# hand\_in\_module3

### January 12, 2024

```
[]: import numpy as np
from itertools import product, combinations, combinations_with_replacement,
permutations
from collections import defaultdict
from tqdm import tqdm
```

(Inductive logic programming in the context of prop ositional logic) Le p,q,r be propositional variables (6p) Since i find it intreating to apply theory to parties i will try to implement the algorithm in python. My argument for that is that if i can implement it then i probably understand it. I will reason for the answers that the algorithm gives.

#### Assignment 1

(a) Suppose that all the formulas  $\neg p$  r,  $\neg q$   $\neg r$  and p are true. Determine the truth values of q and r.

```
[]: true_statements = [
    lambda p, q, r: not p or r,
    lambda p, q, r: not q or not r,
    lambda p, q, r: p,
]

for p, q, r in product([True, False], repeat=3):
    if all(map(lambda f: f(p, q, r), true_statements)):
        print(f"p={p}, q={q}, r={r}")
```

p=True, q=False, r=True

- if p is true then r must be true given true statement  $\neg p$  r.
- if r is true then q must be false given true statement  $\neg q \neg r$ .

**Answer 1.a** q is false and r is true.

(b) Construct a CNF which avoids N and covers E where:

```
\begin{split} \mathbf{N} &= \{(0,1,0), (1,0,0), (1,1,0)\} \text{ and} \\ \mathbf{E} &= \{(0,0,0), (0,0,1), (0,1,1), (1,0,1), (1,1,1)\}. \end{split}
```

Try to simplify as much as possible by removing unnecessary 1 literals (if such exist).

```
[]: \#E = np.array([(1,1,0,1),(1,0,1,0),(0,1,1,0),(0,1,0,1),(1,0,1,1)])
     \# N = np.array([(0,0,0,0),(1,1,1,1),(1,1,1,0),(0,1,0,0),(1,0,0,1)])
     E = np.array([(0,0,0),(0,0,1),(0,1,1),(1,0,1),(1,1,1)])
     N = \text{np.array}([(0,1,0),(1,0,0),(1,1,0)])
     def covers(cause, statements):
         all positive examples satisfy
         11 11 11
         cause = np.array(cause, dtype=bool)
         covered = np.zeros(len(statements), dtype=bool)
         for i, statement in enumerate(statements):
             res = list(map(lambda c, s: c if s else not c, cause, statement))
             covered[i] = any(res)
         return all(covered)
     def avoids(cause, statements):
         no negative example satisfy
         cause = np.array(cause, dtype=bool)
         avoided = np.zeros(len(statements), dtype=bool)
         for i, statement in enumerate(statements):
             res = list(map(lambda c, s: c if s else not c, cause, statement))
             avoided[i] = all(res)
         return not any (avoided)
     def cause str(cause):
         cause, idxs = cause
         return '(' + ' '.join(map(lambda i: f'{L[i]}' if cause[i] else_
      \hookrightarrow f' \neg \{L[i]\}', idxs)) + ')'
     L = ['p', 'q', 'r', 's', 't']
     def find_H(cause, E, N, maximal=True):
         for cause_size in sorted(range(1, len(E[0])+1), reverse=maximal):
             for idxs in combinations(range(len(E[0])), cause_size):
                 curr_cause = [cause[i] for i in idxs]
                 if covers(curr_cause, statements=E[:, idxs]) and avoids(curr_cause,_
      ⇔statements=N[:, idxs]):
                     return cause, idxs
         return None, None
     def algorithm(E, N, maximal=True):
         Algorithm 1; producing a maximally general set or simplified set of clauses
      \hookrightarrow H which covers E and avoids N
         (3.3) in Logic_and_probability_7.pdf
```

```
HHHH
    inxs = []
    H = []
    used = set()
    for cause in N:
        cause = [int(not c) for c in cause]
        cause, idxs = find_H(cause, E, N, maximal)
        if cause is not None:
            curr = tuple([cause[i] for i in idxs] + list(idxs))
            if curr in used:
                continue
            used.add(curr)
            H.append(cause)
            inxs.append(idxs)
    return zip(H, inxs)
Fi = algorithm(E, N, maximal=True)
print('Maximally CNF:')
print(' '.join(map(cause_str, Fi)))
Fi = algorithm(E, N, maximal=False)
print('Simplified CNF:')
        '.join(map(cause_str, Fi)))
print('
```

```
Maximally CNF:

(p ¬q r) (¬p q r) (¬p ¬q r)

Simplified CNF:

(¬q r) (¬p r)
```

**Answer 1.b** Algorithm 1/2; producing a maximally general set or simplified set of clauses H which covers E and avoids N. (3.3) in Logic\_and\_probability\_7.pdf

1. with Maximally CNF:

```
(p \neg q r) (\neg p q r) (\neg p \neg q r)
```

2. with Simplified CNF:

$$(\neg q \ r) \ (\neg p \ r)$$

In the rest of the assignments L and M refer to the language L and L-structure M that we now define. Let  $L = \{P,Q,R,S,T\}$  where the relation symbols P,Q,R,S,T have arities 1,1,2,2,2, respectively.

Let M b e the L-structure with domain  $M = \{1,2,3,...,20\}$  and the following interpretations of the relation symbols: \* PM =  $\{1,2,3,4,5,6,7,8,9,10\}$ , \* QM =  $\{1,2,3,4,5,11,12,13,14,15\}$ , \* RM =  $\{(i,j): i=j,1 \ i \ 5 \ and \ 1 \ j \ 5\}$ , \* SM =  $\{(2,5),(3,1),(4,3),(1,2),(5,4),(2,3),(4,2),(1,3),(3,5),(4,5)\}$ , \* TM =  $\{(2,5),(3,1),(4,3),(1,2),(5,4),(3,2),(2,1),(1,4),(2,4),(5,2)\}$ .

```
[]: | # lets define a base class to work with. it needs to have a name and arity
     class Base:
         name = None
         arity = None
         def __repr__(self) -> str:
             return self.name + '(' + ','.join(map(str, self.args)) + ')'
         def __eq__(self, value: object) -> bool:
             return value.name == self.name and value.args == self.args
         def __hash__(self) -> int:
             return hash(self.name) + hash(self.args)
     class Target:
         def __init__(self, name, arg, pos=0):
             self.name = name
             self.arg = arg
             self.pos = pos
         def __repr__(self) -> str:
             return f'{self.name}'
         def __eq__(self, value: object) -> bool:
            return str(value) == str(self)
         def __hash__(self) -> int:
             return hash(self.name + str(self.arg) + str(self.pos))
     class P(Base):
        name = "P"
         arity = 1
         def __init__(self, *args):
             self.args = args
             assert len(args) == self.arity
     class Q(Base):
        name = "Q"
         arity = 1
         def __init__(self, *args):
             self.args = args
             assert len(args) == self.arity
     class R(Base):
         name = "R"
         arity = 2
         def __init__(self, *args):
             self.args = args
             assert len(args) == self.arity
     class S(Base):
        name = "S"
```

```
arity = 2
    def __init__(self, *args):
        self.args = args
        assert len(args) == self.arity
class T(Base):
    name = "T"
    arity = 2
    def __init__(self, *args):
        self.args = args
        assert len(args) == self.arity
M = set(range(1,21))
PM = set(map(P, [1,2,3,4,5,6,7,8,9,10]))
QM = set(map(Q, [1,2,3,4,5,11,12,13,14,15]))
RM = \{R(i,j) \text{ for } i \text{ in } range(1,6) \text{ for } j \text{ in } range(1,6) \text{ if } i != j\}
SM = set(map(S, [2,3,4,1,5,2,4,1,3,4], [5,1,3,2,4,3,2,3,5,5]))
TM = set(map(T, [2,3,4,1,5,3,2,1,2,5], [5,1,3,2,4,2,1,4,4,2]))
```

#### Inductive logic programming and concept learning

- Would in it be fun to implement the algorithm that helps us to learn concepts? Yes!
- Can we use example in the in Logic\_and\_probability\_7.pdf to guide and validate our implementation? Yes!
- Is it harder then just solving the assignments by hand? Yes!
- Is solving the assignments by hand a good idea? Probably Yes!
- Will we implement the algorithm even though it is harder and christmas is coming close? Yes!

