

Strategies for Positive Partial Transpose (PPT) States in Quantum Metrologies with Noise

By Arunava Majumder
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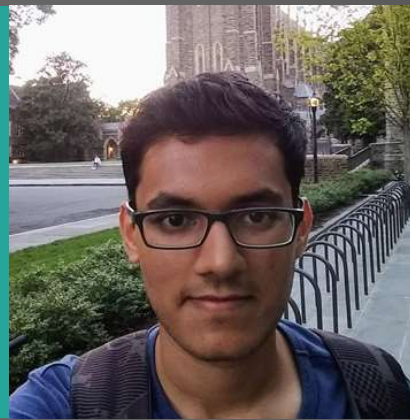
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COLLABORATORS



Dr. LEONG CHUAN KWEK



HARSHANK SHROTRIYA



Centre for
Quantum
Technologies

OVERVIEW OF THE TALK

- Quantum Foundation and information
- Quantum Metrology
- Noisy Quantum Channels and their effects

Quantum Foundation and information

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Bound Entangled or PPT entangled states

Theorem: A higher dimensional PPT state (i.e. a state that remains positive under partial transposition) cannot be distilled (pure entanglement can't be extracted using distillation protocols).

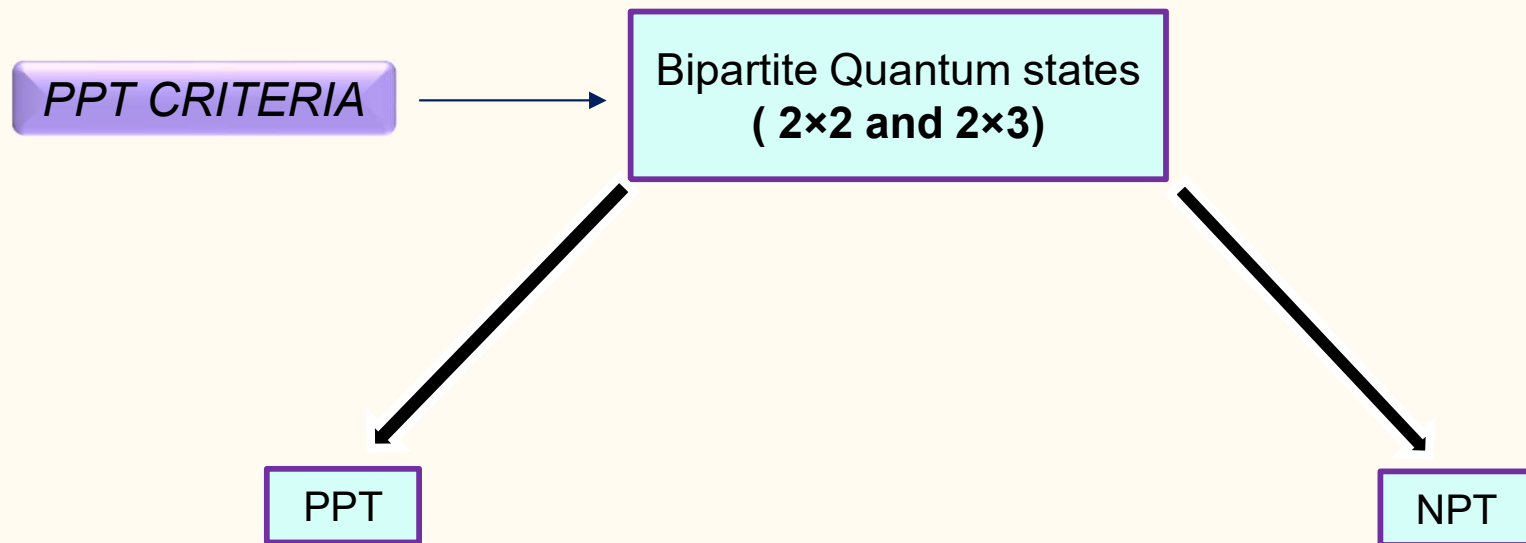
PPT ENTANGLED STATES

PPT CRITERIA

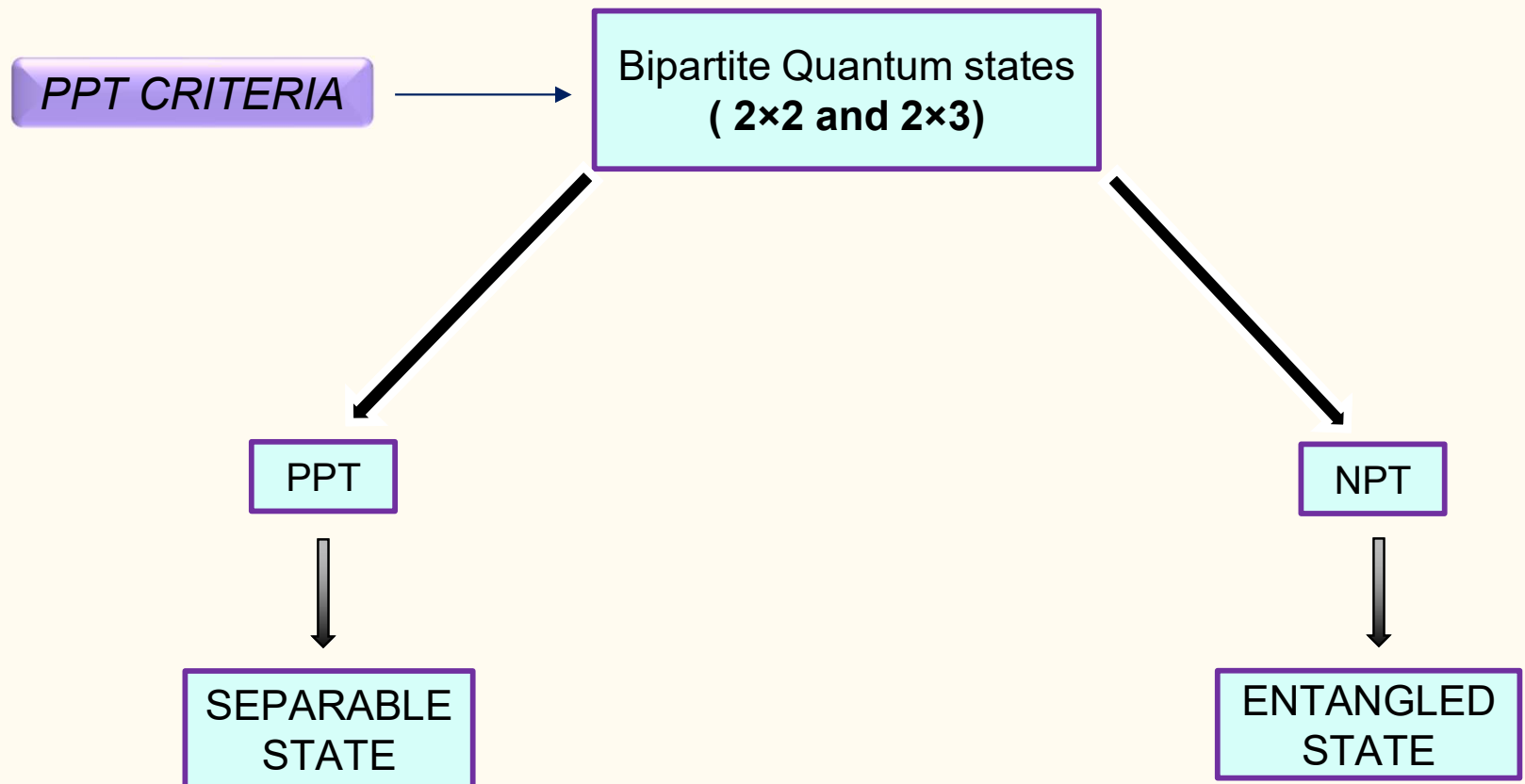


Bipartite Quantum states
(2×2 and 2×3)

