIO_PINS_0);
```

5.11.14 gpio_pins_huge_driven_config function

The table below describes the function gpio_pins_huge_driven_config.

Table 301. gpio_pins_huge_driven_config function

Name	Description
Function name	gpio_pins_huge_driven_config
Function prototype	void gpio_pins_huge_driven_config(gpio_type *gpio_x, uint16_t pins, confirm_state new_state);
Function description	Configure huge drive capability of GPIO pins
Input parameter 1	gpio_x: the selected GPIO peripheral This parameter can be GPIOA, GPIOB, GPIOC, GPIOF.
Input parameter 2	pins: indicates the GPIO pins; refer to gpio_pins for details.
Input parameter 3	new_state: the status of to-be-configured huge current sourcing/sinking capability Enable (TRUE) or disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
gpio_pins_huge_driven_config(GPIOA, GPIO_PINS_0, TRUE);
```

5.11.15 gpio_pin_mux_config function

The table below describes the function gpio_pin_mux_config.

Table 302. gpio_pin_mux_config function

Name	Description
Function name	gpio_pin_mux_config
Function prototype	void gpio_pin_mux_config(gpio_type *gpio_x, gpio_pins_source_type gpio_pin_source, gpio_mux_sel_type gpio_mux);
Function description	Configure GPIO pin multiplexed function
Input parameter 1	gpio_x: the selected GPIO peripheral This parameter can be GPIOA, GPIOB, GPIOC, GPIOF.
Input parameter 2	gpio_pin_source: GPIO pin to be configured
Input parameter 3	gpio_mux: IOMUX index to be configured
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

gpio_pin_source

Set GPIO pins

GPIO_PINS_SOURCE0:	GPIO pin 0
GPIO_PINS_SOURCE1:	GPIO pin 1
GPIO_PINS_SOURCE2:	GPIO pin 2
GPIO_PINS_SOURCE3:	GPIO pin 3
GPIO_PINS_SOURCE4:	GPIO pin 4
GPIO_PINS_SOURCE5:	GPIO pin 5
GPIO_PINS_SOURCE6:	GPIO pin 6
GPIO_PINS_SOURCE7:	GPIO pin 7
GPIO_PINS_SOURCE8:	GPIO pin 8
GPIO_PINS_SOURCE9:	GPIO pin 9
GPIO_PINS_SOURCE10:	GPIO pin 10
GPIO_PINS_SOURCE11:	GPIO pin 11
GPIO_PINS_SOURCE12:	GPIO pin 12
GPIO_PINS_SOURCE13:	GPIO pin 13
GPIO_PINS_SOURCE14:	GPIO pin 14
GPIO_PINS_SOURCE15:	GPIO pin 15

gpio_mux

Select IOMUX index

GPIO_MUX_0	GPIO_MUX_1
GPIO_MUX_2	GPIO_MUX_3
GPIO_MUX_4	GPIO_MUX_5
GPIO_MUX_6	GPIO_MUX_7

Example:

```
gpio_pin_mux_config(GPIOA, GPIO_PINS_SOURCE0, GPIO_MUX_0);
```

5.12 I²C interface

The I²C register structure i2c_type is defined in the “at32f422_426_i2c.h”.

```
/*
 * @brief type define i2c register all
 */
typedef struct
{
    } i2c_type;
```

The table below gives a list of the I²C registers.

Table 303. Summary of I²C registers

Register	Description
ctrl1	I ² C control register 1
ctrl2	I ² C control register 2
oaddr1	I ² C own address register 1
oaddr2	I ² C own address register 2
dt	I ² C data register
sts1	I ² C status register 1
sts2	I ² C status register 2
clkctrl	I ² C clock control register
tmrise	I ² C rise time register

The table below gives a list of I²C library functions.

Table 304. Summary of I²C library functions

Function name	Description
i2c_reset	I ² C peripheral reset
i2c_software_reset	I ² C software reset
i2c_init	Set I ² C bus speed
i2c_own_address1_set	Set I ² C own address 1
i2c_own_address2_set	Set I ² C own address 2
i2c_own_address2_enable	Enable I ² C own address 2
i2c_smbus_enable	Enable Smbus mode
i2c_enable	Enable I ² C
i2c_fast_mode_duty_set	Set fast mode duty cycle
i2c_clock_stretch_enable	Enable clock stretching capability
i2c_ack_enable	Enable ACK response
i2c_master_receive_ack_set	Set master receive mode ACK response
i2c_pec_position_set	Set PEC location in Smbus mod and master receive mode
i2c_general_call_enable	Enable general call (broadcast address enable)
i2c_arp_mode_enable	Enable SMBus ARP address
i2c_smbus_mode_set	SMBus device mode selection

i2c_smbus_alert_set	Set SMBus alert pin level
i2c_pec_transmit_enable	Enable PEC transmit
i2c_pec_calculate_enable	Enable PEC calculation
i2c_pec_value_get	Get current PEC value
i2c_dma_end_transfer_set	DMA transfer end indication
i2c_dma_enable	Enable DMA transfer
i2c_interrupt_enable	Enable I ² C interrupts
i2c_start_generate	Generate Start condition
i2c_stop_generate	Generate Stop condition
i2c_7bit_address_send	Send 7-bit slave address
i2c_data_send	Send data
i2c_data_receive	Receive data
i2c_flag_get	Get flag
i2c_flag_clear	Clear flag
i2c_digital_filter_value_set	Set digital filter value

Table 305. I²C application-layer library functions

Function name	Description
i2c_config	I ² C application initialization
i2c_lowlevel_init	I ² C low-layer initialization
i2c_wait_end	I ² C wait data transmit complete
i2c_wait_flag	I ² C wait flag
i2c_master_transmit	I ² C master transmits data (polling mode)
i2c_master_receive	I ² C master receives data (polling mode)
i2c_slave_transmit	I ² C slave transmits data (polling mode)
i2c_slave_receive	I ² C slave receives data (polling mode)
i2c_master_transmit_int	I ² C master transmits data (interrupt mode)
i2c_master_receive_int	I ² C master receives data (interrupt mode)
i2c_slave_transmit_int	I ² C slave transmits data (interrupt mode)
i2c_slave_receive_int	I ² C slave receives data (interrupt mode)
i2c_master_transmit_dma	I ² C master transmits data (DMA mode)
i2c_master_receive_dma	I ² C master receives data (DMA mode)
i2c_slave_transmit_dma	I ² C slave transmits data (DMA mode)
i2c_slave_receive_dma	I ² C slave receives data (DMA mode)
i2c_memory_write	I ² C writes data to EEPROM (polling mode)
i2c_memory_write_int	I ² C writes data to EEPROM (interrupt mode)
i2c_memory_write_dma	I ² C writes data to EEPROM (DMA mode)
i2c_memory_read	I ² C reads from EEPROM (polling mode)
i2c_memory_read_int	I ² C reads from EEPROM (interrupt mode)
i2c_memory_read_dma	I ² C reads from EEPROM (DMA mode)
i2c_evt_irq_handler	I ² C event interrupt function
i2c_err_irq_handler	I ² C error interrupt function
i2c_dma_tx_irq_handler	I ² C DMA Tx interrupt function
i2c_dma_rx_irq_handler	I ² C DMA Rx interrupt function

5.12.1 i2c_reset function

The table below describes the function i2c_reset.

Table 306. i2c_reset function

Name	Description
Function name	i2c_reset
Function prototype	void i2c_reset(i2c_type *i2c_x)
Function description	Reset all I ² C registers to their initial values through CRM (Clock and reset management)
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	void crm_periph_reset(crm_periph_reset_type value, confirm_state new_state);

Example:

```
i2c_reset(I2C1);
```

5.12.2 i2c_software_reset function

The table below describes the function i2c_software_reset.

Table 307. i2c_software_reset function

Name	Description
Function name	i2c_software_reset
Function prototype	void i2c_software_reset(i2c_type *i2c_x, confirm_state new_state);
Function description	Reset I ² C by software, like the function i2c_reset(i2c_type *i2c_x)
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	new_state: indicates software reset status This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
i2c_software_reset(I2C1, TRUE);
i2c_software_reset(I2C1, FALSE);
```

5.12.3 i2c_init function

The table below describes the function i2c_init.

Table 308. i2c_init function

Name	Description
Function name	i2c_init
Function prototype	void i2c_init(i2c_type *i2c_x, i2c_fsmode_duty_cycle_type duty, uint32_t speed);
Function description	Set I ² C bus speed and duty cycle in fast mode
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	duty: SCL bus duty cycle in fast mode Refer to the "duty" description below for details.
Input parameter 3	speed: bus speed in Hz
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

duty

SCL duty cycle in fast mode ($\geq 400\text{kHz}$)

I2C_FSMODE_DUTY_2_1: SCL duty cycle is 2: 1

I2C_FSMODE_DUTY_16_9: SCL duty cycle is 16: 9

Example:

```
i2c_init(I2C1, I2C_FSMODE_DUTY_2_1, 100000);
```

5.12.4 i2c_own_address1_set function

The table below describes the function i2c_own_address1_set.

Table 309. i2c_own_address1_set function

Name	Description
Function name	i2c_own_address1_set
Function prototype	void i2c_own_address1_set(i2c_type *i2c_x, i2c_address_mode_type mode, uint16_t address);
Function description	Set own address 1
Input parameter 1	mode: Own address 1 address mode Refer to the "mode" description below for details.
Input parameter 2	address: own address 1
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

mode

Own address 1 address mode

I2C_ADDRESS_MODE_7BIT: 7-bit address

I2C_ADDRESS_MODE_10BIT: 10-bit address

Example:

i2c_own_address1_set(I2C1, I2C_ADDRESS_MODE_7BIT, 0xA0);
--

5.12.5 i2c_own_address2_set function

The table below describes the function i2c_own_address2_set.

Table 310. i2c_own_address2_set function

Name	Description
Function name	i2c_own_address2_set
Function prototype	void i2c_own_address2_set(i2c_type *i2c_x, uint8_t address);
Function description	Set own address 2. The address 2 becomes active only after it is enabled. Note: Only 7-bit address is supported, not 10-bit address mode.
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	address: own address 2
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

i2c_own_address2_set(I2C1, 0xB0);

5.12.6 i2c_own_address2_enable function

The table below describes the function i2c_own_address2_enable.

Table 311. i2c_own_address2_enable function

Name	Description
Function name	i2c_own_address2_enable
Function prototype	void i2c_own_address2_enable(i2c_type *i2c_x, confirm_state new_state);
Function description	Enable own address 2. The address becomes active only after it is enabled. Note that this function should be used in conjunction with the i2c_own_address2_set.
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	new_state: indicates address 2 status This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

i2c_own_address2_enable(I2C1, TRUE);

5.12.7 i2c_smbus_enable function

The table below describes the function i2c_smbus_enable.

Table 312. i2c_smbus_enable function

Name	Description
Function name	i2c_smbus_enable
Function prototype	void i2c_smbus_enable(i2c_type *i2c_x, confirm_state new_state);
Function description	Enable SMBus mode. After power-on reset, the default mode is I ² C mode.
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	new_state: indicates SMBus mode status This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
i2c_smbus_enable(I2C1, TRUE);
```

5.12.8 i2c_enable function

The table below describes the function i2c_enable.

Table 313. i2c_enable function

Name	Description
Function name	i2c_enable
Function prototype	void i2c_enable(i2c_type *i2c_x, confirm_state new_state);
Function description	Enable I ² C peripheral
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	new_state: indicates I ² C status This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
i2c_enable(I2C1, TRUE);
```

5.12.9 i2c_fast_mode_duty_set function

The table below describes the function i2c_fast_mode_duty_set.

Table 314. i2c_fast_mode_duty_set function

Name	Description
Function name	i2c_fast_mode_duty_set
Function prototype	void i2c_fast_mode_duty_set(i2c_type *i2c_x, i2c_fsmode_duty_cycle_type duty);
Function description	Configure the ratio of SCL low level to high level in fast mode. This function works in the same way of the duty parameter in the void i2c_init(i2c_type *i2c_x, i2c_fsmode_duty_cycle_type duty, uint32_t speed).
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	duty: indicates the duty cycle of SCL in fast mode. Refer to the “duty” description below for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

duty

SCL duty cycle in fast mode ($\geq 400\text{kHz}$)

I2C_FSMODE_DUTY_2_1: SCL duty cycle is 2: 1

I2C_FSMODE_DUTY_16_9: SCL duty cycle is 16: 9

Example:

```
i2c_fast_mode_duty_set(I2C1, I2C_FSMODE_DUTY_2_1);
```

5.12.10 i2c_clock_stretch_enable function

The table below describes the function i2c_clock_stretch_enable.

Table 315. i2c_clock_stretch_enable function

Name	Description
Function name	i2c_clock_stretch_enable
Function prototype	void i2c_clock_stretch_enable(i2c_type *i2c_x, confirm_state new_state);
Function description	Enable clock stretching capability. This function is applicable to slave mode only. In most cases, enabling the clock stretching mode is recommended in order to prevent slave from having no sufficient time to receive or send data due to slow process speed, which causes a loss of data. It should be noted that the host must be able to support clock stretching function before using this mode by slave. For example, some hosts based on IO analog are not equipped with the clock stretching capability.
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	new_state: indicates clock stretching status This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA

Name	Description
Required preconditions	NA
Called functions	NA

Example:

i2c_clock_stretch_enable(I2C1, TRUE);

5.12.11 i2c_ack_enable function

The table below describes the function i2c_ack_enable.

Table 316. i2c_ack_enable function

Name	Description
Function name	i2c_ack_enable
Function prototype	void i2c_ack_enable(i2c_type *i2c_x, confirm_state new_state);
Function description	Enable ACK and NACK. This function is used to enable ACK or NACK of each byte in master and slave mode. For ACK information on I ² C communication protocol, refer to I ² C protocol or AT32 reference manual.
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	new_state: ACK response status. This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

i2c_ack_enable(I2C1, TRUE);

5.12.12 i2c_master_receive_ack_set function

The table below describes the function i2c_master_receive_ack_set

Table 317. i2c_master_receive_ack_set function

Name	Description
Function name	i2c_master_receive_ack_set
Function prototype	void i2c_master_receive_ack_set(i2c_type *i2c_x, i2c_master_ack_type pos)
Function description	Enable master receive ACK response. This function is used in master receive mode to define the location where the function void i2c_ack_enable(i2c_type *i2c_x, confirm_state new_state) becomes active. The function is aimed at returning a correct NACK response while two bytes are received in master receive mode.
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	pos: indicates the location of ACKEN Refer to the "pos" description below for details.
Output parameter	NA
Return value	NA

Name	Description
Required preconditions	NA
Called functions	NA

pos

ACKEN valid position.

I2C_MASTER_ACK_CURRENT: ACKEN bit effective on the current byte being transferred

I2C_MASTER_ACK_NEXT: ACKEN bit effective on the next byte to be transferred

Example:

```
i2c_master_receive_ack_set(I2C1, TRUE);
```

5.12.13 i2c_pec_position_set function

The table below describes the function i2c_pec_position_set.

Table 318. i2c_pec_position_set function

Name	Description
Function name	i2c_pec_position_set
Function prototype	void i2c_pec_position_set(i2c_type *i2c_x, i2c_pec_position_type pos);
Function description	Set PEC location in SMBus and master receive mode. This function is used to receive PEC and return NACK when two bytes are received in master receive mode.
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	pos: PEC position. Refer to the “pos” description below for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

pos

ACKEN valid position.

I2C_PEC_POSITION_CURRENT: Current byte is PEC

I2C_PEC_POSITION_NEXT: Next byte is PEC

Example:

```
i2c_pec_position_set(I2C1, I2C_PEC_POSITION_CURRENT);
```

5.12.14 i2c_general_call_enable function

The table below describes the function i2c_general_call_enable.

Table 319. i2c_general_call_enable function

Name	Description
Function name	i2c_general_call_enable
Function prototype	void i2c_general_call_enable(i2c_type *i2c_x, confirm_state new_state);
Function description	Enable broadcast address. After enabled, broadcast address 0x00 is responded.
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	new_state: Broadcast address enable state This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

i2c_general_call_enable(I2C1, TRUE);

5.12.15 i2c_arp_mode_enable function

The table below describes the function i2c_arp_mode_enable.

Table 320. i2c_arp_mode_enable function

Name	Description
Function name	i2c_arp_mode_enable
Function prototype	void i2c_arp_mode_enable(i2c_type *i2c_x, confirm_state new_state);
Function description	Enable SMBus ARP In SMBus master mode: respond to master address 0001000x In SMBus device mode: respond to device default address 0001100x For more information on ARP, refer to SMBUS protocol.
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	new_state: indicates ARP address status This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

i2c_arp_mode_enable(I2C1, TRUE);

5.12.16 i2c_smbus_mode_set function

The table below describes the function i2c_smbus_mode_set.

Table 321. i2c_smbus_mode_set function

Name	Description
Function name	i2c_smbus_mode_set
Function prototype	void i2c_smbus_mode_set(i2c_type *i2c_x, i2c_smbus_mode_set_type mode);
Function description	Select SMBus device mode, including SMBus host or SMBus device
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	mode: SMBus device mode Refer to the “mode” description below for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

mode

SMBus device mode

I2C_SMBUS_MODE_DEVICE: SMBus device

I2C_SMBUS_MODE_HOST: SMBus host

Example:

```
i2c_smbus_mode_set(I2C1, I2C_SMBUS_MODE_HOST);
```

5.12.17 i2c_smbus_alert_set function

The table below describes the function i2c_smbus_alert_set.

Table 322. i2c_smbus_alert_set function

Name	Description
Function name	i2c_smbus_alert_set
Function prototype	void i2c_smbus_alert_set(i2c_type *i2c_x, i2c_smbus_alert_set_type level);
Function description	Set SMBus alert pin level (high or low)
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	level: SMBus alert pin level Refer to the following “level” descriptions for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

level

SMBus alert pin level

I2C_SMBUS_ALERT_LOW: SMBus alert pin output low

I2C_SMBUS_ALERT_HIGH: SMBus alert pin output high

Example:

```
i2c_smbus_alert_set(I2C1, I2C_SMBUS_ALERT_LOW);
```

5.12.18 i2c_pec_transmit_enable function

The table below describes the function i2c_pec_transmit_enable.

Table 323. i2c_pec_transmit_enable function

Name	Description
Function name	i2c_pec_transmit_enable
Function prototype	void i2c_pec_transmit_enable(i2c_type *i2c_x, confirm_state new_state);
Function description	PEC transmit enable (send/receive PEC)
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	new_state: PEC transmit enable state This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
i2c_pec_transmit_enable(I2C1, TRUE);
```

5.12.19 i2c_pec_calculate_enable function

The table below describes the function i2c_pec_calculate_enable.

Table 324. i2c_pec_calculate_enable function

Name	Description
Function name	i2c_pec_calculate_enable
Function prototype	void i2c_pec_calculate_enable(i2c_type *i2c_x, confirm_state new_state);
Function description	Enable PEC calculation
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	new_state: PEC calculation state This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
i2c_pec_calculate_enable(I2C1, TRUE);
```

5.12.20 i2c_pec_value_get function

The table below describes the function i2c_pec_value_get.

Table 325. i2c_pec_value_get function

Name	Description
Function name	i2c_pec_value_get
Function prototype	uint8_t i2c_pec_value_get(i2c_type *i2c_x);
Function description	Get current PEC value
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Output parameter	uint8_t: current PEC value
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
Pec_value = i2c_pec_value_get(I2C1);
```

5.12.21 i2c_dma_end_transfer_set function

The table below describes the function i2c_dma_end_transfer_set.

Table 326. i2c_dma_end_transfer_set function

Name	Description
Function name	i2c_dma_end_transfer_set
Function prototype	void i2c_dma_end_transfer_set(i2c_type *i2c_x, confirm_state new_state);
Function description	Indicate DMA transfer complete, that is, indicating whether the last data is being sent or not.
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	new_state: indicates whether it is the last data being transferred or not. This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
i2c_dma_end_transfer_set(I2C1, TRUE);
```

5.12.22 i2c_dma_enable function

The table below describes the function i2c_dma_enable.

Table 327. i2c_dma_enable function

Name	Description
Function name	i2c_dma_enable
Function prototype	void i2c_dma_enable(i2c_type *i2c_x, confirm_state new_state);
Function description	DMA transfer enable
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	new_state: DMA enable state This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

i2c_dma_enable(I2C1, TRUE);

5.12.23 i2c_interrupt_enable function

The table below describes the function i2c_interrupt_enable.

Table 328. i2c_interrupt_enable function

Name	Description
Function name	i2c_interrupt_enable
Function prototype	void i2c_interrupt_enable(i2c_type *i2c_x, uint16_t source, confirm_state new_state)
Function description	I ² C interrupt enable
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	source: interrupt sources Refer to the following "source" descriptions for details.
Input parameter 3	new_state: interrupt enable state This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

source

Interrupt source

I2C_DATA_INT: Data interrupt

I2C_EV_INT: Event interrupt

I2C_ERR_INT: Error interrupt

Example:

i2c_interrupt_enable(I2C1, I2C_DATA_INT, TRUE);

5.12.24 i2c_start_generate function

The table below describes the function i2c_start_generate.

Table 329. i2c_start_generate function

Name	Description
Function name	i2c_start_generate
Function prototype	void i2c_start_generate(i2c_type *i2c_X);
Function description	Generate a START condition (for master)
Input parameter 1	i2c_X: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
i2c_start_generate(I2C1);
```

5.12.25 i2c_stop_generate function

The table below describes the function i2c_stop_generate.

Table 330. i2c_stop_generate function

Name	Description
Function name	i2c_stop_generate
Function prototype	void i2c_stop_generate(i2c_type *i2c_X);
Function description	Generate a STOP condition
Input parameter 1	i2c_X: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
i2c_stop_generate(I2C1);
```

5.12.26 i2c_7bit_address_send function

The table below describes the function i2c_7bit_address_send.

Table 331. i2c_7bit_address_send function

Name	Description
Function name	i2c_7bit_address_send
Function prototype	void i2c_7bit_address_send(i2c_type *i2c_x, uint8_t address, i2c_direction_type direction);
Function description	Send 7-bit slave address (for host)
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	address: slave address
Input parameter 3	direction: data transfer direction Refer to the “direction” description below for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

direction

Data transfer direction

I2C_DIRECTION_TRANSMIT: Master transmit

I2C_DIRECTION_RECEIVE: Master receive

Example:

```
i2c_7bit_address_send(I2C1, 0xB0, I2C_DIRECTION_TRANSMIT);
```

5.12.27 i2c_data_send function

The table below describes the function i2c_data_send.

Table 332. i2c_data_send function

Name	Description
Function name	i2c_data_send
Function prototype	void i2c_data_send(i2c_type *i2c_x, uint8_t data);
Function description	Send data
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	data: data to be sent
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
i2c_data_send(I2C1, 0x55);
```

5.12.28 i2c_data_receive function

The table below describes the function i2c_data_receive.

Table 333. i2c_data_receive function

Name	Description
Function name	i2c_data_receive
Function prototype	uint8_t i2c_data_receive(i2c_type *i2c_x);
Function description	Receive data
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Output parameter	uint8_t: data to be received
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
data_value = i2c_data_receive(I2C1);
```

5.12.29 i2c_flag_get function

The table below describes the function i2c_flag_get.

Table 334. i2c_flag_get function

Name	Description
Function name	i2c_flag_get
Function prototype	flag_status i2c_flag_get(i2c_type *i2c_x, uint32_t flag);
Function description	Get flag status
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	flag: the selected flag Refer to the following "flag" descriptions for details.
Output parameter	NA
Return value	flag_status: flag status This parameter can be SET or RESET.
Required preconditions	NA
Called functions	NA

flag

This bit is used to select a flag to get its status. Optional parameters are below:

I2C_STARTF_FLAG:	Start condition ready flag
I2C_ADDR7F_FLAG:	0~7 bit address match flag
I2C_TDC_FLAG:	Data transfer complete flag
I2C_ADDRHF_FLAG:	9~8 bit address head match flag (host)
I2C_STOPF_FLAG:	Stop condition generation complete flag
I2C_RDBF_FLAG:	Receive data buffer full flag
I2C_TDBE_FLAG:	Transmit data buffer empty flag
I2C_BUSERR_FLAG:	Bus error flag
I2C_ARLOST_FLAG:	Arbitration lost flag

I2C_ACKFAIL_FLAG:	Acknowledge failure flag
I2C_OUF_FLAG:	Overflow or underflow flag
I2C_PECERR_FLAG:	PEC receive error flag
I2C_TMOUT_FLAG:	SMBus timeout flag
I2C_ALERTF_FLAG:	SMBus alert flag
I2C_TRMODE_FLAG:	Transfer mode
I2C_BUSYF_FLAG:	Bus busy flag
I2C_DIRF_FLAG:	Transmission direction flag
I2C_GCADDRF_FLAG:	General call address reception flag
I2C_DEVADDRF_FLAG:	SMBus device address reception flag
I2C_HOSTADDRF_FLAG:	SMBus host address reception flag
I2C_ADDR2_FLAG:	Received address 2 flag

Example:

```
i2c_flag_get(I2C1, I2C_STARTF_FLAG);
```

5.12.30 i2c_interrupt_flag_get function

The table below describes the function i2c_interrupt_flag_get.

Table 335. i2c_interrupt_flag_get function

Name	Description
Function name	i2c_interrupt_flag_get
Function prototype	flag_status i2c_interrupt_flag_get(i2c_type *i2c_x, uint32_t flag);
Function description	Get interrupt flag status, and check the corresponding interrupt enable bit
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	flag: the selected flag Refer to the following "flag" descriptions for details.
Output parameter	NA
Return value	flag_status: flag status This parameter can be SET or RESET.
Required preconditions	NA
Called functions	NA

flag

This bit is used to select a flag, including:

I2C_STARTF_FLAG:	Start condition ready flag
I2C_ADDR7F_FLAG:	0~7 bit address match flag
I2C_TDC_FLAG:	Data transfer complete flag
I2C_ADDRHF_FLAG:	9~8 bit address head match flag (host)
I2C_STOPF_FLAG:	Stop condition generation complete flag
I2C_RDBF_FLAG:	Receive data buffer full flag
I2C_TDBE_FLAG:	Transmit data buffer empty flag
I2C_BUSERR_FLAG:	Bus error flag
I2C_ARLOST_FLAG:	Arbitration lost flag
I2C_ACKFAIL_FLAG:	Acknowledge failure flag
I2C_OUF_FLAG:	Overflow or underflow flag
I2C_PECERR_FLAG:	PEC receive error flag

- I2C_TMOUT_FLAG: SMBus timeout flag
I2C_ALERTF_FLAG: SMBus alert flag

Example:

```
i2c_interrupt_flag_get(I2C1, I2C_STARTF_FLAG);
```

5.12.31 i2c_flag_clear function

The table below describes the function i2c_flag_clear.

Table 336. i2c_flag_clear function

Name	Description
Function name	i2c_flag_clear
Function prototype	void i2c_flag_clear(i2c_type *i2c_x, uint32_t flag);
Function description	Clear flag
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	flag: the selected flag Refer to the following "flag" descriptions for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

flag

This bit is used to select a flag, including:

- I2C_BUSERR_FLAG: Bus error flag
I2C_ARLOST_FLAG: Arbitration lost flag
I2C_ACKFAIL_FLAG: Acknowledge failure flag
I2C_OUF_FLAG: Overflow or underflow flag
I2C_PECERR_FLAG: PEC receive error flag
I2C_TMOUT_FLAG: SMBus timeout flag
I2C_ALERTF_FLAG: SMBus alert flag
I2C_ADDR7F_FLAG: 0~7 bit address match flag
I2C_STOPF_FLAG: Stop condition generation complete flag

Example:

```
i2c_flag_clear(I2C1, I2C_ACKFAIL_FLAG);
```

5.12.32 i2c_digital_filter_value_set function

The table below describes the function i2c_digital_filter_value_set.

Table 337. i2c_digital_filter_value_set function

Name	Description
Function name	i2c_digital_filter_value_set
Function prototype	void i2c_digital_filter_value_set(i2c_type *i2c_x, uint8_t dfilters);
Function description	Set digital filter value
Input parameter 1	i2c_x: indicates the selected I ² C peripheral This parameter can be I ² C1 or I ² C2.
Input parameter 2	dfilters: digital filter value, range 0x00~0x0F
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
i2c_digital_filter_value_set(I2C1, 0x0F);
```

5.12.33 i2c_config function

The table below describes the function i2c_config.

Table 338. i2c_config function

Name	Description
Function name	i2c_config
Function prototype	void i2c_config(i2c_handle_type* hi2c);
Function description	I ² C initialization function used to initialize I ² C. Call the function i2c_lowlevel_init() to initialize I ² C peripherals, GPIO, DMA, interrupts and others.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	void i2c_lowlevel_init(i2c_handle_type* hi2c);

i2c_handle_type* hi2c

The i2c_handle_type is defined in the “i2c_application.h”.

typedef struct

```
{
    i2c_type          *i2cx;
    uint8_t            *pbuf;
    __IO uint16_t      pcount;
    __IO uint32_t      mode;
    __IO uint32_t      timeout;
    __IO uint32_t      status;
    __IO i2c_status_type error_code;
    dma_channel_type   *dma_tx_channel;
```

```
dma_channel_type      *dma_rx_channel;
dma_init_type         dma_init_struct;
}i2c_handle_type;
```

i2cx

Select an I²C peripheral from I²C1 and I²C2.

pbuff

An array of data to be sent or received.

pcount

The number of data to be sent or received.

mode

I²C communication mode. It is used in internal state machine. Users don't care.

timeout

Communications timeout

status

Transfer status. It is used in internal state machine. Users don't care.

error_code

This bit is used to enumerate error code in the i2c_status_type. When a communication error occurred, it logs the corresponding error code.

I2C_OK:	Communication OK
I2C_ERR_STEP_1:	Step 1 error
I2C_ERR_STEP_2:	Step 2 error
I2C_ERR_STEP_3:	Step 3 error
I2C_ERR_STEP_4:	Step 4 error
I2C_ERR_STEP_5:	Step 5 error
I2C_ERR_STEP_6:	Step 6 error
I2C_ERR_STEP_7:	Step 7 error
I2C_ERR_STEP_8:	Step 8 error
I2C_ERR_STEP_9:	Step 9 error
I2C_ERR_STEP_10:	Step 10 error
I2C_ERR_STEP_11:	Step 11 error
I2C_ERR_STEP_12:	Step 12 error
I2C_ERR_START:	START condition error
I2C_ERR_ADDR10:	10-bit address header (bit 9~8) error
I2C_ERR_ADDR:	Address send error
I2C_ERR_STOP:	STOP condition send error
I2C_ERR_ACKFAIL:	Acknowledge error
I2C_ERR_TIMEOUT:	Timeout error
I2C_ERR_INTERRUPT:	Enter an interrupt when an error event occurs

dma_tx_channel

I²C transmit DMA channel

dma_rx_channel

I²C receive DMA channel

dma_init_struct

DMA initialization structure

Example:

```
i2c_handle_type hi2c;  
hi2c.i2cx = I2C1;  
i2c_config(&hi2c);
```

5.12.34 i2c_lowlevel_init function

The table below describes the function `i2c_lowlevel_init`.

