Operating System Concepts

Lecture 28: Frame Allocation Algorithms & Thrashing

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MWF 12:00-12:50 VVC 2 215

Today's class

- Page replacement algorithms
 - second-chance algorithm and its variants
 - counting-based algorithms
- Frame allocation algorithms
- Thrashing
- Kernel memory allocation

Approximating LRU

- basic idea: keep a reference bit for each page
 - on each access to the page, the hardware sets the reference bit to '1'
 - set it to '0' at varying times depending on the page replacement algorithm

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 - set it to '0' at varying times depending on the page replacement algorithm
- Additional-Reference-Bits algorithm
 - maintain more than 1 bit, say for example 8 bits
 - at regular intervals (e.g., every 100 milliseconds) or on each memory access, right shift the byte (an aging mechanism) by one bit, placing a 0 in the high order bit; on a page fault, the lowest numbered page is kicked out
 - it is approximate, since it does not guarantee a total order on the pages; but it is faster, since it requires setting a single bit on each memory access
 - page fault still requires a search through all the pages

Second-chance page replacement algorithm

- use a single reference bit per page
 - OS keeps all pages in a circular list and a pointer to the next frame that must be considered
 - on a page fault, OS checks the reference bit of the frame that the pointer refers to
 - if the reference bit is '0', replaces the page, sets its reference bit to '1', and advances the pointer to the next frame
 - if the reference bit is '1', clears the reference bit (sets bit to '0'), and advances the pointer to the next frame

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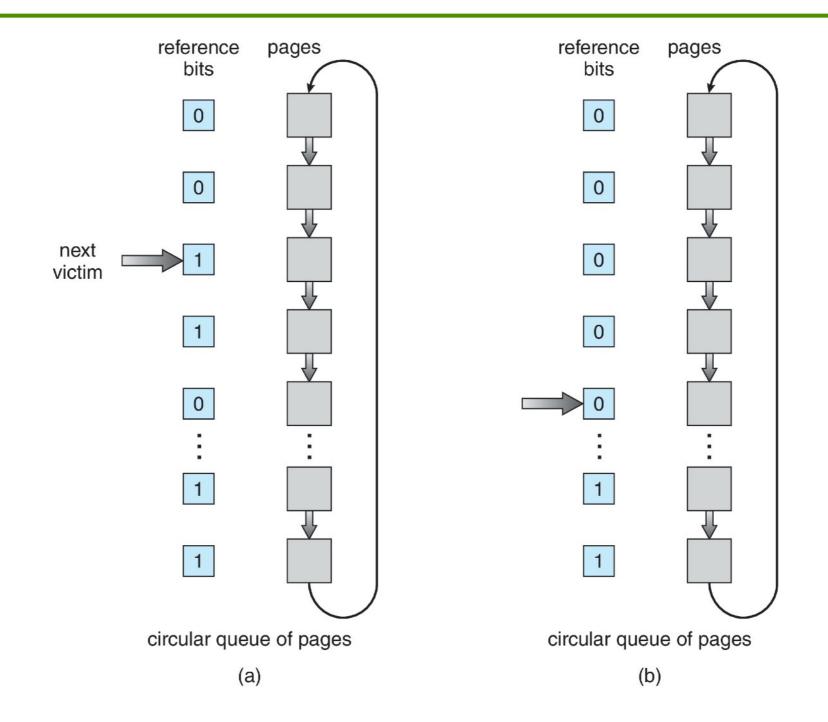
disadvantage

 it is less accurate than the additional-reference-bits algorithm since the reference bit only indicates if the page was used at all since the last time it was checked by the algorithm

advantage

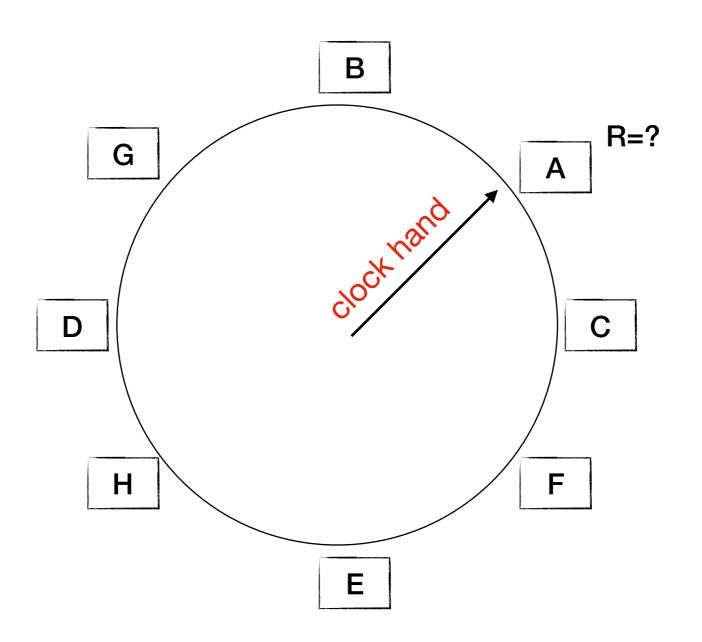
- it is fast as it requires setting a single bit on each memory access (no need for a shift)
- handling a page fault is also faster as we only search the pages until we find one with a reference bit that is not set

Implementation



if R=0 then evict the page and set reference bit of the new page to 1 and advance the pointer otherwise clear R and advance the pointer

Why is it called the clock algorithm?



hand-spread is the size of the active list

a closer look...

