# hypre Reference Manual

— Version 1.9.0b —

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This interface represents a structured-grid conceptual view of a linear system.

Author:

Robert D. Falgout

1.1

# Struct Grids

### Names

 $\label{eq:construct} \begin{array}{lll} \textbf{typedef struct} & \textbf{hypre\_StructGrid\_struct*} & \textbf{HYPRE\_StructGrid} \\ & A \textit{ grid object is constructed out of several "boxes", defined on a global abstract index space} \end{array}$ 

int

**HYPRE\_StructGridCreate** (MPI\_Comm comm, int ndim, HYPRE\_StructGrid \*grid)

 $Create\ an\ {\tt ndim-}dimensional\ grid\ object$ 

1.1.1 int

 $\mathbf{HYPRE\_StructGridDestroy}\ (\mathbf{HYPRE\_StructGrid}\ \mathbf{grid})$ 

int

 ${\bf HYPRE\_StructGridSetExtents}~({\tt HYPRE\_StructGrid~grid},~{\tt int~*ilower},$ 

int \*iupper)

Set the extents for a box on the grid

int

## HYPRE\_StructGridAssemble (HYPRE\_StructGrid grid)

Finalize the construction of the grid before using

int

 $\mathbf{HYPRE\_StructGridSetPeriodic} \ (\mathbf{HYPRE\_StructGrid} \ \mathbf{grid}, \ \ \mathbf{int} \ \ \mathbf{^*periodic})$ 

(Optional) Set periodic

int

 $\mathbf{HYPRE\_StructGridSetNumGhost} \ (\mathbf{HYPRE\_StructGrid} \ \mathbf{grid},$ 

int \*num\_ghost)

(Optional) Set the ghost layer in the grid object

1.1.1

int HYPRE\_StructGridDestroy (HYPRE\_StructGrid grid)

Destroy a grid object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

1.2

## Struct Stencils

#### Names

 $\label{typedef} \begin{array}{ll} \text{typedef struct} & \text{hypre\_StructStencil\_struct*} & \textbf{HYPRE\_StructStencil} \\ & \textit{The stencil object} \end{array}$ 

int

HYPRE\_StructStencilCreate (int ndim, int size,

HYPRE\_StructStencil \*stencil)

Create a stencil object for the specified number of spatial dimensions and stencil entries

int

HYPRE\_StructStencilDestroy (HYPRE\_StructStencil stencil)

 $Destroy\ a\ stencil\ object$ 

1.2.1 int

**HYPRE\_StructStencilSetElement** (HYPRE\_StructStencil stencil, int entry, int \*offset)

Set a stencil entry .....

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int **HYPRE\_StructStencilSetElement** (HYPRE\_StructStencil stencil, int entry, int \*offset)

Set a stencil entry.

NOTE: The name of this routine will eventually be changed to HYPRE\_StructStencilSetEntry.

1.3

# Struct Matrices

## Names

int

HYPRE\_StructMatrixCreate (MPI\_Comm comm, HYPRE\_StructGrid grid, HYPRE\_StructStencil stencil, HYPRE\_StructMatrix \*matrix)

Create a matrix object

int

HYPRE\_StructMatrixDestroy (HYPRE\_StructMatrix matrix)

Destroy a matrix object

int

HYPRE\_StructMatrixInitialize (HYPRE\_StructMatrix matrix)

Prepare a matrix object for setting coefficient values

int

**HYPRE\_StructMatrixSetValues** (HYPRE\_StructMatrix matrix, int \*index, int nentries, int \*entries, double \*values)

Set matrix coefficients index by index

int

HYPRE\_StructMatrixSetBoxValues (HYPRE\_StructMatrix matrix,

int \*ilower, int \*iupper, int nentries, int \*entries, double \*values)

Set matrix coefficients a box at a time

int

	HYPRE_StructMatrixSetConstantValues (HYPRE_StructMatrix matrix, int nentries, int *entries, double *values)	
	Set matrix coefficients which are constant over the grid	
	int  HYPRE_StructMatrixAddToValues (HYPRE_StructMatrix matrix,	
	Add to matrix coefficients index by index	
	int	
	HYPRE_StructMatrixAddToBoxValues (HYPRE_StructMatrix matrix, int *ilower, int *iupper, int nentries, int *entries, double *values)	
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 $\begin{array}{l} \text{int} \\ \textbf{HYPRE\_StructMatrixSetSymmetric} \ (\text{HYPRE\_StructMatrix} \ \text{matrix}, \ \text{int} \\ \end{array}$ symmetric)

(Optional) Define symmetry properties of the matrix. By default, matrices are assumed to be nonsymmetric. Significant storage savings can be made if the matrix is symmetric.

\_\_ 1.3.2 \_\_

int

**HYPRE\_StructMatrixSetConstantEntries** (HYPRE\_StructMatrix matrix, int nentries, int \*entries)

Specifiy which stencil entries are constant over the grid. Presently supported: - no entries constant (this function need not be called) - all entries constant - all but the diagonal entry constant

1.3.3

HYPRE\_StructMatrixPrint (const char \*filename, HYPRE\_StructMatrix matrix, int all)

Print the matrix to file. This is mainly for debugging purposes.

1.4

Struct Vectors

Names

int

**HYPRE\_StructVectorCreate** (MPI\_Comm comm, HYPRE\_StructGrid grid, HYPRE\_StructVector \*vector)

Create a vector object

int

```
Destroy a vector object
            int
            HYPRE_StructVectorInitialize (HYPRE_StructVector vector)
                   Prepare a vector object for setting coefficient values
            int
            HYPRE_StructVectorSetValues (HYPRE_StructVector vector, int *index,
                                              double value)
                   Set vector coefficients index by index
            int
            HYPRE_StructVectorSetBoxValues (HYPRE_StructVector vector,
                                                  int *ilower, int *iupper,
                                                  double *values)
                   Set vector coefficients a box at a time
            int
            HYPRE_StructVectorAddToValues (HYPRE_StructVector vector,
                                                  int *index, double value)
                   Set vector coefficients index by index
            int
            HYPRE_StructVectorAddToBoxValues (HYPRE_StructVector vector,
                                                      int *ilower, int *iupper,
                                                      double *values)
                   Set vector coefficients a box at a time
            HYPRE_StructVectorAssemble (HYPRE_StructVector vector)
                   Finalize the construction of the vector before using
            int
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                   Get vector coefficients index by index
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1.4.1
            int
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   int all)
```

HYPRE\_StructVectorDestroy (HYPRE\_StructVector vector)

Print the vector to file. This is mainly for debugging purposes.

# ${\bf extern} \ \ {\bf SStruct} \ \ {\bf System} \ \ {\bf Interface}$

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This interface represents a semi-structured-grid conceptual view of a linear system.

Author:

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2 1

# SStruct Grids

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	$\operatorname{int}$	
	HYPRE_SStructGridSetVariables (HYPRE_SStructGrid grid, int part,	
	int nvars,	
	HYPRE_SStructVariable *vartypes)	
	Describe the variables that live on a structured part of the grid	
2.1.4	$\operatorname{int}$	
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	int	
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	(Optional) Set periodic for a particular part	
	$\operatorname{int}$	
	$\mathbf{HYPRE\_SStructGridSetNumGhost}$ (HYPRE\_SStructGrid grid,	
	int *num_ghost)	
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## \_ 2.1.1 \_

# $\# define \ \mathbf{HYPRE\_SStructGrid}$

A grid object is constructed out of several structured "parts" and an optional unstructured "part". Each structured part has its own abstract index space.

# #define HYPRE\_SStructVariable

An enumerated type that supports cell centered, node centered, face centered, and edge centered variables. Face centered variables are split into x-face, y-face, and z-face variables, and edge centered variables are split into x-edge, y-edge, and z-edge variables. The edge centered variable types are only used in 3D. In 2D, edge centered variables are handled by the face centered types.

Variables are referenced relative to an abstract (cell centered) index in the following way:

- cell centered variables are aligned with the index;
- node centered variables are aligned with the cell corner at relative index (1/2, 1/2, 1/2);
- x-face, y-face, and z-face centered variables are aligned with the faces at relative indexes (1/2, 0, 0), (0, 1/2, 0), and (0, 0, 1/2), respectively;
- x-edge, y-edge, and z-edge centered variables are aligned with the edges at relative indexes (0, 1/2, 1/2), (1/2, 0, 1/2),and (1/2, 1/2, 0),respectively.

The supported identifiers are:

- HYPRE\_SSTRUCT\_VARIABLE\_CELL
- HYPRE\_SSTRUCT\_VARIABLE\_NODE
- HYPRE\_SSTRUCT\_VARIABLE\_XFACE
- HYPRE\_SSTRUCT\_VARIABLE\_YFACE
- HYPRE\_SSTRUCT\_VARIABLE\_ZFACE
- HYPRE\_SSTRUCT\_VARIABLE\_XEDGE
- HYPRE\_SSTRUCT\_VARIABLE\_YEDGE
- HYPRE\_SSTRUCT\_VARIABLE\_ZEDGE

NOTE: Although variables are referenced relative to a unique abstract cell-centered index, some variables are associated with multiple grid cells. For example, node centered variables in 3D are associated with 8 cells (away from boundaries). Although grid cells are distributed uniquely to different processes, variables may be owned by multiple processes because they may be associated with multiple cells.

int HYPRE\_SStructGridDestroy (HYPRE\_SStructGrid grid)

Destroy a grid object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

#### 2.1.4

int

**HYPRE\_SStructGridAddVariables** (HYPRE\_SStructGrid grid, int part, int \*index, int nvars, HYPRE\_SStructVariable \*vartypes)

Describe additional variables that live at a particular index. These variables are appended to the array of variables set in HYPRE\_SStructGridSetVariables ( $\rightarrow page~12$ ), and are referenced as such.

#### $_{-}$ 2.1.5 $_{-}$

int

**HYPRE\_SStructGridSetNeighborBox** (HYPRE\_SStructGrid grid, int part, int \*ilower, int \*iupper, int nbor\_part, int \*nbor\_ilower, int \*nbor\_iupper, int \*index\_map)

Describe how regions just outside of a part relate to other parts. This is done a box at a time.

The indexes ilower and iupper map directly to the indexes nbor\_ilower and nbor\_iupper. Although, it is required that indexes increase from ilower to iupper, indexes may increase and/or decrease from nbor\_ilower to nbor\_iupper.

The index\_map describes the mapping of indexes 0, 1, and 2 on part part to the corresponding indexes on part nbor\_part. For example, triple (1, 2, 0) means that indexes 0, 1, and 2 on part part map to indexes 1, 2, and 0 on part nbor\_part, respectively.

NOTE: All parts related to each other via this routine must have an identical list of variables and variable types. For example, if part 0 has only two variables on it, a cell centered variable and a node centered variable, and we declare part 1 to be a neighbor of part 0, then part 1 must also have only two variables on it, and they must be of type cell and node.

2.1.6

int **HYPRE\_SStructGridAddUnstructuredPart** (HYPRE\_SStructGrid grid, int ilower, int iupper)

Add an unstructured part to the grid. The variables in the unstructured part of the grid are referenced by a global rank between 0 and the total number of unstructured variables minus one. Each process owns some unique consecutive range of variables, defined by ilower and iupper.

NOTE: This is just a placeholder. This part of the interface is not finished.

2 2

## SStruct Stencils

#### Names

 $\label{typedef} \begin{array}{ll} \textbf{typedef struct} & \textbf{hypre\_SStructStencil\_struct*} & \textbf{HYPRE\_SStructStencil} \\ & \textit{The stencil object} \end{array}$ 

int

 ${\bf HYPRE\_SStructStencilCreate} \ ({\rm int} \ {\rm ndim}, \ {\rm int} \ {\rm size},$ 

HYPRE\_SStructStencil \*stencil)

Create a stencil object for the specified number of spatial dimensions and stencil entries

int

HYPRE\_SStructStencilDestroy (HYPRE\_SStructStencil stencil)

Destroy a stencil object

int

HYPRE\_SStructStencilSetEntry (HYPRE\_SStructStencil stencil, int entry, int \*offset, int var)

Set a stencil entry

# SStruct Graphs

#### Names

typedef struct hypre\_SStructGraph\_struct\* HYPRE\_SStructGraph The graph object is used to describe the nonzero structure of a matrix int HYPRE\_SStructGraphCreate (MPI\_Comm comm, HYPRE\_SStructGrid grid, HYPRE\_SStructGraph \*graph)  $Create\ a\ graph\ object$ int HYPRE\_SStructGraphDestroy (HYPRE\_SStructGraph graph)  $Destroy\ a\ graph\ object$ int HYPRE\_SStructGraphSetStencil (HYPRE\_SStructGraph graph, int part, int var, HYPRE\_SStructStencil stencil) Set the stencil for a variable on a structured part of the grid 2.3.1int HYPRE\_SStructGraphAddEntries (HYPRE\_SStructGraph graph, int part, int \*index, int var, int to\_part, int \*to\_index, int to\_var) Add a non-stencil graph entry at a particular index ..... 16 2.3.2int HYPRE\_SStructGraphSetObjectType (HYPRE\_SStructGraph graph, int type) It is used before AddEntries and Assemble to compute the right ranks in the qraph ..... 17  ${\bf HYPRE\_SStructGraphAssemble}~({\rm HYPRE\_SStructGraph~graph})$ Finalize the construction of the graph before using

#### 2.3.1

HYPRE\_SStructGraphAddEntries (HYPRE\_SStructGraph graph, int part, int \*index, int var, int to\_part, int \*to\_index, int to\_var)

Add a non-stencil graph entry at a particular index. This graph entry is appended to the existing graph entries, and is referenced as such.

NOTE: Users are required to set graph entries on all processes that own the associated variables. This means that some data will be multiply defined.

2.3.2

HYPRE\_SStructGraphSetObjectType (HYPRE\_SStructGraph graph, int type)

It is used before AddEntries and Assemble to compute the right ranks in the graph. Currently, type can be either HYPRE\_SSTRUCT (the default) or HYPRE\_PARCSR.