Table 339. `i2c_lowlevel_init` function

Name	Description
Function name	<code>i2c_lowlevel_init</code>
Function prototype	<code>void i2c_lowlevel_init(i2c_handle_type* hi2c);</code>
Function description	I ² C lower-level initialization callback function. It is called in the <code>i2c_config</code> to initialize I ² C peripherals, GPIO, DMA, interrupts, etc. It requires users to implement I ² C initialization inside the function.
Input parameter 1	hi2c: <code>i2c_handle_type</code> pointer Refer to i2c_handle_type for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
void i2c_lowlevel_init(i2c_handle_type* hi2c)  
{  
    if(hi2c->i2cx == I2C1)  
    {  
        Implement I2C1 initialization  
    }  
    else if(hi2c->i2cx == I2C2)  
    {  
        Implement I2C2 initialization  
    }  
}
```

5.12.35 i2c_wait_end function

The table below describes the function i2c_wait_end.

Table 340. i2c_wait_end function

Name	Description
Function name	i2c_wait_end
Function prototype	i2c_status_type i2c_wait_end(i2c_handle_type* hi2c, uint32_t timeout);
Function description	Wait for the end of communications. This function is used in DMA and interrupt transfer modes as they are non-blocking functions and can thus be used to wait for the end of transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

Example:

```
if (i2c_master_transmit_dma(&hi2c, 0xB0, tx_buf, 8, 0xFFFFFFFF) != I2C_OK)
{
    error_handler(i2c_status);
}

/* wait for the end of transfer */
if(i2c_wait_end(&hi2c, 0xFFFFFFFF) != I2C_OK)
{
    error_handler(i2c_status);
}
```

5.12.36 i2c_wait_flag function

The table below describes the function i2c_wait_flag.

Table 341. i2c_wait_flag function

Name	Description
Function name	i2c_wait_flag
Function prototype	i2c_status_type i2c_wait_flag(i2c_handle_type* hi2c, uint32_t flag, uint32_t event_check, uint32_t timeout)
Function description	Wait for a flag to be set or reset Only BUSFY flag is “wait for a flag to be reset”, and others are “wait for a flag to be set”.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	Flag: the selected flag Refer to the following “flag” descriptions for details.
Input parameter 3	event_check: check if the event has occurred or not while waiting for a flag Refer to the “event_check” descriptions below for details.
Input parameter 4	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

flag

Select a flag to wait for.

I2C_STARTF_FLAG:	Start condition ready flag
I2C_ADDR7F_FLAG:	0~7 bit address match flag
I2C_TDC_FLAG:	Data transfer complete flag
I2C_ADDRHF_FLAG:	9~8 bit address head match flag (host)
I2C_STOPF_FLAG:	Stop condition generation complete flag
I2C_RDBF_FLAG:	Receive data buffer full flag
I2C_TDBE_FLAG:	Transmit data buffer empty flag
I2C_BUSERR_FLAG:	Bus error flag
I2C_ARLOST_FLAG:	Arbitration lost flag
I2C_ACKFAIL_FLAG:	Acknowledge failure flag
I2C_OUF_FLAG:	Overflow or underflow flag
I2C_PECERR_FLAG:	PEC receive error flag
I2C_TMOUT_FLAG:	SMBus timeout flag
I2C_ALERTF_FLAG:	SMBus alert flag
I2C_TRMODE_FLAG:	Transfer mode
I2C_BUSYF_FLAG:	Bus busy flag
I2C_DIRF_FLAG:	Transmission direction flag
I2C_GCADDRF_FLAG:	General call address reception flag
I2C_DEVADDRF_FLAG:	SMBus device address reception flag
I2C_HOSTADDRF_FLAG:	SMBus host address reception flag
I2C_ADDR2_FLAG:	Received address 2 flag

event_check

Check if the event has occurred or not while waiting for a flag.

I2C_EVENT_CHECK_NONE: None

I2C_EVENT_CHECK_ACKFAIL: Check for ACKFAIL event

I2C_EVENT_CHECK_STOP: Check for STOP event

Example:

```
i2c_wait_flag(&hi2c, I2C_BUSYF_FLAG, I2C_EVENT_CHECK_NONE, 0xFFFFFFFF);
```

5.12.37 i2c_master_transmit function

The table below describes the function i2c_master_transmit.

Table 342. i2c_master_transmit function

Name	Description
Function name	i2c_master_transmit
Function prototype	i2c_status_type i2c_master_transmit(i2c_handle_type* hi2c, uint16_t address, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Master sends data (polling mode). This is a blocking function, and so I ² C transfer ends after the function is executed.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	address: slave address
Input parameter 3	pdata: array address of to-be-sent data
Input parameter 4	size: the size of data to be sent
Input parameter 5	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

Example:

```
i2c_master_transmit(&hi2c, 0xB0, tx_buf, 8, 0xFFFFFFFF);
```

5.12.38 i2c_master_receive function

The table below describes the function i2c_master_receive.

Table 343. i2c_master_receive function

Name	Description
Function name	i2c_master_receive
Function prototype	i2c_status_type i2c_master_receive(i2c_handle_type* hi2c, uint16_t address, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Master receives data (polling mode). This function is a blocking type. After the execution is done, so does I ² C transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	address: slave address
Input parameter 3	pdata: array address to receive data
Input parameter 4	size: number of data to receive
Input parameter 5	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

Example:

```
i2c_master_receive(&hi2c, 0xB0, rx_buf, 8, 0xFFFFFFFF);
```

5.12.39 i2c_slave_transmit function

The table below describes the function i2c_slave_transmit.

Table 344. i2c_slave_transmit function

Name	Description
Function name	i2c_slave_transmit
Function prototype	i2c_status_type i2c_slave_transmit(i2c_handle_type* hi2c, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Slave sends data (polling mode). This function is a blocking type. In other words, after the function execution is done, so is I ² C transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	pdata: array address of data to be sent
Input parameter 3	size: number of data to be sent
Input parameter 4	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

Example:

```
i2c_slave_transmit(&hi2c, tx_buf, 8, 0xFFFFFFFF);
```

5.12.40 i2c_slave_receive function

The table below describes the function i2c_slave_receive.

Table 345. i2c_slave_receive function

Name	Description
Function name	i2c_slave_receive
Function prototype	i2c_status_type i2c_slave_receive(i2c_handle_type* hi2c, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Slave receives data (polling mode). This function is a blocking type. In other words, after the function execution is done, so is I ² C transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	pdata: array address to receive data
Input parameter 3	size: number of data to be received
Input parameter 4	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

Example:

```
i2c_slave_receive(&hi2c, rx_buf, 8, 0xFFFFFFFF);
```

5.12.41 i2c_master_transmit_int function

The table below describes the function i2c_master_transmit_int.

Table 346. i2c_master_transmit_int function

Name	Description
Function name	i2c_master_transmit_int
Function prototype	i2c_status_type i2c_master_transmit_int(i2c_handle_type* hi2c, uint16_t address, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Master sends data (interrupt mode). This function is a non-blocking type. In other words, after the function execution is done, I ² C transfer has not completed yet. In this case, it is possible to call the i2c_wait_end() to wait for the completion of communication.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	address: slave address
Input parameter 3	pdata: array address of data to be sent
Input parameter 4	size: number of data to be sent
Input parameter 5	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

Example:

```
i2c_master_transmit_int(&hi2c, 0xB0, tx_buf, 8, 0xFFFFFFFF);
```

5.12.42 i2c_master_receive_int function

The table below describes the function i2c_master_receive_int.

Table 347. i2c_master_receive_int function

Name	Description
Function name	i2c_master_receive_int
Function prototype	i2c_status_type i2c_master_receive_int(i2c_handle_type* hi2c, uint16_t address, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Master receives data (through interrupt mode). This function is a non-blocking type. In other words, after the function is executed, the I ² C transfer has not completed yet. So in this case, it is possible to call the i2c_wait_end() to wait for the end of transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	address: slave address
Input parameter 3	pdata: array address to receive data
Input parameter 4	size: number of data to be received
Input parameter 5	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

Example:

```
i2c_master_receive_int(&hi2c, 0xB0, rx_buf, 8, 0xFFFFFFFF);
```

5.12.43 i2c_slave_transmit_int function

The table below describes the function i2c_slave_transmit_int.

Table 348. i2c_slave_transmit_int function

Name	Description
Function name	i2c_slave_transmit_int
Function prototype	i2c_status_type i2c_slave_transmit_int(i2c_handle_type* hi2c, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Slave sends data (through interrupt mode). This function operates in non-blocking mode. In other words, after the function is executed, the I ² C transfer has not completed yet. So in this case, it is possible to call the i2c_wait_end() to wait for the end of transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	pdata: array address of data to be sent
Input parameter 3	size: number of data to be sent
Input parameter 4	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

Example:

```
i2c_slave_transmit_int(&hi2c, tx_buf, 8, 0xFFFFFFFF);
```

5.12.44 i2c_slave_receive_int function

The table below describes the function i2c_slave_receive_int.

Table 349. i2c_slave_receive_int function

Name	Description
Function name	i2c_slave_receive_int
Function prototype	i2c_status_type i2c_slave_receive_int(i2c_handle_type* hi2c, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Slave receives data (through interrupt mode). This function is a non-blocking type. In other words, after the function is executed, the I ² C transfer has not completed yet. So in this case, it is possible to call the i2c_wait_end() to wait for the end of transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	pdata: array address to receive data
Input parameter 3	size: number of data to be received
Input parameter 4	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

Example:

```
i2c_slave_receive_int(&hi2c, rx_buf, 8, 0xFFFFFFFF);
```

5.12.45 i2c_master_transmit_dma function

The table below describes the function i2c_master_transmit_dma.

Table 350. i2c_master_transmit_dma function

Name	Description
Function name	i2c_master_transmit_dma
Function prototype	i2c_status_type i2c_master_transmit_dma(i2c_handle_type* hi2c, uint16_t address, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Master sends data (through DMA mode). This function is a non-blocking type. In other words, after the function is executed, the I ² C transfer has not completed yet. So in this case, it is possible to call the i2c_wait_end() to wait for the end of transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	address: slave address
Input parameter 3	pdata: array address of data to be sent
Input parameter 4	size: number of data to be sent
Input parameter 5	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

Example:

```
i2c_master_transmit_dma(&hi2c, 0xB0, tx_buf, 8, 0xFFFFFFFF);
```

5.12.46 i2c_master_receive_dma function

The table below describes the function i2c_master_receive_dma.

Table 351. i2c_master_receive_dma function

Name	Description
Function name	i2c_master_receive_dma
Function prototype	i2c_status_type i2c_master_receive_dma(i2c_handle_type* hi2c, uint16_t address, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Master receives data (through DMA mode). This function is a non-blocking type. In other words, after the function is executed, the I ² C transfer has not completed yet. So in this case, it is possible to call the i2c_wait_end() to wait for the end of transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	address: slave address
Input parameter 3	pdata: array address to receive data
Input parameter 4	size: number of data to be received
Input parameter 5	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

Example:

```
i2c_master_receive_dma(&hi2c, 0xB0, rx_buf, 8, 0xFFFFFFFF);
```

5.12.47 i2c_slave_transmit_dma function

The table below describes the function i2c_slave_transmit_dma.

Table 352. i2c_slave_transmit_dma function

Name	Description
Function name	i2c_slave_transmit_dma
Function prototype	i2c_status_type i2c_slave_transmit_dma(i2c_handle_type* hi2c, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Slave sends data (through DMA mode). This function is a non-blocking type. In other words, after the function is executed, the I ² C transfer has not completed yet. So in this case, it is possible to call the i2c_wait_end() to wait for the end of transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	pdata: array address of data to be sent
Input parameter 3	size: number of data to be sent
Input parameter 4	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

Example:

```
i2c_slave_transmit_dma(&hi2c, tx_buf, 8, 0xFFFFFFFF);
```

5.12.48 i2c_slave_receive_dma function

The table below describes the function i2c_slave_receive_dma.

Table 353. i2c_slave_receive_dma function

Name	Description
Function name	i2c_slave_receive_dma
Function prototype	i2c_status_type i2c_slave_receive_dma(i2c_handle_type* hi2c, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Slave receives data (through DMA mode). This function is a non-blocking type. In other words, after the function is executed, the I ² C transfer has not completed yet. So in this case, it is possible to call the i2c_wait_end() to wait for the end of transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	pdata: array address to receive data
Input parameter 3	size: number of data to be received
Input parameter 4	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.

Name	Description
Required preconditions	NA
Called functions	NA

Example:

```
i2c_slave_receive_dma(&hi2c, rx_buf, 8, 0xFFFFFFFF);
```

5.12.49 i2c_memory_write function

The table below describes the function i2c_memory_write.

Table 354. i2c_memory_write function

Name	Description
Function name	i2c_memory_write
Function prototype	i2c_status_type i2c_memory_write(i2c_handle_type* hi2c, i2c_mem_address_width_type mem_address_width, uint16_t address, uint16_t mem_address, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Write data to EEPROM (through polling mode). This function is a blocking type. In other words, after the function execution is done, so does I ² C transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	mem_address_width: EEPROM memory address width Refer to the “mem_address_width” below for details.
Input parameter 3	address: EEPROM address
Input parameter 4	mem_address: EEPROM data memory address
Input parameter 5	pdata: array address of data to be sent
Input parameter 6	size: number of data to be sent
Input parameter 7	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

mem_address_width

EEPROM memory address width

I2C_MEM_ADDR_WIDIH_8: 8-bit address width

I2C_MEM_ADDR_WIDIH_16: 16-bit address width

Example:

```
i2c_memory_write(&hi2c, 0xA0, 0x05, tx_buf, 8, 0xFFFFFFFF);
```

5.12.50 i2c_memory_write_int function

The table below describes the function i2c_memory_write_int.

Table 355. i2c_memory_write_int function

Name	Description
Function name	i2c_memory_write_int
Function prototype	i2c_status_type i2c_memory_write_int(i2c_handle_type* hi2c, i2c_mem_address_width_type mem_address_width, uint16_t address, uint16_t mem_address, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Write EEPROM (through interrupt mode). This function is a non-blocking type. In other words, after the function is executed, the I ² C transfer has not completed yet. So in this case, it is possible to call the i2c_wait_end() to wait for the end of transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	mem_address_width: EEPROM memory address width Refer to "mem_address_width" below for details.
Input parameter 3	address: EEPROM address
Input parameter 4	mem_address: EEPROM data memory address
Input parameter 5	pdata: array address of data to be sent
Input parameter 6	size: number of data to be sent
Input parameter 7	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

mem_address_width

EEPROM memory address width

I2C_MEM_ADDR_WIDIH_8: 8-bit address width

I2C_MEM_ADDR_WIDIH_16: 16-bit address width

Example:

```
i2c_memory_write_int(&hi2c, 0xA0, 0x05, tx_buf, 8, 0xFFFFFFFF);
```

5.12.51 i2c_memory_write_dma function

The table below describes the function i2c_memory_write_dma.

Table 356. i2c_memory_write_dma function

Name	Description
Function name	i2c_memory_write_dma
Function prototype	i2c_status_type i2c_memory_write_dma(i2c_handle_type* hi2c, i2c_mem_address_width_type mem_address_width, uint16_t address, uint16_t mem_address, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Write EEPROM (through DMA mode). This function is a non-blocking type. In other words, after the function is executed, the I ² C transfer has not completed yet. So in this case, it is possible to call the i2c_wait_end() to wait for the end of transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	mem_address_width: EEPROM memory address width Refer to the "mem_address_width" below for details.
Input parameter 3	address: EEPROM address
Input parameter 4	mem_address: EEPROM data memory address
Input parameter 5	pdata: array address of data to be sent
Input parameter 6	size: number of data to be sent
Input parameter 7	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

mem_address_width

EEPROM memory address width

I2C_MEM_ADDR_WIDIH_8: 8-bit address width

I2C_MEM_ADDR_WIDIH_16: 16-bit address width

Example:

```
i2c_memory_write_dma(&hi2c, 0xA0, 0x05, tx_buf, 8, 0xFFFFFFFF);
```

5.12.52 i2c_memory_read function

The table below describes the function i2c_memory_read.

Table 357. i2c_memory_read function

Name	Description
Function name	i2c_memory_read
Function prototype	i2c_status_type i2c_memory_read(i2c_handle_type* hi2c, i2c_mem_address_width_type mem_address_width, uint16_t address, uint16_t mem_address, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Read EEPROM (through polling mode). This function is a blocking type. In other words, after the function execution is done, so does I ² C data transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	mem_address_width: EEPROM memory address width Refer to the "mem_address_width" below for details.
Input parameter 3	address: EEPROM address
Input parameter 4	mem_address: EEPROM data memory address
Input parameter 5	pdata: array address of data to be read
Input parameter 6	size: number of data to be read
Input parameter 7	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

mem_address_width

EEPROM memory address width

I2C_MEM_ADDR_WIDIH_8: 8-bit address width

I2C_MEM_ADDR_WIDIH_16: 16-bit address width

Example:

```
i2c_memory_read(&hi2c, 0xA0, 0x05, rx_buf, 8, 0xFFFFFFFF);
```

5.12.53 i2c_memory_read_int function

The table below describes the function i2c_memory_read_int.

Table 358. i2c_memory_read_int function

Name	Description
Function name	i2c_memory_read_int
Function prototype	i2c_status_type i2c_memory_read_int(i2c_handle_type* hi2c, i2c_mem_address_width_type mem_address_width, uint16_t address, uint16_t mem_address, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Read EEPROM (through interrupt mode). This function is a non-blocking type. In other words, after the function is executed, the I ² C transfer has not completed yet. So in this case, it is possible to call the i2c_wait_end() to wait for the end of transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	mem_address_width: EEPROM memory address width Refer to the "mem_address_width" for details.
Input parameter 3	address: EEPROM address
Input parameter 4	mem_address: EEPROM data memory address
Input parameter 5	pdata: array address of data to be read
Input parameter 6	size: number of data to be read
Input parameter 7	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

mem_address_width

EEPROM memory address width

I2C_MEM_ADDR_WIDIH_8: 8-bit address width

I2C_MEM_ADDR_WIDIH_16: 16-bit address width

Example:

```
i2c_memory_read_int(&hi2c, 0xA0, 0x05, rx_buf, 8, 0xFFFFFFFF);
```

5.12.54 i2c_memory_read_dma function

The table below describes the function i2c_memory_read_dma.

Table 359. i2c_memory_read_dma function

Name	Description
Function name	i2c_memory_read_dma
Function prototype	i2c_status_type i2c_memory_read_dma(i2c_handle_type* hi2c, i2c_mem_address_width_type mem_address_width, uint16_t address, uint16_t mem_address, uint8_t* pdata, uint16_t size, uint32_t timeout);
Function description	Read EEPROM (through DMA mode). This function is a non-blocking type. In other words, after the function is executed, the I ² C transfer has not completed yet. So in this case, it is possible to call the i2c_wait_end() to wait for the end of transfer.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Input parameter 2	mem_address_width: EEPROM memory address width Refer to the "mem_address_width" for details.
Input parameter 3	address: EEPROM address
Input parameter 4	mem_address: EEPROM data memory address
Input parameter 5	pdata: array address of data to be read
Input parameter 6	size: number of data to be read
Input parameter 7	timeout: wait timeout
Output parameter	NA
Return value	i2c_status_type: error code Refer to 5.12.32 for details.
Required preconditions	NA
Called functions	NA

mem_address_width

EEPROM memory address width

I2C_MEM_ADDR_WIDIH_8: 8-bit address width

I2C_MEM_ADDR_WIDIH_16: 16-bit address width

Example:

```
i2c_memory_read_dma(&hi2c, 0xA0, 0x05, rx_buf, 8, 0xFFFFFFFF);
```

5.12.55 i2c_evt_irq_handler function

The table below describes the function i2c_evt_irq_handler.

Table 360. i2c_evt_irq_handler function

Name	Description
Function name	i2c_evt_irq_handler
Function prototype	void i2c_evt_irq_handler(i2c_handle_type* hi2c);
Function description	Event interrupt function. It is used to handle I ² C event interrupt.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
void I2C1_EVT_IRQHandler(void)
{
    i2c_evt_irq_handler(&hi2c);
}
```

5.12.56 i2c_err_irq_handler function

The table below describes the function i2c_err_irq_handler.

Table 361. i2c_err_irq_handler function

Name	Description
Function name	i2c_err_irq_handler
Function prototype	void i2c_err_irq_handler(i2c_handle_type* hi2c);
Function description	Error interrupt function. It is used to handle I ² C error interrupt.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
void I2C1_ERR_IRQHandler(void)
{
    i2c_err_irq_handler(&hi2c);
}
```

5.12.57 i2c_dma_tx_irq_handler function

The table below describes the function i2c_dma_tx_irq_handler.

Table 362. i2c_dma_tx_irq_handler function

Name	Description
Function name	i2c_dma_tx_irq_handler
Function prototype	void i2c_dma_tx_irq_handler(i2c_handle_type* hi2c);
Function description	DMA transmit interrupt function. It is used to handle DMA transmit interrupt.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
void DMA1_Channel6_IRQHandler(void)
{
    i2c_dma_rx_irq_handler(&hi2c);
}
```

5.12.58 i2c_dma_rx_irq_handler function

The table below describes the function i2c_dma_rx_irq_handler.

Table 363. i2c_dma_rx_irq_handler function

Name	Description
Function name	i2c_dma_rx_irq_handler
Function prototype	void i2c_dma_rx_irq_handler(i2c_handle_type* hi2c);
Function description	DMA receive interrupt function. It is used to handle DMA receive interrupt.
Input parameter 1	hi2c: i2c_handle_type pointer Refer to i2c_handle_type for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
void DMA1_Channel7_IRQHandler(void)
{
    i2c_dma_tx_irq_handler(&hi2c);
}
```

5.13 Nested vectored interrupt controller (NVIC)

The NVIC register structure NVIC_Type is defined in the “core_cm4.h”.

```
/*
 * @brief Structure type to access the Nested Vectored Interrupt Controller (NVIC).
 */
typedef struct
{
    .....
} NVIC_Type;
```

The table below gives a list of the NVIC registers.

Table 364. Summary of NVIC registers

Register	Description
iser	Interrupt enable set register
icer	Interrupt enable clear register
ispr	Interrupt suspend set register
icpr	Interrupt suspend clear register
iabr	Interrupt activate bit register
ip	Interrupt priority register
stir	Software trigger interrupt register

The table below gives a list of NVIC library functions.

Table 365. Summary of NVIC library functions

Function name	Description
nvic_system_reset	System software reset
nvic_irq_enable	NVIC interrupt enable and priority enable
nvic_irq_disable	NVIC interrupt disable
nvic_priority_group_config	NVIC interrupt priority grouping configuration
nvic_vector_table_set	NVIC interrupt vector table base address and offset address configuration
nvic_lowpower_mode_config	NVIC low-power mode configuration

5.13.1 nvic_system_reset function

The table below describes the function nvic_system_reset.

Table 366. nvic_system_reset function

Name	Description
Function name	nvic_system_reset
Function prototype	void nvic_system_reset(void)
Function description	System software reset
Input parameter	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NVIC_SystemReset()

Example:

```
/* system reset */
nvic_system_reset();
```

5.13.2 nvic_irq_enable function

The table below describes the function nvic_irq_enable.

Table 367. nvic_irq_enable function

Name	Description
Function name	nvic_irq_enable
Function prototype	void nvic_irq_enable(IRQn_Type irqn, uint32_t preempt_priority, uint32_t sub_priority)
Function description	NVIC interrupt enable and priority configuration
Input parameter 1	irqn: interrupt vector selection Refer to the irqn for details.
Input parameter 2	preempt_priority: set preemption priority This parameter must not be greater than the highest preemption priority defined in the NVIC_PRIORITY_GROUP_x.
Input parameter 3	sub_priority: set response priority This parameter must not be greater than the highest response priority defined in the NVIC_PRIORITY_GROUP_x.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NVIC_SetPriority() NVIC_EnableIRQ()

irqn

The irqn is used to select interrupt vectors, including:

WWDT IRQn: Window timer interrupt

PVM IRQn: PVM interrupt linked to EXINT

.....

I2C1_ERR IRQn: I²C1 error interrupt

I2C2_ERR_IRQn: I²C2 error interrupt

Example:

```
/* enable nvic irq */
nvic_irq_enable(ADC1_CMP_IRQn, 0, 0);
```

5.13.3 nvic_irq_disable function

The table below describes the function nvic_irq_disable.

Table 368. nvic_irq_disable function

Name	Description
Function name	nvic_irq_disable
Function prototype	void nvic_irq_disable(IRQn_Type irqn)
Function description	NVIC interrupt disable
Input parameter	irqn: select interrupt vector. Refer to irqn for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NVIC_DisableIRQ()

Example:

```
/* disable nvic irq */
nvic_irq_disable(ADC1_CMP_IRQn);
```

5.13.4 nvic_priority_group_config function

The table below describes the function nvic_priority_group_config.

Table 369. nvic_priority_group_config function

Name	Description
Function name	nvic_priority_group_config
Function prototype	void nvic_priority_group_config(nvic_priority_group_type priority_group)
Function description	NVIC interrupt priority grouping configuration
Input parameter	priority_group: select interrupt priority group This parameter can be any enumerated value in the nvic_priority_group_type.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NVIC_SetPriorityGrouping()

priority_group

priority_group is used to select priority group from the parameters below:

NVIC_PRIORITY_GROUP_0:

Priority group 0 (0 bit for preemption priority, and 4 bits for response priority)

NVIC_PRIORITY_GROUP_1:

Priority group 1 (1 bit for preemption priority, and 3 bits for response priority)

NVIC_PRIORITY_GROUP_2:

Priority group 2 (2 bits for preemption priority, and 2 bits for response priority)

NVIC_PRIORITY_GROUP_3:

Priority group 3 (3 bits for preemption priority, and 1 bit for response priority)

NVIC_PRIORITY_GROUP_4:

Priority group 4 (4 bits for preemption priority, and 0 bit for response priority)

Example:

```
/* config nvic priority group */  
nvic_priority_group_config(NVIC_PRIORITY_GROUP_4);
```

5.13.5 nvic_vector_table_set function

The table below describes the function nvic_vector_table_set.

Table 370. nvic_vector_table_set function

Name	Description
Function name	nvic_vector_table_set
Function prototype	void nvic_vector_table_set(uint32_t base, uint32_t offset)
Function description	Set NVIC interrupt vector table base address and offset address
Input parameter 1	base: base address of interrupt vector table The base address can be set in RAM or FLASH.
Input parameter 2	offset: offset address of interrupt vector table This parameter defines the start address of interrupt vector table, so it must be set to a multiple of 0x200.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

base

The base is used to select the base address of interrupt vector table, including:

NVIC_VECTTAB_RAM: Interrupt vector table base address is located in RAM

NVIC_VECTTAB_FLASH: Interrupt vector table base address is located in FLASH

Example:

```
/* config vector table offset */  
nvic_vector_table_set(NVIC_VECTTAB_FLASH, 0x4000);
```

5.13.6 nvic_lowpower_mode_config function

The table below describes the function nvic_lowpower_mode_config.

Table 371. nvic_lowpower_mode_config function

Name	Description
Function name	nvic_lowpower_mode_config
Function prototype	void nvic_lowpower_mode_config(nvic_lowpower_mode_type lp_mode, confirm_state new_state)
Function description	Configure NVIC low-power mode
Input parameter 1	lp_mode: select low-power modes This parameter can be any enumerated value in the nvic_lowpower_mode_type.
Input parameter 2	new_state: indicates the pre-configured status of battery powered domain This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

lp_mode

lp_mode is used to select low-power modes, including:

NVIC_LP_SEVONPEND:

Send wakeup event upon interrupt suspend (this option is usually used in conjunction with WFE)

NVIC_LP_SLEEPDEEP:

Deepsleep mode control bit (enable or disable core clock)

NVIC_LP_SLEEPONEXIT:

Sleep mode entry when system leaves the lowest-priority interrupt

Example:

```
/* enable sleep-on-exit feature */  
nvic_lowpower_mode_config(NVIC_LP_SLEEPONEXIT, TRUE);
```

5.14 Power controller (PWC)

The PWC register structure pwc_type is defined in the “at32f422_426_pwc.h”.

```
/*
 * @brief type define pwc register all
 */
typedef struct
{
    .....
} pwc_type;
```

The table below gives a list of the PWC registers.

Table 372. Summary of PWC registers

Register	Description
ctrl	Power control register
ctrlsts	Power control/status register
Ldoov	LDO calibration register

The table below gives a list of PWC library functions.

Table 373. Summary of PWC library functions

Function name	Description
pwc_reset	Reset PWC registers to their reset values
pwc_batteryPoweredDomainAccess	Enable battery powered domain access
pwc_pvmLevelSelect	Select PVM threshold
pwc_powerVoltageMonitorEnable	Enable voltage monitor
pwc_wakeupPinPolaritySelect	Select standby-mode wakeup pin polarity
pwc_wakeupPinEnable	Enable standby-mode wakeup pin
pwc_flagClear	Clear flag
pwc_flagGet	Get flag status
pwc_sleepModeEnter	Enter Sleep mode
pwc_deepSleepModeEnter	Enter Deepsleep mode
pwc_voltageRegulateSet	Select voltage regulator status in Deepsleep mode
pwc_standbyModeEnter	Enter Standby mode

5.14.1 pwc_reset function

The table below describes the function pwc_reset.

Table 374. pwc_reset function

Name	Description
Function name	pwc_reset
Function prototype	void pwc_reset(void)
Function description	Reset all PWC registers to their reset values.
Input parameter	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	crm_periph_reset()

Example:

```
/* deinitialize pwc */
pwc_reset();
```

5.14.2 pwc_batteryPoweredDomainAccess function

The table below describes the function pwc_batteryPoweredDomainAccess.

Table 375. pwc_batteryPoweredDomainAccess function

Name	Description
Function name	pwc_batteryPoweredDomainAccess
Function prototype	void pwc_batteryPoweredDomainAccess(confirm_state new_state)
Function description	Battery powered domain access enable
Input parameter	new_state: indicates the pre-configured status of battery powered domain This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable the battery-powered domain write operations */
pwc_batteryPoweredDomainAccess(TRUE);
```

Note: Access to battery powered domain (such as ERTC) is allowed only after enabling it through this function.

