

SSV COMPUTATION [FOR A FIXED FREQ]

$$N(s) = \begin{bmatrix} \frac{1}{s+1} & \frac{1}{s+2} \\ \frac{1}{s+3} & \frac{1}{s+5} \end{bmatrix} \rightarrow N(j\omega) = \begin{bmatrix} \frac{1}{j\omega+1} & \frac{1}{j\omega+2} \\ \frac{1}{j\omega+3} & \frac{1}{j\omega+5} \end{bmatrix} \rightarrow N(j\omega_x) = \begin{bmatrix} \frac{1}{j\omega_x+1} & \frac{1}{j\omega_x+2} \\ \frac{1}{j\omega_x+3} & \frac{1}{j\omega_x+5} \end{bmatrix}$$

$$N(j1) = \begin{bmatrix} \frac{1}{j1+1} & \frac{1}{j1+2} \\ \frac{1}{j1+3} & \frac{1}{j1+5} \end{bmatrix}$$

| MATLAB code | Code OUTPUT |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------|
| <pre>clear all;close all;clc; %% N_s=[tf([1],[1,1]),tf([1],[1,2]); tf([1],[1,3]),tf([1],[1,5])]; %% compute the matrix for a given freq Njw1=evalfr(N_s,1*i)</pre> | <pre>>> Njw1=evalfr(N_s,1*i) Njw1 = 0.5000 - 0.5000i 0.4000 - 0.2000i 0.3000 - 0.1000i 0.1923 - 0.0385i</pre> |

CASE 1: FULL DELTA [UNSTRUCTURED UNCERTAINTY]

$$\Delta = \{\Delta \in \mathbb{C}^{n \times n}\}$$

$$\mathcal{D} = \{D: D\Delta = \Delta D, \forall \Delta \in \Delta\}$$

$$\mathcal{D} = \{dI_n: d \in \mathbb{R}, d > 0\}$$

$$\mu_{\Delta}(M) = \mu_{\Delta}(DMD^{-1})$$

$$\mu_{\Delta}(M) \leq \inf_{D \in \mathcal{D}} \bar{\sigma}(DMD^{-1})$$

Since, there is a suitable parameterization for $\overline{D \in \mathcal{D}}$, the problem can be expressed more specifically as,

$$\inf_{D \in \mathcal{D}} \bar{\sigma}(DMD^{-1}) = \inf_{D \in \mathcal{D}} \bar{\sigma}(dI_2 M d^{-1} I_2)$$

Matlab code

```
%% ADD YALMIP AND SDPT3 LIBRARIES
%% CASE 1: Full Delta Set ---> single d --> d*eye(n), d in REAL
N_s=[tf([1],[1,1]),tf([1],[1,2]);tf([1],[1,3]),tf([1],[1,5])];
%% compute the matrix for a given freq
Njw1=evalfr(N_s,1*i)
%% CASE 1: Full Delta Set ---> single d --> d*eye(n), d in REAL
% BISECTION PROBLEM
g2=sdpvar(1,1,'symmetric');
eps1=1e-5;

D1=sdpvar(1,1,'symmetric');
% D1=sdpvar(2,2,'hermitian','complex');

% X=blkdiag(D1);
X=[D1*eye(2)];

F=[];
F=[F;Njw1'*X*Njw1-g2*X<=-eps1*eye(2)];
F=[F;eps1<=D1]; % D1 is hermitian, complex,pos-def matrix

% ops = sdpsettings('solver','sdpt3');
ops = sdpsettings('solver','bisection','bisection.solver','sdpt3');
sol = bisection(F,[g2],ops);
sol.info

X=value(X)
g2=value(g2)

gamma=sqrt(g2)
YALMIP_SSV=gamma;
%%
rho_N=max(abs(eig(Njw1))); % spectral radius of Njw1
sigma_max_N=max(svd(Njw1)); % sigma-max of Njw1

% COMPUTE THE SSV USING MATLAB-MUSSV FCN
% bounds = mussv(N,BlockStructure)
[ bounds,muinfo ] = mussv(Njw1,[2,2]);
MATLAB_MUSSV=bounds(2);
clc;
fprintf("YALMIP_SSV \t rho_N \t sigma_max_N \t MATLAB_MUSSV\n");
fprintf("%6.4f \t %6.4f \t %6.4f \t %6.4f\n",YALMIP_SSV,rho_N,sigma_max_N,MATLAB_MUSSV);
```

Code OUTPUT

| YALMIP_SSV | rho_N | sigma_max_N | MATLAB_MUSSV |
|------------|--------|-------------|--------------|
| 0.9152 | 0.8680 | 0.9152 | 0.9152 |

CASE 2: repeating-scalar-delta [STRUCTURED UNCERTAINTY]

$$\Delta = \{\delta I_n : \delta \in \mathbb{C}\}$$

$$\mathcal{D} = \{D : D\Delta = \Delta D, \forall \Delta \in \Delta\}$$

$$\mathcal{D} = \{D : D \in \mathbb{C}^{n \times n}, D = D^H > 0\}$$

$$\mu_{\Delta}(M) = \mu_{\Delta}(DMD^{-1})$$

$$\mu_{\Delta}(M) \leq \inf_{D \in \mathcal{D}} \bar{\sigma}(DMD^{-1})$$

Since, there is a suitable parameterization for $\boxed{D \in \mathcal{D}}$, the problem can be expressed more specifically as,

$$\mathcal{D} = \left\{ D = \begin{bmatrix} d_1 & d_3 + jd_4 \\ d_3 - jd_4 & d_2 \end{bmatrix} : \boxed{d_1, \dots, d_4 \in \mathbb{R}}, \boxed{d_1, \dots, d_4 > 0} \right\}$$

$$\inf_{D \in \mathcal{D}} \bar{\sigma}(DMD^{-1}) = \inf_{d_1, \dots, d_4 > 0} \bar{\sigma} \left(\begin{bmatrix} d_1 & d_3 + jd_4 \\ d_3 - jd_4 & d_2 \end{bmatrix} M \begin{bmatrix} d_1 & d_3 + jd_4 \\ d_3 - jd_4 & d_2 \end{bmatrix}^{-1} \right)$$

$$\begin{array}{l} \inf_{\substack{D \in \mathcal{D} \\ \gamma \in \mathbb{R}^+}} \boxed{\gamma} \\ \text{s. t. } \boxed{\bar{\sigma}(DMD^{-1}) < \gamma} \end{array}$$