2.4

# SStruct Matrices

## Names

typedef struct hypre\_SStructMatrix\_struct\* **HYPRE\_SStructMatrix**The matrix object

int

 ${\bf HYPRE\_SStructMatrixCreate}~({\tt MPI\_Comm}~{\tt comm},$ 

HYPRE\_SStructGraph graph, HYPRE\_SStructMatrix \*matrix)

Create a matrix object

int

HYPRE\_SStructMatrixDestroy (HYPRE\_SStructMatrix matrix)

Destroy a matrix object

int

HYPRE\_SStructMatrixInitialize (HYPRE\_SStructMatrix matrix)

Prepare a matrix object for setting coefficient values

2.4.1 int

 $\mathbf{HYPRE\_SStructMatrixSetValues} \ (\mathbf{HYPRE\_SStructMatrix} \ \mathbf{matrix}, \ \ \mathbf{int} \ \mathbf{part},$ 

int \*index, int var, int nentries,
int \*entries, double \*values)

2.4.2 int

	HYPRE_SStructMatrixSetBoxValues (HYPRE_SStructMatrix matrix, int part, int *ilower, int *iupper, int var, int nentries, int *entries, double *values)	
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2.4.3	int <b>HYPRE_SStructMatrixAddToValues</b> (HYPRE_SStructMatrix matrix,	
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	int nentries, int *entries,	
	double *values)	2.0
	Add to matrix coefficients index by index	20
2.4.4	int	
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	$Add\ to\ matrix\ coefficients\ a\ box\ at\ a\ time\ \dots\dots\dots\dots\dots\dots\dots$	20
	int <b>HYPRE_SStructMatrixAssemble</b> (HYPRE_SStructMatrix matrix)  Finalize the construction of the matrix before using	
2.4.5	int	
	$\mathbf{HYPRE\_SStructMatrixSetSymmetric} \ (\mathbf{HYPRE\_SStructMatrix} \ \mathbf{matrix},$	
	int part, int var, int to_var,	
	int symmetric)  Define symmetry properties for the stencil entries in the matrix	21
	int	
	HYPRE_SStructMatrixSetNSSymmetric (HYPRE_SStructMatrix matrix, int symmetric)	
	Define symmetry properties for all non-stencil matrix entries	
2.4.6	int	
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2.4.7	int	
2.1	HYPRE_SStructMatrixGetObject (HYPRE_SStructMatrix matrix, void **object)	
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	int	
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	Set the matrix to be complex	
2.4.8	int	
	HYPRE_SStructMatrixPrint (const char *filename,	
	HYPRE_SStructMatrix matrix, int all)  Print the matrix to file	22
	1 tim the matrix to file	44

int

**HYPRE\_SStructMatrixSetValues** (HYPRE\_SStructMatrix matrix, int part, int \*index, int var, int nentries, int \*entries, double \*values)

Set matrix coefficients index by index.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

NOTE: The entries in this routine must all be of the same type: either stencil or non-stencil, but not both. Also, if they are stencil entries, they must all represent couplings to the same variable type (there are no such restrictions for non-stencil entries).

If the matrix is complex, then values consists of pairs of doubles representing the real and imaginary parts of each complex value.

See Also:

HYPRE\_SStructMatrixSetComplex ( $\rightarrow page 18$ )

#### 2.4.2

int

HYPRE\_SStructMatrixSetBoxValues (HYPRE\_SStructMatrix matrix, int part, int \*ilower, int \*iupper, int var, int nentries, int \*entries, double \*values)

Set matrix coefficients a box at a time.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

NOTE: The entries in this routine must all be of the same type: either stencil or non-stencil, but not both. Also, if they are stencil entries, they must all represent couplings to the same variable type (there are no such restrictions for non-stencil entries).

If the matrix is complex, then values consists of pairs of doubles representing the real and imaginary parts of each complex value.

See Also:

HYPRE\_SStructMatrixSetComplex ( $\rightarrow page 18$ )

int

**HYPRE\_SStructMatrixAddToValues** (HYPRE\_SStructMatrix matrix, int part, int \*index, int var, int nentries, int \*entries, double \*values)

Add to matrix coefficients index by index.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

NOTE: The entries in this routine must all be of the same type: either stencil or non-stencil, but not both. Also, if they are stencil entries, they must all represent couplings to the same variable type.

If the matrix is complex, then values consists of pairs of doubles representing the real and imaginary parts of each complex value.

See Also:

HYPRE\_SStructMatrixSetComplex ( $\rightarrow page 18$ )

2.4.4

int

HYPRE\_SStructMatrixAddToBoxValues (HYPRE\_SStructMatrix matrix, int part, int \*ilower, int \*iupper, int var, int nentries, int \*entries, double \*values)

Add to matrix coefficients a box at a time.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

NOTE: The entries in this routine must all be of stencil type. Also, they must all represent couplings to the same variable type.

If the matrix is complex, then values consists of pairs of doubles representing the real and imaginary parts of each complex value.

See Also:

HYPRE\_SStructMatrixSetComplex ( $\rightarrow page 18$ )

int

HYPRE\_SStructMatrixSetSymmetric (HYPRE\_SStructMatrix matrix, int part, int var, int to\_var, int symmetric)

Define symmetry properties for the stencil entries in the matrix. The boolean argument symmetric is applied to stencil entries on part part that couple variable var to variable to\_var. A value of -1 may be used for part, var, or to\_var to specify "all". For example, if part and to\_var are set to -1, then the boolean is applied to stencil entries on all parts that couple variable var to all other variables.

By default, matrices are assumed to be nonsymmetric. Significant storage savings can be made if the matrix is symmetric.

 $_{-2.4.6}$ 

int **HYPRE\_SStructMatrixSetObjectType** (HYPRE\_SStructMatrix matrix, int type)

Set the storage type of the matrix object to be constructed. Currently, type can be either HYPRE\_SSTRUCT (the default), HYPRE\_STRUCT, or HYPRE\_PARCSR.

See Also:

HYPRE\_SStructMatrixGetObject ( $\rightarrow 2.4.7$ , page 21)

2.4.7

int
HYPRE\_SStructMatrixGetObject (HYPRE\_SStructMatrix matrix, void
\*\*object)

Get a reference to the constructed matrix object.

See Also:

HYPRE\_SStructMatrixSetObjectType ( $\rightarrow 2.4.6$ , page 21)

int HYPRE\_SStructMatrixPrint (const char \*filename, HYPRE\_SStructMatrix matrix, int all)

Print the matrix to file. This is mainly for debugging purposes.

 $\mathbf{2.5}$ 

## SStruct Vectors

#### Names

typedef struct hypre\_SStructVector\_struct\* HYPRE\_SStructVector The vector object int HYPRE\_SStructVectorCreate (MPI\_Comm comm, HYPRE\_SStructGrid grid, HYPRE\_SStructVector \*vector) Create a vector object HYPRE\_SStructVectorDestroy (HYPRE\_SStructVector vector) Destroy a vector object int HYPRE\_SStructVectorInitialize (HYPRE\_SStructVector vector) Prepare a vector object for setting coefficient values 2.5.1int HYPRE\_SStructVectorSetValues (HYPRE\_SStructVector vector, int part, int \*index, int var, double \*value) 23 Set vector coefficients index by index ..... 2.5.2int HYPRE\_SStructVectorSetBoxValues (HYPRE\_SStructVector vector, int part, int \*ilower, int \*iupper, int var, double \*values) Set vector coefficients a box at a time ..... 242.5.3int HYPRE\_SStructVectorAddToValues (HYPRE\_SStructVector vector, int part, int \*index, int var, double \*value) 24 Set vector coefficients index by index ..... 2.5.4int

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	int	
	HYPRE_SStructVectorAssemble (HYPRE_SStructVector vector)  Finalize the construction of the vector before using	
	int HYPRE_SStructVectorGather (HYPRE_SStructVector vector)	
	Gather vector data so that efficient GetValues can be done	
2.5.5	$\operatorname{int}$	
	HYPRE_SStructVectorGetValues (HYPRE_SStructVector vector, int part, int *index, int var, double *value)	
	Get vector coefficients index by index	25
2.5.6	int  HYPRE_SStructVectorGetBoxValues (HYPRE_SStructVector vector, int part, int *ilower, int *iupper,	
	int var, double *values)	
	Get vector coefficients a box at a time	26
2.5.7	int HYPRE_SStructVectorSetObjectType (HYPRE_SStructVector vector,	
	int type)	
	Set the storage type of the vector object to be constructed	26
2.5.8	int	
2.0.0	HYPRE_SStructVectorGetObject (HYPRE_SStructVector vector, void **object)	
	Get a reference to the constructed vector object	26
	$_{ m int}$	
	HYPRE_SStructVectorSetComplex (HYPRE_SStructVector vector)  Set the vector to be complex	
2.5.9	$\operatorname{int}$	
	HYPRE_SStructVectorPrint (const char *filename, HYPRE_SStructVector vector, int all)	
	Print the vector to file	27

#### 2.5.1

int **HYPRE\_SStructVectorSetValues** (HYPRE\_SStructVector vector, int part, int \*index, int var, double \*value)

Set vector coefficients index by index.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

If the vector is complex, then value consists of a pair of doubles representing the real and imaginary parts of the complex value.

See Also:

HYPRE\_SStructVectorSetComplex ( $\rightarrow page 23$ )

2.5.2

int **HYPRE\_SStructVectorSetBoxValues** (HYPRE\_SStructVector vector, int part, int \*ilower, int \*iupper, int var, double \*values)

Set vector coefficients a box at a time.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

If the vector is complex, then values consists of pairs of doubles representing the real and imaginary parts of each complex value.

See Also:

HYPRE\_SStructVectorSetComplex ( $\rightarrow page 23$ )

2.5.3

HYPRE\_SStructVectorAddToValues (HYPRE\_SStructVector vector, int part, int \*index, int var, double \*value)

Set vector coefficients index by index.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

If the vector is complex, then value consists of a pair of doubles representing the real and imaginary parts of the complex value.

2.5.4

int

**HYPRE\_SStructVectorAddToBoxValues** (HYPRE\_SStructVector vector, int part, int \*ilower, int \*iupper, int var, double \*values)

Set vector coefficients a box at a time.

NOTE: Users are required to set values on all processes that own the associated variables. This means that some data will be multiply defined.

If the vector is complex, then values consists of pairs of doubles representing the real and imaginary parts of each complex value.

See Also:

HYPRE\_SStructVectorSetComplex ( $\rightarrow page 23$ )

\_ 2.5.5 \_\_

int

**HYPRE\_SStructVectorGetValues** (HYPRE\_SStructVector vector, int part, int \*index, int var, double \*value)

Get vector coefficients index by index.

NOTE: Users may only get values on processes that own the associated variables.

If the vector is complex, then value consists of a pair of doubles representing the real and imaginary parts of the complex value.

See Also:

HYPRE\_SStructVectorSetComplex ( $\rightarrow page 23$ )

int **HYPRE\_SStructVectorGetBoxValues** (HYPRE\_SStructVector vector, int part, int \*ilower, int \*iupper, int var, double \*values)

Get vector coefficients a box at a time.

NOTE: Users may only get values on processes that own the associated variables.

If the vector is complex, then values consists of pairs of doubles representing the real and imaginary parts of each complex value.

See Also:

HYPRE\_SStructVectorSetComplex ( $\rightarrow page 23$ )

2.5.7

int **HYPRE\_SStructVectorSetObjectType** (HYPRE\_SStructVector vector, int type)

Set the storage type of the vector object to be constructed. Currently, type can be either HYPRE\_SSTRUCT (the default) or HYPRE\_PARCSR.

See Also:

HYPRE\_SStructVectorGetObject ( $\rightarrow 2.5.8$ , page 26)

\_ 2.5.8 \_

HYPRE\_SStructVectorGetObject (HYPRE\_SStructVector vector, void \*\*object)

Get a reference to the constructed vector object.

\_\_ 2.5.9 \_

HYPRE\_SStructVectorPrint (const char \*filename, HYPRE\_SStructVector vector, int all)

Print the vector to file. This is mainly for debugging purposes.

# extern IJ System Interface

Names		
3.1	IJ Matrices	
		28
3.2	IJ Vectors	
		34

This interface represents a linear-algebraic conceptual view of a linear system. The 'I' and 'J' in the name are meant to be mnemonic for the traditional matrix notation A(I,J).

3.1

# IJ Matrices

Names		
	typedef struct hypre_IJMatrix_struct* <b>HYPRE_IJMatrix</b> The matrix object	
3.1.1	int  HYPRE_IJMatrixCreate (MPI_Comm comm, int ilower, int iupper,	30
3.1.2	int HYPRE_IJMatrixDestroy (HYPRE_IJMatrix matrix)  Destroy a matrix object	30
3.1.3	int HYPRE_IJMatrixInitialize (HYPRE_IJMatrix matrix)  Prepare a matrix object for setting coefficient values	31
3.1.4	int  HYPRE_IJMatrixSetValues (HYPRE_IJMatrix matrix, int nrows, int *ncols, const int *rows, const int *cols, const double *values)  Sets values for nrows rows or partial rows of the matrix	31
3.1.5	$\inf$	

	HYPRE_IJMatrixAddToValues (HYPRE_IJMatrix matrix, int nrows, int *ncols, const int *rows, const int *cols,	
	const double *values)  Adds to values for nrows rows or partial rows of the matrix	31
	$\operatorname{int}$	
	HYPRE_IJMatrixAssemble (HYPRE_IJMatrix matrix)  Finalize the construction of the matrix before using	
	$\operatorname{int}$	
	<b>HYPRE_IJMatrixGetRowCounts</b> (HYPRE_IJMatrix matrix, int nrows, int *rows, int *ncols)	
	Gets number of nonzeros elements for nrows rows specified in rows and returns them in ncols, which needs to be allocated by the user	
3.1.6	$\operatorname{int}$	
	HYPRE_IJMatrixGetValues (HYPRE_IJMatrix matrix, int nrows, int *ncols, int *rows, int *cols, double *values)	
	Gets values for nrows rows or partial rows of the matrix	32
3.1.7	int  HYPRE_IJMatrixSetObjectType (HYPRE_IJMatrix matrix, int type)  Set the storage type of the matrix object to be constructed	32
	int  HYPRE_IJMatrixGetObjectType (HYPRE_IJMatrix matrix, int *type)  Get the storage type of the constructed matrix object	
	int	
	HYPRE_IJMatrixGetLocalRange (HYPRE_IJMatrix matrix, int *ilower, int *iupper, int *jlower, int *jupper)	
	Gets range of rows owned by this processor and range of column partitioning for this processor	
3.1.8	int  HYPRE_IJMatrixGetObject (HYPRE_IJMatrix matrix, void **object)  Get a reference to the constructed matrix object	32
3.1.9	$\operatorname{int}$	
	HYPRE_IJMatrixSetRowSizes (HYPRE_IJMatrix matrix, const int *sizes)  (Optional) Set the max number of nonzeros to expect in each row	32
3.1.10	$\operatorname{int}$	
	HYPRE_IJMatrixSetDiagOffdSizes (HYPRE_IJMatrix matrix, const int *diag_sizes,	
	const int *offdiag_sizes)	
	(Optional) Set the max number of nonzeros to expect in each row of the diagonal and off-diagonal blocks	33
3.1.11	$\operatorname{int}$	
	HYPRE_IJMatrixSetMaxOffProcElmts (HYPRE_IJMatrix matrix, int max_off_proc_elmts)	
	(Optional) Sets the maximum number of elements that are expected to be set (or added) on other processors from this processor This routine can significantly improve the efficiency of matrix construction, and should always be utilized if possible	33
3.1.12	int	00
3.1.12		

	HYPRE_IJMatrixRead (const char *filename, MPI_Comm comm, int type,	
	HYPRE_IJMatrix *matrix)	
	Read the matrix from file	34
3.1.13	$\operatorname{int}$	
	HYPRE_IJMatrixPrint (HYPRE_IJMatrix matrix, const char *filename)	
	Print the matrix to file	34

#### 3 1 1

HYPRE\_IJMatrixCreate (MPI\_Comm comm, int ilower, int iupper, int jlower, int jupper, HYPRE\_IJMatrix \*matrix)

Create a matrix object. Each process owns some unique consecutive range of rows, indicated by the global row indices ilower and iupper. The row data is required to be such that the value of ilower on any process p be exactly one more than the value of iupper on process p-1. Note that the first row of the global matrix may start with any integer value. In particular, one may use zero- or one-based indexing.

