## Garbage collection

- Every modern programming language allows programmers to allocate new storage dynamically
  - New records, arrays, tuples, objects, closures, etc.
- Every modern language needs facilities for reclaiming and recycling the storage used by programs
- It's usually the most complex aspect of the runtime system for any modern language

## Memory layout

per process virtual memory physical memory new pages allocated via calls to OS heap static data TLB address translation stack grows to preset limit

- What is garbage?
  - A value is garbage if it will not be used in any subsequent computation by the program
- Is it easy to determine which objects are garbage?

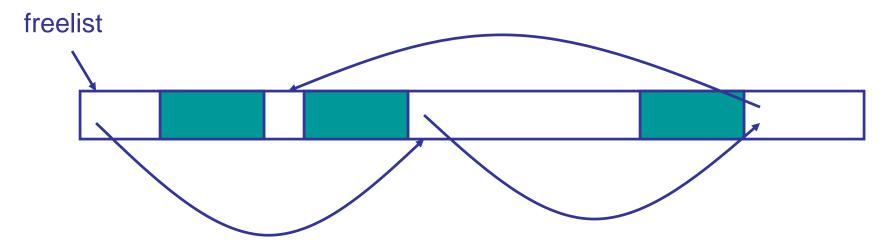
- What is garbage?
  - A value is garbage if it will not be used in any subsequent computation by the program
- Is it easy to determine which objects are garbage?
  - No. It's undecidable. Eg:

if long-and-tricky-computation then use v else don't use v

- Since determining which objects are garbage is tricky, people have come up with many different techniques
  - It's the programmers problem:
    - Explicit allocation/deallocation
  - Reference counting
  - Tracing garbage collection
    - Mark-sweep, copying collection
    - Generational GC

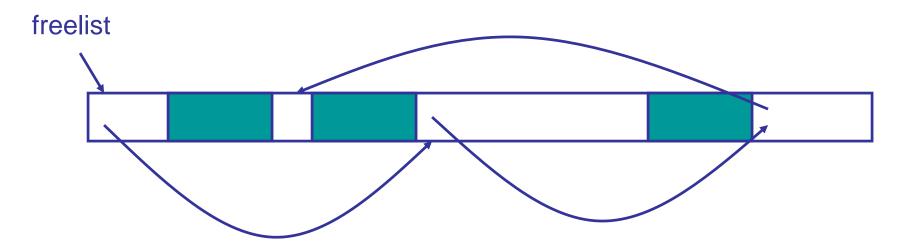
- User library manages memory; programmer decides when and where to allocate and deallocate
  - void\* malloc(long n)
  - void free(void \*addr)
  - Library calls OS for more pages when necessary
  - Advantage: people are smart
  - Disadvantage: people are dumb and they really don't want to bother with such details if they can avoid it

- How does malloc/free work?
  - Blocks of unused memory stored on a freelist
  - malloc: search free list for usable memory block
  - free: put block onto the head of the freelist



### Drawbacks

- malloc is not free: we might have to do a significant search to find a big enough block
- As program runs, the heap fragments leaving many small, unusable pieces



#### Solutions:

- Use multiple free lists, one for each block size
  - Malloc and free become O(1)
  - But can run out of size 4 blocks, even though there are many size 6 blocks or size 2 blocks!
- Blocks are powers of 2
  - Subdivide blocks to get the right size
  - Adjacent free blocks merged into the next biggest size

