OBJECT TRACKING PROJECT

1. Objective

The goal of this task is to develop an object tracking-based application. This application will:

- 1. Track objects in a video
- 2. Calculate and display specific metrics
- 3. Visualise tracking results
- 4. Export and display the output in an HTML window.

2. Approach

- **Detection**: Use YOLOv8 for object detection due to its speed and accuracy.
- Tracking: Match object centroids across frames to maintain consistent object IDs.

· Visualization:

- Draw bounding boxes around detected objects.
- Mark centroids for tracking.
- Visualize object movement with trails.

3. Tech Stack

- Programming Language: Python
- Object Detection Model: YOLO (yolov8)
- . Libraries:
 - o **OpenCV**: For video processing and visualization.
 - NumPy: For mathematical operations.
 - OS: For handling file paths and system operations.

• Output Formats:

- MP4 for processed video.
- HTML for embedding and displaying results in a browser.

4. Implementation Details

1. YOLO Model Selection:

YOLO (You Only Look Once) is a real-time object detection algorithm developed by Joseph Redmon and Ali Farhadi in 2015. It is a single-stage object detector that uses a convolutional neural network (CNN) to predict the bounding boxes and class probabilities of objects in input images.

YOLOv8 is the latest iteration in the YOLO series of real-time object detectors, offering cutting-edge performance in terms of accuracy and speed.

In Yolov8, we use PreTrained Model Yolov8n.pt to detect object in real time.

2. Video Processing:

- Read frames from the input video using OpenCV.
- Extract video properties like FPS, width, and height.

3. Object Tracking:

- Use a centroid-based approach to track objects across frames.
- Match objects based on proximity to the last known centroid.

4. Visualization:

- Draw bounding boxes, centroids, and trails for tracked objects.
- Label each object with its class name (e.g., "person").

5. Metrics Calculation:

- Count unique objects detected.
- Compute time spent in the video for each object.

6. Output Generation:

- Save the processed video.
- Create an HTML file with the embedded video for browser viewing.

5. CODING STEPS:

1. Import Packages:

import cv2

import numpy as np

from ultralytics import YOLO

from collections import defaultdict

import os

2. Import Model:

model = YOLO("yolov8n.pt")

3. Video Capture & its Properties:

cap = cv2.VideoCapture(input_video_path)

fps = int(cap.get(cv2.CAP PROP FPS))

frame_width = int(cap.get(cv2.CAP_PROP_FRAME_WIDTH))

frame_height = int(cap.get(cv2.CAP_PROP_FRAME_HEIGHT))

```
input_video_path = "input_video.mp4"
output video path = "output video.mp4
```

Output Video

```
fourcc = cv2.VideoWriter_fourcc(*"mp4v")

out = cv2.VideoWriter(output_video_path, fourcc, fps,

(frame width, frame height))
```

4. Object tracking data

```
object_data = defaultdict(lambda: {"frames": [], "centroids": []})
next_object_id = 1
Object_id mapping = {}
```

5. Function to calculate centroid of a bounding box

def calculate_centroid(box):

```
x_min, y_min, x_max, y_max = box
return int((x_min + x_max) / 2), int((y_min + y_max) / 2)
```

6. Collect Bounding boxes, Class IDs, Class Names

while cap.isOpened():

```
ret, frame = cap.read()
if not ret:
```

```
break
results = model(frame)
 detections = results[0].boxes.xyxy.cpu().numpy()
  class ids = results[0].boxes.cls.cpu().numpy().astype(int)
  class names = [model.names[class id] for class id in class ids]
     frame data = []
       for det, class name in zip(detections, class names):
          x min, y min, x max, y max = map(int, det)
          centroid = calculate centroid((x min, y min, x max,
     y max))
 Match with existing objects
  matched = False
     for obj id, data in object data.items():
       if data["frames"] and np.linalg.norm(np.array(data["centroids"][-
  1]) - np.array(centroid)) < 50: # Match threshold
 object data[obj id]["frames"].append(len(object data[obj id]["frames"])
  +1)
          object data[obj id]["centroids"].append(centroid)
          frame data.append((obj id, (x min, y min, x max, y max),
  centroid, class name))
          matched = True
```

break

if not matched:

Assign new object ID

```
global next_object_id
  object_data[next_object_id]["frames"].append(1)
  object_data[next_object_id]["centroids"].append(centroid)
  frame_data.append((next_object_id, (x_min, y_min, x_max, y_max), centroid, class_name))
  next_object_id += 1
```

7. Draw bounding boxes, centroids, trails, and labels

```
for obj_id, box, centroid, class_name in frame_data:

x_min, y_min, x_max, y_max = box

cv2.rectangle(frame, (x_min, y_min), (x_max, y_max), (0, 255, 0), 2)

cv2.circle(frame, centroid, 5, (0, 0, 255), -1)

cv2.putText(frame, class_name, (x_min, y_min - 10),

cv2.FONT HERSHEY SIMPLEX, 0.5, (0, 255, 255), 2)
```

Draw trail

```
for i in range(1, len(object_data[obj_id]["centroids"])):

cv2.line(frame, object_data[obj_id]["centroids"][i - 1],
object_data[obj_id]["centroids"][i], (255, 0, 0), 2)
```

```
output video
out.write(frame)
```

8. Export metrics

```
metrics = {
    "unique_object_ids": len(object_data),
    "time_spent_per_object": {
       obj_id: len(data["frames"]) / fps for obj_id, data in object_data.items()
     },
}
```

9. Print metrics

```
print("Metrics:")
print(f"Total Unique Objects Detected:
{metrics['unique_object_ids']}")
for obj_id, time_spent in metrics["time_spent_per_object"].items():
    print(f"Object {obj_id}: {time_spent:.2f} seconds")
```

10. HTML for output

```
<!DOCTYPE html>
<html>
<head>
    <title>Object Tracking Output</title>
</head>
<body>
    <h1>Object Tracking Results</h1>
    <video controls width="640" height="480">
         <source src=" outputfile.mp4" type="video/mp4">
            Your browser does not support the video tag.
         </body>
    </html>
```

HOSTED LINK -> https://brilliant-gelato-2db36d.netlify.app/

11. Output Screenshot

Object Tracking Results



```
0: 384x640 9 persons, 9.0ms
Speed: 4.4ms preprocess, 9.0ms inference, 1.2ms postprocess per image at shape (1, 3, 384, 640)
Metrics:
Total Unique Objects Detected: 45
Object 1: 10.60 seconds
Object 2: 34.50 seconds
Object 3: 20.50 seconds
Object 4: 9.20 seconds
Object 5: 14.93 seconds
Object 6: 7.27 seconds
Object 7: 11.73 seconds
Object 8: 13.17 seconds
Object 9: 5.40 seconds
Object 10: 14.13 seconds
Object 11: 14.60 seconds
Object 12: 4.47 seconds
```

12. Conculsion.

Thus, The Object Tracking Project is completed with the help of YOLO Object Detection Model.