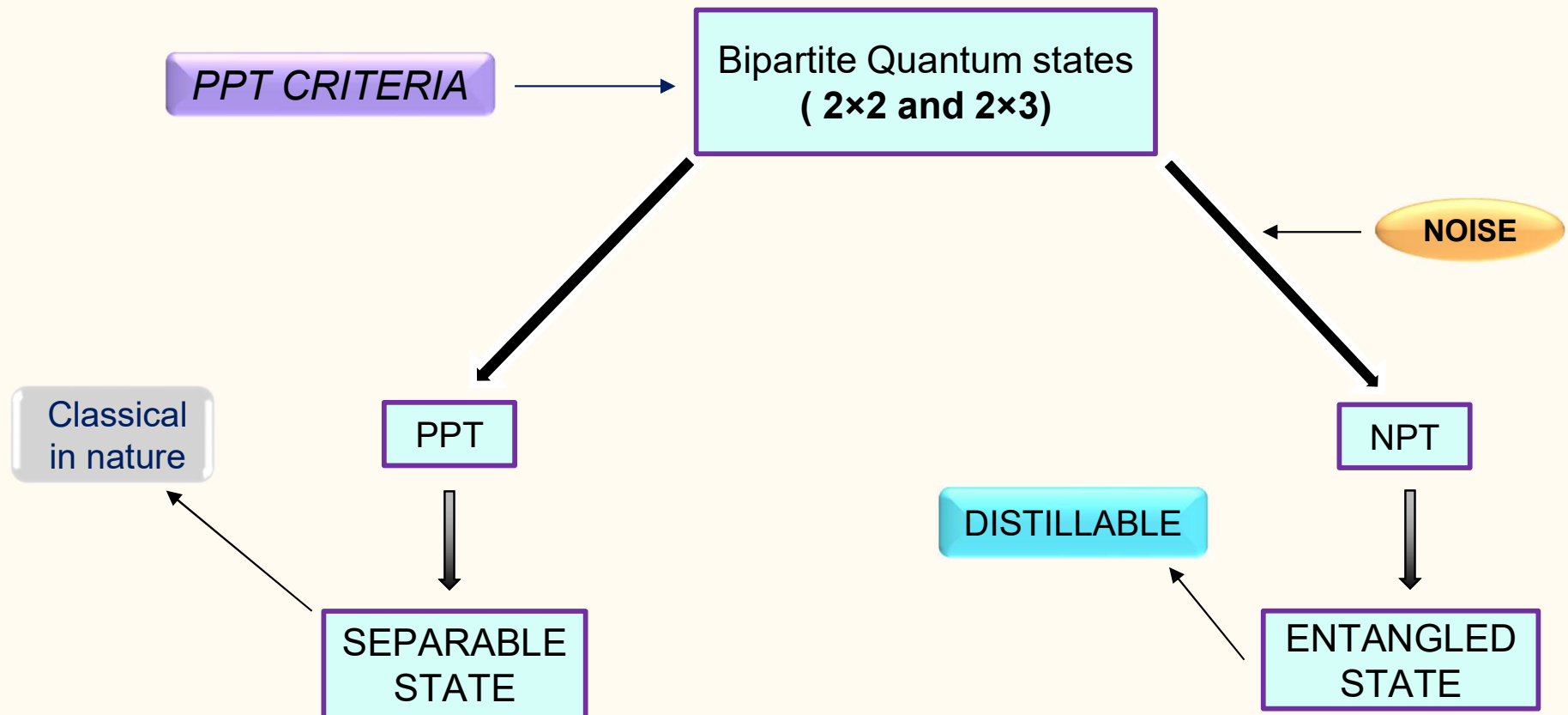
PPT ENTANGLED STATES



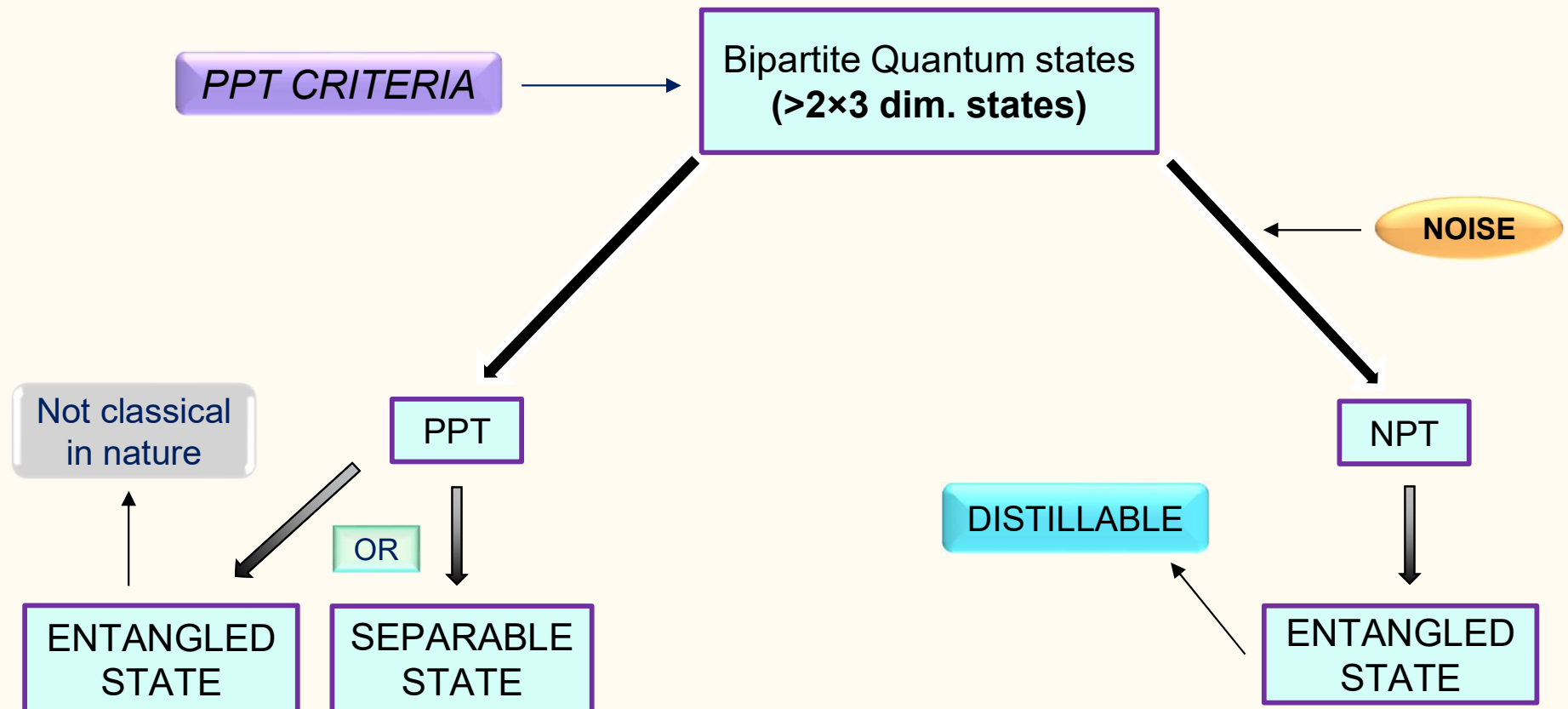
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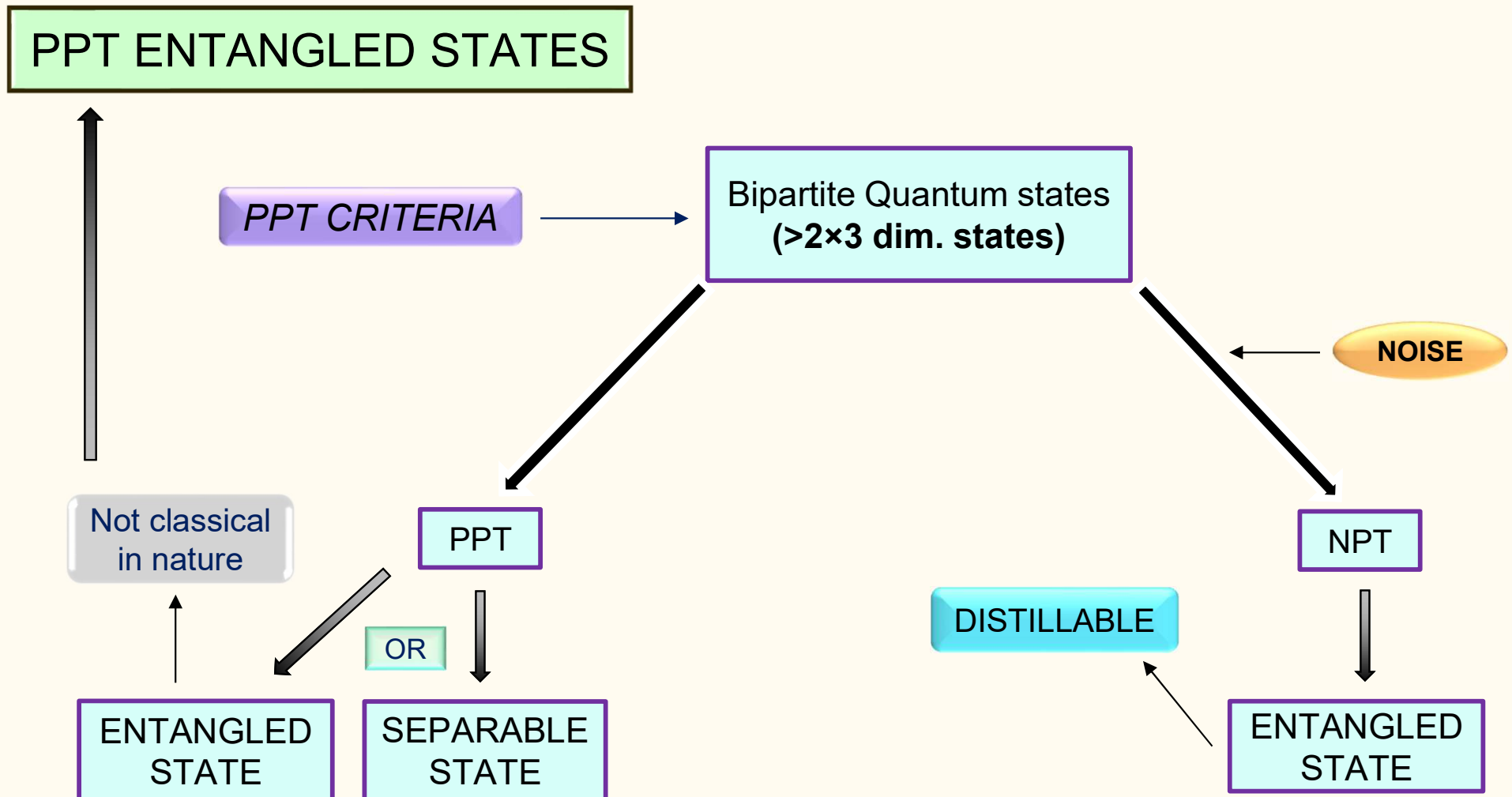