5.14.3 pwc_pvm_level_select function

The table below describes the function pwc_pvm_level_select.

Table 376. pwc_pvm_level_select function

Name	Description
Function name	pwc_pvm_level_select
Function prototype	void pwc_pvm_level_select(pwc_pvm_voltage_type pvm_voltage)
Function description	Select PVM threshold
Input parameter	pvm_voltage: indicates the selected PVM threshold This parameter can be any enumerated value in the pwc_pvm_voltage_type.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

pvm_voltage

pvm_voltage is used to select a PVM threshold from the optional parameters below:

PWC_PVM_VOLTAGE_2V3: PVM threshold is 2.3V
 PWC_PVM_VOLTAGE_2V4: PVM threshold is 2.4V
 PWC_PVM_VOLTAGE_2V5: PVM threshold is 2.5V
 PWC_PVM_VOLTAGE_2V6: PVM threshold is 2.6V
 PWC_PVM_VOLTAGE_2V7: PVM threshold is 2.7V
 PWC_PVM_VOLTAGE_2V8: PVM threshold is 2.8V
 PWC_PVM_VOLTAGE_2V9: PVM threshold is 2.9V

Example:

```
/* set the threshold voltage to 2.9v */
pwc_pvm_level_select(PWC_PVM_VOLTAGE_2V9);
```

5.14.4 pwc_power_voltage_monitor_enable function

The table below describes the function pwc_power_voltage_monitor_enable.

Table 377. pwc_power_voltage_monitor_enable function

Name	Description
Function name	pwc_power_voltage_monitor_enable
Function prototype	void pwc_power_voltage_monitor_enable(confirm_state new_state)
Function description	Enable power voltage monitor (PVM)
Input parameter	new_state: indicates the pre-configured status of PVM This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable power voltage monitor */
pwc_power_voltage_monitor_enable(TRUE);
```

5.14.5 pwc_wakeup_pin_polarity_select function

The table below describes the function pwc_wakeup_pin_polarity_select.

Table 378. pwc_wakeup_pin_polarity_select function

Name	Description
Function name	pwc_wakeup_pin_polarity_select
Function prototype	void pwc_wakeup_pin_polarity_select(uint32_t pin_num, pwc_wakeup_pin_polarity_type wakeup_pin_polarity)
Function description	Select Standby wakeup pin polarity
Input parameter 1	<i>pin_num</i> : select a Standby wakeup pin This parameter can be any pin that is capable of waking up from Standby mode.
Input parameter 2	wakeup_pin_polarity: select the Standby wakeup pin polarity This parameter can be any enumerated value in the pwc_wakeup_pin_polarity_type.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

wakeup_pin_polarity

wakeup_pin_polarity is used to select Standby-mode wakeup pin polarity, including:

PWC_RISING_EDGE_WAKEUP: Rising edge

PWC_FALLING_EDGE_WAKEUP: Falling edge

Example:

```
/* wakeup pin1 polarity set */
pwc_wakeup_pin_polarity_select(PWC_WAKEUP_PIN_1, PWC_RISING_EDGE_WAKEUP);
```

5.14.6 pwc_wakeup_pin_enable function

The table below describes the function pwc_wakeup_pin_enable.

Table 379. pwc_wakeup_pin_enable function

Name	Description
Function name	pwc_wakeup_pin_enable
Function prototype	void pwc_wakeup_pin_enable(uint32_t pin_num, confirm_state new_state)
Function description	Enable Standby wakeup pin
Input parameter 1	<i>pin_num</i> : select a standby wakeup pin This parameter can be any pin that is capable of waking up from Standby mode.
Input parameter 2	<i>new_state</i> : indicates the pre-configured status of Standby wakeup pins This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

pin_num

pin_num is used to select Standby-mode wakeup pin, including:

PWC_WAKEUP_PIN_1: Standby wakeup pin 1 (corresponding GPIO is PA0)

PWC_WAKEUP_PIN_2: Standby wakeup pin 2 (corresponding GPIO is PC13)

PWC_WAKEUP_PIN_6: Standby wakeup pin 6 (corresponding GPIO is PB5)

PWC_WAKEUP_PIN_7: Standby wakeup pin 7 (corresponding GPIO is PB15)

Example:

```
/* enable wakeup pin - pa0 */  
pwc_wakeup_pin_enable(PWC_WAKEUP_PIN_1, TRUE);
```

5.14.7 pwc_flag_clear function

The table below describes the function pwc_flag_clear.

Table 380. pwc_flag_clear function

Name	Description
Function name	pwc_flag_clear
Function prototype	void pwc_flag_clear(uint32_t pwc_flag)
Function description	Clear flag
Input parameter	pwc_flag: to-be-cleared flag Refer to the pwc_flag for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

pwc_flag

pwc_flag is used to select a flag from the optional parameters below:

PWC_WAKEUP_FLAG: Standby wakeup event

PWC_STANDBY_FLAG: Standby mode entry

PWC_PVM_OUTPUT_FLAG: PVM output (this parameter cannot be cleared by software)

PWC_WAKEUP_PIN1_FLAG: Standby wakeup event 1

PWC_WAKEUP_PIN2_FLAG: Standby wakeup event 2

PWC_WAKEUP_PIN6_FLAG: Standby wakeup event 6

PWC_WAKEUP_PIN7_FLAG: Standby wakeup event 7

Example:

```
/* wakeup event flag clear */  
pwc_flag_clear(PWC_WAKEUP_FLAG);
```

5.14.8 pwc_flag_get function

The table below describes the function pwc_flag_get.

Table 381. pwc_flag_get function

Name	Description
Function name	pwc_flag_get
Function prototype	flag_status pwc_flag_get(uint32_t pwc_flag)
Function description	Get flag status
Input parameter	pwc_flag: select a flag. Refer to pwc_flag for details.
Output parameter	NA
Return value	flag_status: flag status Return SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```
/* check if wakeup event flag is set */
if(pwc_flag_get(PWC_WAKEUP_FLAG) != RESET)
```

5.14.9 pwc_sleep_mode_enter function

The table below describes the function pwc_sleep_mode_enter.

Table 382. pwc_sleep_mode_enter function

Name	Description
Function name	pwc_sleep_mode_enter
Function prototype	void pwc_sleep_mode_enter(pwc_sleep_enter_type pwc_sleep_enter)
Function description	Enter Sleep mode
Input parameter	pwc_sleep_enter: select a command to enter Sleep mode This parameter can be any enumerated value in the pwc_sleep_enter_type.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

pwc_sleep_enter

pwc_sleep_enter is used to select a command to enter Sleep mode from the optional parameters below:

PWC_SLEEP_ENTER_WFI:	Enter Sleep mode by WFI
PWC_SLEEP_ENTER_WFE:	Enter Sleep mode by WFE

Example:

```
/* enter sleep mode */
pwc_sleep_mode_enter(PWC_SLEEP_ENTER_WFI);
```

5.14.10 pwc_deep_sleep_mode_enter function

The table below describes the function pwc_deep_sleep_mode_enter.

Table 383. pwc_deep_sleep_mode_enter function

Name	Description
Function name	pwc_deep_sleep_mode_enter
Function prototype	void pwc_deep_sleep_mode_enter(pwc_deep_sleep_enter_type pwc_deep_sleep_enter)
Function description	Enter Deepsleep mode
Input parameter	pwc_deep_sleep_enter: select a command to enter Deepsleep mode This parameter can be any enumerated value in the pwc_deep_sleep_enter_type.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

pwc_deep_sleep_enter

pwc_deep_sleep_enter is used to select a command to enter Deepsleep mode, including:

PWC_DEEP_SLEEP_ENTER_WFI: Enter Deepsleep mode by WFI

PWC_DEEP_SLEEP_ENTER_WFE: Enter Deepsleep mode by WFE

Example:

```
/* enter deep sleep mode */
pwc_deep_sleep_mode_enter(PWC_DEEP_SLEEP_ENTER_WFI);
```

5.14.11 pwc_voltage_regulate_set function

The table below describes the function pwc_voltage_regulate_set.

Table 384. pwc_voltage_regulate_set function

Name	Description
Function name	pwc_voltage_regulate_set
Function prototype	void pwc_voltage_regulate_set(pwc_regulator_type pwc_regulator)
Function description	Select the status of voltage regulator in Deepsleep mode
Input parameter	pwc_regulator: select voltage regulator status This parameter can be any enumerated value in the pwc_regulator_type.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

pwc_regulator

pwc_regulator is used to select the status of voltage regulator from the optional parameters below:

PWC_REGULATOR_ON: Voltage regulator ON in Deepsleep mode

PWC_REGULATOR_LOW_POWER: Voltage regulator low-power mode in Deepsleep mode

PWC_REGULATOR_EXTRA_LOW_POWER:

Voltage regulator extra low-power mode in Deepsleep mode

Example:

```
/* config the voltage regulator mode */
```

```
pwc_voltage_regulate_set(PWC_REGULATOR_LOW_POWER);
```

5.14.12 pwc_standby_mode_enter function

The table below describes the function pwc_standby_mode_enter.

Table 385. pwc_standby_mode_enter function

Name	Description
Function name	pwc_standby_mode_enter
Function prototype	void pwc_standby_mode_enter(void)
Function description	Enter Standby mode
Input parameter	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enter standby mode */
pwc_standby_mode_enter();
```

5.14.13 pwc_ldo_output_voltage_set function

The table below describes the function pwc_ldo_output_voltage_set.

Table 386. pwc_ldo_output_voltage_set function

Name	Description
Function name	pwc_ldo_output_voltage_set
Function prototype	pwc_ldo_output_voltage_set(val)
Function description	Set LDO output voltage
Input parameter	val: LDO output voltage value This parameter can be any enumerated value in the pwc_ldo_output_voltage_type.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

val

val is used to select LDO output voltage from the optional parameters below:

- | | |
|---------------------|------------------|
| PWC_LDO_OUTPUT_1V1: | LDO outputs 1.1V |
| PWC_LDO_OUTPUT_1V2: | LDO outputs 1.2V |
| PWC_LDO_OUTPUT_1V3: | LDO outputs 1.3V |

Example:

```
/* reduce ldo before enter deepsleep mode */
pwc_ldo_output_voltage_set(PWC_LDO_OUTPUT_1V1);
```

5.15 System configuration controller (SCFG)

The SCFG register structure scfg_type is defined in the “at32f422_426_scfg.h”.

```
/*
 * @brief type define scfg register all
 */
typedef struct
{
    ...
} scfg_type;
```

The table below gives a list of the SCFG registers.

Table 387. Summary of SCFG registers

Register	Description
scfg_cfg1	SCFG configuration register 1
scfg_cfg2	SCFG configuration register 2
scfg_exintc1	SCFG external interrupt configuration register 1
scfg_exintc2	SCFG external interrupt configuration register 2
scfg_exintc3	SCFG external interrupt configuration register 3
scfg_exintc4	SCFG external interrupt configuration register 4
scfg_iocfg	SCFG IO configuration register

The table below gives a list of SCFG library functions.

Table 388. Summary of SCFG library functions

Function name	Description
scfg_reset	SCFG reset
scfg_infrared_config	Infrared configuration
scfg_mem_map_get	Get memory address map
scfg_pa11pa12_pin_remap	PA11 and PA12 remap
scfg_adc_dma_channel_remap	ADC DMA channel remap
scfg_usart1_tx_dma_channel_remap	USART1 DMA transmit channel remap
scfg_usart1_rx_dma_channel_remap	USART1 DMA receive channel remap
scfg_tmr16_dma_channel_remap	TMR16 DMA channel remap
scfg_tmr17_dma_channel_remap	TMR17 DMA channel remap
scfg_exint_line_config	Configure external interrupt line
scfg_dma_channel_remap	DMA channel remap

5.15.1 scfg_reset function

The table below describes the function scfg_reset.

Table 389. scfg_reset function

Name	Description
Function name	scfg_reset
Function prototype	void scfg_reset(void);
Function description	Reset SCFG
Input parameter	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
scfg_reset();
```

5.15.2 scfg_infrared_config function

The table below describes the function scfg_infrared_config.

Table 390. scfg_infrared_config function

Name	Description
Function name	scfg_infrared_config
Function prototype	void scfg_infrared_config(scfg_ir_source_type source, scfg_ir_polarity_type polarity);
Function description	Infrared configuration
Input parameter 1	source: infrared modulation signal source
Input parameter 2	polarity: output signal polarity
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_ir_source_type

Select infrared signal source.

SCFG_IR_SOURCE_TMR16: Infrared signal source is tmr16

scfg_ir_polarity_type

Select infrared signal polarity.

SCFG_IR_POLARITY_NO_AFFECTE: Infrared output signal not inverted

SCFG_IR_POLARITY_REVERSE: Infrared output signal inverted

Example:

```
scfg_infrared_config(SCFG_IR_SOURCE_TMR16, SCFG_IR_POLARITY_NO_AFFECTE);
```

5.15.3 scfg_mem_map_get function

The table below describes the function scfg_mem_map_get.

Table 391. scfg_mem_map_get function

Name	Description
Function name	scfg_mem_map_get
Function prototype	uint8_t scfg_mem_map_get(void);
Function description	Get the status of a memory that is mapped on the address 0x00000000.
Input parameter	NA
Output parameter	NA
Return value	uint8_t: memory address map type
Required preconditions	NA
Called functions	NA

memory address mapped type

- SCFG_MEM_MAP_MAIN_MEMORY: Main memory is mapped to 0x00000000
- SCFG_MEM_MAP_BOOT_MEMORY: Boot memory is mapped to 0x00000000
- SCFG_MEM_MAP_INTERNAL_SRAM: Internal memory is mapped to 0x00000000

Example:

```
uint8_t value;
value = scfg_mem_map_get();
```

5.15.4 scfg_pa11pa12_pin_remap function

The table below describes the function scfg_pa11pa12_pin_remap.

Table 392. scfg_pa11pa12_pin_remap function

Name	Description
Function name	scfg_pa11pa12_pin_remap
Function prototype	void scfg_pa11pa12_pin_remap(scfg_pa11pa12_remap_type pin_remap);
Function description	Remap PA11 and PA12
Input parameter	pin_remap: remap option
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_pa11pa12_remap_type

Remap options.

- SCFG_PA11PA12_NO_REMAP: PA11 and PA12 are not remapped
- SCFG_PA11PA12_TO_PA9PA10: PA11 and PA12 are remapped to PA9 and PA10

Example:

```
scfg_pa11pa12_pin_remap(SCFG_PA11PA12_TO_PA9PA10);
```

5.15.5 scfg_adc_dma_channel_remap function

The table below describes the function scfg_adc_dma_channel_remap.

Table 393. scfg_adc_dma_channel_remap function

Name	Description
Function name	scfg_adc_dma_channel_remap
Function prototype	void scfg_adc_dma_channel_remap(scfg_adc_dma_remap_type dma_channel);
Function description	ADC DMA channel remapping
Input parameter	dma_channel: remap option
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_adc_dma_remap_type

Remap options.

SCFG_ADC_TO_DMA_CHANNEL_1: ADC DMA request is mapped to DMA channel 1

SCFG_ADC_TO_DMA_CHANNEL_2: ADC DMA request is mapped to DMA channel 2

Example:

```
scfg_adc_dma_channel_remap(SCFG_ADC_TO_DMA_CHANNEL_2);
```

5.15.6 scfg_usart1_tx_dma_channel_remap function

The table below describes the function scfg_usart1_tx_dma_channel_remap.

Table 394. scfg_usart1_tx_dma_channel_remap function

Name	Description
Function name	scfg_usart1_tx_dma_channel_remap
Function prototype	void scfg_usart1_tx_dma_channel_remap(scfg_usart1_tx_dma_remap_type dma_channel);
Function description	USART1 DMA transmit channel remapping
Input parameter	dma_channel: remap option
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_usart1_tx_dma_remap_type

Remap options.

SCFG_USART1_TX_TO_DMA_CHANNEL_2:

USART1 DMA transmit request is mapped to DMA channel 2

SCFG_USART1_TX_TO_DMA_CHANNEL_4:

USART1 DMA transmit request is mapped to DMA channel 4

Example:

```
scfg_usart1_tx_dma_channel_remap(SCFG_USART1_TX_TO_DMA_CHANNEL_4);
```

5.15.7 scfg_usart1_rx_dma_channel_remap function

The table below describes the function scfg_usart1_rx_dma_channel_remap.

Table 395. scfg_usart1_rx_dma_channel_remap function

Name	Description
Function name	scfg_usart1_rx_dma_channel_remap
Function prototype	void scfg_usart1_rx_dma_channel_remap(scfg_usart1_rx_dma_remap_type dma_channel);
Function description	USART1 DMA receive channel remapping
Input parameter	dma_channel: remap option
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_usart1_rx_dma_remap_type

Remap options.

SCFG_USART1_RX_TO_DMA_CHANNEL_3:

USART1 DMA receive request is mapped to DMA channel 3

SCFG_USART1_RX_TO_DMA_CHANNEL_5:

USART1 DMA receive request is mapped to DMA channel 5

Example:

```
scfg_usart1_rx_dma_channel_remap(SCFG_USART1_RX_TO_DMA_CHANNEL_5);
```

5.15.8 scfg_tmr1_dma_channel_remap function

The table below describes the function scfg_tmr1_dma_channel_remap.

Table 396. scfg_tmr1_dma_channel_remap function

Name	Description
Function name	scfg_tmr1_dma_channel_remap
Function prototype	void scfg_tmr1_dma_channel_remap(scfg_tmr1_dma_remap_type dma_channel);
Function description	TMR1 DMA receive channel remapping
Input parameter	dma_channel: remap option
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_tmr1_dma_remap_type

Remap options.

SCFG_TMR1_DMA_NO_REMAP:

No remap (TMR1_CH1, TMR1_CH2 and TMR1_CH3 DMA requests are mapped on DMA channel 2/3/5, respectively)

SCFG_TMR1_DMA_REMAP:

Remap (TMR1_CH1, TMR1_CH2 and TMR1_CH3 DMA requests are mapped on channel 6)

Example:

scfg_tmr1_dma_channel_remap(SCFG_TMR1_DMA_REMAP);

5.15.9 scfg_tmr3_dma_channel_remap function

The table below describes the function scfg_tmr3_dma_channel_remap.

Table 397. scfg_tmr3_dma_channel_remap function

Name	Description
Function name	scfg_tmr3_dma_channel_remap
Function prototype	void scfg_tmr3_dma_channel_remap(scfg_tmr3_dma_remap_type dma_channel);
Function description	TMR3 DMA receive channel remapping
Input parameter	dma_channel: remap option
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_tmr3_dma_remap_type

Remap options.

SCFG_TMR2_DMA_NO_REMAP: No remap (TMR3_CH1 and TMR3_TRIG DMA requests are mapped on DMA channel 4)

SCFG_TMR2_DMA_REMAP: Remap (TMR3_CH1 and TMR3_TRIG DMA requests are mapped on DMA channel 6)

Example:

scfg_tmr3_dma_channel_remap(SCFG_TMR3_DMA_REMAP);

5.15.10 scfg_tmr16_dma_channel_remap function

The table below describes the function scfg_tmr16_dma_channel_remap.

Table 398. scfg_tmr16_dma_channel_remap function

Name	Description
Function name	scfg_tmr16_dma_channel_remap
Function prototype	void scfg_tmr16_dma_channel_remap(scfg_tmr16_dma_remap_type dma_channel);
Function description	TMR16 DMA receive channel remapping
Input parameter	dma_channel: remap option
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_tmr16_dma_remap_type

Remap options.

SCFG_TMR16_TO_DMA_CHANNEL_3: TMR16 DMA request is mapped to DMA channel 3

SCFG_TMR16_TO_DMA_CHANNEL_4: TMR16 DMA request is mapped to DMA channel 4

Example:

scfg_tmr16_dma_channel_remap(SCFG_TMR16_TO_DMA_CHANNEL_4);
--

5.15.11 scfg_tmr16_dma_channel_remap2 function

The table below describes the function scfg_tmr16_dma_channel_remap2.

Table 399. scfg_tmr16_dma_channel_remap2 function

Name	Description
Function name	scfg_tmr16_dma_channel_remap2
Function prototype	void scfg_tmr16_dma_channel_remap2(scfg_tmr16_dma_remap2_type dma_channel);
Function description	TMR16 DMA receive channel remapping
Input parameter	dma_channel: remap option
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_tmr16_dma_remap2_type

Remap options.

SCFG_TMR16_DMA_NO_REMAP: No extra remap (TMR16_CH1 and TMR16_OVERFLOW DMA request mapping depends on TMR16_DMA_RMP)

SCFG_TMR16_DMA_REMAP: Extra remap (TMR16_CH1 and TMR16_OVERFLOW DMA requests are mapped on DMA channel 6)

Example:

scfg_tmr16_dma_channel_remap2(SCFG_TMR16_DMA_REMAP);
--

5.15.12 scfg_tmr17_dma_channel_remap function

The table below describes the function scfg_tmr17_dma_channel_remap.

Table 400. scfg_tmr17_dma_channel_remap function

Name	Description
Function name	scfg_tmr17_dma_channel_remap
Function prototype	void scfg_tmr17_dma_channel_remap(scfg_tmr17_dma_remap_type dma_channel);
Function description	TMR17 DMA receive channel remapping
Input parameter	dma_channel: remap option
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_tmr17_dma_remap_type

Remap options.

SCFG_TMR17_TO_DMA_CHANNEL_1: TMR17 DMA request is mapped on DMA channel 1

SCFG_TMR17_TO_DMA_CHANNEL_2: TMR17 DMA request is mapped on DMA channel 2

Example:

scfg_tmr17_dma_channel_remap(SCFG_TMR17_TO_DMA_CHANNEL_2);
--

5.15.13 scfg_tmr17_dma_channel_remap2 function

The table below describes the function scfg_tmr17_dma_channel_remap2.

Table 401. scfg_tmr17_dma_channel_remap2 function

Name	Description
Function name	scfg_tmr17_dma_channel_remap2
Function prototype	void scfg_tmr17_dma_channel_remap2(scfg_tmr17_dma_remap2_type dma_channel);
Function description	TMR17 DMA receive channel remapping
Input parameter	dma_channel: remap option
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_tmr17_dma_remap2_type

Remap options.

SCFG_TMR17_DMA_NO_REMAP: No extra remap (TMR17_CH1 and TMR17_OVERFLOW DMA request mapping depends on TMR17_DMA_RMP)

SCFG_TMR17_DMA_REMAP: Extra remap (TMR17_CH1 and TMR17_OVERFLOW DMA requests are mapped on DMA channel 7)

Example:

scfg_tmr17_dma_channel_remap2(SCFG_TMR17_DMA_REMAP);
--

5.15.14 scfg_spi2_dma_channel_remap function

The table below describes the function scfg_spi2_dma_channel_remap.

Table 402. scfg_spi2_dma_channel_remap function

Name	Description
Function name	scfg_spi2_dma_channel_remap
Function prototype	void scfg_spi2_dma_channel_remap(scfg_spi2_dma_remap_type dma_channel);
Function description	SPI2 DMA receive channel remapping
Input parameter	dma_channel: remap option
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_spi2_dma_remap_type

Remap options.

SCFG_SPI2_DMA_NO_REMAP: No remap (SPI2 RX and SPI2 TX DMA requests are mapped to DMA channel 4/5, respectively)

SCFG_SPI2_DMA_REMAP: Remap 1 (SPI2 RX and SPI2 TX DMA requests are mapped to DMA channel 6/7, respectively)

Example:

scfg_spi2_dma_channel_remap (SCFG_SPI2_DMA_REMAP);
--

5.15.15 scfg_usart2_dma_channel_remap function

The table below describes the function scfg_usart2_dma_channel_remap.

Table 403. scfg_usart2_dma_channel_remap function

Name	Description
Function name	scfg_usart2_dma_channel_remap
Function prototype	void scfg_usart2_dma_channel_remap(scfg_usart2_dma_remap_type dma_channel);
Function description	USART2 DMA receive channel remapping
Input parameter	dma_channel: remap option
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_usart2_dma_remap_type

Remap options.

SCFG_USART2_DMA_NO_REMAP: No remap (USART2 RX and USART2 TX DMA requests are mapped to DMA channel 4/5, respectively)

SCFG_USART2_DMA_REMAP: Remap 1 (USART2 RX and USART2 TX DMA requests are mapped to DMA channel 6/7, respectively)

Example:

scfg_usart2_dma_channel_remap (SCFG_USART2_DMA_REMAP);
--

5.15.16 scfg_i2c1_dma_channel_remap function

The table below describes the function scfg_i2c1_dma_channel_remap.

Table 404. scfg_i2c1_dma_channel_remap function

Name	Description
Function name	scfg_i2c1_dma_channel_remap
Function prototype	void scfg_i2c1_dma_channel_remap(scfg_i2c1_dma_remap_type dma_channel);
Function description	I ² C1 DMA receive channel remapping
Input parameter	dma_channel: remap option
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_i2c1_dma_remap_type

Remap options.

SCFG_I2C1_DMA_NO_REMAP: No remap (I²C1 RX and I²C1 TX DMA requests are mapped to DMA channel 3/2, respectively)

SCFG_I2C1_DMA_REMAP: Remap 1 (I²C1 RX and I²C1 TX DMA requests are mapped to DMA channel 7/6, respectively)

Example:

scfg_i2c1_dma_channel_remap (SCFG_I2C1_DMA_REMAP);
--

5.15.17 scfg_can_timestamp_source_set function

The table below describes the function scfg_can_timestamp_source_set.

Table 405. scfg_can_timestamp_source_set function

Name	Description
Function name	scfg_can_timestamp_source_set
Function prototype	void scfg_can_timestamp_source_set(scfg_can_type can_index, scfg_can_timestamp_source_type source);
Function description	Set CAN timestamp count source select
Input parameter	can_index: can selection
Input parameter	source: timestamp counting source
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_can_timestamp_source_type

Timestamp counting source.

SCFG_CAN_TIMESTAMP_TMR3: CAN1 timestamp counting source is TMR3

SCFG_CAN_TIMESTAMP_TMR4: CAN1 timestamp counting source is TMR4

Example:

scfg_can_timestamp_source_set (CAN1, SCFG_CAN_TIMESTAMP_TMR3);
--

5.15.18 scfg_exint_line_config function

The table below describes the function scfg_exint_line_config.

Table 406. scfg_exint_line_config function

Name	Description
Function name	scfg_exint_line_config
Function prototype	void scfg_exint_line_config(scfg_port_source_type port_source, scfg_pins_source_type pin_source);
Function description	External interrupt line configuration
Input parameter 1	port_source: port source
Input parameter 2	pin_source: pin source
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

scfg_port_source_type

SCFG_PORT_SOURCE_GPIOA: port A

SCFG_PORT_SOURCE_GPIOB: port B

SCFG_PORT_SOURCE_GPIOF: port F

scfg_pins_source_type

SCFG_PINS_SOURCE0: pin 0
 SCFG_PINS_SOURCE1: pin 1
 SCFG_PINS_SOURCE2: pin 2

 SCFG_PINS_SOURCE13: pin 13
 SCFG_PINS_SOURCE14: pin 14
 SCFG_PINS_SOURCE15: pin 15

Example:

```
scfg_exint_line_config(SCFG_PORT_SOURCE_GPIOA, SCFG_PINS_SOURCE1);
```

5.15.19 scfg_nrst_rmp_sts_get function

The table below describes the function scfg_nrst_rmp_sts_get.

Table 407. scfg_nrst_rmp_sts_get function

Name	Description
Function name	scfg_nrst_rmp_sts_get
Function prototype	uint8_t scfg_nrst_rmp_sts_get(void);
Function description	Get NRST remapping status
Input parameter	NA
Output parameter	NA
Return value	uint8_t: NRST remapping status
Required preconditions	NA
Called functions	NA

NRST remapping

SCFG_NRST_RMP_NRST: No remap
 SCFG_NRST_RMP_PF2: remap, used as PF2

Example:

```
uint8_t value;  
value = scfg_nrst_rmp_sts_get();
```

5.15.20 scfg_dma_channel_remap function

The table below describes the function scfg_dma_channel_remap.

Table 408. scfg_dma_channel_remap function

Name	Description
Function name	scfg_dma_channel_remap
Function prototype	void scfg_dma_channel_remap(uint32_t dma_channel, confirm_state new_state);
Function description	DMA channel remapping
Input parameter	dma_channel: channel remapping option
Input parameter	new_state: true or false
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

dma_channel

Remap options.

SCFG_ADC_DMA_RMP:

ADC DMA request is mapped on DMA1 channel 2

SCFG_USART1_TX_DMA_RMP:

USART1 TX DMA request is mapped on DMA1 channel 4

SCFG_USART1_RX_DMA_RMP:

USART1 RX DMA request is mapped on DMA1 channel 5

SCFG_TMR16_DMA_RMP:

TMR16_CH1/TMR16_OVERFLOW DMA request is mapped on DMA1 channel 4

SCFG_TMR17_DMA_RMP:

TMR17_CH1/TMR17_OVERFLOW DMA request is mapped on DMA1 channel 2

SCFG_TMR16_DMA_RMP2:

TMR16_CH1/TMR16_OVERFLOW DMA request is mapped on DMA1 channel 6

SCFG_TMR17_DMA_RMP2:

TMR17_CH1/TMR17_OVERFLOW DMA request is mapped on DMA1 channel 7

SCFG_SPI2_DMA_RMP:

SPI2 RX/TX DMA request is mapped on DMA1 channel 6/7

SCFG_USART2_DMA_RMP:

USART2 RX/TX DMA request is mapped on DMA1 channel 6/7

SCFG_I2C1_DMA_RMP:

I2C1 RX/TX DMA request is mapped on DMA1 channel 7/6

SCFG_TMR1_DMA_RMP:

TMR1_CH1/TMR1_CH2/TMR1_CH3 DMA request is mapped on DMA1 channel 6

SCFG_TMR3_DMA_RMP:

TMR3_CH1/TMR3_TRIG request is mapped on DMA1 channel 6

Example:

```
scfg_dma_channel_remap (SCFG_TMR17_DMA_RMP2, TRUE);
```

5.16 SysTick

The SysTick register structure SysTick_Type is defined in the “core_cm4.h”.

typedef struct

{

...

