Garbage collection

- Every modern programming language allows programmers to allocate new storage dynamically
 - New records, arrays, tuples, objects, closures, etc.
- Every modern language needs facilities for reclaiming and recycling the storage used by programs
- It's usually the most complex aspect of the runtime system for any modern language

Memory layout

per process virtual memory physical memory new pages allocated via calls to OS heap static data TLB address translation stack grows to preset limit

- What is garbage?
 - A value is garbage if it will not be used in any subsequent computation by the program
- Is it easy to determine which objects are garbage?

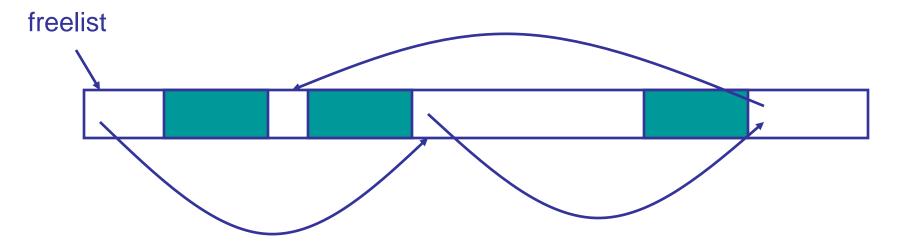
- What is garbage?
 - A value is garbage if it will not be used in any subsequent computation by the program
- Is it easy to determine which objects are garbage?
 - No. It's undecidable. Eg:

if long-and-tricky-computation then use v else don't use v

- Since determining which objects are garbage is tricky, people have come up with many different techniques
 - It's the programmers problem:
 - Explicit allocation/deallocation
 - Reference counting
 - Tracing garbage collection
 - Mark-sweep, copying collection
 - Generational GC

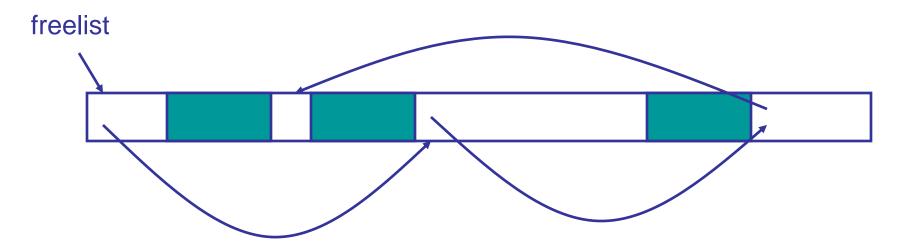
- User library manages memory; programmer decides when and where to allocate and deallocate
 - void* malloc(long n)
 - void free(void *addr)
 - Library calls OS for more pages when necessary
 - Advantage: people are smart
 - Disadvantage: people are dumb and they really don't want to bother with such details if they can avoid it

- How does malloc/free work?
 - Blocks of unused memory stored on a freelist
 - malloc: search free list for usable memory block
 - free: put block onto the head of the freelist



Drawbacks

- malloc is not free: we might have to do a significant search to find a big enough block
- As program runs, the heap fragments leaving many small, unusable pieces



Solutions:

- Use multiple free lists, one for each block size
 - Malloc and free become O(1)
 - But can run out of size 4 blocks, even though there are many size 6 blocks or size 2 blocks!
- Blocks are powers of 2
 - Subdivide blocks to get the right size
 - Adjacent free blocks merged into the next biggest size