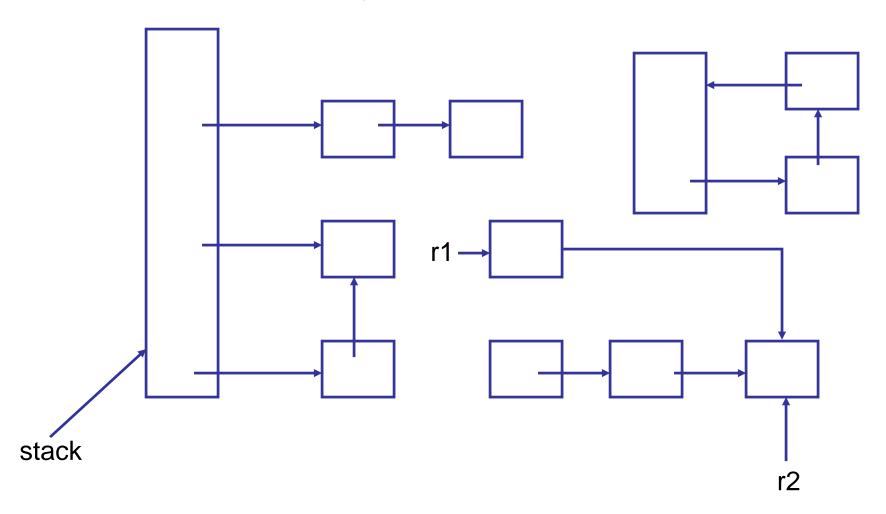
### **Automatic MM**

- Languages with explicit MM are much harder to program than languages with automatic MM
  - Always worrying about dangling pointers, memory leaks: a huge software engineering burden
  - Impossible to develop a secure system, impossible to use these languages in emerging applications involving mobile code
  - languages with unsafe, explicit MM will all but disappear?????

### **Automatic MM**

- Question: how do we decide which objects are garbage?
  - We conservatively approximate
  - Normal solution: an object is garbage when it becomes unreachable from the roots
    - The roots = registers, stack, global static data
    - If there is no path from the roots to an object, it cannot be used later in the computation so we can safely recycle its memory

### Object Graph



– How should we test reachability?

### Reference Counting

- Keep track of the number of pointers to each object (the reference count).
- When the reference count goes to 0, the object is unreachable garbage

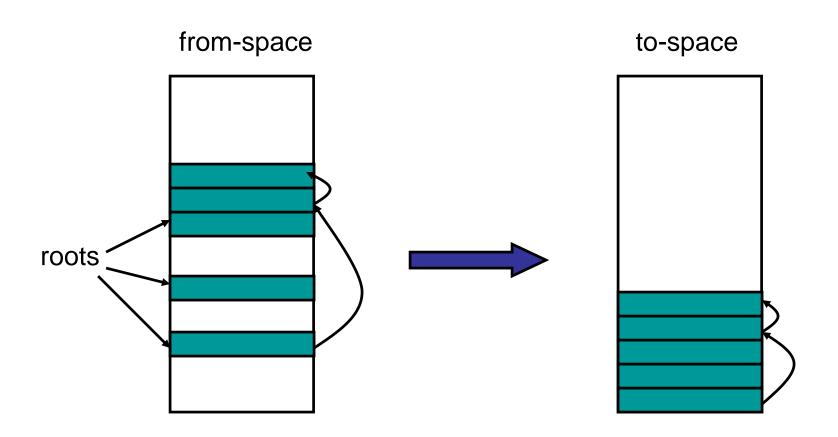
## Copying Collection

- Basic idea: use 2 heaps
  - One used by program
  - The other unused until GC time

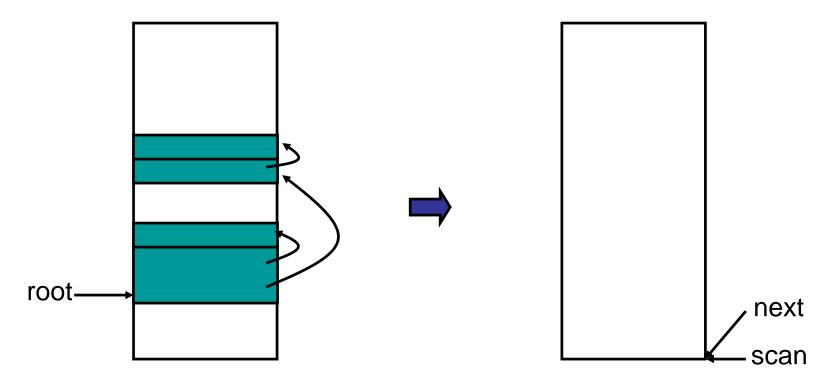
#### • GC:

- Start at the roots & traverse the reachable data
- Copy reachable data from the active heap (fromspace) to the other heap (to-space)
- Dead objects are left behind in from space
- Heaps switch roles