Thank your patience. Lets get started!

PS. I will try to add some comments to the code to make it more readable. Don't skip them pls.

```
[]: def valid_combs(arity, variables):
    return filter(lambda x: len(set(x)) == len(x), product(range(variables),
    repeat=arity))

# how do we learn a concept?
# lets iterate over all possible concepts!
def concept_learning(statement, domain, relations, structures,
    extra_variables=0, concept_size=2):
    # we need to find a concept that is true and false for all relation examples
    result = defaultdict(set)
    # We need to find a concept that has at least the same amount of variables_u
    as the arity as the statement
    variables = statement.arity
# lets iterate over all possible concepts of size concept_size
```

```
for structs in tqdm(list(combinations_with_replacement(structures,_
⇔concept_size))):
       init_var_stat = list(range(variables))
       # lets build and abstract target string
       target_str = str(statement(*[f"x{j}" for j in init_var_stat]))
       # lets iterate possible initializations of the concept
       for init_var_concept in product(*[valid_combs(s.arity,__
→variables+extra_variables) for s in list(structs)]):
           # if the concept has less variables than the target statement the
\hookrightarrowskip it
           if not all(map(lambda x: x in [i for row in init_var_concept for iu
→in row], init_var_stat)):
               continue
           # lets iterate over all possible truth values
           for truths in product([lambda x: x, lambda x: not x], u
→repeat=len(structs)):
               # lets build and abstract concept string
               truths_str = ["¬" if t(False) else "" for t in truths]
               concept_str = ' '.join(sorted(set([t+str(s(*[f"x{i}" for i in_
→v])) for t, s, v in zip(truths_str, structs, init_var_concept)])))
               for d in filter(lambda x: len(set(x)) == len(x),
→product(domain, repeat=variables)):
                   # lets initialize the statement
                   stat = statement(*[d[j] for j in init_var_stat])
                   # lets check if the statement is true or false for all _{\hspace*{-0.05cm}\sqcup}
\negrelations
                   target_stat = stat in relations[stat.name]
                   # if we have extra variables we need to iterate over them_
⇔as well
                   for e in product([dom for dom in domain if dom not in d], u
→repeat=extra_variables):
                       cd = d + e
                        # lets initialize the concept
                       concept = [s(*[cd[j] for j in v]) for s, v in_{\sqcup}]
\rightarrow zip(structs, init_var_concept)]
                        # lets check if the concept is true or false for all_
\rightarrowrelations
                       condition_concept = [ t(r) for r, t in zip(map(lambda x:
→ x in relations[x.name], concept), truths)]
                        # lets save the result
                       result[(concept_str, target_str, e)].
→add((all(condition_concept), target_stat))
```

```
# we are know have a dictionary with all possible concepts and their truth_{\sqcup}
 \rightarrow values
    return result
# how do we read what concepts we have learned?
def parse result(result):
    concepts_eq = set()
    concepts_imp = set()
    # lets iterate over all concepts
    for (c, t, e), examples in result.items():
         # lets check if c implies t and t implies c since thats the same as c_{\sqcup}
 \hookrightarrow <-> t
         if not any(map(lambda x: x[0] and not x[1], examples)) and not_
 \rightarrowany(map(lambda x: not x[0] and x[1], examples)):
             concepts eq.add(f''(c) \leftarrow \{t\}'')
         elif not any(map(lambda x: x[0] and not x[1], examples)): # c \rightarrow t
             concepts_imp.add(f''\{c\} \rightarrow \{t\}'')
    # WOW! we have learned some concepts
    return concepts_eq, concepts_imp
```

### Lets start by solving the assignments in the Logic\_and\_probability\_7.pdf (3.4.1)

```
[]: # python lacks a scope so we need to define a function to not pollute the
      ⇔global namespace
     def scope():
         class F(Base):
             arity = 1
             name = "F"
             def __init__(self, *args):
                 self.args = args
                 assert len(args) == F.arity
         class P(Base):
             arity = 2
             name = "P"
             def __init__(self, *args):
                 self.args = args
                 assert len(args) == P.arity
         class D(Base):
             arity = 2
             name = "D"
             def __init__(self, *args):
                 self.args = args
                 assert len(args) == D.arity
```

```
class G(Base):
        arity = 2
        name = "G"
        def __init__(self, *args):
            self.args = args
            assert len(args) == G.arity
    A = ['a', 'b', 'e', 'g', 'h', 'm', 'n', 't']
    relations = \{'F': \{F('m'), F('h'), F('e'), F('n')\}, \# (i.e. m, n, e, and n_{\parallel})\}
  →are females),
                 'P': {P('g', 'm'), P('h', 'm'), P('h', 't'), P('t', 'e'), L
  \neg P('n', 'e'), P('a', 't'), P('e', 'b')\}, \# (i.e. g is a parent of m, h is a_{\sqcup})
  ⇔parent of m, and so on)
                 'D': {D('m', 'g'), D('m', 'h'), D('e', 't'), D('e', 'n')}, # (i.
 \rightarrowe. m is a daughter of g)
                 'G': \{G('h', 'e'), G('n', 'b')\}, \# (i.e. h is a grandmother of_{\bot})\}
  \rightarrow e, n is a grandmother of b)
    }
    result = concept_learning(D, A, relations, [F, P, G], extra_variables=0,__
 ⇔concept_size=2)
    concepts_eq, concepts_imp = parse_result(result)
    print('Concepts: Daughters')
    for c in concepts_eq:
        print(c)
    result = concept_learning(G, A, relations, [F, P, D], extra_variables=1,_
 ⇔concept size=3)
    concepts_eq, concepts_imp = parse_result(result)
    print('Concepts: Grandmothers')
    for c in concepts_eq:
        print(c)
scope()
100%|
          | 6/6 [00:00<00:00, 352.79it/s]
Concepts: Daughters
F(x0) P(x1,x0) \iff D(x0,x1)
  0%1
               1.27it/s]
Concepts: Grandmothers
F(x0) P(x0,x2) P(x2,x1) \iff G(x0,x1)
D(x2,x0) F(x0) P(x2,x1) <-> G(x0,x1)
```

Result:

We found the following concept for Daughters: 1. F(x1) P(x0,x1) < -> D(x0,x1)

This makes sense witch is good!