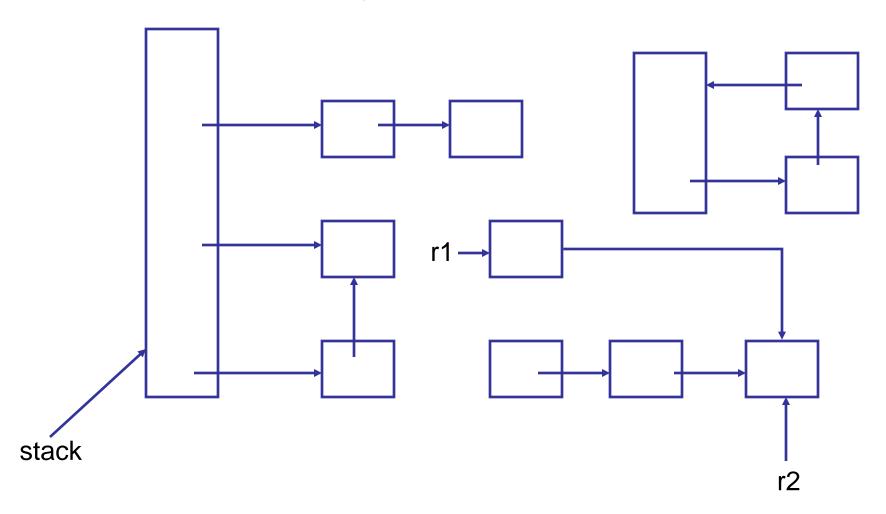
Automatic MM

- Languages with explicit MM are much harder to program than languages with automatic MM
 - Always worrying about dangling pointers, memory leaks: a huge software engineering burden
 - Impossible to develop a secure system, impossible to use these languages in emerging applications involving mobile code
 - languages with unsafe, explicit MM will all but disappear?????

Automatic MM

- Question: how do we decide which objects are garbage?
 - We conservatively approximate
 - Normal solution: an object is garbage when it becomes unreachable from the roots
 - The roots = registers, stack, global static data
 - If there is no path from the roots to an object, it cannot be used later in the computation so we can safely recycle its memory

Object Graph



– How should we test reachability?

Reference Counting

- Keep track of the number of pointers to each object (the reference count).
- When the reference count goes to 0, the object is unreachable garbage

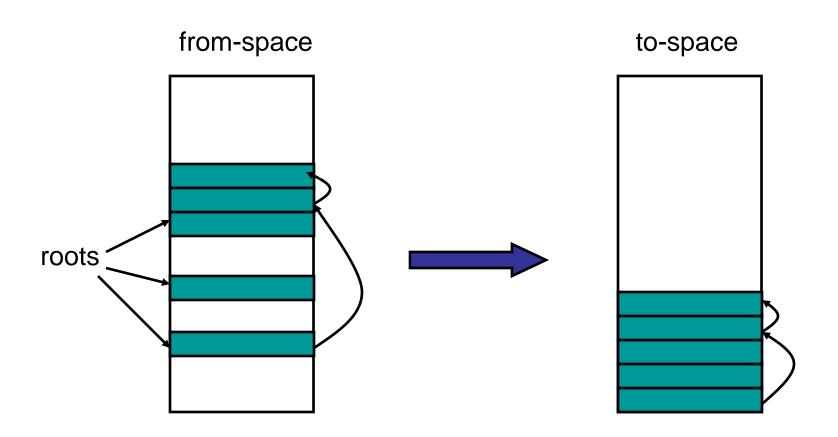
Copying Collection

- Basic idea: use 2 heaps
 - One used by program
 - The other unused until GC time

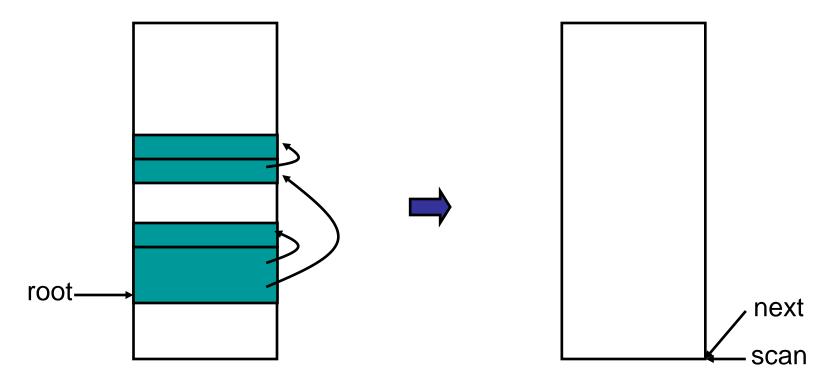
• GC:

- Start at the roots & traverse the reachable data
- Copy reachable data from the active heap (fromspace) to the other heap (to-space)
- Dead objects are left behind in from space
- Heaps switch roles

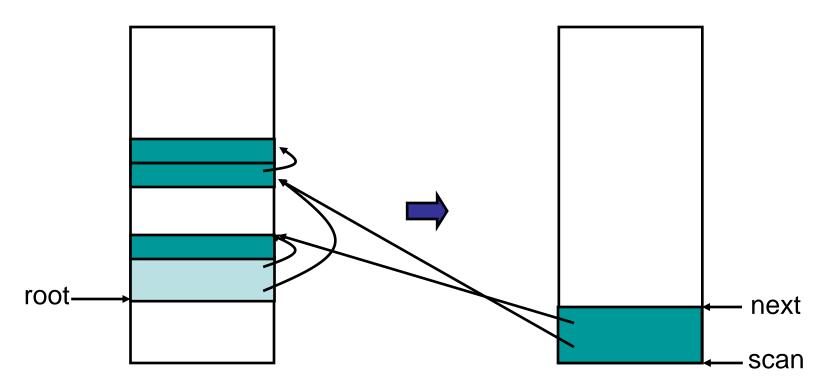
Copying Collection



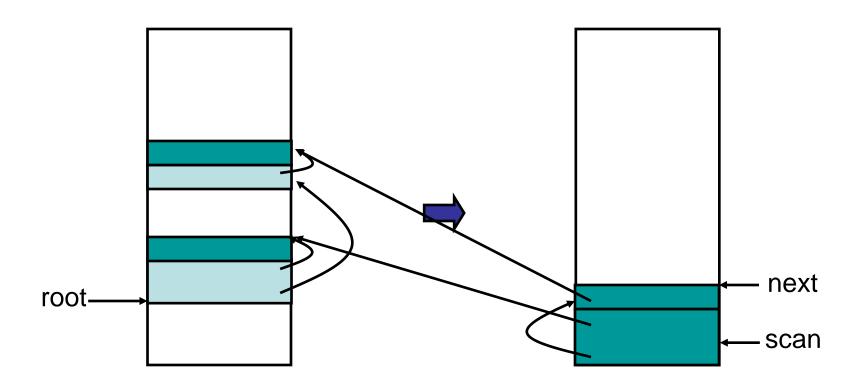
 Traverse data breadth first, copying objects from from-space to to-space



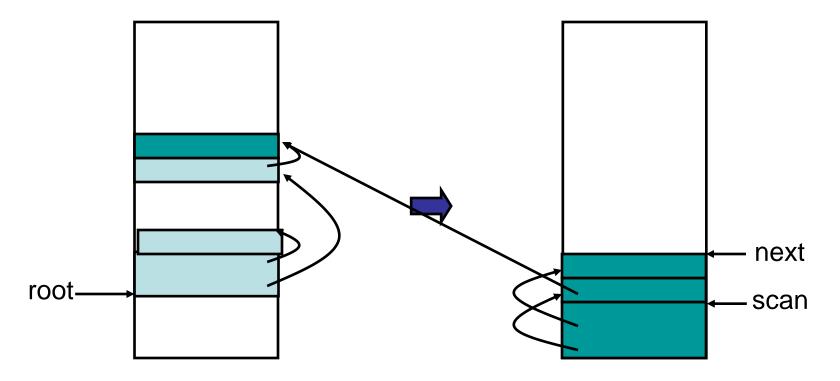
- Cheny's algorithm for copying collection
 - Traverse data breadth first, copying objects from from-space to to-space



