## **Department of Computer Engineering**

## T.E. (Computer Sem VI) Assignment -1 Artificial Intelligence (CSC604)

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CO Addressed:—CSC604.1 -To conceptualize the basic ideas and techniques underlying the design of intelligent systems.

## **Assignment 1:**

- 1. Explain the concept of rationality in the context of intelligent agents. How does rationality relate to the behavior of agents in their environments? Provide examples to illustrate your explanation.
- 2. Discuss the nature of environments in which intelligent agents operate. What are the key characteristics that define an environment, and how do they influence the design and behavior of agents? Provide examples of different types of environments and the challenges they present to agents.
- 3. Describe the structure of intelligent agents and the types of agents commonly used in artificial intelligence. What are the components of an agent, and how do they interact to achieve intelligent behavior? Provide examples of different types of agents and their applications in real-world scenarios.
- 4. Outline the process of problem-solving by searching, including the role of problem-solving agents and the formulation of problems. How do problem-solving agents analyze and approach problems, and what methods do they use to search for solutions? Illustrate your explanation with examples of problem-solving tasks and the strategies employed by agents to solve them.

## Rubrics for the First Assignments:

Indicator	Average	Good	Excellent	Marks
Organization (2)	Readable with some missing points and structured (1)	Readable with improved points coverage and structured (1)	Very well written and fully structured	
Level of content(4)	All major topics are covered, the information is accurate (2)	Most major and some minor criteria are included. Information is accurate (3)	All major and minor criteria are covered and are accurate (4)	
Depth and breadth of discussion and representation(4)	Minor points/information maybe missing and representation isminimal (1)	Discussion focused on some points and covers themadequately (2)	Information is presented indepth and is accurate (4)	
Total				

Signature of the Teacher

2830

Assignment-I

Q1)
Rationality refers to the obility of an agent to make decisions that are excepted to maximize its change of achieving its goals given the available into and resources. A rational agent is one that chaoses consistency actions that are optimal or near

optimol.

Here's how rationality relates to agent behaviour.
I) Goal directed behaviour. Rational agents are
driven by goals or objectives they alm to achieve
Their acheive are selected based on their assessment

of how likely those actions are to bring them closer to their goals

2) Decision making under uncertainity. In many real would scenarios agents don't have complete information about their environment or the outcomes of their action. Rational agents make decision

for weighing the available evidence and assessing

the probablities of different outcomes

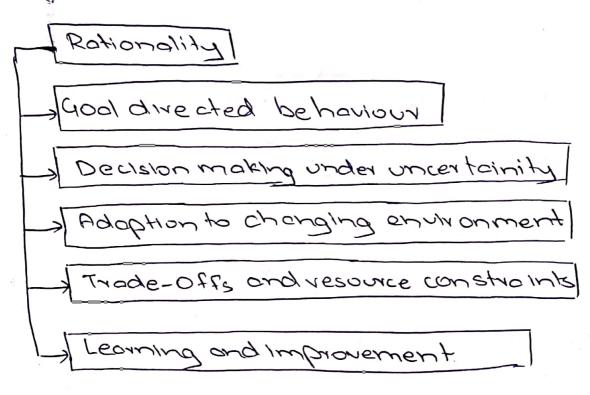
3) Adoption to changing environments. Ethironnents of the often dynamic and rational agents need to adopt this behaviour. Occordingly-This adaption involves continuously updating their beliefs and

strategies based on new information and strate-

gies.

Trade offs and resources constraints! Rational agents must often make trade offs due to limited resources such as time energy or expected to yield highest utility or payoff

5) Learning and improvement: Rational learn from past experiences to improve their future decision making. This learning process involves identifying patterns in date adjusting strategies and refining the models of the environment



(2)
The nature of environments in which intelligent agents operate varies widely depending on application domain. However there are several key characteristics that define an environment and significantly influence the design and behaviour

et gagents		
CHARACTERSTICS	DESCRIPTION	EXAMPLES
Observable	Whether agents have	Chess (fully observ-
2		oble) selfdriving
	information about the	
~~	state of environment	
Deterministic		Chess (de termin-
· .	of action is entirely	
	predictable or if there	1
		chastic
	incertainty in the	
	outcomes	
Episode	Whether each inte-	Chess (episodic)
	raction between.	Moze now gotion.
	the agent and the	(Sequential)
· · ·	environment is self	<b>Y</b>
1. 2.3.	contained or if there	
y .1° '-' y	is a sequence of	
	actions and states	1
Dynamic	whether the en uron	- Financial markets
	ment change over	(dynamic) Roboti
	time with response	
	to agent actions or	
·	external factors	7
Discrete	whether the state	Board games alisa
	and action spaces	etc) Robotics (con
	ore Finite or court	tinuous)
	Minik	( ) ( ) ( )

Examples of diff types of environments and challerges they present challenges for agents.