We found the following concept for Grandmothers:

```
\begin{array}{lll} 1. & F(x0) & P(x2,\!x1) & P(x0,\!x2) <-> G(x0,\!x1) \\ 2. & F(x0) & P(x2,\!x1) & D(x2,\!x0) <-> G(x0,\!x1) \end{array}
```

That is cool since we found one that was expected and one that was not expected but makes sense.

Ether we are a grandmother to the child of our child or that our mother is a grandmother to our child.

Assignment 2 Learning the concept R(x,y): Find literals 1(x,y),..., n(x,y) which do not contain R and such that  $M = x y((1(x,y) ... n(x,y)) \to R(x,y))$  and M = x y(1(x,y) ... n(x,y)). Observe that a literal denoted k(x,y) above need not necessarily contain both variables x and y and it may be of the form x = y or  $\neg(x = y)$ . There may be several possibilities, but to get maximal credit on this assignment you need to find such 1(x,y),...,n(x,y) so that

$$M| = \forall x \forall y ((\theta 1(x, y) \land ... \land \theta n(x, y)) \leftrightarrow R(x, y))$$

```
[]: relations = {'P': PM, 'Q': QM, 'R': RM, 'S': SM, 'T': TM}

result = concept_learning(R, M, relations, [P, Q, S, T], extra_variables=0,__
concept_size=4)

concepts_eq, concepts_imp = parse_result(result)

print('Concepts: R')

for c in concepts_eq:
    print(c)
100%| | 35/35 [00:14<00:00, 2.41it/s]
```

```
Concepts: R

P(x0) P(x1) Q(x0) Q(x1) \leftarrow R(x0,x1)
```

**Answer 2** Concept a that is learned for R is:

$$P(x0) \wedge P(x1) \wedge Q(x0) \wedge Q(x1) \leftrightarrow R(x0, x1)$$

After a solution its easy to see that this is a correct solution. However there might exist other solutions that has a larger set of literals. However the smallest set of literals that gives the correct solution is 4 literals.

Construction of a probabilistic model and inference As previously lets use the course material to guide the implementation and validation of the algorithm. Its imt to travel to the land of chapter 5 in Logic\_and\_probability\_7.pdf

Algorithm1 for finding the arrows of a DAG corresponding to a lifted Bayesian network:

```
Set k := 1 and as long as k < m do:
        For every i = 1, ..., k, add an arrow from i to k+1.
        Set I := \{1, ..., k\}.
        For i = 1, \ldots, k do:
            If k+1 and i are conditionally independent over (j : j I \{i\}), then
                remove i from I (i.e. set I := I \setminus \{i\}) and remove the arrow from i to k+1.
            Otherwise
                do nothing.
        Set k := k + 1.
    Next, for every vertex k with parents i1,..., is , say, one computes the conditional probabili
     {n}(k = 1 \mid i1 = b1,..., is = bs) for every choice of b1,...,bs {0,1}.
[]: import networkx as nx
     import matplotlib.pyplot as plt
     from fractions import Fraction
[]: def intersect(obj, relations, phi):
         offset = 0
         if isinstance(phi, Target):
             offset = phi.pos
         res = set()
         for o in obj:
             for r in relations:
                 if r.args == o[offset:r.arity+offset]:
                     res.add(o)
         return res
     def left_join(obj, relations, phi):
         offset = 0
         if isinstance(phi, Target):
             offset = phi.pos
         res = obj.copy()
         for o in obj:
             for r in relations:
                 if r.args == o[offset:r.arity+offset]:
                     res.discard(o)
         return res
     def full(M, arity):
         return set(product(M, repeat=arity))
     def full_uniq(M, arity):
```

```
return set(filter(lambda x: len(set(x)) == len(x), product(M, u
 →repeat=arity)))
class BayesianNetwork:
    def __init__(self, nodes, M, relations, arity):
        self.nodes = nodes
        self.edges = []
        self.M = M
        self.relations = relations
        self.arity = arity
        self.parents = defaultdict(set)
        self.children = defaultdict(set)
    def add_edge(self, node1, node2):
        self.edges.append((node1, node2))
        self.parents[node2].add(node1)
        self.children[node1].add(node2)
    def remove_edge(self, node1, node2):
        self.edges.remove((node1, node2))
        self.parents[node2].remove(node1)
        self.children[node1].remove(node2)
    def draw(self):
        G = nx.DiGraph()
        G.add_nodes_from([f'{n.name}({n.arg})' if isinstance(n, Target) else_

¬f'{n}' for n in self.nodes])
        for arrow in self.edges:
            a1 = arrow[0]
            a2 = arrow[1]
            if isinstance(a1, Target):
                a1 = f'{a1.name}({a1.arg})'
            if isinstance(a2, Target):
                a2 = f'\{a2.name\}(\{a2.arg\})'
            G.add_edge(a1, a2)
        nx.draw(G, with_labels=True, node_size=2000, node_color="lightblue", u

size=14)

    def table(self):
        # lets build a table using BFS
        used = set()
        frontier = list(filter(lambda x: len(self.parents[x]) == 0, self.nodes))
        print('Conditional probabilities:')
        while len(frontier) > 0:
            node = frontier.pop(0)
            if node in used:
                continue
```

```
used.add(node)
           parents = self.parents[node]
           # lets compute the conditional probability based on the parents
           for op in product([True, False], repeat=len(parents)):
               repr = [] # lets build a representation of the conditional
\hookrightarrow probability
               value = 0
               full set = full uniq(self.M, self.arity) # make sure that x /= y
               for n, p in zip(parents, op):
                   if p:
                       if isinstance(n, Target):
                           repr.append(f'{n}({n.arg})')
                       else:
                           repr.append(f'{n}')
                        # if its true we need to get the intersection if the
\hookrightarrowsets
                       full_set = intersect(full_set, self.relations[str(n)],__
⇔n)
                   else:
                       if isinstance(n, Target):
                           repr.append(f'¬{n}({n.arg})')
                       else:
                           repr.append(f'¬{n}')
                       # if its false we need to get the left join of the sets
                       full_set = left_join(full_set, self.relations[str(n)],__
⇔n)
               p_str = ''
               if len(repr) > 0:
                   p_str = ' | '+' '.join(repr)
               node_str = f'{node}'
               if isinstance(node, Target):
                   node str = f'{node}({node.arg})'
               # if the set is empty then its undefined
               if len(full_set) == 0:
                   print(f'({node_str}{p_str}) = undefined')
               else:
                   # lets count conditional probability
                   known = intersect(full_set, self.relations[str(node)], node)
                   value = len(known)/len(full_set)
                   # lts print the conditional probability as a fraction :)
                   print(f'({node_str}{p_str}) = { Fraction(value).
→limit_denominator(100)}')
                   # print(known)
                   # print(full_set)
           print('-'*20)
```

```
# dont forget you children
            for child in self.children[node]:
                frontier.append(child)
def build_lifted_network(M, phi, relations, arity=1):
    # lets build a network
    network = BayesianNetwork(phi, M, relations, arity)
    # lets make sure that the relations are in the correct order
    rel = [relations[str(n)] for n in phi]
    # following the algorithm in 5.1
    for k in range(len(phi)-1):
        for i in range(0, k+1):
            network.add_edge(phi[i], phi[k+1])
        I = set(range(k+1))
        for i in range(k+1):
            if is_conditionally_independent(rel, phi, k+1, I, i, M, arity):
                I.remove(i)
                network.remove_edge(phi[i], phi[k+1])
    return network
def is_conditionally_independent(relations, phi, k, I, i, M, arity):
    # lets copy the k relation
    k_set = relations[k].copy()
    dependents = []
    for op in product([True, False], repeat=len(I)):
        # lets build the full possible set
        full_set = full(M, arity)
        # lets se what left after evaluating the conjunction
        for j, p in zip(I, op):
            if p:
                # if its true we need to get the intersection if the sets
                full_set = intersect(full_set, relations[j], phi[j])
            else:
                # if its false we need to get the left join of the sets
                full_set = left_join(full_set, relations[j], phi[j])
        # if the set is empty then we cant do anything
        if len(full_set) == 0:
            dependents.append(False)
            continue
        # lets count conditional probability
        full_val = len(intersect(full_set, k_set, phi[k]))/len(full_set)
        # lets build the subset that excludes i
        sub_set = full(M, arity)
        for j, p in zip(I-{i}, op):
```

```
if p:
                     # if its true we need to get the intersection if the sets
                     sub_set = intersect(sub_set, relations[j], phi[j])
                     # if its false we need to get the left join of the sets
                     sub_set = left_join(sub_set, relations[j], phi[j])
             # if the set is empty then we cant do anything
             if len(sub_set) == 0:
                 dependents.append(False)
                 continue
             # lets count conditional probability
             sub_val = len(intersect(sub_set, k_set, phi[k]))/len(sub_set)
             # lets check if the conditional probability is the same
             dependents.append(full_val == sub_val)
         return all(dependents)
[]: class I1(Base):
         arity = 1
         name = "I1"
         def __init__(self, *args):
             self.args = args
             assert len(args) == I1.arity
     class I2(Base):
         arity = 1
         name = "I2"
         def init (self, *args):
             self.args = args
             assert len(args) == I2.arity
     class I3(Base):
         arity = 1
         name = "I3"
         def __init__(self, *args):
             self.args = args
             assert len(args) == I3.arity
```