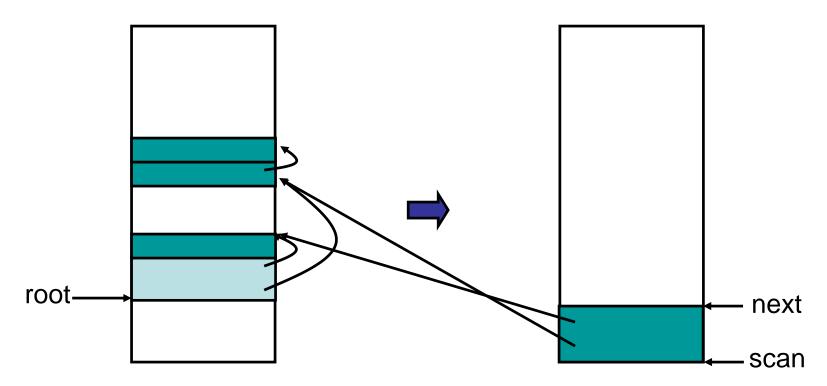
# Copying Collection



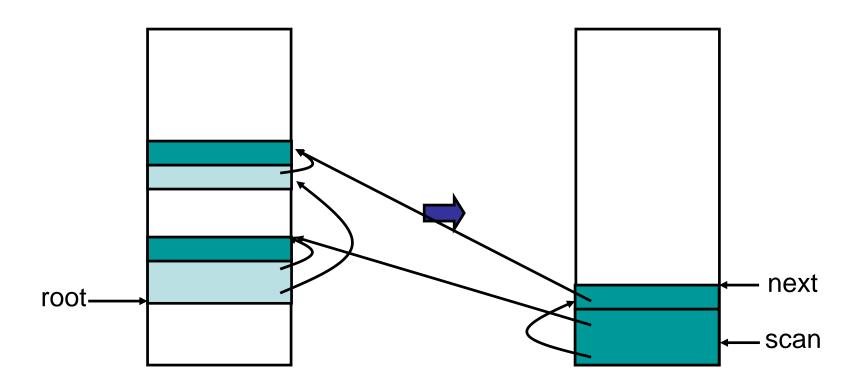
 Traverse data breadth first, copying objects from from-space to to-space



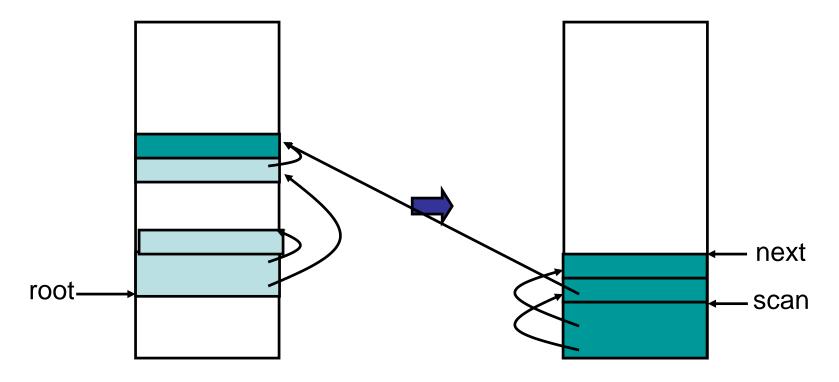
- Cheny's algorithm for copying collection
  - Traverse data breadth first, copying objects from from-space to to-space



