

# ARTHUR FINDELAIR

ASPIRING MACHINE LEARNING ENGINEER  
SEEKING ENTRY-LEVEL OPPORTUNITY

📍 Chicago, Illinois

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## EDUCATION

### **Master of Computational Engineering – Illinois Institute of Technology** **Chicago, USA, 2021**

Expected graduation with specialization in Optimization, Machine Vision and Decision Making.

Relevant coursework: Machine & Deep Learning, Statistical Signal Processing, OOP & Machine Learning

### **Institut Supérieur de l'Aéronautique et de l'Espace** **Poitiers, France, 2020**

#### **Ecole Nationale de Mécanique et d'Aérotechnique (ISAE-ENSMA)**

Expected graduation with Engineering Degree equivalent to MS in Aeronautical Engineering, specialized in Software Engineering and Avionics, March 2021.

### **Classes Préparatoires aux Grandes Ecoles (CPGE)** **Lycée Kleber, Strasbourg, France, 2018**

Undergraduate selective and intensive course in mathematics, physics and engineering science in preparation for the nationwide competitive entrance examinations to leading French engineering schools.

### **Baccalauréat Scientifique** **Lycée Henri Meck, Molsheim, France, 2016**

Equivalent to a high school diploma specialized in science with highest honors ("Mention Très Bien").

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## SOFTWARE PROJECTS

(see more on my GitHub profile: [www.github.com/ArthurFDLR](https://www.github.com/ArthurFDLR))

### **Machine Learning Research Internship (2020)** *Python, TensorFlow, ASP*

- Developed and fine-tuned a hand pose classifier able to precisely detect more than 24 gestures.
- Deployed a simulated environment for human robot-collaboration based on Answer Set Programming.

### **Finalist of the Black-Out Challenge by SAFRAN (2019)** *QT, Python*

- Created a working prototype of a positioning system based on Bluetooth beacons.
- Connected car's trip computer to a Raspberry Pi to utilize inertial and speed data in a dead-reckoning algorithm.

### **Autonomous Robot competing for the French Robotic Cup (2018 - 2020)** *C++, Python (OpenCV)*

- Implemented an autonomous robot's real-time control system, based on LIDAR obstacles avoidances.
- Managed an 8 members team with a 2,000€ budget from conception to delivery

### **Poker bot adapting to opponent strategy (2018)** *Ada, Python*

- Implement Monte Carlo method to determine its winning chances for a given hand and optimize its actions.

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## EXPERIENCE ADDITIONNELLE

### **Internship at Punch Powerglide as workman (2019)**

- Worked on a transmission assembly line.

### **Member of ENSMA's student committee, catering manager**

- Collaborated in a 4 members team, delegate tasks and organize food providing for up to 200 persons.
- Take part to the organization of Freshmen's weekend with a 60,000€ budget.

### **Chairperson of ENSMA's motorbike club**

- Organized biker meet-up and motocross initiation.

### **Drones manager at ENSMAERO (aeromodelism club)**

Taught drone construction and flying basis.

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## Languages and Technologies

*Proficient:* Python, C++    *Familiar:* Ada, C#, Fortran, SQL

Visual Studio Code, GIT, Linux, PlatformIO, CATIA, Altium CircuitMaker, Pack Office, Adobe ecosystem

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## Spoken languages

French (Native Speaker), English (Fluent, TOEIC 970/990, TOEFL 106/120), Italian (Beginner)