 $I3M = \{I3('A'), I3('C'), I3('D'), I3('F'), I3('G'), I3('I'), I3('K'), I3('J'), I3('J'), I3('B'), I3($ 

M2 = {'A', 'B', 'C', 'D', 'E', 'F', 'G', 'H', 'I', 'J', 'K', 'L'}

I1M = {I1('A'), I1('D'), I1('F'), I1('G'), I1('J'), I1('L')}

I2M = {I2('B'), I2('D'), I2('G'), I2('I'), I2('J'), I2('L')}

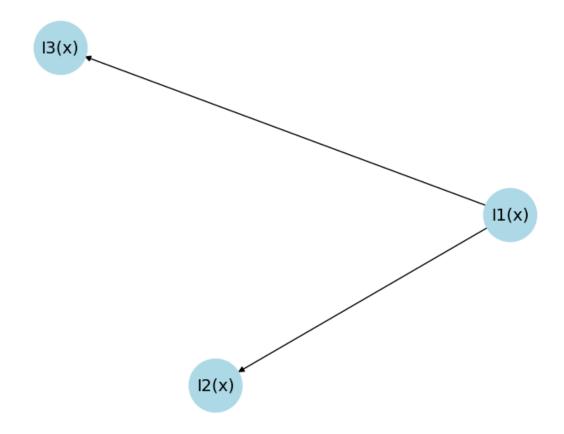
→I3('L')}

```
bayesian_network = build_lifted_network(M2, phi, relations2)
bayesian_network.table()
bayesian_network.draw()
plt.show()
```

## Conditional probabilities:

```
(I1(x)) = 1/2
-----
(I2(x) \mid I1(x)) = 2/3
(I2(x) \mid \neg I1(x)) = 1/3
----
(I3(x) \mid I1(x)) = 1
(I3(x) \mid \neg I1(x)) = 1/2
```

\_\_\_\_\_



```
phi = ['I3(x)', 'I1(x)', 'I2(x)',]

bayesian_network = build_lifted_network(M2, phi, relations2)
bayesian_network.table()
bayesian_network.draw()
```

# plt.show()

## Conditional probabilities:

```
(I3(x)) = 3/4
```

-----

```
(I1(x) \mid I3(x)) = 2/3

(I1(x) \mid \neg I3(x)) = 0

-----

(I2(x) \mid I1(x) \quad I3(x)) = 2/3
```

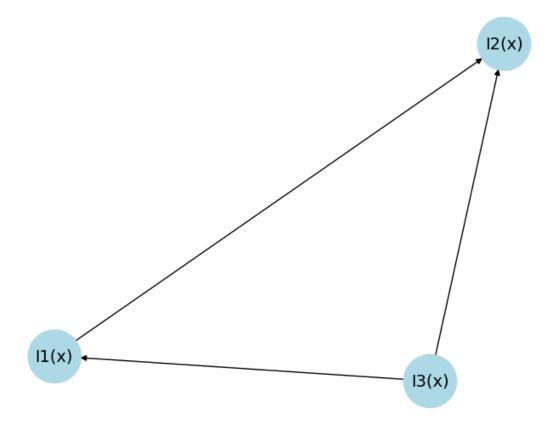
```
(I2(x) \mid I1(x) \quad I3(x)) = 2/3

(I2(x) \mid I1(x) \quad \neg I3(x)) = \text{undefined}

(I2(x) \mid \neg I1(x) \quad I3(x)) = 1/3

(I2(x) \mid \neg I1(x) \quad \neg I3(x)) = 1/3
```

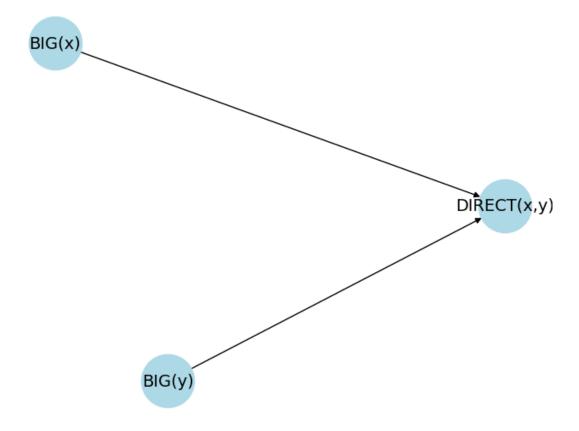
-----



```
[]: class Big(Base):
    arity = 1
    name = "BIG"
    def __init__(self, *args):
        self.args = args
        assert len(args) == Big.arity
```

```
class Direct(Base):
    arity = 2
    name = "DIRECT"
    def __init__(self, *args):
        self.args = args
        assert len(args) == Direct.arity
M3 = \{'A', 'B', 'C', 'D', 'E', 'F', 'G', 'H'\}
BigM = {Big('A'),Big('E'),Big('H')}
DirectM = {Direct('A', 'B'),
           Direct('B', 'A'),
           Direct('A', 'H'),
           Direct('H', 'A'),
           Direct('B', 'C'),
           Direct('C', 'B'),
           Direct('B', 'E'),
           Direct('E', 'B'),
           Direct('E', 'D'),
           Direct('D', 'E'),
           Direct('E', 'F'),
           Direct('F', 'E'),
           Direct('E', 'H'),
           Direct('H', 'E'),
           Direct('H', 'G'),
           Direct('G', 'H'),
relations3 = {'BIG': BigM,
              'DIRECT': DirectM,
}
phi = [Target('BIG', 'x', 0), Target('BIG', 'y', 1), Target('DIRECT', 'x,y')]
bayesian_network = build_lifted_network(M3, phi, relations3, arity=2)
bayesian_network.table()
bayesian_network.draw()
Conditional probabilities:
(BIG(x)) = 3/8
_____
(BIG(y)) = 3/8
_____
```