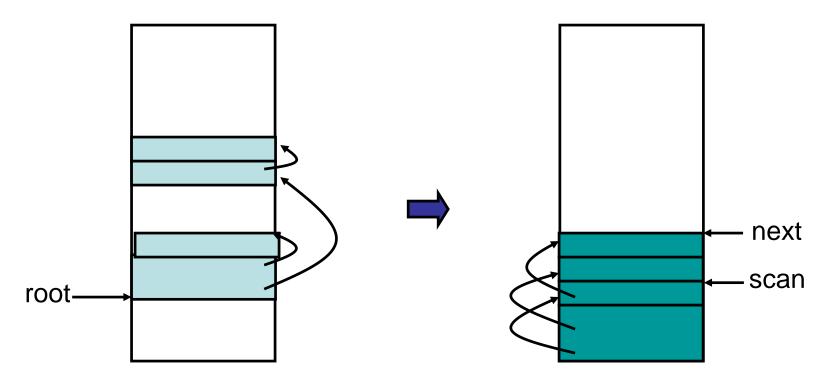
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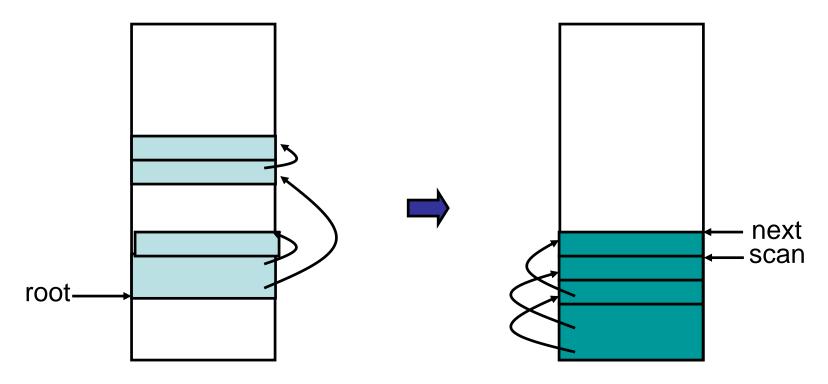
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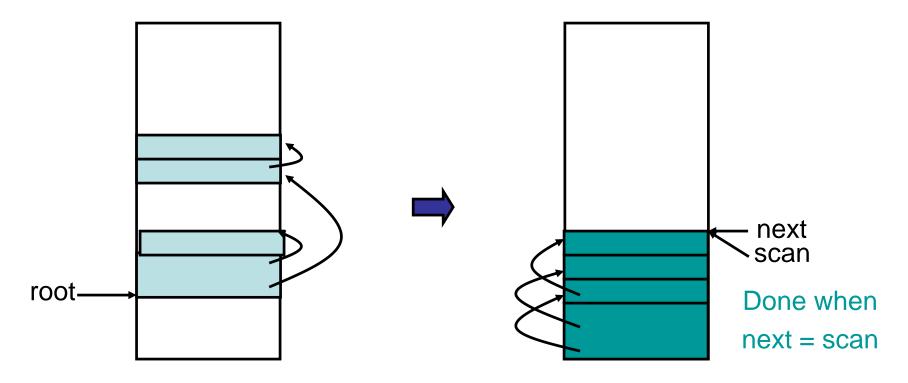
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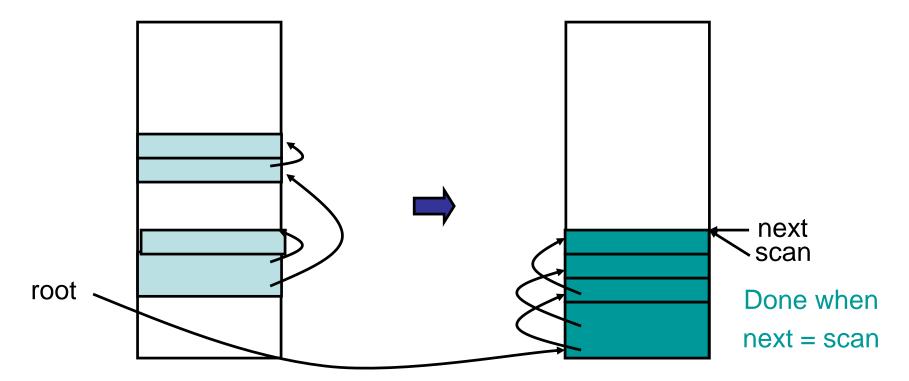
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 Traverse data breadth first, copying objects from from-space to to-space



#### Pros

- Simple & collects cycles
- Run-time proportional to # live objects
- Automatic compaction eliminates fragmentation

#### Cons

- Precise type information required
  - Tag bits take extra space; normally use header word
- Twice as much memory used as program requires
- Long GC pauses = bad for interactive, real-time apps

### Generational GC

- Empirical observation: if an object has been reachable for a long time, it is likely to remain so
- Empirical observation: in many languages, most objects died young
- Conclusion: we save work by scanning the young objects frequently and the old objects infrequently

### Generational GC

- Assign objects to different generations G0, G1,...
  - G0 contains young objects, most likely to be garbage
  - G0 scanned more often than G1
  - Common case is two generations (new, tenured)

### Root to G0

- Roots for GC of G0 include all objects in G1 in addition to stack, registers?
- Card marking
- Write Barrier

### Generational GC

- Other issues
  - When do we promote objects from young generation to old generation
    - Usually after an object survives a collection, it will be promoted
  - When do we collect the old generation?
    - After several minor collections, we do a major collection
  - Tuning for efficiency: how quickly do we scan the young generation?

