University of Alberta Dept. of Electrical and Computer Engineering

ECE 449 Intelligent Systems Engineering

MIDTERM EXAMINATION SOLUTION

Instructor:	P. Musilek		
Exam date:	October 15, 2019		
Exam version:	all		
Start time:	9:30 AM		
Duration:	50 minutes		
Place:	SAB 331		
Instructions:	1. Fill out your printed name, signature and I.D. number on this page 2. Verify that this booklet contains 7 pages (including this cover shee		
	3. Enter your answers in the space provided		

4. Show all of your rough work, marks are awarded for the work, not just the answer.

this cover sheet)

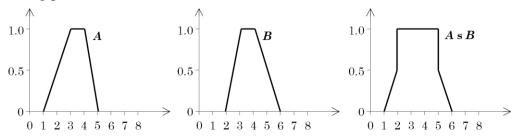
- 5. You are not allowed to use any additional paper. If you require more space for your answer, please use the back of the current sheet, making clear indication that further information is located there.
- 6. You are allowed to use calculator

Name:	 	
Signature:		
Student I D .		

Question(s)	Worth	orth Subject		
I. (1-8)	22	Various (multiple choice, short answer)		
II. (9)	8	Fuzzy relations		
III. (10)	6	Fuzzy rule based system		
IV. (11)	14	Fuzzy controller		
Total	50	-		

I. Multiple choice [18 points total] (there is exactly one correct choice for each question)

- 1. [1 mark] Which of the following relationships can be classified as crisp relation
- ☐ Highway traffic density
- ☐ Gender height
- \square Train speed
- \square Season temperature
- ☐ Student ID
- 2. [1 mark] Possibility measure $Poss(A, B) = \sup_{x \in X} [\min(A(x), B(x))]$ describes
- \square Degree of equality of fuzzy sets A and B
- \square Degree of underlap between fuzzy sets A and B
- \square Degree of inclusion of fuzzy set *A* in fuzzy set *B*
- \square Degree of overlap between fuzzy sets A and B
- \square Degree of inclusion of fuzzy set B in fuzzy set A
- 3. [2 marks] Which s-norm is used to perform fuzzy union of fuzzy sets A and B in the following picture

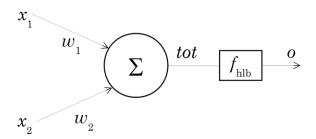


- \square Standard **s**-norm: max(a,b)
- \square Bounded sum **s**-norm: a+b-ab
- \square Lukasiewicz **s**-norm: min(1,a+b)
- Drastic sum s-norm: max(a,b) if min(a,b)=0, otherwise 1
- \square Any of the above
- 4. [4 marks] Consider a fuzzy control system with three output fuzzy sets described by triangular membership functions B1=(y;1,2,3), B2=(y;2,3,4), B3=(y;3,4,5). Suppose that for a given input, these fuzzy sets are activated to levels $\lambda_1 = 0.3$, $\lambda_2 = 0.7$, $\lambda_3 = 0.5$, and that the inference is based on Larsen implication (product). Which of the following relations describes correct ordering of output values obtained using COG (center of gravity), SOM (smallest of maxima), MOM (mean of maxima), and LOM (largest of maxima) defuzzification methods
- \square SOM < MOM < COG < LOM
- \square SOM = MOM = LOM = COG
- \square SOM = MOM = LOM < COG
- \square COG < SOM = MOM = LOM
- \square SOM < COG < MOM < LOM

- 5. [4 marks] Recurrent connections impact the operation of neural networks. Evaluate the following eight statements as characteristic for either feedforwad or recurrent networks by adding appropriate words (feedforwad or recurrent) at the blanks.
- **R**_____ networks are closed loop systems.
- **F** _____ networks perform direct calculations.
- **F** _____ networks have fixed calculation time.
- **R** _____ networks require "setting time".
- **R** _____ networks have memory.
- **F** _____ networks perform direct I/O mapping.
- **R** ______ networks behave as a state-machine.
- **F** _____ networks are open loop systems.
- 6. [2 marks] Briefly explain so called *hundred steps rule*

Complex perceptual decisions are arrived at quickly (within a few hundred ms). Individual neurons operate slowly (10^{-3} sec) , these calculations do not involve more than about 100 serial steps and the information sent from one neuron to another is very small (a few bits)

7. [4 points] Consider artificial neuron shown in the following diagram



a) Write down formulas for calculating tot and o

$$tot = \sum x_i w_i = x_1 w_1 + x_2 w_2; o = f_{hlb} (tot)$$

b) Evaluate tot and o for the input values $x_1 = 1$, $x_2 = -1$ and weights $w_1 = 0.8$, $w_2 = 0.3$

$$tot = 1 \ 0.8 + (-1) \ 0.3 = 0.5; \ o = f_{\text{hlb}} \ (0.5) = +1$$

8. [4 points] Add missing connections to the following figures according to their captions. Only add connections of the requested type to each figure.