 $(DIRECT(x,y) \mid BIG(x) \quad BIG(y)) = 2/3$  $(DIRECT(x,y) \mid BIG(x) \neg BIG(y)) = 1/3$  $(DIRECT(x,y) \mid \neg BIG(x) \quad BIG(y)) = 1/3$  $(DIRECT(x,y) \mid \neg BIG(x) \neg BIG(y)) = 1/10$ 



After evaluating the algorithm on the textbook example i feel confident that it has somewhat reasonable chance of working. Let continue with the assignment 3.

Assignment 3 (Learning a Bayesian network) Construct a Bayesian network from M in the way explained in Chapter 5.1 using the following order of the formulas, also viewed as random variables from  $M^2$  to  $\{0,1\}$ : P(x), P(y), Q(x), Q(y), R(x,y), S(x,y), T(x,y). As explained in Chapter 4, we can identify P(x) with a random variable  $P_x$ : P(x) such that  $P_x(a,b) = 1$  if P(x) and  $P_x(a,b) = 0$  otherwise. P(x) can be identified with a random variable  $P_x$ : P(x) such that  $P_x(a,b) = 1$  if P(x) and  $P_x(x)$  and

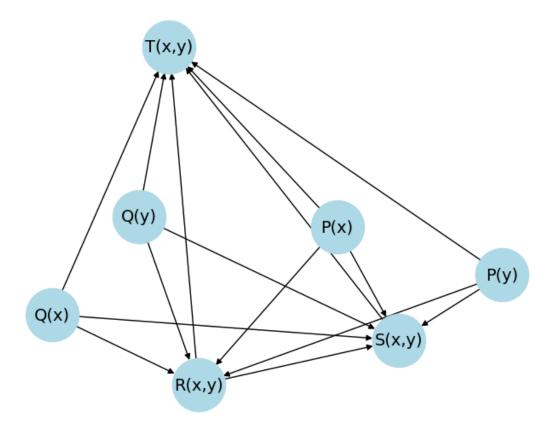
It is also possible, and acceptable, to construct a lifted Bayesian network with vertices P, Q, R, S, T (considered in this order) as defined in Definition 6.2.1 in my notes. The procedure will be essentially the same and you have to do the same calculations. The resulting lifted Bayesian network will be similar to the one obtained by the first approach, but not identical since the later has 5 vertices while the first has 7. (In the later approach P(x) and P(y) are identified, and Q(x) and Q(y) are identified.) When determining (conditional) independence you can use the usual mathematical definition of independence, as there is no need for "approximation" in this assignment. Use the counting measure (i.e. uniform probability distribution) :  $M \to R$  when determining (conditional) probabilities.

```
[]:|phi = [
          Target('P','x'),
          Target('P', 'y', 1),
          Target('Q', 'x'),
          Target('Q', 'y', 1),
          Target('R', 'x,y'),
          Target('S', 'x,y'),
          Target('T', 'x,y'),
     basian_network = build_lifted_network(M, phi, relations, arity=2)
     basian network.table()
     basian_network.draw()
     plt.show()
     Conditional probabilities:
     (P(x)) = 1/2
     _____
     (P(y)) = 1/2
     _____
     (Q(x)) = 1/2
     ______
     (Q(y)) = 1/2
                                                  P(y)) = 1/2
     (S(x,y) \mid P(x)
                         Q(y)
                                Q(x)
                                        R(x,y)
                                        R(x,y)
     (S(x,y) \mid P(x)
                         Q(y)
                                Q(x)
                                                  \neg P(y)) = undefined
                                                  P(y)) = undefined
     (S(x,y) \mid P(x)
                         Q(y)
                                Q(x)
                                        \neg R(x,y)
                                        \neg R(x,y)
     (S(x,y) \mid P(x)
                         Q(y)
                                Q(x)
                                                  \neg P(y)) = 0
     (S(x,y) \mid P(x)
                         Q(y)
                                \neg Q(x)
                                        R(x,y)
                                                  P(y)) = undefined
     (S(x,y) \mid P(x)
                         Q(y)
                                \neg Q(x)
                                         R(x,y) \neg P(y) = undefined
     (S(x,y) \mid P(x)
                         Q(y)
                                \neg Q(x)
                                         \neg R(x,y) \quad P(y)) = 0
     (S(x,y) \mid P(x)
                                \neg Q(x)
                                         \neg R(x,y) \quad \neg P(y)) = 0
                         Q(y)
                                         R(x,y) P(y) = undefined
     (S(x,y) \mid P(x)
                         ¬Q(y)
                                 Q(x)
                                                   \neg P(y)) = undefined
     (S(x,y) \mid P(x)
                         \neg Q(y)
                                 Q(x)
                                         R(x,y)
                                         \neg R(x,y) \quad P(y)) = 0
     (S(x,y) \mid P(x)
                         \neg Q(y)
                                 Q(x)
     (S(x,y) \mid P(x)
                         \neg Q(y)
                                 Q(x)
                                         \neg R(x,y)
                                                    \neg P(y)) = 0
     (S(x,y) \mid P(x)
                         \neg Q(y)
                                 \neg Q(x) R(x,y) P(y)) = undefined
     (S(x,y) \mid P(x)
                         \neg Q(y)
                                 \neg Q(x) \quad R(x,y)
                                                    \neg P(y)) = undefined
     (S(x,y) \mid P(x)
                         \neg Q(y)
                                 \neg Q(x)
                                         \neg R(x,y) \quad P(y)) = 0
     (S(x,y) \mid P(x)
                         \neg Q(y)
                                 \neg Q(x)
                                         \neg R(x,y) \quad \neg P(y)) = 0
     (S(x,y) \mid \neg P(x)
                          Q(y)
                                 Q(x)
                                         R(x,y) P(y) = undefined
                                         R(x,y) \neg P(y) = undefined
     (S(x,y) \mid \neg P(x)
                          Q(y)
                                  Q(x)
     (S(x,y) \mid \neg P(x)
                          Q(y)
                                  Q(x)
                                         \neg R(x,y) \quad P(y)) = 0
     (S(x,y) \mid \neg P(x)
                          Q(y)
                                  Q(x)
                                         \neg R(x,y)
                                                    \neg P(y)) = 0
     (S(x,y) \mid \neg P(x)
                                  \neg Q(x) \quad R(x,y)
                                                    P(y)) = undefined
                          Q(y)
                                                    \neg P(y)) = undefined
     (S(x,y) \mid \neg P(x)
                          Q(y)
                                 \neg Q(x)
                                          R(x,y)
     (S(x,y) \mid \neg P(x)
                          Q(y)
                                 \neg Q(x)
                                          \neg R(x,y) \quad P(y)) = 0
     (S(x,y) \mid \neg P(x)
                          Q(y)
                                  \neg Q(x)
                                          \neg R(x,y) \quad \neg P(y)) = 0
     (S(x,y) \mid \neg P(x)
                          \neg Q(y)
                                   Q(x)
                                          R(x,y) P(y) = undefined
```

```
(S(x,y) \mid \neg P(x)
                                                    \neg P(y)) = undefined
                       \neg Q(y)
                                 Q(x)
                                         R(x,y)
(S(x,y) \mid \neg P(x)
                       \neg Q(y)
                                Q(x)
                                         \neg R(x,y)
                                                      P(y)) = 0
(S(x,y) \mid \neg P(x)
                                         \neg R(x,y)
                                                      \neg P(y)) = 0
                       \neg Q(y)
                                Q(x)
(S(x,y) \mid \neg P(x)
                                 \neg Q(x)
                                          R(x,y)
                                                      P(y)) = undefined
                       \neg Q(y)
                                                      \neg P(y)) = undefined
(S(x,y) \mid \neg P(x)
                       \neg Q(y)
                                \neg Q(x)
                                          R(x,y)
(S(x,y) \mid \neg P(x)
                                          \neg R(x,y)
                                                       P(y)) = 0
                       \neg Q(y)
                                \neg Q(x)
(S(x,y) \mid \neg P(x)
                       \neg Q(y)
                                 \neg Q(x)
                                          \neg R(x,y)
                                                      \neg P(y)) = 0
(R(x,y) \mid P(y)
                     Q(x)
                              P(x)
                                       Q(y)) = 1
(R(x,y) \mid P(y)
                     Q(x)
                              P(x)
                                       \neg Q(y)) = 0
(R(x,y) \mid P(y)
                     Q(x)
                              \neg P(x)
                                        Q(y)) = 0
(R(x,y) \mid P(y)
                     Q(x)
                              \neg P(x)
                                        \neg Q(y)) = 0
(R(x,y) \mid P(y)
                                        Q(y)) = 0
                     \neg Q(x)
                               P(x)
(R(x,y) \mid P(y)
                     \neg Q(x)
                               P(x)
                                        \neg Q(y)) = 0
(R(x,y) \mid P(y)
                     \neg Q(x)
                               \neg P(x)
                                         Q(y)) = 0
                               \neg P(x)
                                         \neg Q(y)) = 0
(R(x,y) \mid P(y)
                     \neg Q(x)
(R(x,y) \mid \neg P(y)
                               P(x)
                                        Q(y)) = 0
                      Q(x)
(R(x,y) \mid \neg P(y)
                       Q(x)
