linear regression with synthetic data

August 19, 2021

```
[10]: from jupyterthemes import jtplot
    jtplot.style()

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```

1 Simple Linear Regression with Synthetic Data

In this first Colab, you'll explore linear regression with a simple database.

1.1 Learning objectives:

After doing this exercise, you'll know how to do the following:

- Run Colabs.
- Tune the following hyperparameters:
 - learning rate
 - number of epochs
 - batch size
- Interpret different kinds of loss curves.

1.2 About Colabs

Machine Learning Crash Course uses Colaboratories (**Colabs**) for all programming exercises. Colab is Google's implementation of Jupyter Notebook. Like all Jupyter Notebooks, a Colab consists of two kinds of components:

• Text cells, which contain explanations. You are currently reading a text cell.

• Code cells, which contain Python code for you to run. Code cells have a light gray background.

You read the text cells and run the code cells.

1.2.1 Running code cells

You must run code cells in order. In other words, you may only run a code cell once all the code cells preceding it have already been run.

To run a code cell:

- 1. Place the cursor anywhere inside the [] area at the top left of a code cell. The area inside the [] will display an arrow.
- 2. Click the arrow.

Alternatively, you may invoke **Runtime->Run all**. Note, though, that some of the code cells will fail because not all the coding is complete. (You'll complete the coding as part of the exercise.)

1.2.2 Understanding hidden code cells

We've hidden the code in code cells that don't advance the learning objectives. For example, we've hidden the code that plots graphs. However, you must still run code cells containing hidden code. You'll know that the code is hidden because you'll see a title (for example, "Load the functions that build and train a model") without seeing the code.

To view the hidden code, just double click the header.

1.2.3 Why did you see an error?

If a code cell returns an error when you run it, consider two common problems:

- You didn't run all of the code cells preceding the current code cell.
- If the code cell is labeled as a **Task**, then you haven't written the necessary code.

1.3 Use the right version of TensorFlow

The following hidden code cell ensures that the Colab will run on TensorFlow 2.X, which is the most recent version of TensorFlow:

```
[2]: #@title Run this Colab on TensorFlow 2.x
# %tensorflow_version 2.x
```

1.4 Import relevant modules

The following cell imports the packages that the program requires:

```
[3]: import pandas as pd
import tensorflow as tf
from matplotlib import pyplot as plt
```

1.5 Define functions that build and train a model

The following code defines two functions:

- build_model(my_learning_rate), which builds an empty model.
- train_model(model, feature, label, epochs), which trains the model from the examples (feature and label) you pass.

Since you don't need to understand model building code right now, we've hidden this code cell. You may optionally double-click the headline to explore this code.

```
[4]: #@title Define the functions that build and train a model
     def build_model(my_learning_rate):
       """Create and compile a simple linear regression model."""
       # Most simple tf.keras models are sequential.
       # A sequential model contains one or more layers.
      model = tf.keras.models.Sequential()
       # Describe the topography of the model.
       # The topography of a simple linear regression model
       # is a single node in a single layer.
       model.add(tf.keras.layers.Dense(units=1,
                                       input shape=(1,)))
       # Compile the model topography into code that
       # TensorFlow can efficiently execute. Configure
       # training to minimize the model's mean squared error.
      model.compile(optimizer=tf.keras.optimizers.
      →RMSprop(learning_rate=my_learning_rate),
                     loss="mean squared error",
                     metrics=[tf.keras.metrics.RootMeanSquaredError()])
       return model
     def train model(model, feature, label, epochs, batch size):
       """Train the model by feeding it data."""
       # Feed the feature values and the label values to the
       # model. The model will train for the specified number
       # of epochs, gradually learning how the feature values
       # relate to the label values.
      history = model.fit(x=feature,
                           y=label,
                           batch_size=None,
                           epochs=epochs)
       # Gather the trained model's weight and bias.
       trained_weight = model.get_weights()[0]
```

```
trained_bias = model.get_weights()[1]

# The list of epochs is stored separately from the
# rest of history.
epochs = history.epoch

# Gather the history (a snapshot) of each epoch.
hist = pd.DataFrame(history.history)

# Specifically gather the model's root mean
#squared error at each epoch.
rmse = hist["root_mean_squared_error"]

return trained_weight, trained_bias, epochs, rmse

print("Defined create_model and train_model")
```

Defined create_model and train_model

1.6 Define plotting functions

We're using a popular Python library called Matplotlib to create the following two plots:

- a plot of the feature values vs. the label values, and a line showing the output of the trained model.
- a loss curve.

We hid the following code cell because learning Matplotlib is not relevant to the learning objectives. Regardless, you must still run all hidden code cells.

```
[5]: #@title Define the plotting functions
def plot_the_model(trained_weight, trained_bias, feature, label):
    """Plot the trained model against the training feature and label."""

# Label the axes.
plt.xlabel("feature")
plt.ylabel("label")

# Plot the feature values vs. label values.
plt.scatter(feature, label)

# Create a red line representing the model. The red line starts
# at coordinates (x0, y0) and ends at coordinates (x1, y1).
x0 = 0
y0 = trained_bias
x1 = my_feature[-1]
y1 = trained_bias + (trained_weight * x1)
plt.plot([x0, x1], [y0, y1], c='r')
```

```
# Render the scatter plot and the red line.
plt.show()

def plot_the_loss_curve(epochs, rmse):
    """Plot the loss curve, which shows loss vs. epoch."""

plt.figure()
plt.xlabel("Epoch")
plt.ylabel("Root Mean Squared Error")

plt.plot(epochs, rmse, label="Loss")
plt.legend()
plt.ylim([rmse.min()*0.97, rmse.max()])
plt.show()

print("Defined the plot_the_model and plot_the_loss_curve functions.")
```

Defined the plot_the_model and plot_the_loss_curve functions.

1.7 Define the dataset

The dataset consists of 12 examples. Each example consists of one feature and one label.

```
[6]: my_feature = ([1.0, 2.0, 3.0, 4.0, 5.0, 6.0, 7.0, 8.0, 9.0, 10.0, 11.0, 12.0])
my_label = ([5.0, 8.8, 9.6, 14.2, 18.8, 19.5, 21.4, 26.8, 28.9, 32.0, 33.8, 19.3 and 19.5 are represented by the second s
```

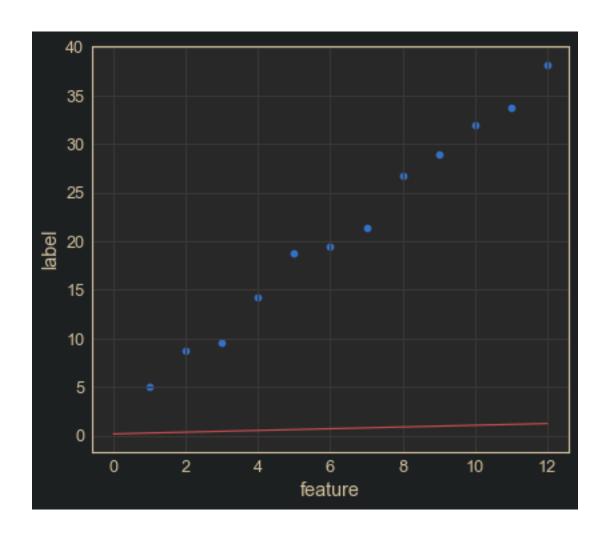
1.8 Specify the hyperparameters

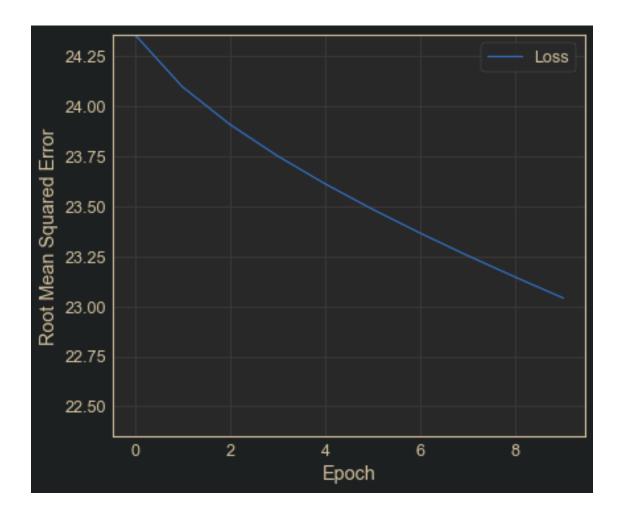
The hyperparameters in this Colab are as follows:

- learning rate
- epochs
- batch size

The following code cell initializes these hyperparameters and then invokes the functions that build and train the model.

```
Epoch 1/10
root_mean_squared_error: 24.3566
Epoch 2/10
1/1 [============ ] - Os 3ms/step - loss: 580.6030 -
root_mean_squared_error: 24.0957
Epoch 3/10
root_mean_squared_error: 23.9074
Epoch 4/10
1/1 [============ ] - Os 4ms/step - loss: 564.0753 -
root_mean_squared_error: 23.7503
Epoch 5/10
1/1 [============ ] - Os 4ms/step - loss: 557.4833 -
root_mean_squared_error: 23.6111
Epoch 6/10
root_mean_squared_error: 23.4838
Epoch 7/10
1/1 [============ ] - Os 3ms/step - loss: 545.9219 -
root_mean_squared_error: 23.3650
Epoch 8/10
1/1 [=========== ] - Os 3ms/step - loss: 540.6804 -
root_mean_squared_error: 23.2525
Epoch 9/10
root_mean_squared_error: 23.1451
Epoch 10/10
1/1 [========== ] - Os 3ms/step - loss: 530.9139 -
root_mean_squared_error: 23.0416
C:\Users\Arunabh\anaconda3\envs\mlcc\lib\site-
packages\numpy\core\ asarray.py:136: VisibleDeprecationWarning: Creating an
ndarray from ragged nested sequences (which is a list-or-tuple of lists-or-
tuples-or ndarrays with different lengths or shapes) is deprecated. If you meant
to do this, you must specify 'dtype=object' when creating the ndarray
 return array(a, dtype, copy=False, order=order, subok=True)
```





1.9 Task 1: Examine the graphs

Examine the top graph. The blue dots identify the actual data; the red line identifies the output of the trained model. Ideally, the red line should align nicely with the blue dots. Does it? Probably not.

A certain amount of randomness plays into training a model, so you'll get somewhat different results every time you train. That said, unless you are an extremely lucky person, the red line probably doesn't align nicely with the blue dots.

Examine the bottom graph, which shows the loss curve. Notice that the loss curve decreases but doesn't flatten out, which is a sign that the model hasn't trained sufficiently.

1.10 Task 2: Increase the number of epochs

Training loss should steadily decrease, steeply at first, and then more slowly. Eventually, training loss should eventually stay steady (zero slope or nearly zero slope), which indicates that training has converged.

In Task 1, the training loss did not converge. One possible solution is to train for more epochs.

Your task is to increase the number of epochs sufficiently to get the model to converge. However, it is inefficient to train past convergence, so don't just set the number of epochs to an arbitrarily high value.

Examine the loss curve. Does the model converge?

```
[13]: learning_rate=0.01
    epochs= 200
            # Replace ? with an integer.
    my_batch_size=12
    my_model = build_model(learning_rate)
    trained_weight, trained_bias, epochs, rmse = train_model(my_model, my_feature,
                                          my_label, epochs,
                                          my batch size)
    plot_the_model(trained_weight, trained_bias, my_feature, my_label)
    plot_the_loss_curve(epochs, rmse)
   Epoch 1/200
   root_mean_squared_error: 12.1243
   Epoch 2/200
   1/1 [============= ] - Os 4ms/step - loss: 140.7581 -
   root_mean_squared_error: 11.8642
   Epoch 3/200
   1/1 [=============== ] - Os 4ms/step - loss: 136.3612 -
   root_mean_squared_error: 11.6774
   Epoch 4/200
   root_mean_squared_error: 11.5220
   Epoch 5/200
   root_mean_squared_error: 11.3848
   Epoch 6/200
   1/1 [============= ] - Os 4ms/step - loss: 126.7765 -
   root_mean_squared_error: 11.2595
   Epoch 7/200
   root_mean_squared_error: 11.1428
   Epoch 8/200
   1/1 [============ ] - Os 3ms/step - loss: 121.7184 -
   root_mean_squared_error: 11.0326
   Epoch 9/200
   root_mean_squared_error: 10.9274
   Epoch 10/200
   1/1 [============ ] - Os 3ms/step - loss: 117.2082 -
   root_mean_squared_error: 10.8263
   Epoch 11/200
```

```
root_mean_squared_error: 10.7284
Epoch 12/200
1/1 [============ ] - Os 3ms/step - loss: 113.0673 -
root_mean_squared_error: 10.6333
Epoch 13/200
1/1 [============== ] - Os 4ms/step - loss: 111.1023 -
root_mean_squared_error: 10.5405
Epoch 14/200
1/1 [============= ] - Os 4ms/step - loss: 109.1956 -
root_mean_squared_error: 10.4497
Epoch 15/200
root_mean_squared_error: 10.3605
Epoch 16/200
root_mean_squared_error: 10.2728
Epoch 17/200
1/1 [============ ] - Os 3ms/step - loss: 103.7626 -
root_mean_squared_error: 10.1864
Epoch 18/200
root_mean_squared_error: 10.1011
Epoch 19/200
root_mean_squared_error: 10.0168
Epoch 20/200
root_mean_squared_error: 9.9333
Epoch 21/200
root_mean_squared_error: 9.8506
Epoch 22/200
1/1 [============ ] - Os 4ms/step - loss: 95.4254 -
root_mean_squared_error: 9.7686
Epoch 23/200
root_mean_squared_error: 9.6872
Epoch 24/200
root_mean_squared_error: 9.6064
Epoch 25/200
1/1 [============ ] - Os 3ms/step - loss: 90.7452 -
root_mean_squared_error: 9.5260
Epoch 26/200
1/1 [=========== ] - Os 4ms/step - loss: 89.2296 -
root_mean_squared_error: 9.4461
Epoch 27/200
1/1 [=========== - - 0s 4ms/step - loss: 87.7344 -
```

```
root_mean_squared_error: 9.3667
Epoch 28/200
root_mean_squared_error: 9.2876
Epoch 29/200
root mean squared error: 9.2088
Epoch 30/200
root_mean_squared_error: 9.1303
Epoch 31/200
1/1 [============ ] - Os 3ms/step - loss: 81.9416 -
root_mean_squared_error: 9.0522
Epoch 32/200
root_mean_squared_error: 8.9743
Epoch 33/200
root_mean_squared_error: 8.8966
Epoch 34/200
root_mean_squared_error: 8.8191
Epoch 35/200
root_mean_squared_error: 8.7419
Epoch 36/200
root_mean_squared_error: 8.6649
Epoch 37/200
root_mean_squared_error: 8.5880
Epoch 38/200
root_mean_squared_error: 8.5113
Epoch 39/200
root_mean_squared_error: 8.4348
Epoch 40/200
root_mean_squared_error: 8.3584
Epoch 41/200
root_mean_squared_error: 8.2822
Epoch 42/200
root_mean_squared_error: 8.2061
Epoch 43/200
1/1 [============ - - 0s 3ms/step - loss: 66.0994 -
```

