

Edge connectivity (Global minimum cut)

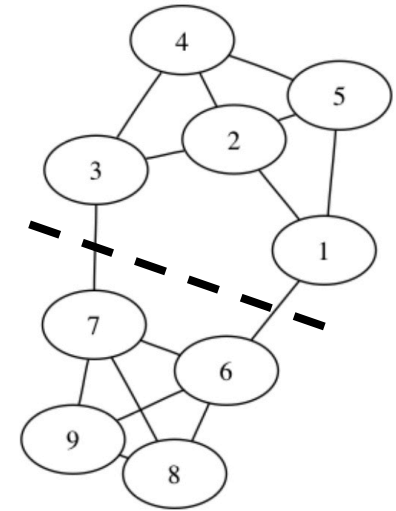
turn the graph into directed graph, set all edge capacities to 1

pick any node v

for all $u \in V \setminus \{v\}$

run max-flow algorithm with source v and sink u

output the minimum flow obtained



Complexity: $O(n \cdot n^3) = O(n^4)$

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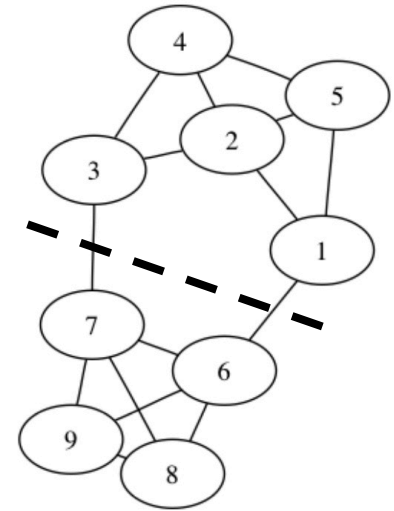
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Improvements:

$O(m \cdot \text{polylog}(n))$ [Karger 1991] *probabilistic algorithm*

$O\left(m + K^2 n \log \frac{n}{K}\right)$ where K is edge connectivity [Gabow 1995]

$O(nm + n^2 \log n)$ [Stoer, Wagner 1997] (*simple! weighted case*)

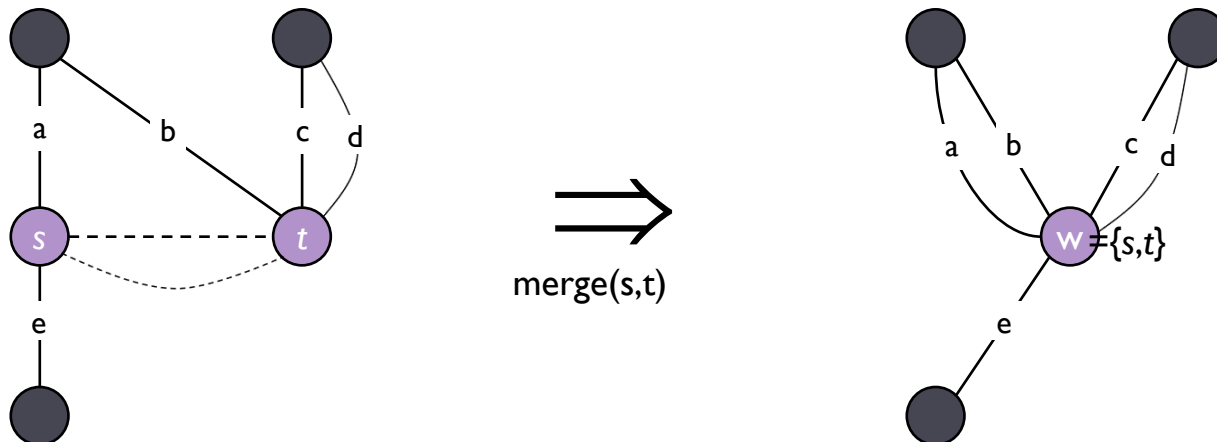
$O(m \cdot \text{polylog}(n))$ [Kawarabayashi, Thorup 2018]

Considerations

- ▶ Enumerating all $u \in V \setminus \{v\}$ in the previous algorithm seems inefficient and *may* be improved
- ▶ Computing edge connectivity *may* be simpler than computing maximal flow, as we don't have fixed s and t . (We only need to find *some* s and t in opposite sides of the cut)