| FOR SQUARE CASE | FOR RECTANGULAR CASE |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $\begin{aligned} &\bar{\sigma}(DMD^{-1}) < \gamma \\ &\ DMD^{-1}\ _2 < \gamma \\ &\ DMD^{-1}\ _2^2 < \gamma^2 \\ &\lambda_{\max}([DMD^{-1}]^T [DMD^{-1}]) < \gamma^2 \\ &[DMD^{-1}]^T [DMD^{-1}] < \gamma^2 I \\ &[D^{-T} M^T D^T] [DMD^{-1}] < \gamma^2 I \\ &D^{-T} M^T [D^T D] MD^{-1} < \gamma^2 I \\ &D^{-T} M^T [D^T D] M < \gamma^2 ID \\ &M^T [D^T D] M < D^T \gamma^2 ID \\ &M^T [D^T D] M < \gamma^2 [D^T D] \\ &X := D \\ &M^T X M < \gamma^2 X \end{aligned}$ <div style="border: 1px solid black; padding: 5px; margin-top: 10px;"> $\begin{array}{l} \inf_{\substack{X \in \mathcal{X} \\ \gamma \in \mathbb{R}^+}} \boxed{\gamma} \\ \text{s. t. } \boxed{M^T X M < \gamma^2 X} \end{array}$ </div> | $\begin{aligned} &\bar{\sigma}(D_L M D_R^{-1}) < \gamma \\ &\ D_L M D_R^{-1}\ _2 < \gamma \\ &\ D_L M D_R^{-1}\ _2^2 < \gamma^2 \\ &\lambda_{\max}([D_L M D_R^{-1}]^T [D_L M D_R^{-1}]) < \gamma^2 \\ &[D_L M D_R^{-1}]^T [D_L M D_R^{-1}] < \gamma^2 I \\ &[D_R^{-T} M^T D_L^T] [D_L M D_R^{-1}] < \gamma^2 I \\ &D_R^{-T} M^T [D_L^T D_L] M D_R^{-1} < \gamma^2 I \\ &D_R^{-T} M^T [D_L^T D_L] M < \gamma^2 ID_R \\ &M^T [D_L^T D_L] M < D_R^T \gamma^2 ID_R \\ &M^T [D_L^T D_L] M < \gamma^2 [D_R^T D_R] \\ &X_L := [D_L^T D_L], X_R := [D_R^T D_R] \\ &M^T X_L M < \gamma^2 X_R \end{aligned}$ <div style="border: 1px solid black; padding: 5px; margin-top: 10px;"> $\begin{array}{l} \inf_{\substack{(X_L, X_R) \in \mathcal{X} \\ \gamma \in \mathbb{R}^+}} \boxed{\gamma} \\ \text{s. t. } \boxed{M^T X_L M < \gamma^2 X_R} \end{array}$ </div> |

Let us determine the structure of X

$$X = D^H D = [D]^T [D] = [D^H D] \rightarrow [D], \boxed{D \in \mathbb{R}, D = D^H > 0}$$

Matlab code

```

%% ADD YALMIP AND SDPT3 LIBRARIES
%% CASE 2: Structured Delta Set [delta*eye(n)] ----> FULL D,hermitian(like symmetric),complex
N_s=[tf([1],[1,1]),tf([1],[1,2]);tf([1],[1,3]),tf([1],[1,5])];
%% compute the matrix for a given freq
Njw1=evalfr(N_s,1*i)
%% CASE 2: Structured Delta Set [delta*eye(n)] ----> FULL D,hermitian(like symmetric),complex
% BISECTION PROBLEM
g2=sdpvar(1,1,'symmetric');
eps1=1e-5;

% D1=sdpvar(1,1,'symmetric');
D1=sdpvar(2,2,'hermitian','complex');

% X=blkdiag(D1,D2);
X=[D1];

F=[];
F=[F;Njw1'*X*Njw1-g2*X<=-eps1*eye(2)];
F=[F;eps1*eye(2)<=D1]; % D1 is hermitian, complex,pos-def matrix

% ops = sdpsettings('solver','sdpt3');
ops = sdpsettings('solver','bisection','bisection.solver','sdpt3');
sol = bisection(F,[g2],ops);
sol.info

X=value(X)
g2=value(g2)

gamma=sqrt(g2)
YALMIP_SSV=gamma;
%%
rho_N=max(abs(eig(Njw1))); % spectral radius of Njw1
sigma_max_N=max(svd(Njw1)); % sigma-max of Njw1

% COMPUTE THE SSV USING MATLAB-MUSSV FCN
% bounds = mussv(N,BlockStructure)
[bounds,muinfo] = mussv(Njw1,[2,0]);
MATLAB_MUSSV=bounds(2);
clc;
fprintf("YALMIP_SSV \t rho_N \t sigma_max_N \t MATLAB_MUSSV\n");
fprintf("%6.4f \t\t %6.4f \t %6.4f \t %6.4f\n",YALMIP_SSV,rho_N,sigma_max_N,MATLAB_MUSSV);

```

Code OUTPUT

| YALMIP_SSV | rho_N | sigma_max_N | MATLAB_MUSSV |
|------------|--------|-------------|--------------|
| 0.8680 | 0.8680 | 0.9152 | 0.8680 |

CASE 3: diagonal-delta [STRUCTURED UNCERTAINTY]

$$\mathbf{\Delta} = \{\text{diag}[\delta_1, \delta_2]: \delta_1, \delta_2 \in \mathbb{C}\}$$

$$\mathcal{D} = \{D: D\mathbf{\Delta} = \mathbf{\Delta}D, \forall \mathbf{\Delta} \in \mathbf{\Delta}\}$$

$$\mathcal{D} = \{\text{diag}[d_1, d_2]: \boxed{d_1, d_2 \in \mathbb{R}}, \boxed{d_1, d_2 > 0}\}$$

$$\mu_{\mathbf{\Delta}}(M) = \mu_{\mathbf{\Delta}}(DMD^{-1})$$

$$\mu_{\mathbf{\Delta}}(M) \leq \inf_{D \in \mathcal{D}} \bar{\sigma}(DMD^{-1})$$