```
root_mean_squared_error: 8.1302
Epoch 44/200
root_mean_squared_error: 8.0543
Epoch 45/200
root mean squared error: 7.9786
Epoch 46/200
root_mean_squared_error: 7.9030
Epoch 47/200
root_mean_squared_error: 7.8275
Epoch 48/200
root_mean_squared_error: 7.7522
Epoch 49/200
root_mean_squared_error: 7.6769
Epoch 50/200
root_mean_squared_error: 7.6018
Epoch 51/200
root_mean_squared_error: 7.5267
Epoch 52/200
root_mean_squared_error: 7.4518
Epoch 53/200
root_mean_squared_error: 7.3770
Epoch 54/200
root_mean_squared_error: 7.3022
Epoch 55/200
root_mean_squared_error: 7.2276
Epoch 56/200
root_mean_squared_error: 7.1531
Epoch 57/200
root_mean_squared_error: 7.0786
Epoch 58/200
1/1 [=========== ] - Os 3ms/step - loss: 49.0603 -
root_mean_squared_error: 7.0043
Epoch 59/200
1/1 [============ - - 0s 4ms/step - loss: 48.0260 -
```

```
root_mean_squared_error: 6.9301
Epoch 60/200
root_mean_squared_error: 6.8560
Epoch 61/200
root_mean_squared_error: 6.7819
Epoch 62/200
1/1 [============= ] - 0s 4ms/step - loss: 44.9974 -
root_mean_squared_error: 6.7080
Epoch 63/200
1/1 [============ ] - Os 4ms/step - loss: 44.0126 -
root_mean_squared_error: 6.6342
Epoch 64/200
root_mean_squared_error: 6.5605
Epoch 65/200
1/1 [============ ] - Os 3ms/step - loss: 42.0796 -
root_mean_squared_error: 6.4869
Epoch 66/200
root_mean_squared_error: 6.4134
Epoch 67/200
root_mean_squared_error: 6.3400
Epoch 68/200
root_mean_squared_error: 6.2667
Epoch 69/200
root_mean_squared_error: 6.1936
Epoch 70/200
root_mean_squared_error: 6.1205
Epoch 71/200
root_mean_squared_error: 6.0476
Epoch 72/200
root_mean_squared_error: 5.9748
Epoch 73/200
1/1 [============ ] - Os 4ms/step - loss: 34.8346 -
root_mean_squared_error: 5.9021
Epoch 74/200
1/1 [=========== ] - Os 4ms/step - loss: 33.9833 -
root_mean_squared_error: 5.8295
Epoch 75/200
1/1 [============ - - 0s 4ms/step - loss: 33.1440 -
```

```
root_mean_squared_error: 5.7571
Epoch 76/200
root_mean_squared_error: 5.6848
Epoch 77/200
root_mean_squared_error: 5.6126
Epoch 78/200
1/1 [============ ] - Os 4ms/step - loss: 30.6978 -
root_mean_squared_error: 5.5406
Epoch 79/200
1/1 [============ ] - Os 3ms/step - loss: 29.9062 -
root_mean_squared_error: 5.4687
Epoch 80/200
root_mean_squared_error: 5.3969
Epoch 81/200
root_mean_squared_error: 5.3253
Epoch 82/200
root_mean_squared_error: 5.2538
Epoch 83/200
root_mean_squared_error: 5.1825
Epoch 84/200
root_mean_squared_error: 5.1113
Epoch 85/200
root_mean_squared_error: 5.0403
Epoch 86/200
root_mean_squared_error: 4.9695
Epoch 87/200
root mean squared error: 4.8988
Epoch 88/200
root_mean_squared_error: 4.8283
Epoch 89/200
1/1 [=========== ] - Os 3ms/step - loss: 22.6384 -
root_mean_squared_error: 4.7580
Epoch 90/200
1/1 [=========== ] - Os 4ms/step - loss: 21.9758 -
root_mean_squared_error: 4.6878
Epoch 91/200
1/1 [============ - - 0s 4ms/step - loss: 21.3249 -
```

```
root_mean_squared_error: 4.6179
Epoch 92/200
1/1 [=========== ] - Os 3ms/step - loss: 20.6854 -
root_mean_squared_error: 4.5481
Epoch 93/200
root mean squared error: 4.4786
Epoch 94/200
root_mean_squared_error: 4.4092
Epoch 95/200
1/1 [============ ] - Os 4ms/step - loss: 18.8359 -
root_mean_squared_error: 4.3400
Epoch 96/200
root_mean_squared_error: 4.2711
Epoch 97/200
root_mean_squared_error: 4.2024
Epoch 98/200
root_mean_squared_error: 4.1339
Epoch 99/200
1/1 [============== ] - 0s 3ms/step - loss: 16.5294 -
root_mean_squared_error: 4.0656
Epoch 100/200
root_mean_squared_error: 3.9976
Epoch 101/200
root_mean_squared_error: 3.9299
Epoch 102/200
root_mean_squared_error: 3.8624
Epoch 103/200
root_mean_squared_error: 3.7951
Epoch 104/200
root_mean_squared_error: 3.7282
Epoch 105/200
root_mean_squared_error: 3.6615
Epoch 106/200
1/1 [=========== ] - Os 3ms/step - loss: 12.9250 -
root_mean_squared_error: 3.5951
Epoch 107/200
1/1 [=========== - - 0s 4ms/step - loss: 12.4543 -
```

```
root_mean_squared_error: 3.5291
Epoch 108/200
1/1 [=========== ] - Os 4ms/step - loss: 11.9945 -
root_mean_squared_error: 3.4633
Epoch 109/200
root_mean_squared_error: 3.3979
Epoch 110/200
1/1 [============== ] - 0s 4ms/step - loss: 11.1075 -
root_mean_squared_error: 3.3328
Epoch 111/200
root_mean_squared_error: 3.2680
Epoch 112/200
root_mean_squared_error: 3.2037
Epoch 113/200
1/1 [============= ] - Os 3ms/step - loss: 9.8576 -
root_mean_squared_error: 3.1397
Epoch 114/200
1/1 [=========== ] - Os 3ms/step - loss: 9.4622 -
root_mean_squared_error: 3.0761
Epoch 115/200
root_mean_squared_error: 3.0129
Epoch 116/200
1/1 [=========== ] - Os 3ms/step - loss: 8.7031 -
root_mean_squared_error: 2.9501
Epoch 117/200
root_mean_squared_error: 2.8878
Epoch 118/200
root_mean_squared_error: 2.8259
Epoch 119/200
1/1 [========= ] - Os 3ms/step - loss: 7.6424 -
root_mean_squared_error: 2.7645
Epoch 120/200
root_mean_squared_error: 2.7036
Epoch 121/200
1/1 [============ ] - Os 3ms/step - loss: 6.9866 -
root_mean_squared_error: 2.6432
Epoch 122/200
1/1 [=========== ] - Os 3ms/step - loss: 6.6738 -
root_mean_squared_error: 2.5834
Epoch 123/200
1/1 [========== ] - Os 3ms/step - loss: 6.3710 -
```

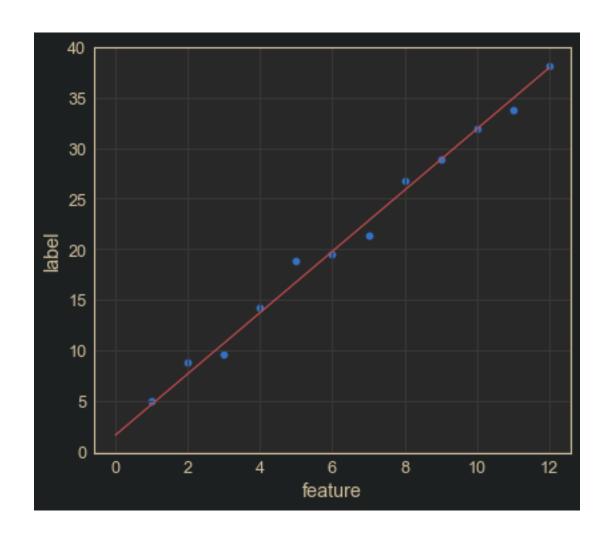
```
root_mean_squared_error: 2.5241
Epoch 124/200
1/1 [============ ] - Os 3ms/step - loss: 6.0781 -
root_mean_squared_error: 2.4654
Epoch 125/200
1/1 [============= ] - Os 3ms/step - loss: 5.7951 -
root_mean_squared_error: 2.4073
Epoch 126/200
1/1 [========== ] - Os 2ms/step - loss: 5.5218 -
root_mean_squared_error: 2.3498
Epoch 127/200
root_mean_squared_error: 2.2931
Epoch 128/200
root_mean_squared_error: 2.2370
Epoch 129/200
1/1 [============ ] - Os 4ms/step - loss: 4.7595 -
root_mean_squared_error: 2.1816
Epoch 130/200
1/1 [============= ] - 0s 4ms/step - loss: 4.5243 -
root_mean_squared_error: 2.1270
Epoch 131/200
1/1 [========= ] - Os 3ms/step - loss: 4.2984 -
root_mean_squared_error: 2.0732
Epoch 132/200
1/1 [========== ] - Os 3ms/step - loss: 4.0816 -
root_mean_squared_error: 2.0203
Epoch 133/200
1/1 [=========== ] - Os 3ms/step - loss: 3.8738 -
root_mean_squared_error: 1.9682
Epoch 134/200
root_mean_squared_error: 1.9170
Epoch 135/200
1/1 [============ ] - Os 4ms/step - loss: 3.4850 -
root_mean_squared_error: 1.8668
Epoch 136/200
root_mean_squared_error: 1.8176
Epoch 137/200
1/1 [============ ] - Os 3ms/step - loss: 3.1309 -
root_mean_squared_error: 1.7694
Epoch 138/200
1/1 [========== ] - Os 3ms/step - loss: 2.9666 -
root_mean_squared_error: 1.7224
Epoch 139/200
1/1 [========== ] - Os 3ms/step - loss: 2.8105 -
```

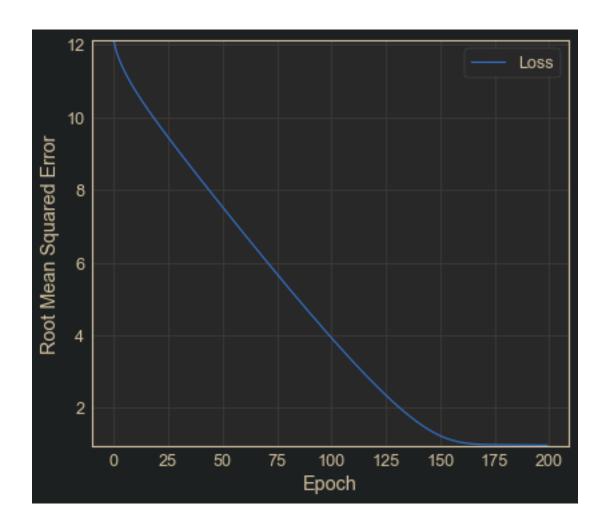
```
root_mean_squared_error: 1.6765
Epoch 140/200
root_mean_squared_error: 1.6317
Epoch 141/200
1/1 [============== ] - Os 3ms/step - loss: 2.5226 -
root_mean_squared_error: 1.5883
Epoch 142/200
1/1 [============ ] - Os 3ms/step - loss: 2.3904 -
root_mean_squared_error: 1.5461
Epoch 143/200
1/1 [============ ] - Os 3ms/step - loss: 2.2659 -
root_mean_squared_error: 1.5053
Epoch 144/200
root_mean_squared_error: 1.4659
Epoch 145/200
root_mean_squared_error: 1.4279
Epoch 146/200
1/1 [=========== ] - Os 3ms/step - loss: 1.9363 -
root_mean_squared_error: 1.3915
Epoch 147/200
root_mean_squared_error: 1.3567
Epoch 148/200
1/1 [=========== ] - Os 3ms/step - loss: 1.7515 -
root_mean_squared_error: 1.3234
Epoch 149/200
1/1 [========== ] - Os 4ms/step - loss: 1.6689 -
root_mean_squared_error: 1.2918
Epoch 150/200
root_mean_squared_error: 1.2620
Epoch 151/200
1/1 [========== ] - Os 3ms/step - loss: 1.5223 -
root_mean_squared_error: 1.2338
Epoch 152/200
root_mean_squared_error: 1.2074
Epoch 153/200
1/1 [============ ] - Os 3ms/step - loss: 1.3989 -
root_mean_squared_error: 1.1827
Epoch 154/200
root_mean_squared_error: 1.1599
Epoch 155/200
1/1 [========= ] - Os 3ms/step - loss: 1.2968 -
```

```
root_mean_squared_error: 1.1388
Epoch 156/200
1/1 [============ ] - Os 4ms/step - loss: 1.2531 -
root_mean_squared_error: 1.1194
Epoch 157/200
1/1 [============= ] - Os 4ms/step - loss: 1.2139 -
root_mean_squared_error: 1.1018
Epoch 158/200
1/1 [============ ] - Os 3ms/step - loss: 1.1790 -
root_mean_squared_error: 1.0858
Epoch 159/200
1/1 [============ ] - Os 4ms/step - loss: 1.1481 -
root_mean_squared_error: 1.0715
Epoch 160/200
root_mean_squared_error: 1.0587
Epoch 161/200
1/1 [============ ] - Os 2ms/step - loss: 1.0971 -
root_mean_squared_error: 1.0474
Epoch 162/200
1/1 [=========== ] - Os 3ms/step - loss: 1.0765 -
root_mean_squared_error: 1.0375
Epoch 163/200
1/1 [=========== ] - Os 3ms/step - loss: 1.0587 -
root_mean_squared_error: 1.0289
Epoch 164/200
1/1 [=========== ] - Os 3ms/step - loss: 1.0435 -
root_mean_squared_error: 1.0215
Epoch 165/200
1/1 [=========== ] - Os 3ms/step - loss: 1.0306 -
root_mean_squared_error: 1.0152
Epoch 166/200
root_mean_squared_error: 1.0099
Epoch 167/200
1/1 [=========== ] - Os 4ms/step - loss: 1.0108 -
root_mean_squared_error: 1.0054
Epoch 168/200
root_mean_squared_error: 1.0017
Epoch 169/200
1/1 [============ ] - Os 3ms/step - loss: 0.9973 -
root_mean_squared_error: 0.9986
Epoch 170/200
1/1 [========== ] - 0s 4ms/step - loss: 0.9923 -
root_mean_squared_error: 0.9961
Epoch 171/200
1/1 [========= ] - 0s 3ms/step - loss: 0.9883 -
```