} SysTick_Type;

The table below gives a list of the SysTick registers.

Table 409. Summary of SysTick registers

Register	Description
ctrl	Control status register
load	Reload value register
val	Current counter value register
calib	Calibration register

The table below gives a list of SysTick library functions.

Table 410. Summary of SysTick library functions

Function name	Description
systick_clock_source_config	Configure SysTick clock sources
SysTick_Config	Configure SysTick counter reload value and interrupts

5.16.1 systick_clock_source_config function

The table below describes the function systick_clock_source_config.

Table 411. systick_clock_source_config function

Name	Description
Function name	systick_clock_source_config
Function prototype	void systick_clock_source_config(systick_clock_source_type source);
Function description	Configure SysTick clock source
Input parameter 1	source: systick clock source
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

source

SYSTICK_CLOCK_SOURCE_AHBCLK_DIV8: AHB/8 as SysTick clock

SYSTICK_CLOCK_SOURCE_AHBCLK_NODIV: AHB as SysTick clock

Example:

```
/* config systick clock source */
systick_clock_source_config(SYSTICK_CLOCK_SOURCE_AHBCLK_NODIV);
```

5.16.2 SysTick_Config function

The table below describes the function SysTick_Config.

Table 412. SysTick_Config function

Name	Description
Function name	SysTick_Config
Function prototype	uint32_t SysTick_Config(uint32_t ticks);
Function description	Configure SysTick counter reload value and enable interrupt
Input parameter 1	ticks: SysTick counter interrupt reload value
Input parameter 2	
Output parameter	NA
Return value	Return the setting status of this function, success (0) or failure (1)
Required preconditions	NA
Called functions	NA

Example:

```
/* config systick reload value and enable interrupt */  
SysTick_Config(1000);
```

5.17 Serial peripheral interface (SPI)/I²S

The SPI register structure spi_type is defined in the “at32f422_426_spi.h”.

```
/*
 * @brief type define spi register all
 */
typedef struct
{
    ...
} spi_type;
```

The table below gives a list of the SPI registers.

Table 413. Summary of SPI registers

Register	Description
ctrl1	SPI control register 1
ctrl2	SPI control register 2
sts	SPI status register
dt	SPI data register
cpoly	SPI CRC polynomial register
rcrc	SPI RxCRC register
tcrc	SPI TxCRC register
i2sctrl	SPI_I2S configuration register
i2sclk	SPI_I2S prescaler register

The table below gives a list of SPI library functions.

Table 414. Summary of SPI library functions

Function name	Description
spi_i2s_reset	Reset SPI/I ² S registers to their reset values
spi_default_para_init	Configure the SPI initialization structure with an initial value
spi_init	Initialize SPI
spi_ti_mode_enable	Enable SPI TI mode
spi_crc_next_transmit	Next data transfer is CRC command
spi_crc_polynomial_set	SPI CRC polynomial configuration
spi_crc_polynomial_get	Get SPI CRC polynomial
spi_crc_enable	Enable SPI CRC
spi_crc_value_get	Get CRC result of SPI receive/transmit
spi_hardware_cs_output_enable	Enable hardware CS output
spi_software_cs_internal_level_set	Set software CS internal level
spi_frame_bit_num_set	Set the number of frame bits
spi_half_duplex_direction_set	Set transfer direction of single-wire bidirectional half-duplex mode
spi_enable	Enable SPI
i2s_default_para_init	Set an initial value for the I ² S initialization structure
i2s_init	Initialize I ² S
i2s_enable	Enable I ² S

spi_i2s_interrupt_enable	Enable SPI/I ² S interrupts
spi_i2s_dma_transmitter_enable	Enable SPI/I ² S DMA transmit
spi_i2s_dma_receiver_enable	Enable SPI/I ² S DMA receive
spi_i2s_data_transmit	SPI/I ² S transmits data
spi_i2s_data_receive	SPI/I ² S receives data
spi_i2s_flag_get	Get SPI/I ² S flag
spi_i2s_interrupt_flag_get	Get SPI/I ² S interrupt flag
spi_i2s_flag_clear	Clear SPI/I ² S flag

5.17.1 spi_i2s_reset function

The table below describes the function spi_i2s_reset.

Table 415. spi_i2s_reset function

Name	Description
Function name	spi_i2s_reset
Function prototype	void spi_i2s_reset(spi_type *spi_x);
Function description	Reset SPI/I ² S registers to their reset values.
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	crm_periph_reset();

Example:

```
spi_i2s_reset (SPI1);
```

5.17.2 spi_default_para_init function

The table below describes the function spi_default_para_init.

Table 416. spi_default_para_init function

Name	Description
Function name	spi_default_para_init
Function prototype	void spi_default_para_init(spi_init_type* spi_init_struct);
Function description	Set an initial value for the SPI initialization structure
Input parameter 1	spi_init_struct: spi_init_type pointer
Output parameter	NA
Return value	NA
Required preconditions	It is necessary to define a variable of spi_init_type before starting.
Called functions	NA

Example:

```
spi_init_type spi_init_struct;  
spi_default_para_init (&spi_init_struct);
```

5.17.3 spi_init function

The table below describes the function spi_init.

Table 417. spi_init function

Name	Description
Function name	spi_init
Function prototype	void spi_init(spi_type* spi_x, spi_init_type* spi_init_struct);
Function description	Initialize SPI
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	spi_init_struct: <i>spi_init_type</i> pointer
Output parameter	NA
Return value	NA
Required preconditions	It is necessary to define a variable of <i>spi_init_type</i> before starting.
Called functions	NA

spi_init_type is defined in the “at32f422_426_spi.h”.

typedef struct

```
{
    spi_transmission_mode_type      transmission_mode;
    spi_master_slave_mode_type     master_slave_mode;
    spi_mclk_freq_div_type        mclk_freq_division;
    spi_first_bit_type            first_bit_transmission;
    spi_frame_bit_num_type        frame_bit_num;
    spi_clock_polarity_type       clock_polarity;
    spi_clock_phase_type          clock_phase;
    spi_cs_mode_type              cs_mode_selection;
}
```

spi_init_type;

spi_transmission_mode

SPI transmission mode.

SPI_TRANSMIT_FULL_DUPLEX: Two-wire unidirectional full-duplex mode

SPI_TRANSMIT_SIMPLEX_RX: Two-wire unidirectional receive-only mode

SPI_TRANSMIT_HALF_DUPLEX_RX: Single-wire bidirectional receive-only mode

SPI_TRANSMIT_HALF_DUPLEX_TX: Single-wire bidirectional transmit-only mode

master_slave_mode

Master/slave mode selection.

SPI_MODE_SLAVE: Slave mode

SPI_MODE_MASTER: Master mode

mclk_freq_division

Frequency division factor selection.

SPI_MCLK_DIV_2: Divided by 2

SPI_MCLK_DIV_3: Divided by 3

SPI_MCLK_DIV_4: Divided by 4

SPI_MCLK_DIV_8: Divided by 8

SPI_MCLK_DIV_16: Divided by 16

SPI_MCLK_DIV_32: Divided by 32

SPI_MCLK_DIV_64: Divided by 64
SPI_MCLK_DIV_128: Divided by 128
SPI_MCLK_DIV_256: Divided by 256
SPI_MCLK_DIV_512: Divided by 512
SPI_MCLK_DIV_1024: Divided by 1024

first_bit_transmission

SPI MSB-first/LSB-first selection
SPI_FIRST_BIT_MSB: MSB-first
SPI_FIRST_BIT_LSB: LSB-first

frame_bit_num

Set the number of bits in a frame

SPI_FRAME_8BIT: 8-bit data in a frame
SPI_FRAME_16BIT: 16-bit data in a frame

clock_polarity

Select Clock polarity.

SPI_CLOCK_POLARITY_LOW: Clock output low in idle state
SPI_CLOCK_POLARITY_HIGH: Clock output high in idle state

clock_phase

Select clock phase.

SPI_CLOCK_PHASE_1EDGE: Sample on the first clock edge
SPI_CLOCK_PHASE_2EDGE: Sample on the second clock edge

cs_mode_selection

Select CS mode.

SPI_CS_HARDWARE_MODE: Hardware CS mode
SPI_CS_SOFTWARE_MODE: Software CS mode

Example:

```
spi_init_type spi_init_struct;
spi_default_para_init(&spi_init_struct);
spi_init_struct.transmission_mode = SPI_TRANSMIT_FULL_DUPLEX;
spi_init_struct.master_slave_mode = SPI_MODE_MASTER;
spi_init_struct.mclk_freq_division = SPI_MCLK_DIV_8;
spi_init_struct.first_bit_transmission = SPI_FIRST_BIT_MSB;
spi_init_struct.frame_bit_num = SPI_FRAME_16BIT;
spi_init_struct.clock_polarity = SPI_CLOCK_POLARITY_LOW;
spi_init_struct.clock_phase = SPI_CLOCK_PHASE_2EDGE;
spi_init_struct.cs_mode_selection = SPI_CS_SOFTWARE_MODE;
spi_init(SPI1, &spi_init_struct);
```

5.17.4 spi_ti_mode_enable function

The table below describes the function spi_ti_mode_enable.

Table 418. spi_ti_mode_enable function

Name	Description
Function name	spi_ti_mode_enable
Function prototype	void spi_ti_mode_enable(spi_type* spi_x, confirm_state new_state);
Function description	Enable SPI TI mode
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	new_state: enable or disable It can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable spi ti mode */
spi_ti_mode_enable (SPI1, TRUE);
```

5.17.5 spi_crc_next_transmit function

The table below describes the function spi_crc_next_transmit.

Table 419. spi_crc_next_transmit function

Name	Description
Function name	spi_crc_next_transmit
Function prototype	void spi_crc_next_transmit(spi_type* spi_x);
Function description	The next data to be sent is CRC command
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
spi_crc_next_transmit (SPI1);
```

5.17.6 spi_crc_polynomial_set function

The table below describes the function spi_crc_polynomial_set.

Table 420. spi_crc_polynomial_set function

Name	Description
Function name	spi_crc_polynomial_set
Function prototype	void spi_crc_polynomial_set(spi_type* spi_x, uint16_t crc_poly);
Function description	Set SPI CRC polynomial
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	crc_poly: CRC polynomial Range: 0x0000~0xFFFF
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* set spi crc polynomial value */
spi_crc_polynomial_set (SPI1, 0x07);
```

5.17.7 spi_crc_polynomial_get function

The table below describes the function spi_crc_polynomial_get.

Table 421. spi_crc_polynomial_get function

Name	Description
Function name	spi_crc_polynomial_get
Function prototype	uint16_t spi_crc_polynomial_get(spi_type* spi_x);
Function description	Get SPI CRC polynomial
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Output parameter	NA
Return value	CRC polynomial Range: 0x0000~0xFFFF
Required preconditions	NA
Called functions	NA

Example:

```
/* get spi crc polynomial value */
uint16_t crc_poly;
crc_poly = spi_crc_polynomial_get (SPI1);
```

5.17.8 spi_crc_enable function

The table below describes the function spi_crc_enable.

Table 422. spi_crc_enable function

Name	Description
Function name	spi_crc_enable
Function prototype	void spi_crc_enable(spi_type* spi_x, confirm_state new_state);
Function description	Enable SPI CRC
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	new_state: enable or disable This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* spi crc enable */
spi_crc_enable (SPI1, TRUE);
```

5.17.9 spi_crc_value_get function

The table below describes the function spi_crc_value_get.

Table 423. spi_crc_value_get function

Name	Description
Function name	spi_crc_value_get
Function prototype	uint16_t spi_crc_value_get(spi_type* spi_x, spi_crc_direction_type crc_direction);
Function description	Get SPI receive/transmit CRC result
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	<i>crc_direction</i> : select receive/transmit CRC
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

crc_direction

Select receive/transmit CRC

SPI_CRC_RX: Receive CRC

SPI_CRC_TX: Transmit CRC

Example:

```
/* get spi rx & tx crc enable */
uint16_t spi_rx_crc, spi_tx_crc;
spi_rx_crc = spi_crc_value_get (SPI1, SPI_CRC_RX);
spi_tx_crc = spi_crc_value_get (SPI1, SPI_CRC_TX);
```

5.17.10 spi_hardware_cs_output_enable function

The table below describes the function spi_hardware_cs_output_enable.

Table 424. spi_hardware_cs_output_enable function

Name	Description
Function name	spi_hardware_cs_output_enable
Function prototype	void spi_hardware_cs_output_enable(spi_type* spi_x, confirm_state new_state);
Function description	Enable hardware CS output
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	new_state: enabled or disabled This parameter can FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	This setting is applicable to SPI master mode only.
Called functions	NA

Example:

```
/* enable the hardware cs output */
spi_hardware_cs_output_enable (SPI1, TRUE);
```

5.17.11 spi_software_cs_internal_level_set function

The table below describes the function spi_software_cs_internal_level_set.

Table 425. spi_software_cs_internal_level_set function

Name	Description
Function name	spi_software_cs_internal_level_set
Function prototype	void spi_software_cs_internal_level_set(spi_type* spi_x, spi_software_cs_level_type level);
Function description	Set software CS internal level
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	<i>level</i> : set software CS internal level
Output parameter	NA
Return value	NA
Required preconditions	1. This setting is applicable to software CS mode only; 2. In master mode, the "level" value must be "SPI_SWCS_INTERNAL_LEVEL_HIGHT".
Called functions	NA

level

Set software CS internal level

SPI_SWCS_INTERNAL_LEVEL_LOW: Software CS internal low level

SPI_SWCS_INTERNAL_LEVEL_HIGHT: Software CS internal high level

Example:

```
/* set the internal level high */
spi_software_cs_internal_level_set (SPI1, SPI_SWCS_INTERNAL_LEVEL_HIGHT);
```

5.17.12 spi_frame_bit_num_set function

The table below describes the function spi_frame_bit_num_set.

Table 426. spi_frame_bit_num_set function

Name	Description
Function name	spi_frame_bit_num_set
Function prototype	void spi_frame_bit_num_set(spi_type* spi_x, spi_frame_bit_num_type bit_num);
Function description	Set the number of bits in a frame
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	<i>bit_num</i> : Set the number of bits in a frame
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

bit_num

Set the number of bits in a frame

SPI_FRAME_8BIT: 8-bit data in a frame

SPI_FRAME_16BIT: 16-bit data in a frame

Example:

```
/* set the data frame bit num as 8 */
spi_frame_bit_num_set (SPI1, SPI_FRAME_8BIT);
```

5.17.13 spi_half_duplex_direction_set function

The table below describes the function spi_half_duplex_direction_set.

Table 427. spi_half_duplex_direction_set function

Name	Description
Function name	spi_half_duplex_direction_set
Function prototype	void spi_half_duplex_direction_set(spi_type* spi_x, spi_half_duplex_direction_type direction);
Function description	Set the transfer direction of single-wire bidirectional half-duplex mode
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	<i>direction</i> : transfer direction
Output parameter	NA
Return value	NA
Required preconditions	This setting is applicable to the single-wire bidirectional half-duplex mode only.
Called functions	NA

direction

Transfer direction

SPI_HALF_DUPLEX_DIRECTION_RX: Receive

SPI_HALF_DUPLEX_DIRECTION_TX: Transmit

Example:

```
/* set the data transmission direction as transmit */
```

```
spi_half_duplex_direction_set (SPI1, SPI_HALF_DUPLEX_DIRECTION_TX);
```

5.17.14 spi_enable function

The table below describes the function spi_enable.

Table 428. spi_enable function

Name	Description
Function name	spi_enable
Function prototype	void spi_enable(spi_type* spi_x, confirm_state new_state);
Function description	Enable SPI
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	new_state: enabled or disabled This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable spi */
spi_enable (SPI1, TRUE);
```

5.17.15 i2s_default_para_init function

The table below describes the function i2s_default_para_init.

Table 429. i2s_default_para_init function

Name	Description
Function name	i2s_default_para_init
Function prototype	void i2s_default_para_init(i2s_init_type* i2s_init_struct);
Function description	Set an initial value for the I ² S initialization structure
Input parameter 1	i2s_init_struct: <i>spi_i2s_flag</i> pointer
Output parameter	NA
Return value	NA
Required preconditions	It is necessary to define a variable of i2s_init_type before starting.
Called functions	NA

Example:

```
i2s_init_type i2s_init_struct;
i2s_default_para_init (&i2s_init_struct);
```

5.17.16 i2s_init function

The table below describes the function i2s_init.

Table 430. i2s_init function

Name	Description
Function name	i2s_init
Function prototype	void i2s_init(spi_type* spi_x, i2s_init_type* i2s_init_struct);
Function description	Initialize I ² S
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	i2s_init_struct: <i>spi_i2s_flag</i> pointer
Output parameter	NA
Return value	NA
Required preconditions	It is necessary to define a variable of i2s_init_type before starting.
Called functions	NA

i2s_init_type is defined in the “at32f422_426_spi.h”.

typedef struct

```
{
    i2s_operation_mode_type          operation_mode;
    i2s_audio_protocol_type         audio_protocol;
    i2s_audio_sampling_freq_type    audio_sampling_freq;
    i2s_data_channel_format_type   data_channel_format;
    i2s_clock_polarity_type        clock_polarity;
    confirm_state                   mclk_output_enable;

} i2s_init_type;
```

operation_mode

I²S transfer mode

I2S_MODE_SLAVE_TX:	I2S slave transmit
I2S_MODE_SLAVE_RX:	I2S slave receive
I2S_MODE_MASTER_TX:	I2S master transmit
I2S_MODE_MASTER_RX:	I2S master receive

audio_protocol

I²S audio protocol standards

I2S_AUDIO_PROTOCOL_PHILLIPS:	Phillips
I2S_AUDIO_PROTOCOL_MSB:	MSB aligned (left-aligned)
I2S_AUDIO_PROTOCOL_LSB:	LSB aligned (right-aligned)
I2S_AUDIO_PROTOCOL_PCM_SHORT:	PCM short frame synchronization
I2S_AUDIO_PROTOCOL_PCM_LONG:	PCM long frame synchronization

audio_sampling_freq

I²S audio sampling frequency

I2S_AUDIO_FREQUENCY_DEFAULT:
Kept at its reset value (sampling frequency changes with SCLK)

I2S_AUDIO_FREQUENCY_8K:	I ² S sampling frequency 8K
I2S_AUDIO_FREQUENCY_11_025K:	I ² S sampling frequency 11.025K
I2S_AUDIO_FREQUENCY_16K:	I ² S sampling frequency 16K

I2S_AUDIO_FREQUENCY_22_05K:	I ² S sampling frequency 22.05K
I2S_AUDIO_FREQUENCY_32K:	I ² S sampling frequency 32K
I2S_AUDIO_FREQUENCY_44_1K:	I ² S sampling frequency 44.1K
I2S_AUDIO_FREQUENCY_48K:	I ² S sampling frequency 48K
I2S_AUDIO_FREQUENCY_96K:	I ² S sampling frequency 96K
I2S_AUDIO_FREQUENCY_192K:	I ² S sampling frequency 192K

data_channel_format

I²S data/channel bits format

I2S_DATA_16BIT_CHANNEL_16BIT: 16-bit data, 16-bit channel

I2S_DATA_16BIT_CHANNEL_32BIT: 16-bit data, 32-bit channel

I2S_DATA_24BIT_CHANNEL_32BIT: 24-bit data, 32-bit channel

I2S_DATA_32BIT_CHANNEL_32BIT: 32-bit data, 32-bit channel

clock_polarity

I²S clock polarity

I2S_CLOCK_POLARITY_LOW: Clock output low in idle state

I2S_CLOCK_POLARITY_HIGH: Clock output high in idle state

mclk_output_enable

Enable mclk clock output

This parameter can be FALSE or TURE.

Example:

```
i2s_init_type i2s_init_struct;  
i2s_default_para_init(&i2s_init_struct);  
i2s_init_struct.audio_protocol = I2S_AUDIO_PROTOCOL_PHILLIPS;  
i2s_init_struct.data_channel_format = I2S_DATA_16BIT_CHANNEL_32BIT;  
i2s_init_struct.mclk_output_enable = FALSE;  
i2s_init_struct.audio_sampling_freq = I2S_AUDIO_FREQUENCY_48K;  
i2s_init_struct.clock_polarity = I2S_CLOCK_POLARITY_LOW;  
i2s_init_struct.operation_mode = I2S_MODE_MASTER_TX;  
i2s_init(SPI2, &i2s_init_struct);
```

5.17.17 i2s_enable function

The table below describes the function i2s_enable.

Table 431. i2s_enable function

Name	Description
Function name	i2s_enable
Function prototype	void i2s_enable(spi_type* spi_x, confirm_state new_state);
Function description	Enable I ² S
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	new_state: enable or disable This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable i2s*/
i2s_enable (SPI1, TRUE);
```

5.17.18 spi_i2s_interrupt_enable function

The table below describes the function spi_i2s_interrupt_enable.

Table 432. spi_i2s_interrupt_enable function

Name	Description
Function name	spi_i2s_interrupt_enable
Function prototype	void spi_i2s_interrupt_enable(spi_type* spi_x, uint32_t spi_i2s_int, confirm_state new_state);
Function description	Enable SPI/I ² S interrupts
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	<i>spi_i2s_int</i> : select SPI interrupts
Input parameter 3	new_state: enable or disable This parameter can be FALSE or TURE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

spi_i2s_int

SPI/I²S interrupt selection.

SPI_I2S_ERROR_INT: SPI/I²S error interrupts (including CRC error, overflow error, underflow error and mode error)

SPI_I2S_RDBF_INT: Receive data buffer full

SPI_I2S_TDBE_INT: Transmit data buffer empty

Example:

```
/* enable the specified spi/i2s interrupts */
spi_i2s_interrupt_enable (SPI1, SPI_I2S_ERROR_INT);
spi_i2s_interrupt_enable (SPI1, SPI_I2S_RDBF_INT);
spi_i2s_interrupt_enable (SPI1, SPI_I2S_TDBE_INT);
```

5.17.19 spi_i2s_dma_transmitter_enable function

The table below describes the function `spi_i2s_dma_transmitter_enable`.

Table 433. spi_i2s_dma_transmitter_enable function

Name	Description
Function name	<code>spi_i2s_dma_transmitter_enable</code>
Function prototype	<code>void spi_i2s_dma_transmitter_enable(spi_type* spi_x, confirm_state new_state);</code>
Function description	Enable SPI/I ² S DMA transmitter
Input parameter 1	<code>spi_x</code> : select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	<code>new_state</code> : enabled or disabled This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable spi transmitter dma */
spi_i2s_dma_transmitter_enable (SPI1, TRUE);
```

5.17.20 spi_i2s_dma_receiver_enable function

The table below describes the function `spi_i2s_dma_receiver_enable`.

Table 434. spi_i2s_dma_receiver_enable function

Name	Description
Function name	<code>spi_i2s_dma_receiver_enable</code>
Function prototype	<code>void spi_i2s_dma_receiver_enable(spi_type* spi_x, confirm_state new_state);</code>
Function description	Enable SPI/I ² S DMA receiver
Input parameter 1	<code>spi_x</code> : select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	<code>new_state</code> : enabled or disabled This parameter can be FALSE or TRUE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable spi dma transmitter */
spi_i2s_dma_transmitter_enable (SPI1, TRUE);
```

5.17.21 spi_i2s_data_transmit function

The table below describes the function spi_i2s_data_transmit.

Table 435. spi_i2s_data_transmit function

Name	Description
Function name	spi_i2s_data_transmit
Function prototype	void spi_i2s_data_transmit(spi_type* spi_x, uint16_t tx_data);
Function description	SPI/I ² S sends data
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	tx_data: data to send Value range (for 8-bit bit in a frame): 0x00~0xFF Value range (for 16-bit bit in a frame): 0x0000~0xFFFF
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* spi data transmit */
uint16_t tx_data = 0x6666;
spi_i2s_data_transmit (SPI1, tx_data);
```

5.17.22 spi_i2s_data_receive function

The table below describes the function spi_i2s_data_receive.

Table 436. spi_i2s_data_receive function

Name	Description
Function name	spi_i2s_data_receive
Function prototype	uint16_t spi_i2s_data_receive(spi_type* spi_x);
Function description	SPI/I ² S receives data
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Output parameter	rx_data: data to receive Value range (for 8-bit bit in a frame): 0x00~0xFF Value range (for 16-bit bit in a frame): 0x0000~0xFFFF
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* spi data receive */
uint16_t rx_data = 0;
rx_data = spi_i2s_data_receive (SPI1);
```

5.17.23 spi_i2s_flag_get function

The table below describes the function spi_i2s_flag_get.

Table 437. spi_i2s_flag_get function

Name	Description
Function name	spi_i2s_flag_get
Function prototype	flag_status spi_i2s_flag_get(spi_type* spi_x, uint32_t spi_i2s_flag);
Function description	Get SPI/I ² S flag status
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	spi_i2s_flag: flag selection Refer to the “spi_i2s_flag” description below for details.
Output parameter	NA
Return value	flag_status: flag status This parameter can be SET or RESET.
Required preconditions	NA
Called functions	NA

spi_i2s_flag

SPI/I²S is used to select a flag from the optional parameters below:

SPI_I2S_RDBF_FLAG:	SPI/I ² S receive data buffer full
SPI_I2S_TDBE_FLAG:	SPI/I ² S transmit data buffer empty
I2S_ACS_FLAG:	I ² S audio channel state (indicating left/right channel)
I2S_TUERR_FLAG:	I ² S transmitter underload error
SPI_CCERR_FLAG:	SPI CRC error
SPI_MMERR_FLAG:	SPI master mode error
SPI_I2S_ROERR_FLAG:	SPI/I ² S receive overflow error
SPI_I2S_BF_FLAG:	SPI/I ² S busy
SPI_CSPAS_FLAG:	SPI CS pulse error (for TI slave mode)

Example:

```
/* get receive data buffer full flag */
flag_status status;
status = spi_i2s_flag_get(SPI1, SPI_I2S_RDBF_FLAG);
```

5.17.24 spi_i2s_interrupt_flag_get function

The table below describes the function spi_i2s_interrupt_flag_get.

Table 438. spi_i2s_interrupt_flag_get function

Name	Description
Function name	spi_i2s_interrupt_flag_get
Function prototype	flag_status spi_i2s_interrupt_flag_get(spi_type* spi_x, uint32_t spi_i2s_flag);
Function description	Get SPI/I ² S interrupt flag status
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	spi_i2s_flag: flag selection Refer to the “spi_i2s_flag” description below for details.
Output parameter	NA
Return value	flag_status: flag status This parameter can be SET or RESET.
Required preconditions	NA
Called functions	NA

spi_i2s_flag

SPI/I²S is used for flag selection, including:

SPI_I2S_RDBF_FLAG:	SPI/I ² S receive data buffer full
SPI_I2S_TDBE_FLAG:	SPI/I ² S transmit data buffer empty
I ² S_TUERR_FLAG:	I ² S transmitter underload error
SPI_CCERR_FLAG:	SPI CRC error
SPI_MMERR_FLAG:	SPI master mode error
SPI_I2S_ROERR_FLAG:	SPI/I ² S receive overflow error
SPI_CSPAS_FLAG:	SPI CS pulse error (for TI slave mode)

Example:

```
/* get receive data buffer full flag */
flag_status status;
status = spi_i2s_interrupt_flag_get(SPI1, SPI_I2S_RDBF_FLAG);
```

5.17.25 spi_i2s_flag_clear function

The table below describes the function spi_i2s_flag_clear.

Table 439. spi_i2s_flag_clear function

Name	Description
Function name	spi_i2s_flag_clear
Function prototype	void spi_i2s_flag_clear(spi_type* spi_x, uint32_t spi_i2s_flag)
Function description	Clear SPI/I ² S flags
Input parameter 1	spi_x: select SPI peripherals This parameter can be SPI1 or SPI2.
Input parameter 2	spi_i2s_flag: select a flag to clear Refer to the “spi_i2s_flag” description below for details.
Output parameter	NA

Name	Description
Return value	NA
Required preconditions	NA
Called functions	NA

spi_i2s_flag:

SPI/I²S is used for flag selection, including:

SPI_I2S_RDBF_FLAG:	SPI/I ² S receive data buffer full
I2S_TUERR_FLAG:	I ² S transmitter underload error
SPI_CCERR_FLAG:	SPI CRC error
SPI_MMERR_FLAG:	SPI master mode error
SPI_I2S_ROERR_FLAG:	SPI/I ² S receive overflow error
SPI_CSPAS_FLAG:	SPI CS pulse error (for TI slave mode)

Note: The SPI_I2S_TDBE_FLAG (SPI/I²S transmit data buffer empty), I2S_ACS_FLAG (I²S audio channel state) and SPI_I2S_BF_FLAG (SPI/I²S busy) are all set and cleared by hardware to indicate communication state, without the intervention of software.

Example:

```
/* clear receive data buffer full flag */  
spi_i2s_flag_clear (SPI1, SPI_I2S_RDBF_FLAG);
```

5.18 TMR

The TMR register structure tmr_type is defined in the “[at32f422_426_tmr.h](#)”.

```
/*
 * @brief type define tmr register all
 */
typedef struct
{

} tmr_type;
```

The table below gives a list of the TMR registers.

Table 440. Summary of TMR registers

Register	Description
ctrl1	TMR control register 1
ctrl2	TMR control register 2
stctrl	TMR slave timer control register
iden	TMR DMA/ interrupt enable register
ists	TMR interrupt status register
swevt	TMR software event register
cm1	TMR channel mode register 1
cm2	TMR channel mode register 2
cctrl	TMR channel control register
cval	TMR counter value register
div	TMR division register
pr	TMR period register
rpr	TMR repetition period channel
c1dt	TMR channel 1 data register
c2dt	TMR channel 2 data register
c3dt	TMR channel 3 data register
c4dt	TMR channel 4 data register
brk	TMR brake register
dmactrl	TMR DMA control register
dmadt	TMR DMA data register
rmp	TMR channel input remap register

The table below gives a list of TMR library functions.