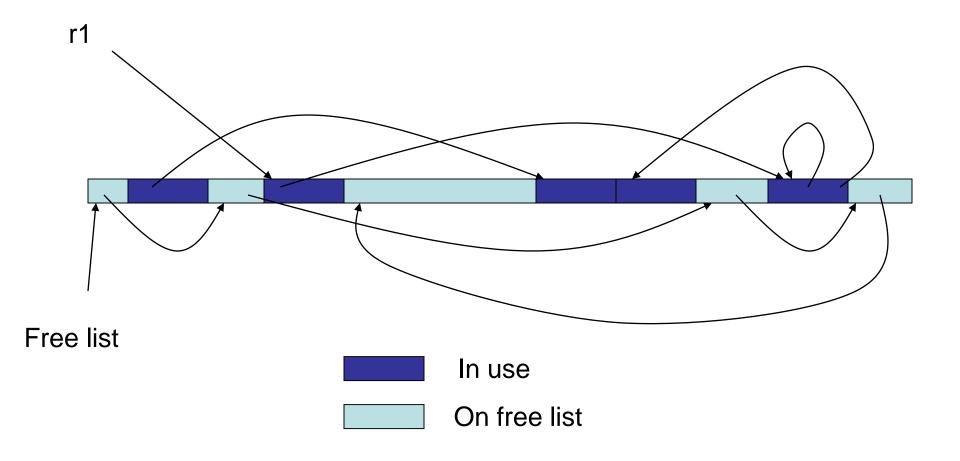
### Generational GC

- Other issues
  - Sometimes different GC algorithms are used for the new and older generations.
    - Why? Because they have different characteristics
  - Copying collection for the new
    - Less than 10% of the new data is usually live
    - Copying collection cost is proportional to the live data
  - Mark-sweep for the old
    - Next topic