PPT ENTANGLED STATES



PPT ENTANGLED STATES





Quantum Metrology

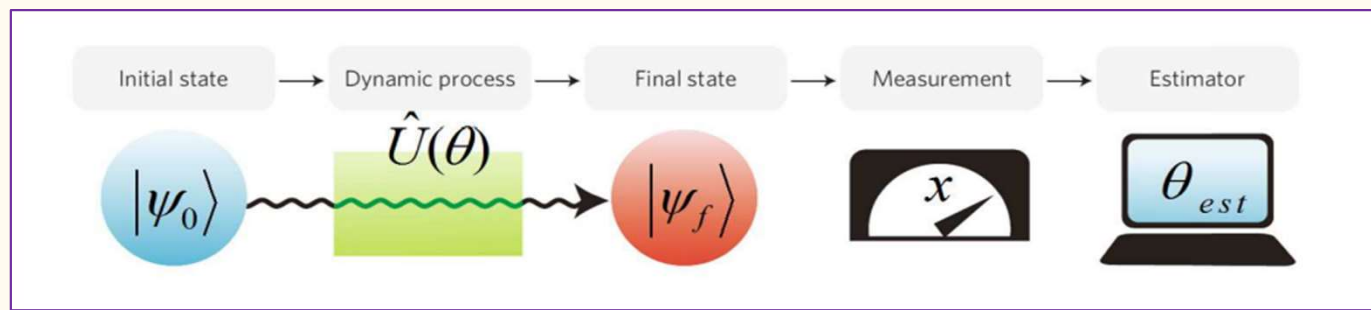
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METROLOGY:

The science of
measurement

- A measurement is a physical process which estimates the quantity of a particular observable (or a physical parameter) of a quantum system.
 - The measurement precision depends on both the performance imperfections and the fundamental limit imposed by the physical laws.
-

General procedure of Measurements



1. Prepare the probe into a desired initial state $\rho_0 = |\psi_0\rangle\langle\psi_0|$. In general it can be either pure or mixed state.
2. Let the probe undergo a dynamical ($U(\theta)$) evolution dependent on the physical parameter ' θ ' to be measured.
3. Read out the final state of the probe using a suitable observable \hat{O} and estimate the physical parameter with the extracted information. The observable \hat{O} should have θ -dependent expectation values $\langle \hat{O} \rangle$.

Classical lower bound to Measurements

- We are focusing on single parameter estimation.

The measurement precision $\Delta\theta$ of an unknown parameter θ is limited by the **CLASSICAL** Cramér – Rao bound

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$$(\Delta\theta) \geq \frac{1}{\sqrt{F_C(\theta)}}$$

• $F_C(\theta)$



CLASSICAL FISHER
INFORMATION

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After N repetition



$$(\Delta\theta) \geq \frac{1}{\sqrt{NF_C(\theta)}}$$

- $F_C(\theta)$



CLASSICAL FISHER
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Quantum lower bound to Measurements

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$$(\Delta\theta) \geq \frac{1}{\sqrt{F_Q(\theta)}}$$

- $F_Q(\theta) = F_Q(\rho, \hat{A})$



QUANTUM FISHER
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QUANTUM FISHER INFORMATION

Limits imposed by Nature

SHOT NOISE
LIMIT (SNL)



For N repetitions of the same measurement,
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STANDARD QUANTUM
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Measurement precision of a Mach-Zehnder interferometer of **N independent particles** is limited by the standard quantum limit (SQL), which has the same scaling $\frac{1}{\sqrt{N}}$ as the SNL.

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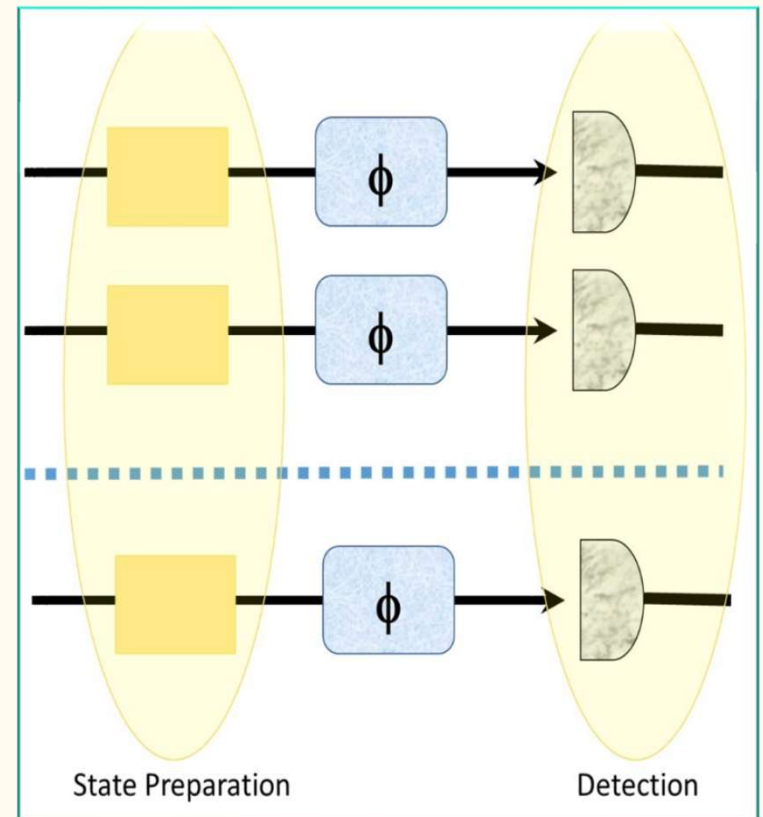
HEISENBERG LIMIT (HL)



Measurement precision of a Mach-Zehnder interferometer of **N entangled particles** in the NOON state can reach the Heisenberg limit which has scaling $\frac{1}{N}$

