NASA: Optimization to Surface planning and Scheduling

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Motivation



"Flight delays cost the airline industry \$8 billion a year"



"Reduce Airlines' carbon footprint"

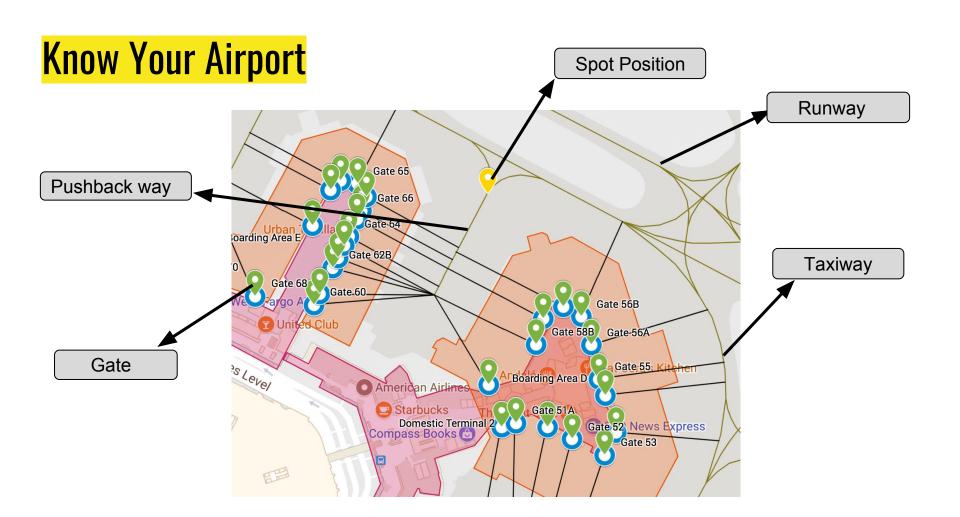


"Reduce probability of human error."

Problem

Goals

- To create a generic airport simulation tool
- To add uncertainty into simulation and to analyze the <u>performance and</u>
 <u>robustness</u> of different scheduling algorithms
- To explore different auto-scheduling methods and to compare with current FCFS method.



Structure

Scheduler

Uncertainty Module

Simulation

Data (Surface Data, Scenario)

Simulation

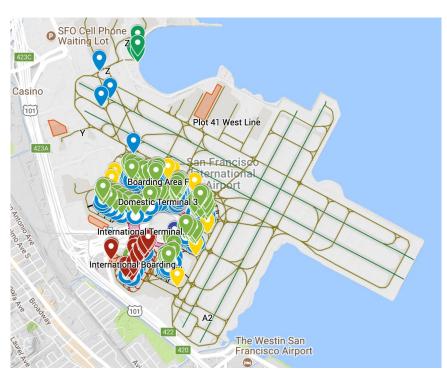
A generic airport simulation written in Python

Designs an airport simulation works for multiple airports sharing the same link-node model