Since, there is a suitable parameterization for $\boxed{D \in \mathcal{D}}$, the problem can be expressed more specifically as,

$$\mathcal{D} = \left\{ D = \begin{bmatrix} d_1 & 0 \\ 0 & d_2 \end{bmatrix} : \boxed{d_1, d_2 \in \mathbb{R}}, \boxed{d_1, d_2 > 0} \right\}$$

$$\inf_{D \in \mathcal{D}} \bar{\sigma}(DMD^{-1}) = \inf_{d_1, d_2 > 0} \bar{\sigma} \left(\begin{bmatrix} d_1 & 0 \\ 0 & d_2 \end{bmatrix} M \begin{bmatrix} d_1 & 0 \\ 0 & d_2 \end{bmatrix}^{-1} \right)$$

$$\boxed{\begin{array}{l} \inf_{\substack{D \in \mathcal{D} \\ \gamma \in \mathbb{R}^+}} \quad \boxed{\gamma} \\ \text{s. t.} \quad \boxed{\bar{\sigma}(DMD^{-1}) < \gamma} \end{array}}$$

| FOR SQUARE CASE | FOR RECTANGULAR CASE |
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| $\begin{aligned} &\bar{\sigma}(DMD^{-1}) < \gamma \\ &\ DMD^{-1}\ _2 < \gamma \\ &\ DMD^{-1}\ _2^2 < \gamma^2 \\ &\lambda_{\max}([DMD^{-1}]^T [DMD^{-1}]) < \gamma^2 \\ &[DMD^{-1}]^T [DMD^{-1}] < \gamma^2 I \\ &[D^{-T} M^T D^T] [DMD^{-1}] < \gamma^2 I \\ &D^{-T} M^T [D^T D] MD^{-1} < \gamma^2 I \\ &D^{-T} M^T [D^T D] M < \gamma^2 ID \\ &M^T [D^T D] M < D^T \gamma^2 ID \\ &M^T [D^T D] M < \gamma^2 [D^T D] \\ &X := D \\ &M^T X M < \gamma^2 X \end{aligned}$ $\boxed{\begin{array}{l} \inf_{\substack{X \in \mathcal{X} \\ \gamma \in \mathbb{R}^+}} \quad \boxed{\gamma} \\ \text{s. t.} \quad \boxed{M^T X M < \gamma^2 X} \end{array}}$ | $\begin{aligned} &\bar{\sigma}(D_L M D_R^{-1}) < \gamma \\ &\ D_L M D_R^{-1}\ _2 < \gamma \\ &\ D_L M D_R^{-1}\ _2^2 < \gamma^2 \\ &\lambda_{\max}([D_L M D_R^{-1}]^T [D_L M D_R^{-1}]) < \gamma^2 \\ &[D_L M D_R^{-1}]^T [D_L M D_R^{-1}] < \gamma^2 I \\ &[D_R^{-T} M^T D_L^T] [D_L M D_R^{-1}] < \gamma^2 I \\ &D_R^{-T} M^T [D_L^T D_L] M D_R^{-1} < \gamma^2 I \\ &D_R^{-T} M^T [D_L^T D_L] M < \gamma^2 ID_R \\ &M^T [D_L^T D_L] M < D_R^T \gamma^2 ID_R \\ &M^T [D_L^T D_L] M < \gamma^2 [D_R^T D_R] \\ &X_L := [D_L^T D_L], X_R := [D_R^T D_R] \\ &M^T X_L M < \gamma^2 X_R \end{aligned}$ $\boxed{\begin{array}{l} \inf_{\substack{(X_L, X_R) \in \mathcal{X} \\ \gamma \in \mathbb{R}^+}} \quad \boxed{\gamma} \\ \text{s. t.} \quad \boxed{M^T X_L M < \gamma^2 X_R} \end{array}}$ |

Let us determine the structure of X

$$X = D^H D = \begin{bmatrix} d_1 & 0 \\ 0 & d_2 \end{bmatrix}^T \begin{bmatrix} d_1 & 0 \\ 0 & d_2 \end{bmatrix} = \begin{bmatrix} (d_1)^2 & \\ & (d_2)^2 \end{bmatrix} \rightarrow \begin{bmatrix} \mathbf{d}_1 & \\ & \mathbf{d}_2 \end{bmatrix}, \boxed{\begin{array}{l} \mathbf{d}_1 \in \mathbb{R}, \mathbf{d}_1 > 0 \\ \mathbf{d}_2 \in \mathbb{R}, \mathbf{d}_2 > 0 \end{array}}$$

| Matlab code | | | | | |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------|-------|-------------|--------------|-----------------------------------------------------------------------------|
| <pre> %% CASE 3: Structured Delta Set diag[delta1,delta2] ----> diag[d1,d2], d1,d2 REAL N_s=[tf([1],[1,1]),tf([1],[1,2]);tf([1],[1,3]),tf([1],[1,5])]; %% compute the matrix for a given freq Njw1=evalfr(N_s,1*i) %% CASE 3: Structured Delta Set diag[delta1,delta2] ----> diag[d1,d2], d1,d2 REAL % BISECTION PROBLEM g2=sdpvar(1,1,'symmetric'); eps1=1e-5; D1=sdpvar(1,1,'symmetric'); % D1=sdpvar(1,1,'hermitian','complex'); D2=sdpvar(1,1,'symmetric'); % D2=sdpvar(1,1,'hermitian','complex'); % X=blkdiag(D1,D2); X=diag([D1,D2]); F=[]; F=[F;Njw1'*X*Njw1-g2*X<=-eps1*eye(2)]; F=[F;eps1<=D1<=1e3]; F=[F;eps1<=D2<=1e3]; % ops = sdpsettings('solver','sdpt3'); ops = sdpsettings('solver','bisection','bisection.solver','sdpt3'); sol = bisection(F,[g2],ops); sol.info X=value(X) g2=value(g2) gamma=sqrt(g2) YALMIP_SSV=gamma; %% rho_N=max(abs(eig(Njw1))); % spectral radius of Njw1 sigma_max_N=max(svd(Njw1)); % sigma-max of Njw1 % COMPUTE THE SSV USING MATLAB-MUSSV FCN % bounds = mussv(N,BlockStructure) [bounds,muinfo] = mussv(Njw1,[1,1;1,1]); MATLAB_MUSSV=bounds(2); clc; fprintf("YALMIP_SSV \t rho_N \t sigma_max_N \t MATLAB_MUSSV\n"); fprintf("%6.4f \t\t %6.4f \t %6.4f \t %6.4f\n",YALMIP_SSV,rho_N,sigma_max_N,MATLAB_MUSSV); </pre> | | | | | |
| Code OUTPU T | YALMIP_SSV | rho_N | sigma_max_N | MATLAB_MUSSV | <pre> >> X X = 664.8191 0 0 940.4891 </pre> |

CASE 4: MIXED CASE [SQUARE CASE]