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- why not partition pages into more than two categories?
 - because handling a page fault would require finding the youngest page
- should we replace any young page?
 - of course it is cheaper to replace a page that has not been modified because the OS does not need to write it out

Enhanced second-chance algorithm

- let's keep a modify bit in addition to the reference bit for each page
 - '1' indicates that the page is modified, hence it is different from the copy residing on disk
 - '0' indicates that the page is the same as the copy residing on disk

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- with these two bits (r, m) we have four possible classes
 - (0,0) neither recently used nor modified
 - best candidate for replacement!
 - (0,1) not recently used, but modified
 - it might not be needed anymore, but not as good to replace since the OS must write out the page
 - (1,0) recently used and unmodified
 - probably will be used again soon, but the OS doesn't need to write it out before replacing it
 - (1,1) recently used and modified
 - probably will be used again soon and the OS must write it out before replacing it

- one the first pass if there is a page with (0,0) then replace it
 - if there is a page with (0,1) then initiate an I/O to write out the page, lock the page in memory until the I/O completes, clear the modified bit and continue the search
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OS goes around at most 3 times searching for the (0,0) class

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- counting based algorithms are expensive and do not approximate OPT (or LRU algorithm)

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 - when a page fault occurs, a victim page is chosen as before and disk I/O is initiated to write out this page
 - instead of waiting for I/O completion, the desired page is quickly read into a free frame from the pool
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- how to size this pool? depends on the page fault service time

Frame allocation

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 - proportional allocation: allocate available frames to each process according to its size (or its priority) so larger processes get more page frames

$$s_i = \text{size of process } p_i$$

$$S = \sum s_i$$

m = total number of frames

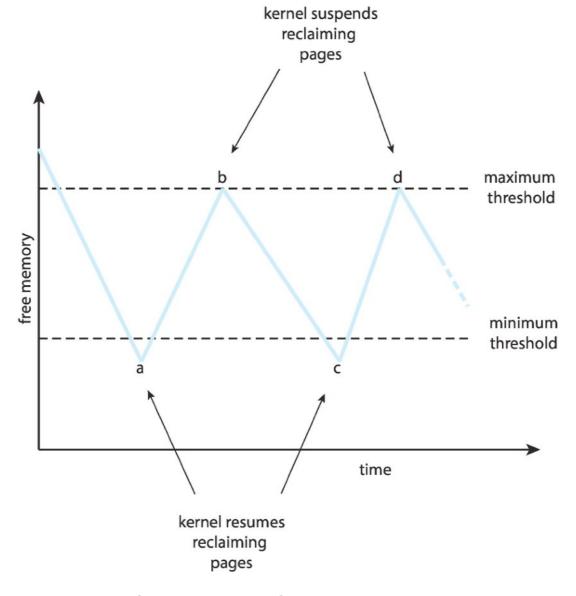
$$a_i$$
 = allocation for $p_i = \frac{s_i}{S} \times m$

Frame allocation policies

- global replacement: each process selects a replacement frame from the set of all frames in the system
 - one process can take a frame from another (more flexible)
 - but a process can't control its own page fault rate as it depends on the paging behaviour of other processes in the system
 - for this reason process execution time can vary greatly
 - thrashing might become more likely
- local replacement: each process selects from only its own set of allocated frames
 - more consistent per-process performance, but memory can be under utilized

Implementing global page-replacement policy

- all memory requests are satisfied from the free-frame list
- page replacement is triggered when the list falls below a certain threshold to ensure that there is always sufficient free frames available



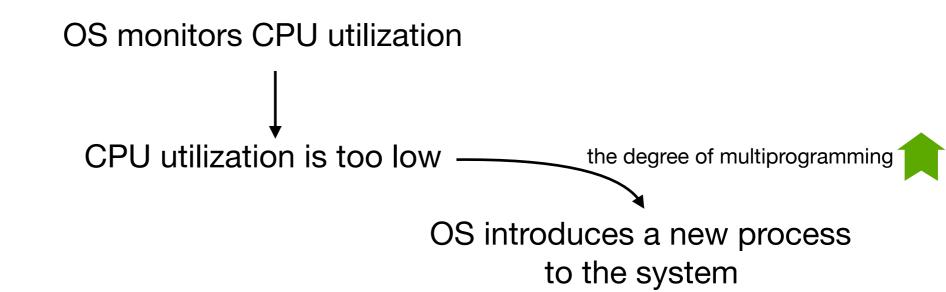
Thrashing

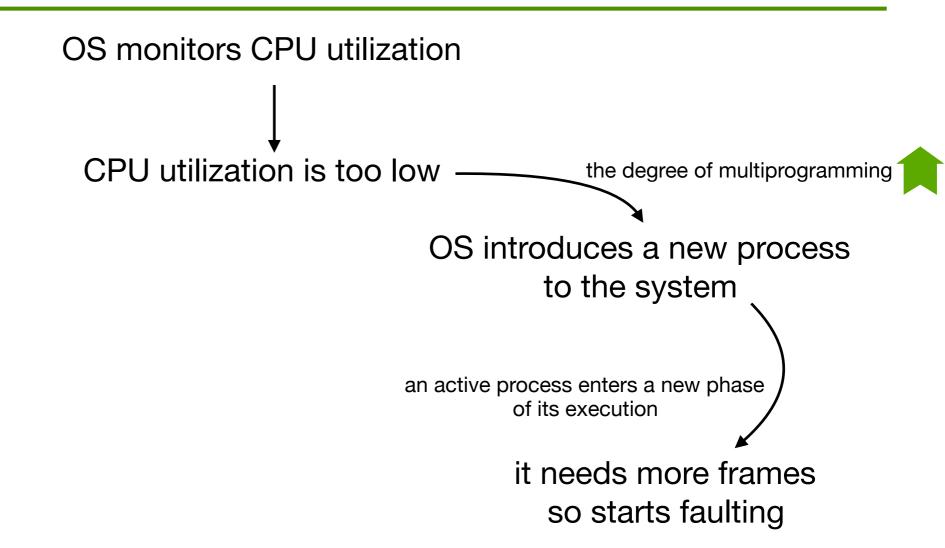
- Definition: a process is thrashing when it spends more time paging than executing
- Why? the memory is over-committed and pages are continuously tossed out (by a global page-replacement algorithm) while they are still in use
 - effective memory access time approaches disk access time since many memory references cause page fault
 - results in very noticeable loss of performance (throughput)

