Neural Networks Associative Networks

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Associative Networks



Hebbian Learning

Donald Hebb (1949)

As neuron *i* becomes more efficient in stimulating neuron *j* during training

- i sensitizes j to its stimulus
- Weight w_{ii} increases

$$w_{ij}^{\text{new}} = w_{ij}^{\text{old}} + \eta x_i o_j$$
Problems?

Modified Hebian learning (Grossberg)

Allows weights to decrease when not longer stimulated

$$w_{ij}^{\mathrm{new}} = w_{ij}^{\mathrm{old}} (1 - \alpha) + \eta x_i o_j$$

forgetting term + Hebbian term

$$\frac{w_{ij}^{\text{new}} - w_{ij}^{\text{old}}}{\Delta t} = \frac{\Delta w_{ij}}{\Delta t} \rightarrow \frac{dw_{ij}}{dt} = -\alpha w_{ij}^{\text{old}} + \eta x_i o_j$$

i.e. slow exponential weight decay with time constant α

Differential Hebian learning

Allows weights to decrease when the output decreases

$$w_{ij}^{
m new} = w_{ij}^{
m old} (1 - \alpha) + \eta \frac{dx_i}{dt} \frac{do_j}{dt}$$

forgetting term + differential term

(rate of change used instead of value)

Note:

No target values used for training - this is an unsupervised learning.

Grossberg Learning

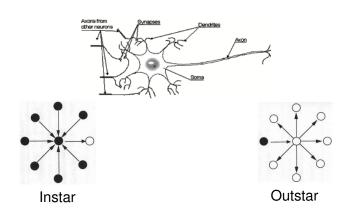
Attempt to mathematically explain psychological conditioning experiments

- Observational conditioning (monkeys)
- Operational conditioning (action/response)
- Classical conditioning (Pavlov)

Pavlov's experiment

Stage	Stimulus	Response
1	Unconditional	Unconditioned
	(food)	(dog salivates)
2	Unconditional (food)	Conditioned
	PLUS Conditioned (bell)	(dog salivates)
3	Conditioned	Conditioned
	(bell)	(dog salivates)

Concepts of instar and outstar



Instar activity

- The activity must grow when there is an external stimulus
- It must rapidly decrease if it is no longer externally stimulated
- It must respond to stimuli from other neurons in the network

Instar Learning rule

If inputs and weights are normalized, *tot* is largest when weights are identical to input values

• weights would be changed only if they are different from the inputs

$$\Delta w_i = \eta (x_i - w_i)$$

- incoming weights of neuron converge to input pattern (previous layer)
- unsupervised learning (no targets available)

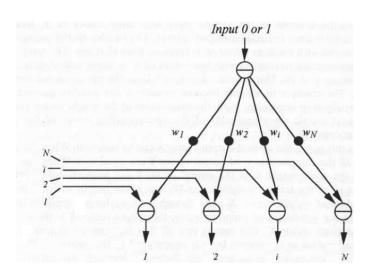
Outstar Learning rule

Weights connected to certain node should be equal to the desired outputs for the neurons they connect

$$\Delta w_{ij} = \eta (t_j - w_{ij})$$

- outgoing weights of neuron converge to output pattern (next layer)
- neuron learns to recall pattern when stimulated
- supervised learning

Outstar learning



Associative Memories (AM)

Systems that store information by associating each data item with one or more other stored data items, (usually) in distributed form.

- Content addressable (CAM)
- Robust
 - Noisy data
 - Incomplete data
 - Failed elements

Associative Memories ...

- Concept: object or pattern x (input) reminds the network of object or pattern o (output)
- Many biological neural nets are associative memories
- Heteroassociative Vs. autoassociative memories
 - If x and o are different, the system is called heteroassociative network
 - If x and o are the same, the system is called autoassociative nettwork

Associative Memories ...

- Unidirectional vs. bidirectional memories
 - Unidirectional: x reminds you of o
 - Bidirectional: x reminds you of o and o reminds you of x
- Recognizing new or incomplete patterns
 - Recognizing patterns that are similar to one of the patterns stored in memory (generalization)
 - Recognizing incomplete or noisy patterns whose complete (correct) forms were previously stored in memory

Bidirectional Associative Memory

BAM is a matrix representing a crossbar network with symmetric weights

- the network has two layers
- each neuron in a layer has one output from the outside, and
- inputs from all neurons of the other layer

BAM can store pattern pairs $[\boldsymbol{x}(k), \boldsymbol{o}(k)]$; k = 1, ..., n and recall

- o corresponding to particular x, or
- x corresponding to particular o
- i.e. it works in both directions → bidirectional