SSV COMPUTATION [FOR A FIXED FREQ]

$$N(s) = \begin{bmatrix} \frac{1}{s+1} & \frac{1}{s+2} & \frac{1}{s+3} & \frac{1}{s+3} & \frac{1}{s+4} \\ \frac{1}{s+5} & \frac{1}{s+1} & \frac{1}{s+2} & \frac{1}{s+3} & \frac{1}{s+4} \\ \frac{1}{s+2} & \frac{1}{s+4} & \frac{1}{s+7} & \frac{1}{s+3} & \frac{1}{s+4} \\ \frac{1}{s+2} & \frac{1}{s+4} & \frac{1}{s+7} & \frac{1}{s+3} & \frac{1}{s+4} \\ \frac{1}{s+2} & \frac{1}{s+4} & \frac{1}{s+7} & \frac{1}{s+3} & \frac{1}{s+4} \end{bmatrix} \rightarrow N(j\omega) = \begin{bmatrix} \frac{1}{j\omega+1} & \frac{1}{j\omega+2} & \frac{1}{j\omega+3} & \frac{1}{j\omega+3} & \frac{1}{j\omega+4} \\ \frac{1}{j\omega+5} & \frac{1}{j\omega+1} & \frac{1}{j\omega+2} & \frac{1}{j\omega+3} & \frac{1}{j\omega+4} \\ \frac{1}{j\omega+2} & \frac{1}{j\omega+4} & \frac{1}{j\omega+7} & \frac{1}{j\omega+3} & \frac{1}{j\omega+4} \\ \frac{1}{j\omega+2} & \frac{1}{j\omega+4} & \frac{1}{j\omega+7} & \frac{1}{j\omega+3} & \frac{1}{j\omega+4} \\ \frac{1}{j\omega+2} & \frac{1}{j\omega+4} & \frac{1}{j\omega+7} & \frac{1}{j\omega+3} & \frac{1}{j\omega+4} \end{bmatrix}$$

$$N(j1) = \begin{bmatrix} \frac{1}{j1+1} & \frac{1}{j1+2} & \frac{1}{j1+3} & \frac{1}{j1+3} & \frac{1}{j1+4} \\ \frac{1}{j1+5} & \frac{1}{j1+1} & \frac{1}{j1+2} & \frac{1}{j1+3} & \frac{1}{j1+4} \\ \frac{1}{j1+2} & \frac{1}{j1+4} & \frac{1}{j1+7} & \frac{1}{j1+3} & \frac{1}{j1+4} \\ \frac{1}{j1+2} & \frac{1}{j1+4} & \frac{1}{j1+7} & \frac{1}{j1+3} & \frac{1}{j1+4} \\ \frac{1}{j1+2} & \frac{1}{j1+4} & \frac{1}{j1+7} & \frac{1}{j1+3} & \frac{1}{j1+4} \end{bmatrix}$$

CASE 4: MIXED CASE [SQUARE CASE]

$$\mathbf{\Delta} = \left\{ \begin{bmatrix} \delta_1 I_2 & & \\ & \delta_2 & \\ & & \Delta_3 \end{bmatrix} : \delta_1, \delta_2 \in \mathbb{C}, \Delta_3 \in \mathbb{C}^{2 \times 2} \right\}, \mathcal{D} = \{D : D\mathbf{\Delta} = \mathbf{\Delta}D, \forall \mathbf{\Delta} \in \mathbf{\Delta}\}$$

$$\mathcal{D} = \left\{ \begin{bmatrix} D_1 & & \\ & D_2 & \\ & & D_3 I_2 \end{bmatrix} : \boxed{D_1 \in \mathbb{C}^{2 \times 2}, D_1 = D_1^H > 0}, \boxed{D_2 \in \mathbb{R}, D_2 > 0}, \boxed{D_3 \in \mathbb{R}, D_3 > 0} \right\}$$

$$\mu_{\mathbf{\Delta}}(M) = \mu_{\mathbf{\Delta}}(DMD^{-1}) \rightarrow \mu_{\mathbf{\Delta}}(M) \leq \inf_{D \in \mathcal{D}} \bar{\sigma}(DMD^{-1})$$

Since, there is a suitable parameterization for $\boxed{D \in \mathcal{D}}$, the problem can be expressed more specifically as,

$$\mathcal{D} = \left\{ \begin{bmatrix} d_1 & d_3 + jd_4 \\ d_3 - jd_4 & d_2 \\ & & d_5 \\ & & & d_6 I_2 \end{bmatrix} : \boxed{d_1, \dots, d_6 \in \mathbb{R}}, \boxed{d_1, \dots, d_6 > 0} \right\}$$

$$\inf_{D \in \mathcal{D}} \bar{\sigma}(DMD^{-1}) = \inf_{d_1, \dots, d_6 > 0} \bar{\sigma}(DMD^{-1})$$

$$\begin{array}{c} \inf_{\substack{D \in \mathcal{D} \\ \gamma \in \mathbb{R}^+}} \boxed{\gamma} \\ \text{s. t. } \boxed{\bar{\sigma}(DMD^{-1}) < \gamma} \end{array}$$

| FOR SQUARE CASE | FOR RECTANGULAR CASE |
|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $\bar{\sigma}(DMD^{-1}) < \gamma$ $\ DMD^{-1}\ _2 < \gamma$ $\ DMD^{-1}\ _2^2 < \gamma^2$ $\lambda_{\max}([DMD^{-1}]^T [DMD^{-1}]) < \gamma^2$ $[DMD^{-1}]^T [DMD^{-1}] < \gamma^2 I$ $[D^{-T} M^T D^T] [DMD^{-1}] < \gamma^2 I$ $D^{-T} M^T [D^T D] MD^{-1} < \gamma^2 I$ $D^{-T} M^T [D^T D] M < \gamma^2 ID$ $M^T [D^T D] M < D^T \gamma^2 ID$ $M^T [D^T D] M < \gamma^2 [D^T D]$ $X := D$ $M^T X M < \gamma^2 X$ <div style="border: 1px solid black; padding: 5px; margin-top: 10px;"> $\inf_{\substack{X \in \mathcal{X} \\ \gamma \in \mathbb{R}^+}} \boxed{\gamma}$ $\text{s. t. } \boxed{M^T X M < \gamma^2 X}$ </div> | $\bar{\sigma}(D_L M D_R^{-1}) < \gamma$ $\ D_L M D_R^{-1}\ _2 < \gamma$ $\ D_L M D_R^{-1}\ _2^2 < \gamma^2$ $\lambda_{\max}([D_L M D_R^{-1}]^T [D_L M D_R^{-1}]) < \gamma^2$ $[D_L M D_R^{-1}]^T [D_L M D_R^{-1}] < \gamma^2 I$ $[D_R^{-T} M^T D_L^T] [D_L M D_R^{-1}] < \gamma^2 I$ $D_R^{-T} M^T [D_L^T D_L] M D_R^{-1} < \gamma^2 I$ $D_R^{-T} M^T [D_L^T D_L] M < \gamma^2 ID_R$ $M^T [D_L^T D_L] M < D_R^T \gamma^2 ID_R$ $M^T [D_L^T D_L] M < \gamma^2 [D_R^T D_R]$ $X_L := [D_L^T D_L], X_R := [D_R^T D_R]$ $M^T X_L M < \gamma^2 X_R$ <div style="border: 1px solid black; padding: 5px; margin-top: 10px;"> $\inf_{\substack{(X_L, X_R) \in \mathcal{X} \\ \gamma \in \mathbb{R}^+}} \boxed{\gamma}$ $\text{s. t. } \boxed{M^T X_L M < \gamma^2 X_R}$ </div> |