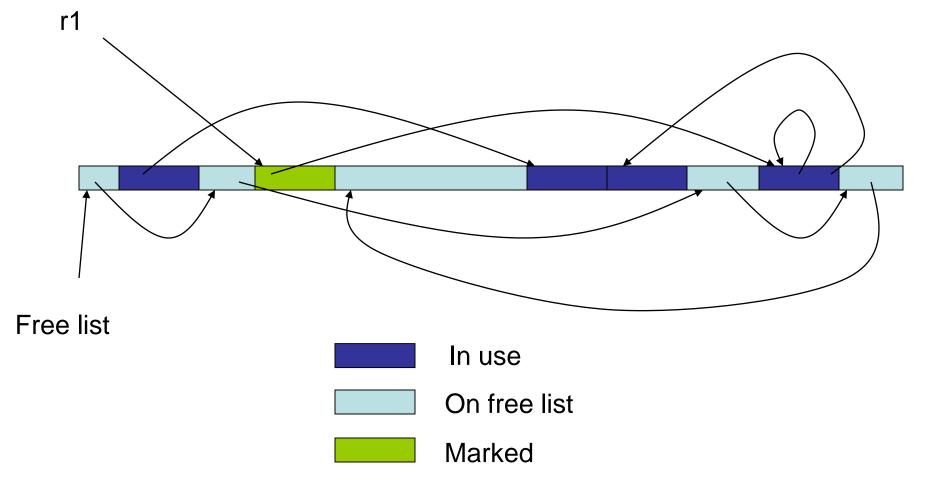
# Mark-Sweep

### Mark-sweep

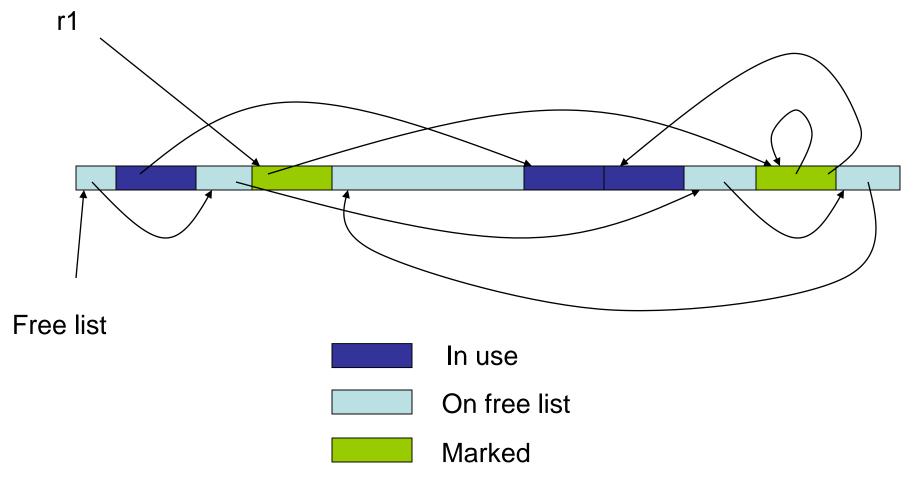
- A two-phase algorithm
  - Mark phase: Depth first traversal of object graph from the roots to mark live data
  - Sweep phase: iterate over entire heap, adding the unmarked data back onto the free list



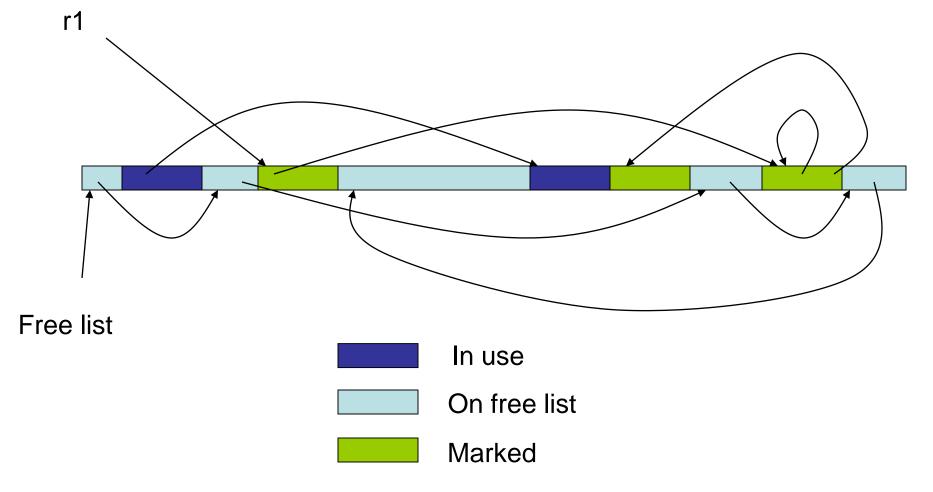
Mark Phase: mark nodes reachable from roots