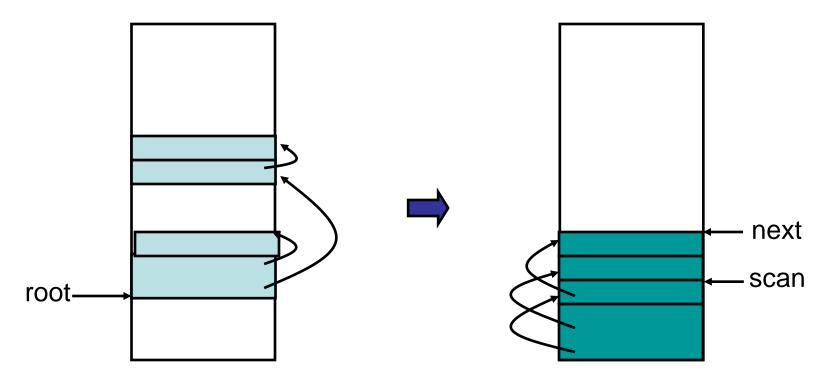
 Traverse data breadth first, copying objects from from-space to to-space



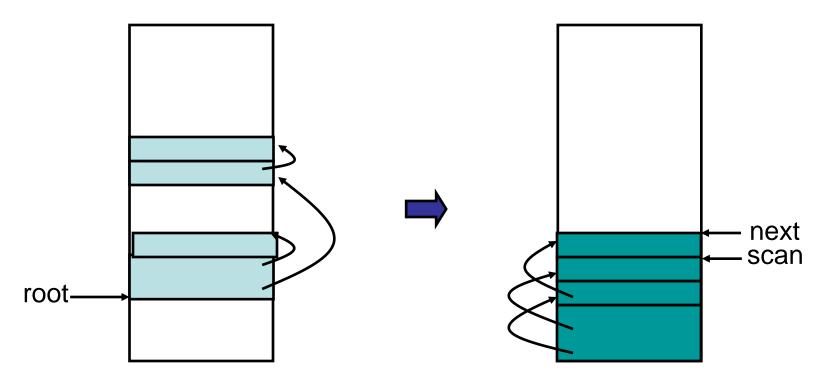
 Traverse data breadth first, copying objects from from-space to to-space



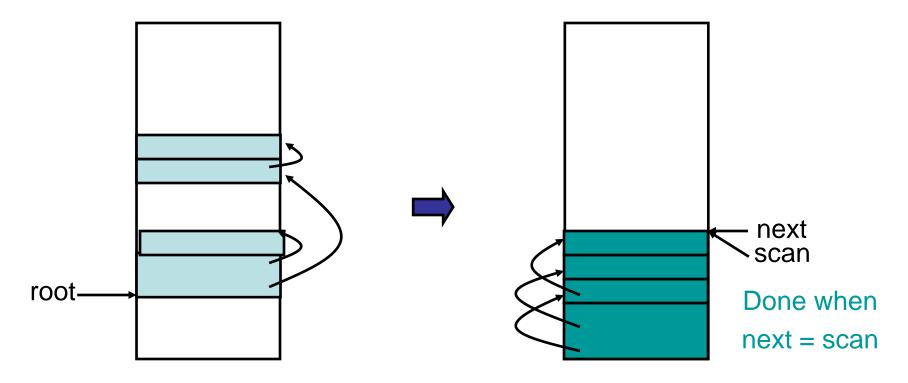
- Cheny's algorithm for copying collection
 - Traverse data breadth first, copying objects from from-space to to-space



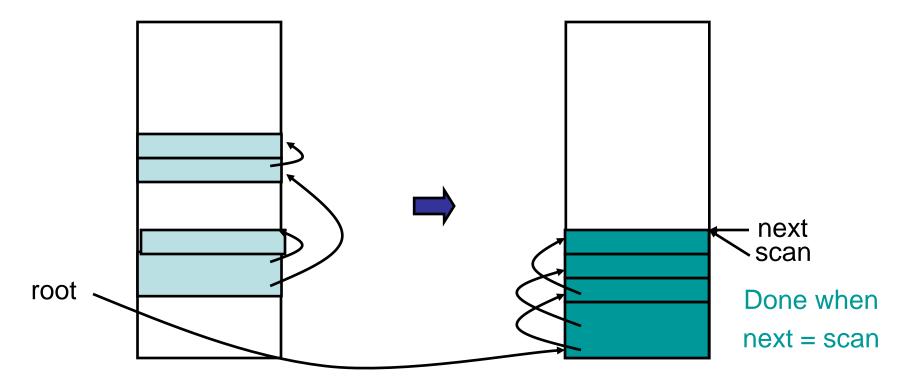
- Cheny's algorithm for copying collection
 - Traverse data breadth first, copying objects from from-space to to-space