EMIRONMENT	EXAMPLE	CHALLENGES FOR ACENB.
Board games	chess, go	Vast search, space, optimal.
	Manufacturing floors	blectsion making uncertain.  114  Sersor preception, poth.  Planning, Object manipublion
Notural language	Text/speech	contexted understanding
processing	recognition	ombiguity resolution

The typical components of an intelligent thagent Include:

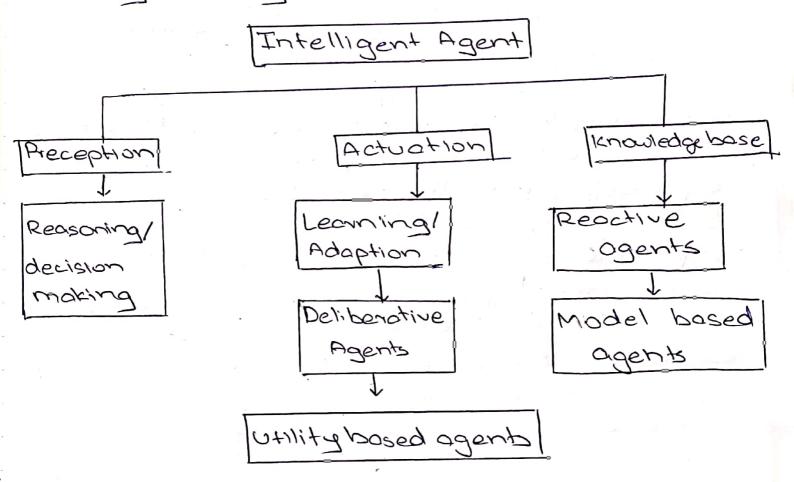
03)

- DPerception! This component is responsible for sensing and precieving the environment. It gathers information from sensors which could be physical sensors like comerces and microphones in reactions. Or abstract sensors like data input in software.
- 2) Actuation: The actuation component stored the agent to interact with the environment. It consists of effectors which ove me chanisms through which the agent can exert control over influence. it corroundings.

3) knowledge base: This component stores the agent. internal represention of the world including its balief, goals, plans and past experiences. The knowledge Base is essential for decision making and guiding the agents behaviour WRecsoning: The reasoning component processes informotion from the preception modile and the knowledge base to make decisions and choose decisions that are expected to acheive the agents goals. s) Leoning/ Adoption: Intelligent agents can learn from experience and adopt their behaviour over time. Some common types of agents can leave from experience and adapt their behaviour over time Some common types of agents used in AI with their opplications 1) Reactive gents: These agents make decisions bosed solely on the current precept. They don't maintain on internal state or modele of 2) Delibrate agents: Delibrate agents maintain an explicit model of the anvivonment which they use to simulate possible future states and out-49 000 3) Model based agents: Model based agents maintain on explicit model of the enworment, which they use to smulate possible future state and atcomes 4) Utitity based agents: These agents make decisions

by evaluating the utility or desirability of different. actions and selections the one that maximizes expected utility.

5) Learning agents: Improve then performance over time by learning from experience



Outline of process of problem solving by searching Driblem formulation: Problem solving agents begin by defuning the problem they need to solve This involves indentifying the initial state , the possible actions or operators available to the agent. The goal state or state that the agent aim.

2) Problem stat representation: Once the problem is formulated problem solving agents represent it in

a suitable marrier formalism such as a state space a graph or a set of logical propositions 3) Search Strategy: 2 selection: Problem solving agents then choose a search strategy to explore the problem space and find a solution 4) search process: Begins the sourch process from the Initial state and systematically explores the problem space by opplying the choosen search strategy s) Solution reconstruction: Once a goal state is reached the problem solving agent reconstruct. the adution path by tracing back, through the sequence of actions or states that lead to the gool. Illustrative example: D Pathfinding in maze Problem formulation: Initial state (starting position in the maze) cetions (movement in four directionsup down left, right) goal state coestination in the mare · problem representation: State space representation where each state corresponds to a position in the maze ·Search strategy: Depth first search or breadth first search to explore the maze by moving from one position to another, avoiding obstacles until it reaches the goal position.

Problem formulation

Problem Representation

Search Strategy selection

Search Process

Solution Reconstruction