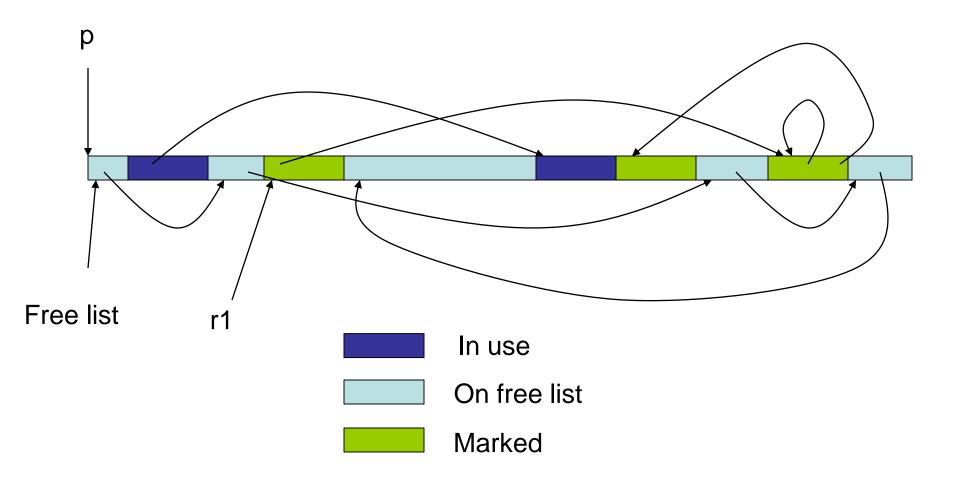
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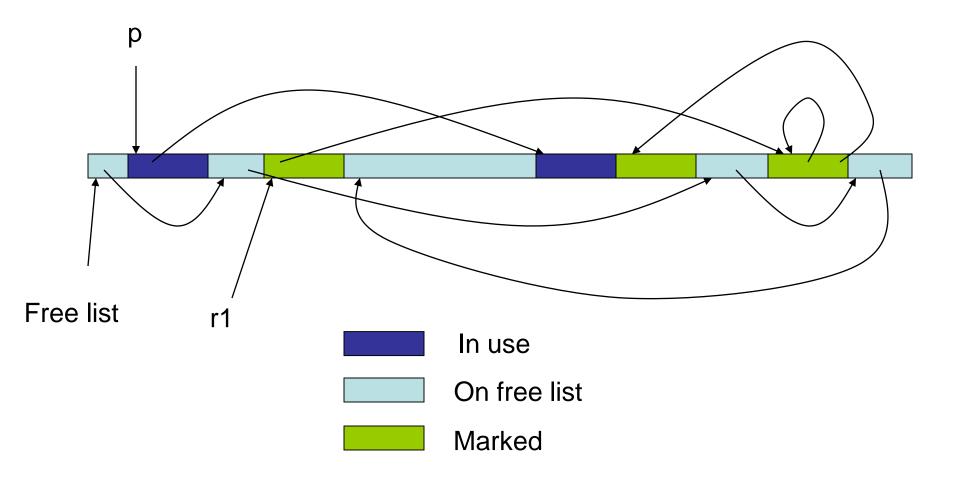
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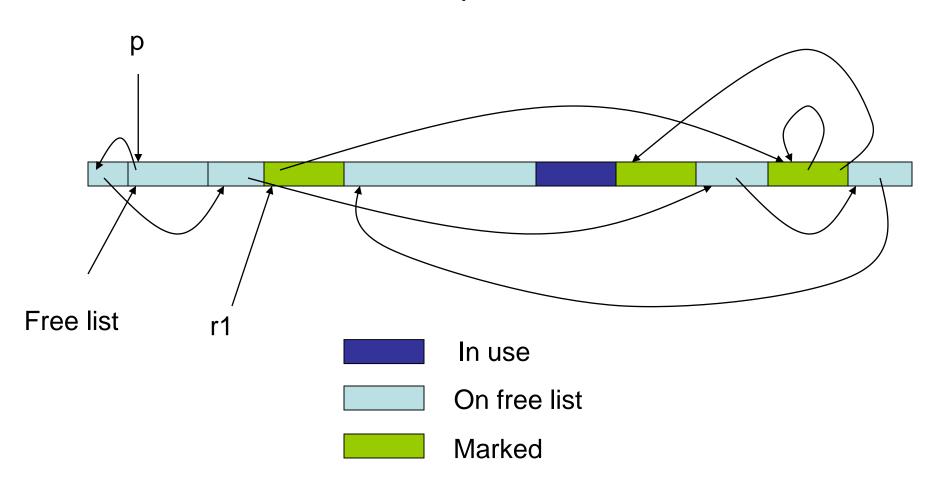
Sweep Phase: set up sweep pointer; begin sweep



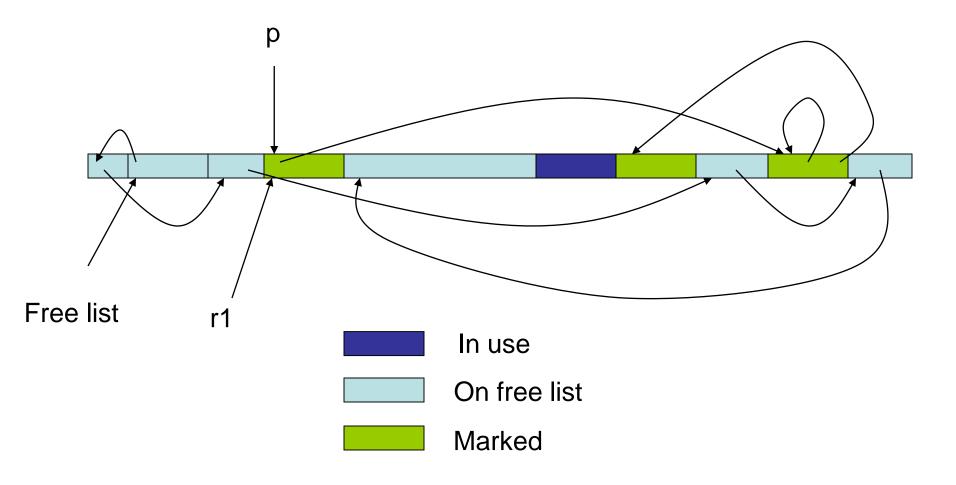
Sweep Phase: add unmarked blocks to free list



