

```
1 using SymPy
```

```
1 using Plots
```

Definindo as variáveis

(t, s, A, B)

```
1 @syms t s A B
```

$R1 = 1$

```
1 R1 = 1
```

$R2 = 2$

```
1 R2 = 2
```

$L = 1$

```
1 L = 1
```

$C = 0.25$

```
1 C = 1/4
```

$v0 = 6$

```
1 v0 = 6
```

Para t=0-

$iL0 = -2$

```
1 iL0 = -2
```

$v0 = 2$

```
1 v0 = 2
```

Para t>0

$\alpha = 2.0$

```
1 alpha = 1/(2*R1*C)
```

$\omega0 = 2.0$

```
1 w0 = 1/sqrt(L*C)
```

$s1 = -2.0 + 0.0im$

```
1 s1 = -alpha + sqrt(Complex(alpha^2 - w0^2))
```

```
s2 = -2.0 - 0.0im
```

```
1 s2 = -α - sqrt(Complex(α^2 - ω0^2))
```

Calculando a Corrente

```
i_t =
```

$$(A + Bt)e^{-2.0t}$$

```
1 i_t = (A + B*t)*exp(s1*t)
```

```
di_dt =
```

$$Be^{-2.0t} - 2.0(A + Bt)e^{-2.0t}$$

```
1 di_dt = diff(i_t, t)
```

```
v_t =
```

$$Be^{-2.0t} - 2.0(A + Bt)e^{-2.0t}$$

```
1 v_t = L*di_dt
```

```
eq1 =
```

$$A = -2$$

```
1 eq1 = subs(i_t, t=>0) ~ iL0
```

```
eq2 =
```

$$-2.0A + B = 2$$

```
1 eq2 = subs(v_t, t=>0) ~ v0
```

```
sol = Dict( B A )
```

$$\Rightarrow -2.0, \Rightarrow -2.0$$

```
1 sol = solve([eq1, eq2], [A, B])
```

```
i_t_sol =
```

$$(-2.0t - 2.0)e^{-2.0t}$$

```
1 i_t_sol = subs(i_t, sol)
```

```
v_t_sol =
```

$$-2.0(-2.0t - 2.0)e^{-2.0t} - 2.0e^{-2.0t}$$

```
1 v_t_sol = subs(v_t, sol)
```

`i_t_simplified =`

$$2.0(-t - 1)e^{-2.0t}$$

```
1 i_t_simplified = simplify(i_t_sol)
```

`v_t_simplified =`

$$(4.0t + 2.0)e^{-2.0t}$$

```
1 v_t_simplified = simplify(v_t_sol)
```

Gráfico

```
1 md"### Gráfico"
```

`i` (generic function with 1 method)