Table 441. Summary of TMR library functions

Function name	Description
tmr_reset	TMR is reset by CRM reset register
tmr_counter_enable	Enable or disable TMR counter
tmr_output_default_para_init	Initialize TMR output default parameters
tmr_input_default_para_init	Initialize TMR input default parameters
tmr_brkdt_default_para_init	Initialize TMR brkdt default parameters
tmr_base_init	Initialize TMR period and division
tmr_clock_source_div_set	Set TMR clock source frequency division factor
tmr_cnt_dir_set	Set TMR counter direction
tmr_repetition_counter_set	Set repetition period register
tmr_counter_value_set	Set TMR counter value
tmr_counter_value_get	Get TMR counter value
tmr_div_value_set	Set TMR division value
tmr_div_value_get	Get TMR division value
tmr_output_channel_config	Configure TMR output channels
tmr_output_channel_mode_select	Select TMR output channel mode
tmr_period_value_set	Set TMR period value
tmr_period_value_get	Get TMR period value
tmr_channel_value_set	Set TMR channel value
tmr_channel_value_get	Get TMR channel value
tmr_period_buffer_enable	Enable or disable TMR periodic buffer
tmr_output_channel_buffer_enable	Enable or disable TMR output channel buffer
tmr_output_channel_immediately_set	TMR output channel enable immediately
tmr_output_channel_switch_select	Select channel output switch source
tmr_output_channel_switch_set	Set TMR output channel switch
tmr_one_cycle_mode_enable	Enable or disable TMR one-cycle mode
tmr_overflow_request_source_set	Select TMR overflow event source
tmr_overflow_event_disable	Enable or disable TMR overflow event generation
tmr_input_channel_init	Initialize TMR input channel
tmr_channel_enable	Enable or disable TMR channels
tmr_input_channel_filter_set	Set TMR input channel filter
tmr_pwm_input_config	Configure TMR pwm input
tmr_channel1_input_select	Select TMR channel 1 input
tmr_input_channel_divider_set	Set TMR input channel divider
tmr_primary_mode_select	Select TMR master mode
tmr_sub_mode_select	Select TMR slave timer mode
tmr_channel_dma_select	Select TMR channel DMA request source
tmr_hall_select	Select TMR hall mode
tmr_channel_buffer_enable	Enable or disable TMR channel buffer
tmr_trigger_input_select	Select TMR slave timer trigger input
tmr_sub_sync_mode_set	Set TMR slave timer synchronization mode
tmr_dma_request_enable	Enable or disable TMR DMA request

tmr_interrupt_enable	Enable or disable TMR interrupt
tmr_interrupt_flag_get	Get TMR interrupt flag
tmr_flag_get	Get TMR flag
tmr_flag_clear	Clear TMR flag
tmr_event_sw_trigger	Software trigger TMR event
tmr_output_enable	Enable or disable TMR output
tmr_internal_clock_set	Set TMR internal clock
tmr_output_channel_polarity_set	Set TMR output channel polarity
tmr_external_clock_config	Set TMR external clock
tmr_external_clock_mode1_config	Set TMR external clock mode 1
tmr_external_clock_mode2_config	Set TMR external clock mode 2
tmr_encoder_mode_config	Set TMR encode mode
tmr_force_output_set	Set TMR forced output
tmr_dma_control_config	Set TMR DMA control
tmr_brkdt_config	Set TMR brake mode and dead-time
tmr_iremap_config	Set TMR input channel remap

5.18.1 tmr_reset function

The table below describes the function tmr_reset.

Table 442. tmr_reset function

Name	Description
Function name	tmr_reset
Function prototype	void tmr_reset(tmr_type *tmr_x);
Function description	TMR is reset by CRM reset register.
Input parameter	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	crm_periph_reset();

Example:

tmr_reset(TMR1);

5.18.2 tmr_counter_enable function

The table below describes the function tmr_counter_enable.

Table 443. tmr_counter_enable function

Name	Description
Function name	tmr_counter_enable
Function prototype	void tmr_counter_enable(tmr_type *tmr_x, confirm_state new_state);
Function description	Enable or disable TMR counter
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	new_state: indicates counter status, ON (TRUE) or OFF (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
tmr_counter_enable(TMR1, TRUE);
```

5.18.3 tmr_output_default_para_init function

The table below describes the function tmr_output_default_para_init.

Table 444. tmr_output_default_para_init function

Name	Description
Function name	tmr_output_default_para_init
Function prototype	void tmr_output_default_para_init(tmr_output_config_type *tmr_output_struct);
Function description	Initialize TMR output default parameters
Input parameter	tmr_output_struct: tmr_output_config_type pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

The table below describes the default values of members of the function tmr_output_struct.

Table 445. tmr_output_struct default values

Member	Default value
oc_mode	TMR_OUTPUT_CONTROL_OFF
oc_idle_state	FALSE
occ_idle_state	FALSE
oc_polarity	TMR_OUTPUT_ACTIVE_HIGH
occ_polarity	TMR_OUTPUT_ACTIVE_HIGH
oc_output_state	FALSE
occ_output_state	FALSE

Example:

```
tmr_output_config_type tmr_output_struct;
tmr_output_default_para_init(&tmr_output_struct);
```

5.18.4 tmr_input_default_para_init function

The table below describes the function tmr_input_default_para_init.

Table 446. tmr_input_default_para_init function

Name	Description
Function name	tmr_input_default_para_init
Function prototype	void tmr_input_default_para_init(tmr_input_config_type *tmr_input_struct);
Function description	Initialize TMR input default parameters
Input parameter	tmr_input_struct: tmr_input_config_type pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

The table below describes the default values of members of the tmr_input_struct.

Table 447. tmr_input_struct default values

Member	Default value
input_channel_select	TMR_SELECT_CHANNEL_1
input_polarity_select	TMR_INPUT_RISING_EDGE
input_mapped_select	TMR_CC_CHANNEL_MAPPED_DIRECT
input_filter_value	0x0

Example:

```
tmr_input_config_type tmr_input_struct;
tmr_input_default_para_init(&tmr_input_struct);
```

5.18.5 tmr_brkdt_default_para_init function

The table below describes the function tmr_brkdt_default_para_init.

Table 448. tmr_brkdt_default_para_init function

Name	Description
Function name	tmr_brkdt_default_para_init
Function prototype	void tmr_brkdt_default_para_init(tmr_brkdt_config_type *tmr_brkdt_struct);
Function description	Initialize TMR brkdt default parameters
Input parameter	tmr_brkdt_struct: tmr_brkdt_config_type pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

The table below describes the default values of members of the tmr_brkdt_struct.

Table 449. tmr_brkdt_struct default values

Member	Default value
brk_filter	0x0
deadtime	0x0
brk_polarity	TMR_BRK_INPUT_ACTIVE_LOW
wp_level	TMR_WP_OFF
auto_output_enable	FALSE
fcsoen_state	FALSE
fcsodis_state	FALSE
brk_enable	FALSE

Example:

```
tmr_brkdt_config_type tmr_brkdt_struct;
tmr_brkdt_default_para_init(&tmr_brkdt_struct);
```

5.18.6 tmr_base_init function

The table below describes the function tmr_base_init.

Table 450. tmr_base_init function

Name	Description
Function name	tmr_base_init
Function prototype	void tmr_base_init(tmr_type* tmr_x, uint32_t tmr_pr, uint32_t tmr_div);
Function description	Initialize TMR period and division
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	tmr_pr: timer period value, 0x0000~0xFFFF for 16-bit timer, and 0x0000_0000~0xFFFF_FFFF for 32-bit timer
Input parameter 3	tmr_div: timer division value, 0x0000~0xFFFF
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
tmr_base_init(TMR1, 0xFFFF, 0xFFFF);
```

5.18.7 tmr_clock_source_div_set function

The table below describes the function tmr_clock_source_div_set.

Table 451. tmr_clock_source_div_set function

Name	Description
Function name	tmr_clock_source_div_set
Function prototype	void tmr_clock_source_div_set(tmr_type *tmr_x, tmr_clock_division_type tmr_clock_div);
Function description	Set TMR clock source division
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	tmr_clock_div: timer clock source frequency division factor
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_clock_div

Select TMR clock source frequency division factor

TMR_CLOCK_DIV1: Divided by 1

TMR_CLOCK_DIV2: Divided by 2

TMR_CLOCK_DIV4: Divided by 4

Example:

```
tmr_clock_source_div_set(TMR1, TMR_CLOCK_DIV4);
```

5.18.8 tmr_cnt_dir_set function

The table below describes the function tmr_cnt_dir_set.

Table 452. tmr_cnt_dir_set function

Name	Description
Function name	tmr_cnt_dir_set
Function prototype	void tmr_cnt_dir_set(tmr_type *tmr_x, tmr_count_mode_type tmr_cnt_dir);
Function description	Set TMR counter direction
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	tmr_cnt_dir: counting direction
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_cnt_dir

Select counting direction.

TMR_COUNT_UP: Up counting

TMR_COUNT_DOWN: Down counting

TMR_COUNT_TWO_WAY_1: Center-aligned mode (up/down counting) 1

TMR_COUNT_TWO_WAY_2: Center-aligned mode (up/down counting) 2

TMR_COUNT_TWO WAY_3: Center-aligned mode (up/down counting) 3

Example:

```
tmr_cnt_dir_set(TMR1, TMR_COUNT_UP);
```

5.18.9 tmr_repetition_counter_set function

The table below describes the function tmr_repetition_counter_set.

Table 453. tmr_repetition_counter_set function

Name	Description
Function name	tmr_repetition_counter_set
Function prototype	void tmr_repetition_counter_set(tmr_type *tmr_x, uint8_t tmr_rpr_value);
Function description	Set repetition period register (rpr)
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR15, TMR16, TMR17
Input parameter 2	tmr_rpr_value: timer repetition period value, it can be 0x00~0xFF
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
tmr_repetition_counter_set(TMR1, 0x10);
```

5.18.10 tmr_counter_value_set function

The table below describes the function tmr_counter_value_set.

Table 454. tmr_counter_value_set function

Name	Description
Function name	tmr_counter_value_set
Function prototype	void tmr_counter_value_set(tmr_type *tmr_x, uint32_t tmr_cnt_value);
Function description	Set TMR counter value
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	tmr_cnt_value: timer counter value, 0x0000~0xFFFF for 16-bit timer and 0x0000_0000~0xFFFF_FFFF for 32-bit timer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
tmr_counter_value_set(TMR1, 0xFFFF);
```

5.18.11 tmr_counter_value_get function

The table below describes the function tmr_counter_value_get.

Table 455. tmr_counter_value_get function

Name	Description
Function name	tmr_counter_value_get
Function prototype	uint32_t tmr_counter_value_get(tmr_type *tmr_x);
Function description	Get TMR counter value
Input parameter	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Output parameter	NA
Return value	Timer counter value
Required preconditions	NA
Called functions	NA

Example:

```
uint32_t counter_value;
counter_value = tmr_counter_value_get(TMR1);
```

5.18.12 tmr_div_value_set function

The table below describes the function tmr_div_value_set.

Table 456. tmr_div_value_set function

Name	Description
Function name	tmr_div_value_set
Function prototype	void tmr_div_value_set(tmr_type *tmr_x, uint32_t tmr_div_value);
Function description	Set TMR frequency division value
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	tmr_div_value: timer frequency division value. 0x0000~0xFFFF for 16-bit timer and 0x0000_0000~0xFFFF_FFFF for 32-bit timer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
tmr_div_value_set(TMR1, 0xFFFF);
```

5.18.13 tmr_div_value_get function

The table below describes the function tmr_div_value_get.

Table 457. tmr_div_value_get function

Name	Description
Function name	tmr_div_value_get
Function prototype	uint32_t tmr_div_value_get(tmr_type *tmr_x);
Function description	Get TMR frequency division value
Input parameter	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Output parameter	NA
Return value	Timer frequency division value
Required preconditions	NA
Called functions	NA

Example:

```
uint32_t div_value;
div_value = tmr_div_value_get(TMR1);
```

5.18.14 tmr_output_channel_config function

The table below describes the function tmr_output_channel_config.

Table 458. tmr_output_channel_config function

Name	Description
Function name	tmr_output_channel_config
Function prototype	void tmr_output_channel_config(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, tmr_output_config_type *tmr_output_struct);
Function description	Configure TMR output channels
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	tmr_channel: timer channel
Input parameter 3	tmr_output_struct: tmr_output_config_type pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_channel

Select a TMR channel.

TMR_SELECT_CHANNEL_1: Channel 1

TMR_SELECT_CHANNEL_2: Channel 2

TMR_SELECT_CHANNEL_3: Channel 3

TMR_SELECT_CHANNEL_4: Channel 4

tmr_output_config_type structure

tmr_output_config_type is defined in the “at32f422_426_tmr.h”.

typedef struct

{

```
    tmr_output_control_mode_type      oc_mode;
    confirm_state                     oc_idle_state;
    confirm_state                     occ_idle_state;
    tmr_output_polarity_type         oc_polarity;
    tmr_output_polarity_type         occ_polarity;
    confirm_state                     oc_output_state;
    confirm_state                     occ_output_state;
} tmr_output_config_type;
```

oc_mode

Set output channel mode, that is, to configure channel original signals (CxORAW).

TMR_OUTPUT_CONTROL_OFF: Disconnect channel output (CxOUT) from CxORAW

TMR_OUTPUT_CONTROL_HIGH: CxORAW high

TMR_OUTPUT_CONTROL_LOW: CxORAW low

TMR_OUTPUT_CONTROL_SWITCH: Switch CxORAW level

TMR_OUTPUT_CONTROL_FORCE_LOW: CxORAW forced low

TMR_OUTPUT_CONTROL_FORCE_HIGH: CxORAW forced high

TMR_OUTPUT_CONTROL_PWM_MODE_A: PWM mode A

TMR_OUTPUT_CONTROL_PWM_MODE_B: PWM mode B

oc_idle_state

Set output channel idle state.

FALSE: Output channel idle state is 0

TRUE: Output channel idle state is 1

occ_idle_state

Set complementary output channel idle state.

FALSE: Complementary output channel idle state is 0

TRUE: Complementary output channel idle state is 1

oc_polarity

Set the polarity of output channels.

TMR_OUTPUT_ACTIVE_HIGH: Active high

TMR_OUTPUT_ACTIVE_LOW: Active low

occ_polarity

Set the polarity of complementary output channels.

TMR_OUTPUT_ACTIVE_HIGH: Active high

TMR_OUTPUT_ACTIVE_LOW: Active low

oc_output_state

Set the state of output channels.

FALSE: Output channel OFF

TRUE: Output channel ON

occ_output_state

Set the state of complementary output channels.

FALSE: Complementary output channel OFF

TRUE: Complementary output channel ON

Example:

```
tmr_output_config_type tmr_output_struct;
tmr_output_struct.oc_mode = TMR_OUTPUT_CONTROL_OFF;
tmr_output_struct.oc_output_state = TRUE;
```

```

tmr_output_struct.oc_polarity = TMR_OUTPUT_ACTIVE_HIGH;
tmr_output_struct.oc_idle_state = TRUE;
tmr_output_struct.occ_output_state = TRUE;
tmr_output_struct.occ_polarity = TMR_OUTPUT_ACTIVE_HIGH;
tmr_output_struct.occ_idle_state = TRUE;
tmr_output_channel_config(TMR1, TMR_SELECT_CHANNEL_1, &tmr_output_struct);

```

5.18.15 tmr_output_channel_mode_select function

The table below describes the function tmr_output_channel_mode_select.

Table 459. tmr_output_channel_mode_select function

Name	Description
Function name	tmr_output_channel_mode_select
Function prototype	void tmr_output_channel_mode_select(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, tmr_output_control_mode_type oc_mode);
Function description	Select TMR output channel mode
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	tmr_channel: timer channel selection
Input parameter 3	oc_mode: output mode
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_channel

Select a TMR channel.

TMR_SELECT_CHANNEL_1: Timer channel 1

TMR_SELECT_CHANNEL_2: Timer channel 2

TMR_SELECT_CHANNEL_3: Timer channel 3

TMR_SELECT_CHANNEL_4: Timer channel 4

oc_mode

Set output channel mode, that is, to configure channel original signals (CxORAW).

TMR_OUTPUT_CONTROL_OFF: Disconnect channel output (CxOUT) from CxORAW

TMR_OUTPUT_CONTROL_HIGH: CxORAW high

TMR_OUTPUT_CONTROL_LOW: CxORAW low

TMR_OUTPUT_CONTROL_SWITCH: Switch CxORAW level

TMR_OUTPUT_CONTROL_FORCE_LOW: CxORAW forced low

TMR_OUTPUT_CONTROL_FORCE_HIGH: CxORAW forced high

TMR_OUTPUT_CONTROL_PWM_MODE_A: PWM mode A

TMR_OUTPUT_CONTROL_PWM_MODE_B: PWM mode B

Example:

```
tmr_output_channel_mode_select(TMR1, TMR_SELECT_CHANNEL_1, TMR_OUTPUT_CONTROL_SWITCH);
```

5.18.16 tmr_period_value_set function

The table below describes the function tmr_period_value_set.

Table 460. tmr_period_value_set function

Name	Description
Function name	tmr_period_value_set
Function prototype	void tmr_period_value_set(tmr_type *tmr_x, uint32_t tmr_pr_value);
Function description	Set TMR period value
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	tmr_pr_value: timer period value. 0x0000~0xFFFF for 16-bit timer, and 0x0000_0000~0xFFFF_FFFF for 32-bit timer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
tmr_period_value_set(TMR1, 0xFFFF);
```

5.18.17 tmr_period_value_get function

The table below describes the function tmr_period_value_get.

Table 461. tmr_period_value_get function

Name	Description
Function name	tmr_period_value_get
Function prototype	uint32_t tmr_period_value_get(tmr_type *tmr_x);
Function description	Get TMR period value
Input parameter	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Output parameter	NA
Return value	Timer period value
Required preconditions	NA
Called functions	NA

Example:

```
uint32_t pr_value;
pr_value = tmr_period_value_get(TMR1);
```

5.18.18 tmr_channel_value_set function

The table below describes the function tmr_channel_value_set.

Table 462. tmr_channel_value_set function

Name	Description
Function name	tmr_channel_value_set
Function prototype	void tmr_channel_value_set(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, uint32_t tmr_channel_value);
Function description	Set TMR channel value
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	tmr_channel: timer channel
Input parameter 3	tmr_channel_value: timer channel value. 0x0000~0xFFFF for 16-bit timer, and 0x0000_0000~0xFFFF_FFFF for 32-bit timer.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_channel

Select a TMR channel.

TMR_SELECT_CHANNEL_1: Timer channel 1

TMR_SELECT_CHANNEL_2: Timer channel 2

TMR_SELECT_CHANNEL_3: Timer channel 3

TMR_SELECT_CHANNEL_4: Timer channel 4

Example:

```
tmr_channel_value_set(TMR1, TMR_SELECT_CHANNEL_1, 0xFFFF);
```

5.18.19 tmr_channel_value_get function

The table below describes the function tmr_channel_value_get.

Table 463. tmr_channel_value_get function

Name	Description
Function name	tmr_channel_value_get
Function prototype	uint32_t tmr_channel_value_get(tmr_type *tmr_x, tmr_channel_select_type tmr_channel);
Function description	Get TMR channel value
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	tmr_channel: timer channel
Output parameter	Timer channel value
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_channel

Select a TMR channel.

- TMR_SELECT_CHANNEL_1: Timer channel 1
- TMR_SELECT_CHANNEL_2: Timer channel 2
- TMR_SELECT_CHANNEL_3: Timer channel 3
- TMR_SELECT_CHANNEL_4: Timer channel 4

Example:

```
uint32_t ch_value;
ch_value = tmr_channel_value_get(TMR1, TMR_SELECT_CHANNEL_1);
```

5.18.20 tmr_period_buffer_enable function

The table below describes the function tmr_period_buffer_enable.

Table 464. tmr_period_buffer_enable function

Name	Description
Function name	tmr_period_buffer_enable
Function prototype	void tmr_period_buffer_enable(tmr_type *tmr_x, confirm_state new_state);
Function description	Enable or disable TMR period buffer
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	new_state: indicates the status of period buffer. It can be Enable (TRUE) or Disable (FALSE).
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
tmr_period_buffer_enable(TMR1, TRUE);
```

5.18.21 tmr_output_channel_buffer_enable function

The table below describes the function tmr_output_channel_buffer_enable.

Table 465. tmr_output_channel_buffer_enable function

Name	Description
Function name	tmr_output_channel_buffer_enable
Function prototype	void tmr_output_channel_buffer_enable(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, confirm_state new_state);
Function description	Enable or disable TMR output channel buffer
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	tmr_channel: timer channel
Input parameter 3	new_state: indicates the status of output channel buffer. It can be Enable (TRUE) or Disable (FALSE).
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_channel

Select a TMR channel.

TMR_SELECT_CHANNEL_1: Timer channel 1

TMR_SELECT_CHANNEL_2: Timer channel 2

TMR_SELECT_CHANNEL_3: Timer channel 3

TMR_SELECT_CHANNEL_4: Timer channel 4

Example:

```
tmr_output_channel_buffer_enable(TMR1, TMR_SELECT_CHANNEL_1, TRUE);
```

5.18.22 tmr_output_channel_immediately_set function

The table below describes the function tmr_output_channel_immediately_set.

Table 466. tmr_output_channel_immediately_set function

Name	Description
Function name	tmr_output_channel_immediately_set
Function prototype	void tmr_output_channel_immediately_set(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, confirm_state new_state);
Function description	Enable TMR output channel immediately
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	tmr_channel: timer channel
Input parameter 3	new_state: indicates the status of output channel enable. This parameter can be Enable (TRUE) or Disable (FALSE).
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_channel

Select a TMR channel.

TMR_SELECT_CHANNEL_1: Timer channel 1

TMR_SELECT_CHANNEL_2: Timer channel 2

TMR_SELECT_CHANNEL_3: Timer channel 3

TMR_SELECT_CHANNEL_4: Timer channel 4

Example:

```
tmr_output_channel_immediately_set(TMR1, TMR_SELECT_CHANNEL_1, TRUE);
```

5.18.23 tmr_output_channel_switch_select function

The table below describes the function tmr_output_channel_switch_select.

Table 467. tmr_output_channel_switch_select function

Name	Description
Function name	tmr_output_channel_switch_select
Function prototype	void tmr_output_channel_switch_select(tmr_type *tmr_x, tmr_ch_switch_select_type switch_sel);
Function description	Select TMR output channel switch
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4
Input parameter 2	switch_sel: channel output switch selection
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

switch_sel

Select channel output switch.

TMR_CH_SWITCH_SELECT_EXT: EXT is selected as CxORAW switch

TMR_CH_SWITCH_SELECT_CXORAW_OFF: CxORAW_OFF is selected as CxORAW switch

Example:

```
tmr_output_channel_switch_select(TMR1, TMR_CH_SWITCH_SELECT_EXT);
```

5.18.24 tmr_output_channel_switch_set function

The table below describes the function tmr_output_channel_switch_set.

Table 468. tmr_output_channel_switch_set function

Name	Description
Function name	tmr_output_channel_switch_set
Function prototype	void tmr_output_channel_switch_set(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, confirm_state new_state);
Function description	Set TMR output channel switch
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	tmr_channel: timer channel
Input parameter 3	new_state: indicates the status of output channel switch. This parameter can be Enable (TRUE) or Disable (FALSE).
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_channel

Select a TMR channel.

TMR_SELECT_CHANNEL_1: Timer channel 1

TMR_SELECT_CHANNEL_2: Timer channel 2

TMR_SELECT_CHANNEL_3: Timer channel 3

TMR_SELECT_CHANNEL_4: Timer channel 4

Example:

```
tmr_output_channel_switch_set(TMR1, TMR_SELECT_CHANNEL_1, TRUE);
```

5.18.25 tmr_one_cycle_mode_enable function

The table below describes the function tmr_one_cycle_mode_enable.

Table 469. tmr_one_cycle_mode_enable function

Name	Description
Function name	tmr_one_cycle_mode_enable
Function prototype	void tmr_one_cycle_mode_enable(tmr_type *tmr_x, confirm_state new_state);
Function description	Enable or disable TMR one-cycle mode
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	new_state: indicates the status of one-cycle mode. This parameter can be Enable (TRUE) or Disable (FALSE).
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
tmr_one_cycle_mode_enable(TMR1, TRUE);
```

5.18.26 tmr_overflow_request_source_set function

The table below describes the function tmr_overflow_request_source_set.

Table 470. tmr_overflow_request_source_set function

Name	Description
Function name	tmr_overflow_request_source_set
Function prototype	void tmr_overflow_request_source_set(tmr_type *tmr_x, confirm_state new_state);
Function description	Select TMR overflow event source
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	new_state: indicates the overflow event source
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

new_state

Select an overflow event source.

FALSE: Counter overflow, OVFSWTR being set, overflow event from slave mode timer controller

TRUE: Counter overflow only.

Example:

<code>tmr_overflow_request_source_set(TMR1, TRUE);</code>

5.18.27 tmr_overflow_event_disable function

The table below describes the function tmr_overflow_event_disable.

Table 471. tmr_overflow_event_disable function

Name	Description
Function name	<code>tmr_overflow_event_disable</code>
Function prototype	<code>void tmr_overflow_event_disable(tmr_type *tmr_x, confirm_state new_state);</code>
Function description	Enable or disable TMR overflow event generation
Input parameter 1	<code>tmr_x</code> : select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	<code>new_state</code> : indicates the status of overflow event generation
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

new_state

Select the status of overflow event generation

FALSE: Enable overflow event generation, which can be generated from the following:

- Counter overflow
- Set OVFSWTR=1
- Overflow event from slave mode timer controller

TRUE: Disable overflow event generation

Example:

<code>tmr_overflow_event_disable(TMR1, TRUE);</code>
--

5.18.28 tmr_input_channel_init function

The table below describes the function tmr_input_channel_init.

Table 472. tmr_input_channel_init function

Name	Description
Function name	<code>tmr_input_channel_init</code>
Function prototype	<code>void tmr_input_channel_init(tmr_type *tmr_x, tmr_input_config_type *input_struct, tmr_channel_input_divider_type divider_factor);</code>
Function description	Initialize TMR input channels
Input parameter 1	<code>tmr_x</code> : select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	<code>input_struct</code> : <code>tmr_input_config_type</code> pointer
Input parameter 3	<code>divider_factor</code> : input channel frequency division factor
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_input_config_type structure

tmr_input_config_type is defined in the “at32f422_426_tmr.h”.

typedef struct

```
{  
    tmr_channel_select_type      input_channel_select;  
    tmr_input_polarity_type      input_polarity_select;  
    tmr_input_direction_mapped_type  input_mapped_select;  
    uint8_t                      input_filter_value;  
} tmr_input_config_type;
```

input_channel_select

Select a TMR input channel.

TMR_SELECT_CHANNEL_1: Timer channel 1

TMR_SELECT_CHANNEL_2: Timer channel 2

TMR_SELECT_CHANNEL_3: Timer channel 3

TMR_SELECT_CHANNEL_4: Timer channel 4

input_polarity_select

Select the polarity of input channels.

TMR_INPUT_RISING_EDGE: Rising edge

TMR_INPUT_FALLING_EDGE: Falling edge

TMR_INPUT_BOTH_EDGE: Both edges (rising edge and falling edge)

input_mapped_select

Select input channel mapping.

TMR_CC_CHANNEL_MAPPED_DIRECT:

TMR input channel 1/2/3/4 are linked to C1IRAW, C2IRAW, C3IRAW and C4IRAW, respectively

TMR_CC_CHANNEL_MAPPED_INDIRECT:

TMR input channel 1/2/3/4 are linked to C2IRAW, C1IRAW, C4IRAW and C3IRAW, respectively

TMR_CC_CHANNEL_MAPPED_STI:

TMR input channel is mapped on STI

input_filter_value

Select an input channel filter value, between 0x00~0x0F

divider_factor

Select input channel frequency division factor.

TMR_CHANNEL_INPUT_DIV_1: Divided by 1

TMR_CHANNEL_INPUT_DIV_2: Divided by 2

TMR_CHANNEL_INPUT_DIV_4: Divided by 4

TMR_CHANNEL_INPUT_DIV_8: Divided by 8

Example:

```
tmr_input_config_type tmr_input_config_struct;  
tmr_input_config_struct.input_channel_select = TMR_SELECT_CHANNEL_2;  
tmr_input_config_struct.input_mapped_select = TMR_CC_CHANNEL_MAPPED_DIRECT;  
tmr_input_config_struct.input_polarity_select = TMR_INPUT_RISING_EDGE;  
tmr_input_config_struct.input_filter_value = 0x00;  
tmr_input_channel_init(TMR1, &tmr_input_config_struct, TMR_CHANNEL_INPUT_DIV_1);
```

5.18.29 tmr_channel_enable function

The table below describes the function tmr_channel_enable.

Table 473. tmr_channel_enable function

Name	Description
Function name	tmr_channel_enable
Function prototype	void tmr_channel_enable(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, confirm_state new_state);
Function description	Enable or disable TMR channels
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	tmr_channel: timer channel
Input parameter 3	new_state: indicates the status of timer channels. This parameter can be Enable (TRUE) or Disable (FALSE).
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_channel

Select a TMR channel.

- TMR_SELECT_CHANNEL_1: Timer channel 1
- TMR_SELECT_CHANNEL_1C: Complementary channel 1
- TMR_SELECT_CHANNEL_2: Timer channel 2
- TMR_SELECT_CHANNEL_2C: Complementary channel 2
- TMR_SELECT_CHANNEL_3: Timer channel 3
- TMR_SELECT_CHANNEL_3C: Complementary channel 3
- TMR_SELECT_CHANNEL_4: Timer channel 4
- TMR_SELECT_CHANNEL_4C: Complementary channel 4

Example:

```
tmr_channel_enable(TMR1, TMR_SELECT_CHANNEL_1, TRUE);
```

5.18.30 tmr_input_channel_filter_set function

The table below describes the function tmr_input_channel_filter_set.

Table 474. tmr_input_channel_filter_set function

Name	Description
Function name	tmr_input_channel_filter_set
Function prototype	void tmr_input_channel_filter_set(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, uint16_t filter_value);
Function description	Set TMR input channel filter
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	tmr_channel: timer channel
Input parameter 3	filter_value: set channel filter value, 0x00~0x0F
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_channel

Select a TMR channel.

TMR_SELECT_CHANNEL_1: Timer channel 1

TMR_SELECT_CHANNEL_2: Timer channel 2

TMR_SELECT_CHANNEL_3: Timer channel 3

TMR_SELECT_CHANNEL_4: Timer channel 4

Example:

```
tmr_input_channel_filter_set(TMR1, TMR_SELECT_CHANNEL_1, 0x0F);
```

5.18.31 tmr_pwm_input_config function

The table below describes the function tmr_pwm_input_config.

Table 475. tmr_pwm_input_config function

Name	Description
Function name	tmr_pwm_input_config
Function prototype	void tmr_pwm_input_config(tmr_type *tmr_x, tmr_input_config_type *input_struct, tmr_channel_input_divider_type divider_factor);
Function description	Configure TMR pwm input
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15
Input parameter 2	input_struct: tmr_input_config_type pointer
Input parameter 3	divider_factor: input channel frequency division factor
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

input_struct

Point to the tmr_input_config_type. See [tmr_input_config_type](#) for details.

divider_factor

Select input channel frequency division factor.