For square matrices, jlower and jupper typically should match ilower and iupper, respectively. For rectangular matrices, jlower and jupper should define a partitioning of the columns. This partitioning must be used for any vector v that will be used in matrix-vector products with the rectangular matrix. The matrix data structure may use jlower and jupper to store the diagonal blocks (rectangular in general) of the matrix separately from the rest of the matrix.

Collective.

#### 3.1.2 .

int HYPRE\_IJMatrixDestroy (HYPRE\_IJMatrix matrix)

Destroy a matrix object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

# int **HYPRE\_IJMatrixInitialize** (HYPRE\_IJMatrix matrix)

Prepare a matrix object for setting coefficient values. This routine will also re-initialize an already assembled matrix, allowing users to modify coefficient values.

#### \_ 3.1.4 \_

int

**HYPRE\_IJMatrixSetValues** (HYPRE\_IJMatrix matrix, int nrows, int \*ncols, const int \*rows, const int \*cols, const double \*values)

Sets values for nrows rows or partial rows of the matrix. The arrays ncols and rows are of dimension nrows and contain the number of columns in each row and the row indices, respectively. The array cols contains the column indices for each of the rows, and is ordered by rows. The data in the values array corresponds directly to the column entries in cols. Erases any previous values at the specified locations and replaces them with new ones, or, if there was no value there before, inserts a new one.

Not collective.

#### 3.1.5

int

**HYPRE\_IJMatrixAddToValues** (HYPRE\_IJMatrix matrix, int nrows, int \*ncols, const int \*rows, const int \*cols, const double \*values)

Adds to values for nrows rows or partial rows of the matrix. Usage details are analogous to HYPRE\_IJMatrixSetValues ( $\rightarrow 3.1.4$ , page 31). Adds to any previous values at the specified locations, or, if there was no value there before, inserts a new one.

Not collective.

3.1.6

int **HYPRE\_IJMatrixGetValues** (HYPRE\_IJMatrix matrix, int nrows, int \*ncols, int \*rows, int \*cols, double \*values)

Gets values for nrows rows or partial rows of the matrix. Usage details are analogous to HYPRE\_IJMatrixSetValues ( $\rightarrow 3.1.4$ , page 31).

\_ 3.1.7 \_

int **HYPRE\_IJMatrixSetObjectType** (HYPRE\_IJMatrix matrix, int type)

Set the storage type of the matrix object to be constructed. Currently, type can only be HYPRE\_PARCSR.

Not collective, but must be the same on all processes.

See Also:

HYPRE\_IJMatrixGetObject ( $\rightarrow 3.1.8$ , page 32)

\_ 3.1.8 \_

int **HYPRE\_IJMatrixGetObject** (HYPRE\_IJMatrix matrix, void \*\*object)

Get a reference to the constructed matrix object.

See Also:

HYPRE\_IJMatrixSetObjectType ( $\rightarrow 3.1.7$ , page 32)

\_ 3.1.9 \_

int **HYPRE\_JJMatrixSetRowSizes** (HYPRE\_JJMatrix matrix, const int \*sizes)

(Optional) Set the max number of nonzeros to expect in each row. The array sizes contains estimated sizes for each row on this process. This call can significantly improve the efficiency of matrix construction, and should always be utilized if possible.

Not collective.

3.1.10

int **HYPRE\_IJMatrixSetDiagOffdSizes** (HYPRE\_IJMatrix matrix, const int
\*diag\_sizes, const int \*offdiag\_sizes)

(Optional) Set the max number of nonzeros to expect in each row of the diagonal and off-diagonal blocks. The diagonal block is the submatrix whose column numbers correspond to rows owned by this process, and the off-diagonal block is everything else. The arrays diag\_sizes and offdiag\_sizes contain estimated sizes for each row of the diagonal and off-diagonal blocks, respectively. This routine can significantly improve the efficiency of matrix construction, and should always be utilized if possible.

Not collective.

#### 3.1.11

int
HYPRE\_IJMatrixSetMaxOffProcElmts (HYPRE\_IJMatrix matrix, int
max\_off\_proc\_elmts)

(Optional) Sets the maximum number of elements that are expected to be set (or added) on other processors from this processor This routine can significantly improve the efficiency of matrix construction, and should always be utilized if possible.

Not collective.

#### 3.1.12

HYPRE\_IJMatrixRead (const char \*filename, MPI\_Comm comm, int type, HYPRE\_IJMatrix \*matrix)

Read the matrix from file. This is mainly for debugging purposes.

## \_\_\_ 3.1.13 \_\_\_\_\_

int **HYPRE\_IJMatrixPrint** (HYPRE\_IJMatrix matrix, const char \*filename)

Print the matrix to file. This is mainly for debugging purposes.

## 3.2

# IJ Vectors

$\mathbf{Names}$		
	typedef struct hypre_IJVector_struct* <b>HYPRE_IJVector</b> The vector object	
3.2.1	int	
	HYPRE_IJVectorCreate (MPI_Comm comm, int jlower, int jupper, HYPRE_IJVector *vector)	
	Create a vector object	36
3.2.2	int	
	HYPRE_IJVectorDestroy (HYPRE_IJVector vector)	
	Destroy a vector object	36
3.2.3	int	
	HYPRE_IJVectorInitialize (HYPRE_IJVector vector)	
	Prepare a vector object for setting coefficient values	36
3.2.4	$\operatorname{int}$	

	HYPRE_IJVectorSetMaxOffProcElmts (HYPRE_IJVector vector, int max_off_proc_elmts)	
	(Optional) Sets the maximum number of elements that are expected to be set (or added) on other processors from this processor This routine can significantly improve the efficiency of matrix construction, and should always be utilized if possible	36
3.2.5	$\operatorname{int}$	
	HYPRE_IJVectorSetValues (HYPRE_IJVector vector, int nvalues, const int *indices, const double *values)	
	Sets values in vector	37
3.2.6	$\operatorname{int}$	
	HYPRE_IJVectorAddToValues (HYPRE_IJVector vector, int nvalues, const int *indices, const double *values)	
	Adds to values in vector	37
	$\operatorname{int}$	
	HYPRE_IJVectorAssemble (HYPRE_IJVector vector)	
	Finalize the construction of the vector before using	
3.2.7	$\operatorname{int}$	
	HYPRE_IJVectorGetValues (HYPRE_IJVector vector, int nvalues, const int *indices, double *values)	
	Gets values in vector	37
3.2.8	int  HYPRE_IJVectorSetObjectType (HYPRE_IJVector vector, int type)  Set the storage type of the vector object to be constructed	38
	$\operatorname{int}$	
	HYPRE_IJVectorGetObjectType (HYPRE_IJVector vector, int *type)  Get the storage type of the constructed vector object	
	int	
	HYPRE_IJVectorGetLocalRange (HYPRE_IJVector vector, int *jlower, int *jupper)	
	Returns range of the part of the vector owned by this processor	
3.2.9	int	
0.2.0	HYPRE_IJVectorGetObject (HYPRE_IJVector vector, void **object)  Get a reference to the constructed vector object	38
2 2 10	· · · · · · · · · · · · · · · · · · ·	
3.2.10	int  HYPRE_IJVectorRead (const char *filename, MPI_Comm comm, int type,  HYPRE_IJVector *vector)	
	Read the vector from file	38
3.2.11	int	
J.2.11	HYPRE_IJVectorPrint (HYPRE_IJVector vector, const char *filename)  Print the vector to file	39
	1 1 11 10 10 10 10 10 10 10 10 10 10 10	95

int **HYPRE\_IJVectorCreate** (MPI\_Comm comm, int jlower, int jupper,
HYPRE\_IJVector \*vector)

Create a vector object. Each process owns some unique consecutive range of vector unknowns, indicated by the global indices jlower and jupper. The data is required to be such that the value of jlower on any process p be exactly one more than the value of jupper on process p-1. Note that the first index of the global vector may start with any integer value. In particular, one may use zero- or one-based indexing.

Collective.

3.2.2

int **HYPRE\_IJVectorDestroy** (HYPRE\_IJVector vector)

Destroy a vector object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

\_ 3.2.3 \_

int HYPRE\_IJVectorInitialize (HYPRE\_IJVector vector)

Prepare a vector object for setting coefficient values. This routine will also re-initialize an already assembled vector, allowing users to modify coefficient values.

3.2.4

int **HYPRE\_IJVectorSetMaxOffProcElmts** (HYPRE\_IJVector vector, int max\_off\_proc\_elmts)

(Optional) Sets the maximum number of elements that are expected to be set (or added) on other processors from this processor This routine can significantly improve the efficiency of matrix construction, and should always be utilized if possible.

Not collective.

3 2 5

int **HYPRE\_IJVectorSetValues** (HYPRE\_IJVector vector, int nvalues, const int
\*indices, const double \*values)

Sets values in vector. The arrays values and indices are of dimension nvalues and contain the vector values to be set and the corresponding global vector indices, respectively. Erases any previous values at the specified locations and replaces them with new ones.

Not collective.

3.2.6

int

**HYPRE\_IJVectorAddToValues** (HYPRE\_IJVector vector, int nvalues, const int \*indices, const double \*values)

Adds to values in vector. Usage details are analogous to HYPRE\_IJVectorSetValues ( $\rightarrow 3.2.5$ , page 37).

Not collective.

3.2.7

int

**HYPRE\_IJVectorGetValues** (HYPRE\_IJVector vector, int nvalues, const int \*indices, double \*values)

Gets values in vector. Usage details are analogous to HYPRE\_JJVectorSetValues ( $\rightarrow 3.2.5$ , page 37).

Not collective.

3.2.8

int HYPRE\_IJVectorSetObjectType (HYPRE\_IJVector vector, int type)

Set the storage type of the vector object to be constructed. Currently, type can only be HYPRE\_PARCSR.

Not collective, but must be the same on all processes.

See Also:

HYPRE\_IJVectorGetObject ( $\rightarrow$ 3.2.9, page 38)

3.2.9

int HYPRE\_JJVectorGetObject (HYPRE\_JJVector vector, void \*\*object)

Get a reference to the constructed vector object.

See Also:

HYPRE\_IJVectorSetObjectType ( $\rightarrow$ 3.2.8, page 38)

3 2 10

int
HYPRE\_IJVectorRead (const char \*filename, MPI\_Comm comm, int type,
HYPRE\_IJVector \*vector)

Read the vector from file. This is mainly for debugging purposes.

int HYPRE\_IJVectorPrint (HYPRE\_IJVector vector, const char \*filename)

Print the vector to file. This is mainly for debugging purposes.

4

# extern Struct Solvers

Names		
4.1	Struct Solvers	40
4.2	Struct Jacobi Solver	40
		40
4.3	Struct PFMG Solver	42
4.4	Struct SMG Solver	44
4.5	Struct PCG Solver	44
4.6	Struct GMRES Solver	45
		47
4.7	Struct BiCGSTAB Solver	48

These solvers use matrix/vector storage schemes that are tailored to structured grid problems.

4.1

# Struct Solvers

Names

 $\label{typedef} \begin{tabular}{ll} typedef struct & hypre\_StructSolver\_struct* & HYPRE\_StructSolver \\ The solver object \\ \end{tabular}$ 

4.2

# Struct Jacobi Solver

# Names int HYPRE\_StructJacobiCreate (MPI\_Comm comm, HYPRE\_StructSolver \*solver) Create a solver object 4.2.1 int HYPRE\_StructJacobiDestroy (HYPRE\_StructSolver solver) Destroy a solver object ...... 41 int HYPRE\_StructJacobiSetup (HYPRE\_StructSolver solver, HYPRE\_StructMatrix A, HYPRE\_StructVector b, HYPRE\_StructVector x) int HYPRE\_StructJacobiSolve (HYPRE\_StructSolver solver, HYPRE\_StructMatrix A, HYPRE\_StructVector b, HYPRE\_StructVector x) Solve the system int HYPRE\_StructJacobiSetTol (HYPRE\_StructSolver solver, double tol) (Optional) Set the convergence tolerance int HYPRE\_StructJacobiSetMaxIter (HYPRE\_StructSolver solver, int max\_iter) (Optional) Set maximum number of iterations int HYPRE\_StructJacobiSetZeroGuess (HYPRE\_StructSolver solver) (Optional) Use a zero initial guess int HYPRE\_StructJacobiSetNonZeroGuess (HYPRE\_StructSolver solver) (Optional) Use a nonzero initial guess int

 $\begin{tabular}{ll} HYPRE\_StructJacobiGetNumIterations & (HYPRE\_StructSolver solver, \\ int *num\_iterations) \end{tabular}$ 

Return the number of iterations taken

int

 $HYPRE\_StructJacobiGetFinalRelativeResidualNorm$ 

(HYPRE\_StructSolver solver, double \*norm)

Return the norm of the final relative residual

4.2.1

int HYPRE\_StructJacobiDestroy (HYPRE\_StructSolver solver)

Destroy a solver object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

4.3

# Struct PFMG Solver

#### Names

int

HYPRE\_StructPFMGCreate (MPI\_Comm comm,

HYPRE\_StructSolver \*solver)

Create a solver object

int

HYPRE\_StructPFMGDestroy (HYPRE\_StructSolver solver)

Destroy a solver object

int

HYPRE\_StructPFMGSetup (HYPRE\_StructSolver solver,

HYPRE\_StructWatrix A,
HYPRE\_StructVector b,
HYPRE\_StructVector x)

int

HYPRE\_StructPFMGSolve (HYPRE\_StructSolver solver,

HYPRE\_StructVector b, HYPRE\_StructVector x)