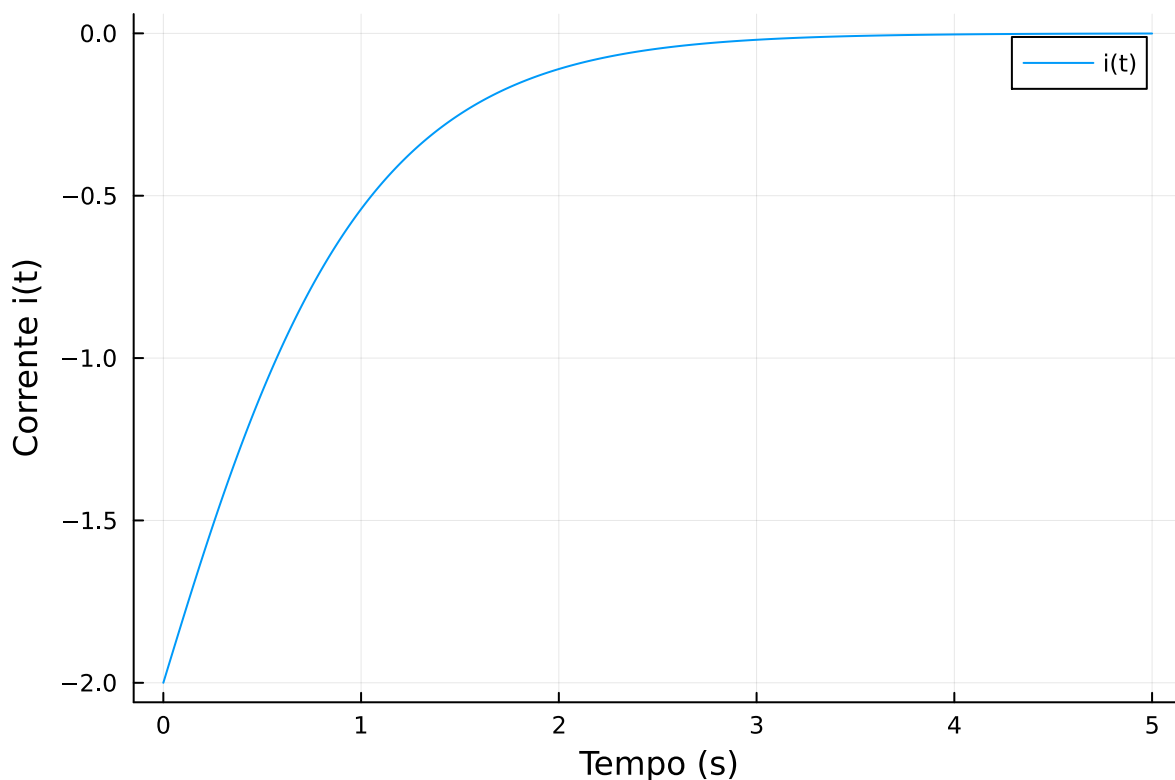
```
1 i(t) = (-2 - 2*t)*exp(-2*t)
```

`v` (generic function with 1 method)

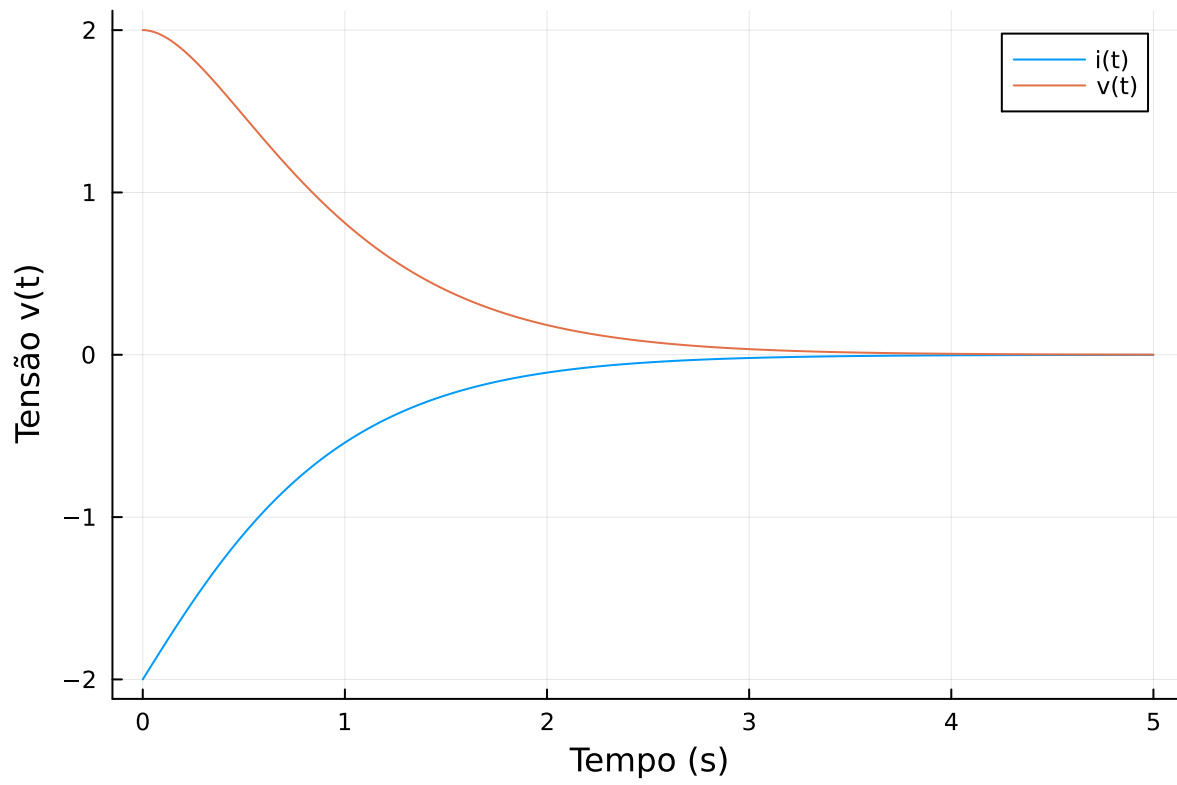
```
1 v(t) = (2 + 4*t)*exp(-2*t)
```

`t_values = 0.0:0.01:5.0`

```
1 t_values = 0:0.01:5
```



```
1 plot(t_values, i.(t_values), xlabel="Tempo (s)", ylabel="Corrente i(t)",  
label="i(t)", legend=:topright)
```



```
1 plot!(t_values, v.(t_values), xlabel="Tempo (s)", ylabel="Tensão v(t)",  
label="v(t)", legend=:topright)
```