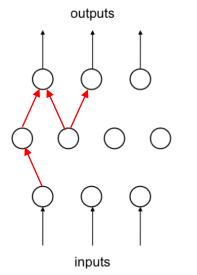


Figure 11 a) Feedforward connections

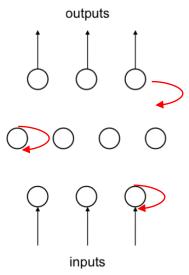


Figure 11 b) Local feedback connections

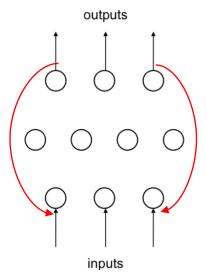


Figure 11 c) Global feedback connections

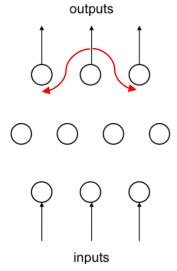


Figure 11 d) Lateral connections

II. Fuzzy relations [8 points]

9. Consider a fuzzy relation, R, defined in matrix form

$$R(x,y) = \begin{bmatrix} 1.0 & 0.4 & 0.8 & 0.3 & 0.0 \\ 0.5 & 1.0 & 0.6 & 0.7 & 1.0 \\ 0.9 & 1.0 & 0 & 0.6 & 0.8 \\ 1.0 & 0.5 & 0.2 & 0.0 & 0.9 \\ 0.3 & 0.5 & 0.3 & 0.1 & 1.0 \end{bmatrix}$$

a) [3 marks] Determine projections $ProjR_x$ and $ProjR_y$ of the relation R.

$$ProjR_x(x) = \sup_{x \in X} R(x, y) = \begin{bmatrix} 1.0 & 1.0 & 1.0 & 1.0 \end{bmatrix}^{T}$$

$$ProjR_y(y) = \sup_{y \in Y} R(x, y) = \begin{bmatrix} 1.0 & 1.0 & 0.8 & 0.7 & 1.0 \end{bmatrix}$$

b) [3 marks] Reconstruct the relation from these projections using min *t*-norm.

c) [2 mark] Comment on quality of the reconstruction obtained in 9b).

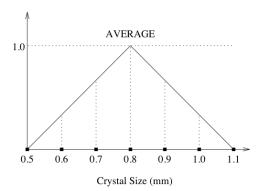
Reconstruction is poor. In fact, only the 'envelope' of the original relation can be reconstructed. Reason: by projection, the data has been compressed (dimensionality has been reduced).

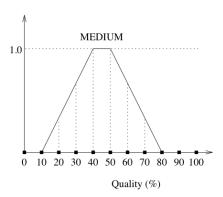
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III. Fuzzy rule based system [6 points]

10. Consider a fuzzy system containing the following rule

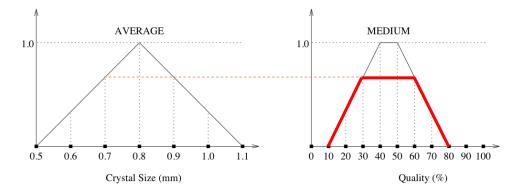
with memberships discretely defined as





a) [4 marks] Derive the relation matrix of the rule using min implication

b) [2 marks] In the provided figures, sketch the membership function of quality for crystal_size 0.7 mm, obtained using Mamdani implication.



IV. Fuzzy controller [14 points]

11. [14 marks total] Consider a fuzzy controller using Sugeno inference with the following rules

R1: IF x is A1 THEN c is {10} ELSE

R2: IF x is A2 THEN c is $\{30\}$ ELSE

R3: IF x is A3 THEN c is $\{20\}$ ELSE

R4: IF x is A4 THEN c is $\{40\}$

and with fuzzy sets defined using the following triangular membership functions

$$A1 = (x; 2, 2, 6)$$

$$A2 = (x; 2, 6, 10)$$

$$A3 = (x; 6, 10, 14)$$

$$A4 = (x; 10, 14, 14)$$

a) [4 marks] Determine the degree of fulfillment, λ , of each rule, for input value x = 10.

$$\lambda$$
 (R1) = 0

$$\lambda$$
 (R2) = 0

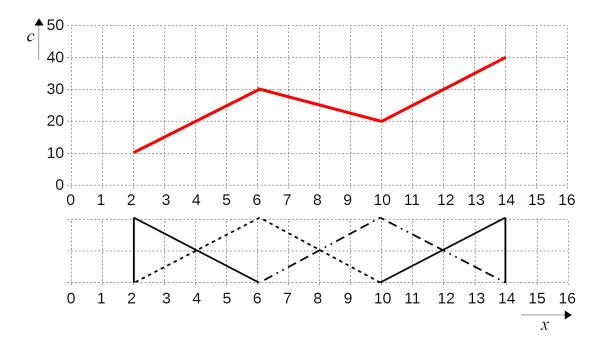
$$\lambda$$
 (R3) = 1

$$\lambda$$
 (R4) = 0

b) [2 marks] Determine the value of the crisp output of the controller for the same input value (x = 10).

C = 20

c) [8 marks] Sketch the numerical characteristic of the controller



Note: for your convenience, description of rules and fuzzy sets is copied below

Rules

R1: IF x is A1 THEN c is {10} ELSE

R2: IF x is A2 THEN c is $\{30\}$ ELSE

R3: IF x is A3 THEN c is $\{20\}$ ELSE

R4: IF x is A4 THEN c is $\{40\}$

Input fuzzy sets (triangular membership functions)

$$A1 = (x; 2, 2, 6)$$

$$A2 = (x; 2, 6, 10)$$

$$A3 = (x; 6, 10, 14)$$

$$A4 = (x; 10, 14, 14)$$

Do not write in this space!

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