                               P(x)
                                        \neg Q(y)) = 0
(R(x,y) \mid \neg P(y)
                               \neg P(x)
                       Q(x)
                                         Q(y)) = 0
(R(x,y) \mid \neg P(y)
                               \neg P(x)
                                         \neg Q(y)) = 0
                       Q(x)
(R(x,y) \mid \neg P(y)
                      \neg Q(x)
                                P(x)
                                         Q(y)) = 0
(R(x,y) \mid \neg P(y)
                       \neg Q(x)
                                P(x)
                                         \neg Q(y)) = 0
(R(x,y) \mid \neg P(y)
                       \neg Q(x)
                                 \neg P(x)
                                          Q(y)) = 0
                                 \neg P(x)
                                          \neg Q(y)) = 0
(R(x,y) \mid \neg P(y)
                      \neg Q(x)
                                                             P(y)) = 1/2
(T(x,y) \mid P(x)
                     Q(y)
                              S(x,y)
                                         Q(x)
                                                  R(x,y)
(T(x,y) \mid P(x)
                              S(x,y)
                                         Q(x)
                                                  R(x,y)
                                                             \neg P(y)) = undefined
                     Q(y)
(T(x,y) \mid P(x)
                     Q(y)
                              S(x,y)
                                         Q(x)
                                                  \neg R(x,y)
                                                              P(y)) = undefined
(T(x,y) \mid P(x)
                     Q(y)
                              S(x,y)
                                         Q(x)
                                                  \neg R(x,y)
                                                              \neg P(y)) = undefined
(T(x,y) \mid P(x)
                              S(x,y)
                                         \neg Q(x)
                                                   R(x,y)
                                                              P(y)) = undefined
                     Q(y)
                                                              \neg P(y)) = undefined
(T(x,y) \mid P(x)
                     Q(y)
                              S(x,y)
                                         \neg Q(x)
                                                   R(x,y)
(T(x,y) \mid P(x)
                     Q(y)
                              S(x,y)
                                         \neg Q(x)
                                                   \neg R(x,y)
                                                                P(y)) = undefined
(T(x,y) \mid P(x)
                     Q(y)
                              S(x,y)
                                         \neg Q(x)
                                                   \neg R(x,y)
                                                                \neg P(y)) = undefined
                              \neg S(x,y)
                                                   R(x,y)
                                                              P(y)) = 1/2
(T(x,y) \mid P(x)
                     Q(y)
                                          Q(x)
                                                              \neg P(y)) = undefined
(T(x,y) \mid P(x)
                              \neg S(x,y)
                                          Q(x)
                                                   R(x,y)
                     Q(y)
(T(x,y) \mid P(x)
                                                                P(y)) = undefined
                     Q(y)
                              \neg S(x,y)
                                          Q(x)
                                                   \neg R(x,y)
(T(x,y) \mid P(x)
                     Q(y)
                              \neg S(x,y)
                                          Q(x)
                                                   \neg R(x,y)
                                                                \neg P(y)) = 0
(T(x,y) \mid P(x)
                              \neg S(x,y)
                                          \neg Q(x)
                                                    R(x,y)
                                                                P(y)) = undefined
                     Q(y)
                                                    R(x,y)
                                                                \neg P(y)) = undefined
(T(x,y) \mid P(x)
                     Q(y)
                              \neg S(x,y)
                                          \neg Q(x)
(T(x,y) \mid P(x)
                     Q(y)
                              \neg S(x,y)
                                          \neg Q(x)
                                                    \neg R(x,y)
                                                                 P(y)) = 0
                                                                 \neg P(y)) = 0
(T(x,y) \mid P(x)
                     Q(y)
                              \neg S(x,y)
                                          \neg Q(x)
                                                    \neg R(x,y)
                                                              P(y)) = undefined
(T(x,y) \mid P(x)
                     \neg Q(y)
                               S(x,y)
                                          Q(x)
                                                   R(x,y)
(T(x,y) \mid P(x)
                               S(x,y)
                                          Q(x)
                                                   R(x,y)
                                                               \neg P(y)) = undefined
                     \neg Q(y)
(T(x,y) \mid P(x)
                     \neg Q(y)
                               S(x,y)
                                          Q(x)
                                                   \neg R(x,y)
                                                                P(y)) = undefined
(T(x,y) \mid P(x)
                     \neg Q(y)
                               S(x,y)
                                          Q(x)
                                                   \neg R(x,y)
                                                                \neg P(y)) = undefined
                                                    R(x,y)
(T(x,y) \mid P(x)
                     \neg Q(y)
                               S(x,y)
                                          \neg Q(x)
                                                                P(y)) = undefined
(T(x,y) \mid P(x)
                     ¬Q(y)
                               S(x,y)
                                          \neg Q(x)
                                                    R(x,y)
                                                                \neg P(y)) = undefined
(T(x,y) \mid P(x)
                                          \neg Q(x)
                                                    \neg R(x,y) \quad P(y)) = undefined
                     ¬Q(y)
                               S(x,y)
```

```
(T(x,y) \mid P(x)
                      \neg Q(y)
                                S(x,y)
                                           \neg Q(x)
                                                     \neg R(x,y)
                                                                  \neg P(y)) = undefined
                                                                 P(y)) = undefined
(T(x,y) \mid P(x)
                      ¬Q(y)
                                \neg S(x,y)
                                            Q(x)
                                                     R(x,y)
                                                     R(x,y)
(T(x,y) \mid P(x)
                      \neg Q(y)
                                \neg S(x,y)
                                                                 \neg P(y)) = undefined
                                            Q(x)
(T(x,y) \mid P(x)
                                \neg S(x,y)
                                                     \neg R(x,y)
                                                                  P(y)) = 0
                      \neg Q(y)
                                            Q(x)
                                                     \neg R(x,y)
                                                                  \neg P(y)) = 0
(T(x,y) \mid P(x)
                      \neg Q(y)
                                \neg S(x,y)
                                            Q(x)
(T(x,y) \mid P(x)
                                \neg S(x,y)
                                                       R(x,y)
                                                                  P(y)) = undefined
                      \neg Q(y)
                                            \neg Q(x)
(T(x,y) \mid P(x)
                      \neg Q(y)
                                \neg S(x,y)
                                            \neg Q(x)
                                                       R(x,y)
                                                                  \neg P(y)) = undefined
(T(x,y) \mid P(x)
                      ¬Q(y)
                                \neg S(x,y)
                                            \neg Q(x)
                                                       \neg R(x,y)
                                                                   P(y)) = 0
                                                                   \neg P(y)) = 0