Works with an external scheduler in runtime, and be able to show performances

Be extensible for adding new constraints, features in the future

Data



1. San Francisco Airport Data

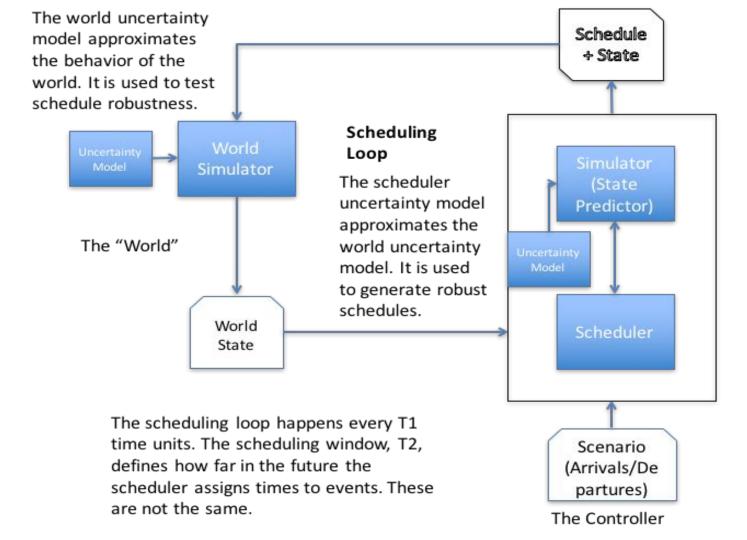
a. Open Street Data

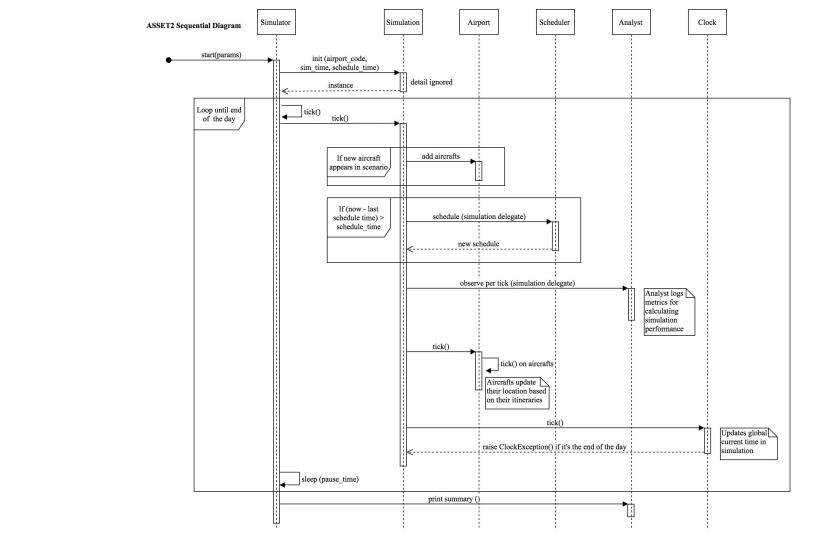
2. Simple Test Data

a. Automatically generated scenarios



Flow





Scheduler

A scheduler for aircraft routes written in Python

Repeatedly generates schedules for aircrafts that enter the airport during the day

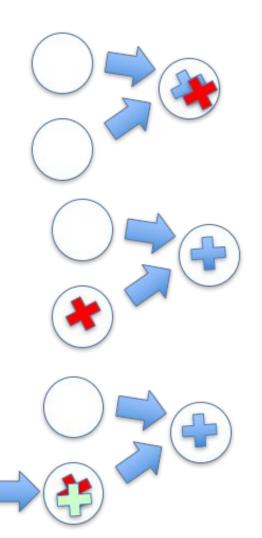
Ensure that the schedules generated are free of conflicts in the absence of uncertainty

Use the simulation to predict possible airport state in the future, and relax tightness at possible bottlenecks

Scheduler Optimization

Un-serviced requests (scenario) System Snapshot (aa4, G34, 4R, 0700) Scheduled Future Unscheduled Future Now Past (ua39,G2, 3L, 0730) (sa32,G15, 3C,2100) Time 0 Schedule Horizon Flex horizon Schedule

Conflicts

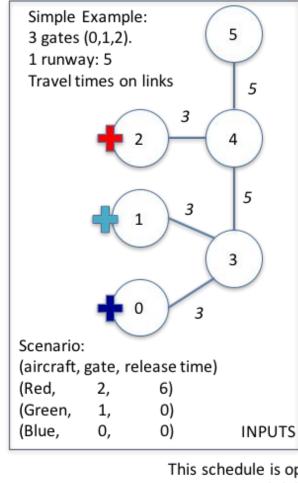


Definition of Conflict: Two aircraft occupy same position at same time.

Solution: Delay one of the aircraft at previous location.

Note: Inserting delays might cause other conflicts, either forward or backward in time.

A Simple Example



Predefined Routes

Blue: 0,3,4,5

Green: 1,3,4,5

Red: 2,4,5

Scheduling with conflict detection and resolution

Format: Time n: {(aircraft, locations)}

Time 0: (Blue,0), (Green,1)

Time 3: (Blue,3), (Green, 3) Conflict

Time 1: (Green,1) (Delay Green at previous location)

Time 4: (Green,3)

Time 6: (Red, 2)

Time 8: (Blue, 4)

Time 9: (Red,4), (Green,4) Conflict Time 7: (Red,2) (Delay Red at previous location)

Time 10: (Red, 4)

Time 13: (Blue, 5) Time 14: (Green, 5)

Time 15: (Red,5)

This schedule is optimal for the scenario. Total delay time: 2;

Final Schedule

Format: flight: {(location, time)} Blue: (0,0),(3,3),(4,8),(5,13)

Green: (1,1),(3,4),(4,9),(5,14) Red: (2,7),(4,10),(5,15)

makespan: 15

Uncertainty Module

A module for simulating real-world uncertainty.

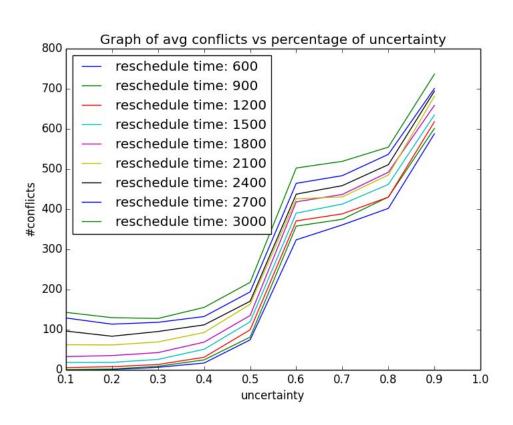
A generic module for uncertainty that can take into account multiple factors for calculating uncertainty.