```
root_mean_squared_error: 0.9941
Epoch 172/200
1/1 [============ ] - Os 1ms/step - loss: 0.9850 -
root_mean_squared_error: 0.9925
Epoch 173/200
1/1 [============= ] - Os 4ms/step - loss: 0.9823 -
root_mean_squared_error: 0.9911
Epoch 174/200
1/1 [=========== ] - Os 5ms/step - loss: 0.9802 -
root_mean_squared_error: 0.9900
Epoch 175/200
1/1 [============ ] - Os 3ms/step - loss: 0.9784 -
root_mean_squared_error: 0.9891
Epoch 176/200
root_mean_squared_error: 0.9883
Epoch 177/200
1/1 [============= ] - Os 3ms/step - loss: 0.9755 -
root_mean_squared_error: 0.9877
Epoch 178/200
1/1 [============= ] - 0s 3ms/step - loss: 0.9743 -
root_mean_squared_error: 0.9870
Epoch 179/200
1/1 [========== ] - Os 4ms/step - loss: 0.9731 -
root_mean_squared_error: 0.9865
Epoch 180/200
1/1 [=========== ] - Os 3ms/step - loss: 0.9720 -
root_mean_squared_error: 0.9859
Epoch 181/200
1/1 [========== ] - Os 3ms/step - loss: 0.9710 -
root_mean_squared_error: 0.9854
Epoch 182/200
root_mean_squared_error: 0.9848
Epoch 183/200
1/1 [========== ] - 0s 4ms/step - loss: 0.9688 -
root mean squared error: 0.9843
Epoch 184/200
root_mean_squared_error: 0.9837
Epoch 185/200
1/1 [============ ] - Os 4ms/step - loss: 0.9665 -
root_mean_squared_error: 0.9831
Epoch 186/200
1/1 [========== ] - Os 4ms/step - loss: 0.9653 -
root_mean_squared_error: 0.9825
Epoch 187/200
1/1 [========= ] - Os 3ms/step - loss: 0.9641 -
```

```
root_mean_squared_error: 0.9819
Epoch 188/200
1/1 [============ ] - Os 3ms/step - loss: 0.9629 -
root_mean_squared_error: 0.9813
Epoch 189/200
1/1 [============= ] - Os 3ms/step - loss: 0.9616 -
root_mean_squared_error: 0.9806
Epoch 190/200
1/1 [=========== ] - Os 3ms/step - loss: 0.9603 -
root_mean_squared_error: 0.9799
Epoch 191/200
1/1 [============ ] - Os 3ms/step - loss: 0.9589 -
root_mean_squared_error: 0.9792
Epoch 192/200
root_mean_squared_error: 0.9785
Epoch 193/200
1/1 [============ ] - Os 4ms/step - loss: 0.9561 -
root_mean_squared_error: 0.9778
Epoch 194/200
1/1 [============= ] - 0s 3ms/step - loss: 0.9547 -
root_mean_squared_error: 0.9771
Epoch 195/200
root_mean_squared_error: 0.9763
Epoch 196/200
1/1 [=========== ] - Os 3ms/step - loss: 0.9517 -
root_mean_squared_error: 0.9755
Epoch 197/200
1/1 [=========== ] - Os 4ms/step - loss: 0.9501 -
root_mean_squared_error: 0.9748
Epoch 198/200
root_mean_squared_error: 0.9740
Epoch 199/200
1/1 [========== ] - Os 3ms/step - loss: 0.9470 -
root_mean_squared_error: 0.9731
Epoch 200/200
root_mean_squared_error: 0.9723
C:\Users\Arunabh\anaconda3\envs\mlcc\lib\site-
packages\numpy\core\_asarray.py:136: VisibleDeprecationWarning: Creating an
ndarray from ragged nested sequences (which is a list-or-tuple of lists-or-
tuples-or ndarrays with different lengths or shapes) is deprecated. If you meant
to do this, you must specify 'dtype=object' when creating the ndarray
 return array(a, dtype, copy=False, order=order, subok=True)
```





1.11 Task 3: Increase the learning rate

In Task 2, you increased the number of epochs to get the model to converge. Sometimes, you can get the model to converge more quickly by increasing the learning rate. However, setting the learning

rate too high often makes it impossible for a model to converge. In Task 3, we've intentionally set the learning rate too high. Run the following code cell and see what happens.

```
[14]: # Increase the learning rate and decrease the number of epochs.
    learning_rate=100
    epochs=500
    my_model = build_model(learning_rate)
    trained_weight, trained_bias, epochs, rmse = train_model(my_model, my_feature,
                                           my_label, epochs,
                                           my batch size)
    plot_the_model(trained_weight, trained_bias, my_feature, my_label)
    plot the loss curve(epochs, rmse)
   Epoch 1/500
   root_mean_squared_error: 14.2605
   Epoch 2/500
   root_mean_squared_error: 2596.6462
   Epoch 3/500
   1/1 [============ ] - Os 3ms/step - loss: 202.3578 -
   root_mean_squared_error: 14.2253
   Epoch 4/500
   root_mean_squared_error: 1.2806
   Epoch 5/500
   1/1 [=========== ] - Os 4ms/step - loss: 0.9261 -
   root_mean_squared_error: 0.9623
   Epoch 6/500
   root_mean_squared_error: 0.9560
   Epoch 7/500
   1/1 [========== ] - Os 4ms/step - loss: 0.9112 -
   root_mean_squared_error: 0.9546
   Epoch 8/500
   1/1 [========== ] - 0s 3ms/step - loss: 0.9088 -
   root_mean_squared_error: 0.9533
   Epoch 9/500
   root_mean_squared_error: 0.9520
   Epoch 10/500
   1/1 [============ ] - Os 3ms/step - loss: 0.9040 -
   root_mean_squared_error: 0.9508
   Epoch 11/500
   root_mean_squared_error: 0.9496
   Epoch 12/500
```

```
1/1 [============ ] - Os 4ms/step - loss: 0.8996 -
root_mean_squared_error: 0.9485
Epoch 13/500
1/1 [============ ] - Os 4ms/step - loss: 0.8974 -
root mean squared error: 0.9473
Epoch 14/500
1/1 [=========== ] - Os 3ms/step - loss: 0.8954 -
root_mean_squared_error: 0.9462
Epoch 15/500
1/1 [============= ] - 0s 4ms/step - loss: 0.8934 -
root_mean_squared_error: 0.9452
Epoch 16/500
1/1 [============== ] - Os 4ms/step - loss: 0.8916 -
root_mean_squared_error: 0.9442
Epoch 17/500
1/1 [=========== ] - Os 4ms/step - loss: 0.8898 -
root_mean_squared_error: 0.9433
Epoch 18/500
1/1 [========== ] - 0s 4ms/step - loss: 0.8881 -
root mean squared error: 0.9424
Epoch 19/500
1/1 [============ ] - Os 4ms/step - loss: 0.8866 -
root_mean_squared_error: 0.9416
Epoch 20/500
1/1 [========== ] - Os 3ms/step - loss: 0.8852 -
root_mean_squared_error: 0.9408
Epoch 21/500
root_mean_squared_error: 0.9401
Epoch 22/500
1/1 [========== ] - Os 3ms/step - loss: 0.8826 -
root_mean_squared_error: 0.9395
Epoch 23/500
1/1 [============ ] - Os 3ms/step - loss: 0.8815 -
root mean squared error: 0.9389
Epoch 24/500
root_mean_squared_error: 0.9384
Epoch 25/500
1/1 [=========== ] - Os 2ms/step - loss: 0.8797 -
root_mean_squared_error: 0.9379
Epoch 26/500
root_mean_squared_error: 0.9375
Epoch 27/500
1/1 [=========== ] - Os 3ms/step - loss: 0.8784 -
root_mean_squared_error: 0.9372
Epoch 28/500
```

```
1/1 [============ ] - Os 5ms/step - loss: 0.8791 -
root_mean_squared_error: 0.9376
Epoch 29/500
1/1 [============ ] - Os 3ms/step - loss: 0.8900 -
root mean squared error: 0.9434
Epoch 30/500
1/1 [============= ] - 0s 3ms/step - loss: 1.0056 -
root_mean_squared_error: 1.0028
Epoch 31/500
1/1 [============= ] - 0s 3ms/step - loss: 2.3612 -
root_mean_squared_error: 1.5366
Epoch 32/500
root_mean_squared_error: 4.5246
Epoch 33/500
1/1 [============== ] - Os 4ms/step - loss: 296.3673 -
root_mean_squared_error: 17.2153
Epoch 34/500
root_mean_squared_error: 71.2481
Epoch 35/500
root_mean_squared_error: 310.9217
Epoch 36/500
root_mean_squared_error: 1147.3672
Epoch 37/500
root_mean_squared_error: 1224.3463
Epoch 38/500
root_mean_squared_error: 641.6002
Epoch 39/500
1/1 [============ ] - Os 3ms/step - loss: 100559.7109 -
root mean squared error: 317.1115
Epoch 40/500
root_mean_squared_error: 173.4690
Epoch 41/500
root_mean_squared_error: 107.7645
Epoch 42/500
root_mean_squared_error: 75.9422
Epoch 43/500
root_mean_squared_error: 60.3342
Epoch 44/500
```

```
root_mean_squared_error: 53.6812
Epoch 45/500
root mean squared error: 53.1581
Epoch 46/500
root_mean_squared_error: 58.2598
Epoch 47/500
root_mean_squared_error: 70.2992
Epoch 48/500
root_mean_squared_error: 92.8980
Epoch 49/500
root_mean_squared_error: 133.5719
Epoch 50/500
root_mean_squared_error: 206.7421
Epoch 51/500
1/1 [=============== ] - 0s 4ms/step - loss: 113128.1797 -
root_mean_squared_error: 336.3453
Epoch 52/500
root_mean_squared_error: 540.8517
Epoch 53/500
1/1 [=========== ] - Os 3ms/step - loss: 564273.7500 -
root_mean_squared_error: 751.1816
Epoch 54/500
root_mean_squared_error: 780.6127
Epoch 55/500
1/1 [============ ] - Os 4ms/step - loss: 398082.2500 -
root mean squared error: 630.9376
Epoch 56/500
root_mean_squared_error: 461.3694
Epoch 57/500
root_mean_squared_error: 339.9453
Epoch 58/500
root_mean_squared_error: 265.4535
Epoch 59/500
root_mean_squared_error: 224.0214
Epoch 60/500
```

```
root_mean_squared_error: 205.4687
Epoch 61/500
1/1 [============ ] - Os 4ms/step - loss: 41863.9336 -
root mean squared error: 204.6068
Epoch 62/500
root_mean_squared_error: 220.1040
Epoch 63/500
root_mean_squared_error: 253.4991
Epoch 64/500
root_mean_squared_error: 308.0120
Epoch 65/500
root_mean_squared_error: 385.3310
Epoch 66/500
root_mean_squared_error: 477.5961
Epoch 67/500
root_mean_squared_error: 557.4346
Epoch 68/500
root_mean_squared_error: 587.0924
Epoch 69/500
1/1 [=========== ] - Os 3ms/step - loss: 308488.6562 -
root_mean_squared_error: 555.4175
Epoch 70/500
root_mean_squared_error: 488.8227
Epoch 71/500
root_mean_squared_error: 419.4207
Epoch 72/500
root_mean_squared_error: 364.1586
Epoch 73/500
root_mean_squared_error: 327.3671
Epoch 74/500
root_mean_squared_error: 308.2074
Epoch 75/500
root_mean_squared_error: 304.8993
Epoch 76/500
```

```
root_mean_squared_error: 316.0882
Epoch 77/500
1/1 [============ ] - Os 3ms/step - loss: 116069.3203 -
root mean squared error: 340.6895
Epoch 78/500
root_mean_squared_error: 376.7710
Epoch 79/500
root_mean_squared_error: 419.7245
Epoch 80/500
root_mean_squared_error: 460.7791
Epoch 81/500
root_mean_squared_error: 488.4157
Epoch 82/500
root_mean_squared_error: 494.1639
Epoch 83/500
root_mean_squared_error: 478.3460
Epoch 84/500
root_mean_squared_error: 449.2220
Epoch 85/500
1/1 [=========== ] - Os 4ms/step - loss: 173875.8281 -
root_mean_squared_error: 416.9842
Epoch 86/500
root_mean_squared_error: 389.1431
Epoch 87/500
root mean squared error: 369.6283
Epoch 88/500
root_mean_squared_error: 359.8246
Epoch 89/500
root_mean_squared_error: 359.7064
Epoch 90/500
root_mean_squared_error: 368.4158
Epoch 91/500
root_mean_squared_error: 384.2986
Epoch 92/500
```

```
root_mean_squared_error: 404.6472
Epoch 93/500
1/1 [============ ] - Os 4ms/step - loss: 181101.7500 -
root mean squared error: 425.5605
Epoch 94/500
root_mean_squared_error: 442.4345
Epoch 95/500
root_mean_squared_error: 451.3215
Epoch 96/500
root_mean_squared_error: 450.5483
Epoch 97/500
root_mean_squared_error: 441.3820
Epoch 98/500
root_mean_squared_error: 427.2044
Epoch 99/500
root_mean_squared_error: 411.9398
Epoch 100/500
root_mean_squared_error: 398.8235
Epoch 101/500
1/1 [=========== ] - Os 3ms/step - loss: 152041.6250 -
root_mean_squared_error: 389.9251
Epoch 102/500
root_mean_squared_error: 386.1937
Epoch 103/500
1/1 [============ ] - Os 3ms/step - loss: 150286.7188 -
root_mean_squared_error: 387.6683
Epoch 104/500
root_mean_squared_error: 393.6446
Epoch 105/500
root_mean_squared_error: 402.7713
Epoch 106/500
root_mean_squared_error: 413.1660
Epoch 107/500
root_mean_squared_error: 422.6716
Epoch 108/500
```

```
root_mean_squared_error: 429.3100
Epoch 109/500
1/1 [============ ] - Os 4ms/step - loss: 186468.1250 -
root_mean_squared_error: 431.8195
Epoch 110/500
root_mean_squared_error: 430.0201
Epoch 111/500
root_mean_squared_error: 424.7916
Epoch 112/500
root_mean_squared_error: 417.6901
Epoch 113/500
root_mean_squared_error: 410.4297
Epoch 114/500
root_mean_squared_error: 404.4633
Epoch 115/500
root_mean_squared_error: 400.7592
Epoch 116/500
root_mean_squared_error: 399.7420
Epoch 117/500
1/1 [=========== ] - Os 3ms/step - loss: 161060.8281 -
root_mean_squared_error: 401.3239
Epoch 118/500
root_mean_squared_error: 404.9771
Epoch 119/500
1/1 [=========== ] - Os 4ms/step - loss: 167968.2969 -
root_mean_squared_error: 409.8394
Epoch 120/500
root_mean_squared_error: 414.8633
Epoch 121/500
root_mean_squared_error: 419.0170
Epoch 122/500
root_mean_squared_error: 421.5075
Epoch 123/500
root_mean_squared_error: 421.9593
Epoch 124/500
```

