





Microcontroladores Aplicados a IoT

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02 – ESP32: GPIO

Microcontroladores Aplicados a IoT

Estabelecendo comunicação serial



- Checar a porta serial no Linux

```
$ ls /dev/ttyUSB*
```

- Quando há um dispositivo conectado

```
dilson@dilson-VirtualBox:~$ ls /dev/ttyUSB*  
ls: não foi possível acessar '/dev/ttyUSB*': Arquivo ou diretório inexistente  
dilson@dilson-VirtualBox:~$
```

- Quando não há dispositivo serial conectado

```
dilson@dilson-VirtualBox:~$ ls /dev/ttyUSB*  
/dev/ttyUSB0  
dilson@dilson-VirtualBox:~$
```

Erro de permissão na serial



```
0x8000 partition_table/partition-table.bin 0x1000 bootloader/bootloader.bin 0x10000 main.bin
esptool.py v3.3-dev
Serial port /dev/ttyUSB0
Traceback (most recent call last):
  File "/home/dilson/.espressif/python_env/idf4.3_py3.8_env/lib/python3.8/site-packages/serial/serialposix.py", line 322, in open
    self.fd = os.open(self.portstr, os.O_RDWR | os.O_NOCTTY | os.O_NONBLOCK)
PermissionError: [Errno 13] Permission denied: '/dev/ttyUSB0'

During handling of the above exception, another exception occurred:

Traceback (most recent call last):
  File "/home/dilson/Documentos/PadoLabs/ESP32/esp-idf/components/esptool_py/esptool/esptool.py", line 5347, in <module>
    main()
  File "/home/dilson/Documentos/PadoLabs/ESP32/esp-idf/components/esptool_py/esptool/esptool.py", line 5340, in _main
    main()
  File "/home/dilson/Documentos/PadoLabs/ESP32/esp-idf/components/esptool_py/esptool/esptool.py", line 4647, in main
    esp = esp or get_default_connected_device(ser_list, port=args.port, connect_attempts=args.connect_attempts,
  File "/home/dilson/Documentos/PadoLabs/ESP32/esp-idf/components/esptool_py/esptool/esptool.py", line 114, in get_default_connected_device
    esp = chip_class(each_port, initial_baud, trace)
  File "/home/dilson/Documentos/PadoLabs/ESP32/esp-idf/components/esptool_py/esptool/esptool.py", line 320, in __init__
    self._port = serial.serial_for_url(port)
  File "/home/dilson/.espressif/python_env/idf4.3_py3.8_env/lib/python3.8/site-packages/serial/__init__.py", line 90, in serial_for_url
    instance.open()
  File "/home/dilson/.espressif/python_env/idf4.3_py3.8_env/lib/python3.8/site-packages/serial/serialposix.py", line 325, in open
    raise SerialException(msg.errno, "could not open port {}: {}".format(self._port, msg))
serial.serialutil.SerialException: [Errno 13] could not open port /dev/ttyUSB0: [Errno 13] Permission denied: '/dev/ttyUSB0'
CMake Error at run_serial_tool.cmake:50 (message):
  /home/dilson/.espressif/python_env/idf4.3_py3.8_env/bin/python
  /home/dilson/Documentos/PadoLabs/ESP32/esp-idf/components/esptool_py/esptool/esptool.py
  --chip esp32 failed
```

Acesso à comunicação serial



- Verifique se seu usuário está no grupo dialout

\$ id

```
dilson@dilson-VirtualBox:~$ id
uid=1000(dilson) gid=1000(dilson) grupos=1000(dilson),4(adm),20(dialout),24(cdrom),27(sudo),30(dip),46(plugdev),120(lpadmin),132(lxd),133(sambashare)
dilson@dilson-VirtualBox:~$
```

- Se não estiver, adicione seu usuário ao grupo dialout

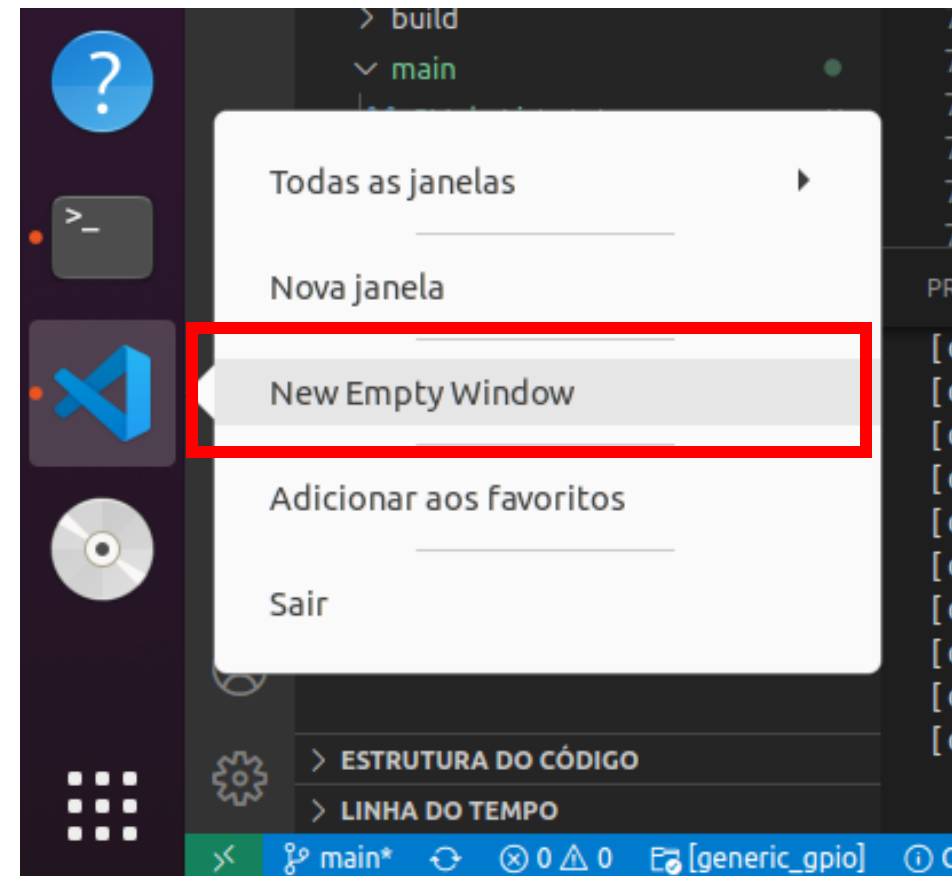
\$ sudo usermod -a -G dialout \$USER

\$ sudo adduser \$USER dialout

- Faça o logout e o login para ter acessos de escrita na porta serial

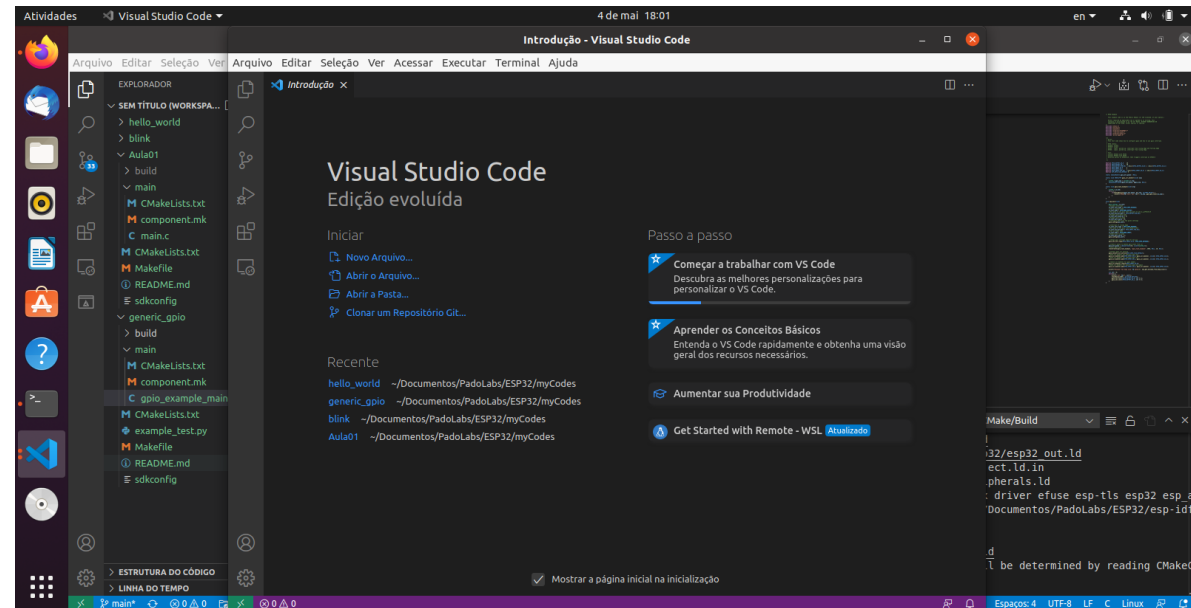
Resetar "view" do VSCode

- Clique com o botão direito do mouse sobre o ícone do VSCode na barra de tarefas.
- Na janela que se abre, clique em "New Empty Window"