- Cheny's algorithm for copying collection
 - Traverse data breadth first, copying objects from from-space to to-space



 Traverse data breadth first, copying objects from from-space to to-space



Pros

- Simple & collects cycles
- Run-time proportional to # live objects
- Automatic compaction eliminates fragmentation

Cons

- Precise type information required
 - Tag bits take extra space; normally use header word
- Twice as much memory used as program requires
- Long GC pauses = bad for interactive, real-time apps

- Empirical observation: if an object has been reachable for a long time, it is likely to remain so
- Empirical observation: in many languages, most objects died young
- Conclusion: we save work by scanning the young objects frequently and the old objects infrequently

- Assign objects to different generations G0, G1,...
 - G0 contains young objects, most likely to be garbage
 - G0 scanned more often than G1
 - Common case is two generations (new, tenured)
 - Roots for GC of G0 include all objects in G1 in addition to stack, registers

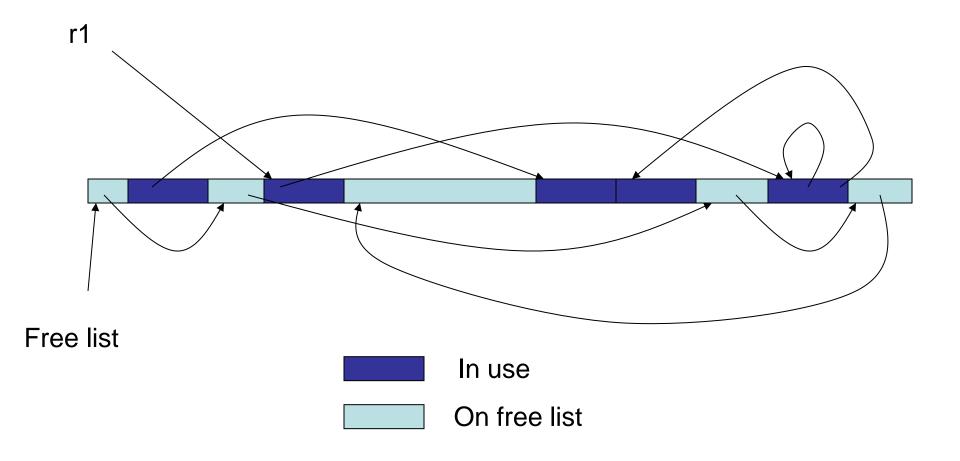
- Other issues
 - When do we promote objects from young generation to old generation
 - Usually after an object survives a collection, it will be promoted
 - When do we collect the old generation?
 - After several minor collections, we do a major collection

- Other issues
 - Sometimes different GC algorithms are used for the new and older generations.
 - Why? Because the have different characteristics
 - Copying collection for the new
 - Less than 10% of the new data is usually live
 - Copying collection cost is proportional to the live data
 - Mark-sweep for the old
 - Next topic