Integrates with external scheduler and simulator in runtime.
Controllable by user to inject randomness.

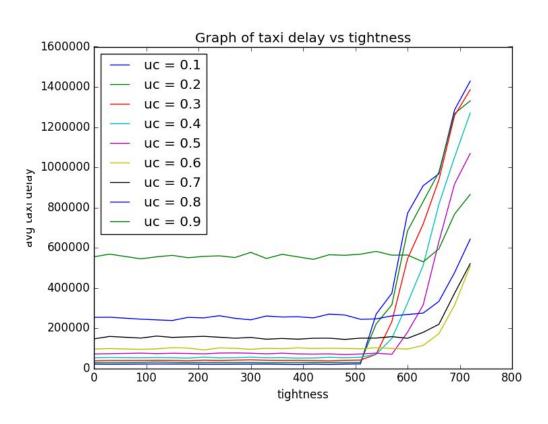
Takes into account terminal uncertainty at gates and runways.

Experiment

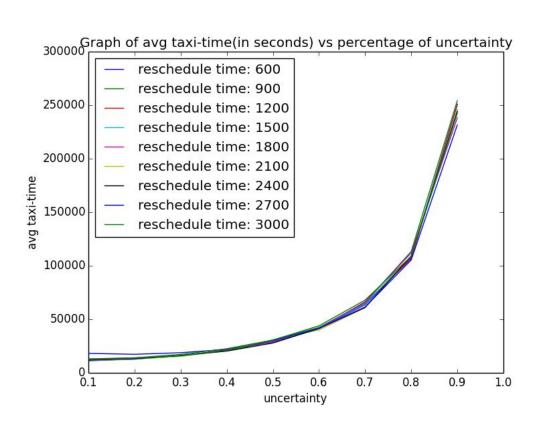
Experiment 1 : Conflicts v.s. Uncertainty

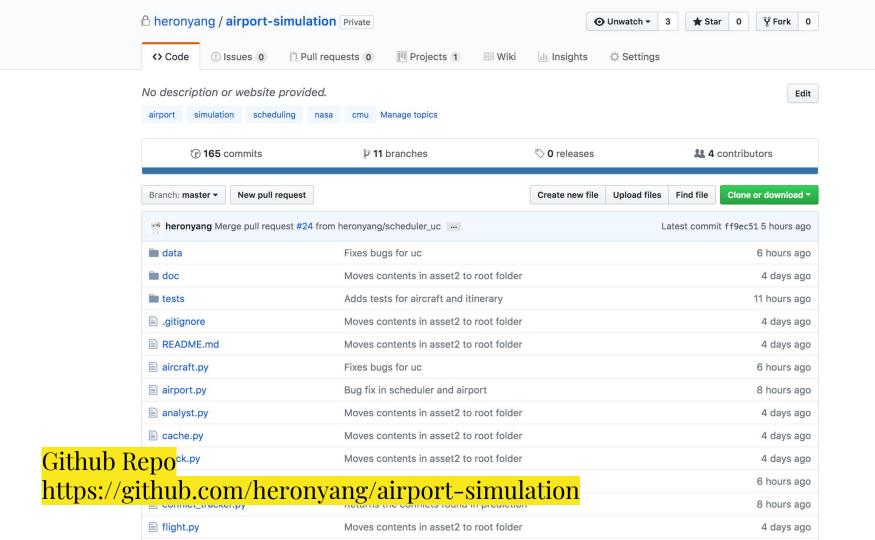


Experiment 2 : Taxi Delay v.s. Tightness



Experiment 3 : Taxi Delay v.s. Uncertainty





Demo

House, etc.

t on <Aircroft: F6>>: It's too early to start f conflicts found: 0 ent Time: 00:50:00 based_on_scenario:120] Adds flight «Departure 37.412284,-122.054973> runway:<RUNWAY: R1> ti

-Aircraft: F7> changed location to <Node: G</p>

aft (<Alrcraft: F6>) location: ⊲Node: G1:37.4
] ⊲Aircraft: F6> changed location to ⊲Node: G
o_next_target_node:147] ⊲Pilot on ⊲Aircraft:

o_next_target_node:147] <Pilot on <Aircraft: 26,-122:057451> | exp arrive at 00:48:00 | ex uft (<Aircraft: F7>) location: <Node: G2(37.4

,-122,057451> | exp arrive at 00:48:00 | exp

«Aircraft: F6» changed location to «Node: N

t on <Aircraft: F7>>: No on-going itinerary r