(T(x,y) \mid P(x)
                      \neg Q(y)
                                \neg S(x,y)
                                            \neg Q(x)
                                                       \neg R(x,y)
                                                               P(y)) = undefined
(T(x,y) \mid \neg P(x)
                       Q(y)
                                S(x,y)
                                           Q(x)
                                                    R(x,y)
(T(x,y) \mid \neg P(x)
                                                                \neg P(y)) = undefined
                                S(x,y)
                                           Q(x)
                                                    R(x,y)
                       Q(y)
(T(x,y) \mid \neg P(x)
                                S(x,y)
                                           Q(x)
                                                                 P(y)) = undefined
                       Q(y)
                                                    \neg R(x,y)
                                                                 \neg P(y)) = undefined
(T(x,y) \mid \neg P(x)
                                S(x,y)
                                           Q(x)
                                                    \neg R(x,y)
                       Q(y)
(T(x,y) \mid \neg P(x)
                                                                 P(y)) = undefined
                       Q(y)
                                S(x,y)
                                           \neg Q(x)
                                                     R(x,y)
                                                                 \neg P(y)) = undefined
(T(x,y) \mid \neg P(x)
                       Q(y)
                                S(x,y)
                                           \neg Q(x)
                                                     R(x,y)
(T(x,y) \mid \neg P(x)
                                S(x,y)
                                                                  P(y)) = undefined
                       Q(y)
                                           \neg Q(x)
                                                     \neg R(x,y)
(T(x,y) \mid \neg P(x)
                                S(x,y)
                                           \neg Q(x)
                                                     \neg R(x,y)
                                                                  \neg P(y)) = undefined
                       Q(y)
(T(x,y) \mid \neg P(x)
                                \neg S(x,y)
                                                     R(x,y)
                                                                 P(y)) = undefined
                       Q(y)
                                            Q(x)
(T(x,y) \mid \neg P(x)
                                \neg S(x,y)
                                                     R(x,y)
                                                                 \neg P(y)) = undefined
                       Q(y)
                                            Q(x)
(T(x,y) \mid \neg P(x)
                                \neg S(x,y)
                                            Q(x)
                                                     \neg R(x,y)
                                                                  P(y)) = 0
                       Q(y)
(T(x,y) \mid \neg P(x)
                       Q(y)
                                \neg S(x,y)
                                            Q(x)
                                                     \neg R(x,y)
                                                                  \neg P(y)) = 0
                                                       R(x,y)
                                                                  P(y)) = undefined
(T(x,y) \mid \neg P(x)
                       Q(y)
                                \neg S(x,y)
                                            \neg Q(x)
                                                                  \neg P(y)) = undefined
(T(x,y) \mid \neg P(x)
                       Q(y)
                                \neg S(x,y)
                                            \neg Q(x)
                                                       R(x,y)
(T(x,y) \mid \neg P(x)
                                                                   P(y)) = 0
                       Q(y)
                                \neg S(x,y)
                                            \neg Q(x)
                                                       \neg R(x,y)
(T(x,y) \mid \neg P(x)
                                \neg S(x,y)
                                            \neg Q(x)
                                                       \neg R(x,y)
                                                                   \neg P(y)) = 0
                       Q(y)
                                                                 P(y)) = undefined
(T(x,y) \mid \neg P(x)
                                 S(x,y)
                                            Q(x)
                                                     R(x,y)
                       \neg Q(y)
(T(x,y) \mid \neg P(x)
                                                     R(x,y)
                                 S(x,y)
                                                                 \neg P(y)) = undefined
                       \neg Q(y)
                                            Q(x)
                                                                  P(y)) = undefined
(T(x,y) \mid \neg P(x)
                       \neg Q(y)
                                 S(x,y)
                                            Q(x)
                                                     \neg R(x,y)
(T(x,y) \mid \neg P(x)
                                                     \neg R(x,y)
                                                                  \neg P(y)) = undefined
                       \neg Q(y)
                                 S(x,y)
                                            Q(x)
(T(x,y) \mid \neg P(x)
                       \neg Q(y)
                                 S(x,y)
                                            \neg Q(x)
                                                       R(x,y)
                                                                  P(y)) = undefined
(T(x,y) \mid \neg P(x)
                                 S(x,y)
                                                       R(x,y)
                                                                  \neg P(y)) = undefined
                       \neg Q(y)
                                            \neg Q(x)
                                                                   P(y)) = undefined
(T(x,y) \mid \neg P(x)
                       \neg Q(y)
                                 S(x,y)
                                            \neg Q(x)
                                                       \neg R(x,y)
(T(x,y) \mid \neg P(x)
                       \neg Q(y)
                                 S(x,y)
                                            \neg Q(x)
                                                       \neg R(x,y)
                                                                   \neg P(y)) = undefined
                                                                  P(y)) = undefined
(T(x,y) \mid \neg P(x)
                                 \neg S(x,y)
                                                       R(x,y)
                       \neg Q(y)
                                              Q(x)
                                                       R(x,y)
                                                                  \neg P(y)) = undefined
(T(x,y) \mid \neg P(x)
                       \neg Q(y)
                                 \neg S(x,y)
                                              Q(x)
(T(x,y) \mid \neg P(x)
                       \neg Q(y)
                                 \neg S(x,y)
                                              Q(x)
                                                       \neg R(x,y)
                                                                   P(y)) = 0
(T(x,y) \mid \neg P(x)
                                                                   \neg P(y)) = 0
                       \neg Q(y)
                                 \neg S(x,y)
                                              Q(x)
                                                       \neg R(x,y)
(T(x,y) \mid \neg P(x)
                                 \neg S(x,y)
                                              \neg Q(x)
                                                       R(x,y)
                                                                   P(y)) = undefined
                       \neg Q(y)
(T(x,y) \mid \neg P(x)
                                 \neg S(x,y)
                                                        R(x,y)
                                                                   \neg P(y)) = undefined
                       \neg Q(y)
                                              \neg Q(x)
                                                                    P(y)) = 0
(T(x,y) \mid \neg P(x)
                       \neg Q(y)
                                 \neg S(x,y)
                                              \neg Q(x)
                                                        \neg R(x,y)
(T(x,y) \mid \neg P(x)
                                 \neg S(x,y)
                                                        \neg R(x,y)
                                                                    \neg P(y)) = 0
                       \neg Q(y)
                                              \neg Q(x)
```

