

# Optimization with PYPOWER

You can run an Optimal Power Flow using the PYPOWER OPF

## AC OPF

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```
pandapower.runopp(net, verbose=False, calculate_voltage_angles=True, check_connectivity=True, suppress_warnings=True, switch_rx_ratio=2, delta=1e-10, init='flat', numba=True, trafo3w_losses='hv', consider_line_temperature=False, **kwargs)
```

Runs the pandapower Optimal Power Flow. Flexibilities, constraints and cost parameters are defined in the pandapower element tables.

Flexibilities can be defined in net.sgen / net.gen / net.load / net.storage / net.ext\_grid net.sgen.controllable if a static generator is controllable. If False, the active and reactive power are assigned as in a normal power flow. If True, the following flexibilities apply:

- net.gen.min\_p\_mw / net.gen.max\_p\_mw
- net.gen.min\_q\_mvar / net.gen.max\_q\_mvar
- net.sgen.min\_p\_mw / net.sgen.max\_p\_mw
- net.sgen.min\_q\_mvar / net.sgen.max\_q\_mvar
- net.dcline.max\_p\_mw
- net.dcline.min\_q\_to\_mvar / net.dcline.max\_q\_to\_mvar / net.dcline.min\_q\_from\_mvar / net.dcline.max\_q\_from\_mvar
- net.ext\_grid.min\_p\_mw / net.ext\_grid.max\_p\_mw
- net.ext\_grid.min\_q\_mvar / net.ext\_grid.max\_q\_mvar
- net.load.min\_p\_mw / net.load.max\_p\_mw
- net.load.min\_q\_mvar / net.load.max\_q\_mvar
- net.storage.min\_p\_mw / net.storage.max\_p\_mw
- net.storage.min\_q\_mvar / net.storage.max\_q\_mvar

Controllable loads behave just like controllable static generators. It must be stated if they are controllable. Otherwise, they are not respected as flexibilities. Dc lines are controllable per default

Network constraints can be defined for buses, lines and transformers the elements in the following columns:

- `net.bus.min_vm_pu / net.bus.max_vm_pu`
- `net.line.max_loading_percent`
- `net.trafo.max_loading_percent`
- `net.trafo3w.max_loading_percent`

If the external grid is controllable, the voltage setpoint of the external grid can be optimized within the

voltage constraints by the OPF. The same applies to the voltage setpoints of the controllable generator elements.

How these costs are combined into a cost function depends on the `cost_function` parameter.

#### INPUT:

**net** - The pandapower format network

#### OPTIONAL:

**verbose** (bool, False) - If True, some basic information is printed

**suppress\_warnings** (bool, True) - suppress warnings in pypower

If set to True, warnings are disabled during the loadflow. Because of the way data is processed in pypower, ComplexWarnings are raised during the loadflow. These warnings are suppressed by this option, however keep in mind all other pypower warnings are suppressed, too.

**init** (str, "flat") - init of starting opf vector. Options are "flat" or "pf"

Starting solution vector ( $x_0$ ) for opf calculations is determined by this flag. Options are: "flat" (default): starting vector is  $(\text{upper bound} - \text{lower bound}) / 2$  "pf": a power flow is executed prior to the opf and the pf solution is the starting vector. This may improve convergence, but takes a longer runtime (which are probably neglectable for opf calculations)

**delta** (float,  $1e-10$ ) - power tolerance

**trafo3w\_losses** (str, "hv") - defines where open loop losses of three-winding transformers are considered. Valid options are "hv", "mv", "lv" for HV/MV/LV side or "star" for the star point.

**consider\_line\_temperature** (bool, False) - adjustment of line impedance based on provided line temperature. If True, `net.line` must contain a column "temperature\_degree\_celsius". The temperature dependency coefficient  $\alpha$  must be provided in the `net.line.alpha` column, otherwise the default value of 0.004 is used

**kwargs** - Pypower / Matpower keyword arguments:

- OPF\_VIOLATION (5e-6) constraint violation tolerance
- PDIPM\_COSTTOL (1e-6) optimality tolerance
- PDIPM\_GRADTOL (1e-6) gradient tolerance
- PDIPM\_COMPTOL (1e-6) complementarity condition (inequality) tolerance
- PDIPM\_FEASTOL (set to OPF\_VIOLATION if not specified) feasibility (equality) tolerance
- PDIPM\_MAX\_IT (150) maximum number of iterations
- SCPDIPM\_RED\_IT(20) maximum number of step size reductions per iteration

The internal solver uses the interior point method. By default, the initial state is the center of the operational constraints. Another option would be to initialize the optimisation with a valid loadflow solution. For optimisation of a timeseries, this warm start possibility could imply a significant speedup. This is not yet provided in the actual version, but could be an useful extension in the future. Another parametrisation for the AC OPF is, if voltage angles should be considered, which is the same option than for the loadflow calculation with `pandapower.runpp`:

## References:

- “On the Computation and Application of Multi-period Security-Constrained Optimal Power Flow for Real-time Electricity Market Operations”, Cornell University, May 2007.
- H. Wang, C. E. Murillo-Sanchez, R. D. Zimmerman, R. J. Thomas, “On Computational Issues of Market-Based Optimal Power Flow”, IEEE Transactions on Power Systems, Vol. 22, No. 3, Aug. 2007, pp. 1185-1193.
- R. D. Zimmerman, C. E. Murillo-Sánchez, and R. J. Thomas, “MATPOWER: Steady-State Operations, Planning and Analysis Tools for Power Systems Research and Education,” Power Systems, IEEE Transactions on, vol. 26, no. 1, pp. 12-19, Feb. 2011.

## DC OPF

The dc optimal power flow is a linearized optimization of the grid state. It offers two cost function options, that are fitting special use cases. To understand the usage, the [DC OPF tutorial](#) is recommended.

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```
pandapower.rundcopp(net, verbose=False, check_connectivity=True, suppress_warnings=True,  
switch_rx_ratio=0.5, delta=1e-10, trafo3w_losses='hv', **kwargs)
```