Let us determine the structure of X

$$X = D^H D = \begin{bmatrix} D_1 & & \\ & D_2 & \\ & & D_3 I_2 \end{bmatrix}^T \begin{bmatrix} D_1 & & \\ & D_2 & \\ & & D_3 I_2 \end{bmatrix} = \begin{bmatrix} D_1^H D_1 & & \\ & (D_2)^2 & \\ & & (D_3)^2 I_2 \end{bmatrix} \rightarrow \begin{bmatrix} D_1 & & \\ & D_2 & \\ & & D_3 I_2 \end{bmatrix},$$

$D_1 \in \mathbb{C}^{2 \times 2}, D_1 = D_1^H > 0$

$D_2 \in \mathbb{R}, D_2 > 0$

$D_3 \in \mathbb{R}, D_3 > 0$

| MATLAB code | | | | |
|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------|--------|-------------|--------------|
| <pre>% ADD YALMIP AND SDPT3 LIBRARIES % CASE 4: DELTA STRUCTURE = blkdiag([delta1*eye(2),delta2,DELTA_3]):delta1,delta2 in COMPLEX, DELTA_3 in 2x2 COMPLEX MATRIX N_s=[tf([1],[1,1]),tf([1],[1,2]),tf([1],[1,3]),tf([1],[1,3]),tf([1],[1,4]); tf([1],[1,5]),tf([1],[1,1]),tf([1],[1,2]),tf([1],[1,3]),tf([1],[1,4]); tf([1],[1,2]),tf([1],[1,4]),tf([1],[1,7]),tf([1],[1,3]),tf([1],[1,4]); tf([1],[1,2]),tf([1],[1,4]),tf([1],[1,7]),tf([1],[1,3]),tf([1],[1,4]); tf([1],[1,2]),tf([1],[1,4]),tf([1],[1,7]),tf([1],[1,3]),tf([1],[1,4])]; % compute the matrix for a given freq Njw1=evalfr(N_s,1*i) % CASE 4: DELTA STRUCTURE = blkdiag([delta1*eye(2),delta2,DELTA_3]):delta1,delta2 in COMPLEX, DELTA_3 in 2x2 COMPLEX MATRIX % BISECTION PROBLEM g2=sdppvar(1,1,'symmetric'); eps1=1e-3; D1=sdppvar(2,2,'hermitian','complex'); D2=sdppvar(1,1,'symmetric'); D3=sdppvar(1,1,'symmetric'); X=blkdiag(D1,D2,D3*eye(2)); F=[]; F=[F;Njw1'*X*Njw1-g2*X<=-eps1*eye(5)]; % ops = sdpsettings('solver','sdpt3'); ops = sdpsettings('solver','bisection','bisection.solver','sdpt3'); sol = bisection(F,[g2],ops); sol.info X=value(X) g2=value(g2) gamma=sqrt(g2) YALMIP_SSV=gamma; %% rho_N=max(abs(eig(Njw1))); % spectral radius of Njw1 sigma_max_N=max(svd(Njw1)); % sigma-max of Njw1 % COMPUTE THE SSV USING MATLAB-MUSSV FCN % bounds = mussv(N,BlockStructure) [bounds,muinfo] = mussv(Njw1,[2,0;1,1;2,2]); MATLAB_MUSSV=bounds(2); clc; fprintf("YALMIP_SSV \t rho_N \t sigma_max_N \t MATLAB_MUSSV\n"); fprintf("%6.4f \t \t %6.4f \t %6.4f \t %6.4f\n",YALMIP_SSV,rho_N,sigma_max_N,MATLAB_MUSSV);</pre> | | | | |
| Code | YALMIP_SSV | rho_N | sigma_max_N | MATLAB_MUSSV |
| OUTPUT | 1.6757 | 1.6313 | 1.6797 | 1.6757 |

CASE 5: MIXED CASE [RECTANGULAR CASE]

SSV COMPUTATION [FOR A FIXED FREQ]

$$N(s) = \begin{bmatrix} \frac{1}{s+1} & \frac{1}{s+2} & \frac{1}{s+3} & \frac{1}{s+3} & \frac{1}{s+4} & \frac{1}{s+3} & \frac{1}{s+4} \\ \frac{1}{s+5} & \frac{1}{s+1} & \frac{1}{s+2} & \frac{1}{s+3} & \frac{1}{s+4} & \frac{1}{s+3} & \frac{1}{s+4} \\ \frac{1}{s+2} & \frac{1}{s+4} & \frac{1}{s+7} & \frac{1}{s+3} & \frac{1}{s+4} & \frac{1}{s+3} & \frac{1}{s+2} \\ \frac{1}{s+2} & \frac{1}{s+4} & \frac{1}{s+7} & \frac{1}{s+3} & \frac{1}{s+4} & \frac{1}{s+3} & \frac{1}{s+4} \\ \frac{1}{s+2} & \frac{1}{s+4} & \frac{1}{s+7} & \frac{1}{s+3} & \frac{1}{s+4} & \frac{1}{s+3} & \frac{1}{s+3} \\ \frac{1}{s+5} & \frac{1}{s+1} & \frac{1}{s+2} & \frac{1}{s+3} & \frac{1}{s+4} & \frac{1}{s+3} & \frac{1}{s+4} \\ \frac{1}{s+2} & \frac{1}{s+4} & \frac{1}{s+7} & \frac{1}{s+3} & \frac{1}{s+4} & \frac{1}{s+3} & \frac{1}{s+4} \end{bmatrix}$$