Resetar "view" do VSCode

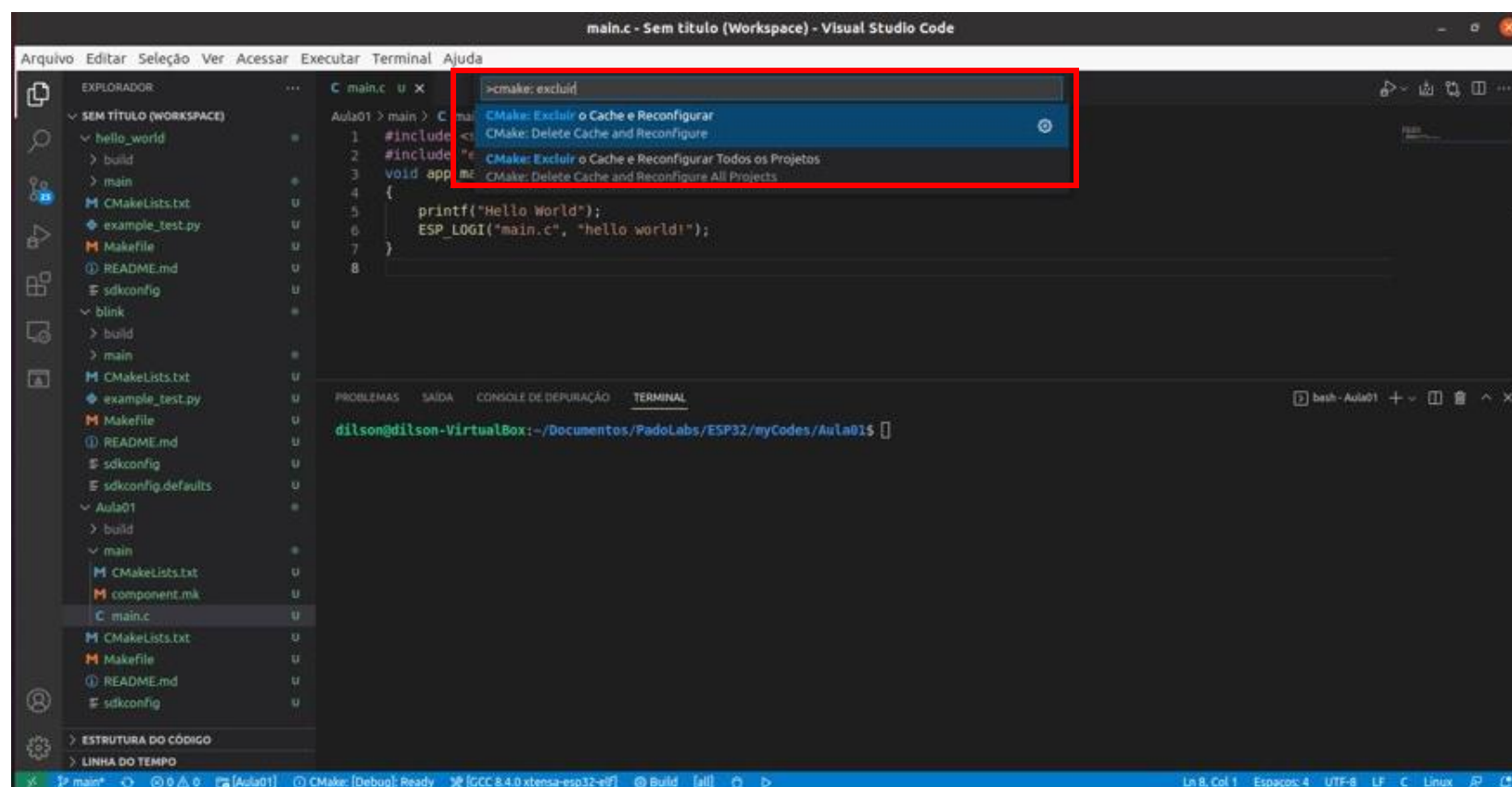
- Uma nova instância do VSCode irá se iniciar (com a página Introdução aberta)
- Feche as outras janelas do VSCode, deixando a nova instância por último.
- A próxima vez que executar o arquivo edit.desktop o VSCode abrirá em uma "instância limpa"



CMake: excluir e reconfigurar



- Ctrl + Shift + P
- Digite "cmake: Excluir"
- Na lista que aparece, clique em "CMake: Excluir o Cache e Reconfigurar"



idf.py



- Deleta todo o diretório build

\$ idf.py fullclean

idf.py



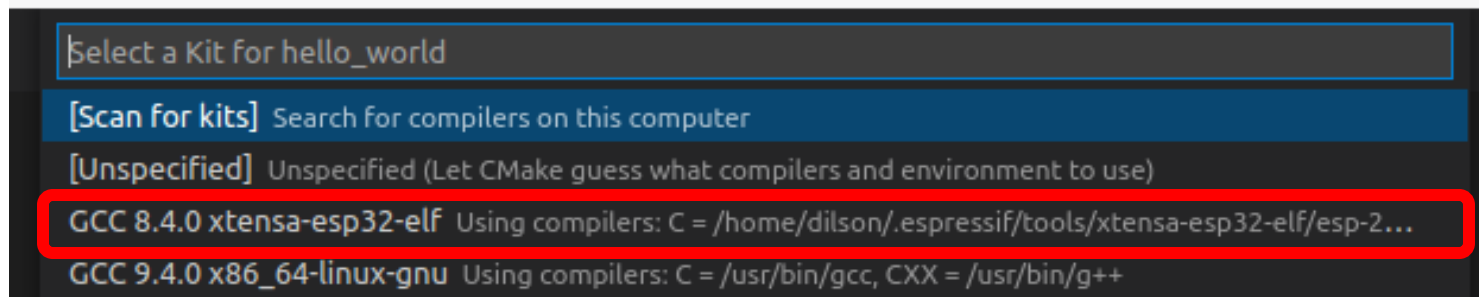
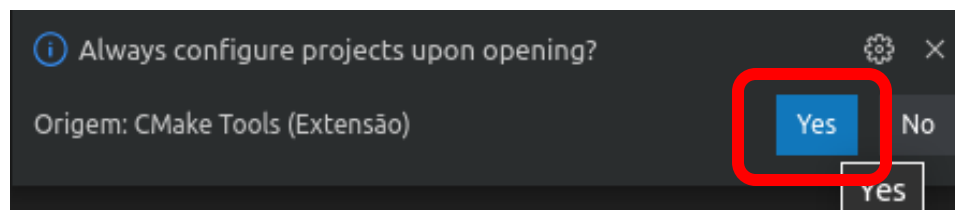
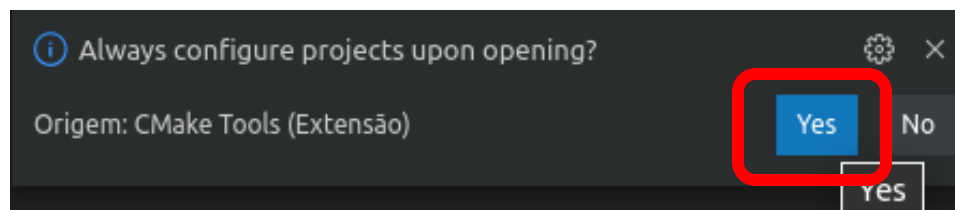
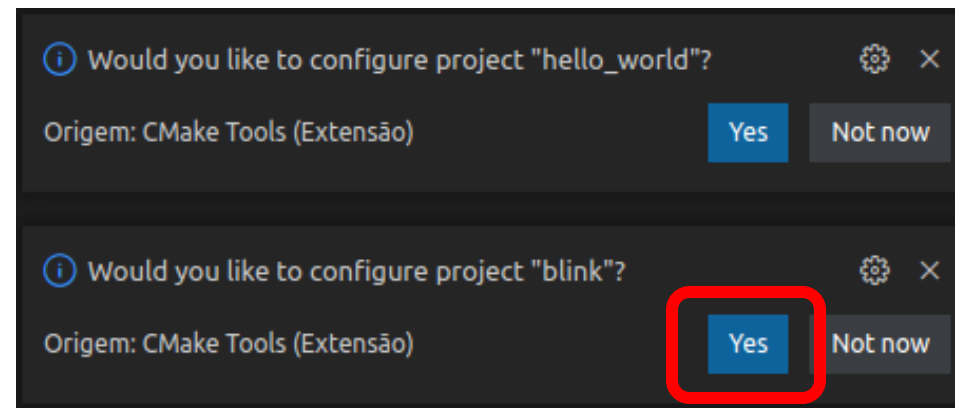
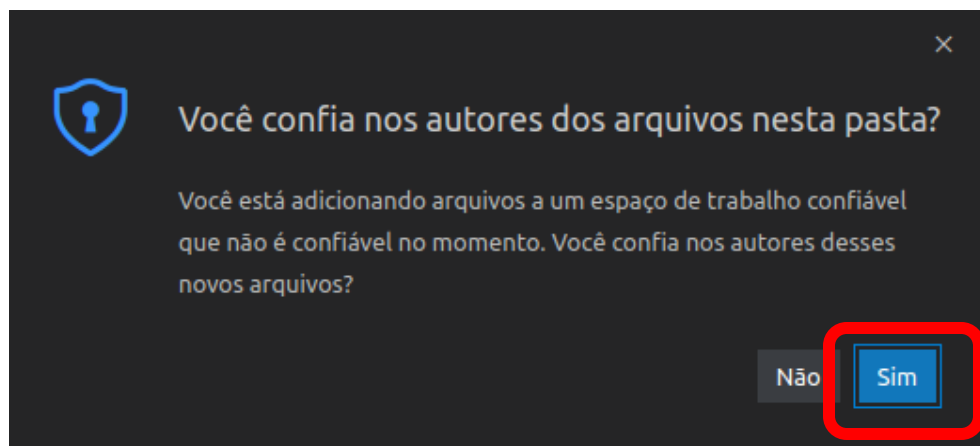
- Deve ser executado dentro de um diretório de "projeto", que contenha um arquivo "CMakeLists.txt"
- Para fazer o build do projeto `$ idf.py build` `$ idf.py all`
- Para gravar no ESP32 `$ idf.py flash` `-p /dev/ttyUSB0`
- Para estabelecer uma comunicação serial
 `$ idf.py monitor` `-p /dev/ttyUSB0`
- Para finalizar a comunicação serial `Ctrl +]`