[Stoer, Wagner 97]: first idea

- ▶ Consider some nodes s and t and assume we know $\text{mincut}(s, t)$ (minimum cut which separates s and t)
- ▶ **Case 1**: $\text{mincut}(s, t)$ is the global minimum cut
- ▶ **Case 2**: otherwise, s and t are on the same side of the global min cut \Rightarrow global min cut is not changed if s and t are **merged** (parallel edges allowed)



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```
function GlobalMinCut( $G$ )
```

```
  if  $V = \{u, v\}$  then
```

```
    return nb of edges between  $u$  and  $v$ 
```

```
  else
```

```
     $(C_1, s, t) = \text{stMinCut}(G)$ 
```

```
     $C_2 = \text{GlobalMinCut}(G / \{s, t\})$ 
```

```
    return  $\min\{C_1, C_2\}$ 
```

returns $s, t \in V$ with
 $C_1 = \text{mincut}(s, t)$

G with merged s, t

[Stoer, Wagner 97]: second idea

- ▶ $stMinCut(G)$ returns some nodes $s, t \in V$ with $C_1 = mincut(s, t)$
- ▶ can be done more efficiently than computing max flow!

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function $stMinCut(G)$

$A = \{v\}$

arbitrary node

while $A \neq V$

 pick $u \in V \setminus A$ s.t. nb of edges between A and u is maximized


$A = A \cup \{u\}$

let s, t be the last two nodes added to A and C the number
 of edges between t and $V \setminus \{t\}$,

return (C, s, t)

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- ▶ $stMinCut(G)$ returns some nodes $s, t \in V$ with $C_1 = mincut(s, t)$
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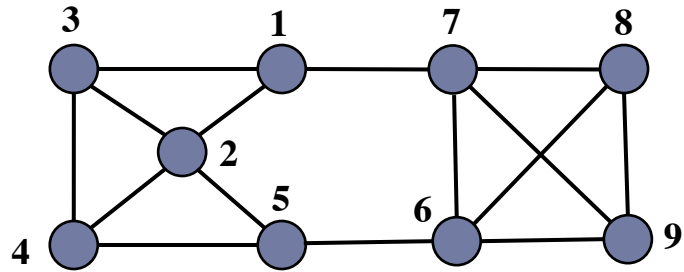
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function  $stMinCut(G)$ 
     $A = \{v\}$   arbitrary node
    while  $A \neq V$ 
        pick  $u \in V \setminus A$  s.t. nb of edges between  $A$  and  $u$  is maximized
         $A = A \cup \{u\}$ 
    let  $s, t$  be the last two nodes added to  $A$  and  $C$  the number
        of edges between  $t$  and  $V \setminus \{t\}$ ,
    return  $(C, s, t)$ 
```

