Written Contract

Upon completion, our robot should be able to achieve the following in a specific session:

1. The robot will start at a starting base location.
2. The robot will recognize the specific plants that need watering and start moving towards one of them.
3. The robot then navigates towards the specified plant autonomously, without user input.
4. Once the robot reaches the plant, it will dispense a specific quantity of water to the specific plant.
5. After the robot has finished watering a plant, it navigates to the next plant if applicable, and repeats steps 4 and 5 for all plants.
6. After the robot is finished with watering the different plants that needed to be watered, the robot will autonomously navigate back to the starting base location.