Exemplo

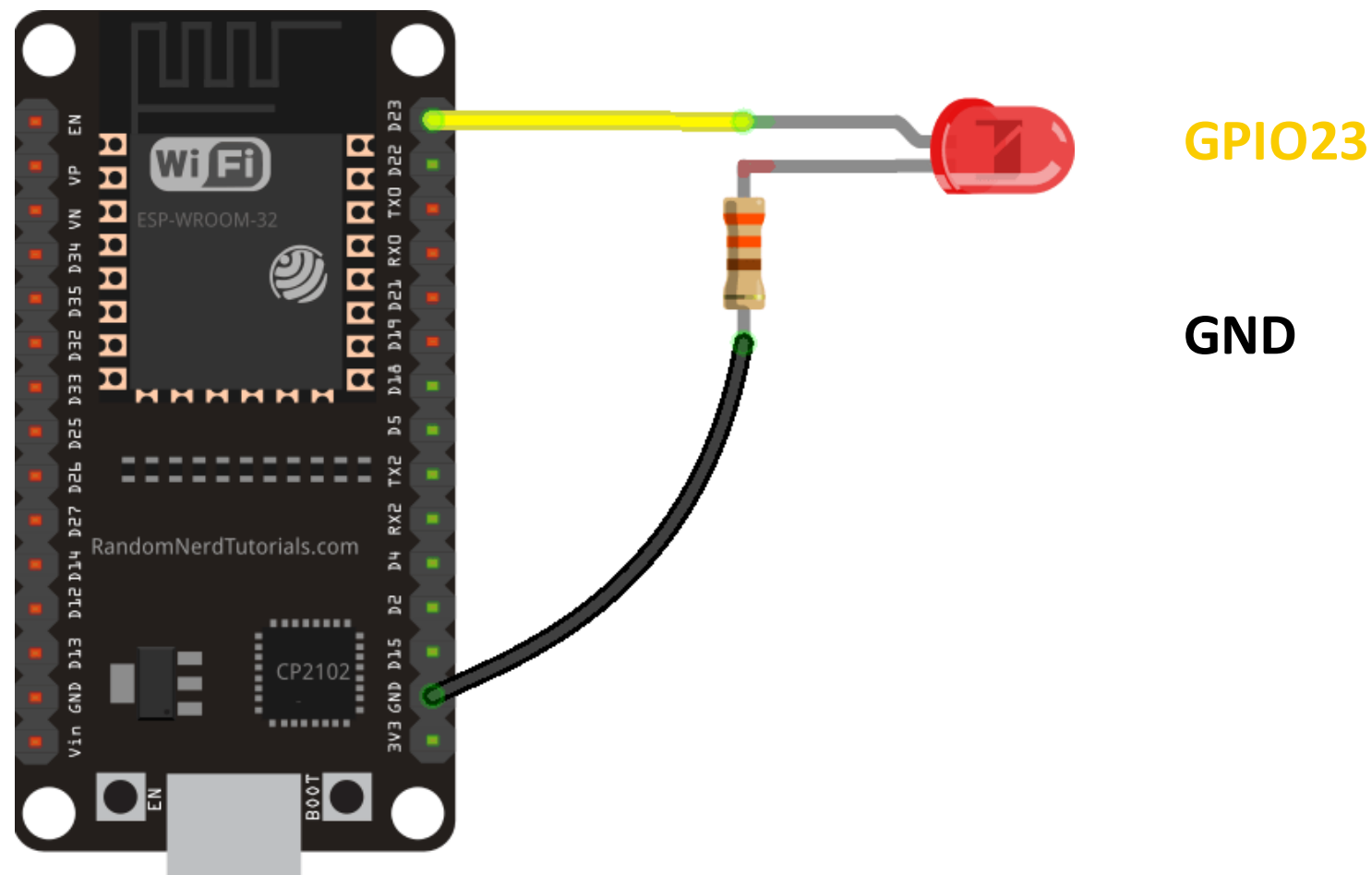
- Navegue até `/ESP32/esp-idf/examples/get-started/`
- Copie a pasta `blink` e `sample_project` para o `ESP32/myCodes/`
- Renomeie a pasta `sample_project` em `ESP32/myCodes/` para `Aula02`
- Navegue até `/ESP32/`
- Execute no terminal

```
$ dex edit.desktop
```

Avisos ao abrir o VSCode



Monte o circuito abaixo



No VSCode



- Abra um terminal para o projeto blink
- Digite
\$ idf.py menuconfig

idf.py menuconfig



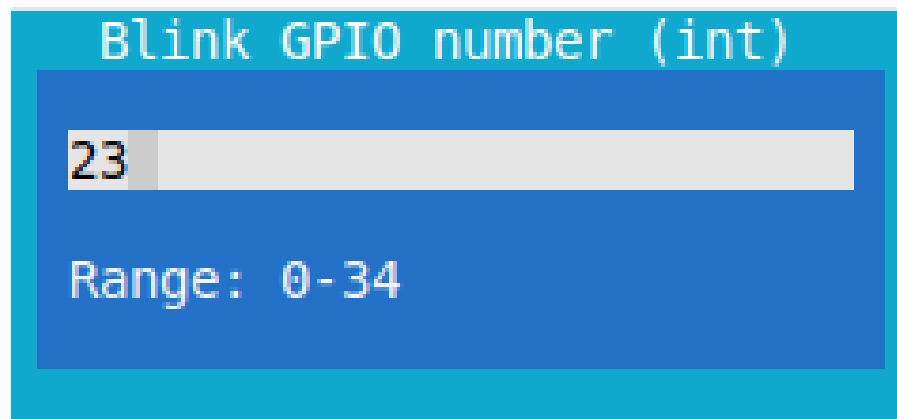
```
(Top)
Espressif IoT Development Framework Configuration
SDK tool configuration --->
Build type --->
Application manager --->
Bootloader config --->
Security features --->
Serial flasher config --->
Partition Table --->
Example Configuration --->
Compiler options --->
Component config --->
Compatibility options --->

[Space/Enter] Toggle/enter  [ESC] Leave menu          [S] Save
[O] Load                  [?] Symbol info          [/] Jump to symbol
[F] Toggle show-help mode  [C] Toggle show-name mode [A] Toggle show-all mode
[Q] Quit (prompts for save) [D] Save minimal config (advanced)
```


idf.py



- Navegue até Example Configuration / Blink GPIO number;
- Altere o número para 23;
- Tecle Enter;