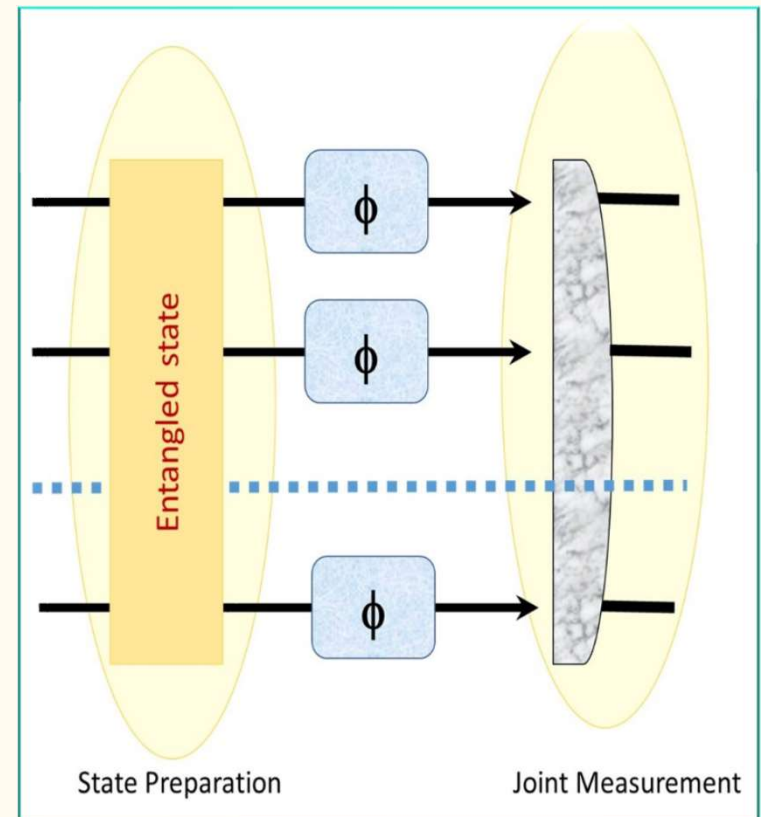
Experimental Realization 1

1. Indirect estimation of the unknown parameter by imprinting it to a probe state.
2. Taking N identical **SEPARABLE** probe states and going through the required steps.
3. Analogous to classical estimation of unknown parameter, provide no advantage. Scales $\frac{1}{\sqrt{N}}$.
4. Mach-Zehnder interferometry, Ramsey interferometry.



Experimental Realization 2

1. Indirect estimation of the unknown parameter by imprinting it to a probe state.
2. Taking N identical **ENTANGLED** probe states and going through the required steps.
3. Analogous to classical estimation of unknown parameter, provide no advantage. Scales $\frac{1}{N}$.
4. Mach-Zehnder interferometry, Ramsey interferometry.



Quantum Fisher Information (QFI)

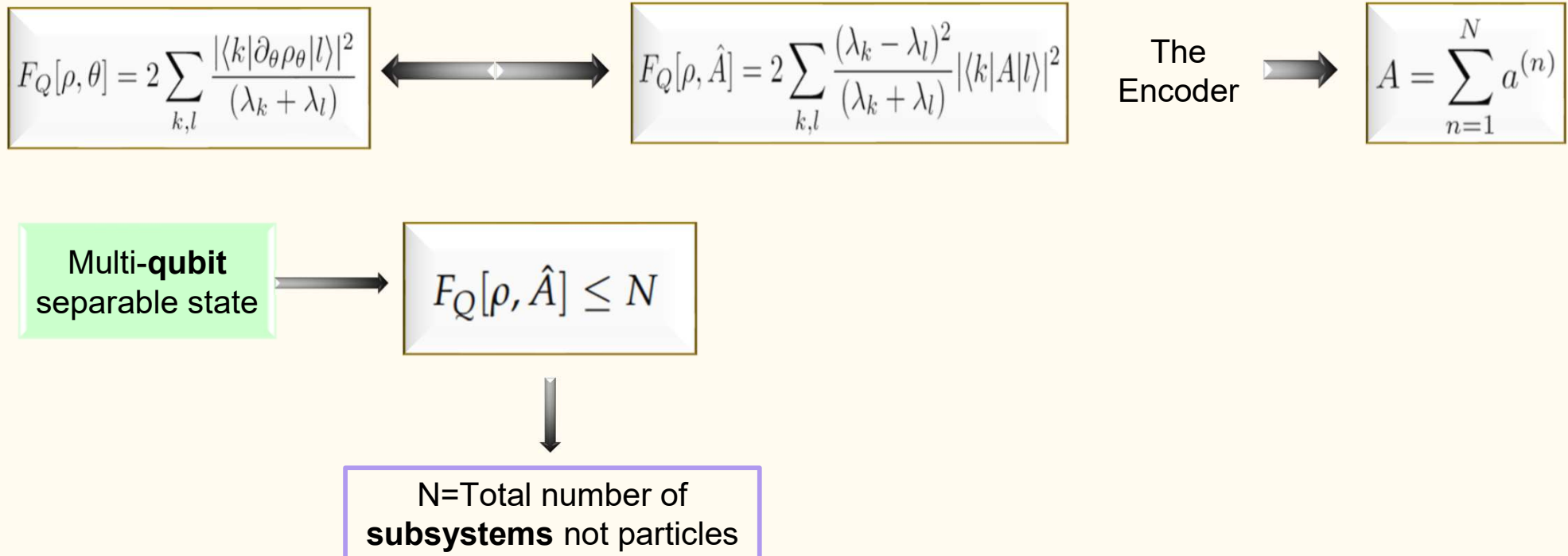
- We are focusing on single parameter estimation.

$$F_Q[\rho, \theta] = 2 \sum_{k,l} \frac{|\langle k | \partial_\theta \rho_\theta | l \rangle|^2}{(\lambda_k + \lambda_l)} \longleftrightarrow F_Q[\rho, \hat{A}] = 2 \sum_{k,l} \frac{(\lambda_k - \lambda_l)^2}{(\lambda_k + \lambda_l)} |\langle k | \hat{A} | l \rangle|^2$$

The Encoder \rightarrow $A = \sum_{n=1}^N a^{(n)}$

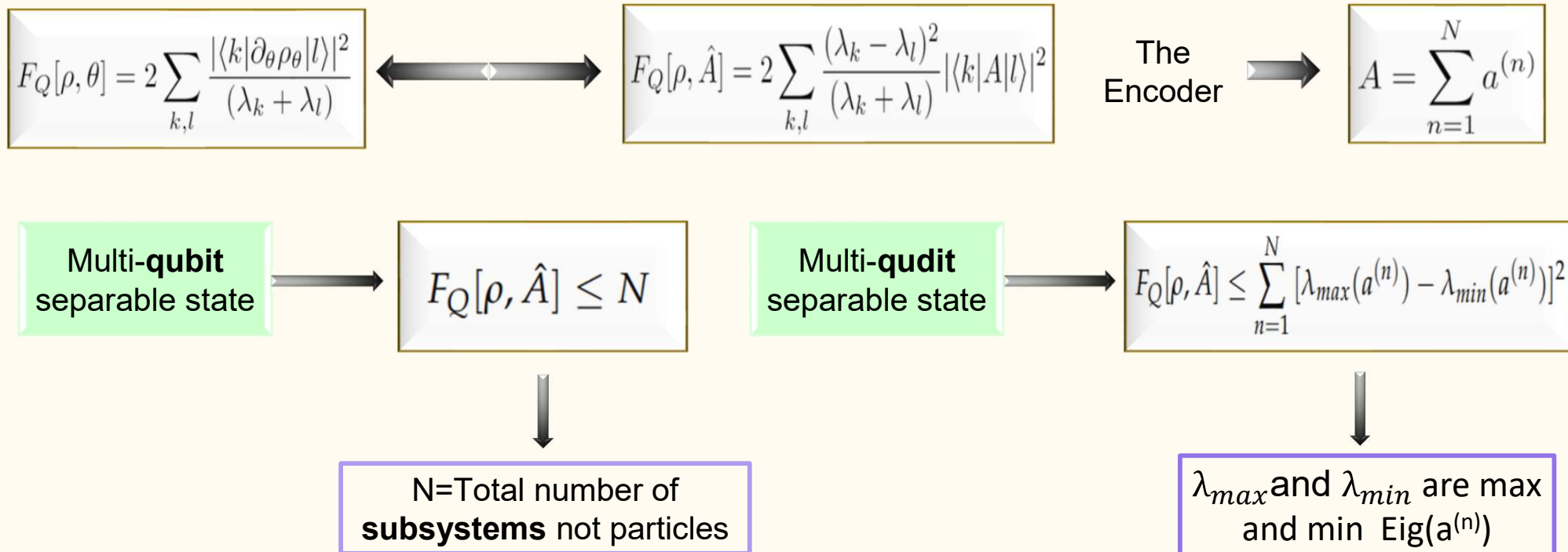
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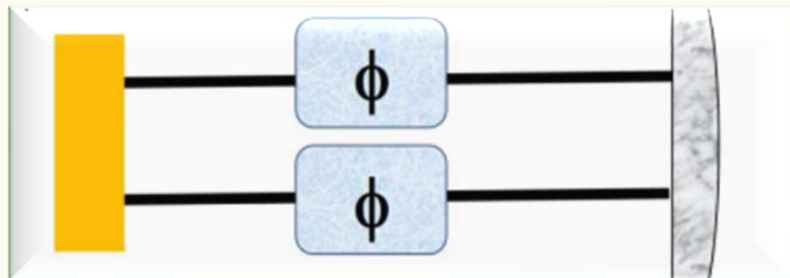
Parameter encoding schemes