-----



**Answer 3** This was a massive Basian Network. However it make sense, from the previous assignment we learn concept  $P(x0) \wedge P(x1) \wedge Q(x0) \wedge Q(x1) < -> R(x0,x1)$  this is present in the network and it confirms the equivalence of the concept since the conditional probability of  $\mu(R(x,y)|Q(y) \wedge P(x) \wedge P(y) \wedge Q(x))$  is 1.

Following up on the rest R(x,y), S(x,y), T(x,y) we can se that there is a lot of state overlap in the data and that the dependency are arbitrary and are mostly dependent on the algorithm and the order that we used to construct the network.

**Incomplete Data** Lets start at figure 5.7 in Logic\_and\_probability\_7.pdf and see if we can implement the EM algorithm.

```
results = [p]
         # lets iterate
         for i in range(iterations):
             # lets compute the expected values
             p = (truth + unk*p)/(number_of_variables)
             results.append(p)
         return results
     def compute likelihood(data):
         truth = len(list(filter(lambda x: x, data)))
         none truth = len(list(filter(lambda x: not x and x is not None, data)))
         return truth/(truth+none_truth)
[]: customer = ['A', 'B', 'C', 'D', 'E', 'F', 'G', 'H', 'I', 'J', 'K', 'L']
     I1C = [True, False, None, True, False, True, True, False, False, None, False,

¬Truel
     I2C = [False, True, False, True, False, False, True, False, True, True, False, I
     I3C = [True, False, True, True, False, True, None, False, True, True, True, L
      →True]
     print('(I1(x))')
     data = I1C
     p0 = 0.1
     res = EM_algorithm(data, p0, iterations=6)
     print('EM algorithm:')
     print(' \rightarrow '.join(map(lambda x: f'{x:.4f}', res)))
     print(f'Computed Likelihood:\n{compute_likelihood(data):.4f}')
     (I1(x))
    EM algorithm:
    0.1000 -> 0.4333 -> 0.4889 -> 0.4981 -> 0.4997 -> 0.4999 -> 0.5000
    Computed Likelihood:
    0.5000
[]: print('(I3(x))')
     data = I3C
     p0 = 0.1
     res = EM_algorithm(data, p0, iterations=5)
     print('EM algorithm:')
     print(' -> '.join(map(lambda x: f'{x:.4f}', res)))
     print(f'Computed Likelihood:\n{compute_likelihood(data):.4f}')
     (I3(x))
    EM algorithm:
    0.1000 \rightarrow 0.6750 \rightarrow 0.7229 \rightarrow 0.7269 \rightarrow 0.7272 \rightarrow 0.7273
```

```
Computed Likelihood: 0.7273
```

```
(I3(x) | I1(x)) = (I3(x) | I1(x)) / (I1(x)) = (4/9)/(1/2) = 8/9
```

We can se that the iterative algorithm converges fast. However it is faster to just use the closed form solution.

Lets apply it to the data in the assignment.

**Assignment 4** Now assume that for each of the pairs (1,4),(5,10),(14,6) and (3,5) we do not know if it belongs to RM or not, and for each of the pairs (4,3),(1,3) and (6,8) we do not know if it belongs to SM or not, but otherwise all assumptions are as before.

Estimate (R(x,y)) (also denoted (R=1)) and  $(S(x,y) \mid R(x,y))$  (also denoted  $(S=1 \mid R=1)$ ) by the methods described in Chapter 5.3.

```
[]: print("Estimate (R(x,y))")
     all_r = {n: False for n in full_uniq(M, 2)}
     all_r.update({n.args: True for n in relations['R']}) # Set the True values
     all_r.update(\{n: None for n in [(1,4),(5,10),(14,6),(3,5)]\}) # Set the unknown_
      →values
     res = EM_algorithm(list(all_r.values()), 0.5, iterations=5)
     print('EM algorithm:')
     print(' -> '.join(map(lambda x: f'{x:.4f}', res)))
     print(f'Computed Likelihood:\n{compute_likelihood(list(all_r.values())):.4f}')
    Estimate (R(x,y))
    EM algorithm:
    0.5000 \rightarrow 0.0526 \rightarrow 0.0479 \rightarrow 0.0479 \rightarrow 0.0479 \rightarrow 0.0479
    Computed Likelihood:
    0.0479
[]: print("Estimate (S(x,y) \mid R(x,y))")
     all s = \{n: False for n in full uniq(M, 2)\}
     all_s.update({n.args: True for n in relations['S']}) # Set the True values
     all_s.update(\{n: None for n in [(4,3),(1,3),(6,8)]\}) # Set the unknown values
```

```
Estimate (S(x,y) \mid R(x,y))

(S(x,y) \mid R(x,y)) = (S(x,y) \mid R(x,y)) / (R(x,y)) = (1/53)/(1/21) = 0.3920
```

**Answer 4** Estimating  $\mu(R(x,y))$  with 5 iteration of EM algorithm with p0 of 0.5 gives us the following result:

```
0.5000 -> 0.0526 -> 0.0479 -> 0.0479 -> 0.0479 -> 0.0479
```

Computed the likelihood gives us 0.0479

we can se that we have converged to the same result after 2 iterations.

Estimating  $\mu(S(x,y)|R(x,y))$  we rewrite the formula to  $\frac{\mu(S(x,y)\wedge R(x,y))}{\mu(R(x,y))}$  and we get the following result:

$$\mu(S(x,y)|R(x,y)) = \frac{\mu(S(x,y) \wedge R(x,y))}{\mu(R(x,y))} \approx \frac{1/53}{1/21} \approx 0.3920$$

You have to excuse me for the fraction approximation. I did not want to calculate the fraction by hand.