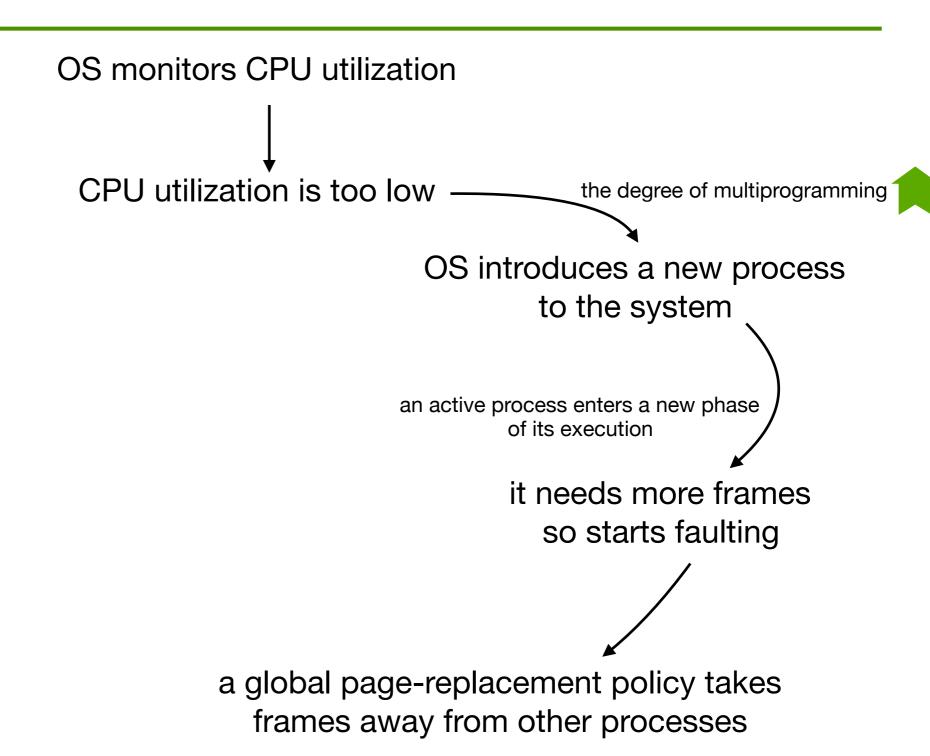
OS monitors CPU utilization

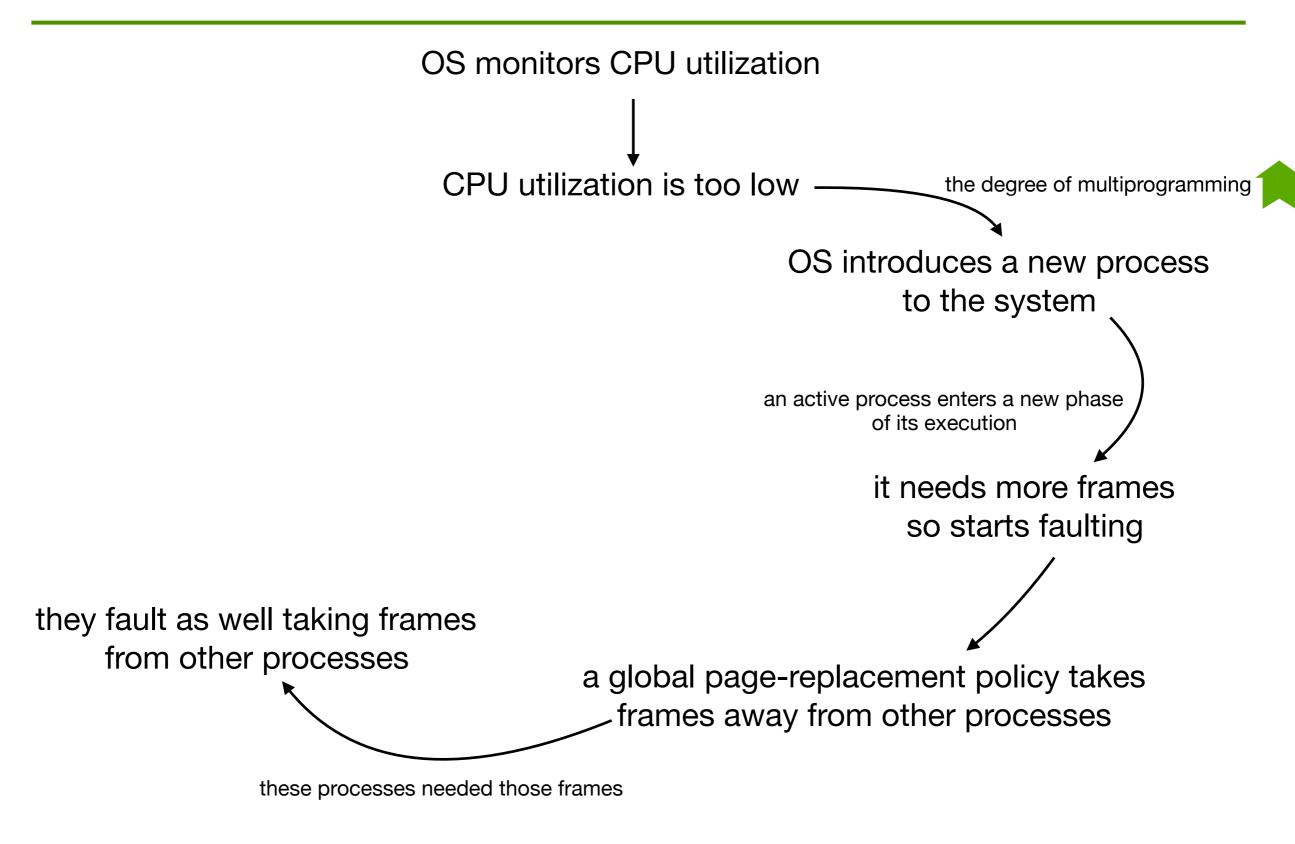