$$D = \text{Diag}[1, 1, \dots, -1, -1]$$

- Further we'll only consider **Bipartite systems** of various dimensions

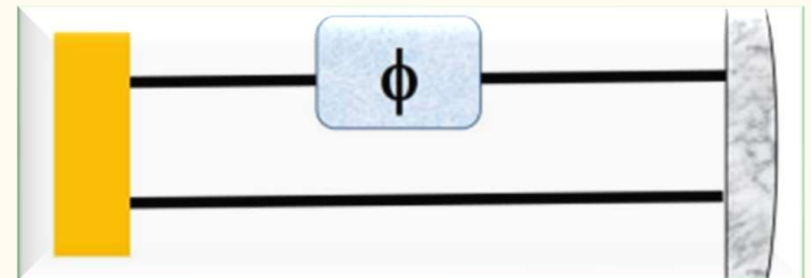
ENTANGLED ASSISTED STRATEGY

$$A = D \otimes I + I \otimes D$$



ANCILLA ASSISTED STRATEGY

$$A = D \otimes I \text{ or } I \otimes D$$

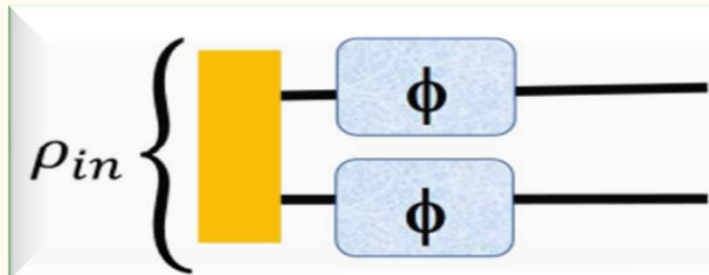


Adding Sequence to parameter encoding schemes

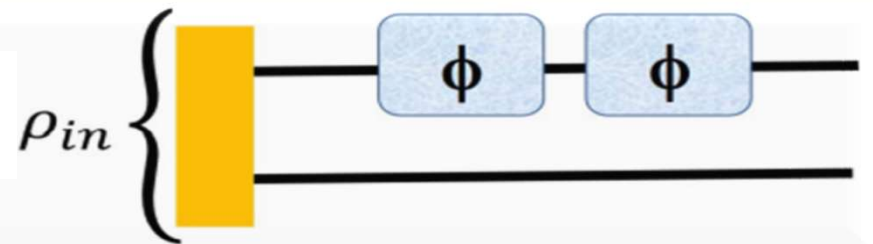
- Considering only **Bipartite systems** of various dimensions

ENTANGLED
ASSISTED STRATEGY

$$A = D \otimes I + I \otimes D$$



SEQUENTIAL ANCILLA
ASSISTED STRATEGY

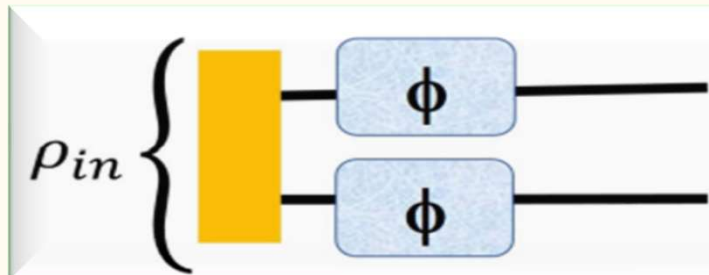


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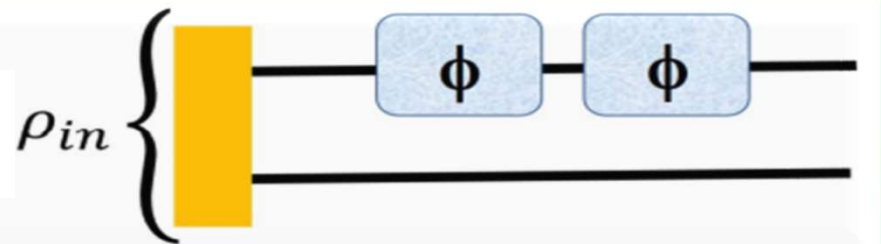
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Optimal probe state and optimal encoder

Quantum states with a positive partial transpose are useful for metrology

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¹*Department of Theoretical Physics, University of the Basque Country UPV/EHU, P.O. Box 644, E-48080 Bilbao, Spain*

²*IKERBASQUE, Basque Foundation for Science, E-48013 Bilbao, Spain*

³*Wigner Research Centre for Physics, Hungarian Academy of Sciences, P.O. Box 49, H-1525 Budapest, Hungary*

⁴*Institute for Nuclear Research, Hungarian Academy of Sciences, P.O. Box 51, H-4001 Debrecen, Hungary*

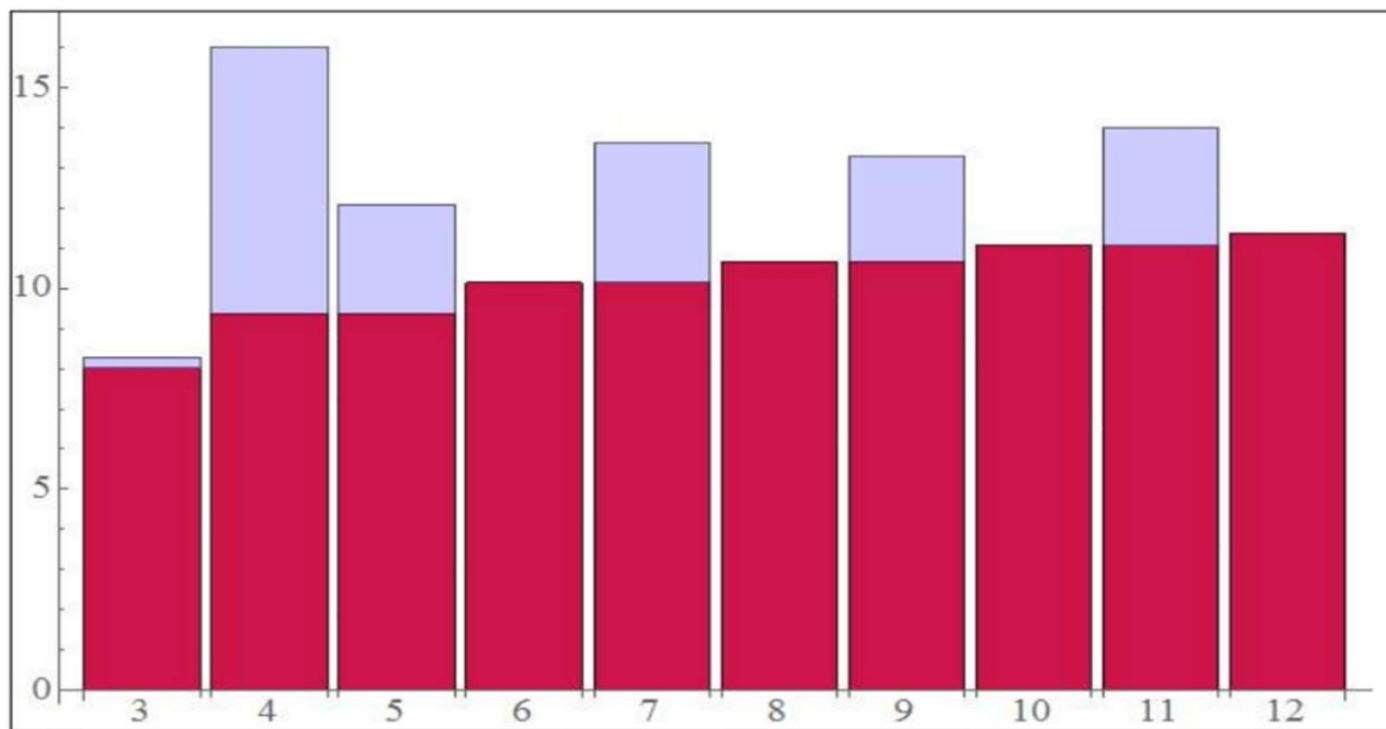
(Dated: April 27, 2018)