Runs the pandapower Optimal Power Flow. Flexibilities, constraints and cost parameters are defined in the pandapower element tables.

Flexibilities for generators can be defined in `net.sgen / net.gen`. `net.sgen.controllable / net.gen.controllable` signals if a generator is controllable. If False, the active and reactive power are assigned as in a normal power flow. If yes, the following flexibilities apply:

- `net.sgen.min_p_mw / net.sgen.max_p_mw`
- `net.gen.min_p_mw / net.gen.max_p_mw`
- `net.load.min_p_mw / net.load.max_p_mw`

Network constraints can be defined for buses, lines and transformers the elements in the following columns: - `net.line.max_loading_percent` - `net.trafo.max_loading_percent` - `net.trafo3w.max_loading_percent`

## INPUT:

**net** - The pandapower format network

## OPTIONAL:

**verbose** (bool, False) - If True, some basic information is printed

**suppress\_warnings** (bool, True) - suppress warnings in pypower

If set to True, warnings are disabled during the loadflow. Because of the way data is processed in pypower, ComplexWarnings are raised during the loadflow. These warnings are suppressed by this option, however keep in mind all other pypower warnings are suppressed, too.

**delta** (float, 1e-10) - power tolerance

**trafo3w\_losses** (str, "hv") - defines where open loop losses of three-winding transformers are considered. Valid options are "hv", "mv", "lv" for HV/MV/LV side or "star" for the star point.

Flexibilities, costs and constraints (except voltage constraints) are handled as in the [Optimisation problem](#). Voltage constraints are not considered in the DC OPF, since voltage magnitudes are not part of the linearized power flow equations.

## ! Note

If you are interested in the pypower casefile that pandapower is using for power flow, you can find it in `net["_ppc_opf"]`. However all necessary informations are written into the pandpower format net, so the pandapower user should not usually have to deal with pypower.