```
root_mean_squared_error: 420.4800
Epoch 125/500
1/1 [=========== ] - Os 3ms/step - loss: 174380.7656 -
root mean squared error: 417.5892
Epoch 126/500
root_mean_squared_error: 414.0437
Epoch 127/500
root_mean_squared_error: 410.6341
Epoch 128/500
root_mean_squared_error: 408.0175
Epoch 129/500
root_mean_squared_error: 406.6130
Epoch 130/500
root mean squared error: 406.5630
Epoch 131/500
root_mean_squared_error: 407.7429
Epoch 132/500
root_mean_squared_error: 409.8096
Epoch 133/500
1/1 [=========== ] - Os 3ms/step - loss: 169973.0625 -
root_mean_squared_error: 412.2779
Epoch 134/500
root_mean_squared_error: 414.6202
Epoch 135/500
root_mean_squared_error: 416.3736
Epoch 136/500
root_mean_squared_error: 417.2341
Epoch 137/500
root_mean_squared_error: 417.1113
Epoch 138/500
root_mean_squared_error: 416.1301
Epoch 139/500
root_mean_squared_error: 414.5811
Epoch 140/500
```

```
root_mean_squared_error: 412.8387
Epoch 141/500
1/1 [============ ] - Os 4ms/step - loss: 169144.8281 -
root_mean_squared_error: 411.2722
Epoch 142/500
root_mean_squared_error: 410.1731
Epoch 143/500
root_mean_squared_error: 409.7086
Epoch 144/500
root_mean_squared_error: 409.9054
Epoch 145/500
root_mean_squared_error: 410.6597
Epoch 146/500
root_mean_squared_error: 411.7690
Epoch 147/500
root_mean_squared_error: 412.9795
Epoch 148/500
root_mean_squared_error: 414.0392
Epoch 149/500
1/1 [=========== ] - Os 3ms/step - loss: 172016.6094 -
root_mean_squared_error: 414.7488
Epoch 150/500
root_mean_squared_error: 414.9986
Epoch 151/500
root_mean_squared_error: 414.7837
Epoch 152/500
root_mean_squared_error: 414.1946
Epoch 153/500
root_mean_squared_error: 413.3890
Epoch 154/500
root_mean_squared_error: 412.5508
Epoch 155/500
root_mean_squared_error: 411.8507
Epoch 156/500
```

```
root_mean_squared_error: 411.4138
Epoch 157/500
1/1 [============ ] - Os 3ms/step - loss: 169167.6094 -
root mean squared error: 411.2999
Epoch 158/500
root_mean_squared_error: 411.4992
Epoch 159/500
root_mean_squared_error: 411.9411
Epoch 160/500
root_mean_squared_error: 412.5140
Epoch 161/500
root_mean_squared_error: 413.0909
Epoch 162/500
root_mean_squared_error: 413.5557
Epoch 163/500
root_mean_squared_error: 413.8261
Epoch 164/500
root_mean_squared_error: 413.8667
Epoch 165/500
1/1 [========== ] - Os 4ms/step - loss: 171141.6094 -
root_mean_squared_error: 413.6927
Epoch 166/500
root_mean_squared_error: 413.3604
Epoch 167/500
1/1 [============ ] - Os 2ms/step - loss: 170530.0625 -
root_mean_squared_error: 412.9529
Epoch 168/500
1/1 [============ ] - Os 3ms/step - loss: 170205.0312 -
root_mean_squared_error: 412.5591
Epoch 169/500
root_mean_squared_error: 412.2564
Epoch 170/500
root_mean_squared_error: 412.0958
Epoch 171/500
root_mean_squared_error: 412.0951
Epoch 172/500
```

```
root_mean_squared_error: 412.2385
Epoch 173/500
1/1 [============ ] - Os 3ms/step - loss: 170142.1406 -
root_mean_squared_error: 412.4829
Epoch 174/500
root_mean_squared_error: 412.7699
Epoch 175/500
root_mean_squared_error: 413.0375
Epoch 176/500
root_mean_squared_error: 413.2344
Epoch 177/500
root_mean_squared_error: 413.3278
Epoch 178/500
root_mean_squared_error: 413.3096
Epoch 179/500
root_mean_squared_error: 413.1943
Epoch 180/500
root_mean_squared_error: 413.0150
Epoch 181/500
1/1 [=========== ] - Os 4ms/step - loss: 170415.4062 -
root_mean_squared_error: 412.8140
Epoch 182/500
root_mean_squared_error: 412.6338
Epoch 183/500
1/1 [=========== ] - Os 4ms/step - loss: 170162.9531 -
root_mean_squared_error: 412.5081
Epoch 184/500
1/1 [=============== ] - 0s 4ms/step - loss: 170120.5781 -
root_mean_squared_error: 412.4568
Epoch 185/500
root_mean_squared_error: 412.4823
Epoch 186/500
root_mean_squared_error: 412.5721
Epoch 187/500
root_mean_squared_error: 412.7018
Epoch 188/500
```

```
root_mean_squared_error: 412.8415
Epoch 189/500
1/1 [============ ] - Os 3ms/step - loss: 170537.9375 -
root_mean_squared_error: 412.9624
Epoch 190/500
root_mean_squared_error: 413.0421
Epoch 191/500
root_mean_squared_error: 413.0686
Epoch 192/500
root_mean_squared_error: 413.0421
Epoch 193/500
root_mean_squared_error: 412.9731
Epoch 194/500
root_mean_squared_error: 412.8796
Epoch 195/500
root_mean_squared_error: 412.7829
Epoch 196/500
root_mean_squared_error: 412.7026
Epoch 197/500
1/1 [=========== ] - Os 3ms/step - loss: 170282.6250 -
root_mean_squared_error: 412.6532
Epoch 198/500
root_mean_squared_error: 412.6413
Epoch 199/500
1/1 [=========== ] - Os 4ms/step - loss: 170292.9531 -
root_mean_squared_error: 412.6657
Epoch 200/500
root_mean_squared_error: 412.7179
Epoch 201/500
root_mean_squared_error: 412.7846
Epoch 202/500
root_mean_squared_error: 412.8510
Epoch 203/500
root_mean_squared_error: 412.9037
Epoch 204/500
```

```
root_mean_squared_error: 412.9338
Epoch 205/500
1/1 [=========== ] - Os 3ms/step - loss: 170517.3906 -
root mean squared error: 412.9375
Epoch 206/500
root_mean_squared_error: 412.9167
Epoch 207/500
root_mean_squared_error: 412.8779
Epoch 208/500
root_mean_squared_error: 412.8307
Epoch 209/500
root_mean_squared_error: 412.7853
Epoch 210/500
root_mean_squared_error: 412.7509
Epoch 211/500
root_mean_squared_error: 412.7331
Epoch 212/500
root_mean_squared_error: 412.7337
Epoch 213/500
1/1 [=========== ] - Os 4ms/step - loss: 170363.2031 -
root_mean_squared_error: 412.7508
Epoch 214/500
root_mean_squared_error: 412.7793
Epoch 215/500
1/1 [============ ] - Os 4ms/step - loss: 170414.1406 -
root_mean_squared_error: 412.8125
Epoch 216/500
root_mean_squared_error: 412.8431
Epoch 217/500
root_mean_squared_error: 412.8654
Epoch 218/500
root_mean_squared_error: 412.8758
Epoch 219/500
root_mean_squared_error: 412.8731
Epoch 220/500
```

```
root_mean_squared_error: 412.8595
Epoch 221/500
1/1 [============ ] - Os 4ms/step - loss: 170435.7344 -
root_mean_squared_error: 412.8386
Epoch 222/500
1/1 [=============== ] - 0s 4ms/step - loss: 170416.5781 -
root_mean_squared_error: 412.8154
Epoch 223/500
root_mean_squared_error: 412.7948
Epoch 224/500
root_mean_squared_error: 412.7807
Epoch 225/500
root_mean_squared_error: 412.7751
Epoch 226/500
root_mean_squared_error: 412.7784
Epoch 227/500
root_mean_squared_error: 412.7891
Epoch 228/500
root_mean_squared_error: 412.8042
Epoch 229/500
1/1 [=========== ] - Os 4ms/step - loss: 170420.6250 -
root_mean_squared_error: 412.8203
Epoch 230/500
root_mean_squared_error: 412.8340
Epoch 231/500
1/1 [============= ] - Os 4ms/step - loss: 170439.2656 -
root_mean_squared_error: 412.8429
Epoch 232/500
1/1 [=============== ] - 0s 3ms/step - loss: 170441.4531 -
root_mean_squared_error: 412.8456
Epoch 233/500
root_mean_squared_error: 412.8422
Epoch 234/500
root_mean_squared_error: 412.8341
Epoch 235/500
root_mean_squared_error: 412.8232
Epoch 236/500
```

```
root_mean_squared_error: 412.8122
Epoch 237/500
1/1 [============ ] - Os 4ms/step - loss: 170406.3281 -
root_mean_squared_error: 412.8030
Epoch 238/500
root_mean_squared_error: 412.7975
Epoch 239/500
root_mean_squared_error: 412.7964
Epoch 240/500
root_mean_squared_error: 412.7993
Epoch 241/500
root_mean_squared_error: 412.8055
Epoch 242/500
root_mean_squared_error: 412.8133
Epoch 243/500
root_mean_squared_error: 412.8210
Epoch 244/500
root_mean_squared_error: 412.8270
Epoch 245/500
1/1 [=========== ] - Os 3ms/step - loss: 170428.8594 -
root_mean_squared_error: 412.8303
Epoch 246/500
root_mean_squared_error: 412.8305
Epoch 247/500
1/1 [============ ] - Os 3ms/step - loss: 170427.0000 -
root_mean_squared_error: 412.8281
Epoch 248/500
root_mean_squared_error: 412.8235
Epoch 249/500
root_mean_squared_error: 412.8180
Epoch 250/500
root_mean_squared_error: 412.8127
Epoch 251/500
root_mean_squared_error: 412.8088
Epoch 252/500
```

```
root_mean_squared_error: 412.8069
Epoch 253/500
1/1 [=========== ] - Os 3ms/step - loss: 170409.6094 -
root_mean_squared_error: 412.8070
Epoch 254/500
root_mean_squared_error: 412.8090
Epoch 255/500
root_mean_squared_error: 412.8124
Epoch 256/500
root_mean_squared_error: 412.8163
Epoch 257/500
root_mean_squared_error: 412.8199
Epoch 258/500
root_mean_squared_error: 412.8225
Epoch 259/500
root_mean_squared_error: 412.8236
Epoch 260/500
root_mean_squared_error: 412.8233
Epoch 261/500
1/1 [=========== ] - Os 4ms/step - loss: 170421.7031 -
root_mean_squared_error: 412.8216
Epoch 262/500
root_mean_squared_error: 412.8191
Epoch 263/500
1/1 [============ ] - Os 4ms/step - loss: 170417.1719 -
root_mean_squared_error: 412.8162
Epoch 264/500
root_mean_squared_error: 412.8137
Epoch 265/500
root_mean_squared_error: 412.8121
Epoch 266/500
root_mean_squared_error: 412.8116
Epoch 267/500
root_mean_squared_error: 412.8121
Epoch 268/500
```

```
root_mean_squared_error: 412.8133
Epoch 269/500
1/1 [=========== ] - Os 3ms/step - loss: 170416.2656 -
root_mean_squared_error: 412.8151
Epoch 270/500
root_mean_squared_error: 412.8170
Epoch 271/500
root_mean_squared_error: 412.8188
Epoch 272/500
root_mean_squared_error: 412.8198
Epoch 273/500
root_mean_squared_error: 412.8202
Epoch 274/500
root_mean_squared_error: 412.8198
Epoch 275/500
root_mean_squared_error: 412.8187
Epoch 276/500
root_mean_squared_error: 412.8175
Epoch 277/500
1/1 [=========== ] - Os 3ms/step - loss: 170417.1094 -
root_mean_squared_error: 412.8161
Epoch 278/500
root_mean_squared_error: 412.8150
Epoch 279/500
1/1 [============ ] - Os 4ms/step - loss: 170415.6719 -
root_mean_squared_error: 412.8143
Epoch 280/500
root_mean_squared_error: 412.8141
Epoch 281/500
root_mean_squared_error: 412.8145
Epoch 282/500
1/1 [=========== ] - Os 3ms/step - loss: 170416.3906 -
root_mean_squared_error: 412.8152
Epoch 283/500
root_mean_squared_error: 412.8161
Epoch 284/500
```

```
root_mean_squared_error: 412.8170
Epoch 285/500
1/1 [============ ] - Os 4ms/step - loss: 170418.5469 -
root_mean_squared_error: 412.8178
Epoch 286/500
root_mean_squared_error: 412.8182
Epoch 287/500
root_mean_squared_error: 412.8184
Epoch 288/500
root_mean_squared_error: 412.8182
Epoch 289/500
root_mean_squared_error: 412.8177
Epoch 290/500
root_mean_squared_error: 412.8170
Epoch 291/500
root_mean_squared_error: 412.8162
Epoch 292/500
root_mean_squared_error: 412.8156
Epoch 293/500
1/1 [=========== ] - Os 3ms/step - loss: 170416.4219 -
root_mean_squared_error: 412.8152
Epoch 294/500
root_mean_squared_error: 412.8152
Epoch 295/500
1/1 [============ ] - Os 3ms/step - loss: 170416.5938 -
root_mean_squared_error: 412.8155
Epoch 296/500
root_mean_squared_error: 412.8159
Epoch 297/500
root_mean_squared_error: 412.8164
Epoch 298/500
1/1 [=========== ] - Os 4ms/step - loss: 170417.7344 -
root_mean_squared_error: 412.8168
Epoch 299/500
root_mean_squared_error: 412.8173
Epoch 300/500
```