A screenshot of a configuration interface. At the top, the text "Blink GPIO number (int)" is displayed in a light blue font on a dark blue background. Below this, there is a text input field with a light gray border and a light gray background. The number "23" is entered into this field. Below the input field, the text "Range: 0-34" is displayed in a light blue font on a dark blue background.

idf.py



- Tecle "S" para salvar. Uma nova janela irá aparecer

```
Filename to save configuration to
/home/dilson/Documentos/PadoLabs/ESP32/myCodes/blink/sdkconfig
(Relative to /home/dilson/Documentos/PadoLabs/ESP32/myCodes/blink/build/)
Refer to your home directory with ~
```

- Confirme com Enter;

```
Success
Configuration saved to '/home/dilson/Documentos/PadoLabs/ESP32/myCodes/blink/sdkco
```

- Tecle ESC até sair e retornar ao terminal;

No VSCode abra o projeto blink



- Execute no terminal do VSCode no projeto blink:

```
$ idf.py build
```

- Conecte o ESP32 ao USB do PC;
- Faça o upload e inicie a comunicação com o kit ESP32

```
$ idf.py flash monitor
```

Kconfig

- Setar configurações do projeto
- <https://docs.espressif.com/projects/esp-idf/en/latest/esp32/api-reference/kconfig.html>

menu "Example Configuration"

config BLINK_GPIO

int "Blink GPIO number"

range 0 34

default 5

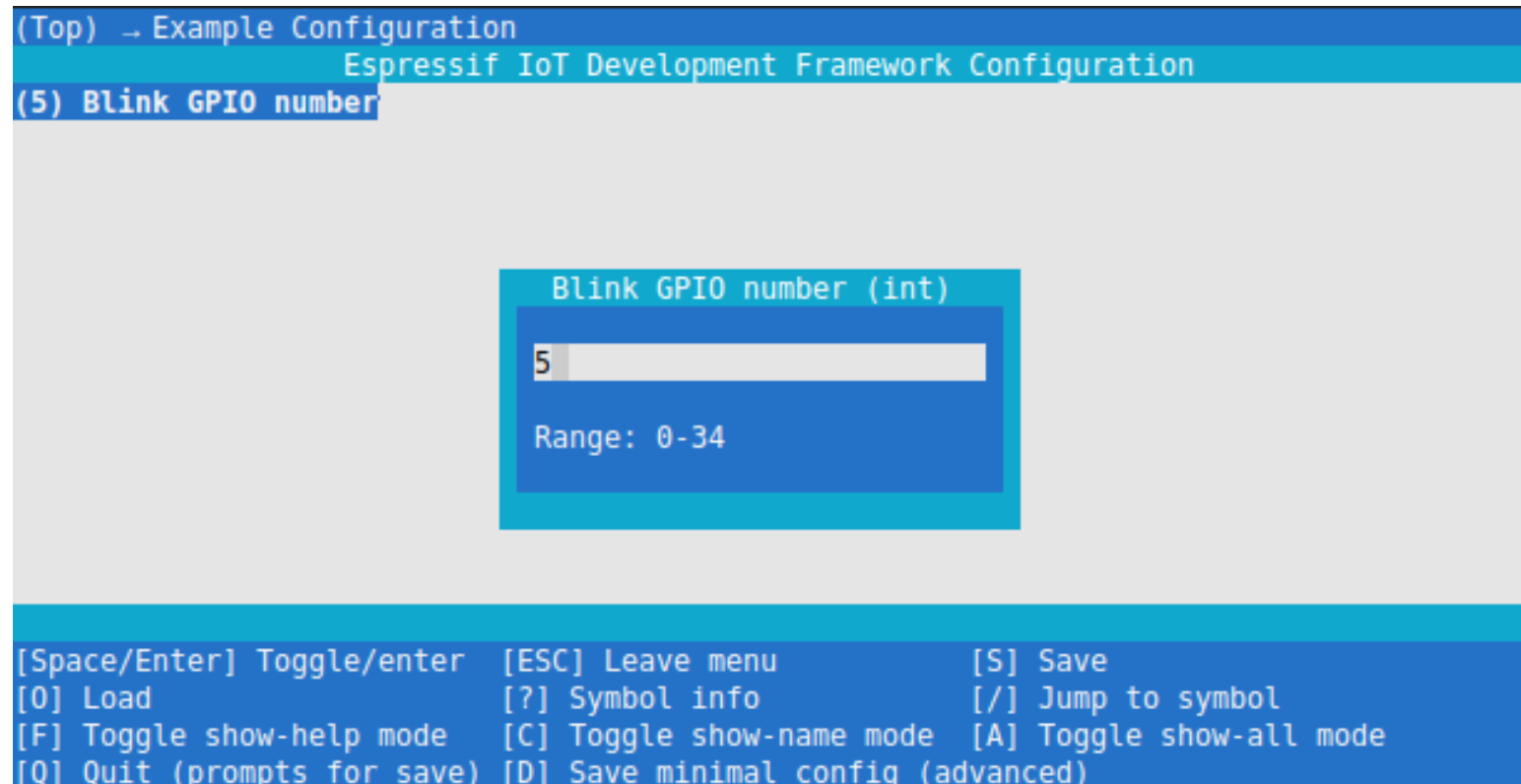
help

GPIO number (IOxx) to blink on and off.

Some GPIOs are used for other purposes
(flash connections, etc.) and cannot be
used to blink.

GPIOs 35-39 are input-only so cannot
be used as outputs.

endmenu



Kconfig (cont.)

menu "Example Configuration"

config BLINK_GPIO

int "Blink GPIO number"

range 0 34

default 5

help

GPIO number (IOxx) to blink on and off.

Some GPIOs are used for other purposes
(flash connections, etc.) and cannot be
used to blink.

GPIOs 35-39 are input-only so cannot
be used as outputs.

endmenu

```
Symbol information
Name: BLINK_GPIO
Prompt: Blink GPIO number
Type: int
Value: 5
Help:
    GPIO number (IOxx) to blink on and off.
    Some GPIOs are used for other purposes (flash connections, etc.) and cannot be used t
    GPIOs 35-39 are input-only so cannot be used as outputs.
Default:
    - 5
Kconfig definition, with parent deps. propagated to 'depends on'
=====
|||||
[ESC/q] Return to menu    [/] Jump to symbol
```

.clang-format

- Aplica uma formatação em todo o código
- Ctrl + Shift + I

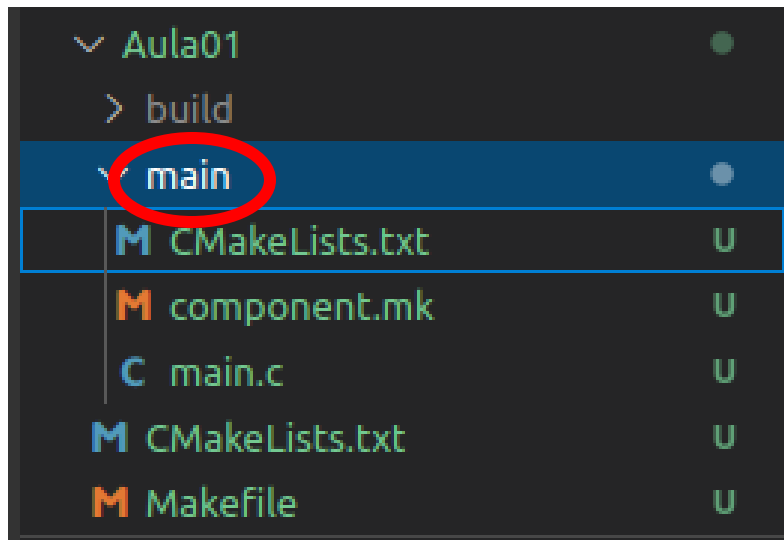
```
{  
  BasedOnStyle: LLVM,  
  IndentWidth: 4,  
  TabWidth: 4,  
  UseTab: Never,  
  BreakBeforeBraces: Allman,  
  AllowShortIfStatementsOnASingleLine: false,  
  AllowShortFunctionsOnASingleLine: false,  
  AllowShortBlocksOnASingleLine: true,  
  IndentCaseLabels: false,  
  ColumnLimit: 80,  
  AccessModifierOffset: -4,  
  SortIncludes: false,  
}
```