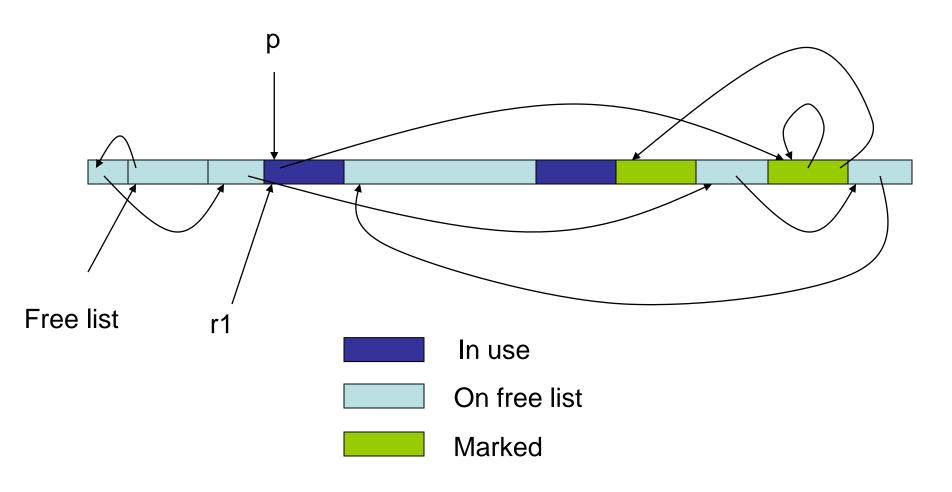
### Sweep Phase



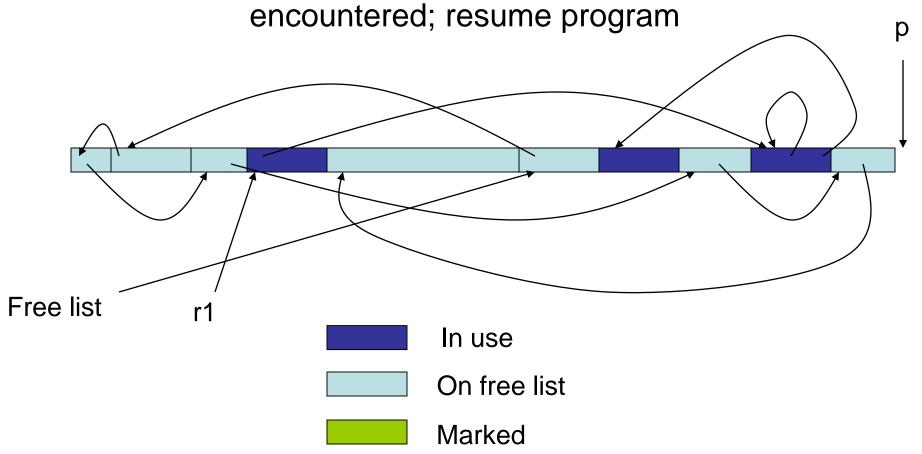
Sweep Phase: retain & unmark marked blocks



### Sweep Phase



Sweep Phase: GC complete when heap boundary



### Discussion

- Relationship between GC cpu usage and size of heap / live set
  - General efficiency (GC cpu / Over-all cpu)
  - Frequency of pauses
  - Lengh of pause?
    - Copy
    - Mark-sweep

### **CMS**

- Concurrent Mark Sweep GC
- Stop-the-world copy new generation
- Concurrent, non-compacting old gen
  - Concurrent vs parallel
  - Concurrent marking
    - Lost Object
    - Stop-the-world remark
  - Concurrent sweeping
- Stop-the-world Compacting

## Garbage First (G1)

- New default in JDK 9
- Fine-grained control (target pause time)
  - 2048 regions
  - Eden / Survivor / Tenured
- Stop-the-world copy Young GC
- Concurrent marking
- Incremental compaction <u>Piggybacked</u> on Young GC
  - Do easier ones first (mostly garbage)