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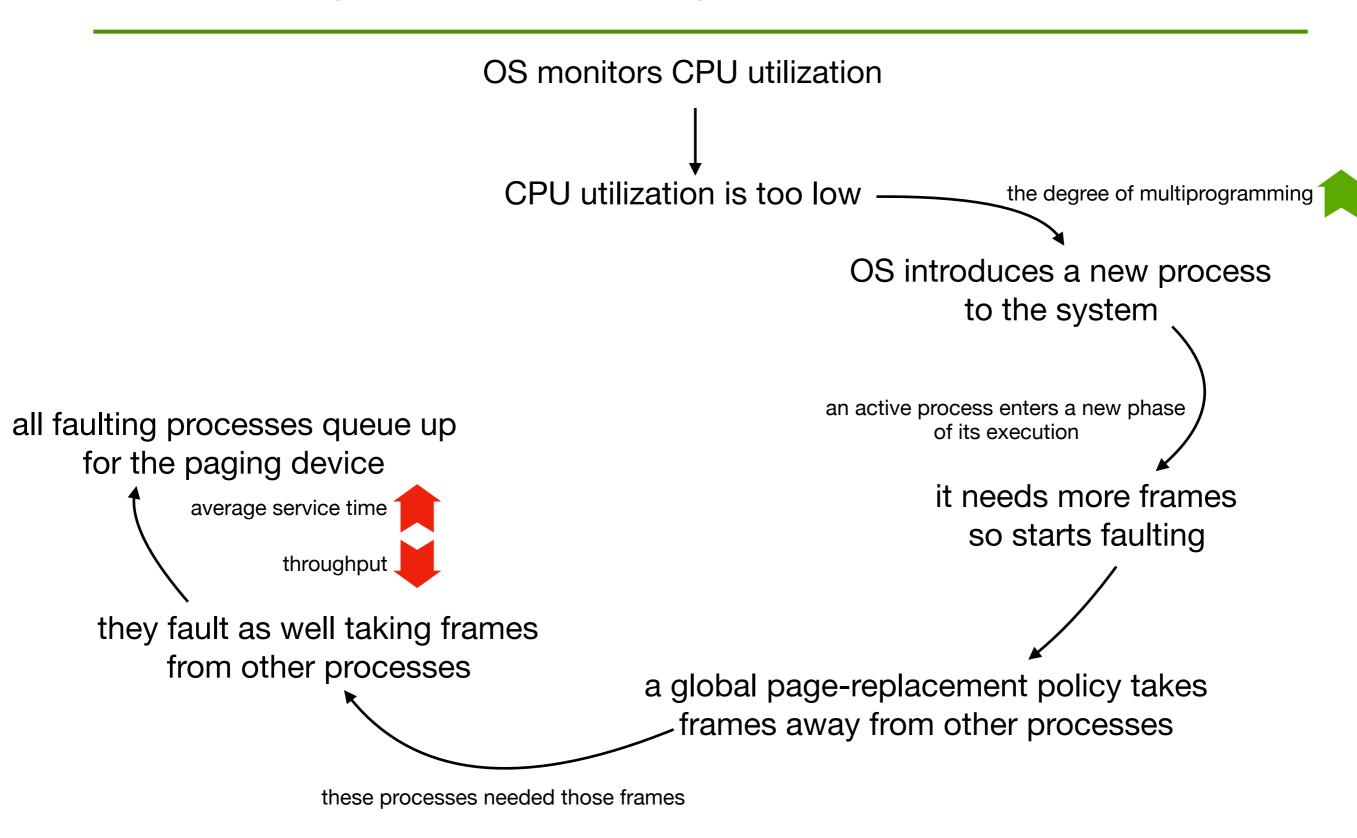
♦ CPU utilization is too low