Solve the system

int

HYPRE\_StructPFMGSetTol (HYPRE\_StructSolver solver, double tol)

(Optional) Set the convergence tolerance

int

HYPRE\_StructPFMGSetMaxIter (HYPRE\_StructSolver solver,

int max\_iter)

(Optional) Set maximum number of iterations

int

HYPRE\_StructPFMGSetRelChange (HYPRE\_StructSolver solver,

int rel\_change)

(Optional) Additionally require that the relative difference in successive iterates be small

```
HYPRE_StructPFMGSetZeroGuess (HYPRE_StructSolver solver)
       (Optional) Use a zero initial guess
int
HYPRE_StructPFMGSetNonZeroGuess (HYPRE_StructSolver solver)
      (Optional) Use a nonzero initial guess
int
HYPRE_StructPFMGSetRelaxType (HYPRE_StructSolver solver,
                                      int relax_type)
      (Optional) Set relaxation type
int
HYPRE_StructPFMGSetRAPType (HYPRE_StructSolver solver,
                                      int rap_type)
      (Optional) Set type of code used for coarse operator
int
HYPRE_StructPFMGSetNumPreRelax (HYPRE_StructSolver solver,
                                          int num_pre_relax)
      (Optional) Set number of pre-relaxation sweeps
HYPRE_StructPFMGSetNumPostRelax (HYPRE_StructSolver solver,
                                           int num_post_relax)
      (Optional) Set number of post-relaxation sweeps
int
HYPRE_StructPFMGSetSkipRelax (HYPRE_StructSolver solver,
                                      int skip_relax)
      (Optional) Skip relaxation on certain grids for isotropic problems
int
HYPRE_StructPFMGSetLogging (HYPRE_StructSolver solver, int logging)
      (Optional) Set the amount of logging to do
int
HYPRE_StructPFMGSetPrintLevel (HYPRE_StructSolver solver,
                                      int print_level)
       (Optional) To allow printing to the screen
```

int

**HYPRE\_StructPFMGGetNumIterations** (HYPRE\_StructSolver solver, int \*num\_iterations)

 $Return\ the\ number\ of\ iterations\ taken$ 

int

 $HYPRE\_StructPFMGGetFinalRelativeResidualNorm$ 

(HYPRE\_StructSolver solver, double \*norm)

Return the norm of the final relative residual

# Struct SMG Solver

#### Names

int

HYPRE\_StructSMGCreate (MPI\_Comm comm,

HYPRE\_StructSolver \*solver)

Create a solver object

int

HYPRE\_StructSMGDestroy (HYPRE\_StructSolver solver)

Destroy a solver object

int

HYPRE\_StructSMGSetup (HYPRE\_StructSolver solver,

HYPRE\_StructMatrix A,

HYPRE\_StructVector b, HYPRE\_StructVector x)

int

HYPRE\_StructSMGSolve (HYPRE\_StructSolver solver,

HYPRE\_StructMatrix A, HYPRE\_StructVector b, HYPRE\_StructVector x)

Solve the system

int

HYPRE\_StructSMGSetTol (HYPRE\_StructSolver solver, double tol)

(Optional) Set the convergence tolerance

int

HYPRE\_StructSMGSetMaxIter (HYPRE\_StructSolver solver, int max\_iter)

(Optional) Set maximum number of iterations

int

HYPRE\_StructSMGSetRelChange (HYPRE\_StructSolver solver,

int rel\_change)

(Optional) Additionally require that the relative difference in successive iterates be small

int

HYPRE\_StructSMGSetZeroGuess (HYPRE\_StructSolver solver)

(Optional) Use a zero initial guess

int

HYPRE\_StructSMGSetNonZeroGuess (HYPRE\_StructSolver solver)

(Optional) Use a nonzero initial guess

int

HYPRE\_StructSMGSetNumPreRelax (HYPRE\_StructSolver solver,

int num\_pre\_relax)

(Optional) Set number of pre-relaxation sweeps

#### HYPRE\_StructSMGSetNumPostRelax (HYPRE\_StructSolver solver,

int num\_post\_relax)

(Optional) Set number of post-relaxation sweeps

int

HYPRE\_StructSMGSetLogging (HYPRE\_StructSolver solver, int logging)

(Optional) Set the amount of logging to do

int

HYPRE\_StructSMGSetPrintLevel (HYPRE\_StructSolver solver,

int print\_level)

(Optional) To allow printing to the screen

int

HYPRE\_StructSMGGetNumIterations (HYPRE\_StructSolver solver,

int \*num\_iterations)

Return the number of iterations taken

int

 ${\bf HYPRE\_StructSMGGetFinalRelativeResidualNorm}~({\tt HYPRE\_StructSolver})$ 

solver,

double \*norm)

Return the norm of the final relative residual

4.5

# Struct PCG Solver

#### Names

int

HYPRE\_StructPCGCreate (MPI\_Comm comm,

HYPRE\_StructSolver \*solver)

Create a solver object

int

HYPRE\_StructPCGDestroy (HYPRE\_StructSolver solver)

Destroy a solver object

int

HYPRE\_StructPCGSetup (HYPRE\_StructSolver solver,

HYPRE\_StructMatrix A,

HYPRE\_StructVector b, HYPRE\_StructVector x)

int

HYPRE\_StructPCGSolve (HYPRE\_StructSolver solver,

 $HYPRE\_StructMatrix\ A,\ HYPRE\_StructVector\ b,$ 

HYPRE\_StructVector x)

Solve the system

```
HYPRE_StructPCGSetTol (HYPRE_StructSolver solver, double tol)
       (Optional) Set the convergence tolerance
int
HYPRE_StructPCGSetMaxIter (HYPRE_StructSolver solver, int max_iter)
      (Optional) Set maximum number of iterations
int
HYPRE_StructPCGSetTwoNorm (HYPRE_StructSolver solver,
                                    int two_norm)
      (Optional) Use the two-norm in stopping criteria
int
HYPRE_StructPCGSetRelChange (HYPRE_StructSolver solver,
                                     int rel_change)
      (Optional) Additionally require that the relative difference in successive it-
      erates be small
int
HYPRE_StructPCGSetPrecond (HYPRE_StructSolver solver,
                                  HYPRE_PtrToStructSolverFcn precond,
                                  HYPRE_PtrToStructSolverFcn
                                  precond_setup,
                                  HYPRE_StructSolver precond_solver)
      (Optional) Set the preconditioner to use
int
HYPRE_StructPCGSetLogging (HYPRE_StructSolver solver, int logging)
      (Optional) Set the amount of logging to do
int
HYPRE_StructPCGSetPrintLevel (HYPRE_StructSolver solver, int level)
      (Optional) Set the print level
int
HYPRE_StructPCGGetNumIterations (HYPRE_StructSolver solver,
                                         int *num_iterations)
      Return the number of iterations taken
int
HYPRE_StructPCGGetFinalRelativeResidualNorm (HYPRE_StructSolver
                                                       solver,
                                                       double *norm)
      Return the norm of the final relative residual
```

int

# **HYPRE\_StructPCGGetResidual** (HYPRE\_StructSolver solver, void \*\*residual)

Return the residual

int

# HYPRE\_StructDiagScaleSetup (HYPRE\_StructSolver solver, HYPRE\_StructMatrix A, HYPRE\_StructVector y,

HYPRE\_StructVector x)

Setup routine for diagonal preconditioning

# **HYPRE\_StructDiagScale** (HYPRE\_StructSolver solver, HYPRE\_StructMatrix HA,

HYPRE\_StructVector Hy, HYPRE\_StructVector Hx)

Solve routine for diagonal preconditioning

4.6

# Struct GMRES Solver

```
Names
```

int

HYPRE\_StructGMRESCreate (MPI\_Comm comm,

HYPRE\_StructSolver \*solver )

Create a solver object

int

**HYPRE\_StructGMRESDestroy** ( HYPRE\_StructSolver solver )

Destroy a solver object

int

HYPRE\_StructGMRESSetup (HYPRE\_StructSolver solver,

HYPRE\_StructVector b, HYPRE\_StructVector x)

set up

int

HYPRE\_StructGMRESSolve ( HYPRE\_StructSolver solver,

HYPRE\_StructVector b, HYPRE\_StructVector x)

Solve the system

int

HYPRE\_StructGMRESSetTol (HYPRE\_StructSolver solver, double tol)

(Optional) Set the convergence tolerance

int

HYPRE\_StructGMRESSetMaxIter (HYPRE\_StructSolver solver,

int max\_iter)

(Optional) Set maximum number of iterations

int

HYPRE\_StructGMRESSetPrecond (HYPRE\_StructSolver solver,

HYPRE\_PtrToStructSolverFcn precond,

 $HYPRE\_PtrToStructSolverFcn$ 

precond\_setup,

HYPRE\_StructSolver precond\_solver)

(Optional) Set the preconditioner to use

```
HYPRE_StructGMRESSetLogging (HYPRE_StructSolver solver,
                                    int logging )
      (Optional) Set the amount of logging to do
int
HYPRE_StructGMRESSetPrintLevel (HYPRE_StructSolver solver,
                                       int level)
      (Optional) Set the print level
int
HYPRE_StructGMRESGetNumIterations (HYPRE_StructSolver solver,
                                            int *num_iterations )
      Return the number of iterations taken
int
HYPRE\_StructGMRESGetFinalRelativeResidualNorm (
                                                         HYPRE_StructSolver
                                                         solver,
                                                         double *norm )
      Return the norm of the final relative residual
int
HYPRE_StructGMRESGetResidual (HYPRE_StructSolver solver,
                                      void **residual)
```

4.7

### Struct BiCGSTAB Solver

#### Names

int

HYPRE\_StructBiCGSTABCreate (MPI\_Comm comm,

HYPRE\_StructSolver \*solver )

 $Create\ a\ solver\ object$ 

Return the residual

int

**HYPRE\_StructBiCGSTABDestroy** (HYPRE\_StructSolver solver)

Destroy a solver object

int

HYPRE\_StructBiCGSTABSetup (HYPRE\_StructSolver solver,

HYPRE\_StructVector b, HYPRE\_StructVector x)

set up

```
HYPRE_StructBiCGSTABSolve (HYPRE_StructSolver solver,
                                  HYPRE_StructMatrix A,
                                  HYPRE_StructVector b,
                                  HYPRE_StructVector x )
      Solve the system
int
HYPRE_StructBiCGSTABSetTol (HYPRE_StructSolver solver, double tol)
      (Optional) Set the convergence tolerance
int
HYPRE_StructBiCGSTABSetMaxIter (HYPRE_StructSolver solver,
                                        int max_iter)
      (Optional) Set maximum number of iterations
int
HYPRE_StructBiCGSTABSetPrecond (HYPRE_StructSolver solver,
                                        HYPRE\_PtrToStructSolverFcn
                                        precond.
                                        HYPRE\_PtrToStructSolverFcn
                                        precond_setup,
                                        HYPRE_StructSolver precond_solver
      (Optional) Set the preconditioner to use
HYPRE_StructBiCGSTABSetLogging (HYPRE_StructSolver solver,
                                       int logging)
      (Optional) Set the amount of logging to do
int
HYPRE_StructBiCGSTABSetPrintLevel (HYPRE_StructSolver solver,
                                          int level)
      (Optional) Set the print level
HYPRE_StructBiCGSTABGetNumIterations (HYPRE_StructSolver
                                               solver, int *num_iterations)
      Return the number of iterations taken
int
HYPRE\_StructBiCGSTABGetFinalRelativeResidualNorm\ (
                                                            HYPRE_StructSolver
                                                            solver,
                                                            double *norm
      Return the norm of the final relative residual
HYPRE_StructBiCGSTABGetResidual (HYPRE_StructSolver solver,
                                         void **residual)
```

Return the residual

# extern SStruct Solvers

$\mathbf{Names}$		
5.1	SStruct Solvers	50
5.2	CS4 + DCC S 1	90
3.2	SStruct PCG Solver	50
5.3	SStruct BiCGSTAB Solver	
		52
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		57
5.7	extern ParCSR Solvers	
	Linear solvers for sparse matrix systems	59

These solvers use matrix/vector storage schemes that are taylored to semi-structured grid problems.

5.1

# SStruct Solvers

# Names

 $\label{typedef} \begin{tabular}{ll} typedef struct & hypre\_SStructSolver\_struct* & HYPRE\_SStructSolver\\ & The \ solver \ object \\ \end{tabular}$ 

5.2

# SStruct PCG Solver

# Names int HYPRE\_SStructPCGCreate (MPI\_Comm comm, HYPRE\_SStructSolver \*solver) Create a solver object 5.2.1int HYPRE\_SStructPCGDestroy (HYPRE\_SStructSolver solver) Destroy a solver object ...... int HYPRE\_SStructPCGSetup (HYPRE\_SStructSolver solver, HYPRE\_SStructMatrix A, HYPRE\_SStructVector b, HYPRE\_SStructVector x) int HYPRE\_SStructPCGSolve (HYPRE\_SStructSolver solver, HYPRE\_SStructMatrix A, HYPRE\_SStructVector b, HYPRE\_SStructVector x) Solve the system int HYPRE\_SStructPCGSetTol (HYPRE\_SStructSolver solver, double tol) (Optional) Set the convergence tolerance int HYPRE\_SStructPCGSetMaxIter (HYPRE\_SStructSolver solver, int max\_iter) (Optional) Set maximum number of iterations int HYPRE\_SStructPCGSetTwoNorm (HYPRE\_SStructSolver solver, int two\_norm ) (Optional) Set type of norm to use in stopping criteria int HYPRE\_SStructPCGSetRelChange (HYPRE\_SStructSolver solver, int rel\_change) (Optional) Set to use additional relative-change convergence test int HYPRE\_SStructPCGSetPrecond (HYPRE\_SStructSolver solver, HYPRE\_PtrToSStructSolverFcn precond, $HYPRE\_PtrToSStructSolverFcn$

precond\_setup, void \*precond\_solver)

(Optional) Set the preconditioner to use

int

HYPRE\_SStructPCGSetLogging (HYPRE\_SStructSolver solver, int logging) (Optional) Set the amount of logging to do

int

HYPRE\_SStructPCGSetPrintLevel (HYPRE\_SStructSolver solver, int level) (Optional) Set the print level

int

52

# **HYPRE\_SStructPCGGetNumIterations** (HYPRE\_SStructSolver solver, int \*num\_iterations)

Return the number of iterations taken

int

### $HYPRE\_SStructPCGGetFinalRelativeResidualNorm$

(HYPRE\_SStructSolver solver, double \*norm)

Return the norm of the final relative residual

int

 $\begin{array}{c} \textbf{HYPRE\_SStructPCGGetResidual} \; (\texttt{HYPRE\_SStructSolver solver}, \\ \text{void **residual}) \end{array}$ 