```
root_mean_squared_error: 412.8175
Epoch 301/500
1/1 [============ ] - Os 4ms/step - loss: 170418.3750 -
root mean squared error: 412.8176
Epoch 302/500
root_mean_squared_error: 412.8174
Epoch 303/500
root_mean_squared_error: 412.8171
Epoch 304/500
root_mean_squared_error: 412.8167
Epoch 305/500
root_mean_squared_error: 412.8164
Epoch 306/500
root_mean_squared_error: 412.8161
Epoch 307/500
root_mean_squared_error: 412.8159
Epoch 308/500
root_mean_squared_error: 412.8158
Epoch 309/500
1/1 [=========== ] - Os 3ms/step - loss: 170417.0781 -
root_mean_squared_error: 412.8160
Epoch 310/500
root_mean_squared_error: 412.8162
Epoch 311/500
root_mean_squared_error: 412.8165
Epoch 312/500
root_mean_squared_error: 412.8168
Epoch 313/500
root_mean_squared_error: 412.8170
Epoch 314/500
root_mean_squared_error: 412.8172
Epoch 315/500
root_mean_squared_error: 412.8171
Epoch 316/500
```

```
root_mean_squared_error: 412.8172
Epoch 317/500
1/1 [============ ] - Os 4ms/step - loss: 170417.8281 -
root mean squared error: 412.8170
Epoch 318/500
1/1 [=============== ] - 0s 4ms/step - loss: 170417.6406 -
root_mean_squared_error: 412.8167
Epoch 319/500
root_mean_squared_error: 412.8165
Epoch 320/500
root_mean_squared_error: 412.8163
Epoch 321/500
root_mean_squared_error: 412.8162
Epoch 322/500
root_mean_squared_error: 412.8162
Epoch 323/500
1/1 [=============== ] - 0s 3ms/step - loss: 170417.1719 -
root_mean_squared_error: 412.8162
Epoch 324/500
root_mean_squared_error: 412.8163
Epoch 325/500
1/1 [=========== ] - Os 3ms/step - loss: 170417.3594 -
root_mean_squared_error: 412.8164
Epoch 326/500
root_mean_squared_error: 412.8166
Epoch 327/500
1/1 [============ ] - Os 4ms/step - loss: 170417.7344 -
root_mean_squared_error: 412.8168
Epoch 328/500
root_mean_squared_error: 412.8170
Epoch 329/500
root_mean_squared_error: 412.8170
Epoch 330/500
root_mean_squared_error: 412.8170
Epoch 331/500
root_mean_squared_error: 412.8169
Epoch 332/500
```

```
root_mean_squared_error: 412.8168
Epoch 333/500
1/1 [============ ] - Os 3ms/step - loss: 170417.5781 -
root_mean_squared_error: 412.8167
Epoch 334/500
root_mean_squared_error: 412.8164
Epoch 335/500
root_mean_squared_error: 412.8164
Epoch 336/500
root_mean_squared_error: 412.8163
Epoch 337/500
root_mean_squared_error: 412.8163
Epoch 338/500
root_mean_squared_error: 412.8163
Epoch 339/500
1/1 [================== ] - Os 3ms/step - loss: 170417.3594 -
root_mean_squared_error: 412.8164
Epoch 340/500
root_mean_squared_error: 412.8166
Epoch 341/500
1/1 [=========== ] - Os 3ms/step - loss: 170417.6719 -
root_mean_squared_error: 412.8167
Epoch 342/500
root_mean_squared_error: 412.8168
Epoch 343/500
1/1 [============ ] - Os 3ms/step - loss: 170417.7656 -
root_mean_squared_error: 412.8169
Epoch 344/500
1/1 [=============== ] - 0s 3ms/step - loss: 170417.7656 -
root_mean_squared_error: 412.8169
Epoch 345/500
root_mean_squared_error: 412.8168
Epoch 346/500
1/1 [=========== ] - Os 3ms/step - loss: 170417.6250 -
root_mean_squared_error: 412.8167
Epoch 347/500
root_mean_squared_error: 412.8167
Epoch 348/500
```

```
root_mean_squared_error: 412.8166
Epoch 349/500
1/1 [============ ] - Os 3ms/step - loss: 170417.4844 -
root_mean_squared_error: 412.8165
Epoch 350/500
1/1 [=============== ] - 0s 4ms/step - loss: 170417.4219 -
root_mean_squared_error: 412.8164
Epoch 351/500
root_mean_squared_error: 412.8163
Epoch 352/500
root_mean_squared_error: 412.8163
Epoch 353/500
root_mean_squared_error: 412.8163
Epoch 354/500
root_mean_squared_error: 412.8163
Epoch 355/500
root_mean_squared_error: 412.8164
Epoch 356/500
root_mean_squared_error: 412.8166
Epoch 357/500
1/1 [=========== ] - Os 3ms/step - loss: 170417.6719 -
root_mean_squared_error: 412.8167
Epoch 358/500
root_mean_squared_error: 412.8168
Epoch 359/500
1/1 [============ ] - Os 3ms/step - loss: 170417.8125 -
root_mean_squared_error: 412.8169
Epoch 360/500
root_mean_squared_error: 412.8170
Epoch 361/500
root_mean_squared_error: 412.8168
Epoch 362/500
root_mean_squared_error: 412.8167
Epoch 363/500
root_mean_squared_error: 412.8167
Epoch 364/500
```

```
root_mean_squared_error: 412.8165
Epoch 365/500
root mean squared error: 412.8165
Epoch 366/500
root_mean_squared_error: 412.8164
Epoch 367/500
root_mean_squared_error: 412.8165
Epoch 368/500
root_mean_squared_error: 412.8165
Epoch 369/500
root_mean_squared_error: 412.8165
Epoch 370/500
root_mean_squared_error: 412.8165
Epoch 371/500
root_mean_squared_error: 412.8165
Epoch 372/500
root_mean_squared_error: 412.8165
Epoch 373/500
1/1 [=========== ] - Os 4ms/step - loss: 170417.5156 -
root_mean_squared_error: 412.8166
Epoch 374/500
root_mean_squared_error: 412.8167
Epoch 375/500
1/1 [============ ] - Os 4ms/step - loss: 170417.7188 -
root_mean_squared_error: 412.8168
Epoch 376/500
root_mean_squared_error: 412.8168
Epoch 377/500
root_mean_squared_error: 412.8167
Epoch 378/500
1/1 [=========== ] - Os 4ms/step - loss: 170417.5469 -
root_mean_squared_error: 412.8166
Epoch 379/500
root_mean_squared_error: 412.8167
Epoch 380/500
```

```
root_mean_squared_error: 412.8167
Epoch 381/500
1/1 [============ ] - Os 2ms/step - loss: 170417.6094 -
root mean squared error: 412.8167
Epoch 382/500
1/1 [=============== ] - 0s 3ms/step - loss: 170417.6094 -
root_mean_squared_error: 412.8167
Epoch 383/500
root_mean_squared_error: 412.8167
Epoch 384/500
root_mean_squared_error: 412.8166
Epoch 385/500
root_mean_squared_error: 412.8164
Epoch 386/500
root_mean_squared_error: 412.8163
Epoch 387/500
1/1 [================== ] - Os 3ms/step - loss: 170417.3906 -
root_mean_squared_error: 412.8164
Epoch 388/500
root_mean_squared_error: 412.8164
Epoch 389/500
1/1 [========== ] - Os 4ms/step - loss: 170417.4844 -
root_mean_squared_error: 412.8165
Epoch 390/500
root_mean_squared_error: 412.8166
Epoch 391/500
root_mean_squared_error: 412.8166
Epoch 392/500
root_mean_squared_error: 412.8166
Epoch 393/500
root_mean_squared_error: 412.8167
Epoch 394/500
1/1 [=========== ] - Os 3ms/step - loss: 170417.6719 -
root_mean_squared_error: 412.8167
Epoch 395/500
root_mean_squared_error: 412.8167
Epoch 396/500
```

```
root_mean_squared_error: 412.8167
Epoch 397/500
1/1 [============= ] - Os 3ms/step - loss: 170417.6250 -
root_mean_squared_error: 412.8167
Epoch 398/500
root_mean_squared_error: 412.8166
Epoch 399/500
root_mean_squared_error: 412.8168
Epoch 400/500
root_mean_squared_error: 412.8167
Epoch 401/500
root_mean_squared_error: 412.8167
Epoch 402/500
root_mean_squared_error: 412.8166
Epoch 403/500
root_mean_squared_error: 412.8164
Epoch 404/500
root_mean_squared_error: 412.8164
Epoch 405/500
1/1 [========== ] - Os 4ms/step - loss: 170417.4844 -
root_mean_squared_error: 412.8165
Epoch 406/500
root_mean_squared_error: 412.8165
Epoch 407/500
1/1 [============= ] - Os 3ms/step - loss: 170417.5000 -
root_mean_squared_error: 412.8166
Epoch 408/500
root_mean_squared_error: 412.8165
Epoch 409/500
root_mean_squared_error: 412.8164
Epoch 410/500
root_mean_squared_error: 412.8164
Epoch 411/500
root_mean_squared_error: 412.8165
Epoch 412/500
```

```
root_mean_squared_error: 412.8166
Epoch 413/500
1/1 [=========== ] - Os 4ms/step - loss: 170417.6094 -
root_mean_squared_error: 412.8167
Epoch 414/500
1/1 [=============== ] - 0s 4ms/step - loss: 170417.5938 -
root_mean_squared_error: 412.8167
Epoch 415/500
root_mean_squared_error: 412.8168
Epoch 416/500
root_mean_squared_error: 412.8167
Epoch 417/500
root_mean_squared_error: 412.8167
Epoch 418/500
root_mean_squared_error: 412.8166
Epoch 419/500
1/1 [================== ] - Os 4ms/step - loss: 170417.5781 -
root_mean_squared_error: 412.8167
Epoch 420/500
root_mean_squared_error: 412.8166
Epoch 421/500
1/1 [=========== ] - Os 3ms/step - loss: 170417.5469 -
root_mean_squared_error: 412.8166
Epoch 422/500
root_mean_squared_error: 412.8166
Epoch 423/500
1/1 [============ ] - Os 4ms/step - loss: 170417.5469 -
root_mean_squared_error: 412.8166
Epoch 424/500
root_mean_squared_error: 412.8165
Epoch 425/500
root_mean_squared_error: 412.8166
Epoch 426/500
root_mean_squared_error: 412.8165
Epoch 427/500
root_mean_squared_error: 412.8165
Epoch 428/500
```

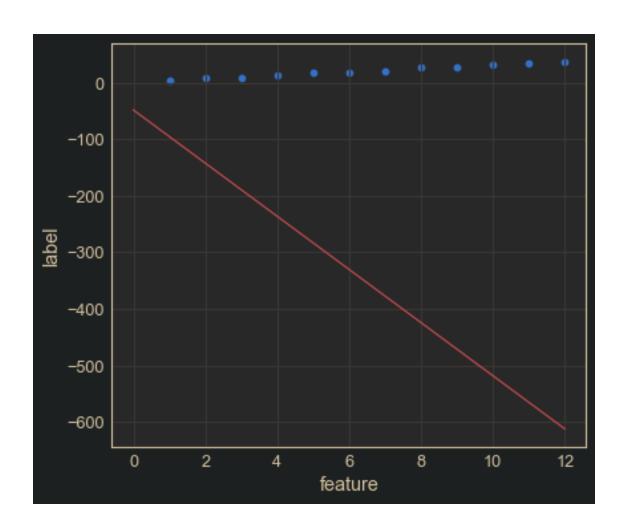
```
root_mean_squared_error: 412.8165
Epoch 429/500
1/1 [============ ] - Os 4ms/step - loss: 170417.4844 -
root_mean_squared_error: 412.8165
Epoch 430/500
root_mean_squared_error: 412.8166
Epoch 431/500
root_mean_squared_error: 412.8167
Epoch 432/500
root_mean_squared_error: 412.8168
Epoch 433/500
root_mean_squared_error: 412.8167
Epoch 434/500
root_mean_squared_error: 412.8167
Epoch 435/500
1/1 [================== ] - Os 3ms/step - loss: 170417.5625 -
root_mean_squared_error: 412.8166
Epoch 436/500
root_mean_squared_error: 412.8166
Epoch 437/500
1/1 [=========== ] - Os 3ms/step - loss: 170417.4531 -
root_mean_squared_error: 412.8165
Epoch 438/500
root_mean_squared_error: 412.8165
Epoch 439/500
1/1 [============ ] - Os 3ms/step - loss: 170417.4531 -
root_mean_squared_error: 412.8165
Epoch 440/500
root_mean_squared_error: 412.8166
Epoch 441/500
root_mean_squared_error: 412.8166
Epoch 442/500
root_mean_squared_error: 412.8166
Epoch 443/500
root_mean_squared_error: 412.8167
Epoch 444/500
```

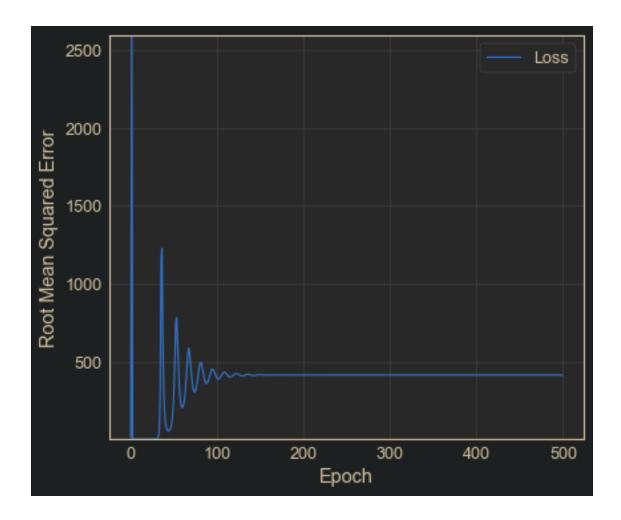
```
root_mean_squared_error: 412.8168
Epoch 445/500
1/1 [============ ] - Os 4ms/step - loss: 170417.7656 -
root_mean_squared_error: 412.8169
Epoch 446/500
root_mean_squared_error: 412.8168
Epoch 447/500
root_mean_squared_error: 412.8167
Epoch 448/500
root_mean_squared_error: 412.8167
Epoch 449/500
root_mean_squared_error: 412.8167
Epoch 450/500
root_mean_squared_error: 412.8166
Epoch 451/500
1/1 [================== ] - 0s 4ms/step - loss: 170417.5000 -
root_mean_squared_error: 412.8166
Epoch 452/500
root_mean_squared_error: 412.8164
Epoch 453/500
1/1 [=========== ] - Os 3ms/step - loss: 170417.2969 -
root_mean_squared_error: 412.8163
Epoch 454/500
root_mean_squared_error: 412.8163
Epoch 455/500
1/1 [============ ] - Os 4ms/step - loss: 170417.3594 -
root_mean_squared_error: 412.8164
Epoch 456/500
root_mean_squared_error: 412.8166
Epoch 457/500
root_mean_squared_error: 412.8167
Epoch 458/500
root_mean_squared_error: 412.8168
Epoch 459/500
root_mean_squared_error: 412.8169
Epoch 460/500
```