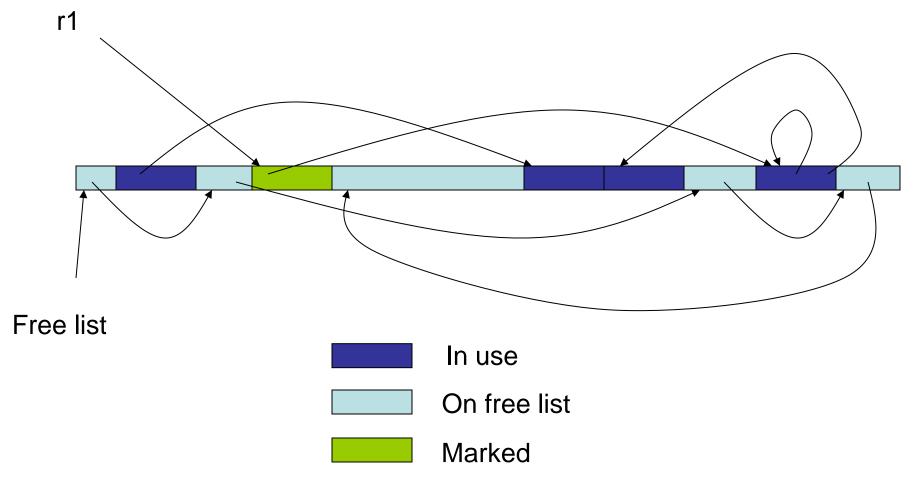
Mark-Sweep

Mark-sweep

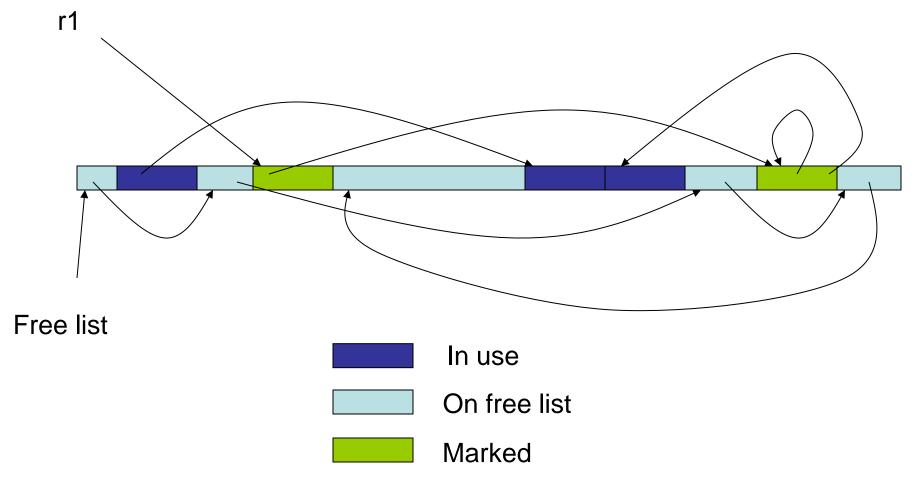
- A two-phase algorithm
 - Mark phase: Depth first traversal of object graph from the roots to mark live data
 - Sweep phase: iterate over entire heap, adding the unmarked data back onto the free list



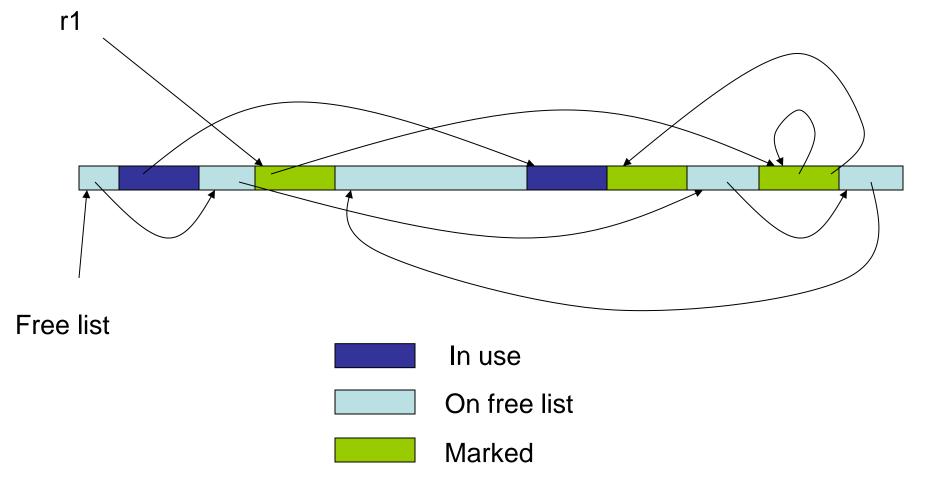
Mark Phase: mark nodes reachable from roots