$$N(j1) = \begin{bmatrix} \frac{1}{s+1} & \frac{1}{s+2} & \frac{1}{s+3} & \frac{1}{s+3} & \frac{1}{s+4} & \frac{1}{s+3} & \frac{1}{s+4} \\ \frac{1}{s+5} & \frac{1}{s+1} & \frac{1}{s+2} & \frac{1}{s+3} & \frac{1}{s+4} & \frac{1}{s+3} & \frac{1}{s+4} \\ \frac{1}{s+2} & \frac{1}{s+4} & \frac{1}{s+7} & \frac{1}{s+3} & \frac{1}{s+4} & \frac{1}{s+3} & \frac{1}{s+2} \\ \frac{1}{s+2} & \frac{1}{s+4} & \frac{1}{s+7} & \frac{1}{s+3} & \frac{1}{s+4} & \frac{1}{s+3} & \frac{1}{s+4} \\ \frac{1}{s+2} & \frac{1}{s+4} & \frac{1}{s+7} & \frac{1}{s+3} & \frac{1}{s+4} & \frac{1}{s+3} & \frac{1}{s+3} \\ \frac{1}{s+5} & \frac{1}{s+1} & \frac{1}{s+2} & \frac{1}{s+3} & \frac{1}{s+4} & \frac{1}{s+3} & \frac{1}{s+4} \\ \frac{1}{s+2} & \frac{1}{s+4} & \frac{1}{s+7} & \frac{1}{s+3} & \frac{1}{s+4} & \frac{1}{s+3} & \frac{1}{s+4} \end{bmatrix}_{s \leftarrow j1}$$

CASE 5: MIXED CASE [RECTANGULAR CASE]

$$\Delta = \left\{ \begin{bmatrix} \delta_1 I_2 & & & \\ & \delta_2 & & \\ & & \Delta_3 & \\ & & & \Delta_4 \end{bmatrix} : \begin{array}{l} \delta_1 \in \mathbb{C} \\ \delta_2 \in \mathbb{C} \\ \Delta_3 \in \mathbb{C}^{2 \times 3} \\ \Delta_4 \in \mathbb{C}^{2 \times 1} \end{array} \right\}, \mathcal{D} = \{D: D\Delta = \Delta D, \forall \Delta \in \Delta\}$$

$$\mathcal{D} = \{\mathcal{D}_L, \mathcal{D}_R\} = \left\{ D_L = \begin{bmatrix} D_1 & & & \\ & D_2 & & \\ & & D_3 I_3 & \\ & & & D_4 \end{bmatrix}, D_R = \begin{bmatrix} D_1 & & & \\ & D_2 & & \\ & & D_3 I_2 & \\ & & & D_4 I_2 \end{bmatrix} : \begin{array}{l} D_1 \in \mathbb{C}^{2 \times 2}, D_1 = D_1^H > 0 \\ D_2 \in \mathbb{R}, D_2 > 0 \\ D_3 \in \mathbb{R}, D_3 > 0 \\ D_4 \in \mathbb{R}, D_4 > 0 \end{array} \right\}$$

$$\mathcal{D} = \{\mathcal{D}_L, \mathcal{D}_R\} = \left\{ D_L = \begin{bmatrix} \begin{array}{cc} d_1 & d_3 + jd_4 \\ d_3 - jd_4 & d_2 \end{array} & & & \\ & d_5 & & \\ & & d_6 I_3 & \\ & & & d_7 \end{bmatrix}, D_R = \begin{bmatrix} \begin{array}{cc} d_1 & d_3 + jd_4 \\ d_3 - jd_4 & d_2 \end{array} & & & \\ & d_5 & & \\ & & d_6 I_2 & \\ & & & d_7 I_2 \end{bmatrix} : \begin{array}{l} d_1, \dots, d_7 \in \mathbb{R} \\ d_1, \dots, d_7 \in \mathbb{R} \end{array} \right\}$$

$$\mu_\Delta(M) = \mu_\Delta(DMD^{-1}) \rightarrow \mu_\Delta(M) \leq \inf_{D \in \mathcal{D}} \bar{\sigma}(DMD^{-1}) = \inf_{d_1, \dots, d_7 > 0} \bar{\sigma}(DMD^{-1})$$

$$\begin{array}{l} \inf_{\substack{D \in \mathcal{D} \\ \gamma \in \mathbb{R}^+}} \gamma \\ \text{s. t. } \bar{\sigma}(DMD^{-1}) < \gamma \end{array}$$

| FOR SQUARE CASE | FOR RECTANGULAR CASE |
|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $\bar{\sigma}(DMD^{-1}) < \gamma$ $\ DMD^{-1}\ _2 < \gamma$ $\ DMD^{-1}\ _2^2 < \gamma^2$ $\lambda_{\max}([DMD^{-1}]^T [DMD^{-1}]) < \gamma^2$ $[DMD^{-1}]^T [DMD^{-1}] < \gamma^2 I$ $[D^{-T} M^T D^T] [DMD^{-1}] < \gamma^2 I$ $D^{-T} M^T [D^T D] MD^{-1} < \gamma^2 I$ $D^{-T} M^T [D^T D] M < \gamma^2 ID$ $M^T [D^T D] M < D^T \gamma^2 ID$ $M^T [D^T D] M < \gamma^2 [D^T D]$ $X := D$ $M^T X M < \gamma^2 X$ <div style="border: 1px solid black; padding: 5px; margin-top: 10px;"> $\inf_{\substack{X \in \mathcal{X} \\ \gamma \in \mathbb{R}^+}} \gamma$ $\text{s. t. } M^T X M < \gamma^2 X$ </div> | $\bar{\sigma}(D_L M D_R^{-1}) < \gamma$ $\ D_L M D_R^{-1}\ _2 < \gamma$ $\ D_L M D_R^{-1}\ _2^2 < \gamma^2$ $\lambda_{\max}([D_L M D_R^{-1}]^T [D_L M D_R^{-1}]) < \gamma^2$ $[D_L M D_R^{-1}]^T [D_L M D_R^{-1}] < \gamma^2 I$ $[D_R^{-T} M^T D_L^T] [D_L M D_R^{-1}] < \gamma^2 I$ $D_R^{-T} M^T [D_L^T D_L] M D_R^{-1} < \gamma^2 I$ $D_R^{-T} M^T [D_L^T D_L] M < \gamma^2 I D_R$ $M^T [D_L^T D_L] M < D_R^T \gamma^2 I D_R$ $M^T [D_L^T D_L] M < \gamma^2 [D_R^T D_R]$ $X_L := [D_L^T D_L], X_R := [D_R^T D_R]$ $M^T X_L M < \gamma^2 X_R$ <div style="border: 1px solid black; padding: 5px; margin-top: 10px;"> $\inf_{\substack{(X_L, X_R) \in \mathcal{X} \\ \gamma \in \mathbb{R}^+}} \gamma$ $\text{s. t. } M^T X_L M < \gamma^2 X_R$ </div> |