Theorem: $stMinCut$ is correct

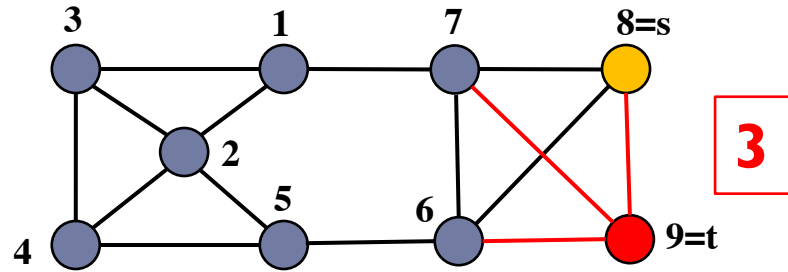
Proof: cf [Stoer, Wagner 97] or

<http://www.cs.tau.ac.il/~zwick/grad-algo-08/gmc.pdf>

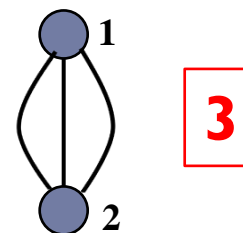
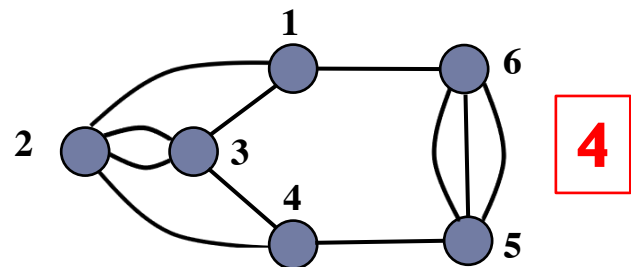
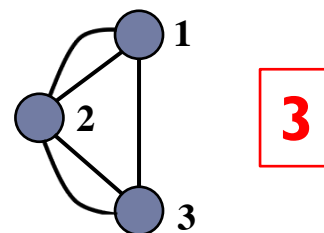
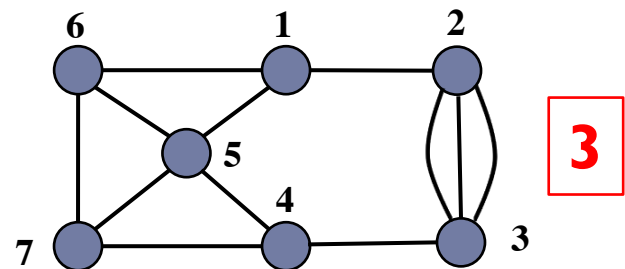
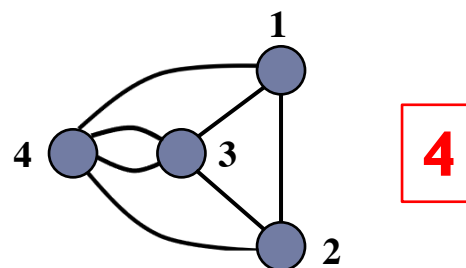
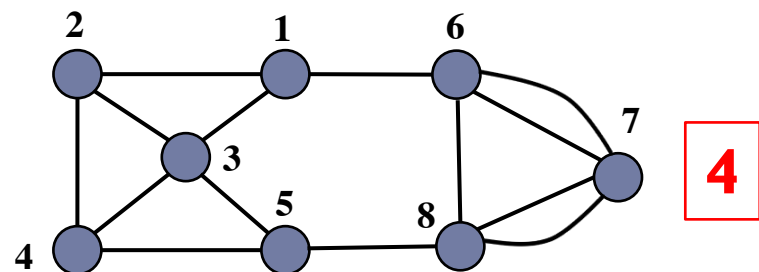
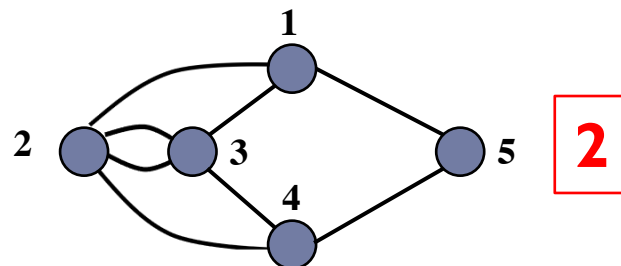
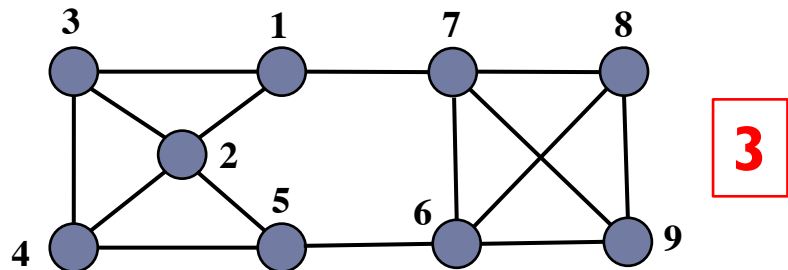
Example



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[Stoer, Wagner 97]: resulting complexity

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- ▶ how $stMinCut(G)$ is implemented?
- ▶ max-priority queue!
 - ▶ maintain all nodes outside A in a max-priority queue
 - ▶ when adding a node u to A , increment keys of all nodes $x \in V \setminus A$ by the number of edges $\{u, x\}$
- ▶ implementation with binary heaps:
 - ▶ construction: $O(n \log n)$ (all keys set to 0)
 - ▶ $n - 1$ extract-max: $O(n \log n)$
 - ▶ m updates (increments): $O(m \log n)$
 - ▶ altogether, $stMinCut(G)$ takes time $O((m + n) \log n)$
- ▶ resulting complexity of $GlobalMinCut(G)$:
 $O(n(n + m) \log n)$
- ▶ with Fibonacci heaps: $O(nm + n^2 \log n)$