We show that multipartite quantum states that have a positive partial transpose with respect to all bipartitions of the particles can outperform separable states in linear interferometers. We introduce a powerful iterative method to find such states. We present some examples for multipartite states and examine the scaling of the precision with the particle number. Some bipartite examples are also shown that possess an entanglement very robust to noise. We also discuss the relation of metrological usefulness to Bell inequality violation. We find that quantum states that do not violate any Bell inequality can outperform separable states metrologically. We present such states with a positive partial transpose, as well as with a non-positive partial transpose.

(iii) We show an iterative method based on semidefinite programming (SDP) that can generate such states very efficiently. The method, starting from a given initial state, provides a series of PPT quantum states with a rapidly increasing metrological usefulness.

$$A = D \otimes I + I \otimes D$$

RESULT 1



X : Represents the PPT states $N \otimes N$, $N=3$ to 12

Y : Quantum Fisher information (QFI)

■ : QFI using $A = D \otimes I + D \otimes I$

■ : QFI using $A = D \otimes I + I \otimes D$

Why even dim. $4 \otimes 4$ is showing odd nature ?

- The family we are talking about here is different from the family of states found from SDP

5. A Family of Even Dimensional PPT States Having a Higher Fisher Information for Sequential Ancilla Assisted Strategy Compared to Entanglement Assisted Strategy

In this section we highlight the advantage of using the sequential ancilla assisted strategy by showing that the family of bipartite even dimensional states recently introduced in reference [17] shows an improvement in the Fisher information as compared to the entanglement assisted strategy. The family of $2d \times 2d$ dimensional states is given as:

$$\begin{aligned}
 \rho_{F1} = & \frac{p_1}{2d^2} \sum_{i,j=0}^{d-1} (|00ij\rangle\langle 00ij| + |11ij\rangle\langle 11ij|) \\
 & + \frac{p_1}{2d\sqrt{d}} \sum_{i,j=0}^{d-1} (u_{ij}|00ij\rangle\langle 11ji| + u_{ij}^*|11ji\rangle\langle 00ij|) \\
 & + \frac{p_2}{2d} \sum_{i=0}^{d-1} (|01ii\rangle\langle 01ii| + |10ii\rangle\langle 10ii|) \\
 & + \frac{p_2}{2d} \sum_{i,j=0}^{d-1} (u_{ij}|01ii\rangle\langle 10jj| + u_{ij}^*|10jj\rangle\langle 01ii|)
 \end{aligned} \tag{17}$$

Parameter encoding schemes with Multiple Sequences

- Considering only **Bipartite systems** of various dimensions

SEQUENTIAL ENTANGLED ASSISTED STRATEGY

$$A = (D \otimes I + I \otimes D) + (D \otimes I + I \otimes D)$$

SEQUENTIAL ANCILLA ASSISTED STRATEGY

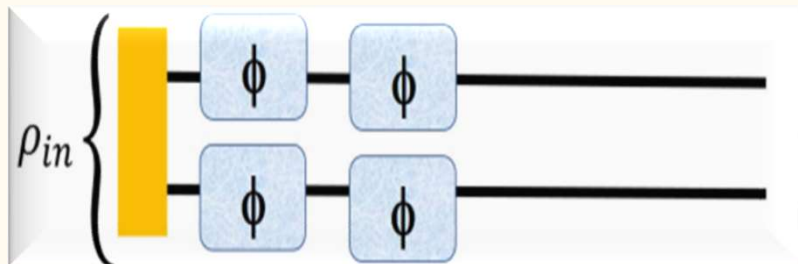
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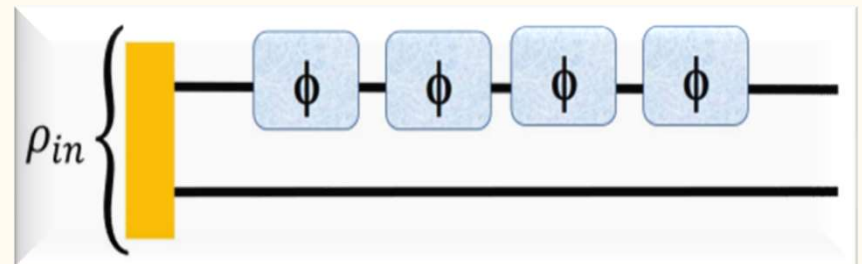
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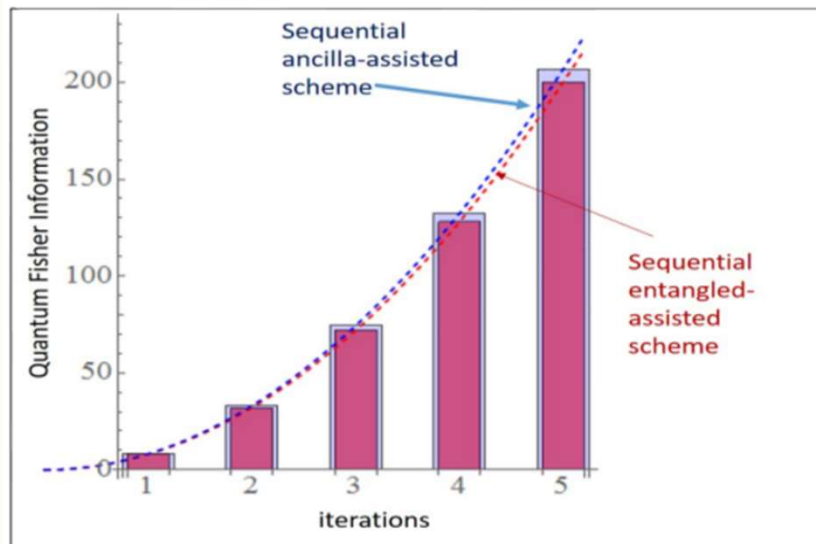


SEQUENTIAL ANCILLA ASSISTED STRATEGY

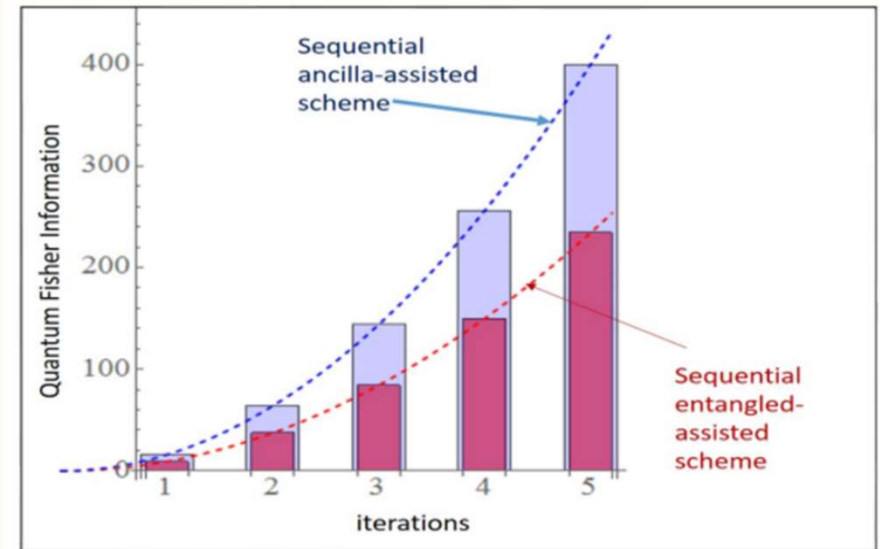
$$A = (D \otimes I + D \otimes I) + (D \otimes I + D \otimes I)$$