Let us determine the structure of X_L & X_R

$$X_L = D_L^H D_L = \begin{bmatrix} D_1 & & & \\ & D_2 & & \\ & & D_3 I_3 & \\ & & & D_4 \end{bmatrix}^T \begin{bmatrix} D_1 & & & \\ & D_2 & & \\ & & D_3 I_3 & \\ & & & D_4 \end{bmatrix} = \begin{bmatrix} D_1^H D_1 & & & \\ & (D_2)^2 (D_2) & & \\ & & (D_3)^2 (D_3) I_3 & \\ & & & (D_4)^2 (D_4) \end{bmatrix} \rightarrow \begin{bmatrix} D_1 & & & \\ & D_2 & & \\ & & D_3 I_3 & \\ & & & D_4 \end{bmatrix}$$

$$X_R = D_R^H D_R = \begin{bmatrix} D_1 & & & \\ & D_2 & & \\ & & D_3 I_2 & \\ & & & D_4 I_2 \end{bmatrix}^T \begin{bmatrix} D_1 & & & \\ & D_2 & & \\ & & D_3 I_2 & \\ & & & D_4 I_2 \end{bmatrix} = \begin{bmatrix} D_1^H D_1 & & & \\ & (D_2)^2 (D_2) & & \\ & & (D_3)^2 (D_3) I_2 & \\ & & & (D_4)^2 (D_4) I_2 \end{bmatrix} \rightarrow \begin{bmatrix} D_1 & & & \\ & D_2 & & \\ & & D_3 I_2 & \\ & & & D_4 I_2 \end{bmatrix}$$

$$\mathcal{D} = \{\mathcal{D}_L, \mathcal{D}_R\} = \left\{ D_L = \begin{bmatrix} D_1 & & & \\ & D_2 & & \\ & & D_3 I_3 & \\ & & & D_4 \end{bmatrix}, D_R = \begin{bmatrix} D_1 & & & \\ & D_2 & & \\ & & D_3 I_2 & \\ & & & D_4 I_2 \end{bmatrix} : \begin{array}{l} \boxed{D_1 \in \mathbb{C}^{2 \times 2}, D_1 = D_1^H > 0} \\ \boxed{D_2 \in \mathbb{R}, D_2 > 0} \\ \boxed{D_3 \in \mathbb{R}, D_3 > 0} \\ \boxed{D_4 \in \mathbb{R}, D_4 > 0} \end{array} \right\}$$

| MATLAB code-FEASIBILITY (for a given γ , does $\exists X_L, X_R$?) | | |
|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <pre> %% ADD YALMIP AND SDPT3 LIBRARIES %% CASE 5: Mixed DELTA, rectangular case clear all; close all; clc; N_s=[tf([1],[1,1]),tf([1],[1,2]),tf([1],[1,3]),tf([1],[1,4]),tf([1],[1,3]),tf([1],[1,4]); tf([1],[1,5]),tf([1],[1,1]),tf([1],[1,2]),tf([1],[1,3]),tf([1],[1,4]),tf([1],[1,3]),tf([1],[1,4]); tf([1],[1,2]),tf([1],[1,4]),tf([1],[1,7]),tf([1],[1,3]),tf([1],[1,4]),tf([1],[1,3]),tf([1],[1,2]); tf([1],[1,2]),tf([1],[1,4]),tf([1],[1,7]),tf([1],[1,3]),tf([1],[1,4]),tf([1],[1,3]),tf([1],[1,4]); tf([1],[1,2]),tf([1],[1,4]),tf([1],[1,7]),tf([1],[1,3]),tf([1],[1,4]),tf([1],[1,3]),tf([1],[1,3]); tf([1],[1,5]),tf([1],[1,1]),tf([1],[1,2]),tf([1],[1,3]),tf([1],[1,4]),tf([1],[1,3]),tf([1],[1,4]); tf([1],[1,2]),tf([1],[1,4]),tf([1],[1,7]),tf([1],[1,3]),tf([1],[1,4]),tf([1],[1,3]),tf([1],[1,4])]; %% compute the matrix for a given freq Njw1=evalfr(N_s,1*i) %% CASE 5: mixed DELTA - RECTANGULAR CASE % FEASIBILITY PROBLEM % COST FUNCTION % For full delta --> d*eye(n) % For delta*eye(n) --> FULL D % For diag[delta1*eye(s1),delta2*eye(s2),delta3*eye(s3)] --> diag[D1,D2,D3] gamma=100; eps1=1e-3; D1=sdpvar(2,2,'hermitian','complex'); D2=sdpvar(1,1,'symmetric'); D3=sdpvar(1,1,'symmetric'); D4=sdpvar(1,1,'symmetric'); XL=blkdiag(D1,D2,D3*eye(3),D4); XR=blkdiag(D1,D2,D3*eye(2),D4*eye(2)); F=[]; % F=[F;M'*XL*M-gamma^2*XR<=-eps1*eye(7)] F=[F;Njw1'*XL*Njw1-gamma^2*XR<=-eps1*eye(7)] % F=[F;0<=vec(XL)<=1e3]; ops = sdpsettings('solver','sdpt3'); sol = optimize(F,[],ops); sol.info XL=value(XL) XR=value(XR) </pre> | | |
| Code OUTPUT | | <pre> Total CPU time (secs) = 0.20 CPU time per iteration = 0.02 termination code = 0 DIMACS errors: 1.4e-10 0.0e+00 2.6e-09 ----- ans = 'Successfully solved (SDPT3-4)' </pre> |