Return the residual

5.2.1

int HYPRE\_SStructPCGDestroy (HYPRE\_SStructSolver solver)

Destroy a solver object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

5.3

### SStruct BiCGSTAB Solver

Names

int

HYPRE\_SStructBiCGSTABCreate (MPI\_Comm comm,

HYPRE\_SStructSolver \*solver)

Create a solver object

5.3.1 int

HYPRE\_SStructBiCGSTABDestroy (HYPRE\_SStructSolver solver)

```
HYPRE_SStructBiCGSTABSetup (HYPRE_SStructSolver solver,
                                    HYPRE_SStructMatrix A,
                                    HYPRE_SStructVector b,
                                    HYPRE_SStructVector x)
int
HYPRE_SStructBiCGSTABSolve (HYPRE_SStructSolver solver,
                                   HYPRE_SStructMatrix A,
                                   HYPRE_SStructVector b,
                                   HYPRE_SStructVector x)
      Solve the system
int
HYPRE_SStructBiCGSTABSetTol (HYPRE_SStructSolver solver,
                                     double tol)
      (Optional) Set the convergence tolerance
int
HYPRE_SStructBiCGSTABSetMaxIter (HYPRE_SStructSolver solver,
                                         int max_iter)
      (Optional) Set maximum number of iterations
int
HYPRE_SStructBiCGSTABSetPrecond (HYPRE_SStructSolver solver,
                                          HYPRE\_PtrToSStructSolverFcn
                                          precond,
                                         HYPRE_PtrToSStructSolverFcn
                                         precond_setup,
                                          void *precond_solver)
      (Optional) Set the preconditioner to use
int
HYPRE_SStructBiCGSTABSetLogging (HYPRE_SStructSolver solver,
                                         int logging)
      (Optional) Set the amount of logging to do
int
HYPRE_SStructBiCGSTABSetPrintLevel (HYPRE_SStructSolver solver,
                                            int level)
      (Optional) Set the print level
int
{\bf HYPRE\_SStructBiCGSTABGetNumIterations}~({\tt HYPRE\_SStructSolver}
                                                 solver,
                                                 int *num_iterations)
      Return the number of iterations taken
int
HYPRE\_SStructBiCGSTABGetFinalRelativeResidualNorm
```

(HYPRE\_SStructSolver solver, double \*norm)

Return the norm of the final relative residual

# **HYPRE\_SStructBiCGSTABGetResidual** (HYPRE\_SStructSolver solver, void \*\*residual)

Return the residual

 $_{-}$  5.3.1

# int HYPRE\_SStructBiCGSTABDestroy (HYPRE\_SStructSolver solver)

Destroy a solver object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

**5.4** 

### SStruct GMRES Solver

Names

int

HYPRE\_SStructGMRESCreate (MPI\_Comm comm,

HYPRE\_SStructSolver \*solver)

Create a solver object

5.4.1 int

HYPRE\_SStructGMRESDestroy (HYPRE\_SStructSolver solver)

int

HYPRE\_SStructGMRESSetup (HYPRE\_SStructSolver solver,

HYPRE\_SStructVector b, HYPRE\_SStructVector x)

int

HYPRE\_SStructGMRESSolve (HYPRE\_SStructSolver solver,

HYPRE\_SStructVector b, HYPRE\_SStructVector x)

Solve the system

```
HYPRE_SStructGMRESSetKDim (HYPRE_SStructSolver solver, int k_dim)
       (Optional) Set the maximum size of the Krylov space
int
HYPRE_SStructGMRESSetTol (HYPRE_SStructSolver solver, double tol)
      (Optional) Set the convergence tolerance
int
HYPRE_SStructGMRESSetMaxIter (HYPRE_SStructSolver solver,
                                      int max_iter)
      (Optional) Set maximum number of iterations
int
HYPRE_SStructGMRESSetPrecond (HYPRE_SStructSolver solver,
                                      HYPRE_PtrToSStructSolverFcn
                                      precond,
                                      HYPRE\_PtrToSStructSolverFcn
                                      precond_setup, void *precond_solver)
      (Optional) Set the preconditioner to use
int
HYPRE_SStructGMRESSetLogging (HYPRE_SStructSolver solver,
                                      int logging)
      (Optional) Set the amount of logging to do
int
HYPRE_SStructGMRESSetPrintLevel (HYPRE_SStructSolver solver,
                                         int print_level)
      (Optional) Set the print level
int
HYPRE_SStructGMRESGetNumIterations (HYPRE_SStructSolver solver,
                                              int *num_iterations)
       Return the number of iterations taken
int
```

### $HYPRE\_SStructGMRESGetFinalRelativeResidualNorm$

(HYPRE\_SStructSolver solver, double \*norm)

 $Return\ the\ norm\ of\ the\ final\ relative\ residual$ 

int

# **HYPRE\_SStructGMRESGetResidual** (HYPRE\_SStructSolver solver, void \*\*residual)

Return the residual

5.4.1

int HYPRE\_SStructGMRESDestroy (HYPRE\_SStructSolver solver)

Destroy a solver object. An object should be explicitly destroyed using this destructor when the user's code no longer needs direct access to it. Once destroyed, the object must not be referenced again. Note that the object may not be deallocated at the completion of this call, since there may be internal package references to the object. The object will then be destroyed when all internal reference counts go to zero.

5.5

# SStruct SysPFMG Solver

#### Names

int

Create a solver object

int

HYPRE\_SStructSysPFMGDestroy (HYPRE\_SStructSolver solver)

Destroy a solver object

int

HYPRE\_SStructSysPFMGSetup (HYPRE\_SStructSolver solver,

HYPRE\_SStructMatrix A,
HYPRE\_SStructVector b,
HYPRE\_SStructVector x)

int

HYPRE\_SStructSysPFMGSolve (HYPRE\_SStructSolver solver,

HYPRE\_SStructVector b, HYPRE\_SStructVector x)

Solve the system

int

HYPRE\_SStructSysPFMGSetTol (HYPRE\_SStructSolver solver, double tol)

(Optional) Set the convergence tolerance

int

HYPRE\_SStructSysPFMGSetMaxIter (HYPRE\_SStructSolver solver,

int max\_iter)

(Optional) Set maximum number of iterations

int

HYPRE\_SStructSysPFMGSetRelChange (HYPRE\_SStructSolver solver,

int rel\_change)

(Optional) Additionally require that the relative difference in successive iterates be small

int

HYPRE\_SStructSysPFMGSetZeroGuess (HYPRE\_SStructSolver solver)

(Optional) Use a zero initial guess

# ${\bf HYPRE\_SStructSysPFMGSetNonZeroGuess}~({\tt HYPRE\_SStructSolver}$ solver) (Optional) Use a nonzero initial guess int HYPRE\_SStructSysPFMGSetRelaxType (HYPRE\_SStructSolver solver, int relax\_type) (Optional) Set relaxation type int HYPRE\_SStructSysPFMGSetNumPreRelax (HYPRE\_SStructSolver solver, int num\_pre\_relax) (Optional) Set number of pre-relaxation sweeps int ${\bf HYPRE\_SStructSysPFMGSetNumPostRelax}~({\tt HYPRE\_SStructSolver}$ solver, int num\_post\_relax) (Optional) Set number of post-relaxation sweeps int HYPRE\_SStructSysPFMGSetSkipRelax (HYPRE\_SStructSolver solver, int skip\_relax) (Optional) Skip relaxation on certain grids for isotropic problems int HYPRE\_SStructSysPFMGSetLogging (HYPRE\_SStructSolver solver, int logging) (Optional) Set the amount of logging to do HYPRE\_SStructSysPFMGSetPrintLevel (HYPRE\_SStructSolver solver, int print\_level) (Optional) Set the print level int ${\bf HYPRE\_SStructSysPFMGGetNumIterations}~({\tt HYPRE\_SStructSolver}$ solver, int \*num\_iterations) Return the number of iterations taken int HYPRE\_SStructSysPFMGGetFinalRelativeResidualNorm ( $HYPRE\_SStructSolver$ solver, double \*norm)

 $Return\ the\ norm\ of\ the\ final\ relative\ residual$ 

5.6

# SStruct FAC Solver

Names

```
HYPRE_SStructFACCreate (MPI_Comm comm,
                              HYPRE_SStructSolver *solver )
       Create a FAC solver object
int
HYPRE_SStructFACDestroy2 (HYPRE_SStructSolver solver)
      Destroy a FAC solver object
int
HYPRE_SStructFACSetup2 (HYPRE_SStructSolver solver,
                              HYPRE_SStructMatrix A,
                              HYPRE_SStructVector b.
                              HYPRE_SStructVector x)
      Set up the FAC solver structure
int
HYPRE_SStructFACSolve3 (HYPRE_SStructSolver solver,
                             HYPRE_SStructMatrix A,
                             HYPRE_SStructVector b,
                             HYPRE_SStructVector x)
      Solve the system
int
HYPRE_SStructFACSetPLevels (HYPRE_SStructSolver solver, int nparts,
                                  int *plevels)
      Set up amr structure
int
HYPRE_SStructFACSetPRefinements (HYPRE_SStructSolver solver,
                                        int nparts, int (*rfactors)[3])
      Set up amr refinement factors
int
HYPRE_SStructFACSetMaxLevels (HYPRE_SStructSolver solver,
                                     int max_levels )
       (Optional) Set max FAC levels
int
HYPRE_SStructFACSetTol (HYPRE_SStructSolver solver, double tol)
      (Optional) Set the convergence tolerance
int
HYPRE_SStructFACSetMaxIter (HYPRE_SStructSolver solver,
                                  int max_iter)
      (Optional) Set maximum number of iterations
int
HYPRE_SStructFACSetRelChange (HYPRE_SStructSolver solver,
                                     int rel_change)
       (Optional) Additionally require that the relative difference in successive it-
       erates be small
int
HYPRE_SStructFACSetZeroGuess (HYPRE_SStructSolver solver)
      (Optional) Use a zero initial guess
int
HYPRE_SStructFACSetNonZeroGuess (HYPRE_SStructSolver solver)
       (Optional) Use a nonzero initial guess
```

# HYPRE\_SStructFACSetRelaxType (HYPRE\_SStructSolver solver, int relax\_type) (Optional) Set relaxation type int HYPRE\_SStructFACSetNumPreRelax (HYPRE\_SStructSolver solver, int num\_pre\_relax) (Optional) Set number of pre-relaxation sweeps int HYPRE\_SStructFACSetNumPostRelax (HYPRE\_SStructSolver solver, int num\_post\_relax) (Optional) Set number of post-relaxation sweeps int ${\bf HYPRE\_SStructFACSetCoarseSolverType}~({\tt HYPRE\_SStructSolver}~solver,$ int csolver\_type) (Optional) Set coarsest solver type int HYPRE\_SStructFACSetLogging (HYPRE\_SStructSolver solver, int logging) (Optional) Set the amount of logging to do ${\rm int}$ HYPRE\_SStructFACGetNumIterations (HYPRE\_SStructSolver solver, int \*num\_iterations) Return the number of iterations taken int ${\bf HYPRE\_SStructFACGetFinalRelativeResidualNorm}$ ( HYPRE\_SStructSolver solver, double \*norm)

Return the norm of the final relative residual

5.7

# extern ParCSR Solvers

$\mathbf{Names}$		
5.7.1	ParCSR Solvers	
		60
5.7.2	ParCSR BoomerAMG Solver and Preconditioner	
		60
5.7.3	ParCSR ParaSails Preconditioner	
		79
5.7.4	ParCSR Euclid Preconditioner	
		84
5.7.5	ParCSR Pilut Preconditioner	

	86
ParCSR PCG Solver	
	87
ParCSR GMRES Solver	
	88
	ParCSR PCG Solver ParCSR GMRES Solver

These solvers use matrix/vector storage schemes that are taylored for general sparse matrix systems.

5.7.1

# ParCSR Solvers

Names

#define HYPRE\_SOLVER\_STRUCT

The solver object

5.7.2

# ParCSR BoomerAMG Solver and Preconditioner

#### Names

int

**HYPRE\_BoomerAMGCreate** (HYPRE\_Solver \*solver)

Create a solver object

int

HYPRE\_BoomerAMGDestroy (HYPRE\_Solver solver)

Destroy a solver object

5.7.2.1 int

HYPRE\_BoomerAMGSetup (HYPRE\_Solver solver,

HYPRE\_ParCSRMatrix A,

HYPRE\_ParVector b, HYPRE\_ParVector x)

Set up the BoomerAMG solver or preconditioner .....