RESULT 2



$3 \otimes 3$



$4 \otimes 4$

Blue bar: QFI using $A = D \otimes I + D \otimes I + \dots$ [10 iterations in total]

Red bar: QFI using $A = (D \otimes I + I \otimes D) + (D \otimes I + I \otimes D) + \dots$ [5 term iterations in total]

Advantage of having sequences

Considering F_Q^0 is the fisher information at the initial point without any sequence or repetition

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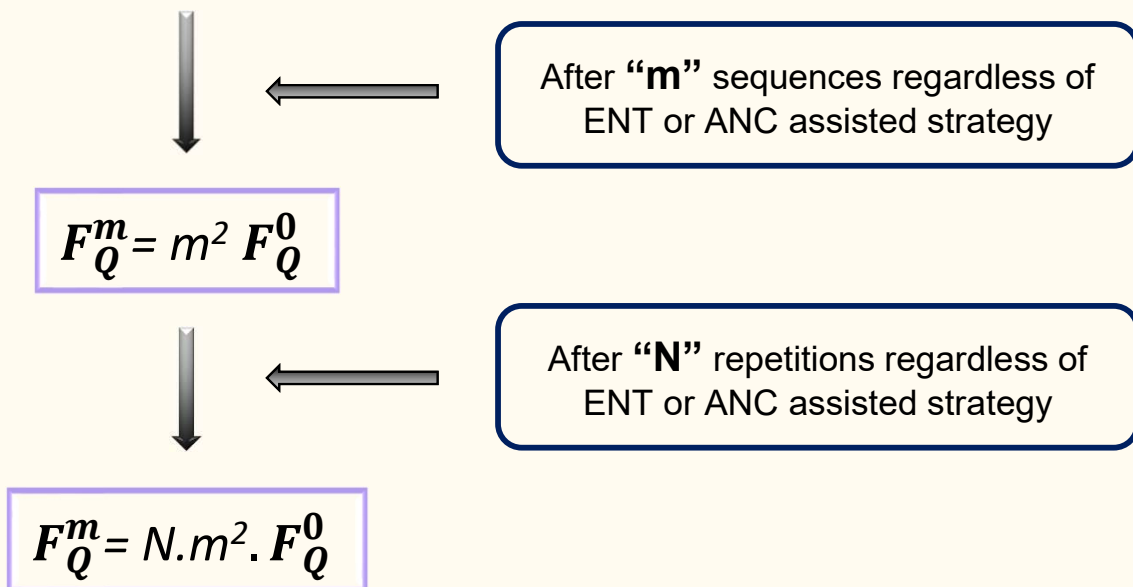


After “**m**” sequences regardless of ENT or ANC assisted strategy

$$F_Q^m = m^2 F_Q^0$$

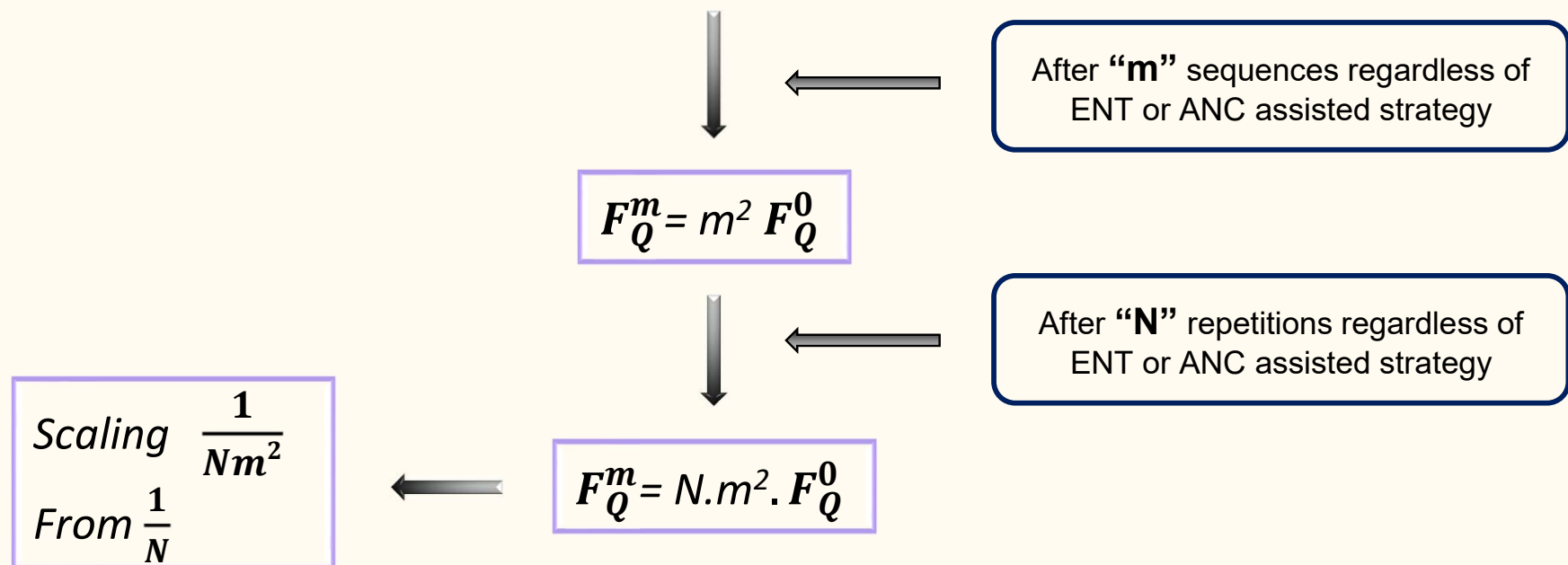
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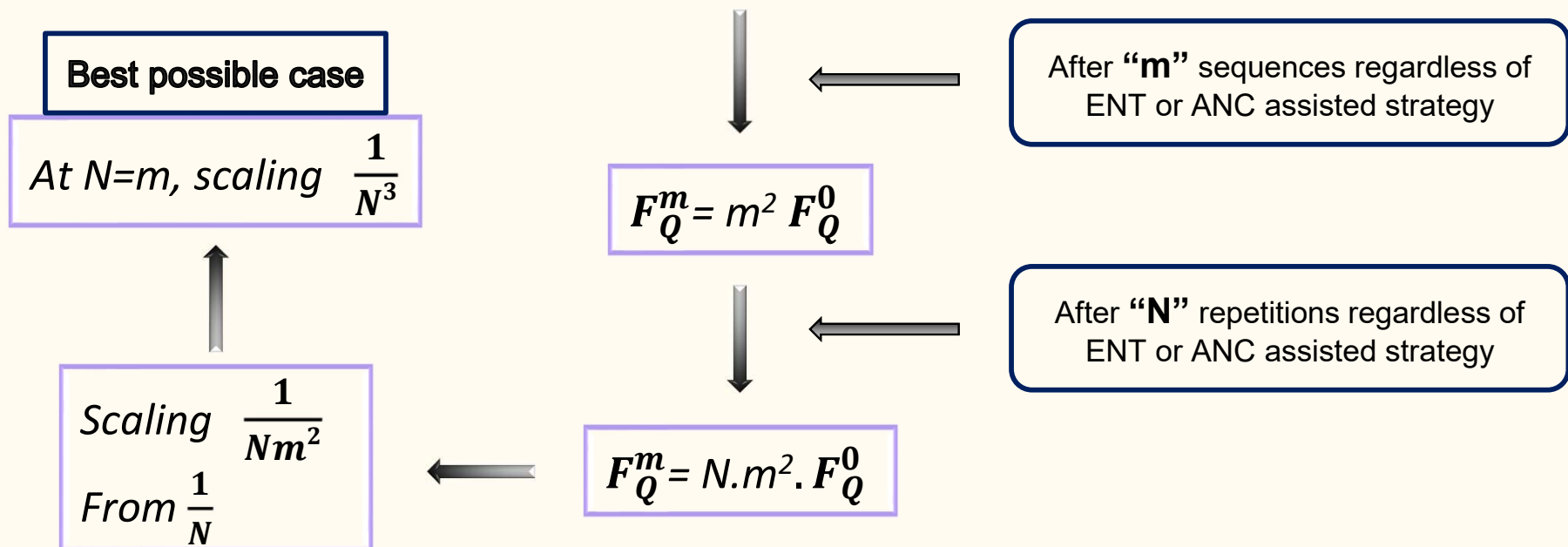
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Applications