- TMR_CHANNEL_INPUT_DIV_1: Divided by 1
- TMR_CHANNEL_INPUT_DIV_2: Divided by 2
- TMR_CHANNEL_INPUT_DIV_4: Divided by 4
- TMR_CHANNEL_INPUT_DIV_8: Divided by 8

Example:

```
tmr_input_config_type tmr_ic_init_structure;
tmr_ic_init_structure.input_filter_value = 0;
tmr_ic_init_structure.input_channel_select = TMR_SELECT_CHANNEL_2;
tmr_ic_init_structure.input_mapped_select = TMR_CC_CHANNEL_MAPPED_DIRECT;
tmr_ic_init_structure.input_polarity_select = TMR_INPUT_RISING_EDGE;
tmr_pwm_input_config(TMR1, &tmr_ic_init_structure, TMR_CHANNEL_INPUT_DIV_1);
```

5.18.32 tmr_channel1_input_select function

The table below describes the function tmr_channel1_input_select.

Table 476. tmr_channel1_input_select function

Name	Description
Function name	tmr_channel1_input_select
Function prototype	void tmr_channel1_input_select(tmr_type *tmr_x, tmr_channel1_input_connected_type ch1_connect);
Function description	Select TMR channel 1 input
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4
Input parameter 2	ch1_connect: channel 1 input selection
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

ch1_connect

Select channel 1 input.

TMR_CHANNEL1_CONNECTED_C1IRAW: CH1 pin is connected to C1IRAW

TMR_CHANNEL1_2_3_CONNECTED_C1IRAW_XOR: Connect the XOR results of CH1, CH2 and CH3 pins to C1IRAW

Example:

```
tmr_channel1_input_select(TMR1, TMR_CHANNEL1_2_3_CONNECTED_C1IRAW_XOR);
```

5.18.33 tmr_input_channel_divider_set function

The table below describes the function tmr_input_channel_divider_set.

Table 477. tmr_input_channel_divider_set function

Name	Description
Function name	tmr_input_channel_divider_set
Function prototype	void tmr_input_channel_divider_set(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, tmr_channel_input_divider_type divider_factor);
Function description	Set TMR input channel divider
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	tmr_channel: timer channel
Input parameter 3	divider_factor: input channel frequency division factor
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_channel

Select a TMR channel.

TMR_SELECT_CHANNEL_1: Timer channel 1

TMR_SELECT_CHANNEL_2: Timer channel 2

TMR_SELECT_CHANNEL_3: Timer channel 3

TMR_SELECT_CHANNEL_4: Timer channel 4

divider_factor

Select input channel frequency division factor

TMR_CHANNEL_INPUT_DIV_1: Divided by 1

TMR_CHANNEL_INPUT_DIV_2: Divided by 2

TMR_CHANNEL_INPUT_DIV_4: Divided by 4

TMR_CHANNEL_INPUT_DIV_8: Divided by 8

Example:

```
tmr_input_channel_divider_set(TMR1, TMR_SELECT_CHANNEL_1, TMR_CHANNEL_INPUT_DIV_2);
```

5.18.34 tmr_primary_mode_select function

The table below describes the function tmr_primary_mode_select.

Table 478. tmr_primary_mode_select function

Name	Description
Function name	tmr_primary_mode_select
Function prototype	void tmr_primary_mode_select(tmr_type *tmr_x, tmr_primary_select_type primary_mode);
Function description	Select TMR primary (master) mode
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6, TMR15
Input parameter 2	primary_mode: master mode
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

primary_mode

Select primary mode, that is, master timer output signal selection.

TMR_PRIMARY_SEL_RESET:	Reset
TMR_PRIMARY_SEL_ENABLE:	Enable
TMR_PRIMARY_SEL_OVERFLOW:	Overflow
TMR_PRIMARY_SEL_COMPARE:	Compare pulse
TMR_PRIMARY_SEL_C1ORAW:	C1ORAW
TMR_PRIMARY_SEL_C2ORAW:	C2ORAW
TMR_PRIMARY_SEL_C3ORAW:	C3ORAW
TMR_PRIMARY_SEL_C4ORAW:	C4ORAW

Example:

```
tmr_primary_mode_select(TMR1, TMR_PRIMARY_SEL_RESET);
```

5.18.35 tmr_sub_mode_select function

The table below describes the function tmr_sub_mode_select.

Table 479. tmr_sub_mode_select function

Name	Description
Function name	tmr_sub_mode_select
Function prototype	void tmr_sub_mode_select(tmr_type *tmr_x, tmr_sub_mode_select_type sub_mode);
Function description	Select TMR slave timer mode
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4 and TMR15
Input parameter 2	sub_mode: slave timer mode
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

primary_mode

Select slave timer mode.

TMR_SUB_MODE_DISABLE:	Disable
TMR_SUB_ENCODER_MODE_A:	Encoder mode A
TMR_SUB_ENCODER_MODE_B:	Encoder mode B
TMR_SUB_ENCODER_MODE_C:	Encoder mode C
TMR_SUB_ENCODER_MODE_D:	Encoder mode D
TMR_SUB_ENCODER_MODE_E:	Encoder mode E
TMR_SUB_RESET_MODE:	Reset
TMR_SUB_HANG_MODE:	Suspend
TMR_SUB_TRIGGER_MODE:	Trigger
TMR_SUB_EXTERNAL_CLOCK_MODE_A:	External clock A

Example:

```
tmr_sub_mode_select(TMR1, TMR_SUB_HANG_MODE);
```

5.18.36 tmr_channel_dma_select function

The table below describes the function tmr_channel_dma_select.

Table 480. tmr_channel_dma_select function

Name	Description
Function name	tmr_channel_dma_select
Function prototype	void tmr_channel_dma_select(tmr_type *tmr_x, tmr_dma_request_source_type cc_dma_select);
Function description	Select TMR channel DMA request source
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	cc_dma_select: TMR channel DMA request source
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

cc_dma_select

Select DMA request source for TMR channels.

TMR_DMA_REQUEST_BY_CHANNEL:	DMA request upon a channel event (CxIF = 1)
TMR_DMA_REQUEST_BY_OVERFLOW:	DMA request upon a overflow event (OVFIF = 1)

Example:

```
tmr_channel_dma_select(TMR1, TMR_DMA_REQUEST_BY_OVERFLOW);
```

5.18.37 tmr_hall_select function

The table below describes the function tmr_hall_select.

Table 481. tmr_hall_select function

Name	Description
Function name	tmr_hall_select
Function prototype	void tmr_hall_select(tmr_type *tmr_x, confirm_state new_state);
Function description	Select TMR hall mode
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR15, TMR16, TMR17
Input parameter 2	new_state: indicates the status of TMR hall mode
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

new_state

Select the status of TMR hall mode in order to refresh channel control bit.

FALSE: Refresh channel control bit through HALL

TRUE: Refresh channel control bit through HALL or the rising edge of TRGIN

Example:

```
tmr_hall_select(TMR1, TRUE);
```

5.18.38 tmr_channel_buffer_enable function

The table below describes the function tmr_channel_buffer_enable.

Table 482. tmr_channel_buffer_enable function

Name	Description
Function name	tmr_channel_buffer_enable
Function prototype	void tmr_channel_buffer_enable(tmr_type *tmr_x, confirm_state new_state);
Function description	Enable or disable TMR channel buffer
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR15, TMR16, TMR17
Input parameter 2	new_state: indicates the status of TMR channel buffer. This parameter can be Enable (TRUE) or Disable (FALSE).
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
tmr_channel_buffer_enable(TMR1, TRUE);
```

5.18.39 tmr_trigger_input_select function

The table below describes the function tmr_trigger_input_select.

Table 483. tmr_trigger_input_select function

Name	Description
Function name	tmr_trigger_input_select
Function prototype	void tmr_trigger_input_select(tmr_type *tmr_x, sub_tmr_input_sel_type trigger_select);
Function description	Select TMR slave timer trigger input
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15
Input parameter 2	trigger_select: select TMR slave timer trigger input
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

trigger_select

Select TMR slave timer trigger input.

- TMR_SUB_INPUT_SEL_IS0: Internal input 0
- TMR_SUB_INPUT_SEL_IS1: Internal input 1
- TMR_SUB_INPUT_SEL_IS2: Internal input 2
- TMR_SUB_INPUT_SEL_IS3: Internal input 3
- TMR_SUB_INPUT_SEL_C1INC: C1IRAW input detection
- TMR_SUB_INPUT_SEL_C1DF1: Filter input channel 1
- TMR_SUB_INPUT_SEL_C2DF2: Filter input channel 2
- TMR_SUB_INPUT_SEL_EXTIN: External input channel EXT

Example:

```
tmr_trigger_input_select(TMR1, TMR_SUB_INPUT_SEL_IS0);
```

5.18.40 tmr_sub_sync_mode_set function

The table below describes the function tmr_sub_sync_mode_set.

Table 484. tmr_sub_sync_mode_set function

Name	Description
Function name	tmr_sub_sync_mode_set
Function prototype	void tmr_sub_sync_mode_set(tmr_type *tmr_x, confirm_state new_state);
Function description	Set TMR slave timer synchronization mode
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15
Input parameter 2	new_state: indicates the status of TMR slave timer synchronization mode This parameter can be Enable (TRUE) or Disable (FALSE).
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
tmr_sub_sync_mode_set(TMR1, TRUE);
```

5.18.41 tmr_dma_request_enable function

The table below describes the function tmr_dma_request_enable.

Table 485. tmr_dma_request_enable function

Name	Description
Function name	tmr_dma_request_enable
Function prototype	void tmr_dma_request_enable(tmr_type *tmr_x, tmr_dma_request_type dma_request, confirm_state new_state);
Function description	Enable or disable TMR DMA request
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	dma_request: DMA request
Input parameter 3	new_state: indicates the status of DMA request. This parameter can be Enable (TRUE) or Disable (FALSE).
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

dma_request

Select a DMA request.

- TMR_OVERFLOW_DMA_REQUEST: Overflow event DMA request
- TMR_C1_DMA_REQUEST: Channel 1 DMA request
- TMR_C2_DMA_REQUEST: Channel 2 DMA request
- TMR_C3_DMA_REQUEST: Channel 3 DMA request
- TMR_C4_DMA_REQUEST: Channel 4 DMA request
- TMR_HALL_DMA_REQUEST: HALL event DMA request
- TMR_TRIGGER_DMA_REQUEST: Trigger event DMA request

Example:

```
tmr_dma_request_enable(TMR1, TMR_OVERFLOW_DMA_REQUEST, TRUE);
```

5.18.42 tmr_interrupt_enable function

The table below describes the function tmr_interrupt_enable.

Table 486. tmr_interrupt_enable function

Name	Description
Function name	tmr_interrupt_enable
Function prototype	void tmr_interrupt_enable(tmr_type *tmr_x, uint32_t tmr_interrupt, confirm_state new_state);
Function description	Enable or disable TMR interrupts
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	tmr_interrupt: TMR interrupts
Input parameter 3	new_state: indicates the status of TMR interrupts. This parameter can be Enable (TRUE) or Disable (FALSE).
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_interrupt

Select a TMR interrupt.

TMR_OVF_INT:	Overflow event interrupt
TMR_C1_INT:	Channel 1 event interrupt
TMR_C2_INT:	Channel 2 event interrupt
TMR_C3_INT:	Channel 3 event interrupt
TMR_C4_INT:	Channel 4 event interrupt
TMR_HALL_INT:	HALL event interrupt
TMR_TRIGGER_INT:	Trigger event interrupt
TMR_BRK_INT:	Brake event interrupt

Example:

```
tmr_interrupt_enable(TMR1, TMR_OVF_INT, TRUE);
```

5.18.43 tmr_interrupt_flag_get function

The table below describes the function tmr_interrupt_flag_get.

Table 487. tmr_interrupt_flag_get function

Name	Description
Function name	tmr_interrupt_flag_get
Function prototype	flag_status tmr_interrupt_flag_get (tmr_type *tmr_x, uint32_t tmr_flag);
Function description	Get interrupt flag status
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	tmr_flag: flag selection Refer to the "tmr_flag" description below for details.
Output parameter	NA
Return value	flag_status: flag status It can be SET or RESET.
Required preconditions	NA
Called functions	NA

tmr_flag

This is used for flag selection, including:

TMR_OVF_FLAG:	Overflow interrupt flag
TMR_C1_FLAG:	Channel 1 interrupt flag
TMR_C2_FLAG:	Channel 2 interrupt flag
TMR_C3_FLAG:	Channel 3 interrupt flag
TMR_C4_FLAG:	Channel 4 interrupt flag
TMR_HALL_FLAG:	HALL interrupt flag
TMR_TRIGGER_FLAG:	Trigger interrupt flag
TMR_BRK_FLAG:	Brake interrupt flag

Example:

```
if(tmr_interrupt_flag_get (TMR1, TMR_OVF_FLAG) != RESET)
```

5.18.44 tmr_flag_get function

The table below describes the function tmr_flag_get.

Table 488. tmr_flag_get function

Name	Description
Function name	tmr_flag_get
Function prototype	flag_status tmr_flag_get(tmr_type *tmr_x, uint32_t tmr_flag);
Function description	Get flag status
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	tmr_flag: flag selection Refer to the "tmr_flag" description below for details.
Output parameter	NA
Return value	flag_status: indicates the status of flag Return SET or RESET.
Required preconditions	NA
Called functions	NA

tmr_flag

This is used for flag selection, including:

TMR_OVF_FLAG:	Overflow interrupt flag
TMR_C1_FLAG:	Channel 1 interrupt flag
TMR_C2_FLAG:	Channel 2 interrupt flag
TMR_C3_FLAG:	Channel 3 interrupt flag
TMR_C4_FLAG:	Channel 4 interrupt flag
TMR_HALL_FLAG:	HALL interrupt flag
TMR_TRIGGER_FLAG:	Trigger interrupt flag
TMR_BRK_FLAG:	Brake interrupt flag
TMR_C1_RECAPTURE_FLAG:	Channel 1 recapture flag
TMR_C2_RECAPTURE_FLAG:	Channel 2 recapture flag
TMR_C3_RECAPTURE_FLAG:	Channel 3 recapture flag
TMR_C4_RECAPTURE_FLAG:	Channel 4 recapture flag

Example:

```
if(tmr_flag_get(TMR1, TMR_OVF_FLAG) != RESET)
```

5.18.45 tmr_flag_clear function

The table below describes the function tmr_flag_clear.

Table 489. tmr_flag_clear function

Name	Description
Function name	tmr_flag_clear
Function prototype	void tmr_flag_clear(tmr_type *tmr_x, uint32_t tmr_flag);
Function description	Clear flag
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	tmr_flag: flag selection Refer to “tmr_flag” description for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
tmr_flag_clear(TMR1, TMR_OVF_FLAG);
```

5.18.46 tmr_event_sw_trigger function

The table below describes the function tmr_event_sw_trigger.

Table 490. tmr_event_sw_trigger function

Name	Description
Function name	tmr_event_sw_trigger
Function prototype	void tmr_event_sw_trigger(tmr_type *tmr_x, tmr_event_trigger_type tmr_event);
Function description	Software triggers TMR events
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR6 TMR15, TMR16, TMR17
Input parameter 2	tmr_event: select a TMR event to be triggered by software
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_event

Set TMR events triggered by software.

TMR_OVERFLOW_SWTRIG:	Overflow event
TMR_C1_SWTRIG:	Channel 1 event
TMR_C2_SWTRIG:	Channel 2 event
TMR_C3_SWTRIG:	Channel 3 event
TMR_C4_SWTRIG:	Channel 4 event
TMR_HALL_SWTRIG:	HALL event
TMR_TRIGGER_SWTRIG:	Trigger event
TMR_BRK_SWTRIG:	Brake event

Example:

<code>tmr_event_sw_trigger(TMR1, TMR_OVERFLOW_SWTRIG);</code>

5.18.47 tmr_output_enable function

The table below describes the function tmr_output_enable.

Table 491. tmr_output_enable function

Name	Description
Function name	<code>tmr_output_enable</code>
Function prototype	<code>void tmr_output_enable(tmr_type *tmr_x, confirm_state new_state);</code>
Function description	Enable or disable TMR output
Input parameter 1	<code>tmr_x</code> : select TMR peripheral, including: TMR1, TMR15, TMR16, TMR17
Input parameter 2	<code>new_state</code> : TMR output status This parameter can be Enable (TRUE) or Disable (FALSE).
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

<code>tmr_output_enable(TMR1, TRUE);</code>

5.18.48 tmr_internal_clock_set function

The table below describes the function tmr_internal_clock_set.

Table 492. tmr_internal_clock_set function

Name	Description
Function name	<code>tmr_internal_clock_set</code>
Function prototype	<code>void tmr_internal_clock_set(tmr_type *tmr_x);</code>
Function description	Set TMR internal clock
Input parameter	<code>tmr_x</code> : select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

<code>tmr_internal_clock_set(TMR1);</code>
--

5.18.49 tmr_output_channel_polarity_set function

The table below describes the function tmr_output_channel_polarity_set.

Table 493. tmr_output_channel_polarity_set function

Name	Description
Function name	tmr_output_channel_polarity_set
Function prototype	void tmr_output_channel_polarity_set(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, tmr_polarity_active_type oc_polarity);
Function description	Set TMR output channel polarity
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	tmr_channel: Timer channel
Input parameter 3	oc_polarity: output channel polarity
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_channel

Select a TMR channel.

TMR_SELECT_CHANNEL_1:	Timer channel 1
TMR_SELECT_CHANNEL_1C:	Complementary channel 1
TMR_SELECT_CHANNEL_2:	Timer channel 2
TMR_SELECT_CHANNEL_2C:	Complementary channel 2
TMR_SELECT_CHANNEL_3:	Timer channel 3
TMR_SELECT_CHANNEL_3C:	Complementary channel 3
TMR_SELECT_CHANNEL_4:	Timer channel 4
TMR_SELECT_CHANNEL_4C:	Complementary channel 4

oc_polarity

Select TMR channel polarity.

TMR_POLARITY_ACTIVE_HIGH: Active high

TMR_POLARITY_ACTIVE_LOW: Active low

Example:

```
tmr_output_channel_polarity_set(TMR1, TMR_SELECT_CHANNEL_1, TMR_POLARITY_ACTIVE_HIGH);
```

5.18.50 tmr_external_clock_config function

The table below describes the function tmr_external_clock_config.

Table 494. tmr_external_clock_config function

Name	Description
Function name	tmr_external_clock_config
Function prototype	void tmr_external_clock_config(tmr_type *tmr_x, tmr_external_signal_divider_type es_divide, tmr_external_signal_polarity_type es_polarity, uint16_t es_filter);
Function description	Configure TMR external clock
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4
Input parameter 2	es_divide: external signal frequency division factor
Input parameter 3	es_polarity: external signal polarity
Input parameter 4	es_filter: external signal filter value, 0x00~0x0F
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

es_divide

Set TMR external signal frequency division factor.

TMR_ES_FREQUENCY_DIV_1: Divided by 1

TMR_ES_FREQUENCY_DIV_2: Divided by 2

TMR_ES_FREQUENCY_DIV_4: Divided by 4

TMR_ES_FREQUENCY_DIV_8: Divided by 8

es_polarity

Select TMR external signal polarity.

TMR_ES_POLARITY_NON_INVERTED: High or rising edge

TMR_ES_POLARITY_INVERTED: Low or falling edge

Example:

```
tmr_external_clock_config(TMR1, TMR_ES_FREQUENCY_DIV_1, TMR_ES_POLARITY_INVERTED, 0x0F);
```

5.18.51 tmr_external_clock_mode1_config function

The table below describes the function tmr_external_clock_mode1_config.

Table 495. tmr_external_clock_mode1_config function

Name	Description
Function name	tmr_external_clock_mode1_config
Function prototype	void tmr_external_clock_mode1_config(tmr_type *tmr_x, tmr_external_signal_divider_type es_divide, tmr_external_signal_polarity_type es_polarity, uint16_t es_filter);
Function description	Configure TMR external clock mode 1 (corresponding to external mode A in the reference manual)
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3 and TMR4
Input parameter 2	es_divide: external signal frequency division factor
Input parameter 3	es_polarity: external signal polarity
Input parameter 4	es_filter: external signal filter value, 0x00~0x0F
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

es_divide

Set TMR external signal frequency division factor; refer to [es_divide](#) for details.

es_polarity

Set TMR external signal polarity; refer to [es_polarity](#) for details.

Example:

```
tmr_external_clock_mode1_config(TMR1, TMR_ES_FREQUENCY_DIV_1, TMR_ES_POLARITY_INVERTED,
0x0F);
```

5.18.52 tmr_external_clock_mode2_config function

The table below describes the function tmr_external_clock_mode2_config.

Table 496. tmr_external_clock_mode2_config function

Name	Description
Function name	tmr_external_clock_mode2_config
Function prototype	void tmr_external_clock_mode2_config(tmr_type *tmr_x, tmr_external_signal_divider_type es_divide, tmr_external_signal_polarity_type es_polarity, uint16_t es_filter);
Function description	Configure TMR external clock mode 2 (corresponding to external mode B in the reference manual)
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3 and TMR4
Input parameter 2	es_divide: external signal frequency division factor
Input parameter 3	es_polarity: external signal polarity
Input parameter 4	es_filter: external signal filter value, 0x00~0x0F
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

es_divide

Set TMR external signal frequency division factor; refer to [es_divide](#) for details.

es_polarity

Set TMR external signal polarity; refer to [es_polarity](#) for details.

Example:

```
tmr_external_clock_mode2_config(TMR1, TMR_ES_FREQUENCY_DIV_1, TMR_ES_POLARITY_INVERTED,
0x0F);
```

5.18.53 tmr_encoder_mode_config function

The table below describes the function tmr_encoder_mode_config.

Table 497. tmr_encoder_mode_config function

Name	Description
Function name	tmr_encoder_mode_config
Function prototype	void tmr_encoder_mode_config(tmr_type *tmr_x, tmr_encoder_mode_type encoder_mode, tmr_input_polarity_type ic1_polarity, tmr_input_polarity_type ic2_polarity);
Function description	Configure TMR encoder mode
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4
Input parameter 2	encoder_mode: encoder mode
Input parameter 3	ic1_polarity: input channel 1 polarity
Input parameter 4	ic2_polarity: input channel 2 polarity
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

encoder_mode

Select a TMR encoder mode.

TMR_ENCODER_MODE_A: Encoder mode A

TMR_ENCODER_MODE_B: Encoder mode B

TMR_ENCODER_MODE_C: Encoder mode C

TMR_ENCODER_MODE_D: Encoder mode D

TMR_ENCODER_MODE_E: Encoder mode E

ic1_polarity

Select TMR input channel 1 polarity.

TMR_INPUT_RISING_EDGE: Rising edge

TMR_INPUT_FALLING_EDGE: Falling edge

TMR_INPUT_BOTH_EDGE: Both edges (rising edge and falling edge)

ic2_polarity

Select TMR input channel 2 polarity.

TMR_INPUT_RISING_EDGE: Rising edge

TMR_INPUT_FALLING_EDGE: Falling edge

TMR_INPUT_BOTH_EDGE: Both edges (rising edge and falling edge)

Example:

```
tmr_encoder_mode_config(TMR1, TMR_ENCODER_MODE_A, TMR_INPUT_RISING_EDGE,  
TMR_INPUT_RISING_EDGE);
```

5.18.54 tmr_force_output_set function

The table below describes the function tmr_force_output_set.

Table 498. tmr_force_output_set function

Name	Description
Function name	tmr_force_output_set
Function prototype	void tmr_force_output_set(tmr_type *tmr_x, tmr_channel_select_type tmr_channel, tmr_force_output_type force_output);
Function description	Set TMR forced output
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	tmr_channel: timer channel
Input parameter 3	force_output: forced output level
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_channel

Select a TMR channel.

TMR_SELECT_CHANNEL_1: Timer channel 1

TMR_SELECT_CHANNEL_2: Timer channel 2

TMR_SELECT_CHANNEL_3: Timer channel 3

TMR_SELECT_CHANNEL_4: Timer channel 4

force_output

Forced output level of output channels.

TMR_FORCE_OUTPUT_HIGH: CxORAW forced high

TMR_FORCE_OUTPUT_LOW: CxORAW forced low

Example:

```
tmr_force_output_set(TMR1, TMR_SELECT_CHANNEL_1, TMR_FORCE_OUTPUT_HIGH);
```

5.18.55 tmr_dma_control_config function

The table below describes the function tmr_dma_control_config.

Table 499. tmr_dma_control_config function

Name	Description
Function name	tmr_dma_control_config
Function prototype	void tmr_dma_control_config(tmr_type *tmr_x, tmr_dma_transfer_length_type dma_length, tmr_dma_address_type dma_base_address);
Function description	Configure TMR DMA control
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR3, TMR4, TMR15, TMR16, TMR17
Input parameter 2	dma_length: DMA transfer length
Input parameter 3	dma_base_address: DMA transfer offset address
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

dma_length

Set DAM transfer bytes, including:

TMR_DMA_TRANSFER_1BYTE: 1 byte

TMR_DMA_TRANSFER_2BYTES: 2 bytes

TMR_DMA_TRANSFER_3BYTES: 3 bytes

...

TMR_DMA_TRANSFER_17BYTES: 17 bytes

TMR_DMA_TRANSFER_18BYTES: 18 bytes

dma_base_address

Set DMA transfer offset address, starting from TMR control register 1, including:

TMR_CTRL1_ADDRESS

TMR_CTRL2_ADDRESS

TMR_STCTRL_ADDRESS

TMR_IDEN_ADDRESS

TMRISTS_ADDRESS

TMR_SWEVT_ADDRESS

TMR_CM1_ADDRESS

TMR_CM2_ADDRESS

TMR_CCTRL_ADDRESS

TMR_CVAL_ADDRESS

TMR_DIV_ADDRESS

TMR_PR_ADDRESS

TMR_RPR_ADDRESS

TMR_C1DT_ADDRESS

TMR_C2DT_ADDRESS

TMR_C3DT_ADDRESS

TMR_C4DT_ADDRESS

TMR_BRK_ADDRESS

TMR_DMACTRL_ADDRESS

Example:

```
tmr_dma_control_config(TMR1, TMR_DMA_TRANSFER_8BYTES, TMR_CTRL1_ADDRESS);
```

5.18.56 tmr_brkdt_config function

The table below describes the function tmr_brkdt_config.

Table 500. tmr_brkdt_config function

Name	Description
Function name	tmr_brkdt_config
Function prototype	void tmr_brkdt_config(tmr_type *tmr_x, tmr_brkdt_config_type *brkdt_struct);
Function description	Configure TMR brake mode and dead time
Input parameter 1	tmr_x: select TMR peripheral, including: TMR1, TMR15, TMR16, TMR17
Input parameter 2	brkdt_struct: tmr_brkdt_config_type pointer
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

tmr_brkdt_config_type structure

tmr_brkdt_config_type is defined in the “at32f422_426_tmr.h”.

typedef struct

```
{
    uint8_t                      deadtime;
    tmr_brk_polarity_type        brk_polarity;
    tmr_wp_level_type            wp_level;
    confirm_state                auto_output_enable;
    confirm_state                fcsoen_state;
    confirm_state                fcsodis_state;
    uint8_t                      brk_filter;
    confirm_state                brk_enable;
}
```

} tmr_brkdt_config_type;

deadtime

Set dead time, between 0x00~0xFF

brk_polarity

Select brake input polarity

TMR_BRK_INPUT_ACTIVE_LOW: Active low

TMR_BRK_INPUT_ACTIVE_HIGH: Active high

wp_level

Set write protection level.

TMR_WP_OFF: Write protection OFF

TMR_WP_LEVEL_3:

Level 3 write protection, protecting the bits below:

- TMRx_BRK: DTC, BRKEN, BRKV and AOEN

- TMRx_CTRL2: CxIOS and CxCIOS

TMR_WP_LEVEL_2:

Level 2 write protection, protecting the bits below in addition to level-3 protected bits:

- TMRx_CCTRL: CxP and CxCP
- TMRx_BRK: FCSODIS and FCSOEN

TMR_WP_LEVEL_1:

Level 1 write protection, protecting the bits below in addition to level-2 protected bits:

- TMRx_CMx: CxOCTRL and CxOBEN

auto_output_enable

Enable auto output; enable (TRUE) or disable (FALSE)

fcsoen_state

Indicates the frozen status when main output is ON. It is used to configure the status of complementary output channels when timer is OFF and output is enabled (OEN=1).

FALSE: Disable CxOUT/CxCOUT output

TRUE: Enable CxOUT/CxCOUT output, inactive level

fcsodis_state

Indicates the frozen status when main output is OFF. It is used to configure the status of complementary output channels when timer is OFF and output is disabled (OEN=0).

FALSE: Disable CxOUT/CxCOUT output

TRUE: Enable CxOUT/CxCOUT output, idle level

brk_filter

Set brake input filter, between 0x00~0x0F

brk_enable

Enable brake feature; enable (TRUE) or disable (FALSE).

Example:

```
tmr_brkdt_config_type tmr_brkdt_config_struct;
tmr_brkdt_config_struct.brk_enable = TRUE;
tmr_brkdt_config_struct.auto_output_enable = TRUE;
tmr_brkdt_config_struct.deadtime = 0;
tmr_brkdt_config_struct.fcsodis_state = TRUE;
tmr_brkdt_config_struct.fcsoen_state = TRUE;
tmr_brkdt_config_struct.brk_polarity = TMR_BRK_INPUT_ACTIVE_HIGH;
tmr_brkdt_config_struct.wp_level = TMR_WP_OFF;
tmr_brkdt_config(TMR1, &tmr_brkdt_config_struct);
```

5.18.57 tmr_iremap_config function

The table below describes the function tmr_iremap_config.

Table 501. tmr_iremap_config function

Name	Description
Function name	tmr_iremap_config
Function prototype	void tmr_iremap_config(tmr_type *tmr_x, tmr_input_remap_type input_remap);
Function description	Set TMR internal channel remapping
Input parameter 1	tmr_x: select TMR peripheral. It can be TMR4.
Input parameter 2	input_remap: TMR input channel remap to be configured
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

input_remap

Set TMR4 channel 1 input remapping.

TMR4_GPIO: TMR4 channel 1 is connected to GPIO

TMR4_ERTCCLK: TMR4 channel 1 is connected to ERTC

TMR4_HEXT_DIV32: TMR4 channel 1 is connected to HEXT/32

TMR4_CLKOUT: TMR4 channel 1 is connected to CLKOUT

Example:

```
tmr_iremap_config(TMR4, TMR4_HEXT_DIV32);
```

5.19 Universal synchronous/asynchronous receiver/transmitter (USART)

The USART register structure usart_type is defined in the “at32f422_426_usart.h”.