Estrutura de um projeto

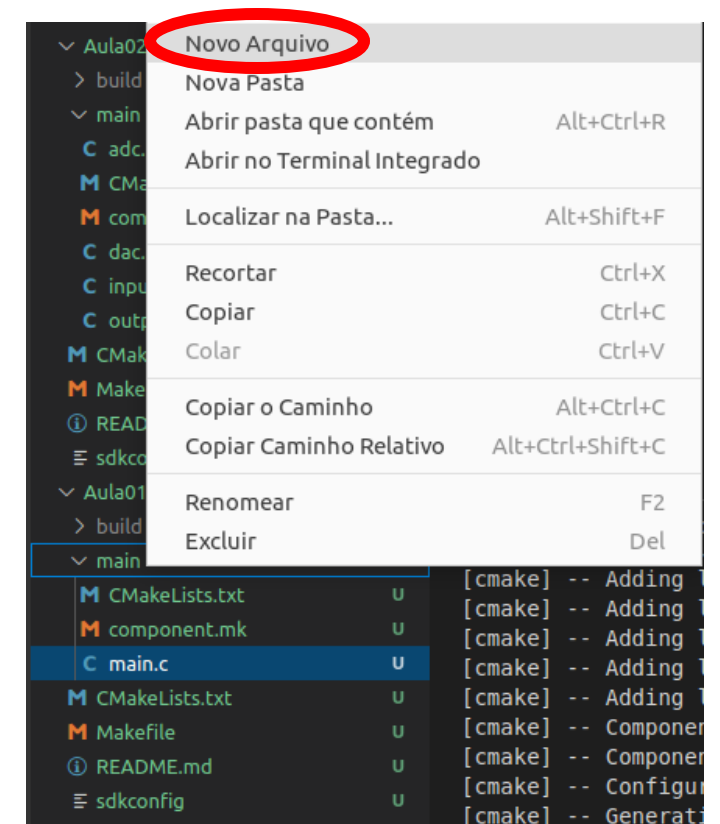
- Dois arquivos CMakeLists.txt
 - Um dentro do diretório raiz do projeto
 - Outro dentro dos arquivos de código ("main")
- Pasta build
 - Nomedoprojeto.bin
- Pasta dos arquivos de código ("main")
- Arquivo sdkconfig
- Arquivo KConfig
- Arquivos mk / Makefile

Hello World

- Clique com o botão direito sobre "main"

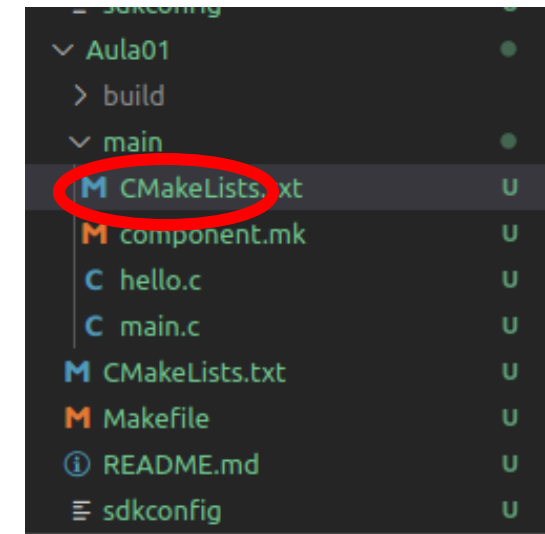
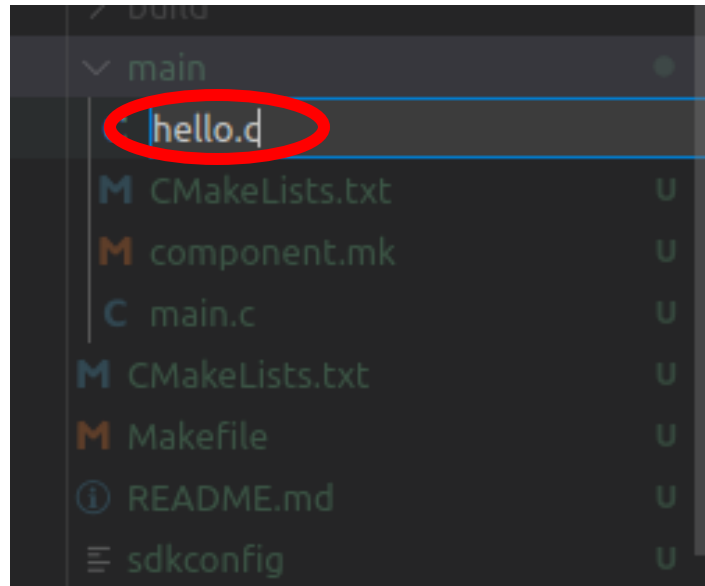


- No menu que surge, clique em Novo Arquivo

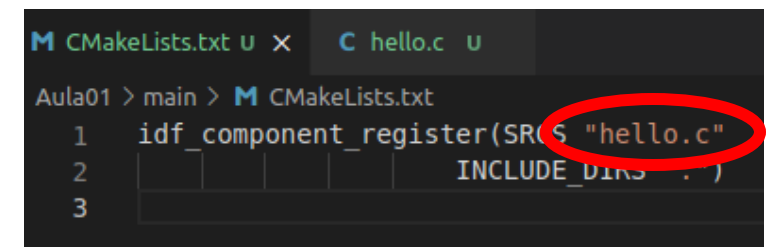


Hello World (cont.)

- Digite hello.c como nome do arquivo



- Edite o arquivo CMakeLists.txt de dentro do diretório "main"



hello.c

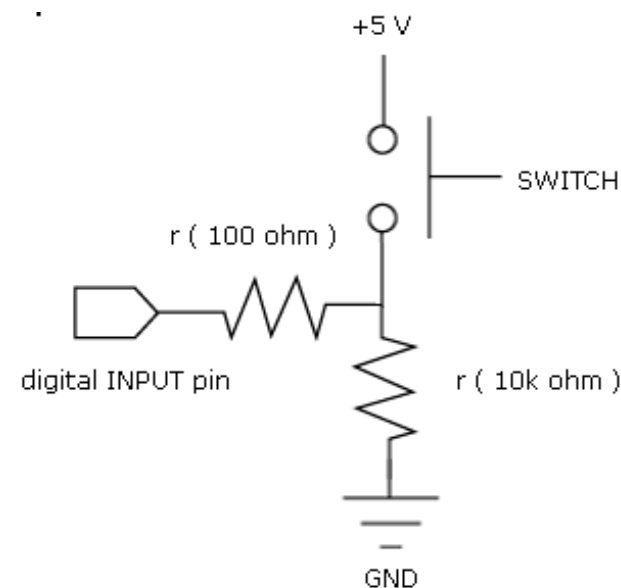
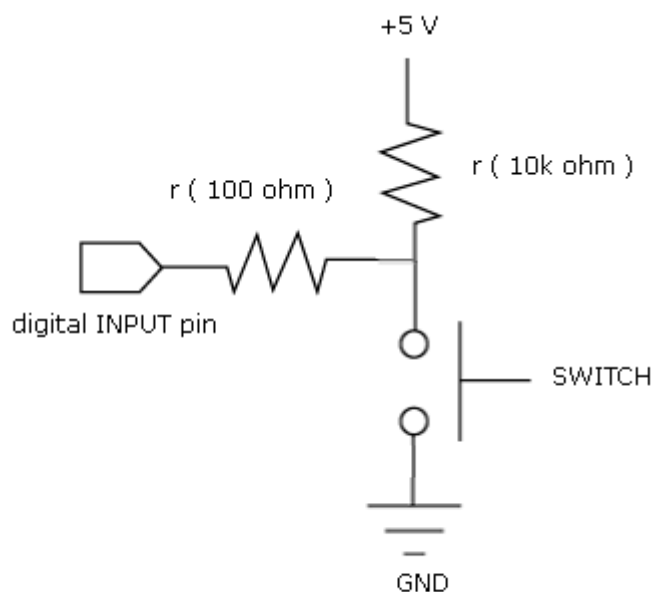


```
#include <stdio.h>
#include "esp_log.h"
void app_main(void)
{
    printf("Hello World\n");
    ESP_LOGI("hello.c", "hello world!");
}
```

