

# ARTHUR FINDELAIR

DUAL MASTER'S DEGREE STUDENT SPECIALIZED IN MACHINE LEARNING

Chicago, Illinois, USA

arthfind@gmail.com

312-619-1343

 [linkedin.com/in/arthurfdlr](https://www.linkedin.com/in/arthurfdlr)

 [arthurfindelair.com](https://arthurfindelair.com)

 [github.com/arthurfdlr](https://github.com/arthurfdlr)

## EDUCATION

### ILLINOIS INSTITUTE OF TECHNOLOGY (IIT) - CHICAGO, IL, USA

Expected August 2021

#### MASTER OF SCIENCE IN ELECTRICAL ENGINEERING (Current GPA: 4.0)

Relevant coursework: Machine & Deep Learning, Computer Vision and Image Processing, OOP & Machine Learning.

### ISAE-ENSMA - POITIERS, FRANCE

Expected August 2021

#### DIPLOME D'INGENIEUR IN AERONAUTICAL ENGINEERING

Equivalent to **MASTER OF SCIENCE** | Specialized in avionics software and embedded systems.

### LYCEE KLEBER, CLASSES PREPARATOIRES AUX GRANDES ECOLES (CPGE) - STRASBOURG, FRANCE

Sept. 2016 - June 2018

Intensive program in mathematics and physics in preparation for competitive entrance examinations to French engineering schools.

## PROFESSIONAL EXPERIENCES

### INTELLIGENT ROBOTICS LAB, UNIVERSITY OF BIRMINGHAM - UNITED KINGDOM

June - August 2020

#### MACHINE LEARNING RESEARCH INTERN

- Deployed a simulated environment to efficiently enhance the common-sense reasoning system (ASP) of an assistant robot.
- Built a hand signs classification application to ease labeled images dataset creation and neural networks experimentations.
- Developed a TensorFlow model on a self-made dataset to enforce human-robot communication through hand signs.

### ENSMASTEEL, FRENCH ROBOTIC CUP

June 2019 - Mai 2020

#### TEAM LEADER

- Managed an 8-persons team and a 2,000€ budget to create an autonomous robot competing in the French Robotic Cup.
- Oversaw parallel evolutions of mechanical, electrical, and software sub-teams to ensure a smooth system integration.
- Implemented a robust finite-state robotic framework in C++ to guarantee precise navigation and multiple actuators control.

## SELECTED PROJECTS

### THISNIGHTSKYDOESNOTEXIST.COM

- Trained and fine-tuned a StyleGAN2 model on Google Colab using 4500 images scraped from Instagram.
- Deployed a website built on top of a 5000 generated images database using Firebase to showcase GANs' potential.

### AN INTER-LOCATING NETWORK (TOP 10 OUT OF 250 TEAMS ON THE BLACK-OUT CHALLENGE BY SAFRAN)

- Designed and pitched an alternative to GNSS through dead-reckoning, BLE beacons, and an inter-locating network of users.
- Engineered a locating module through inertial measurements and real-time vehicle data achieving less than a 2% drift error.

### NEURAL-NETWORK LIBRARY ACCELERATOR

- Programmed a Python package integrating an optimized C++ back-end library to fasten CNN inference execution time.

## SKILLS

**Industry Knowledge:** Machine Learning (DNN, CNN, GAN ...) • Computer Vision • Signal Processing • Microcontrollers • FPGAs

**Programming Languages:** Python (TensorFlow, Numpy, Pandas, PyTest, Scikit-Learn, PyQt) • C++ • Java • Ada • SQL

**Tools:** Linux • Version Control (Git) • Cloud Computing (Google Colab) • Visual Studio Code • PlatformIO

**Soft Skills:** Bilingual Communicator (English, French) • Initiative • Focus • Adaptability • Creativity & Innovation

## ADDITIONAL EXPERIENCE

### ISAE-ENSMA STUDENT COMMITTEE MEMBER

2019 - 2020

Collaborated on a 28-persons team to organize multiple school events, including Freshmen's weekend with a 40,000€ budget.

### DRONE INSTRUCTOR AT ENSMAERO

2019 - 2020

Taught racing drone building process and flying fundamentals to half a dozen beginners.