the bisection part

| MATLAB code-BISECTION (Find min γ , s.t. $\exists X_L, X_R$) | | | | |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------|--------|-------------|--------------|
| <pre> %% ADD YALMIP AND SDPT3 LIBRARIES %% CASE 5: Mixed DELTA, rectangular case clear all; close all; clc; N_s=[tf([1],[1,1]),tf([1],[1,2]),tf([1],[1,3]),tf([1],[1,3]),tf([1],[1,4]),tf([1],[1,3]),tf([1],[1,4]); tf([1],[1,5]),tf([1],[1,1]),tf([1],[1,2]),tf([1],[1,2]),tf([1],[1,3]),tf([1],[1,4]),tf([1],[1,3]),tf([1],[1,4]); tf([1],[1,2]),tf([1],[1,4]),tf([1],[1,7]),tf([1],[1,3]),tf([1],[1,3]),tf([1],[1,4]),tf([1],[1,3]),tf([1],[1,2]); tf([1],[1,2]),tf([1],[1,4]),tf([1],[1,7]),tf([1],[1,3]),tf([1],[1,4]),tf([1],[1,3]),tf([1],[1,3]),tf([1],[1,4]); tf([1],[1,2]),tf([1],[1,4]),tf([1],[1,7]),tf([1],[1,3]),tf([1],[1,4]),tf([1],[1,3]),tf([1],[1,3]),tf([1],[1,3]); tf([1],[1,5]),tf([1],[1,1]),tf([1],[1,2]),tf([1],[1,3]),tf([1],[1,4]),tf([1],[1,3]),tf([1],[1,4]); tf([1],[1,2]),tf([1],[1,4]),tf([1],[1,7]),tf([1],[1,3]),tf([1],[1,4]),tf([1],[1,3]),tf([1],[1,4])]; %% compute the matrix for a given freq Njw1=evalfr(N_s,1*i) % CASE 5: mixed DELTA - RECTANGULAR CASE % BISECTION PROBLEM g2=sdpvar(1,1,'symmetric'); eps1=1e-3; D1=sdpvar(2,2,'hermitian','complex'); D2=sdpvar(1,1,'symmetric'); D3=sdpvar(1,1,'symmetric'); D4=sdpvar(1,1,'symmetric'); XL=blkdiag(D1,D2,D3*eye(3),D4); XR=blkdiag(D1,D2,D3*eye(2),D4*eye(2)); F=[]; % F=[F;M'*XL*M-gamma^2*XR<=-eps1*eye(7)] F=[F;Njw1'*XL*Njw1-g2*XR<=-eps1*eye(7)] % F=[F;0<=vec(XL)<=1e3]; % ops = sdpsettings('solver','sdpt3'); ops = sdpsettings('solver','bisection','bisection.solver','sdpt3'); sol = bisection(F,[g2],ops); sol.info XL=value(XL) XR=value(XR) g2=value(g2) gamma=sqrt(g2) YALMIP_SSV=gamma; %% rho_N=max(abs(eig(Njw1))); % spectral radius of Njw1 sigma_max_N=max(svd(Njw1)); % sigma-max of Njw1 % COMPUTE THE SSV USING MATLAB-MUSSV FCN % bounds = muussv(N,BlockStructure) [bounds,muinfo] = muussv(Njw1,[2,0;1,1;2,3;2,1]); MATLAB_MUSSV=bounds(2); clc; fprintf("YALMIP_SSV \t rho_N \t sigma_max_N \t MATLAB_MUSSV\n"); fprintf("%6.4f \t %6.4f \t %6.4f \t %6.4f\n",YALMIP_SSV,rho_N,sigma_max_N,MATLAB_MUSSV); </pre> | | | | |
| Code OUTPUT | YALMIP_SSV | rho_N | sigma_max_N | MATLAB_MUSSV |
| | 2.1974 | 2.2120 | 2.2646 | 2.1974 |

INFO ABOUT MATLAB MUSSV

» **[bounds,rowd] = mu(M,blk)**

where the structure of the Δ is specified by a two-column matrix **blk**. for example, a

$$\Delta = \begin{bmatrix} \delta_1 I_2 & 0 & 0 & 0 & 0 & 0 \\ 0 & \delta_2 & 0 & 0 & 0 & 0 \\ 0 & 0 & \Delta_3 & 0 & 0 & 0 \\ 0 & 0 & 0 & \Delta_4 & 0 & 0 \\ 0 & 0 & 0 & 0 & \delta_5 I_3 & 0 \\ 0 & 0 & 0 & 0 & 0 & \Delta_6 \end{bmatrix}$$

$$\delta_1, \delta_2, \delta_5, \in \mathbb{C}, \Delta_3 \in \mathbb{C}^{2 \times 3}, \Delta_4 \in \mathbb{C}^{3 \times 3}, \Delta_6 \in \mathbb{C}^{2 \times 1}$$

can be specified by

$$\mathbf{blk} = \begin{bmatrix} 2 & 0 \\ 1 & 1 \\ 2 & 3 \\ 3 & 3 \\ 3 & 0 \\ 2 & 1 \end{bmatrix}.$$

Note that Δ_j is not required to be square. The outputs of the program include a 2×1 vector **bounds** containing the upper and lower bounds of $\mu_{\Delta}(M)$ and the row vector **rowd** containing the scaling D . The D matrix can be recovered by

» **[D_ℓ, D_r] = unwrapd(rowd, blk)**

where D_{ℓ} and D_r denote the left and right scaling matrices used in computing the upper-bound $\inf \bar{\sigma}(D_{\ell} M D_r^{-1})$ when some full blocks are not necessarily square and they are equal if all full blocks are square.

INFO ABOUT MATLAB MUSSV

INFO ABOUT D_L, D_R

$$\mu_{\Delta}(M) \leq \inf_{D \in \mathcal{D}} \bar{\sigma}(DMD^{-1})$$

$$\mu_{\Delta}(M) \leq \inf_{D \in \mathcal{D}} \bar{\sigma}(D_L M D_R^{-1})$$

and

$$\Delta = \left\{ \Delta = \begin{bmatrix} \delta_1 I_2 & & & \\ & \delta_2 & & \\ & & \Delta_3 & \\ & & & \Delta_4 \end{bmatrix} : \delta_1, \delta_2 \in \mathbb{C}, \Delta_3 \in \mathbb{C}^{2 \times 3}, \Delta_4 \in \mathbb{C}^{2 \times 1} \right\}.$$

Then $\text{blk} = \begin{bmatrix} 2 & 0 \\ 1 & 1 \\ 2 & 3 \\ 2 & 1 \end{bmatrix}$ and the MATLAB program gives bounds = $\begin{bmatrix} 10.5955 & 10.5518 \end{bmatrix}$

and

$$D_\ell = \begin{bmatrix} D_1 & & & \\ & 0.7638 & & \\ & & 0.8809 I_3 & \\ & & & 1.0293 \end{bmatrix}$$

$$D_r = \begin{bmatrix} D_1 & & & \\ & 0.7638 & & \\ & & 0.8809 I_2 & \\ & & & 1.0293 I_2 \end{bmatrix}$$