

Name	Meeting 1(Oct 6th)	Meeting 2(Oct 7th)	Meeting 3(Oct 10th)
Arthur Chen	Yes	Yes	Yes
Avinash Chaurasia	Yes	Yes	Yes
Kyle Lamb	Yes	Yes	Yes
Michaela Matocha	Yes	Yes	Yes
Osric Nagle	Yes	No	Yes

Meeting 1:

1. Duplicated relevant files into Mini-Project-2 directory on Github
2. Updated the GUI to include buttons for world mode control
3. Discussed scope of the project and estimated deadline of Oct 8th
4. Discussed the specificities of the math required to achieve inverse kinematics
5. Plan on determining the math to discover all solutions for the RRR robot by tomorrow at 5:30 pm CST.

Meeting 2:

1. The mathematical approach to resolve the problem is identified.
2. Each member of the team is assigned with a specific task for the implementation.
3. Discussed some of the corner cases and strategies to resolve or avoid them.
4. Scheduled the next meeting time for integration and testing

Meeting 3:

1. Completed the integration between the frontend and backend.
2. Tested the project with corner cases then imposed adjustments.
3. Prepared deliverables for the submission.