In general, it were looking for constant solutions xCts=C to x'= S(t,x), note LHS x'= C'=0 is & RHS is f(t, x(+)) = f(t, c) = 0 as well. Therefore, look for constants (so that f(t,c)=0 for all t Ex: y'= ty(3-y) w(t)=0 and x(t)=3 are constant solutions Check conditions for uniqueness: Uniqueness Thm implies that 2 DISTINCT solution curves conf meet, since various solution curves don't meet, 16 Unique. If y(t) is a solution to IVP: y'=ty(3-y), y(0)=2, is it possible for y(t) Recult xL=3 is a solution. (, (1, 4) y(+) must be continuous, but if y(1)=4 that many of will cross x(+)=3 and some (0,2) point as sail in the Intermediate Value Thing Since there's some it so that y(it) = x(it) = 3. and Uniqueners Thm Says solution convers cont meet, y(1) = 4 isn't possible. Busically Oxycto 43. In R2 if solution cames cont meet, then a Solution curve divides plane into 2 separate sections. 2.9 Autonomous Equations & Stubility Def: First-order autonomous equations is equation of form X'= 3(x) independent variable doesn't Ly explicitly show on RHS, detailing feature of autonomous equations Examples: $\chi' = sh(x)$ $\gamma' = e^{\gamma^2 + 1}$

In this section, we'll look at how the solution behaves as the contable goes to I a

Not Autonomous: X' = Sin(tx) Y' = XY

Direction Fields & Solutions ex: Modeling a proportation graph X(+) = population at time t constate (= intrinsic growth rate

K = carrying capacity Logistic Equation: dx = v (1-x)x x'(+)= f(x) Fratures: S(x) doein't depend on t explicitly, so slope, of direction lines don't change moving left or right DF y'=5(y) shift left a A solution came translated left or right is left y(-6) = y(-6+0) another solution curve y, = & (y(t+c)) = y'(t+c) = f(y(t+c)) = f(y(t+c)) so [yi'= S(yi) is also a solution Equilibrium Polits and Solutions x'= f(x) If S(x0)=0, then we have constant for some x. ER solutions XC+)= xo Previous Ex: x'=r(1- x)x=s(x) S(x0)=r(1- x)x0 = 0 Since (x'=0 = 5(x0)= 5(x(+)), a poil+ x0 such that f(x0)=0 is an eavilibrium point Xo=k or Xo=O 50 equilibrium solutions are x, (t) = 0 and x2 (t)=k and constant function x(t)=x0 is an equilibrium solution. Non equilibrium Solutions: $x' = r(1 - \frac{x}{k}) \times c$ hormal form $f(x)=r(1-\frac{x}{x})x$ and $\frac{\partial f}{\partial x}=r-\frac{2\pi}{k}x$ Both f and of are on R2 so x'=r(1-x)x salisties hypothesis of Uniqueness Than => Engphs of X(+) and equilibrium solutions X, (+) { x2(+) cont cross Meretire, if x(+) is a solution to x'=r(1-\frac{7}{2})x w/ xcos=x. OLX, ck, then OLXLESLK for all t. (k rk) Furthermore, x'=r(1-x)x>0 for 0 <x<k derivative x'(+) is positive for all t implying that x(4) is monotone thereasing; since x(+) is bounded above by k, x(+) also approaches linit of k.

f(x)=r(1- *)x

solutions in this case I O < x o < k approach k but don't exceed it, hence it being the carrying capacity. | linx(+)= k & linx(+) = O Phase Line: consider y'= S(y)
and y as "distance" from D
along number line (y-axis) · 4'= S(4) describes motion Expansing modeles by yet) Along the x-axis line which is called the phase line Equilibrium point types: 101 -6 5 At pointily over means

50 lation increases avont equilibrian points, - armor means devening