5.7.2.2 int

65

	HYPRE_BoomerAMGSolve (HYPRE_Solver solver, HYPRE_ParCSRMatrix A, HYPRE_ParVector b, HYPRE_ParVector x)	
	Solve the system or apply AMG as a preconditioner	65
5.7.2.3	int <b>HYPRE_BoomerAMGSolveT</b> (HYPRE_Solver solver,  HYPRE_ParCSRMatrix A,  HYPRE_ParVector b, HYPRE_ParVector x)  Solve the transpose system $A^Tx = b$ or apply AMG as a preconditioner to	
	the transpose system $A = b$ or apply AMO as a preconationer to	66
5.7.2.4	int  HYPRE_BoomerAMGSetTol (HYPRE_Solver solver, double tol)  (Optional) Set the convergence tolerance, if BoomerAMG is used as a solver	66
5.7.2.5	int  HYPRE_BoomerAMGSetMaxIter (HYPRE_Solver solver, int max_iter)  (Optional) Sets maximum number of iterations, if BoomerAMG is used as a solver	66
5.7.2.6	int  HYPRE_BoomerAMGSetMaxLevels (HYPRE_Solver solver, int max_levels)  (Optional) Sets maximum number of multigrid levels	67
5.7.2.7	int HYPRE_BoomerAMGSetStrongThreshold (HYPRE_Solver solver, double strong_threshold)	01
	(Optional) Sets AMG strength threshold	67
5.7.2.8	int HYPRE_BoomerAMGSetMaxRowSum (HYPRE_Solver solver, double max_row_sum)  (Optional) Sets a parameter to modify the definition of strength for diagonal	
£ 7 2 0	dominant portions of the matrix	67
5.7.2.9	int HYPRE_BoomerAMGSetCoarsenType (HYPRE_Solver solver, int coarsen_type)  (Optional) Defines which parallel coarsening algorithm is used	68
	int  HYPRE_BoomerAMGSetMeasureType (HYPRE_Solver solver,	
5.7.2.10	int	
	HYPRE_BoomerAMGSetCycleType (HYPRE_Solver solver, int cycle_type)  (Optional) Defines the type of cycle	68
5.7.2.11	int  HYPRE_BoomerAMGSetNumGridSweeps (HYPRE_Solver solver,	
	up and down cycle	68
5.7.2.12	int	

	HYPRE_BoomerAMGSetNumSweeps (HYPRE_Solver solver,	
	${ m int\ num\_sweeps})$ (Optional) Sets the number of sweeps	69
r 7 0 10		03
5.7.2.13	int HYPRE_BoomerAMGSetCycleNumSweeps (HYPRE_Solver solver,	
		69
5.7.2.14	int HYPRE_BoomerAMGSetGridRelaxType (HYPRE_Solver solver, int *grid_relax_type)	
	(Optional) Defines which smoother is used on the fine and coarse grid, the up and down cycle	69
5.7.2.15	int  HYPRE_BoomerAMGSetRelaxType (HYPRE_Solver solver, int relax_type)  (Optional) Defines the smoother to be used	70
5.7.2.16	int	
02.10	HYPRE_BoomerAMGSetCycleRelaxType (HYPRE_Solver solver, int relax_type, int k)	
	(Optional) Defines the smoother at a given cycle	70
5.7.2.17	int	
	HYPRE_BoomerAMGSetRelaxOrder (HYPRE_Solver solver, int relax_order)	
	(Optional) Defines in which order the points are relaxed	71
5.7.2.18	int HYPRE_BoomerAMGSetGridRelaxPoints (HYPRE_Solver solver,	
	int **grid_relax_points) (Optional) Defines in which order the points are relaxed	71
5.7.2.19	$ \begin{array}{l} \text{int} \\ \textbf{HYPRE\_BoomerAMGSetRelaxWeight} \ (\text{HYPRE\_Solver solver}, \end{array} \\ \\$	
	double *relax_weight) (Optional) Defines the relaxation weight for smoothed Jacobi and hybrid SOR	71
5.7.2.20	int HYPRE_BoomerAMGSetRelaxWt (HYPRE_Solver solver,	
	double relax_weight) (Optional) Defines the relaxation weight for smoothed Jacobi and hybrid SOR on all levels	72
5.7.2.21	$\begin{array}{l} \operatorname{int} \\ \mathbf{HYPRE\_BoomerAMGSetLevelRelaxWt} \ (\operatorname{HYPRE\_Solver} \ \operatorname{solver}, \end{array}$	
	double relax_weight, int level)  (Optional) Defines the relaxation weight for smoothed Jacobi and hybrid  SOR on the user defined level	72
5.7.2.22	int	, –
Ç <b>2.22</b>	HYPRE_BoomerAMGSetOmega (HYPRE_Solver solver, double *omega)  (Optional) Defines the outer relaxation weight for hybrid SOR	72
5.7.2.23	int	

	HYPRE_BoomerAMGSetOuterWt (HYPRE_Solver solver, double omega)  (Optional) Defines the outer relaxation weight for hybrid SOR and SSOR on all levels	7
5.7.2.24	$\operatorname{int}$	
	HYPRE_BoomerAMGSetLevelOuterWt (HYPRE_Solver solver,	
	double omega, int level) (Optional) Defines the outer relaxation weight for hybrid SOR or SSOR on the user defined level	7
	$\label{eq:hypre_bound} \begin{split} & \text{HYPRE\_BoomerAMGSetDebugFlag} \text{ (HYPRE\_Solver solver, int debug\_flag)} \\ & & (Optional) \end{split}$	
	int HYPRE_BoomerAMGGetNumIterations (HYPRE_Solver solver,	
	$\operatorname{int} *\operatorname{num\_iterations})$ $Returns \ the \ number \ of \ iterations \ taken$	
	int HYPRE_BoomerAMGGetFinalRelativeResidualNorm (HYPRE_Solver solver, double *rel_resid_norm)	
	Returns the norm of the final relative residual	
5.7.2.25	int HYPRE_BoomerAMGSetTruncFactor (HYPRE_Solver solver,	
	double trunc_factor) (Optional) Defines a truncation factor for the interpolation	7
5.7.2.26	int HYPRE_BoomerAMGSetSCommPkgSwitch (HYPRE_Solver solver, double S_commpkg_switch)  (Optional) Defines the largest strength threshold for which the strength matrix S uses the communication package of the operator A	7
5.7.2.27	$\operatorname{int}$	•
	HYPRE_BoomerAMGSetSmoothType (HYPRE_Solver solver, int smooth_type)	
	(Optional) Enables the use of more complex smoothers	7
5.7.2.28	int HYPRE_BoomerAMGSetSmoothNumLevels (HYPRE_Solver solver, int smooth_num_levels)	
	(Optional) Sets the number of levels for more complex smoothers	7
5.7.2.29	$\mathbf{HYPRE\_BoomerAMGSetSmoothNumSweeps} \ (\mathbf{HYPRE\_Solver} \ \mathbf{solver},$	
	int smooth_num_sweeps) (Optional) Sets the number of sweeps for more complex smoothers	7
	int  HYPRE_BoomerAMGSetPrintLevel (HYPRE_Solver solver, int print_level)  (Optional) Requests automatic printing of solver performance and debugging data; default to 0 for no printing	
5.7.2.30	$\operatorname{int}$	

	HYPRE_BoomerAMGSetLogging (HYPRE_Solver solver, int logging)  (Optional) Requests additional computations for diagnostic and similar data to be logged by the user
5.7.2.31	int
	HYPRE_BoomerAMGSetNumFunctions (HYPRE_Solver solver,
	int num_functions)
	(Optional) Sets the size of the system of PDEs, if using the systems version
5.7.2.32	int
	HYPRE_BoomerAMGSetNodal (HYPRE_Solver solver, int nodal)  (Optional) Sets whether to use the nodal systems version
5.7.2.33	int
	HYPRE_BoomerAMGSetDofFunc (HYPRE_Solver solver, int *dof_func)
	(Optional) Sets the mapping that assigns the function to each variable, if using the systems version
5.7.2.34	int
	HYPRE_BoomerAMGSetVariant (HYPRE_Solver solver, int variant)
	(Optional) Defines which variant of the Schwarz method is used
5.7.2.35	int
	HYPRE_BoomerAMGSetOverlap (HYPRE_Solver solver, int overlap)
	(Optional) Defines the overlap for the Schwarz method
5.7.2.36	int
	HYPRE_BoomerAMGSetDomainType (HYPRE_Solver solver,
	int domain_type) (Optional) Defines the type of domain used for the Schwarz method
	int
	HYPRE_BoomerAMGSetSchwarzRlxWeight (HYPRE_Solver solver, double schwarz_rlx_weight)
	(Optional) Defines a smoothing parameter for the additive Schwarz method
5.7.2.37	int
0.1.2.31	HYPRE_BoomerAMGSetSym (HYPRE_Solver solver, int sym)
	(Optional) Defines symmetry for ParaSAILS
5.7.2.38	int
0.1.2.30	HYPRE_BoomerAMGSetLevel (HYPRE_Solver solver, int level)
	(Optional) Defines number of levels for ParaSAILS
5.7.2.39	int
0.11.2.00	HYPRE_BoomerAMGSetThreshold (HYPRE_Solver solver,
	double threshold)
	(Optional) Defines threshold for ParaSAILS
5.7.2.40	int
	HYPRE_BoomerAMGSetFilter (HYPRE_Solver solver, double filter)
	(Optional) Defines filter for ParaSAILS
5.7.2.41	int
	HYPRE_BoomerAMGSetDropTol (HYPRE_Solver solver, double drop_tol)
	(Optional) Defines drop tolerance for PILUT
5.7.2.42	int

	HYPRE_BoomerAMGSetMaxNzPerRow (HYPRE_Solver solver,	
	$\operatorname{int\ max\_nz\_per\_row})$	
	(Optional) Defines maximal number of nonzeros for PILUT	78
5.7.2.43	$\operatorname{int}$	
	HYPRE_BoomerAMGSetEuclidFile (HYPRE_Solver solver, char *euclidfile)	
	(Optional) Defines name of an input file for Euclid parameters	79
5.7.2.44	$\operatorname{int}$	
	HYPRE_BoomerAMGSetGSMG (HYPRE_Solver solver, int gsmg)	
	$(Optional)\ Specifies\ the\ use\ of\ GSMG$ - $geometrically\ smooth\ coarsening\ and$	
	interpolation	79
	$\operatorname{int}$	
	HYPRE_BoomerAMGSetNumSamples (HYPRE_Solver solver,	
	${ m int\ num\_samples})$	
	(Optional) Defines the number of sample vectors used in GSMG or LS interpolation	

Parallel unstructured algebraic multigrid solver and preconditioner

#### \_ 5.7.2.1 \_

 $_{\rm int}$ 

**HYPRE\_BoomerAMGSetup** (HYPRE\_Solver solver, HYPRE\_ParCSRMatrix A, HYPRE\_ParVector b, HYPRE\_ParVector x)

Set up the BoomerAMG solver or preconditioner. If used as a preconditioner, this function should be passed to the iterative solver SetPrecond function.

Parameters:

solver — [IN] object to be set up.

A — [IN] ParCSR matrix used to construct the solver/preconditioner.

b — Ignored by this function.

x — Ignored by this function.

### 5.7.2.2

int

**HYPRE\_BoomerAMGSolve** (HYPRE\_Solver solver, HYPRE\_ParCSRMatrix A, HYPRE\_ParVector b, HYPRE\_ParVector x)

Solve the system or apply AMG as a preconditioner. If used as a preconditioner, this function should be passed to the iterative solver SetPrecond function.

Parameters: solver — [IN] solver or preconditioner object to be applied.

A — [IN] ParCSR matrix, matrix of the linear system to be solved

b — [IN] right hand side of the linear system to be solved

x — [OUT] approximated solution of the linear system to be solved

5.7.2.3

int

**HYPRE\_BoomerAMGSolveT** (HYPRE\_Solver solver, HYPRE\_ParCSRMatrix A, HYPRE\_ParVector b, HYPRE\_ParVector x)

Solve the transpose system  $A^Tx = b$  or apply AMG as a preconditioner to the transpose system . If used as a preconditioner, this function should be passed to the iterative solver **SetPrecond** function.

Parameters: solver — [IN] solver or preconditioner object to be applied.

A — [IN] ParCSR matrix

b — [IN] right hand side of the linear system to be solved

x — [OUT] approximated solution of the linear system to be solved

\_ 5.7.2.4 \_\_\_

int HYPRE\_BoomerAMGSetTol (HYPRE\_Solver solver, double tol)

(Optional) Set the convergence tolerance, if BoomerAMG is used as a solver. If it is used as a preconditioner, this function has no effect. The default is 1.e-7.

 $_{-}$  5.7.2.5 .

int HYPRE\_BoomerAMGSetMaxIter (HYPRE\_Solver solver, int max\_iter)

(Optional) Sets maximum number of iterations, if BoomerAMG is used as a solver. If it is used as a preconditioner, this function has no effect. The default is 20.

5.7.2.6

int

HYPRE\_BoomerAMGSetMaxLevels (HYPRE\_Solver solver, int max\_levels)

(Optional) Sets maximum number of multigrid levels. The default is 25.

\_ 5.7.2.7 \_

HYPRE\_BoomerAMGSetStrongThreshold (HYPRE\_Solver solver, double strong\_threshold)

(Optional) Sets AMG strength threshold. The default is 0.25. For 2d Laplace operators, 0.25 is a good value, for 3d Laplace operators, 0.5 or 0.6 is a better value. For elasticity problems, a large strength threshold, such as 0.9, is often better.

5.7.2.8

int HYPRE\_BoomerAMGSetMaxRowSum (HYPRE\_Solver solver, double max\_row\_sum)

(Optional) Sets a parameter to modify the definition of strength for diagonal dominant portions of the matrix. The default is 0.9. If max\_row\_sum is 1, no checking for diagonally dominant rows is performed.

int

**HYPRE\_BoomerAMGSetCoarsenType** (HYPRE\_Solver solver, int coarsen\_type)

(Optional) Defines which parallel coarsening algorithm is used. There are the following options for coarsen\_type:

- 0 CLJP-coarsening (a parallel coarsening algorithm using independent sets.
- 1 | classical Ruge-Stueben coarsening on each processor, no boundary treatment (not recommended!)
- 3 classical Ruge-Stueben coarsening on each processor, followed by a third pass, which adds coarse points on the boundaries
- Falgout coarsening (uses 1 first, followed by CLJP using the interior coarse points generated by 1 as its first independent set)
- 7 CLJP-coarsening (using a fixed random vector, for debugging purposes only)
- 8 PMIS-coarsening (a parallel coarsening algorithm using independent sets, generating lower complexities than CLJP, might also lead to slower convergence)
- 9 | PMIS-coarsening (using a fixed random vector, for debugging purposes only)
- HMIS-coarsening (uses one pass Ruge-Stueben on each processor independently, followed by PMIS using the interior C-points generated as its first independent set)
- 11 one-pass Ruge-Stueben coarsening on each processor, no boundary treatment (not recommended!)

The default is 6.

5.7.2.10

int

**HYPRE\_BoomerAMGSetCycleType** (HYPRE\_Solver solver, int cycle\_type)

(Optional) Defines the type of cycle. For a V-cycle, set cycle\_type to 1, for a W-cycle set cycle\_type to 2. The default is 1.

5.7.2.11

int

**HYPRE\_BoomerAMGSetNumGridSweeps** (HYPRE\_Solver solver, int \*num\_grid\_sweeps)

(Optional) Defines the number of sweeps for the fine and coarse grid, the up and down cycle.

Note: This routine will be phased out!!!! Use HYPRE\_BoomerAMGSetNumSweeps or HYPRE\_BoomerAMGSetCycleNumSweeps instead.

#### 5.7.2.12

int

HYPRE\_BoomerAMGSetNumSweeps (HYPRE\_Solver solver, int num\_sweeps)

(Optional) Sets the number of sweeps. On the finest level, the up and the down cycle the number of sweeps are set to num\_sweeps and on the coarsest level to 1. The default is 1.

#### \_ 5.7.2.13 \_\_\_\_\_

int

**HYPRE\_BoomerAMGSetCycleNumSweeps** (HYPRE\_Solver solver, int num\_sweeps, int k)

(Optional) Sets the number of sweeps at a specified cycle. There are the following options for k:

the finest level	if k=0
the down cycle	if k=1
the up cycle	if $k=2$
the coarsest level	if $k=3$ .

### \_ 5.7.2.14 \_

int

**HYPRE\_BoomerAMGSetGridRelaxType** (HYPRE\_Solver solver, int \*grid\_relax\_type)

(Optional) Defines which smoother is used on the fine and coarse grid, the up and down cycle.

Note: This routine will be phased out!!!! Use  $HYPRE\_BoomerAMGSetRelaxType$  or  $HYPRE\_BoomerAMGSetCycleRelaxType$  instead.