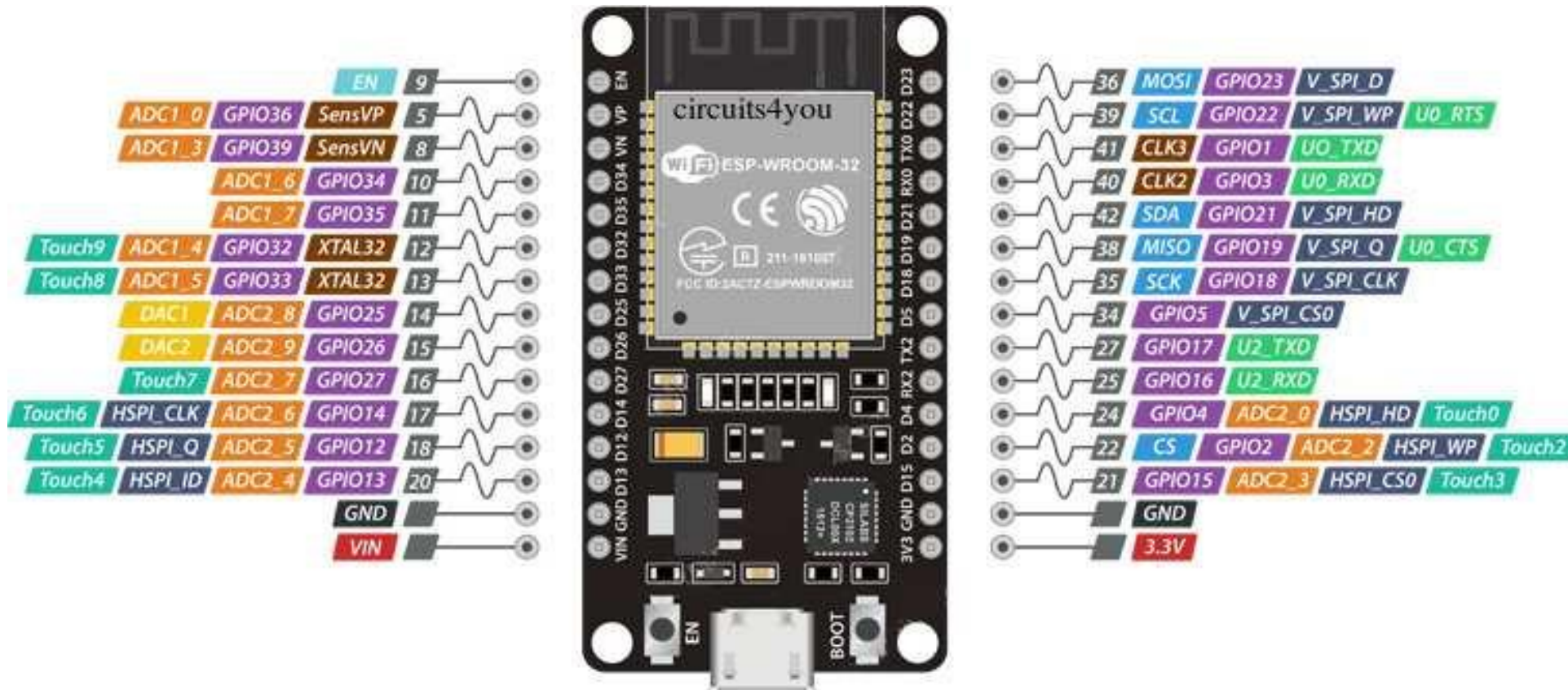
GPIO



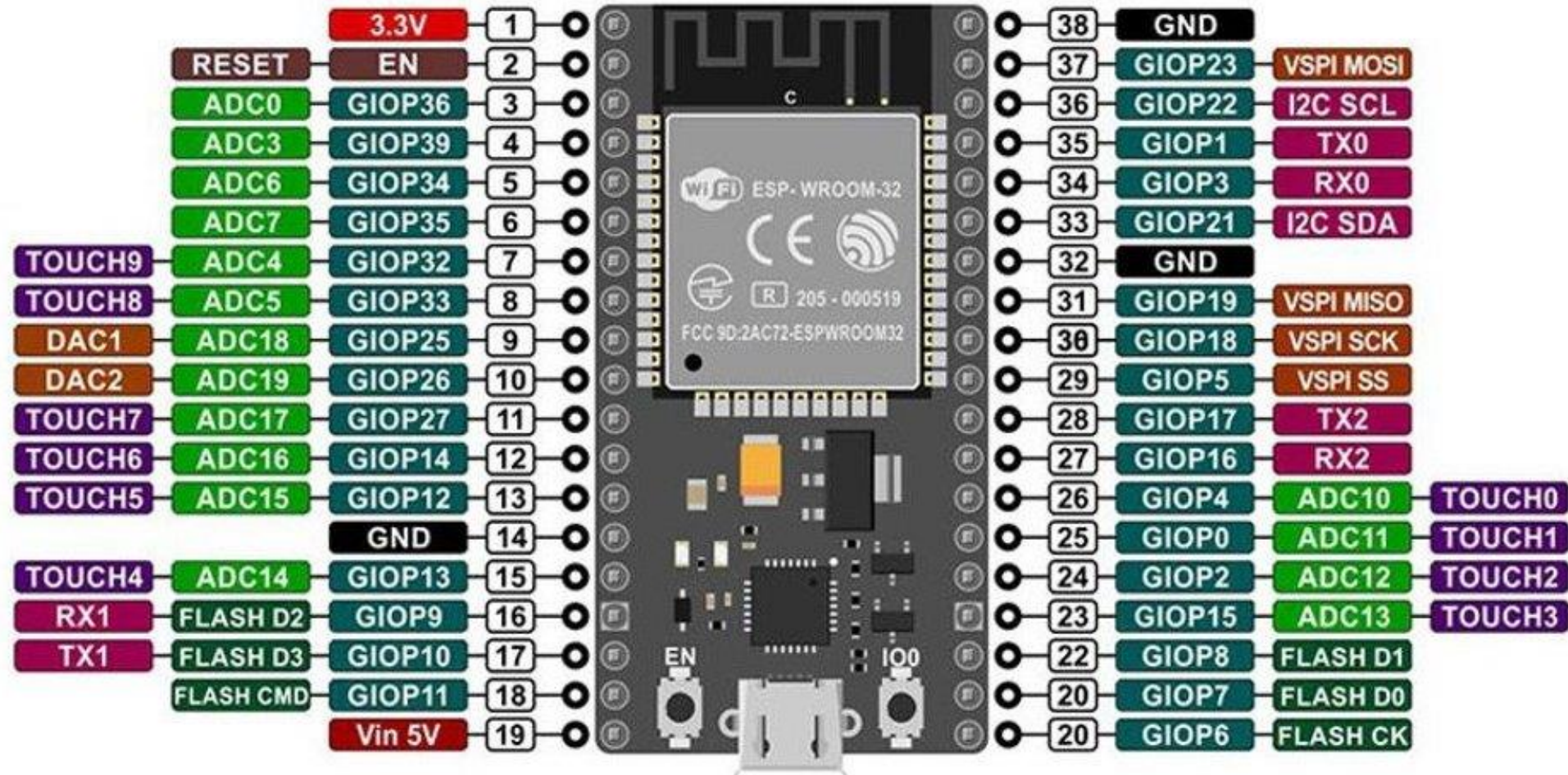
- General Purpose Input Output
- Entrada e saída
- Meio por onde o chip se comunica com o mundo externo
- Pull-up, pull-down;



Kit 30 pinos

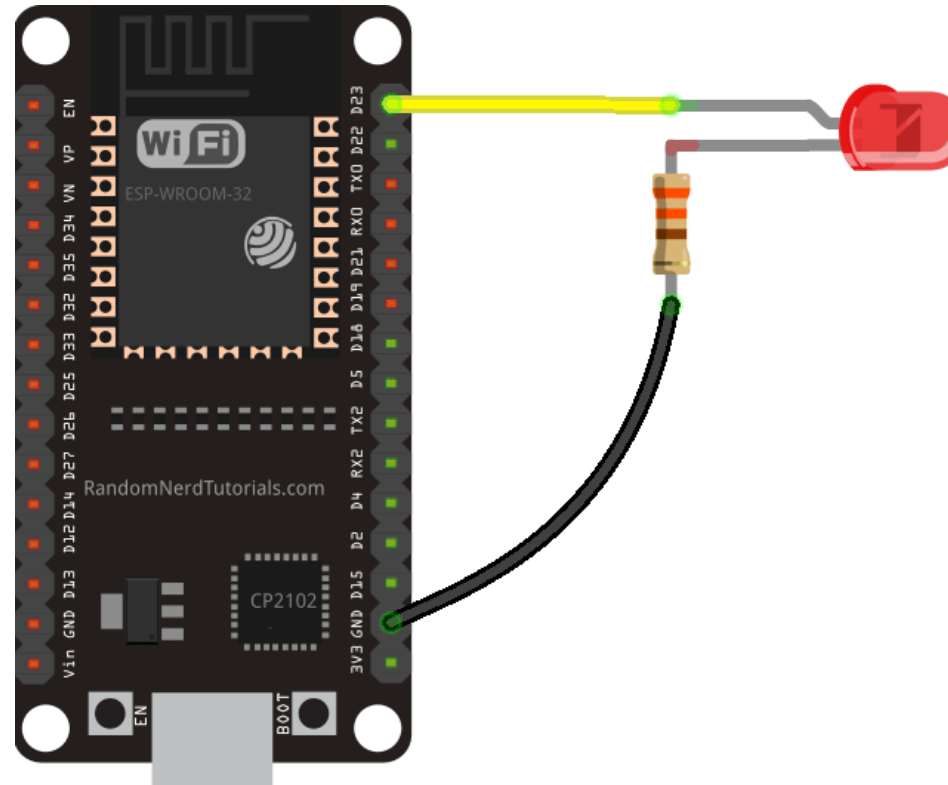


Kit 38 pinos



Pino como saída

- Não exceder 20mA por pino!