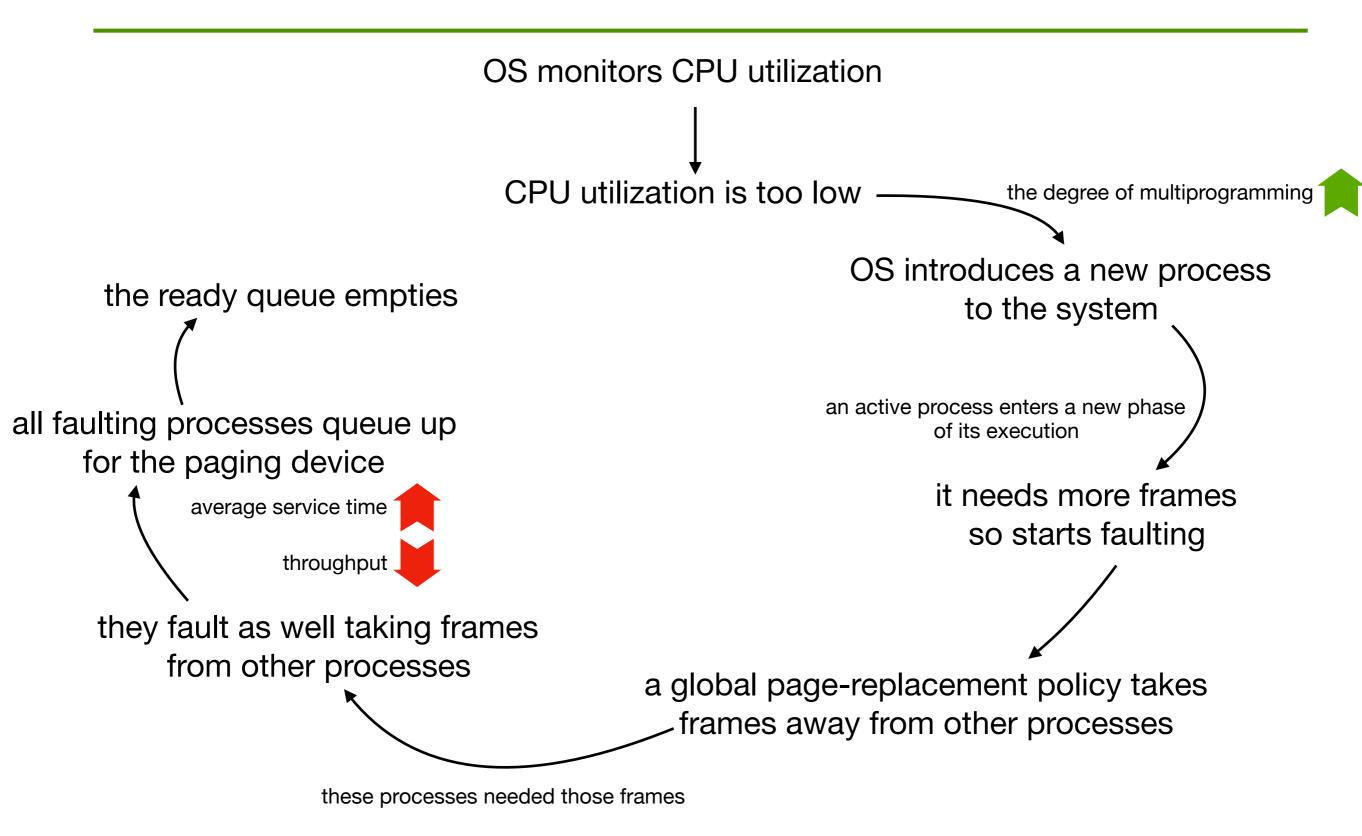


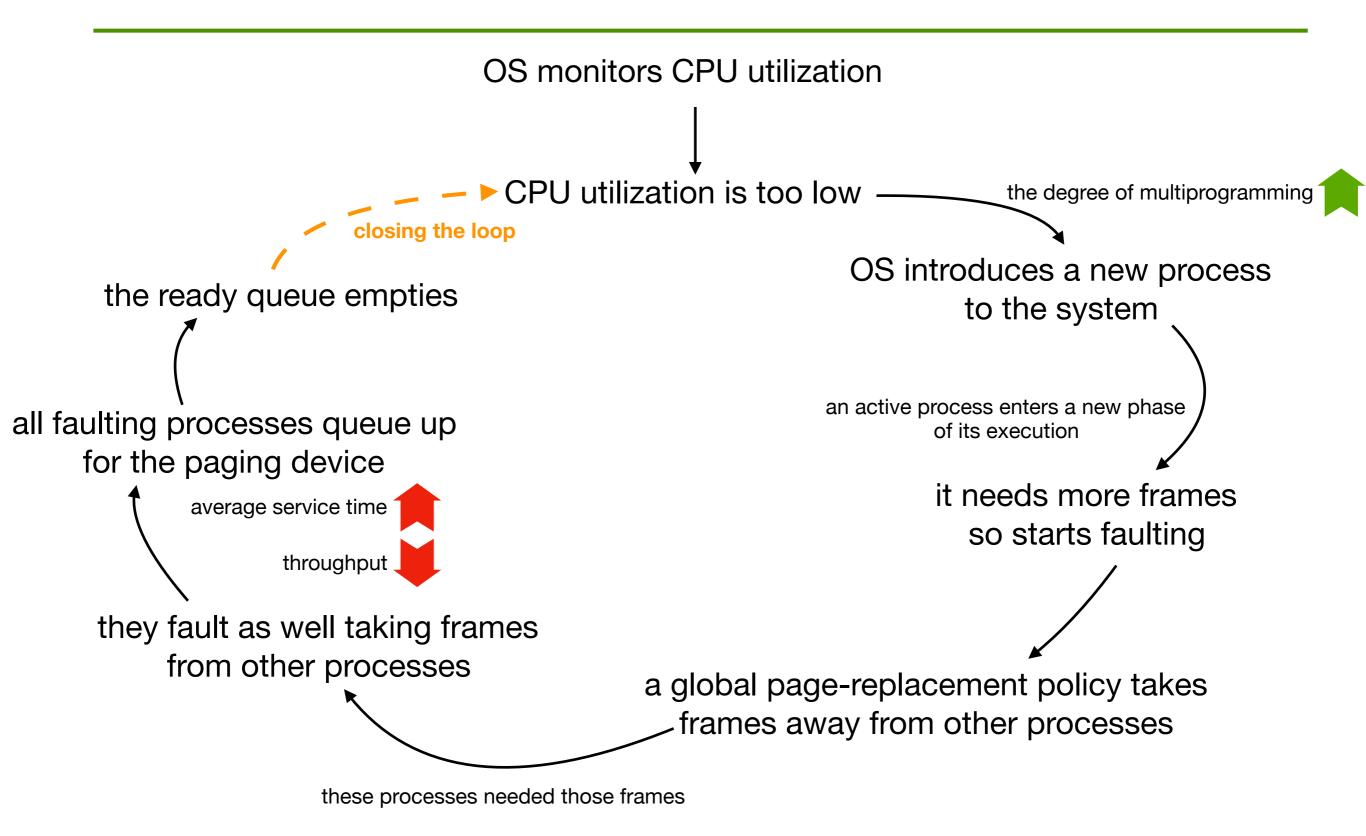


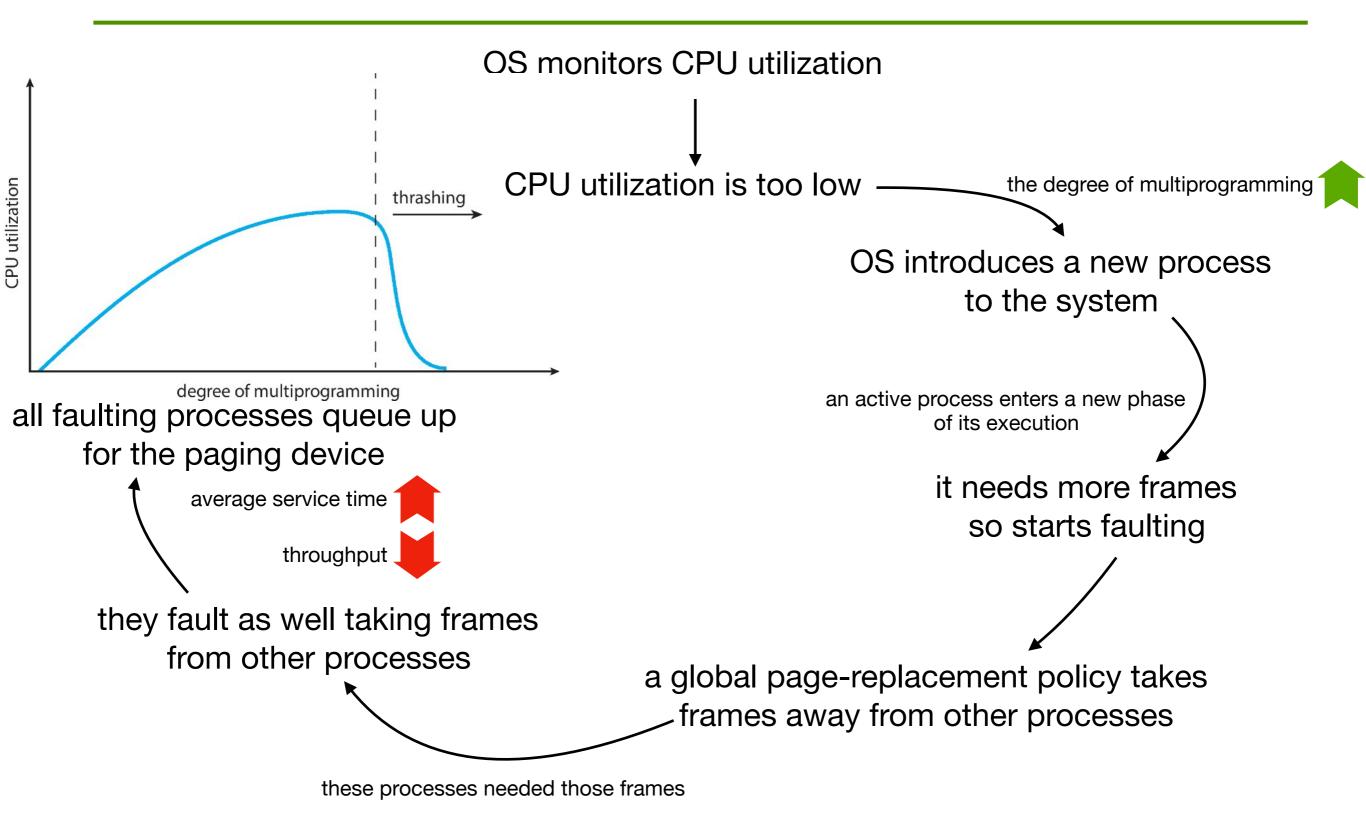