```
root_mean_squared_error: 412.8170
Epoch 461/500
1/1 [============ ] - Os 3ms/step - loss: 170417.8125 -
root_mean_squared_error: 412.8169
Epoch 462/500
root_mean_squared_error: 412.8168
Epoch 463/500
root_mean_squared_error: 412.8166
Epoch 464/500
root_mean_squared_error: 412.8164
Epoch 465/500
root_mean_squared_error: 412.8163
Epoch 466/500
root_mean_squared_error: 412.8162
Epoch 467/500
1/1 [================== ] - Os 3ms/step - loss: 170417.3125 -
root_mean_squared_error: 412.8163
Epoch 468/500
root_mean_squared_error: 412.8163
Epoch 469/500
1/1 [========== ] - Os 4ms/step - loss: 170417.4844 -
root_mean_squared_error: 412.8165
Epoch 470/500
root_mean_squared_error: 412.8167
Epoch 471/500
1/1 [============ ] - Os 3ms/step - loss: 170417.7656 -
root_mean_squared_error: 412.8169
Epoch 472/500
root_mean_squared_error: 412.8169
Epoch 473/500
root_mean_squared_error: 412.8168
Epoch 474/500
root_mean_squared_error: 412.8168
Epoch 475/500
root_mean_squared_error: 412.8168
Epoch 476/500
```

```
root_mean_squared_error: 412.8168
Epoch 477/500
1/1 [============ ] - Os 3ms/step - loss: 170417.5469 -
root mean squared error: 412.8166
Epoch 478/500
root_mean_squared_error: 412.8164
Epoch 479/500
root_mean_squared_error: 412.8163
Epoch 480/500
root_mean_squared_error: 412.8163
Epoch 481/500
root_mean_squared_error: 412.8163
Epoch 482/500
root_mean_squared_error: 412.8163
Epoch 483/500
1/1 [================== ] - Os 3ms/step - loss: 170417.3906 -
root_mean_squared_error: 412.8164
Epoch 484/500
root_mean_squared_error: 412.8165
Epoch 485/500
1/1 [=========== ] - Os 3ms/step - loss: 170417.6875 -
root_mean_squared_error: 412.8168
Epoch 486/500
root_mean_squared_error: 412.8168
Epoch 487/500
1/1 [============ ] - Os 3ms/step - loss: 170417.8281 -
root_mean_squared_error: 412.8170
Epoch 488/500
root_mean_squared_error: 412.8170
Epoch 489/500
root_mean_squared_error: 412.8168
Epoch 490/500
1/1 [=========== ] - Os 3ms/step - loss: 170417.6875 -
root_mean_squared_error: 412.8168
Epoch 491/500
root_mean_squared_error: 412.8166
Epoch 492/500
```

```
root_mean_squared_error: 412.8164
Epoch 493/500
1/1 [============ ] - Os 3ms/step - loss: 170417.3906 -
root mean squared error: 412.8164
Epoch 494/500
root_mean_squared_error: 412.8163
Epoch 495/500
root_mean_squared_error: 412.8163
Epoch 496/500
root_mean_squared_error: 412.8163
Epoch 497/500
root_mean_squared_error: 412.8165
Epoch 498/500
root_mean_squared_error: 412.8167
Epoch 499/500
1/1 [============ ] - Os 4ms/step - loss: 170417.5781 -
root_mean_squared_error: 412.8167
Epoch 500/500
root_mean_squared_error: 412.8168
C:\Users\Arunabh\anaconda3\envs\mlcc\lib\site-
packages\numpy\core\ asarray.py:136: VisibleDeprecationWarning: Creating an
ndarray from ragged nested sequences (which is a list-or-tuple of lists-or-
tuples-or ndarrays with different lengths or shapes) is deprecated. If you meant
to do this, you must specify 'dtype=object' when creating the ndarray
 return array(a, dtype, copy=False, order=order, subok=True)
```





The resulting model is terrible; the red line doesn't align with the blue dots. Furthermore, the loss curve oscillates like a roller coaster. An oscillating loss curve strongly suggests that the learning rate is too high.

1.12 Task 4: Find the ideal combination of epochs and learning rate

Assign values to the following two hyperparameters to make training converge as efficiently as possible:

- learning rate
- epochs

```
my_batch_size)
plot_the_model(trained_weight, trained_bias, my_feature, my_label)
plot_the_loss_curve(epochs, rmse)
```

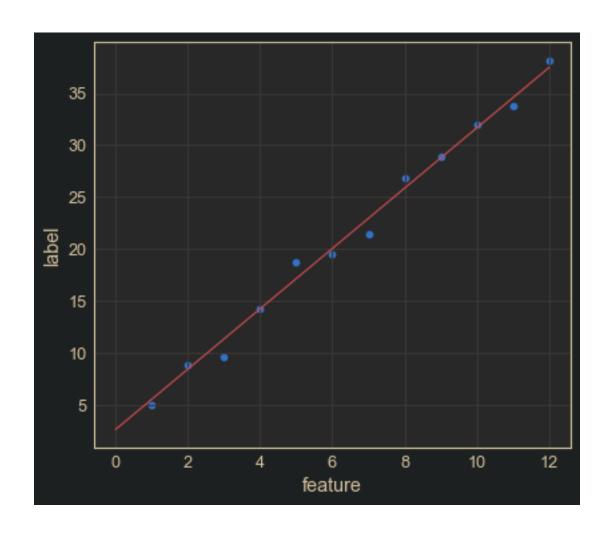
```
Epoch 1/70
root_mean_squared_error: 26.6128
Epoch 2/70
1/1 [============ ] - Os 4ms/step - loss: 527.2039 -
root_mean_squared_error: 22.9609
Epoch 3/70
1/1 [============= ] - Os 3ms/step - loss: 420.4508 -
root_mean_squared_error: 20.5049
Epoch 4/70
1/1 [============= ] - Os 4ms/step - loss: 344.1979 -
root_mean_squared_error: 18.5526
Epoch 5/70
1/1 [=============== ] - Os 3ms/step - loss: 285.4361 -
root_mean_squared_error: 16.8949
Epoch 6/70
1/1 [============ ] - Os 4ms/step - loss: 238.3073 -
root_mean_squared_error: 15.4372
Epoch 7/70
root_mean_squared_error: 14.1280
Epoch 8/70
1/1 [============= ] - Os 4ms/step - loss: 167.3302 -
root_mean_squared_error: 12.9356
Epoch 9/70
1/1 [============= ] - Os 4ms/step - loss: 140.1724 -
root_mean_squared_error: 11.8394
Epoch 10/70
root_mean_squared_error: 10.8252
Epoch 11/70
root_mean_squared_error: 9.8826
Epoch 12/70
root_mean_squared_error: 9.0042
Epoch 13/70
root_mean_squared_error: 8.1845
Epoch 14/70
1/1 [============ ] - Os 4ms/step - loss: 55.0445 -
root_mean_squared_error: 7.4192
Epoch 15/70
```

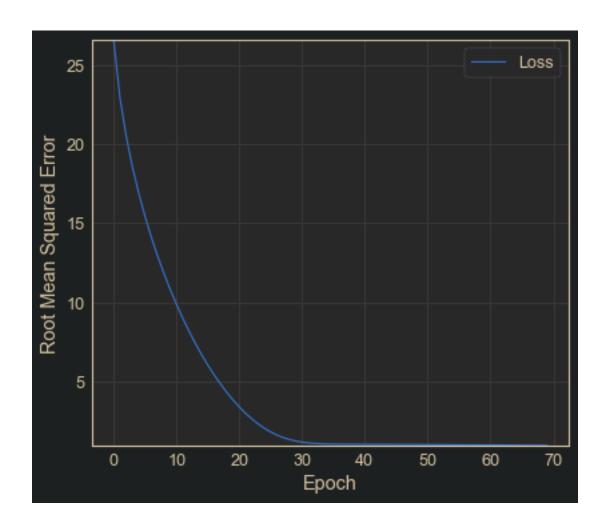
```
root_mean_squared_error: 6.7051
Epoch 16/70
root_mean_squared_error: 6.0398
Epoch 17/70
root mean squared error: 5.4214
Epoch 18/70
root_mean_squared_error: 4.8485
Epoch 19/70
1/1 [============ ] - Os 4ms/step - loss: 18.6622 -
root_mean_squared_error: 4.3200
Epoch 20/70
root_mean_squared_error: 3.8350
Epoch 21/70
1/1 [============ ] - Os 4ms/step - loss: 11.5127 -
root_mean_squared_error: 3.3930
Epoch 22/70
1/1 [============= ] - 0s 3ms/step - loss: 8.9610 -
root_mean_squared_error: 2.9935
Epoch 23/70
root_mean_squared_error: 2.6359
Epoch 24/70
1/1 [=========== ] - Os 3ms/step - loss: 5.3823 -
root_mean_squared_error: 2.3200
Epoch 25/70
root_mean_squared_error: 2.0451
Epoch 26/70
root_mean_squared_error: 1.8104
Epoch 27/70
1/1 [========== ] - Os 4ms/step - loss: 2.6072 -
root mean squared error: 1.6147
Epoch 28/70
root_mean_squared_error: 1.4561
Epoch 29/70
1/1 [============ ] - Os 4ms/step - loss: 1.7732 -
root_mean_squared_error: 1.3316
Epoch 30/70
root_mean_squared_error: 1.2375
Epoch 31/70
1/1 [========== ] - Os 4ms/step - loss: 1.3666 -
```

```
root_mean_squared_error: 1.1690
Epoch 32/70
1/1 [============ ] - Os 4ms/step - loss: 1.2568 -
root_mean_squared_error: 1.1211
Epoch 33/70
1/1 [============== ] - Os 3ms/step - loss: 1.1853 -
root mean squared error: 1.0887
Epoch 34/70
1/1 [============ ] - Os 3ms/step - loss: 1.1397 -
root_mean_squared_error: 1.0676
Epoch 35/70
1/1 [============ ] - Os 3ms/step - loss: 1.1111 -
root_mean_squared_error: 1.0541
Epoch 36/70
root_mean_squared_error: 1.0455
Epoch 37/70
1/1 [============ ] - Os 3ms/step - loss: 1.0816 -
root_mean_squared_error: 1.0400
Epoch 38/70
1/1 [=========== ] - Os 3ms/step - loss: 1.0739 -
root_mean_squared_error: 1.0363
Epoch 39/70
root_mean_squared_error: 1.0336
Epoch 40/70
1/1 [=========== ] - Os 3ms/step - loss: 1.0638 -
root_mean_squared_error: 1.0314
Epoch 41/70
root_mean_squared_error: 1.0294
Epoch 42/70
root_mean_squared_error: 1.0276
Epoch 43/70
1/1 [=========== ] - Os 4ms/step - loss: 1.0521 -
root mean squared error: 1.0257
Epoch 44/70
root_mean_squared_error: 1.0238
Epoch 45/70
1/1 [============ ] - Os 3ms/step - loss: 1.0443 -
root_mean_squared_error: 1.0219
Epoch 46/70
root_mean_squared_error: 1.0199
Epoch 47/70
1/1 [========== ] - Os 3ms/step - loss: 1.0360 -
```

```
root_mean_squared_error: 1.0178
Epoch 48/70
1/1 [============ ] - Os 3ms/step - loss: 1.0317 -
root_mean_squared_error: 1.0157
Epoch 49/70
1/1 [============= ] - Os 2ms/step - loss: 1.0273 -
root mean squared error: 1.0135
Epoch 50/70
1/1 [============ ] - Os 3ms/step - loss: 1.0228 -
root_mean_squared_error: 1.0113
Epoch 51/70
1/1 [============ ] - Os 2ms/step - loss: 1.0182 -
root_mean_squared_error: 1.0090
Epoch 52/70
root_mean_squared_error: 1.0067
Epoch 53/70
1/1 [============ ] - Os 3ms/step - loss: 1.0087 -
root_mean_squared_error: 1.0043
Epoch 54/70
1/1 [============ ] - 0s 4ms/step - loss: 1.0038 -
root_mean_squared_error: 1.0019
Epoch 55/70
root_mean_squared_error: 0.9994
Epoch 56/70
1/1 [============ ] - Os 5ms/step - loss: 0.9938 -
root_mean_squared_error: 0.9969
Epoch 57/70
1/1 [========== ] - Os 3ms/step - loss: 0.9888 -
root_mean_squared_error: 0.9944
Epoch 58/70
root_mean_squared_error: 0.9918
Epoch 59/70
1/1 [=========== ] - Os 3ms/step - loss: 0.9786 -
root mean squared error: 0.9892
Epoch 60/70
root_mean_squared_error: 0.9866
Epoch 61/70
1/1 [============ ] - Os 3ms/step - loss: 0.9683 -
root_mean_squared_error: 0.9840
Epoch 62/70
1/1 [========== ] - Os 2ms/step - loss: 0.9631 -
root_mean_squared_error: 0.9814
Epoch 63/70
1/1 [========== ] - 0s 4ms/step - loss: 0.9580 -
```

```
root_mean_squared_error: 0.9788
Epoch 64/70
root_mean_squared_error: 0.9762
Epoch 65/70
1/1 [========== ] - Os 4ms/step - loss: 0.9480 -
root_mean_squared_error: 0.9736
Epoch 66/70
1/1 [============ ] - Os 3ms/step - loss: 0.9431 -
root_mean_squared_error: 0.9711
Epoch 67/70
root_mean_squared_error: 0.9686
Epoch 68/70
root_mean_squared_error: 0.9662
Epoch 69/70
root_mean_squared_error: 0.9638
Epoch 70/70
1/1 [========== ] - Os 3ms/step - loss: 0.9245 -
root_mean_squared_error: 0.9615
C:\Users\Arunabh\anaconda3\envs\mlcc\lib\site-
packages\numpy\core\_asarray.py:136: VisibleDeprecationWarning: Creating an
ndarray from ragged nested sequences (which is a list-or-tuple of lists-or-
tuples-or ndarrays with different lengths or shapes) is deprecated. If you meant
to do this, you must specify 'dtype=object' when creating the ndarray
 return array(a, dtype, copy=False, order=order, subok=True)
```





```
[]: #@title Double-click to view a possible solution

learning_rate=0.14
epochs=70
my_batch_size=12

my_model = build_model(learning_rate)
trained_weight, trained_bias, epochs, rmse = train_model(my_model, my_feature, my_label, epochs, my_batch_size)
plot_the_model(trained_weight, trained_bias, my_feature, my_label)
plot_the_loss_curve(epochs, rmse)
```

1.13 Task 5: Adjust the batch size

The system recalculates the model's loss value and adjusts the model's weights and bias after each **iteration**. Each iteration is the span in which the system processes one batch. For example, if the **batch size** is 6, then the system recalculates the model's loss value and adjusts the model's

weights and bias after processing every 6 examples.

One **epoch** spans sufficient iterations to process every example in the dataset. For example, if the batch size is 12, then each epoch lasts one iteration. However, if the batch size is 6, then each epoch consumes two iterations.

It is tempting to simply set the batch size to the number of examples in the dataset (12, in this case). However, the model might actually train faster on smaller batches. Conversely, very small batches might not contain enough information to help the model converge.

Experiment with batch_size in the following code cell. What's the smallest integer you can set for batch_size and still have the model converge in a hundred epochs?