#### 5.7.2.15

int **HYPRE\_BoomerAMGSetRelaxType** (HYPRE\_Solver solver, int relax\_type)

(Optional) Defines the smoother to be used. It uses the given smoother on the fine grid, the up and the down cycle and sets the solver on the coarsest level to Gaussian elimination (9). The default is Gauss-Seidel (3).

There are the following options for relax\_type:

- 0 Jacobi
- 1 | Gauss-Seidel, sequential (very slow!)
- 2 Gauss-Seidel, interior points in parallel, boundary sequential (slow!)
- 3 hybrid Gauss-Seidel or SOR, forward solve
- 4 hybrid Gauss-Seidel or SOR, backward solve
- 5 | hybrid chaotic Gauss-Seidel (works only with OpenMP)
- 6 hybrid symmetric Gauss-Seidel or SSOR
- 9 Gaussian elimination (only on coarsest level)

#### \_ 5.7.2.16 \_

int **HYPRE\_BoomerAMGSetCycleRelaxType** (HYPRE\_Solver solver, int relax\_type, int k)

(Optional) Defines the smoother at a given cycle. For options of relax\_type see description of HYPRE\_BoomerAMGSetRelaxType). Options for k are

the finest level	if k=0
the down cycle	if k=1
the up cycle	if k=2
the coarsest level	if k=3.

int

HYPRE\_BoomerAMGSetRelaxOrder (HYPRE\_Solver solver, int relax\_order)

(Optional) Defines in which order the points are relaxed. There are the following options for relax\_order:

- 0 the points are relaxed in natural or lexicographic order on each processor
- CF-relaxation is used, i.e on the fine grid and the down cycle the coarse points are relaxed first, followed by the fine points; on the up cycle the F-points are relaxed first, followed by the C-points. On the coarsest level, if an iterative scheme is used, the points are relaxed in lexicographic order.

The default is 1 (CF-relaxation).

5.7.2.18

HYPRE\_BoomerAMGSetGridRelaxPoints (HYPRE\_Solver solver, int \*\*grid\_relax\_points)

(Optional) Defines in which order the points are relaxed.

Note: This routine will be phased out!!!! Use HYPRE\_BoomerAMGSetRelaxOrder instead.

\_ 5.7.2.19 \_

int
HYPRE\_BoomerAMGSetRelaxWeight (HYPRE\_Solver solver, double
\*relax\_weight)

(Optional) Defines the relaxation weight for smoothed Jacobi and hybrid SOR.

Note: This routine will be phased out!!!! Use HYPRE\_BoomerAMGSetRelaxWt or HYPRE\_BoomerAMGSetLevelRelaxWt instead.

int **HYPRE\_BoomerAMGSetRelaxWt** (HYPRE\_Solver solver, double relax\_weight)

(Optional) Defines the relaxation weight for smoothed Jacobi and hybrid SOR on all levels.

relax_weight > 0	this assigns the given relaxation weight on all levels
$relax_weight = 0$	the weight is determined on each level with the estimate $\frac{3}{4\ D^{-1/2}AD^{-1/2}\ }$ ,
	where $D$ is the diagonal matrix of $A$ (this should only be used with Jacobi)
$relax_weight = -k$	the relaxation weight is determined with at most k CG steps on each level
	this should only be used for symmetric positive definite problems)

The default is 1.

#### 5.7.2.21

int HYPRE\_BoomerAMGSetLevelRelaxWt (HYPRE\_Solver solver, double relax\_weight, int level)

(Optional) Defines the relaxation weight for smoothed Jacobi and hybrid SOR on the user defined level. Note that the finest level is denoted 0, the next coarser level 1, etc. For nonpositive relax\_weight, the parameter is determined on the given level as described for HYPRE\_BoomerAMGSetRelaxWt. The default is 1.

### 5.7.2.22

int HYPRE\_BoomerAMGSetOmega (HYPRE\_Solver solver, double \*omega)

(Optional) Defines the outer relaxation weight for hybrid SOR. Note: This routine will be phased out!!!! Use HYPRE\_BoomerAMGSetOuterWt or HYPRE\_BoomerAMGSetLevelOuterWt instead.

int HYPRE\_BoomerAMGSetOuterWt (HYPRE\_Solver solver, double omega)

(Optional) Defines the outer relaxation weight for hybrid SOR and SSOR on all levels.

omega > 0	this assigns the same outer relaxation weight omega on each level
omega = -k	an outer relaxation weight is determined with at most k CG steps on each level
	(this only makes sense for symmetric positive definite problems and smoothers, e.g. SSOR)

The default is 1.

\_ 5.7.2.24 \_

int

**HYPRE\_BoomerAMGSetLevelOuterWt** (HYPRE\_Solver solver, double omega, int level)

(Optional) Defines the outer relaxation weight for hybrid SOR or SSOR on the user defined level. Note that the finest level is denoted 0, the next coarser level 1, etc. For nonpositive omega, the parameter is determined on the given level as described for HYPRE\_BoomerAMGSetOuterWt. The default is 1.

5.7.2.25

int
HYPRE\_BoomerAMGSetTruncFactor (HYPRE\_Solver solver, double trunc\_factor)

(Optional) Defines a truncation factor for the interpolation. The default is 0.

**HYPRE\_BoomerAMGSetSCommPkgSwitch** (HYPRE\_Solver solver, double S\_commpkg\_switch)

(Optional) Defines the largest strength threshold for which the strength matrix S uses the communication package of the operator A. If the strength threshold is larger than this values, a communication package is generated for S. This can save memory and decrease the amount of data that needs to be communicated, if S is substantially sparser than A. The default is 0.05.

#### \_ 5.7.2.27 \_

int

**HYPRE\_BoomerAMGSetSmoothType** (HYPRE\_Solver solver, int smooth\_type)

(Optional) Enables the use of more complex smoothers. The following options exist for smooth\_type:

value	smoother	routines needed to set smoother parameters
6	Schwarz smoothers	HYPRE_BoomerAMGSetDomainType, HYPRE_BoomerAMGSetOverlap,
		HYPRE_BoomerAMGSetVariant, HYPRE_BoomerAMGSetSchwarzRlxWeigh
7	Pilut	HYPRE_BoomerAMGSetDropTol, HYPRE_BoomerAMGSetMaxNzPerRow
8	ParaSails	HYPRE_BoomerAMGSetSym, HYPRE_BoomerAMGSetLevel,
		HYPRE_BoomerAMGSetFilter, HYPRE_BoomerAMGSetThreshold
9	Euclid	HYPRE_BoomerAMGSetEuclidFile
16	CG preconditioned with Schwarz	see routines under 6
17	CG preconditioned with Pilut	see routines under 7
18	CG preconditioned with ParaSails	see routines under 8
19	CG preconditioned with Euclid	see routines under 9

The default is 6. Also, if no smoother parameters are set via the routines mentioned in the table above, default values are used.

## \_ 5.7.2.28 \_

int

**HYPRE\_BoomerAMGSetSmoothNumLevels** (HYPRE\_Solver solver, int smooth\_num\_levels)

(Optional) Sets the number of levels for more complex smoothers. The smoothers, as defined by HYPRE\_BoomerAMGSetSmoothType, will be used on level 0 (the finest level) through level smooth\_num\_levels-1. The default is 0, i.e. no complex smoothers are used.

5.7.2.29

int

**HYPRE\_BoomerAMGSetSmoothNumSweeps** (HYPRE\_Solver solver, int smooth\_num\_sweeps)

(Optional) Sets the number of sweeps for more complex smoothers. The default is 1.

\_ 5.7.2.30 \_\_\_\_\_

int HYPRE\_BoomerAMGSetLogging (HYPRE\_Solver solver, int logging)

(Optional) Requests additional computations for diagnostic and similar data to be logged by the user. Default to 0 for do nothing. The latest residual will be available if logging > 1.

-5.7.2.31

ınt

**HYPRE\_BoomerAMGSetNumFunctions** (HYPRE\_Solver solver, int num\_functions)

(Optional) Sets the size of the system of PDEs, if using the systems version. The default is 1.

int HYPRE\_BoomerAMGSetNodal (HYPRE\_Solver solver, int nodal)

(Optional) Sets whether to use the nodal systems version. The default is 0.

\_ 5.7.2.33 \_

int HYPRE\_BoomerAMGSetDofFunc (HYPRE\_Solver solver, int \*dof\_func)

(Optional) Sets the mapping that assigns the function to each variable, if using the systems version. If no assignment is made and the number of functions is k > 1, the mapping generated is (0,1,...,k-1,0,1,...,k-1,...).

5.7.2.34

int HYPRE\_BoomerAMGSetVariant (HYPRE\_Solver solver, int variant)

(Optional) Defines which variant of the Schwarz method is used. The following options exist for variant:

- 0 hybrid multiplicative Schwarz method (no overlap across processor boundaries)
- 1 | hybrid additive Schwarz method (no overlap across processor boundaries)
- 2 | additive Schwarz method
- 3 hybrid multiplicative Schwarz method (with overlap across processor boundaries)

The default is 0.

5.7.2.35

int HYPRE\_BoomerAMGSetOverlap (HYPRE\_Solver solver, int overlap)

(Optional) Defines the overlap for the Schwarz method. The following options exist for overlap:

- 0 no overlap
- 1 minimal overlap (default)
- 2 overlap generated by including all neighbors of domain boundaries

 $\_$  5.7.2.36  $\_$ 

int

**HYPRE\_BoomerAMGSetDomainType** (HYPRE\_Solver solver, int domain\_type)

(Optional) Defines the type of domain used for the Schwarz method. The following options exist for domain\_type:

- 0 each point is a domain
- each node is a domain (only of interest in "systems" AMG)
- 2 each domain is generated by agglomeration (default)

5.7.2.37

int HYPRE\_BoomerAMGSetSym (HYPRE\_Solver solver, int sym)

(Optional) Defines symmetry for ParaSAILS. For further explanation see description of ParaSAILS.

\_ 5.7.2.38 \_

int HYPRE\_BoomerAMGSetLevel (HYPRE\_Solver solver, int level)

(Optional) Defines number of levels for ParaSAILS. For further explanation see description of ParaSAILS.

HYPRE\_BoomerAMGSetThreshold (HYPRE\_Solver solver, double threshold)

(Optional) Defines threshold for ParaSAILS. For further explanation see description of ParaSAILS.

\_ 5.7.2.40 \_\_\_

int HYPRE\_BoomerAMGSetFilter (HYPRE\_Solver solver, double filter)

(Optional) Defines filter for ParaSAILS. For further explanation see description of ParaSAILS.

5.7.2.41

int HYPRE\_BoomerAMGSetDropTol (HYPRE\_Solver solver, double drop\_tol)

(Optional) Defines drop tolerance for PILUT. For further explanation see description of PILUT.

\_ 5.7.2.42 \_\_

int

**HYPRE\_BoomerAMGSetMaxNzPerRow** (HYPRE\_Solver solver, int max\_nz\_per\_row)

(Optional) Defines maximal number of nonzeros for PILUT. For further explanation see description of PILUT.

HYPRE\_BoomerAMGSetEuclidFile (HYPRE\_Solver solver, char \*euclidfile)

(Optional) Defines name of an input file for Euclid parameters. For further explanation see description of Euclid.

\_ 5.7.2.44 \_

int HYPRE\_BoomerAMGSetGSMG (HYPRE\_Solver solver, int gsmg)

(Optional) Specifies the use of GSMG - geometrically smooth coarsening and interpolation. Currently any nonzero value for gsmg will lead to the use of GSMG. The default is 0, i.e. (GSMG is not used)

\_ 5.7.3 \_

## ParCSR ParaSails Preconditioner

### Names

int

HYPRE\_ParaSailsCreate (MPI\_Comm comm, HYPRE\_Solver \*solver)

Create a ParaSails preconditioner

int

HYPRE\_ParaSailsDestroy (HYPRE\_Solver solver)

Destroy a ParaSails preconditioner

5.7.3.1 int

HYPRE\_ParaSailsSetup (HYPRE\_Solver solver, HYPRE\_ParCSRMatrix A, HYPRE\_ParVector b, HYPRE\_ParVector x)

5.7.3.2 int

HYPRE\_ParaSailsSolve (HYPRE\_Solver solver, HYPRE\_ParCSRMatrix A, HYPRE\_ParVector b, HYPRE\_ParVector x)

5.7.3.3 int

81

	HYPRE_ParaSailsSetParams (HYPRE_Solver solver, double thresh,	
	int nlevels)	
	Set the threshold and levels parameter for the ParaSails preconditioner	81
5.7.3.4	int	
	HYPRE_ParaSailsSetFilter (HYPRE_Solver solver, double filter)	
	Set the filter parameter for the ParaSails preconditioner	81
5.7.3.5	int	
	HYPRE_ParaSailsSetSym (HYPRE_Solver solver, int sym)	
	Set the symmetry parameter for the ParaSails preconditioner	82
5.7.3.6	$\operatorname{int}$	
	HYPRE_ParaSailsSetLoadbal (HYPRE_Solver solver, double loadbal)	
	Set the load balance parameter for the ParaSails preconditioner	82
5.7.3.7	$\operatorname{int}$	
	HYPRE_ParaSailsSetReuse (HYPRE_Solver solver, int reuse)	
	Set the pattern reuse parameter for the ParaSails preconditioner	83
5.7.3.8	int	
	HYPRE_ParaSailsSetLogging (HYPRE_Solver solver, int logging)	
	Set the logging parameter for the ParaSails preconditioner	83
5.7.3.9	$\operatorname{int}$	
	HYPRE_ParaSailsBuildIJMatrix (HYPRE_Solver solver,	
	HYPRE_IJMatrix *pij_A)	
	Build IJ Matrix of the sparse approximate inverse (factor)	83

Parallel sparse approximate inverse preconditioner for the ParCSR matrix format.

## \_ 5.7.3.1 \_

int
HYPRE\_ParaSailsSetup (HYPRE\_Solver solver, HYPRE\_ParCSRMatrix A,
HYPRE\_ParVector b, HYPRE\_ParVector x)

Set up the ParaSails preconditioner. This function should be passed to the iterative solver SetPrecond function.

Parameters:

solver — [IN] Preconditioner object to set up.

A — [IN] ParCSR matrix used to construct the preconditioner.

b — Ignored by this function.

x — Ignored by this function.

**HYPRE\_ParaSailsSolve** (HYPRE\_Solver solver, HYPRE\_ParCSRMatrix A, HYPRE\_ParVector b, HYPRE\_ParVector x)

Apply the ParaSails preconditioner. This function should be passed to the iterative solver SetPrecond function.

Parameters:

solver — [IN] Preconditioner object to apply.