```
/*
 * @brief type define usart register all
 */
typedef struct
{
    ...
} usart_type;
```

The table below gives a list of the USART registers.

Table 502. Summary of USART registers

Register	Description
sts	Status register
dt	Data register
baudr	Baud rate register
ctrl1	Control register 1
ctrl2	Control register 2
ctrl3	Control register 3
gdiv	Guard time and divider control register
rtoi	Receiver timeout detection value register
ifc	Interrupt flag clear register

The table below gives a list of USART library functions.

Table 503. Summary of USART library functions

Function name	Description
usart_reset	Reset USART peripheral registers
usart_init	Set baud rate, data bits and stop bits
usart_parity_selection_config	Parity selection
usart_enable	Enable USART peripherals
usart_transmitter_enable	Enable USART transmitter
usart_receiver_enable	Enable USART receiver
usart_clock_config	Set clock polarity and phases for synchronization
usart_clock_enable	Set clock output for synchronization
usart_interrupt_enable	Enable interrupts
usart_dma_transmitter_enable	Enable DMA transmitter
usart_dma_receiver_enable	Enable DMA receiver
usart_wakeup_id_set	Set wakeup ID
usart_wakeup_mode_set	Set wakeup mode
usart_receiver_mute_enable	Enable receiver mute mode
usart_break_bit_num_set	Set break frame length
usart_lin_mode_enable	Enable LIN mode

uart_data_transmit	Data transmit
uart_data_receive	Data receive
uart_break_send	Send break frame
uart_smartcard_guard_time_set	Set smartcard guard time
uart_irda_smartcard_division_set	Set infrared and smartcard division
uart_smartcard_mode_enable	Enable smartcard mode
uart_smartcard_nack_set	Enable smartcard NACK
uart_single_line_halfduplex_select	Enable single-wire half-duplex mode
uart_irda_mode_enable	Enable infrared mode
uart_irda_low_power_enable	Enable infrared low-power mode
uart_hardware_flow_control_set	Enable hardware flow control
uart_flag_get	Get flag
uart_interrupt_flag_get	Get USART interrupt flag status
uart_flag_clear	Clear flag
uart_rs485_delay_time_config	Set latency for starting or ending consecutive data transmission in RS485
uart_transmit_receive_pin_swap	Swap transmit/receive pins
uart_de_polarity_set	DE signal polarity selection
uart_rs485_mode_enable	RS485 mode enable
uart_dt_polarity_reverse	Enable data polarity reverse mode
uart_transmit_pin_polarity_reverse	Enable data TX pin polarity reverse mode
uart_receive_pin_polarity_reverse	Enable data RX pin polarity reverse mode
uart_receiver_timeout_detection_enable	Enable data receive timeout detection
uart_receiver_timeout_value_set	Set data receive timeout value

5.19.1 usart_reset function

The table below describes the function usart_reset.

Table 504. usart_reset function

Name	Description
Function name	usart_reset
Function prototype	void usart_reset(usart_type* usart_x);
Function description	Reset USART peripheral registers
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	crm_periph_reset

Example:

```
/* reset usart1 */
usart_reset(USART1);
```

5.19.2 usart_init function

The table below describes the function usart_init.

Table 505. usart_init function

Name	Description
Function name	usart_init
Function prototype	void usart_init(usart_type* usart_x, uint32_t baud_rate, usart_data_bit_num_type data_bit, usart_stop_bit_num_type stop_bit);
Function description	Set baud rate, data bits and stop bits.
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	baud_rate: baud rate for serial interfaces
Input parameter 3	data_bit: data bit width for serial interfaces
Input parameter 4	stop_bit: stop bit width for serial interfaces
Output parameter	NA
Return value	NA
Required preconditions	This operation can be allowed only when external low-speed clock is disabled.
Called functions	NA

data_bit

Select data bit size for serial interface communication.

USART_DATA_7BITS: 7-bit

USART_DATA_8BITS: 8-bit

USART_DATA_9BITS: 9-bit

stop_bit

Select stop bit size for serial interface communication.

USART_STOP_1_BIT: 1 bit

USART_STOP_0_5_BIT: 0.5 bit

USART_STOP_2_BIT: 2 bits

USART_STOP_1_5_BIT: 1.5 bits

Example:

```
/* configure uart param */  
usart_init(USART1, 115200, USART_DATA_8BITS, USART_STOP_1_BIT);
```

5.19.3 usart_parity_selection_config function

The table below describes the function usart_parity_selection_config.

Table 506. usart_parity_selection_config function

Name	Description
Function name	usart_parity_selection_config
Function prototype	void usart_parity_selection_config(usart_type* usart_x, usart_parity_selection_type parity);
Function description	Parity method selection
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	parity: parity mode for serial interface communication
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

parity

Select parity mode for serial interface communication.

USART_PARITY_NONE: No parity

USART_PARITY EVEN: Even

USART_PARITY ODD: Odd

Example:

```
/* config usart even parity */
usart_parity_selection_config(USART1, USART_PARITY EVEN);
```

5.19.4 usart_enable function

The table below describes the function usart_enable.

Table 507. usart_enable function

Name	Description
Function name	usart_enable
Function prototype	void usart_enable(usart_type* usart_x, confirm_state new_state);
Function description	Enable USART
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable usart1 */
usart_enable(USART1, TRUE);
```

5.19.5 usart_transmitter_enable function

The table below describes the function usart_transmitter_enable.

Table 508. usart_transmitter_enable function

Name	Description
Function name	usart_transmitter_enable
Function prototype	void usart_transmitter_enable(usart_type* usart_x, confirm_state new_state);
Function description	Enable USART transmitter
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable usart1 transmitter */
usart_transmitter_enable(USART1, TRUE);
```

5.19.6 usart_receiver_enable function

The table below describes the function usart_receiver_enable.

Table 509. usart_receiver_enable function

Name	Description
Function name	usart_receiver_enable
Function prototype	void usart_receiver_enable(usart_type* usart_x, confirm_state new_state);
Function description	Enable USART receiver
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable usart1 receiver */
usart_receiver_enable(USART1, TRUE);
```

5.19.7 usart_clock_config function

The table below describes the function usart_clock_config.

Table 510. usart_clock_config function

Name	Description
Function name	usart_clock_config
Function prototype	void usart_clock_config(usart_type* usart_x, usart_clock_polarity_type clk_pol, usart_clock_phase_type clk_ph, usart_lbc_type clk_lb);
Function description	Configure clock polarity and phase for synchronization feature
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	clk_pol: clock polarity for synchronization
Input parameter 3	clk_ph: clock phase for synchronization
Input parameter 4	clk_lb: selects whether to output clock on the last bit (MSB) of data sent through synchronization feature
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

clk_pol

Clock polarity selection.

USART_CLOCK_POLARITY_LOW: Low

USART_CLOCK_POLARITY_HIGH: High

clk_ph

Clock phase selection.

USART_CLOCK_PHASE_1EDGE: 1st edge

USART_CLOCK_PHASE_2EDGE: 2nd edge

clk_lb

Select whether to output clock on the last bit of data.

USART_CLOCK_LAST_BIT_NONE: No clock output

USART_CLOCK_LAST_BIT_OUTPUT: Clock output

Example:

```
/* config synchronous mode */
usart_clock_config(USART1, USART_CLOCK_POLARITY_HIGH, USART_CLOCK_PHASE_2EDGE,
USART_CLOCK_LAST_BIT_OUTPUT);
```

5.19.8 usart_clock_enable function

The table below describes the function usart_clock_enable.

Table 511. usart_clock_enable function

Name	Description
Function name	usart_clock_enable
Function prototype	void usart_clock_enable(usart_type* usart_x, confirm_state new_state);
Function description	Enable clock output
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable clock */
usart_clock_enable(USART1, TRUE);
```

5.19.9 usart_interrupt_enable function

The table below describes the function usart_interrupt_enable.

Table 512. usart_interrupt_enable function

Name	Description
Function name	usart_interrupt_enable
Function prototype	void usart_interrupt_enable(usart_type* usart_x, uint32_t usart_int, confirm_state new_state);
Function description	Enable interrupts
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	usart_int: interrupt type
Input parameter 3	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

usart_int

Defines a peripheral interrupt.

- USART_IDLE_INT: Bus idle
- USART_RDBF_INT: Receive data buffer full
- USART_TDC_INT: Transmit data complete
- USART_TDBE_INT: Transmit data buffer empty
- USART_PERR_INT: Parity error
- USART_BF_INT: Break frame receive
- USART_ERR_INT: Error interrupt
- USART_CTSCF_INT: CTS (Clear To Send) change

Example:

```
/* enable usart1 transmit complete interrupt */
usart_interrupt_enable (USART1, USART_TDC_INT, TRUE);
```

5.19.10 usart_dma_transmitter_enable function

The table below describes the function usart_dma_transmitter_enable.

Table 513. usart_dma_transmitter_enable function

Name	Description
Function name	usart_dma_transmitter_enable
Function prototype	void usart_dma_transmitter_enable(usart_type* usart_x, confirm_state new_state);
Function description	Enable DMA transmitter
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable dma transmitter */
usart_dma_transmitter_enable (USART1, TRUE);
```

5.19.11 usart_dma_receiver_enable function

The table below describes the function usart_dma_receiver_enable.

Table 514. usart_dma_receiver_enable function

Name	Description
Function name	usart_dma_receiver_enable
Function prototype	void usart_dma_receiver_enable(usart_type* usart_x, confirm_state new_state);
Function description	Enable DMA receiver
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable dma receiver */
usart_dma_receiver_enable (USART1, TRUE);
```

5.19.12 usart_wakeup_id_set function

The table below describes the function usart_wakeup_id_set.

Table 515. usart_wakeup_id_set function

Name	Description
Function name	usart_wakeup_id_set
Function prototype	void usart_wakeup_id_set(usart_type* usart_x, uint8_t usart_id);
Function description	Set wakeup ID
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	usart_id: wakeup ID
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* config wakeup id */  
usart_wakeup_id_set (USART1, 0x88);
```

5.19.13 usart_wakeup_mode_set function

The table below describes the function usart_wakeup_mode_set.

Table 516. usart_wakeup_mode_set function

Name	Description
Function name	usart_wakeup_mode_set
Function prototype	void usart_wakeup_mode_set(usart_type* usart_x, usart_wakeup_mode_type wakeup_mode);
Function description	Set wakeup mode
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	wakeup_mode: wakeup mode
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

wakeup_mode

Set wakeup mode to wake up from silent state.

USART_WAKEUP_BY_IDLE_FRAME: Woke up by idle frame

USART_WAKEUP_BY_MATCHING_ID: Woke up by ID matching

Example:

```
/* config usart1 wakeup mode */
usart_wakeup_mode_set (USART1, USART_WAKEUP_BY_MATCHING_ID);
```

5.19.14 usart_receiver_mute_enable function

The table below describes the function usart_receiver_mute_enable.

Table 517. usart_receiver_mute_enable function

Name	Description
Function name	usart_receiver_mute_enable
Function prototype	void usart_receiver_mute_enable(usart_type* usart_x, confirm_state new_state);
Function description	Enable USART receiver mute mode
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* config receiver mute */
usart_receiver_mute_enable (USART1, TRUE);
```

5.19.15 usart_break_bit_num_set function

The table below describes the function usart_break_bit_num_set.

Table 518. usart_break_bit_num_set function

Name	Description
Function name	usart_break_bit_num_set
Function prototype	void usart_break_bit_num_set(usart_type* usart_x, usart_break_bit_num_type break_bit);
Function description	Set USART break frame length
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	break_bit: break frame length type
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

break_bit

Set break frame length.

USART_BREAK_10BITS: 10 bits

USART_BREAK_11BITS: 11 bits

Example:

```
/* config break frame length 10bits */
usart_break_bit_num_set (USART1, USART_BREAK_10BITS);
```

5.19.16 usart_lin_mode_enable function

The table below describes the function usart_lin_mode_enable.

Table 519. usart_lin_mode_enable function

Name	Description
Function name	usart_lin_mode_enable
Function prototype	void usart_lin_mode_enable(usart_type* usart_x, confirm_state new_state);
Function description	Enable LIN mode
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable usart1 lin mode */
usart_lin_mode_enable (USART1, TRUE);
```

5.19.17 usart_data_transmit function

The table below describes the function usart_data_transmit.

Table 520. usart_data_transmit function

Name	Description
Function name	usart_data_transmit
Function prototype	void usart_data_transmit(usart_type* usart_x, uint16_t data);
Function description	Transmit data
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	data: data to be sent
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* transmit data */  
uint16_t data = 0x88;  
usart_data_transmit (USART1, data);
```

5.19.18 usart_data_receive function

The table below describes the function usart_data_receive.

Table 521. usart_data_receive function

Name	Description
Function name	usart_data_receive
Function prototype	uint16_t usart_data_receive(usart_type* usart_x);
Function description	Receive data
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	NA
Output parameter	NA
Return value	uint16_t: return the received data
Required preconditions	NA
Called functions	NA

Example:

```
/* receive data */  
uint16_t data = 0;  
data = usart_data_receive (USART1);
```

5.19.19 usart_break_send function

The table below describes the function usart_break_send.

Table 522. usart_break_send function

Name	Description
Function name	usart_break_send
Function prototype	void usart_break_send(usart_type* usart_x);
Function description	Send break frame
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* send break frame */
usart_break_send (USART1);
```

5.19.20 usart_smartcard_guard_time_set function

The table below describes the function usart_smartcard_guard_time_set.

Table 523. usart_smartcard_guard_time_set function

Name	Description
Function name	usart_smartcard_guard_time_set
Function prototype	void usart_smartcard_guard_time_set(usart_type* usart_x, uint8_t guard_time_val);
Function description	Set smartcard guard time
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	guard_time_val: guard time, 0x00~0xFF
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* usart guard time set to 2 bit */
usart_smartcard_guard_time_set(USART1, 0x2);
```

5.19.21 usart_irda_smartcard_division_set function

The table below describes the function usart_irda_smartcard_division_set.

Table 524. usart_irda_smartcard_division_set function

Name	Description
Function name	usart_irda_smartcard_division_set
Function prototype	void usart_irda_smartcard_division_set(usart_type* usart_x, uint8_t div_val);
Function description	Infrared and smartcard frequency division settings
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	div_val: division value
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* usart clock set to (apbclk / (2 * 20)) */
usart_irda_smartcard_division_set(USART1, 20);
```

5.19.22 usart_smartcard_mode_enable function

The table below describes the function usart_smartcard_mode_enable.

Table 525. usart_smartcard_mode_enable function

Name	Description
Function name	usart_smartcard_mode_enable
Function prototype	void usart_smartcard_mode_enable(usart_type* usart_x, confirm_state new_state);
Function description	Enable smartcode mode
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable the smartcard mode */
usart_smartcard_mode_enable(USART1, TRUE);
```

5.19.23 usart_smartcard_nack_set function

The table below describes the function usart_smartcard_nack_set.

Table 526. usart_smartcard_nack_set function

Name	Description
Function name	usart_smartcard_nack_set
Function prototype	void usart_smartcard_nack_set(usart_type* usart_x, confirm_state new_state);
Function description	Enable smartcard NACK
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable the nack transmission */
usart_smartcard_nack_set(USART1, TRUE);
```

5.19.24 usart_single_line_halfduplex_select function

The table below describes the function usart_single_line_halfduplex_select.

Table 527. usart_single_line_halfduplex_select function

Name	Description
Function name	usart_single_line_halfduplex_select
Function prototype	void usart_single_line_halfduplex_select(usart_type* usart_x, confirm_state new_state);
Function description	Enable single-wire half-duplex mode
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable halfduplex */
usart_single_line_halfduplex_select(USART1, TRUE);
```

5.19.25 usart_irda_mode_enable function

The table below describes the function usart_irda_mode_enable.

Table 528. usart_irda_mode_enable function

Name	Description
Function name	usart_irda_mode_enable
Function prototype	void usart_irda_mode_enable(usart_type* usart_x, confirm_state new_state);
Function description	Enable infrared mode
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable irda mode */
usart_irda_mode_enable(USART1, TRUE);
```

5.19.26 usart_irda_low_power_enable function

The table below describes the function usart_irda_low_power_enable.

Table 529. usart_irda_low_power_enable function

Name	Description
Function name	usart_irda_low_power_enable
Function prototype	void usart_irda_low_power_enable(usart_type* usart_x, confirm_state new_state);
Function description	Enable infrared low-power mode
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable irda lowpower mode */
usart_irda_low_power_enable (USART1, TRUE);
```

5.19.27 usart_hardware_flow_control_set function

The table below describes the function usart_hardware_flow_control_set.

Table 530. usart_hardware_flow_control_set function

Name	Description
Function name	usart_hardware_flow_control_set
Function prototype	void usart_hardware_flow_control_set(usart_type* usart_x, usart_hardware_flow_control_type flow_state);
Function description	Set peripheral hardware flow control
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	flow_state: flow control type
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

flow_state

USART_HARDWARE_FLOW_NONE:	No hardware flow control
USART_HARDWARE_FLOW_RTS:	RTS
USART_HARDWARE_FLOW_CTS:	CTS
USART_HARDWARE_FLOW_RTS_CTS:	RTS and CTS

Example:

```
/* hardware flow set none */
usart_hardware_flow_control_set (USART1, USART_HARDWARE_FLOW_NONE);
```

5.19.28 usart_flag_get function

The table below describes the function usart_flag_get.

Table 531. usart_flag_get function

Name	Description
Function name	usart_flag_get
Function prototype	flag_status usart_flag_get(usart_type* usart_x, uint32_t flag);
Function description	Get flag status
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	flag: flag selection
Output parameter	NA
Return value	flag_status: flag status; SET or RESET
Required preconditions	NA
Called functions	NA

flag

USART_CTSCF_FLAG:	CTS (Clear To Send) change flag
USART_BFF_FLAG:	Break frame receive flag
USART_TDBE_FLAG:	Transmit buffer empty flag
USART_TDC_FLAG:	Transmit complete flag
USART_RDBF_FLAG:	Receive data buffer full flag
USART_IDLEF_FLAG:	Idle frame flag

USART_ROERR_FLAG:	Receive overflow flag
USART_NERR_FLAG:	Noise error flag
USART_FERR_FLAG:	Frame error flag
USART_PERR_FLAG:	Parity error flag

Example:

```
/* wait data transmit complete flag */
while(usart_flag_get (USART1, USART_TDC_FLAG) == RESET);
```

5.19.29 usart_interrupt_flag_get function

The table below describes the function usart_interrupt_flag_get.

Table 532. usart_interrupt_flag_get function

Name	Description
Function name	usart_interrupt_flag_get
Function prototype	flag_status usart_interrupt_flag_get(usart_type* usart_x, uint32_t flag);
Function description	Get interrupt flag status
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	flag: flag selection
Output parameter	NA
Return value	flag_status: flag status; return SET or RESET.
Required preconditions	NA
Called functions	NA

flag

USART_CTSCF_FLAG:	CTS (Clear To Send) change flag
USART_BFF_FLAG:	Break frame receive flag
USART_TDBE_FLAG:	Transmit buffer empty flag
USART_TDC_FLAG:	Transmit complete flag
USART_RDBF_FLAG:	Receive data buffer full flag
USART_IDLEF_FLAG:	Idle frame flag
USART_ROERR_FLAG:	Receive overflow flag
USART_NERR_FLAG:	Noise error flag
USART_FERR_FLAG:	Frame error flag
USART_PERR_FLAG:	Parity error flag

Example:

```
/* check received data flag */
if(usart_interrupt_flag_get(USART1, USART_RDBF_FLAG) != RESET)
{
}
```

5.19.30 usart_flag_clear function

The table below describes the function usart_flag_clear.

Table 533. usart_flag_clear function

Name	Description
Function name	usart_flag_clear
Function prototype	void usart_flag_clear(usart_type* usart_x, uint32_t flag);
Function description	Clear flag
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	flag: flag selection
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

flag

- USART_CTSFLAG: CTS (Clear To Send) change flag
- USART_BFFFLAG: Break frame receive flag
- USART_TDCFLAG: Transmit complete flag
- USART_RDBFFLAG: Receive data buffer full flag

Example:

```
/* clear data transmit complete flag */
usart_flag_clear (USART1, USART_TDCFLAG );
```

5.19.31 usart_rs485_delay_time_config function

The table below describes the function usart_rs485_delay_time_config.

Table 534. usart_rs485_delay_time_config function

Name	Description
Function name	usart_rs485_delay_time_config
Function prototype	void usart_rs485_delay_time_config(usart_type* usart_x, uint8_t start_delay_time, uint8_t complete_delay_time);
Function description	Delay time for setting and clearing data valid signal for continuous data transmission in RS485 mode
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	start_delay_time: After the first data is written in continuous transmit mode, data valid signal is set and "start_delay_time" is inserted before sending data. The time unit is 1/16 baud rate period.
Input parameter 3	complete_delay_time: After the last data is sent in continuous transmit mode, the "complete_delay_time" is inserted before clearing data valid signal. The time unit is 1/16 baud rate period.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* config rs485 delay time */
usart_rs485_delay_time_config(USART1, 2, 2);
```

5.19.32 usart_transmit_receive_pin_swap function

The table below describes the function usart_transmit_receive_pin_swap.

Table 535. usart_transmit_receive_pin_swap function

Name	Description
Function name	usart_transmit_receive_pin_swap
Function prototype	void usart_transmit_receive_pin_swap(usart_type* usart_x, confirm_state new_state);
Function description	Swap transmit/receive pins
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable tx/rx swap */
usart_transmit_receive_pin_swap (USART1, TRUE);
```

5.19.33 usart_de_polarity_set function

The table below describes the function usart_de_polarity_set.

Table 536. usart_de_polarity_set function

Name	Description
Function name	usart_de_polarity_set
Function prototype	void usart_de_polarity_set(usart_type* usart_x, usart_de_polarity_type de_polarity);
Function description	Set DE signal polarity
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	de_polarity: DE signal polarity
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

de_polarity

USART_DE_POLARITY_HIGH: Active high

USART_DE_POLARITY_LOW: Active low

Example:

```
/* config DE polarity */
usart_de_polarity_set(USART1, USART_DE_POLARITY_HIGH);
```

5.19.34 usart_rs485_mode_enable function

The table below describes the function usart_rs485_mode_enable.

Table 537. usart_rs485_mode_enable function

Name	Description
Function name	usart_rs485_mode_enable
Function prototype	void usart_rs485_mode_enable(usart_type* usart_x, confirm_state new_state);
Function description	RS485 mode enable
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable rs485 mode */
usart_rs485_mode_enable (USART1, TRUE);
```

5.19.35 usart_dt_polarity_reverse function

The table below describes the function usart_dt_polarity_reverse.

Table 538. usart_dt_polarity_reverse function

Name	Description
Function name	usart_dt_polarity_reverse
Function prototype	void usart_dt_polarity_reverse(usart_type* usart_x, confirm_state new_state);
Function description	Reverse data polarity
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable DT polarity reverse */
usart_dt_polarity_reverse (USART1, TRUE);
```

5.19.36 usart_transmit_pin_polarity_reverse function

The table below describes the function usart_transmit_pin_polarity_reverse.

Table 539. usart_transmit_pin_polarity_reverse function

Name	Description
Function name	usart_transmit_pin_polarity_reverse
Function prototype	void usart_transmit_pin_polarity_reverse (usart_type* usart_x, confirm_state new_state);
Function description	Reverse data transmit pin polarity
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable TX-pin polarity reverse */
usart_transmit_pin_polarity_reverse (USART1, TRUE);
```

5.19.37 usart_receive_pin_polarity_reverse function

The table below describes the function usart_receive_pin_polarity_reverse.

Table 540. usart_receive_pin_polarity_reverse function

Name	Description
Function name	usart_receive_pin_polarity_reverse
Function prototype	void usart_receive_pin_polarity_reverse (usart_type* usart_x, confirm_state new_state);
Function description	Reverse data receive pin polarity
Input parameter 1	usart_x: indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	new_state: Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable RX-pin polarity reverse */
usart_receive_pin_polarity_reverse (USART1, TRUE);
```

5.19.38 uart_receiver_timeout_detection_enable function

The table below describes the function `uart_receiver_timeout_detection_enable`.

Table 541. `uart_receiver_timeout_detection_enable` function

Name	Description
Function name	<code>uart_receiver_timeout_detection_enable</code>
Function prototype	<code>void uart_receiver_timeout_detection_enable(usart_type* usart_x, confirm_state new_state)</code>
Function description	Enable data receive timeout detection
Input parameter 1	<code>usart_x</code> : indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	<code>new_state</code> : Enable (TRUE) and disable (FALSE)
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* enable receiver timeout detection */
uart_receiver_timeout_detection_enable (USART1, TRUE);
```

5.19.39 uart_receiver_timeout_value_set function

The table below describes the function `uart_receiver_timeout_value_set`.

Table 542. `uart_receiver_timeout_value_set` function

Name	Description
Function name	<code>uart_receiver_timeout_value_set</code>
Function prototype	<code>void uart_receiver_timeout_value_set(usart_type* usart_x, uint32_t value);</code>
Function description	Set data receive timeout value
Input parameter 1	<code>usart_x</code> : indicates the selected peripherals. It can be USART1 and USART2...
Input parameter 2	<code>value</code> : data receive timeout threshold, in terms of 1-bit width
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
/* set receiver timeout detection value */
uart_receiver_timeout_value_set (USART1, 8);
```

5.20 Watchdog timer (WDT)

The WDT register structure `wdt_type` is defined in the “`at32f422_426_wdt.h`”.

```
/*
 * @brief type define wdt register all
 */
typedef struct
{
}
```

}

The table below gives a list of the WDT registers.

Table 543. Summary of WDT registers

Register	Description
cmd	Command register
div	Divider register
rld	Reload register
sts	Status register

The table below gives a list of WDT library functions.

Table 544. Summary of WDT library functions

Function name	Description
<code>wdt_enable</code>	Enable watchdog
<code>wdt_counter_reload</code>	Reload counter
<code>wdt_reload_value_set</code>	Set reload value
<code>wdt_divider_set</code>	Set division value
<code>wdt_register_write_enable</code>	Unlock WDT_DIV and WDT_RLD register write protection
<code>wdt_flag_get</code>	Get flag

5.20.1 `wdt_enable` function

The table below describes the function `wdt_enable`.

Table 545. `wdt_enable` function

Name	Description
Function name	<code>wdt_enable</code>
Function prototype	<code>void wdt_enable(void);</code>
Function description	Enable watchdog
Input parameter 1	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
wdt_enable();
```

5.20.2 **wdt_counter_reload** function

The table below describes the function `wdt_counter_reload`.

Table 546. `wdt_counter_reload` function

Name	Description
Function name	<code>wdt_counter_reload</code>
Function prototype	<code>void wdt_counter_reload(void);</code>
Function description	Reload counter
Input parameter 1	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
wdt_counter_reload();
```

5.20.3 **wdt_reload_value_set** function

The table below describes the function `wdt_reload_value_set`.

Table 547. `wdt_reload_value_set` function

Name	Description
Function name	<code>wdt_reload_value_set</code>
Function prototype	<code>void wdt_reload_value_set(uint16_t reload_value);</code>
Function description	Set reload value
Input parameter 1	reload_value: reload value, 0x000~0xFFFF
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
wdt_reload_value_set(0xFFFF);
```

5.20.4 wdt_divider_set function

The table below describes the function wdt_divider_set.

Table 548. wdt_divider_set function

Name	Description
Function name	wdt_divider_set
Function prototype	void wdt_divider_set(wdt_division_type division);
Function description	Set division value
Input parameter 1	division: watchdog division value Refer to the “division” description below for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

division

Select watchdog division value.

- WDT_CLK_DIV_4: Divided by 4
- WDT_CLK_DIV_8: Divided by 8
- WDT_CLK_DIV_16: Divided by 16
- WDT_CLK_DIV_32: Divided by 32
- WDT_CLK_DIV_64: Divided by 64
- WDT_CLK_DIV_128: Divided by 128
- WDT_CLK_DIV_256: Divided by 256

Example:

```
wdt_divider_set(WDT_CLK_DIV_4);
```

5.20.5 wdt_register_write_enable function

The table below describes the function wdt_register_write_enable.

Table 549. wdt_register_write_enable function

Name	Description
Function name	wdt_register_write_enable
Function prototype	void wdt_register_write_enable(confirm_state new_state);
Function description	Unlock WDT_DIV and WDT_RLD write protection
Input parameter 1	new_state: unlock register write protection This parameter can be TRUE or FALSE.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
wdt_register_write_enable(TRUE);
```

5.20.6 wdt_flag_get function

The table below describes the function wdt_flag_get.

Table 550. wdt_flag_get function

Name	Description
Function name	wdt_flag_get
Function prototype	flag_status wdt_flag_get(uint16_t wdt_flag);
Function description	Get flag status
Input parameter 1	flag: flag selection Refer to the “flag” description below flag
Output parameter	NA
Return value	flag_status: flag status Return SET or RESET.
Required preconditions	NA
Called functions	NA

flag

This is used for flag selection, including:

WDT_DIVF_UPDATE_FLAG: Division value update complete

WDT_RLDF_UPDATE_FLAG: Reload value update complete

Example:

```
wdt_flag_get(WDT_DIVF_UPDATE_FLAG);
```

5.21 Window watchdog timer (WWDT)

The WWDT register structure wwdt_type is defined in the “at32f422_426_wwdt.h”.