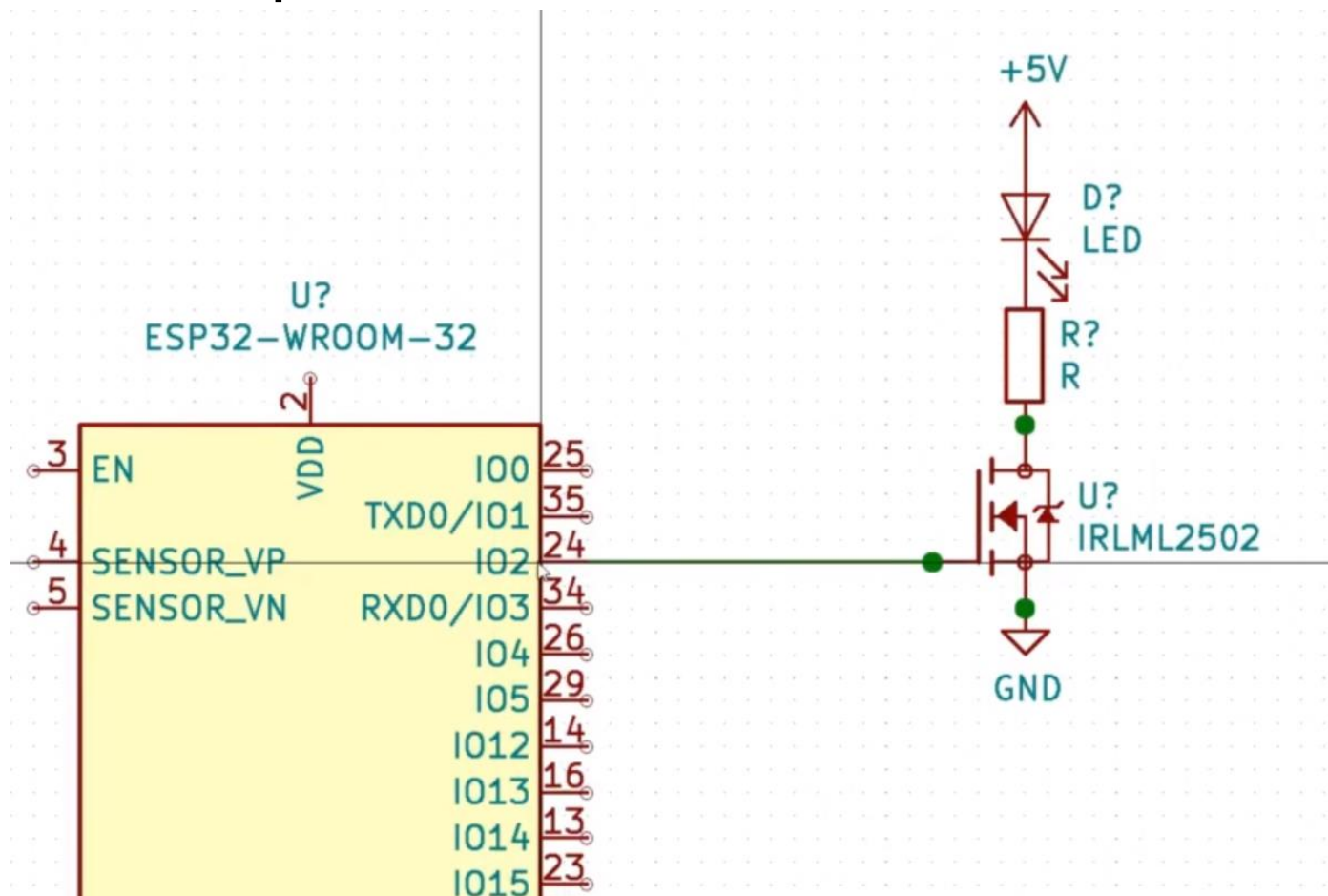


GPIO23

GND

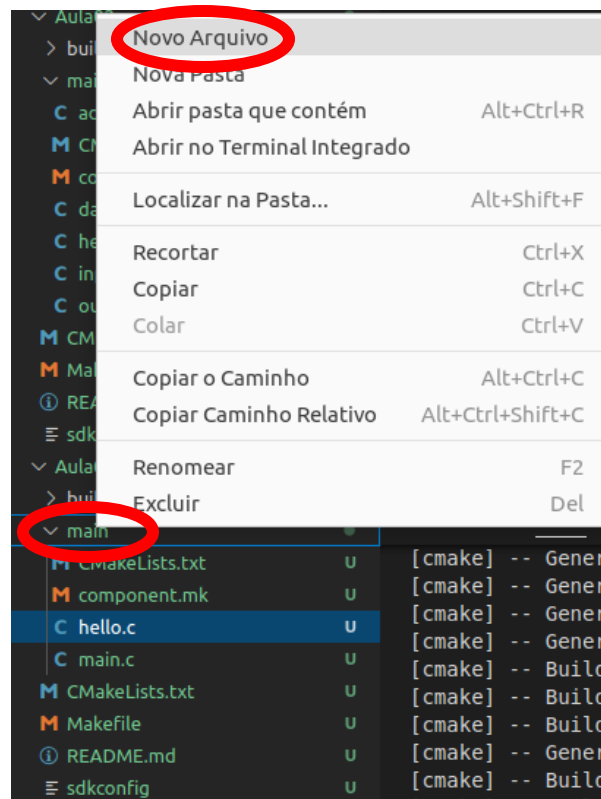
Pino como saída

- Como fazer para lidar com correntes maiores?



Criando arquivo output.c

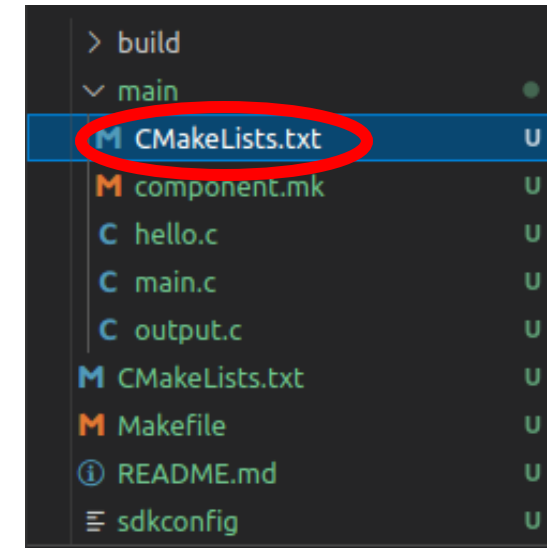
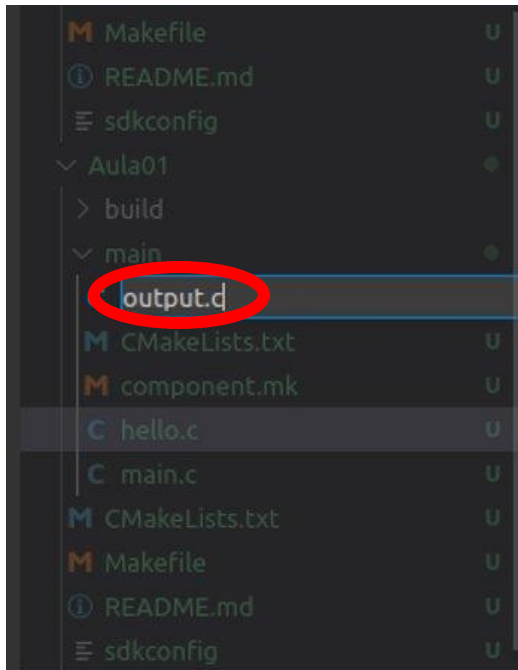
- Clique com o botão direito sobre "main"
- No menu que surge, clique em Novo Arquivo



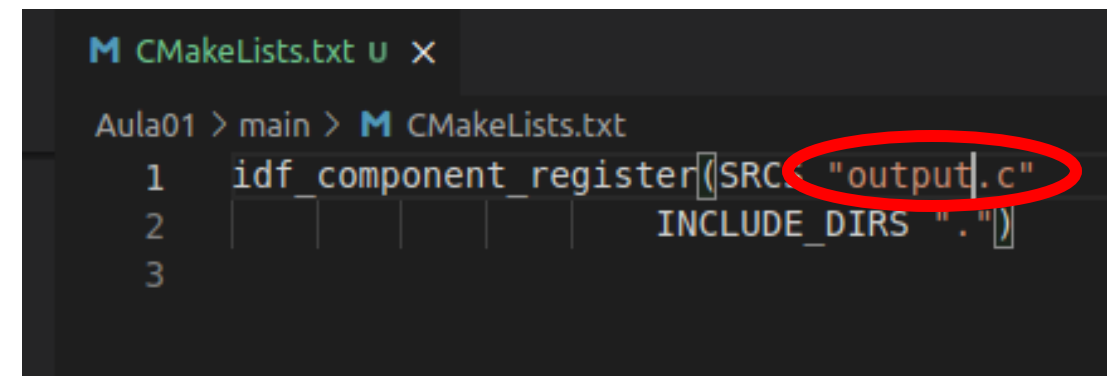
Criando arquivo output.c (cont.)