- Magnetometry: Magnetometry allows one to measure the magnetic field precisely by measuring the phase shift of the particles due to magnetic field (as particles are waves). If the particles are entangled, precision of this measurement will improve  [Quantum enhanced magnetometry](#)
- LIGO Gravitational wave detection: To improve the sensitivity of laser light, it is prepared in squeezed state which is less sensitive to noise. Thus can perform precise measurement of the periodic distortion of space and time.
- Thermometry

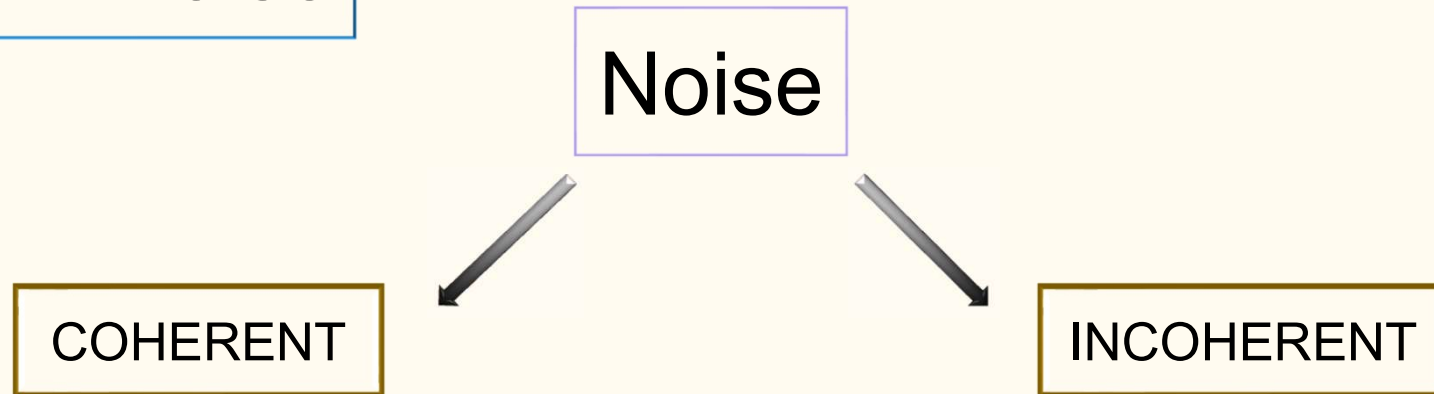
Noisy Quantum Channels and their effects

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Quantum Noise

Noise

Quantum Noise



Quantum Noise

Noise

```
graph TD; Noise[Noise] --> COHERENT[COHERENT]; Noise --> INCOHERENT[INCOHERENT];
```

COHERENT

- Due to miscalibrations, crosstalk in hardware / experimental setup.
- Maintains coherence, results in an under or over rotation

INCOHERENT

- Due to interaction of physical system with noisy environment.
- Doesn't maintain quantum coherence
- Example: Depolarizing channel.....

Incoherent Quantum Noise

Noisy channel /
CPTP map

Incoherent Quantum Noise

Noisy channel /
CPTP map



$$\epsilon[\rho_{in}] = \rho_{out} = \sum_i K_i \rho_{in} K_i^\dagger$$

Incoherent Quantum Noise

Noisy channel /
CPTP map



$$\epsilon[\rho_{in}] = \rho_{out} = \sum_i K_i \rho_{in} K_i^\dagger$$



Depolarizing Noisy channel

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Depolarizing Noisy channel

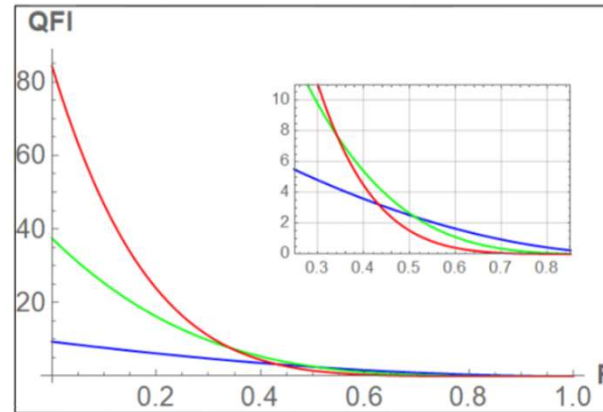
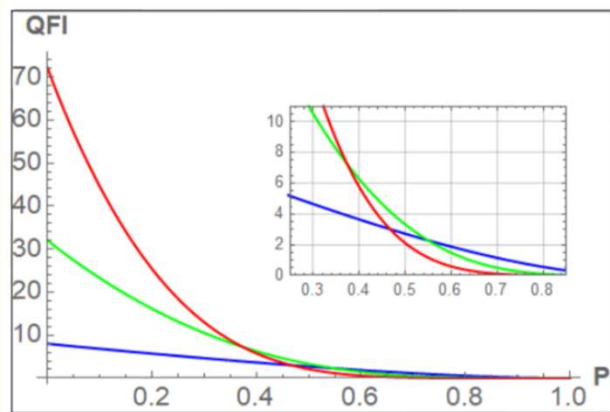
Asymmetric

$$\epsilon[\rho] = (1 - p_1 - p_2 - p_3)\rho + p_1(\sigma_x \rho \sigma_x^\dagger) + p_2(\sigma_y \rho \sigma_y^\dagger) + p_3(\sigma_z \rho \sigma_z^\dagger)$$

Symmetric

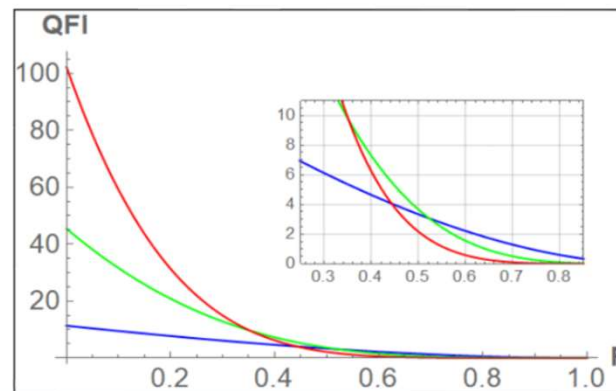
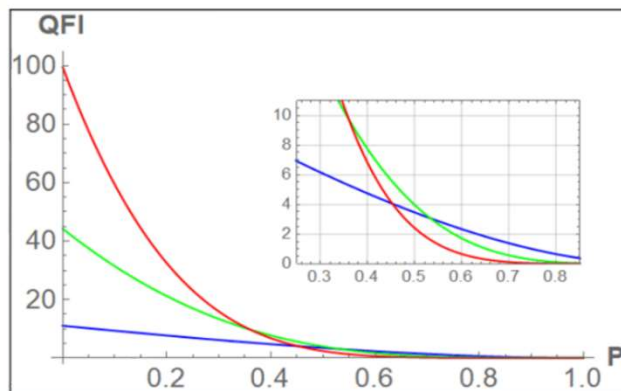
$$\epsilon[\rho] = (1 - p)\rho + p \frac{I}{d}$$

Results including noise



$3 \otimes 3$ and $4 \otimes 4$
respectively

For a total 3
sequences



$11 \otimes 11$ and $12 \otimes 12$
respectively

Selected in International conferences

- QuApps 2021 (International Conference on Applications of Quantum Technologies).
- IEEE international conference for quantum computing (among one of the 30 posters selected from all over the world).
- WE-Heraeus-Seminar, an international seminar on "Sensing with Quantum Light".
- Institute of Physics Singapore (IPS meeting 2021) annual international conference.

THANK YOU SO MUCH!

Experimental Realization

- Various convex sets of quantum states represented by circles: (P) PPT states, (M) states that are not useful for metrology, (S) separable states, (L) states with a local hidden variable model. (grey area) Metrologically useful PPT states. Such states are in $P \setminus M$, where “\” denotes the difference between two sets.