```
root_mean_squared_error: 26.8983
Epoch 3/100
1/1 [============= ] - Os 3ms/step - loss: 674.6304 -
root_mean_squared_error: 25.9736
Epoch 4/100
1/1 [============= ] - Os 3ms/step - loss: 635.5685 -
root_mean_squared_error: 25.2105
Epoch 5/100
1/1 [============= ] - Os 3ms/step - loss: 602.2419 -
root_mean_squared_error: 24.5406
Epoch 6/100
1/1 [============== ] - Os 3ms/step - loss: 572.7701 -
root_mean_squared_error: 23.9326
Epoch 7/100
1/1 [========== ] - Os 3ms/step - loss: 546.1123 -
root_mean_squared_error: 23.3690
Epoch 8/100
1/1 [============ ] - Os 4ms/step - loss: 521.6245 -
root_mean_squared_error: 22.8391
Epoch 9/100
```

```
root_mean_squared_error: 22.3356
Epoch 10/100
1/1 [============ ] - Os 4ms/step - loss: 477.5688 -
root_mean_squared_error: 21.8533
Epoch 11/100
1/1 [=============== ] - Os 3ms/step - loss: 457.4775 -
root_mean_squared_error: 21.3887
Epoch 12/100
1/1 [============ ] - Os 3ms/step - loss: 438.4364 -
root_mean_squared_error: 20.9389
Epoch 13/100
1/1 [============ ] - Os 3ms/step - loss: 420.3159 -
root_mean_squared_error: 20.5016
Epoch 14/100
root_mean_squared_error: 20.0752
Epoch 15/100
1/1 [============ ] - Os 3ms/step - loss: 386.4466 -
root_mean_squared_error: 19.6582
Epoch 16/100
root_mean_squared_error: 19.2496
Epoch 17/100
root_mean_squared_error: 18.8484
Epoch 18/100
1/1 [============= ] - Os 3ms/step - loss: 340.5414 -
root_mean_squared_error: 18.4538
Epoch 19/100
1/1 [============= ] - Os 4ms/step - loss: 326.3479 -
root_mean_squared_error: 18.0651
Epoch 20/100
1/1 [============ ] - Os 3ms/step - loss: 312.6476 -
root_mean_squared_error: 17.6818
Epoch 21/100
1/1 [=========== ] - Os 3ms/step - loss: 299.4120 -
root_mean_squared_error: 17.3035
Epoch 22/100
root_mean_squared_error: 16.9298
Epoch 23/100
1/1 [============ ] - Os 3ms/step - loss: 274.2394 -
root_mean_squared_error: 16.5602
Epoch 24/100
1/1 [=========== ] - Os 3ms/step - loss: 262.2621 -
root_mean_squared_error: 16.1945
Epoch 25/100
1/1 [========== ] - Os 3ms/step - loss: 250.6681 -
```

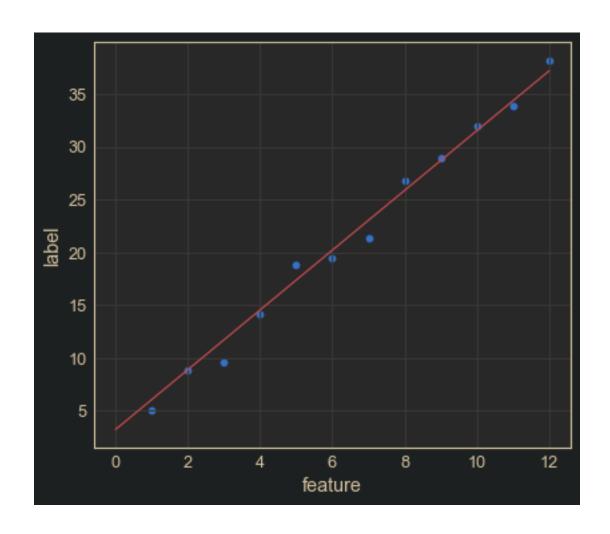
```
root_mean_squared_error: 15.8325
Epoch 26/100
1/1 [============ ] - Os 3ms/step - loss: 239.4428 -
root_mean_squared_error: 15.4739
Epoch 27/100
1/1 [=============== ] - Os 3ms/step - loss: 228.5734 -
root_mean_squared_error: 15.1186
Epoch 28/100
1/1 [============ ] - Os 4ms/step - loss: 218.0483 -
root_mean_squared_error: 14.7665
Epoch 29/100
1/1 [============= ] - Os 3ms/step - loss: 207.8571 -
root_mean_squared_error: 14.4173
Epoch 30/100
root_mean_squared_error: 14.0709
Epoch 31/100
1/1 [============ ] - Os 4ms/step - loss: 188.4402 -
root_mean_squared_error: 13.7274
Epoch 32/100
1/1 [============ ] - Os 3ms/step - loss: 179.1983 -
root_mean_squared_error: 13.3865
Epoch 33/100
root_mean_squared_error: 13.0483
Epoch 34/100
1/1 [============= ] - Os 3ms/step - loss: 161.6122 -
root_mean_squared_error: 12.7127
Epoch 35/100
1/1 [============== ] - Os 4ms/step - loss: 153.2555 -
root_mean_squared_error: 12.3796
Epoch 36/100
root_mean_squared_error: 12.0492
Epoch 37/100
1/1 [============= ] - Os 3ms/step - loss: 137.3866 -
root_mean_squared_error: 11.7212
Epoch 38/100
root_mean_squared_error: 11.3958
Epoch 39/100
1/1 [============ ] - Os 3ms/step - loss: 122.6098 -
root_mean_squared_error: 11.0729
Epoch 40/100
1/1 [=========== ] - Os 3ms/step - loss: 115.6194 -
root_mean_squared_error: 10.7526
Epoch 41/100
1/1 [========== ] - Os 3ms/step - loss: 108.8883 -
```

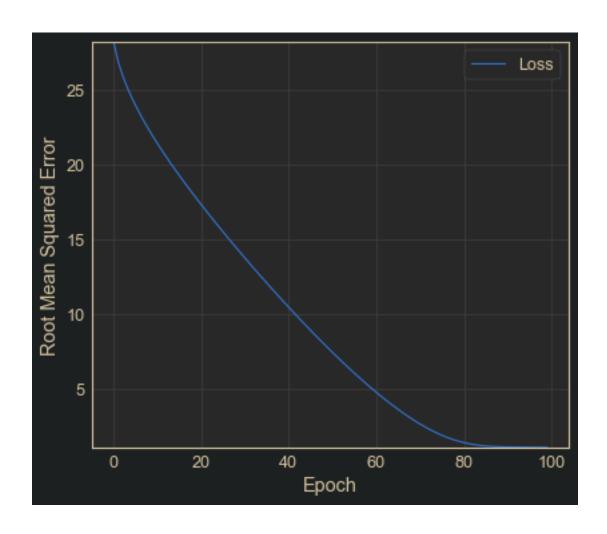
```
root_mean_squared_error: 10.4350
Epoch 42/100
1/1 [============ ] - Os 3ms/step - loss: 102.4125 -
root_mean_squared_error: 10.1199
Epoch 43/100
root mean squared error: 9.8075
Epoch 44/100
root_mean_squared_error: 9.4979
Epoch 45/100
root_mean_squared_error: 9.1911
Epoch 46/100
root_mean_squared_error: 8.8871
Epoch 47/100
root_mean_squared_error: 8.5861
Epoch 48/100
root_mean_squared_error: 8.2881
Epoch 49/100
root_mean_squared_error: 7.9933
Epoch 50/100
root_mean_squared_error: 7.7017
Epoch 51/100
root_mean_squared_error: 7.4134
Epoch 52/100
root_mean_squared_error: 7.1286
Epoch 53/100
root mean squared error: 6.8475
Epoch 54/100
root_mean_squared_error: 6.5700
Epoch 55/100
1/1 [============ ] - Os 3ms/step - loss: 39.6457 -
root_mean_squared_error: 6.2965
Epoch 56/100
1/1 [=========== ] - Os 3ms/step - loss: 36.3249 -
root_mean_squared_error: 6.0270
Epoch 57/100
1/1 [============ - - 0s 5ms/step - loss: 33.1981 -
```

```
root_mean_squared_error: 5.7618
Epoch 58/100
1/1 [============ ] - Os 4ms/step - loss: 30.2607 -
root_mean_squared_error: 5.5010
Epoch 59/100
root mean squared error: 5.2448
Epoch 60/100
root_mean_squared_error: 4.9935
Epoch 61/100
1/1 [============ ] - Os 4ms/step - loss: 22.5360 -
root_mean_squared_error: 4.7472
Epoch 62/100
root_mean_squared_error: 4.5063
Epoch 63/100
root_mean_squared_error: 4.2709
Epoch 64/100
root_mean_squared_error: 4.0414
Epoch 65/100
1/1 [============== ] - 0s 3ms/step - loss: 14.5780 -
root_mean_squared_error: 3.8181
Epoch 66/100
root_mean_squared_error: 3.6013
Epoch 67/100
root_mean_squared_error: 3.3912
Epoch 68/100
root_mean_squared_error: 3.1884
Epoch 69/100
1/1 [========== ] - Os 3ms/step - loss: 8.9584 -
root_mean_squared_error: 2.9931
Epoch 70/100
root_mean_squared_error: 2.8057
Epoch 71/100
1/1 [============ ] - Os 3ms/step - loss: 6.8995 -
root_mean_squared_error: 2.6267
Epoch 72/100
1/1 [=========== ] - Os 3ms/step - loss: 6.0342 -
root_mean_squared_error: 2.4565
Epoch 73/100
1/1 [========== ] - Os 3ms/step - loss: 5.2692 -
```

```
root_mean_squared_error: 2.2955
Epoch 74/100
root_mean_squared_error: 2.1442
Epoch 75/100
1/1 [============= ] - Os 4ms/step - loss: 4.0117 -
root mean squared error: 2.0029
Epoch 76/100
1/1 [============ ] - Os 3ms/step - loss: 3.5052 -
root_mean_squared_error: 1.8722
Epoch 77/100
1/1 [============ ] - Os 3ms/step - loss: 3.0707 -
root_mean_squared_error: 1.7523
Epoch 78/100
root_mean_squared_error: 1.6436
Epoch 79/100
1/1 [============ ] - Os 3ms/step - loss: 2.3906 -
root_mean_squared_error: 1.5462
Epoch 80/100
1/1 [=========== ] - Os 3ms/step - loss: 2.1317 -
root_mean_squared_error: 1.4600
Epoch 81/100
root_mean_squared_error: 1.3851
Epoch 82/100
1/1 [========== ] - Os 3ms/step - loss: 1.7447 -
root_mean_squared_error: 1.3209
Epoch 83/100
1/1 [=========== ] - Os 4ms/step - loss: 1.6051 -
root_mean_squared_error: 1.2669
Epoch 84/100
root_mean_squared_error: 1.2224
Epoch 85/100
1/1 [=========== ] - Os 4ms/step - loss: 1.4075 -
root mean squared error: 1.1864
Epoch 86/100
root_mean_squared_error: 1.1578
Epoch 87/100
1/1 [============ ] - Os 3ms/step - loss: 1.2894 -
root_mean_squared_error: 1.1355
Epoch 88/100
1/1 [========== ] - Os 4ms/step - loss: 1.2509 -
root_mean_squared_error: 1.1184
Epoch 89/100
1/1 [========= ] - Os 3ms/step - loss: 1.2222 -
```

```
root_mean_squared_error: 1.1055
Epoch 90/100
1/1 [========== ] - Os 3ms/step - loss: 1.2010 -
root_mean_squared_error: 1.0959
Epoch 91/100
1/1 [============== ] - Os 3ms/step - loss: 1.1853 -
root mean squared error: 1.0887
Epoch 92/100
1/1 [============ ] - Os 4ms/step - loss: 1.1735 -
root_mean_squared_error: 1.0833
Epoch 93/100
root_mean_squared_error: 1.0791
Epoch 94/100
root_mean_squared_error: 1.0758
Epoch 95/100
root_mean_squared_error: 1.0731
Epoch 96/100
1/1 [=========== ] - Os 4ms/step - loss: 1.1463 -
root_mean_squared_error: 1.0706
Epoch 97/100
root_mean_squared_error: 1.0684
Epoch 98/100
1/1 [============ ] - Os 4ms/step - loss: 1.1368 -
root_mean_squared_error: 1.0662
Epoch 99/100
root_mean_squared_error: 1.0641
Epoch 100/100
root_mean_squared_error: 1.0619
C:\Users\Arunabh\anaconda3\envs\mlcc\lib\site-
packages\numpy\core\_asarray.py:136: VisibleDeprecationWarning: Creating an
ndarray from ragged nested sequences (which is a list-or-tuple of lists-or-
tuples-or ndarrays with different lengths or shapes) is deprecated. If you meant
to do this, you must specify 'dtype=object' when creating the ndarray
 return array(a, dtype, copy=False, order=order, subok=True)
```





```
root_mean_squared_error: 28.4640
Epoch 3/125
1/1 [============ ] - Os 4ms/step - loss: 758.3486 -
root_mean_squared_error: 27.5381
Epoch 4/125
1/1 [============== ] - Os 3ms/step - loss: 716.8121 -
root_mean_squared_error: 26.7733
Epoch 5/125
1/1 [============ ] - Os 4ms/step - loss: 681.2937 -
root_mean_squared_error: 26.1016
Epoch 6/125
root_mean_squared_error: 25.4915
Epoch 7/125
root_mean_squared_error: 24.9257
Epoch 8/125
1/1 [============ ] - Os 4ms/step - loss: 595.0396 -
root_mean_squared_error: 24.3934
Epoch 9/125
root_mean_squared_error: 23.8874
Epoch 10/125
1/1 [============ ] - Os 3ms/step - loss: 547.6794 -
root_mean_squared_error: 23.4026
Epoch 11/125
1/1 [============= ] - Os 4ms/step - loss: 526.0222 -
root_mean_squared_error: 22.9352
Epoch 12/125
root_mean_squared_error: 22.4824
Epoch 13/125
root_mean_squared_error: 22.0422
Epoch 14/125
1/1 [============ ] - Os 4ms/step - loss: 467.1057 -
root_mean_squared_error: 21.6126
Epoch 15/125
root_mean_squared_error: 21.1924
Epoch 16/125
1/1 [============ ] - Os 3ms/step - loss: 431.8253 -
root_mean_squared_error: 20.7804
Epoch 17/125
1/1 [============ ] - Os 4ms/step - loss: 415.1673 -
root_mean_squared_error: 20.3757
Epoch 18/125
1/1 [========== ] - Os 3ms/step - loss: 399.0956 -
```