```
/*
 * @brief type define wwdt register all
 */
typedef struct
{

} wwdt_type;
```

The table below gives a list of the WWDT registers.

Table 551. Summary of WWDT registers

Register	Description
ctrl	Control register
cfg	Configuration register
sts	Status register

The table below gives a list of WWDT library functions.

Table 552. Summary of WWDT library functions

Function name	Description
wwdt_reset	Reset window watchdog registers
wwdt_divider_set	Set divider
wwdt_flag_clear	Clear reload counter interrupt flag
wwdt_enable	Enable WWDT
wwdt_interrupt_enable	Enable reload counter interrupt
wwdt_flag_get	Get flag
wwdt_counter_set	Set counter value
wwdt_window_counter_set	Set window value

5.21.1 wwdt_reset function

The table below describes the function wwdt_reset.

Table 553. wwdt_reset function

Name	Description
Function name	wwdt_reset
Function prototype	void wwdt_reset(void);
Function description	Reset window watchdog registers to their initial values.
Input parameter 1	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	void crrm_periph_reset(crrm_periph_reset_type value, confirm_state new_state);

Example:

```
wwdt_reset();
```

5.21.2 wwdt_divider_set function

The table below describes the function wwdt_divider_set.

Table 554. wwdt_divider_set function

Name	Description
Function name	wwdt_divider_set
Function prototype	void wwdt_divider_set(wwdt_division_type division);
Function description	Set divider
Input parameter 1	division: WWDT division value Refer to the “division” description below for details.
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

division

Select WWDT division value.

- WWDT_PCLK1_DIV_4096: Divided by 4096
- WWDT_PCLK1_DIV_8192: Divided by 8192
- WWDT_PCLK1_DIV_16384: Divided by 16384
- WWDT_PCLK1_DIV_32768: Divided by 32768

Example:

```
wwdt_divider_set(WWDT_PCLK1_DIV_4096);
```

5.21.3 wwdt_enable function

The table below describes the function wwdt_enable.

Table 555. wwdt_enable function

Name	Description
Function name	wwdt_enable
Function prototype	void wwdt_enable(uint8_t wwdt_cnt);
Function description	Enable WWDT
Input parameter 1	wwdt_cnt: WWDT counter initial value, 0x40~0x7F
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
wwdt_enable(0x7F);
```

5.21.4 wwdt_interrupt_enable function

The table below describes the function wwdt_interrupt_enable.

Table 556. wwdt_interrupt_enable function

Name	Description
Function name	wwdt_interrupt_enable
Function prototype	void wwdt_interrupt_enable(void);
Function description	Enable reload counter interrupt
Input parameter 1	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
wwdt_interrupt_enable();
```

5.21.5 wwdt_counter_set function

The table below describes the function wwdt_counter_set.

Table 557. wwdt_counter_set function

Name	Description
Function name	wwdt_counter_set
Function prototype	void wwdt_counter_set(uint8_t wwdt_cnt);
Function description	Set counter value
Input parameter 1	wwdt_cnt: WWDT counter value, 0x40~0x7F
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
wwdt_counter_set(0x7F);
```

5.21.6 wwdt_window_counter_set function

The table below describes the function wwdt_window_counter_set.

Table 558. wwdt_window_counter_set function

Name	Description
Function name	wwdt_window_counter_set
Function prototype	void wwdt_window_counter_set(uint8_t window_cnt);
Function description	Set window counter value
Input parameter 1	wwdt_cnt: WWDT window counter value,0x40~0x7F
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
wwdt_window_counter_set(0x6F);
```

5.21.7 wwdt_flag_get function

The table below describes the function wwdt_flag_get.

Table 559. wwdt_flag_get function

Name	Description
Function name	wwdt_flag_get
Function prototype	flag_status wwdt_flag_get(void);
Function description	Get reload counter interrupt flag
Input parameter 1	NA
Output parameter	NA
Return value	flag_status: flag status Return SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```
wwdt_flag_get();
```

5.21.8 wwdt_interrupt_flag_get function

The table below describes the function wwdt_interrupt_flag_get.

Table 560. wwdt_interrupt_flag_get function

Name	Description
Function name	wwdt_interrupt_flag_get
Function prototype	flag_status wwdt_interrupt_flag_get(void);
Function description	Get reload counter interrupt flag status, and check the corresponding interrupt enable bit.
Input parameter 1	NA
Output parameter	NA
Return value	flag_status: flag status Return SET or RESET.
Required preconditions	NA
Called functions	NA

Example:

```
wwdt_interrupt_flag_get();
```

5.21.9 wwdt_flag_clear function

The table below describes the function wwdt_flag_clear.

Table 561. wwdt_flag_clear function

Name	Description
Function name	wwdt_flag_clear
Function prototype	void wwdt_flag_clear(void);
Function description	Clear reload counter interrupt flag
Input parameter 1	NA
Output parameter	NA
Return value	NA
Required preconditions	NA
Called functions	NA

Example:

```
wwdt_flag_clear();
```

6 Precautions

6.1 Device model replacement

While replacing the device part number in an existing project or demo with another one, if necessary, it is necessary to check the macro definitions corresponding to the device defined in [Table 1](#) before replacement.

The subsequent sections give a detailed description of how to replace a device in KEIL and IAR environments (Just taking the at32f403avgt7 as an example as other devices share similar operations).

There are two steps to get this happen:

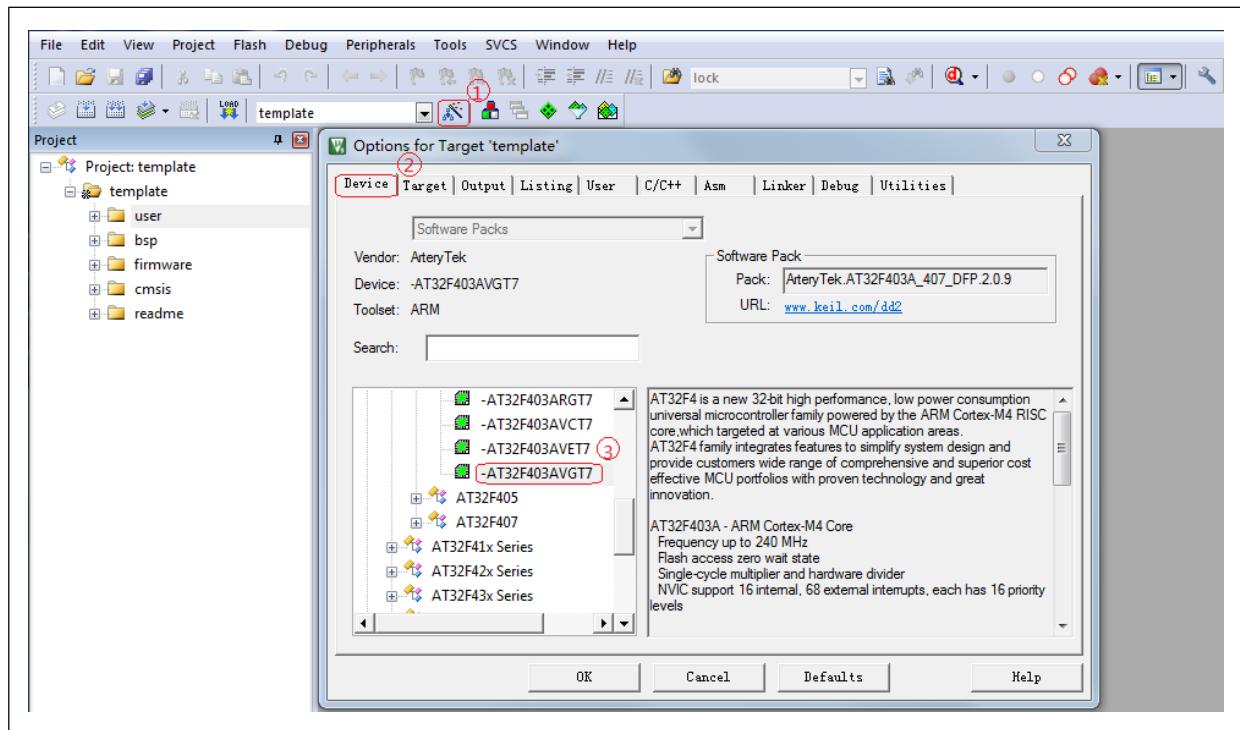
1. By changing device
2. By changing macro definition

6.1.1 KEIL environment

Follow the steps and illustration below for device replacement in Keil environment:

- ① Click on magic stick “Options for Target”
- ② Click on “Device”
- ③ Select the desired device part number

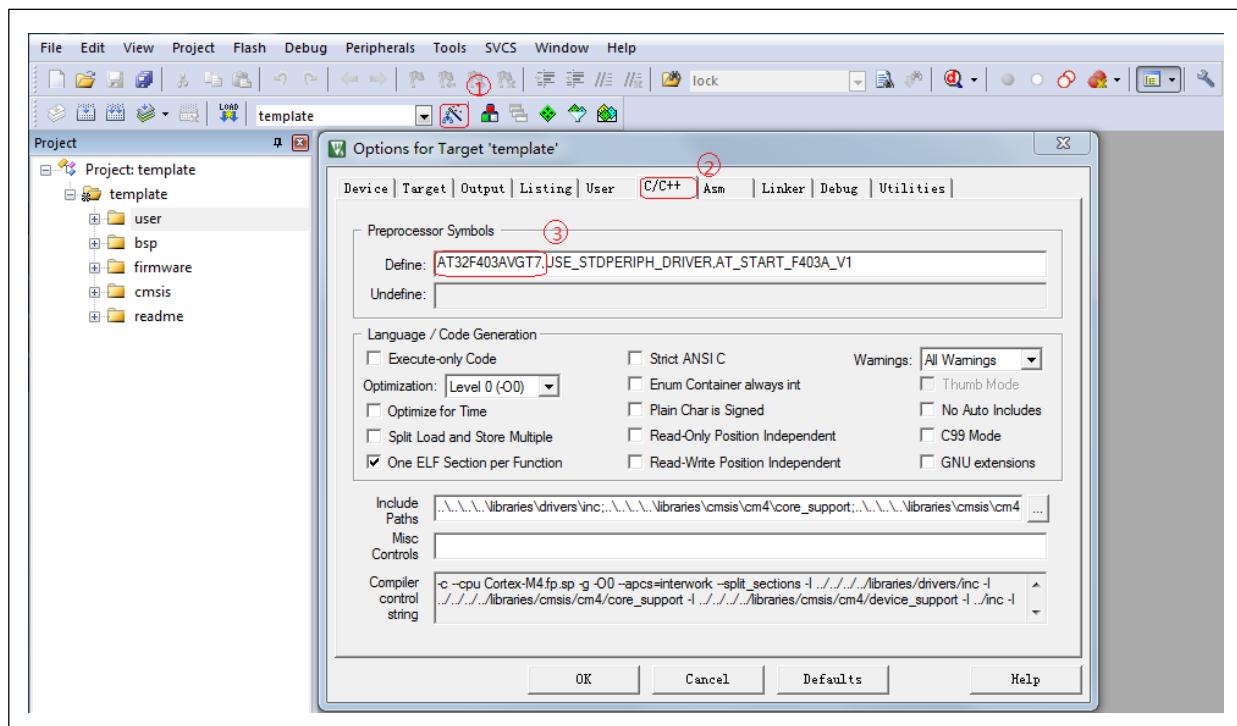
Figure 29. Change device part number in Keil



Follow the steps and illustration below to change macro definition.

- ① Click on magic stick “Options for Target”
- ② Click on “C/C++”
- ③ Delete the original macro definition in “Define” box, and write the desired one corresponding to the selected device part number based on [Table 1](#).

Figure 30. Change macro definition in Keil

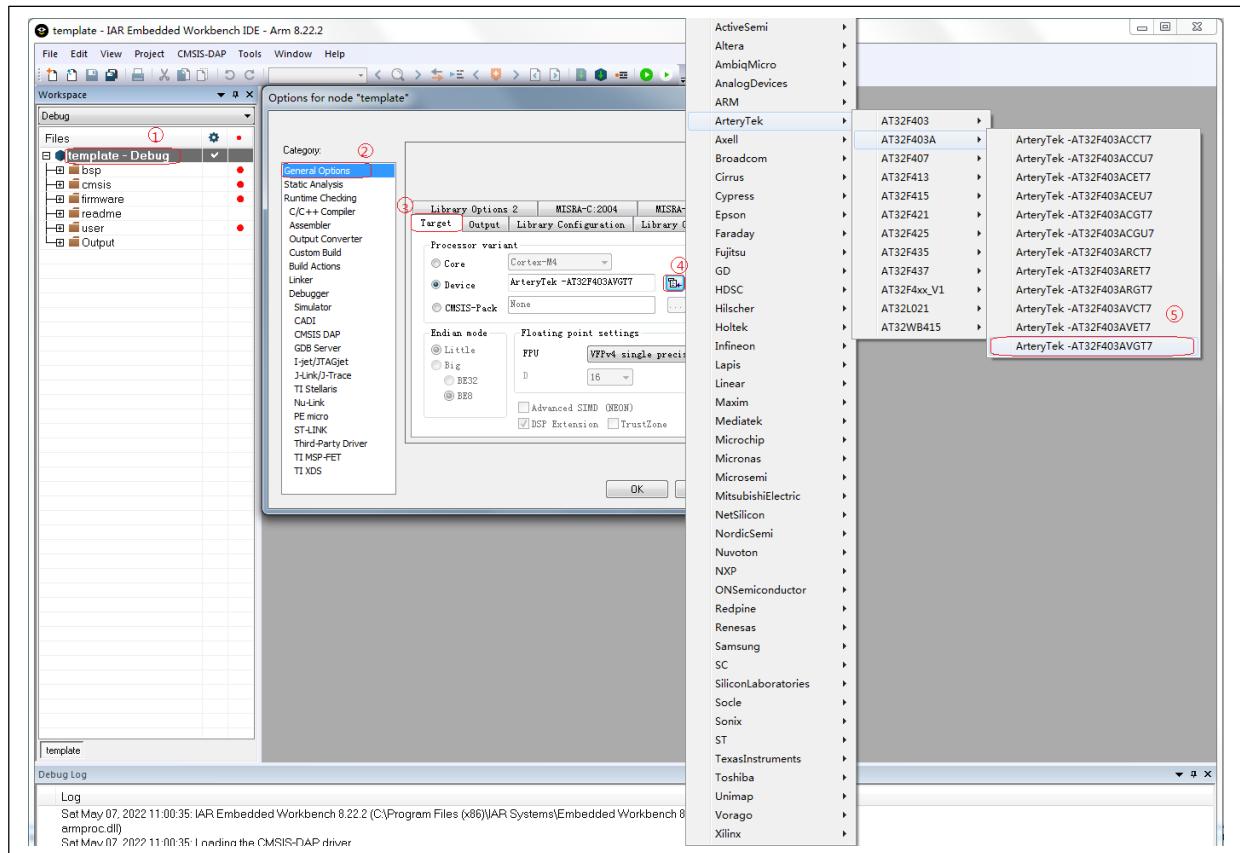


6.1.2 IAR environment

Follow the steps and illustration below for device replacement in IAR environment.

- ① Right click on the file name, and select “Options...”
- ② Select “General Options”
- ③ Select “Target”
- ④ Click on check box
- ⑤ Select the desired device part number.

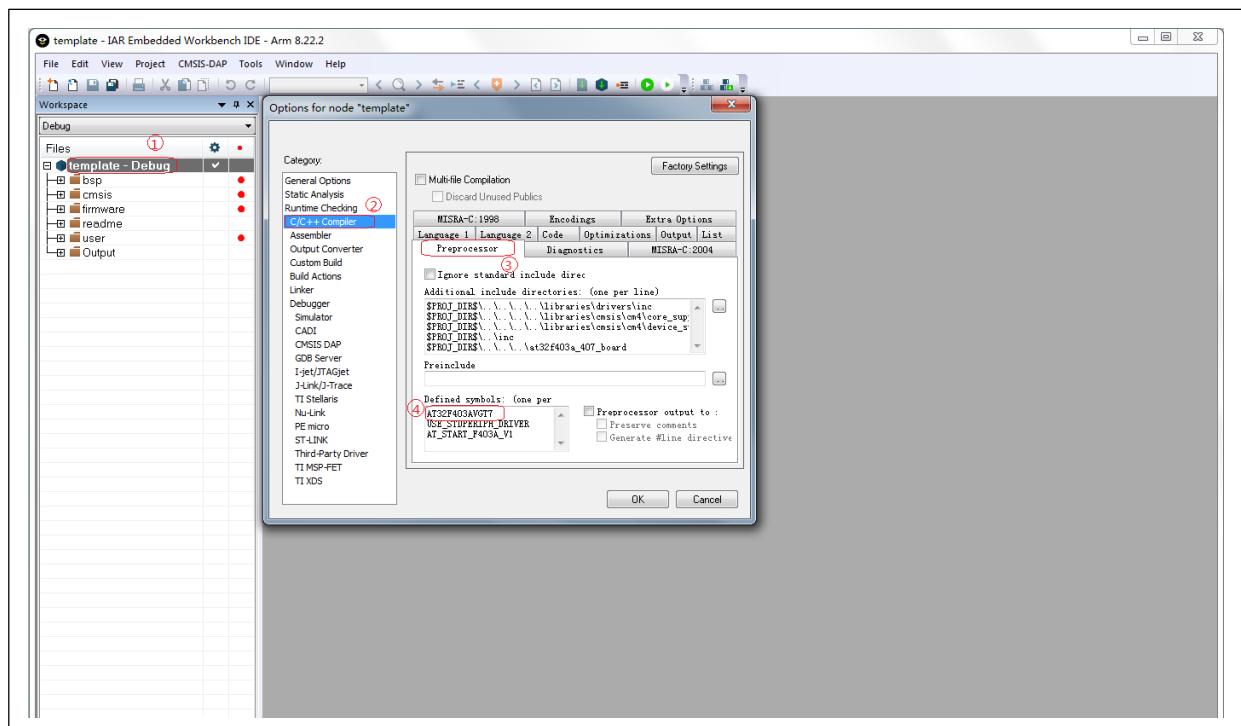
Figure 31. Change device part number in IAR



Follow the steps and illustration below to change macro definition in IAR environment.

- ① Right click on the file name, and select “Options...”
- ② Select “C/C++ Compiler”
- ③ Click on “Preprocessor”
- ④ Delete the original macro definition in “Defined symbols” column, and write the desired one corresponding to the selected device part number based on [Table 1](#).

Figure 32. Change macro definition in IAR



6.2 Unable to identify IC by JLink software in Keil

In special circumstances, the Keil project compiled by an engineer is unknown to the J-Link software even if it can be compiled by other engineers and identified by ICP software. For example, some warnings like below will be displayed.

Figure 33. Error warning 1

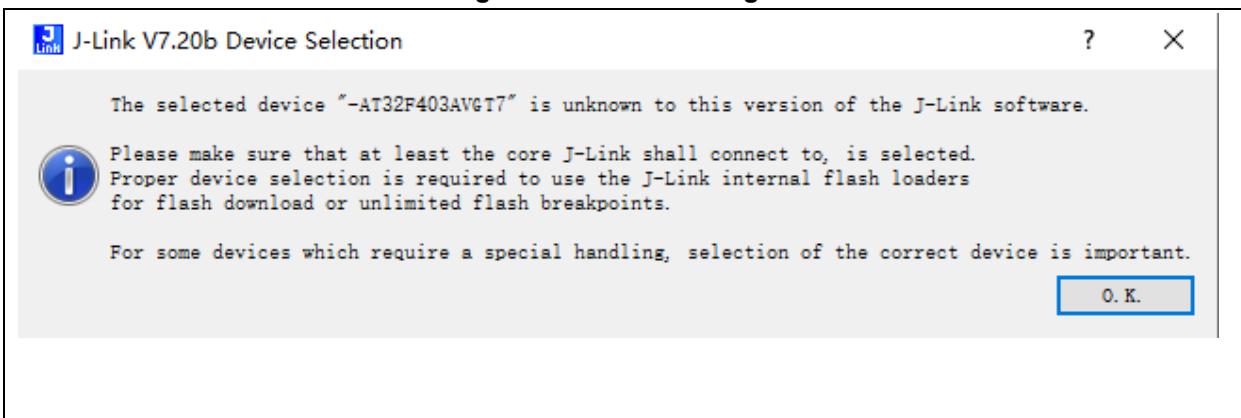


Figure 34. Error warning 2

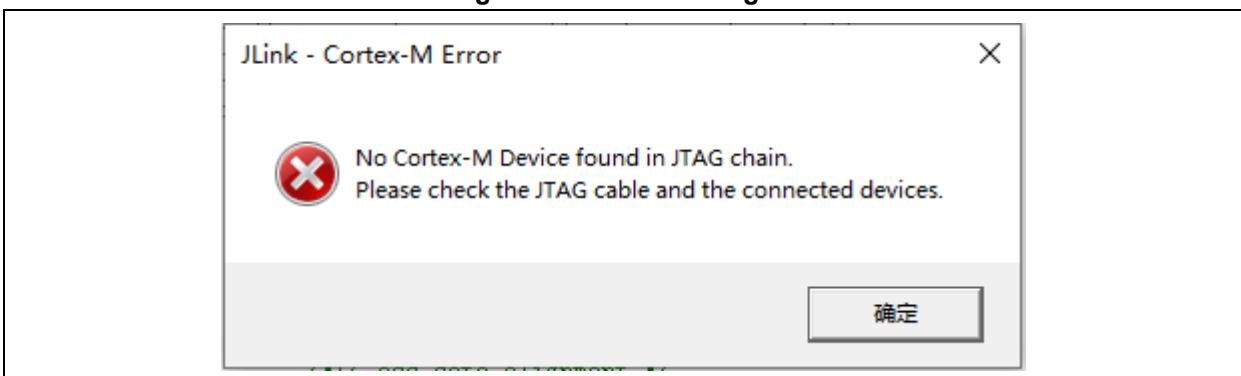
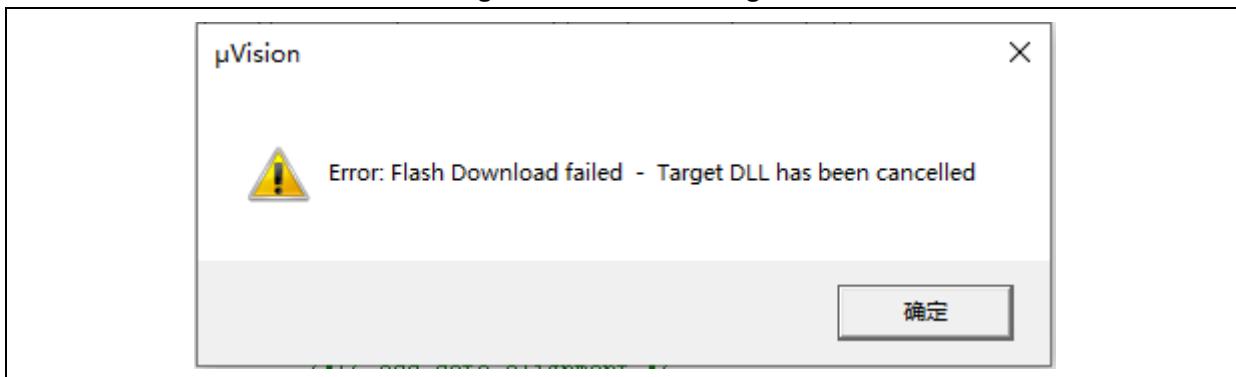


Figure 35. Error warning 3

**How to fix this problem?**

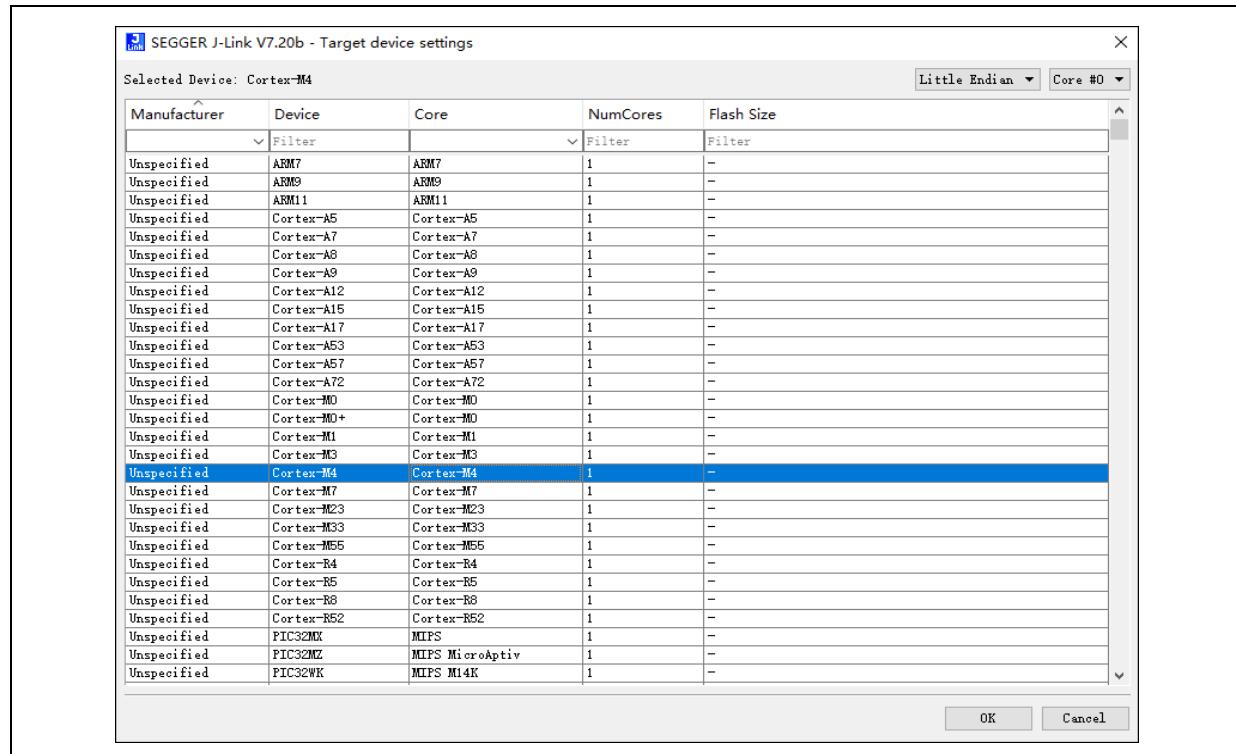
Step 1: Find “JLinkLog” and “JLinkSettings” files according to project path, and delete them.

Figure 36. JLinkLog and JLinkSettings

名称	修改日期	类型	大小
listings	2022/2/22 19:28	文件夹	
objects	2022/2/22 19:28	文件夹	
combine_mode_ordinary_simult.uvoptx	2022/2/22 19:28	UVOPTX 文件	12 KB
combine_mode_ordinary_simult	2022/2/22 19:28	礦ision5 Project	17 KB
JLinkLog	2022/2/22 19:28	文本文档	7 KB
JLinkSettings	2022/2/22 19:27	配置设置	1 KB

Step 2: Click on magic wand, go to “Debug”, select “Unspecified Cortex-M4”.

Figure 37. Unspecified Cortex-M4



6.3 How to change HEXT crystal

All examples used in BSP implements frequency multiplication based on 8 MHz external high-speed crystal oscillator on the evaluation board. If a non-8 MHz external crystal is used in actual scenarios, it is necessary to modify clock configuration in BSP to allow for accurate and stable clock frequency.

Therefore, the “AT32_New_Clock_Configuration” tool is specially developed by Artery to generate the desired BSP system clock code file, including external clock source, frequency division factor, frequency multiplication factor, clock source selection and other parameters, marked in red in Figure 38. After the completion of parameter configuration, it is ready to generate code file, avoiding complicated operations involved in code modification.

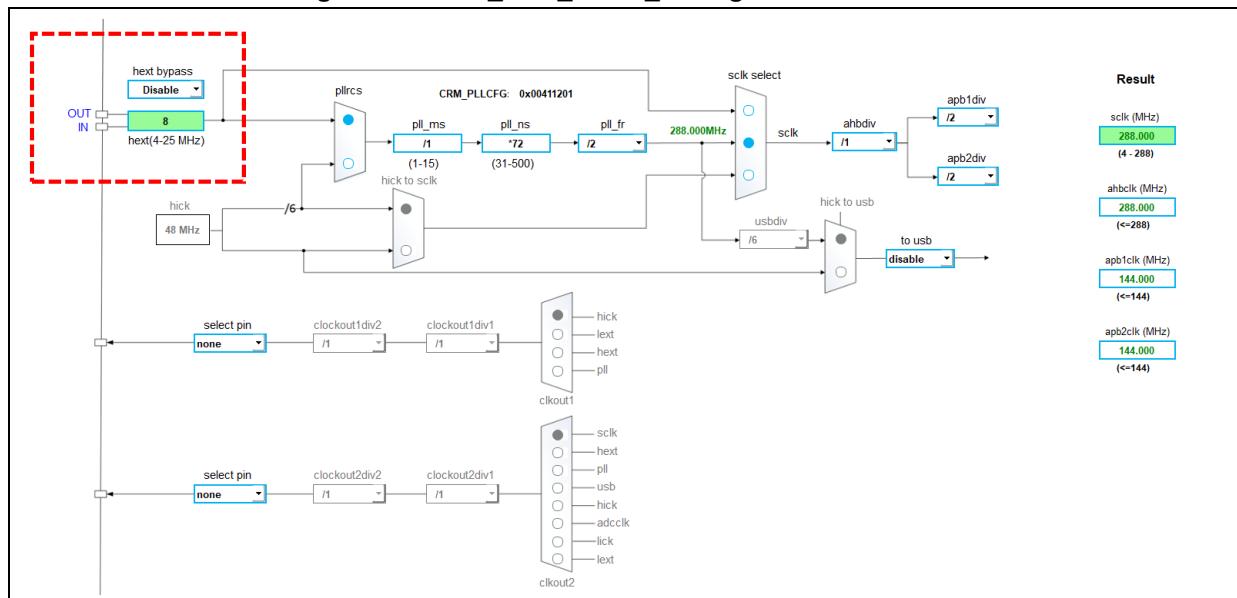
The users simply need to replace the original one in BSP demo with the newly generated clock code file (at32f4xx_clock.c/ at32f4xx_clock.h/ at32f4xx_conf.h), and call the function system_clock_config in main function.

Also, it is necessary to replace the macro definition HEXT_VALUE in the at32f4xx_conf.h. Taking the AT32F403A as an example, the HEXT_VALUE of the at32f403a_407_conf.h is defined as:

```
#define HEXT_VALUE ((uint32_t)8000000) /*!< value of the high speed external crystal in hz */
```

Figure 38 shows the window of AT32_New_Clock_Configuration tool.

Figure 38. AT32_New_Clock_Configuration window



For more information on the AT32_New_Clock_Configuration, please refer to the corresponding Application Note shown in Table 562, which are all available from the official website of Artery.

Table 562. Clock configuration guideline

Part number	Application Note
AT32F403A/407 clock configuration	AN0082
AT32F435/437 clock configuration	AN0084
AT32F421 clock configuration	AN0116
AT32F415 clock configuration	AN0117
AT32F413 clock configuration	AN0118
AT32F425 clock configuration	AN0121

7 Revision history

Table 563. Document revision history

Date	Version	Revision note
2025.06.12	2.0.0	Initial release.

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