Your grade: 90%

Your latest: 90% · Your highest: 90% · To pass you need at least 80%. We keep your highest score.

Next item \rightarrow

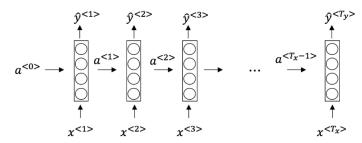
- 1. Suppose your training examples are sentences (sequences of words). Which of the following refers to the j^{th} word in the i^{th} training example?
- 1/1 point

- $\bigcirc \ x^{(i) < j >}$
- $\bigcirc \ x^{< i > (j)}$
- $\bigcirc \ x^{(j) < i >}$
- $\bigcirc \ x^{< j > (i)}$
- **⊘** Correct

We index into the i^{th} row first to get the i^{th} training example (represented by parentheses), then the j^{th} column to get the j^{th} word (represented by the brackets).

2. Consider this RNN:

1/1 point



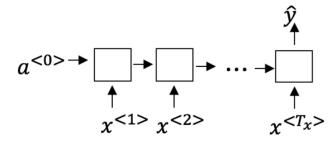
This specific type of architecture is appropriate when:

- \bigcirc $T_x = T_y$
- $\bigcap T_x < T_y$
- $\bigcap T_x > T_y$
- $\bigcap T_x = 1$
 - Correct
 Correct

It is appropriate when every input should have an output.

3. To which of these tasks would you apply a many-to-one RNN architecture?

1/1 point



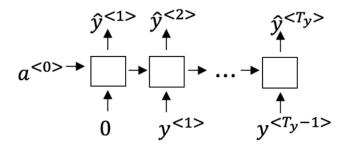
- ☐ Image classification (input an image and output a label)
- Music genre recognition
- **⊘** Correct

This is an example of many-to-one architecture.

- Language recognition from speech (input an audio clip and output a label indicating the language being spoken)
- **⊘** Correct

This is an example of many-to-one architecture.

Speech recognition (input an audio clip and output a transcript)



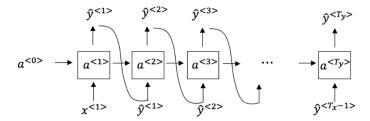
True/False: At the t^{th} time step the RNN is estimating $P(y^{< t>} \mid y^{< 1>}, y^{< 2>}, \dots, y^{< t-1>})$

- O False
- True
- **⊘** Correct

Yes, in a training model we try to predict the next step based on knowledge of all prior steps.

5. You have finished training a language model RNN and are using it to sample random sentences, as follows:

1/1 point



 $\label{thm:continuity} True/False: In this sample sentence, step t uses the probabilities output by the RNN to pick the highest probability word for that time-step. Then it passes the ground-truth word from the training set to the next time-step.$

- O True
- False
- **⊘** Correct

The probabilities output by the RNN are not used to pick the highest probability word and the ground-truth word from the training set is not the input to the next time-step.

6. True/False: If you are training an RNN model, and find that your weights and activations are all taking on the value of NaN ("Not a Number") then you have an exploding gradient problem.

1/1 point

- O False
- True
- **⊘** Correct

Correct! Exploding gradients happen when large error gradients accumulate and result in very large updates to the NN model weights during training. These weights can become too large and cause an overflow, identified as NaN.

7. Suppose you are training an LSTM. You have a 10000 word vocabulary, and are using an LSTM with 100-dimensional activations $a^{<t>}$. What is the dimension of Γ_u at each time step?

1/1 point

- O 1
- 100
- O 300
- 0 10000

⊘ Correct

Correct, Γ_u is a vector of dimension equal to the number of hidden units in the LSTM.

GRU

$$\begin{split} \tilde{c}^{< t>} &= \tanh(W_c [\Gamma_r * c^{< t-1>}, x^{< t>}] + b_c) \\ \Gamma_u &= \sigma(W_u [c^{< t-1>}, x^{< t>}] + b_u) \\ \Gamma_r &= \sigma(W_r [c^{< t-1>}, x^{< t>}] + b_r) \\ c^{< t>} &= \Gamma_u * \tilde{c}^{< t>} + (1 - \Gamma_u) * c^{< t-1>} \\ a^{< t>} &= c^{< t>} \end{split}$$

- O Sarah's model (removing \(\Gamma \)), because if \(\Gamma \) for a timestep, the gradient can propagate back through that timestep without much decay.
- O Sarah's model (removing \(\Pi \)), because if \(\Gamma \) a timestep, the gradient can propagate back through that timestep without much decay.
- Ashely's model (removing Γr), because if Γu≈1 for a timestep, the gradient can propagate back through that timestep without much decay.
- Ashely's model (removing Γr), because if Γu≈0 for a timestep, the gradient can propagate back through that timestep without much decay.
- **⊗** Incorrect

No. For the signal to backpropagate without vanishing, we need $c^{< t>}$ to be highly dependent on

True/False: Using the equations for the GRU and LSTM below the Update Gate and Forget Gate in the LSTM play a different role to Γu and 1- Γu .

1/1 point

1/1 point

GRU

$$\begin{aligned} & \text{GRU} & \text{LSTM} \\ & \bar{c}^{< t>} = \tanh(W_c [\Gamma_r * c^{< t-1>}, x^{< t>}] + b_c) & \bar{c}^{< t>} = \tanh(W_c [a^{< t-1>}, x^{< t>}] + b_c) \\ & \Gamma_u = \sigma(W_u [c^{< t-1>}, x^{< t>}] + b_u) & \Gamma_u = \sigma(W_u [a^{< t-1>}, x^{< t>}] + b_u) \\ & \Gamma_r = \sigma(W_r [c^{< t-1>}, x^{< t>}] + b_r) & \Gamma_f = \sigma(W_f [a^{< t-1>}, x^{< t>}] + b_f) \\ & c^{< t>} = \Gamma_u * \bar{c}^{< t>} + (1 - \Gamma_u) * c^{< t-1>} & \Gamma_o = \sigma(W_o [a^{< t-1>}, x^{< t>}] + b_o) \\ & a^{< t>} = c^{< t>} & c^{< t>} = \Gamma_u * \bar{c}^{< t>} + \Gamma_f * c^{< t-1>} \end{aligned}$$

 $a^{< t>} = \Gamma_o * \tanh c^{< t>}$

- True
- O False

Correct! Instead of using Γu to compute $1 - \Gamma u$, LSTM uses 2 gates (Γu and Γf) to compute the final value of the hidden state. So, Γf is used instead of 1 - $\Gamma u.$

- 10. Your mood is heavily dependent on the current and past few days' weather. You've collected data for the past 365 days on the weather, which you represent as a sequence as $x^{<1>},\dots,x^{<365>}$. You've also collected data on your mood, which you represent as $y^{<1>},\dots,y^{<365>}$. You'd like to build a model to map from $x \rightarrow y$. Should you use a Unidirectional RNN or Bidirectional RNN for this problem?
 - O Bidirectional RNN, because this allows the prediction of mood on day t to take into account more information.
 - O Bidirectional RNN, because this allows backpropagation to compute more accurate gradients.
 - $\ \, igotarrow$ Unidirectional RNN, because the value of $y^{< t>}$ depends only on $x^{< 1>}, \ldots, x^{< t>}$, but not on $x^{<1>}, \dots, x^{<365>}$.

 - **⊘** Correct