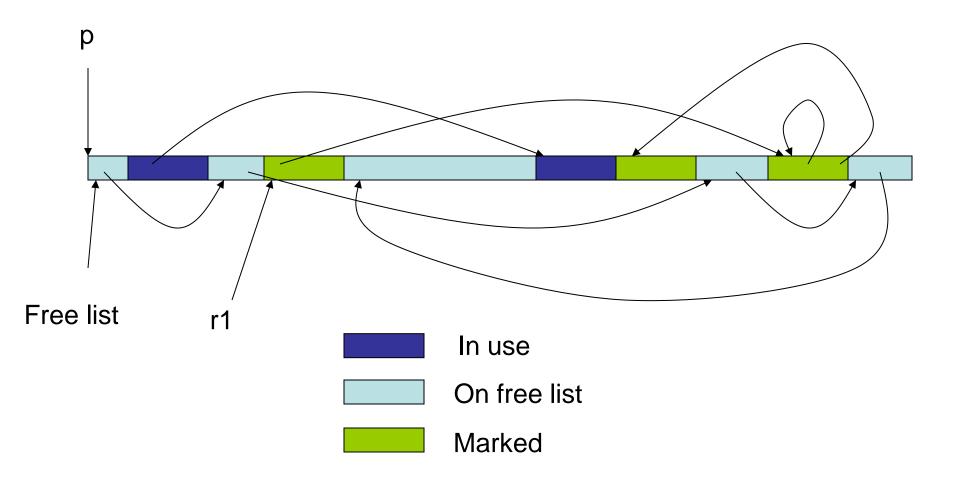
Mark Phase: mark nodes reachable from roots



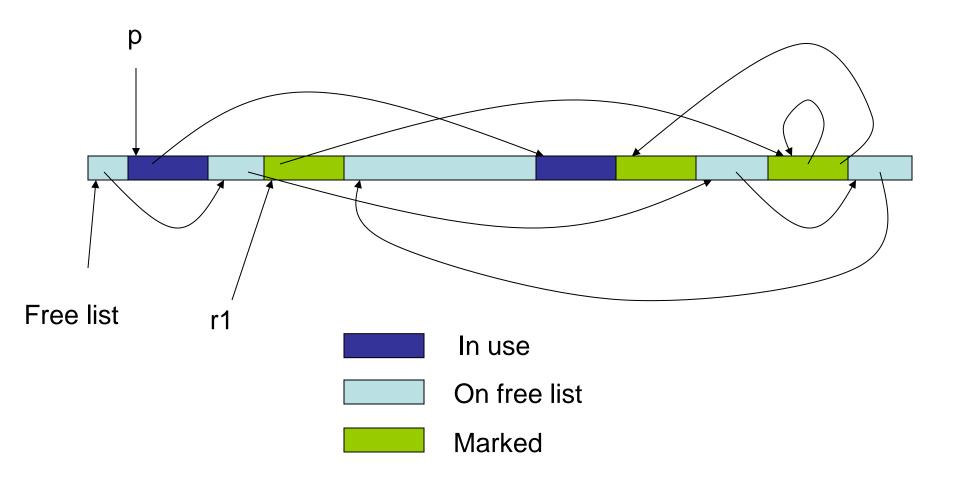
Mark Phase: mark nodes reachable from roots



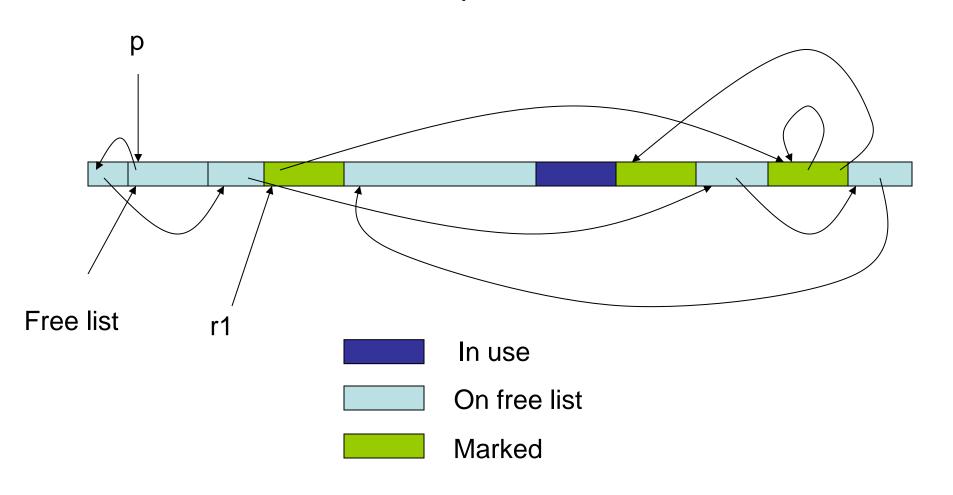
Sweep Phase: set up sweep pointer; begin sweep