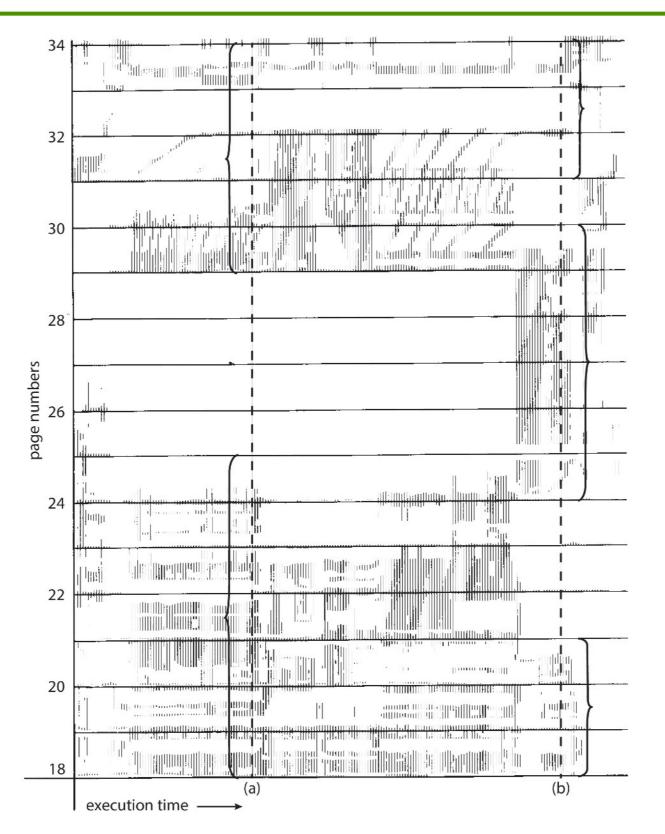


What can be done in a multiprogrammed environment to limit thrashing?