Setting of BAM weights

Weights are not obtained by training process but directly constructed from input-output pairs, e.g. binary to grey code

```
m{x}(1): ( 0 0 1 0 ) \iff ( 0 0 1 1 ) :m{o}(1)
m{x}(2): ( 0 0 1 1 ) \iff ( 0 0 0 0 ) :m{o}(2)
m{x}(3): ( 0 1 0 0 ) \iff ( 0 1 1 0 ) :m{o}(3)
```

- Before proceeding, the values must be converted to bipolar (0s become -1s while 1s remain)
- From each pair, a mapping matrix $\mathbf{M}_k = \mathbf{x}(k) \times \mathbf{o}(k)$ is constructed
- The matrices are then combined into a master matrix $\mathbf{M} = \mathbf{M}_1 + \mathbf{M}_2 + \cdots + \mathbf{M}_n$

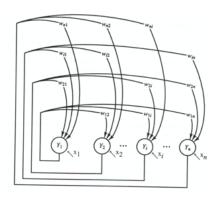
Hopfield Network



- A more advanced type of autoassociative memory
- Almost fully connected
- Architecture
 - symmetric weights

$$w_{ij} = w_{ji}$$

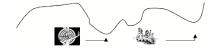
- notice the "feedback" in the network structure
- no feedback from a cell to itself $w_{ii} = 0$



Principle

Based on the physical principle that every object seek a low energy static position.

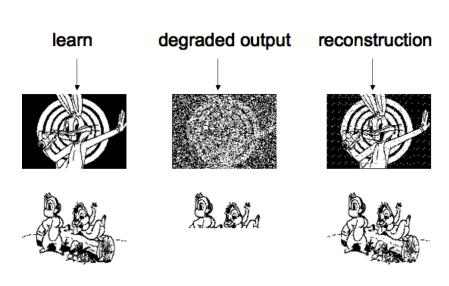
During learning, the network uses input to define the low energy points.



When a similar to a learned position is encountered, some neurons will drag the other neurons to the static position.



Illustration



Operation

- Task: Store images with resolution 20×20 pixels (need a network with 400 nodes)
- Learning:
 - 1. Present image
 - Apply Hebb rule: cells that fire together, wire together (increase weight between two nodes if both have same activity, otherwise decrease)
 - 3. Go back to 1
- Recall:
 - 1. Present incomplete pattern
 - 2. Pick random node, update
 - 3. Repeat 2 until settled

Hebbian rule for Hopfield network

Changes are proportional to the correlation between the firing (activity) of the pre- and post-synaptic neurons.

Technically:

Consider

$$T = \{x(k)|x(k) = (x_1(k), \dots, x_m(k)) \in \{-1, 1\}^m, k = 1, \dots, n\}$$

- Start with $w_{ii} = 0 (j = 1, ..., m; i = 1, ..., m)$
- For given training set T do

$$w_{ij} = \sum_{k=1}^{n} x_j(k)x_i(k), 1 \leq j \neq i \leq m$$

Active Mode of Hopfield Network

- 1. Set $o_i = x_i (i = 1, ..., m)$
- 2. Go through all neurons and at each time step select one neuron j to be updated according the following rule:
 - compute its internal potential $tot_j = \sum_{i=1}^m w_{ij} o_i$
 - set its new state $o_j = \begin{cases} 1 & \text{if } tot_j > 0, \\ o_i & \text{if } tot_j = 0, \\ -1 & \text{if } tot_j < 0. \end{cases}$
- IF not stable configuration THEN go to step 2
 ELSE end - output of the net is determined by the current state of neurons.

Energy Function and Landscape

Energy function
$$E(o) = -\frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} w_{ij} o_i o_j$$

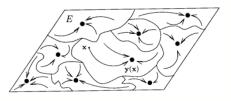
Energy Landscape

- high energy unstable states
- low energy more stable states
- energy always decreases (or remain constant) as the system evolves according to its dynamical rule



Attractors and Phantoms

- Local minima of the energy function represent stored examples - attractors
- Basins of attraction catchment areas around each minimum
- False local optima phantoms





Storage Capacity of Hopfield Network

- Capacity of the network maximum number of patterns that can be stored without unacceptable errors.
- Empirical results
 - $n \le 0.138m$ training examples as local minima of E(o)
 - n < 0.05m training examples as global minima of E(o), deeper minima than those corresponding to phantoms
- Example: 10 tr. examples, 200 neurons → 40000 weights

Example

Pattern recognition

- 8 examples, matrix 12×10 pixels → 120 neurons
- input pattern with 25% bits incorrect