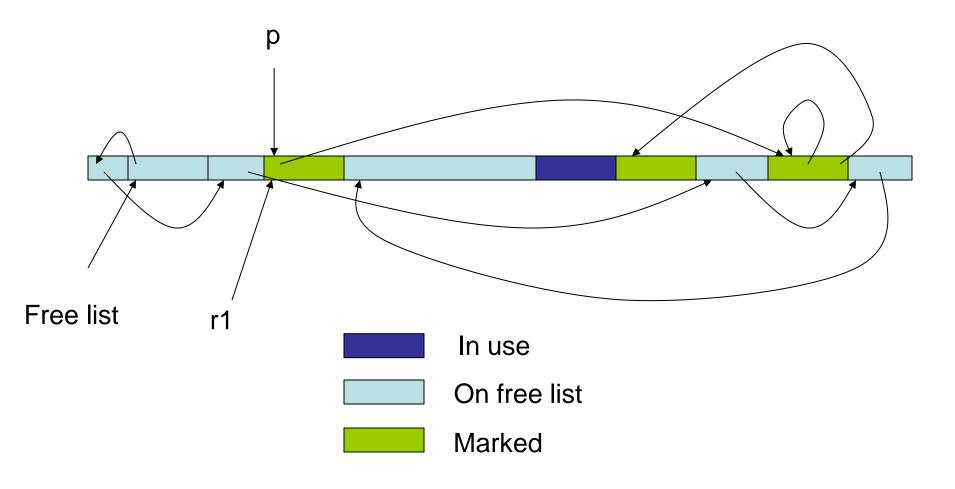
Sweep Phase: add unmarked blocks to free list



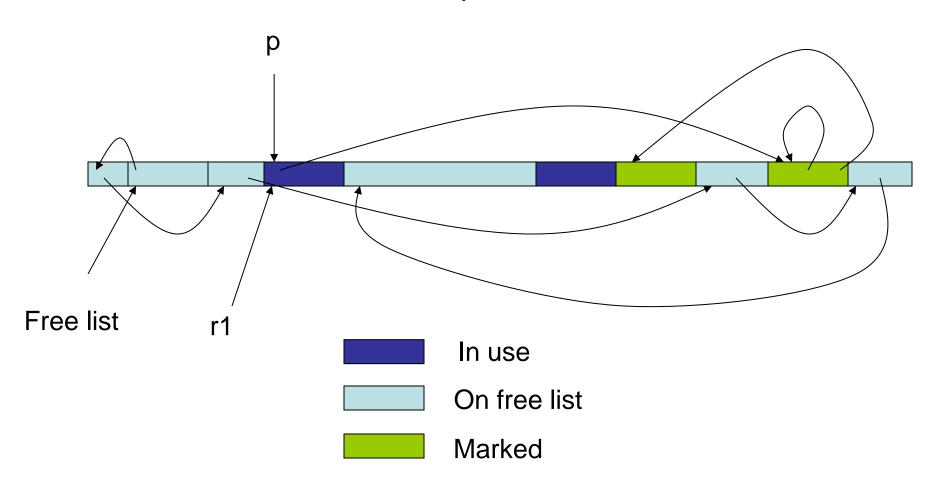
Sweep Phase



Sweep Phase: retain & unmark marked blocks



Sweep Phase



Sweep Phase: GC complete when heap boundary