- per-process replacement
 - each process has its own pool of pages which is large enough (i.e., contains as many page frames as it needs)
 - run only groups of processes that fit in memory and suspend the rest
- how to determine how many pages a process actually needs?
 - use the working-set model which approximates the program locality (i.e., set of pages that are actively used together)
 - **definition:** working set is the set of all pages that a process referenced in the past Δ time units
 - hence, a page that is in active use will be in the working set

Process's locality changes over time

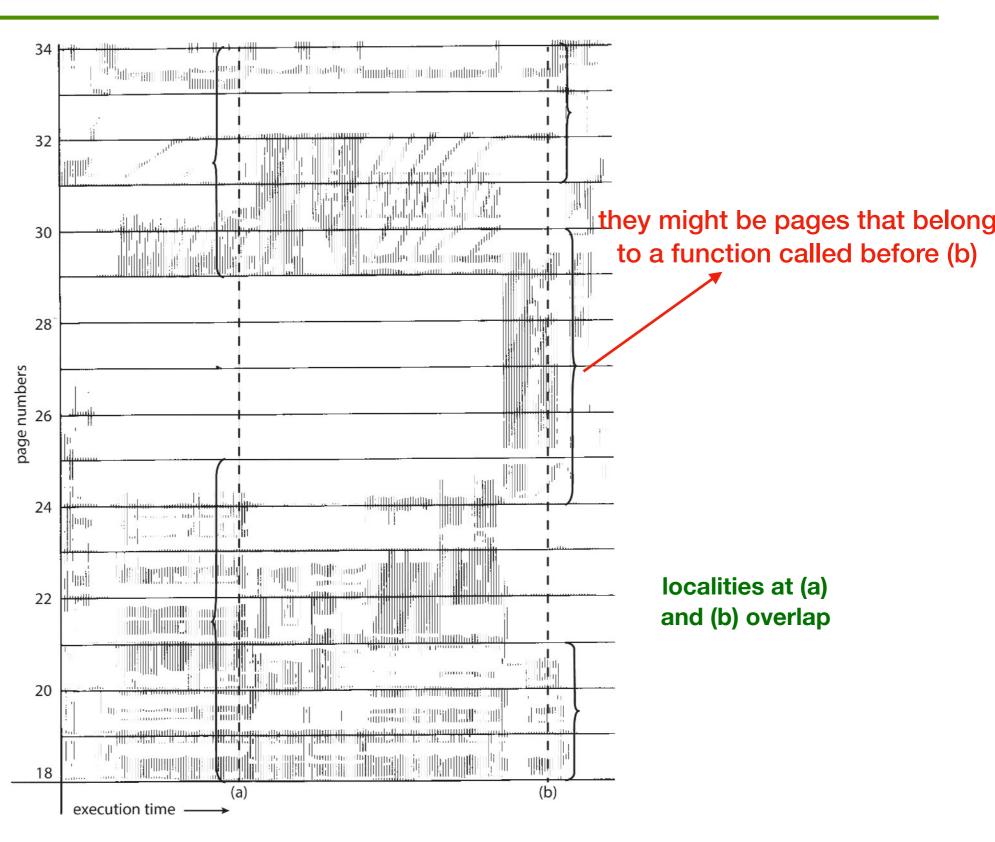
process's
localities depends
on its program
structure and data
structure



localities at (a) and (b) overlap

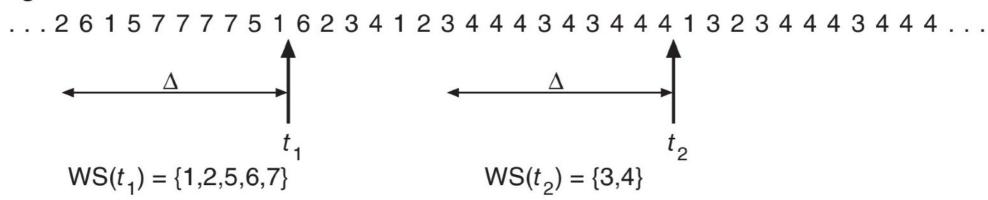
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Working set determination

page reference table



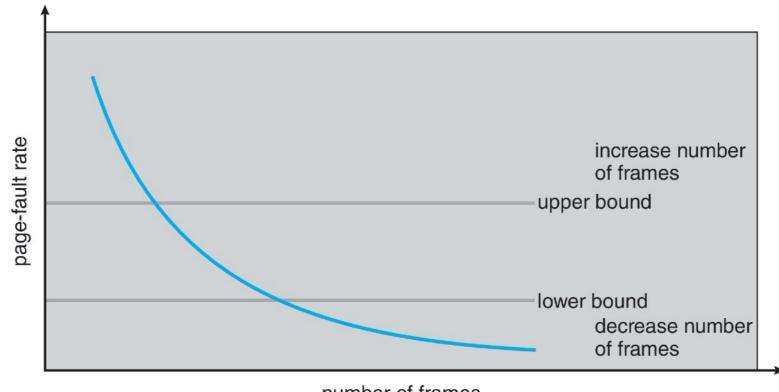
the working set updates dynamically

how to pick Δ ?