 $\label{eq:local_problem} \begin{array}{l} \mathtt{A} \longrightarrow \mathrm{Ignored} \ \mathrm{by} \ \mathrm{this} \ \mathrm{function}. \\ \mathtt{b} \longrightarrow [\mathrm{IN}] \ \mathrm{Vector} \ \mathrm{to} \ \mathrm{precondition}. \\ \mathtt{x} \longrightarrow [\mathrm{OUT}] \ \mathrm{Preconditioned} \ \mathrm{vector}. \end{array}$ 

\_ 5.7.3.3 \_

int

HYPRE\_ParaSailsSetParams (HYPRE\_Solver solver, double thresh, int nlevels)

Set the threshold and levels parameter for the ParaSails preconditioner. The accuracy and cost of ParaSails are parameterized by these two parameters. Lower values of the threshold parameter and higher values of levels parameter lead to more accurate, but more expensive preconditioners.

Parameters:

solver — [IN] Preconditioner object for which to set parameters. thresh — [IN] Value of threshold parameter,  $0 \le \text{thresh} \le 1$ . The default value is 0.1. nlevels — [IN] Value of levels parameter,  $0 \le \text{nlevels}$ . The default value is 1.

5.7.3.4

int HYPRE\_ParaSailsSetFilter (HYPRE\_Solver solver, double filter)

Set the filter parameter for the ParaSails preconditioner.

#### Parameters:

solver — [IN] Preconditioner object for which to set filter parameter. filter — [IN] Value of filter parameter. The filter parameter is used to drop small nonzeros in the preconditioner, to reduce the cost of applying the preconditioner. Values from 0.05 to 0.1 are recommended. The default value is 0.1.

5.7.3.5

int HYPRE\_ParaSailsSetSym (HYPRE\_Solver solver, int sym)

Set the symmetry parameter for the ParaSails preconditioner.

## Parameters:

solver — [IN] Preconditioner object for which to set symmetry parameter.

sym — [IN] Value of the symmetry parameter:

value	meaning
0	nonsymmetric and/or indefinite problem, and nonsymmetric preconditioner
1	SPD problem, and SPD (factored) preconditioner
2	nonsymmetric, definite problem, and SPD (factored) preconditioner

5.7.3.6

int HYPRE\_ParaSailsSetLoadbal (HYPRE\_Solver solver, double loadbal)

Set the load balance parameter for the ParaSails preconditioner.

Parameters:

solver — [IN] Preconditioner object for which to set the load balance parameter.

loadbal — [IN] Value of the load balance parameter,  $0 \le loadbal \le 1$ . A zero value indicates that no load balance is attempted; a value of unity indicates that perfect load balance will be attempted. The recommended value is 0.9 to balance the overhead of data exchanges for load balancing. No load balancing is needed if the preconditioner is very sparse and fast to construct. The default value when this parameter is not set is 0.

int HYPRE\_ParaSailsSetReuse (HYPRE\_Solver solver, int reuse)

Set the pattern reuse parameter for the ParaSails preconditioner.

## Parameters:

 ${\tt solver}$  — [IN] Preconditioner object for which to set the pattern reuse parameter.

reuse — [IN] Value of the pattern reuse parameter. A nonzero value indicates that the pattern of the preconditioner should be reused for subsequent constructions of the preconditioner. A zero value indicates that the preconditioner should be constructed from scratch. The default value when this parameter is not set is 0.

#### \_ 5.7.3.8 \_

int HYPRE\_ParaSailsSetLogging (HYPRE\_Solver solver, int logging)

Set the logging parameter for the ParaSails preconditioner.

## Parameters:

solver — [IN] Preconditioner object for which to set the logging parameter. logging — [IN] Value of the logging parameter. A nonzero value sends statistics of the setup procedure to stdout. The default value when this parameter is not set is 0.

#### 5.7.3.9

int **HYPRE\_ParaSailsBuildIJMatrix** (HYPRE\_Solver solver, HYPRE\_IJMatrix \*pij\_A)

Build IJ Matrix of the sparse approximate inverse (factor). This function explicitly creates the IJ Matrix corresponding to the sparse approximate inverse or the inverse factor. Example: HYPRE\_IJMatrix ij\_A; HYPRE\_ParaSailsBuildIJMatrix(solver, &ij\_A);

\_ 5.7.4 \_

## ParCSR Euclid Preconditioner

Names		
	int	
	HYPRE_EuclidCreate (MPI_Comm comm, HYPRE_Solver *solver)  Create a Euclid object	
	$\operatorname{int}$	
	HYPRE_EuclidDestroy (HYPRE_Solver solver)  Destroy a Euclid object	
5.7.4.1	$\operatorname{int}$	
	HYPRE_EuclidSetup (HYPRE_Solver solver, HYPRE_ParCSRMatrix A, HYPRE_ParVector b, HYPRE_ParVector x)	
	Set up the Euclid preconditioner	85
5.7.4.2	int	
-	HYPRE_EuclidSolve (HYPRE_Solver solver, HYPRE_ParCSRMatrix A, HYPRE_ParVector b, HYPRE_ParVector x)	
	Apply the Euclid preconditioner	85
5.7.4.3	$\operatorname{int}$	
	HYPRE_EuclidSetParams (HYPRE_Solver solver, int argc, char *argv[])  Insert (name, value) pairs in Euclid's options database by passing Euclid  the common divisor (on one argue of strings)	85
	the command line (or an array of strings)	00
5.7.4.4	int	
	HYPRE_EuclidSetParamsFromFile (HYPRE_Solver solver, char *filename)  Insert (name, value) pairs in Euclid's options database	86

## MPI Parallel ILU preconditioner

## Options summary:

Option	$\mathbf{Default}$	Synopsis
-level	1	$\mathrm{ILU}(k)$ factorization level
-bj	0 (false)	Use Block Jacobi ILU instead of PILU
-eu_stats	0 (false)	Print internal timing and statistics
-eu_mem	0 (false)	Print internal memory usage

int **HYPRE\_EuclidSetup** (HYPRE\_Solver solver, HYPRE\_ParCSRMatrix A,
HYPRE\_ParVector b, HYPRE\_ParVector x)

Set up the Euclid preconditioner. This function should be passed to the iterative solver SetPrecond function.

Parameters: solver — [IN] Preconditioner object to set up.

A — [IN] ParCSR matrix used to construct the preconditioner.

b — Ignored by this function.x — Ignored by this function.

\_ 5.7.4.2 \_

int **HYPRE\_EuclidSolve** (HYPRE\_Solver solver, HYPRE\_ParCSRMatrix A,
HYPRE\_ParVector b, HYPRE\_ParVector x)

Apply the Euclid preconditioner. This function should be passed to the iterative solver SetPrecond function.

Parameters: solver — [IN] Preconditioner object to apply.

A — Ignored by this function.
b — [IN] Vector to precondition.

x — [OUT] Preconditioned vector.

5.7.4.3

int HYPRE\_EuclidSetParams (HYPRE\_Solver solver, int argc, char \*argv[])

Insert (name, value) pairs in Euclid's options database by passing Euclid the command line (or an array of strings). All Euclid options (e.g, level, drop-tolerance) are stored in this database. If a (name, value) pair already exists, this call updates the value. See also: HYPRE\_EuclidSetParamsFromFile.

Parameters:

argc — [IN] Length of argv array argv — [IN] Array of strings

\_ 5.7.4.4 \_

int

HYPRE\_EuclidSetParamsFromFile (HYPRE\_Solver solver, char \*filename)

Insert (name, value) pairs in Euclid's options database. Each line of the file should either begin with a "#," indicating a comment line, or contain a (name value) pair, e.g:

>cat optionsFile

#sample runtime parameter file

- -blockJacobi 3
- -matFile /home/hysom/myfile.euclid
- -doSomething true
- $-xx\_coeff -1.0$

See also: HYPRE\_EuclidSetParams.

Parameters:

filename[IN] — Pathname/filename to read

5.7.5

## ParCSR Pilut Preconditioner

Names

int

HYPRE\_ParCSRPilutCreate (MPI\_Comm comm, HYPRE\_Solver \*solver)

Create a preconditioner object

int

HYPRE\_ParCSRPilutDestroy (HYPRE\_Solver solver)

Destroy a preconditioner object

int

HYPRE\_ParCSRPilutSetup (HYPRE\_Solver solver,

HYPRE\_ParCSRMatrix A,

 ${\tt HYPRE\_ParVector}\ b,\ {\tt HYPRE\_ParVector}\ x)$ 

int

 ${\bf HYPRE\_ParCSRPilutSolve} \ ({\tt HYPRE\_Solver} \ {\tt solver},$ 

HYPRE\_ParCSRMatrix A,

HYPRE\_ParVector b, HYPRE\_ParVector x)

Precondition the system

int

HYPRE\_ParCSRPilutSetMaxIter (HYPRE\_Solver solver, int max\_iter)

(Optional) Set maximum number of iterations

 $_{
m int}$ 

 ${\bf HYPRE\_ParCSRPilutSetDropTolerance}~({\tt HYPRE\_Solver}~solver,~double~tol)$ 

(Optional)

int

 $\mathbf{HYPRE\_ParCSRPilutSetFactorRowSize} \; (\mathbf{HYPRE\_Solver} \; \text{solver}, \; \; \mathbf{int} \; \mathbf{size})$ 

(Optional)

5.7.6

## ParCSR PCG Solver

#### Names

int

HYPRE\_ParCSRPCGCreate (MPI\_Comm comm, HYPRE\_Solver \*solver)

Create a solver object

int

HYPRE\_ParCSRPCGDestroy (HYPRE\_Solver solver)

Destroy a solver object

int

HYPRE\_ParCSRPCGSetup (HYPRE\_Solver solver,

HYPRE\_ParCSRMatrix A,

HYPRE\_ParVector b, HYPRE\_ParVector x)

int

HYPRE\_ParCSRPCGSolve (HYPRE\_Solver solver,

HYPRE\_ParCSRMatrix A,

HYPRE\_ParVector b, HYPRE\_ParVector x)

Solve the system

int

HYPRE\_ParCSRPCGSetTol (HYPRE\_Solver solver, double tol)

(Optional) Set the convergence tolerance

int

HYPRE\_ParCSRPCGSetMaxIter (HYPRE\_Solver solver, int max\_iter)

(Optional) Set maximum number of iterations

int

HYPRE\_ParCSRPCGSetTwoNorm (HYPRE\_Solver solver, int two\_norm)

(Optional) Use the two-norm in stopping criteria

int

HYPRE\_ParCSRPCGSetRelChange (HYPRE\_Solver solver, int rel\_change)
(Optional) Additionally require that the relative difference in successive it-

(Optional) Additionally require that the relative difference erates be small

int

HYPRE\_ParCSRPCGSetPrecond (HYPRE\_Solver solver,

HYPRE\_PtrToParSolverFcn precond, HYPRE\_PtrToParSolverFcn precond\_setup,

HYPRE\_Solver precond\_solver)

(Optional) Set the preconditioner to use

int

HYPRE\_ParCSRPCGGetPrecond (HYPRE\_Solver solver,

HYPRE\_Solver \*precond\_data)

int

HYPRE\_ParCSRPCGSetLogging (HYPRE\_Solver solver, int logging)

(Optional) Set the amount of logging to do

int

 $\label{eq:hypre_parcsrpcgsetPrintLevel} \textbf{HYPRE\_Solver solver}, \ \ \text{int print\_level})$ 

(Optional) Set the print level

int

 ${\bf HYPRE\_ParCSRPCGGetNumIterations}~({\tt HYPRE\_Solver}~solver,$ 

int \*num\_iterations)

Return the number of iterations taken

int

 ${\bf HYPRE\_ParCSRPCGGetFinalRelativeResidualNorm}~({\tt HYPRE\_Solver}$ 

solver,

double \*norm)

Return the norm of the final relative residual

int

HYPRE\_ParCSRDiagScaleSetup (HYPRE\_Solver solver,

HYPRE\_ParCSRMatrix A, HYPRE\_ParVector y, HYPRE\_ParVector x)

Setup routine for diagonal preconditioning

int

HYPRE\_ParCSRDiagScale (HYPRE\_Solver solver,

HYPRE\_ParCSRMatrix HA,

HYPRE\_ParVector Hy, HYPRE\_ParVector Hx)

Solve routine for diagonal preconditioning

5.7.7

ParCSR GMRES Solver

Names

## HYPRE\_ParCSRGMRESCreate (MPI\_Comm comm, HYPRE\_Solver \*solver)

Create a solver object

int

## HYPRE\_ParCSRGMRESDestroy (HYPRE\_Solver solver)

Destroy a solver object

int

HYPRE\_ParCSRGMRESSetup (HYPRE\_Solver solver,

HYPRE\_ParCSRMatrix A, HYPRE\_ParVector b, HYPRE\_ParVector x)

int

HYPRE\_ParCSRGMRESSolve (HYPRE\_Solver solver,

HYPRE\_ParCSRMatrix A,

HYPRE\_ParVector b, HYPRE\_ParVector x)

Solve the system

int

 $\label{eq:hypre_parcsr} \textbf{HYPRE\_Solver solver}, \ \ \text{int } \ k\_\text{dim})$ 

(Optional) Set the maximum size of the Krylov space

int

HYPRE\_ParCSRGMRESSetTol (HYPRE\_Solver solver, double tol)

(Optional) Set the convergence tolerance

int

HYPRE\_ParCSRGMRESSetMaxIter (HYPRE\_Solver solver, int max\_iter)

 $(Optional) \ Set \ maximum \ number \ of \ iterations$ 

int

HYPRE\_ParCSRGMRESSetPrecond (HYPRE\_Solver solver,

HYPRE\_PtrToParSolverFcn precond, HYPRE\_PtrToParSolverFcn precond\_setup, HYPRE\_Solver precond\_solver)

(Optional) Set the preconditioner to use

int

HYPRE\_ParCSRGMRESGetPrecond (HYPRE\_Solver solver,

HYPRE\_Solver \*precond\_data)

int

HYPRE\_ParCSRGMRESSetLogging (HYPRE\_Solver solver, int logging)

(Optional) Set the amount of logging to do

int

HYPRE\_ParCSRGMRESSetPrintLevel (HYPRE\_Solver solver,

int print\_level)

(Optional) Set print level

int

HYPRE\_ParCSRGMRESGetNumIterations (HYPRE\_Solver solver,

int \*num\_iterations)

Return the number of iterations taken

int

# $\begin{tabular}{ll} HYPRE\_ParCSRGMRESGetFinalRelativeResidualNorm~(HYPRE\_Solver,\\ solver,\\ double~*norm) \end{tabular}$

 $Return\ the\ norm\ of\ the\ final\ relative\ residual$ 

## Class Graph