

CS111 Chapter 5.2, 4.2 Outline #7

- Virtual Links using SEND/RECEIVE and a bounded buffer
 - Allows remote procedure calls between threads on same physical computer
 - Sequence Coordination with bounded buffer
 - One approach: assume the programmer makes no mistakes
 - Other approach: provide strong support for coordination correctness; loses flexibility
 - The first approach is actually better in some situations
 - Sharing a bounded buffer between two threads results in producer and consumer problem; sequence coordination is required
 - Implementation dependent on assumptions below
 - One-writer principle: one thread to send, receive, and update (each)
 - Threads run on dedicated (their own) processors
 - No overflow (long integers)
 - Read/write coherence
 - Before-or-after atomicity
 - Race Conditions
 - Error that results from a dependence on exact timing of two threads
 - Ex: Therac-25 had race conditions due to thread/operator (typing) conflicts, killed patients
 - Locks and Before-or-After Actions
 - Locks involve ACQUIRE and RELEASE, serving as a flag for coordinating shared usage of variables
 - Locks are not mechanically protective; they are only flags for convention
 - Locks help with before-or-after atomicity implementation
 - The latter is also known as isolation, isolated actions, mutual exclusions, critical sections
 - Single-acquire protocol: only one thread can acquire a given lock at a given time
 - Deadlock
 - Condition in which a group of threads is waiting for some other thread to make progress
 - Represented using a wait-for graph (nodes are threads/locks, edges are acquires)
 - Might even occur with a single lock due to, say, waiting for buffer space, etc.
 - Livelock: condition in which thread is repeating some operations but not the entire sequence
 - ACQUIRE and RELEASE can be reduced by bootstrapping, an inductive proof
 - RSM (read and set memory) performs statements as before-or-after actions
 - Coordination between Synchronous Islands with Asynchronous Connections
 - Arbiter failure: not reaching a decision before the clock ticks
 - Avoid by
 - Synchronizing clocks of two components
 - Design arbiters with multiple stages
 - Stop clock of synchronous component
 - Make all components asynchronous
- Communication between client and service
 - Remote procedure call (RPC): stylized form of client/service interaction
 - Each request is followed by response
 - System goal: make RPC look like ordinary procedure call
 - Also, it is sometimes desirable to be able to send messages to offline recipients
 - Stubs: procedures that hide marshaling/communication details from caller/callee
 - RPCs differ from regular procedure calls
 - RPCs can reduce fate sharing between caller and callee by exposing failures of callee to caller
 - RPCs introduce new failures
 - RPCs take more time (stub, (un)marshaling arguments, sending request over network, etc.)
 - Some programming languages don't combine well with RPC
 - No response case handled by implementations:
 - At-least-once RPC
 - Stub resends requests until service responds
 - Idempotent: for some operations, repeating same request has no effect

- At-most-once RPC
 - No response with specific time means caller receives an error
 - Important for operations with side effects
- Exactly-once RPC
 - Ideal, but independence between client/service makes this principle impossible to guarantee
 - Return error status, sends a separate RPC request to inquire about status, etc.
 - Requires both client/service stubs to track RPC requests/responses
- Communicating through intermediary
 - Use buffered communication to allow sender/receive to be not present at the same time
 - Sender/receiver can push or pull messages
 - Decouple modules with indirection: intermediary determines message recipient
 - Choice of when/where to duplicate messages
 - Publish/subscribe is a general communication style
 - Sender is publisher, notifies event service of new message
 - Recipients subscribe to event services