- what if Δ is too small? it does not encompass the entire locality
- what if Δ is too big? it overlaps several localities and may result in thrashing

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- an alternative approach is to track page-fault frequency of each process and use it to create a control signal
 - give a process more page frames if the page fault frequency > some threshold
 - if no free frame is available we may need to suspend some processes
 - take away some page frames if the page fault frequency < another threshold



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- Goal: the system-wide mean time between page faults should be equal to the time it takes
 to handle a page fault

Kernel memory allocator

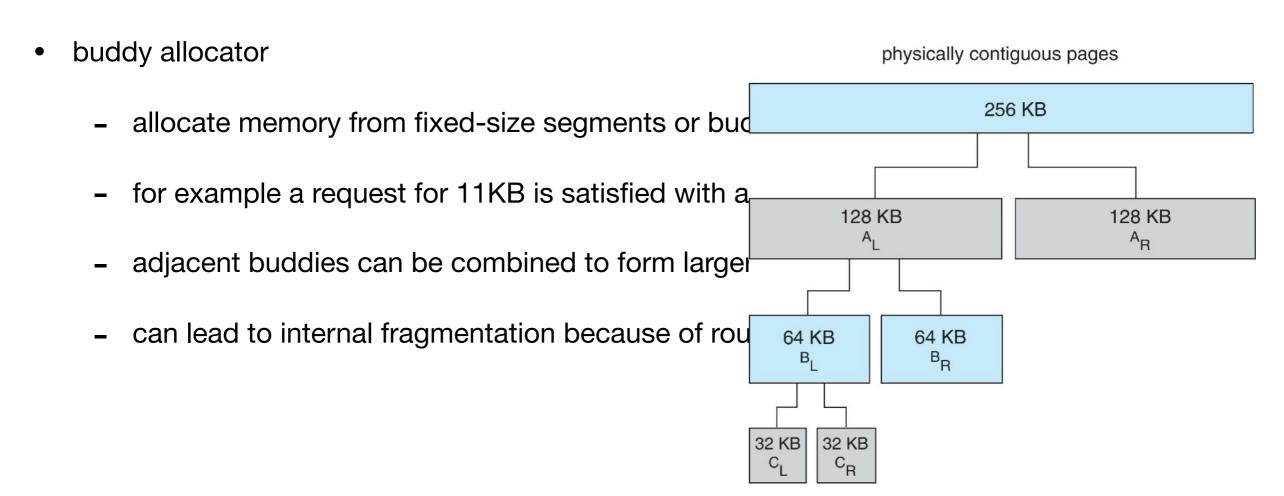
- Kernel memory is often allocated from a free-memory pool which is different from the free-frame list used to allocate frames to user-level processes
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 - kernel code or data may not be subject to the paging system
 - kernel code may need to be in contiguous physical memory
- buddy allocator
 - allocate memory from fixed-size segments or buddies (i.e., power-of-2 allocator)
 - for example a request for 11KB is satisfied with a 16KB segment
 - adjacent buddies can be combined to form larger segments
 - can lead to internal fragmentation because of rounding up to the highest power of 2

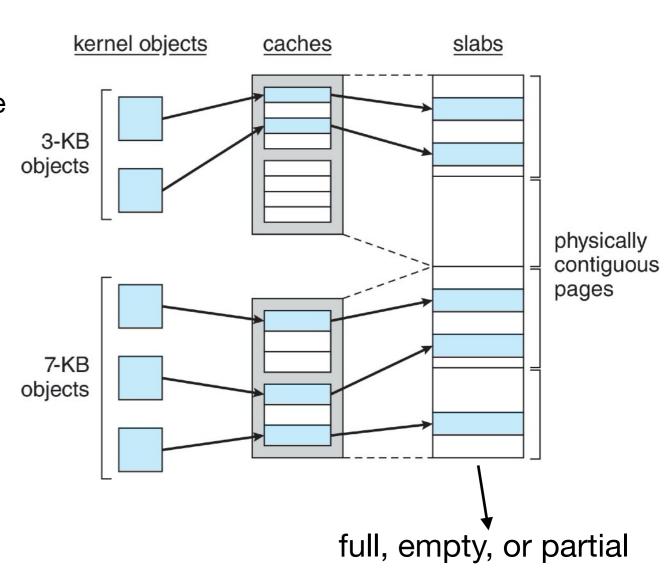
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Slab allocator

- group objects of same size in a "slab"; a slab is made up of one or more physically contiguous pages; a cache consists of one or more slabs
- there is a separate cache for each kernel data structure (e.g., PCB, semaphores, file tables)
 - a cache contains many preallocated objects that are marked as free initially
- no memory is wasted due to internal fragmentation; memory allocation is faster
- used in Solaris and Linux



Page replacement in practice

UNIX and Linux use variants of the LRU algorithm* (e.g., the clock algorithm), Windows NT uses the clock algorithm (on a uniprocessor system) and random replacement (on a multiprocessor system)

- experiments show that all algorithms do poorly if processes have insufficient physical memory (less than half of their virtual address space)
- all algorithms approach optimal as the physical memory allocated to a process approaches the virtual memory size
- the more processes running concurrently, the less physical memory each process can have
- a critical issue the OS must decide is how many processes may share memory simultaneously and how many frames should be allocated to each process

^{*} https://www.kernel.org/doc/gorman/html/understand/understand013.html