```
root_mean_squared_error: 19.9774
Epoch 19/125
1/1 [============ ] - Os 3ms/step - loss: 383.5691 -
root_mean_squared_error: 19.5849
Epoch 20/125
1/1 [=============== ] - Os 4ms/step - loss: 368.5528 -
root_mean_squared_error: 19.1977
Epoch 21/125
1/1 [============ ] - Os 3ms/step - loss: 354.0167 -
root_mean_squared_error: 18.8153
Epoch 22/125
root_mean_squared_error: 18.4373
Epoch 23/125
root_mean_squared_error: 18.0634
Epoch 24/125
1/1 [============ ] - Os 3ms/step - loss: 313.0478 -
root_mean_squared_error: 17.6932
Epoch 25/125
root_mean_squared_error: 17.3264
Epoch 26/125
root_mean_squared_error: 16.9630
Epoch 27/125
1/1 [============= ] - Os 4ms/step - loss: 275.6482 -
root_mean_squared_error: 16.6027
Epoch 28/125
root_mean_squared_error: 16.2452
Epoch 29/125
root_mean_squared_error: 15.8906
Epoch 30/125
1/1 [============ ] - Os 3ms/step - loss: 241.4495 -
root_mean_squared_error: 15.5386
Epoch 31/125
root_mean_squared_error: 15.1893
Epoch 32/125
1/1 [============ ] - Os 3ms/step - loss: 220.2959 -
root_mean_squared_error: 14.8424
Epoch 33/125
1/1 [=========== ] - Os 3ms/step - loss: 210.1891 -
root_mean_squared_error: 14.4979
Epoch 34/125
1/1 [========== ] - Os 3ms/step - loss: 200.3868 -
```

```
root_mean_squared_error: 14.1558
Epoch 35/125
1/1 [============ ] - Os 3ms/step - loss: 190.8828 -
root_mean_squared_error: 13.8160
Epoch 36/125
1/1 [=============== ] - Os 3ms/step - loss: 181.6718 -
root_mean_squared_error: 13.4786
Epoch 37/125
1/1 [============= ] - Os 4ms/step - loss: 172.7483 -
root_mean_squared_error: 13.1434
Epoch 38/125
root_mean_squared_error: 12.8105
Epoch 39/125
root_mean_squared_error: 12.4798
Epoch 40/125
1/1 [============ ] - Os 4ms/step - loss: 147.6566 -
root_mean_squared_error: 12.1514
Epoch 41/125
root_mean_squared_error: 11.8253
Epoch 42/125
root_mean_squared_error: 11.5015
Epoch 43/125
1/1 [============== ] - Os 4ms/step - loss: 124.9936 -
root_mean_squared_error: 11.1801
Epoch 44/125
root_mean_squared_error: 10.8610
Epoch 45/125
root_mean_squared_error: 10.5443
Epoch 46/125
1/1 [============= ] - Os 4ms/step - loss: 104.6553 -
root_mean_squared_error: 10.2301
Epoch 47/125
root_mean_squared_error: 9.9185
Epoch 48/125
root_mean_squared_error: 9.6094
Epoch 49/125
1/1 [=========== ] - Os 3ms/step - loss: 86.5451 -
root_mean_squared_error: 9.3030
Epoch 50/125
1/1 [============ - - 0s 4ms/step - loss: 80.9873 -
```

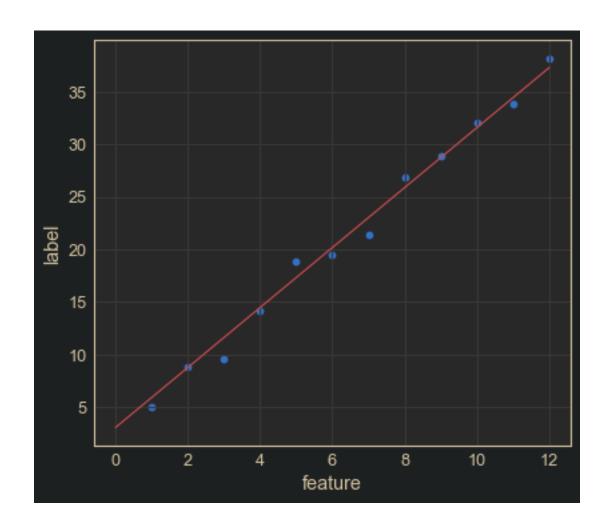
```
root_mean_squared_error: 8.9993
Epoch 51/125
root_mean_squared_error: 8.6984
Epoch 52/125
root mean squared error: 8.4005
Epoch 53/125
root_mean_squared_error: 8.1056
Epoch 54/125
root_mean_squared_error: 7.8139
Epoch 55/125
root_mean_squared_error: 7.5253
Epoch 56/125
root_mean_squared_error: 7.2402
Epoch 57/125
root_mean_squared_error: 6.9586
Epoch 58/125
root_mean_squared_error: 6.6806
Epoch 59/125
root_mean_squared_error: 6.4064
Epoch 60/125
root_mean_squared_error: 6.1362
Epoch 61/125
root_mean_squared_error: 5.8702
Epoch 62/125
root mean squared error: 5.6085
Epoch 63/125
root_mean_squared_error: 5.3513
Epoch 64/125
1/1 [============ ] - Os 4ms/step - loss: 25.9993 -
root_mean_squared_error: 5.0990
Epoch 65/125
1/1 [=========== ] - Os 3ms/step - loss: 23.5377 -
root_mean_squared_error: 4.8516
Epoch 66/125
1/1 [============ - - 0s 3ms/step - loss: 21.2467 -
```

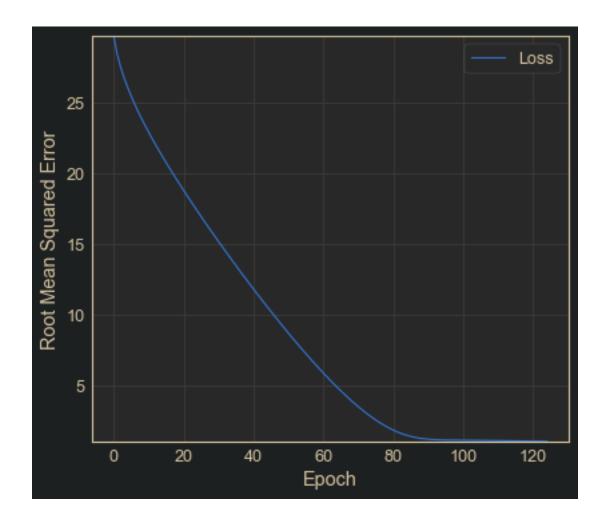
```
root_mean_squared_error: 4.6094
Epoch 67/125
root_mean_squared_error: 4.3728
Epoch 68/125
root_mean_squared_error: 4.1419
Epoch 69/125
root_mean_squared_error: 3.9171
Epoch 70/125
root_mean_squared_error: 3.6987
Epoch 71/125
root_mean_squared_error: 3.4870
Epoch 72/125
1/1 [=========== ] - Os 3ms/step - loss: 10.7744 -
root_mean_squared_error: 3.2824
Epoch 73/125
1/1 [=========== ] - Os 3ms/step - loss: 9.5192 -
root_mean_squared_error: 3.0853
Epoch 74/125
root_mean_squared_error: 2.8960
Epoch 75/125
1/1 [=========== ] - Os 3ms/step - loss: 7.3715 -
root_mean_squared_error: 2.7151
Epoch 76/125
root_mean_squared_error: 2.5428
Epoch 77/125
root_mean_squared_error: 2.3796
Epoch 78/125
1/1 [=========== ] - Os 4ms/step - loss: 4.9553 -
root_mean_squared_error: 2.2260
Epoch 79/125
root_mean_squared_error: 2.0825
Epoch 80/125
1/1 [============ ] - Os 3ms/step - loss: 3.8000 -
root_mean_squared_error: 1.9494
Epoch 81/125
1/1 [=========== ] - Os 4ms/step - loss: 3.3379 -
root_mean_squared_error: 1.8270
Epoch 82/125
1/1 [========== ] - Os 4ms/step - loss: 2.9436 -
```

```
root_mean_squared_error: 1.7157
Epoch 83/125
1/1 [============ ] - Os 4ms/step - loss: 2.6103 -
root_mean_squared_error: 1.6156
Epoch 84/125
1/1 [============= ] - Os 4ms/step - loss: 2.3314 -
root_mean_squared_error: 1.5269
Epoch 85/125
1/1 [=========== ] - Os 4ms/step - loss: 2.1004 -
root_mean_squared_error: 1.4493
Epoch 86/125
1/1 [============ ] - Os 3ms/step - loss: 1.9113 -
root_mean_squared_error: 1.3825
Epoch 87/125
root_mean_squared_error: 1.3260
Epoch 88/125
1/1 [============ ] - Os 3ms/step - loss: 1.6361 -
root_mean_squared_error: 1.2791
Epoch 89/125
1/1 [============= ] - 0s 3ms/step - loss: 1.5397 -
root_mean_squared_error: 1.2408
Epoch 90/125
root_mean_squared_error: 1.2102
Epoch 91/125
1/1 [============ ] - Os 4ms/step - loss: 1.4067 -
root_mean_squared_error: 1.1861
Epoch 92/125
1/1 [=========== ] - Os 3ms/step - loss: 1.3628 -
root_mean_squared_error: 1.1674
Epoch 93/125
root_mean_squared_error: 1.1531
Epoch 94/125
1/1 [========== ] - Os 3ms/step - loss: 1.3047 -
root_mean_squared_error: 1.1422
Epoch 95/125
root_mean_squared_error: 1.1340
Epoch 96/125
1/1 [============ ] - Os 3ms/step - loss: 1.2716 -
root_mean_squared_error: 1.1277
Epoch 97/125
1/1 [========== ] - Os 3ms/step - loss: 1.2605 -
root_mean_squared_error: 1.1227
Epoch 98/125
1/1 [========== ] - Os 3ms/step - loss: 1.2515 -
```

```
root_mean_squared_error: 1.1187
Epoch 99/125
1/1 [========= ] - Os 4ms/step - loss: 1.2440 -
root_mean_squared_error: 1.1153
Epoch 100/125
1/1 [============= ] - Os 3ms/step - loss: 1.2372 -
root_mean_squared_error: 1.1123
Epoch 101/125
1/1 [=========== ] - Os 3ms/step - loss: 1.2309 -
root_mean_squared_error: 1.1095
Epoch 102/125
1/1 [============ ] - Os 4ms/step - loss: 1.2249 -
root_mean_squared_error: 1.1067
Epoch 103/125
root_mean_squared_error: 1.1040
Epoch 104/125
1/1 [============ ] - Os 5ms/step - loss: 1.2127 -
root_mean_squared_error: 1.1012
Epoch 105/125
1/1 [============= ] - 0s 3ms/step - loss: 1.2065 -
root_mean_squared_error: 1.0984
Epoch 106/125
1/1 [========== ] - Os 3ms/step - loss: 1.2001 -
root_mean_squared_error: 1.0955
Epoch 107/125
1/1 [============ ] - Os 4ms/step - loss: 1.1936 -
root_mean_squared_error: 1.0925
Epoch 108/125
root_mean_squared_error: 1.0894
Epoch 109/125
root_mean_squared_error: 1.0862
Epoch 110/125
1/1 [=========== ] - Os 3ms/step - loss: 1.1728 -
root_mean_squared_error: 1.0829
Epoch 111/125
root_mean_squared_error: 1.0796
Epoch 112/125
1/1 [============= ] - Os 3ms/step - loss: 1.1580 -
root_mean_squared_error: 1.0761
Epoch 113/125
root_mean_squared_error: 1.0725
Epoch 114/125
1/1 [========= ] - Os 3ms/step - loss: 1.1425 -
```

```
root_mean_squared_error: 1.0689
Epoch 115/125
1/1 [========== ] - Os 3ms/step - loss: 1.1346 -
root_mean_squared_error: 1.0652
Epoch 116/125
1/1 [============== ] - Os 4ms/step - loss: 1.1265 -
root_mean_squared_error: 1.0614
Epoch 117/125
1/1 [=========== ] - Os 4ms/step - loss: 1.1183 -
root_mean_squared_error: 1.0575
Epoch 118/125
1/1 [============ ] - Os 4ms/step - loss: 1.1100 -
root_mean_squared_error: 1.0536
Epoch 119/125
root_mean_squared_error: 1.0496
Epoch 120/125
root_mean_squared_error: 1.0455
Epoch 121/125
1/1 [=========== ] - Os 4ms/step - loss: 1.0846 -
root_mean_squared_error: 1.0414
Epoch 122/125
1/1 [=========== ] - Os 4ms/step - loss: 1.0760 -
root_mean_squared_error: 1.0373
Epoch 123/125
1/1 [=========== ] - Os 3ms/step - loss: 1.0674 -
root_mean_squared_error: 1.0331
Epoch 124/125
root_mean_squared_error: 1.0290
Epoch 125/125
root_mean_squared_error: 1.0248
C:\Users\Arunabh\anaconda3\envs\mlcc\lib\site-
packages\numpy\core\_asarray.py:136: VisibleDeprecationWarning: Creating an
ndarray from ragged nested sequences (which is a list-or-tuple of lists-or-
tuples-or ndarrays with different lengths or shapes) is deprecated. If you meant
to do this, you must specify 'dtype=object' when creating the ndarray
 return array(a, dtype, copy=False, order=order, subok=True)
```





1.14 Summary of hyperparameter tuning

Most machine learning problems require a lot of hyperparameter tuning. Unfortunately, we can't provide concrete tuning rules for every model. Lowering the learning rate can help one model converge efficiently but make another model converge much too slowly. You must experiment to find the best set of hyperparameters for your dataset. That said, here are a few rules of thumb:

- Training loss should steadily decrease, steeply at first, and then more slowly until the slope of the curve reaches or approaches zero.
- If the training loss does not converge, train for more epochs.
- If the training loss decreases too slowly, increase the learning rate. Note that setting the training loss too high may also prevent training loss from converging.
- If the training loss varies wildly (that is, the training loss jumps around), decrease the learning rate
- Lowering the learning rate while increasing the number of epochs or the batch size is often a good combination.
- Setting the batch size to a *very* small batch number can also cause instability. First, try large batch size values. Then, decrease the batch size until you see degradation.
- For real-world datasets consisting of a very large number of examples, the entire dataset might

not fit into memory. In such cases, you'll need to reduce the batch size to enable a batch to fit into memory.

Remember: the ideal combination of hyperparameters is data dependent, so you must always experiment and verify.