## CS111 Chapter 5.5 Outline #5

- Virtualizing Processors Using Threads
  - Each thread does NOT necessarily have its own processor
  - Thread manager allows sharing of processors
    - One slow thread might slow down the progress of other threads on same processor
- Sharing procedure among multiple threads
  - o Thread: abstraction that encapsulates the state of a running module
  - o thread\_id ← ALLOCATE\_THREAD(starting\_procedure, address\_space\_id)
    - Not enough space results in an error
    - Allows many threads to share a limited amount of processors
    - Solution depends on the fact that most threads spend most of their lives waiting for events
  - Virtualizing the processor
    - When thread is waiting, processor switches to another thread by saving the previous state and loading the new thread state
    - Also known as time-sharing, processor multiplexing, etc.
    - YIELD: entry point to thread manager, allows sender to add new item (thread?) to buffer
      - Thread manager hands calling thread's processor to some other thread
      - RUNNING (executing on processor) vs. RUNNABLE (ready to run, waiting for processor)
      - Three steps
        - Save: save thread state to resume later
        - o Schedule: schedule other thread to run on current processor
        - o Dispatch: dispatch processor to thread
  - YIELD procedure:
    - Thread running in thread layer calls YIELD
    - YIELD enters processor layer, which saves its current state
    - When processor later exits processor layer, it runs new thread
    - New thread might run in the same or different address space
  - o YIELD is usually written in low-level instructions as a kernel procedure via supervisor call
  - o Interrupts invoke interrupt handler, which always runs in processor layer
    - Does not invoke procedures like YIELD
    - No relation to current thread
  - o Exceptions occur in thread layer, accessing interrupted thread's state
    - Invokes procedures
    - Specific to current thread
- Implementing YIELD
  - o Relies on GET\_THREAD\_ID, ENTER\_PROCESSOR\_LAYER, EXIT\_PROCESSOR\_LAYER, SCHEDULER
  - o Involves processor\_table (info on processor) and thread\_table (array with one entry per thread)
  - Steps
    - Virtualize register CPUID to create virtual ID register for each thread
    - YIELD calls ENTER\_PROCESSOR\_LAYER, releasing predecessor
      - Stack pointer is stored
    - Scheduling searches until it finds a runnable thread
    - EXIT\_PROCESSOR\_LAYER loads saved stack pointer from ENTER
  - Flow of control results in abandoning the two stack frames allocated to SCHEDULER and EXIT
  - o Thread releases processor by ENTER call, then resumes immediately after the same ENTER call
    - Known as a "co-routine"
  - Enforcing atomicity: ENTER thread acquires thread table lock; EXIT thread releases it
- Creating and terminating threads
  - o Supporting management of a variable number of threads requires
    - EXIT\_THREAD(): destroys and cleans up calling thread to release its state
    - DESTROY\_THREAD(id): destroy specified id thread; a thread might need to terminate another
  - At least as many threads as processors need to be supported, so a processor has a separate thread
    - Known as processor-layer thread, or processor thread

- Runs SCHEDULER procedure
- Each processor needs its own processor thread to deallocate thread layer thread stack spaces
- ALLOCATE THREAD
  - Allocate memory space for new thread
  - Place empty frame on new stack with EXIT\_THREAD as return address
  - Place second empty frame with starting\_procedure return address
  - Find FREE entry in thread table
  - Incompletion of these steps returns an error
- DESTROY\_THREAD
  - Calling thread cannot free target stack; only processor running that thread can do that
    - Set kill or continue variable to KILL
    - Processor thread checks variable during YIELD, possibly releasing resources
- Enforcing modularity with threads: preemptive scheduling
  - o Non-preemptive scheduling: thread runs until it gives up processor
    - New thread that called YIELD is then run
    - Problematic: that thread might never give up control
  - Cooperative scheduling (cooperative multitasking)
    - Every thread will call YIELD occasionally
    - Not robust; programmer might forget to put in YIELD, or program errors might arise
  - Preemptive scheduling
    - Thread manager can force a thread to give up the processor based on time (ex: 100 ms)
      - Clock might trigger an interrupt to switch processor layer to kernel mode
        - Interrupt handler invokes exception handler, forcing current thread to YIELD
    - Thread manager needs to allow interrupt handler to invoke procedures
      - But concurrent execution within processor layer with calling YIELD can cause deadlock
      - Thread layer has its own lock mechanism
      - One solution: enable/disable interrupts
        - Make both streams separate (before-or-after actions)
    - Preemptive scheduling isolates thread behavior, making it like each thread has its own process
- Enforcing modularity with threads and address spaces
  - o Sharing a single address space between threads can cause accidental memory changes
  - o Thread manager needs to switch address spaces when threads are switched
  - One solution: map instructions and data of thread manager into same virtual addresses in every virtual address space
  - o Another solution: use hardware to load PMAR, SP, PC as single before-or-after action
    - Returns control to thread in new virtual address space at saved location with saved pointer
- Layering threads
  - Create several threads in thread layer from a single thread in processor layer
  - Interrupt support
    - Processor as a hard-wired thread manager with a processor thread (for SCHEDULER) and interrupt thread (runs interrupt handlers in kernel mode, capable of YIELD)
  - OS layer uses processor threads of processor layer to make a second layer of threads
    - Each application module is given at least one preemptively scheduled virtual processor
    - Each application module can implement its own third-layer thread manager
      - Usually nonpreemptive
      - Threads don't need to be protected, as they belong in the same application module
  - Hardware processor at lowest layer creates a processor thread and an interrupt thread