- Digite output.c como nome do arquivo



- Edite o arquivo CMakeLists.txt de dentro do diretório "main"



app_main template



```
#include <stdio.h>
#include "freertos/FreeRTOS.h"
#include "freertos/task.h"
#include "esp_log.h"

const char *TAG = "arquivo.c";

void app_main(void)
{
    ESP_LOGI(TAG, "Starting!");
}
```

output.c (cont.)



```
#include <stdio.h>
#include "freertos/FreeRTOS.h"
#include "freertos/task.h"
#include "driver/gpio.h"
#include "esp_log.h"

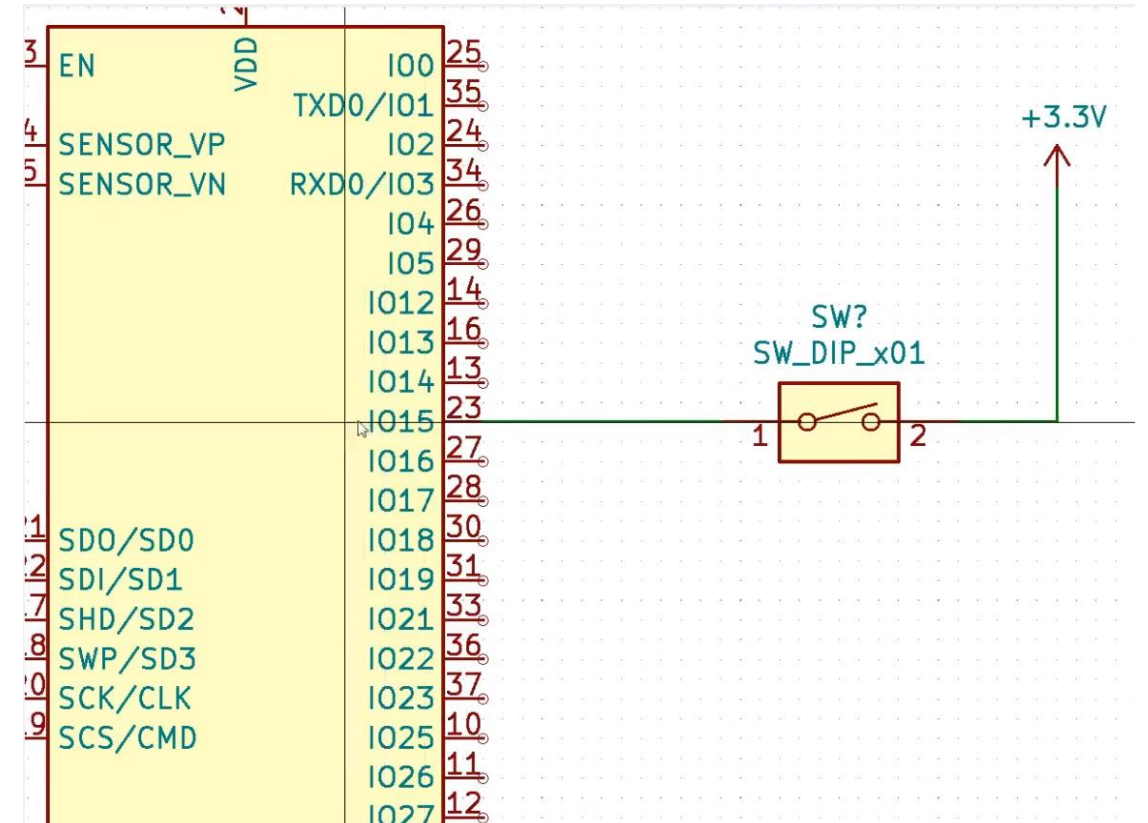
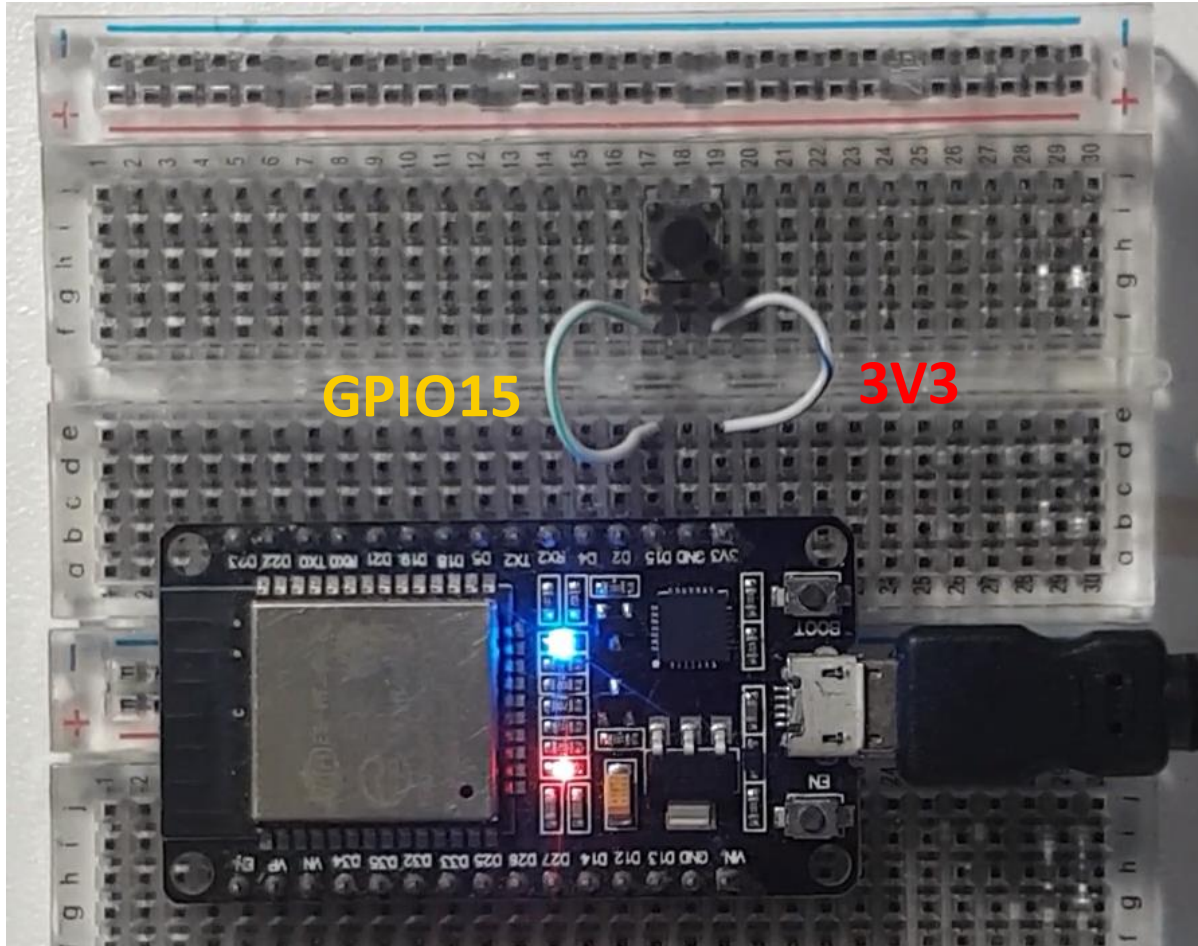
#define PIN_LED 2
const char *TAG = "output.c";
```

```
void app_main(void)
{
    printf("Blink LED\n");
    ESP_LOGI(TAG, "Starting!");

    gpio_pad_select_gpio(PIN_LED);
    gpio_set_direction(PIN_LED, GPIO_MODE_OUTPUT);

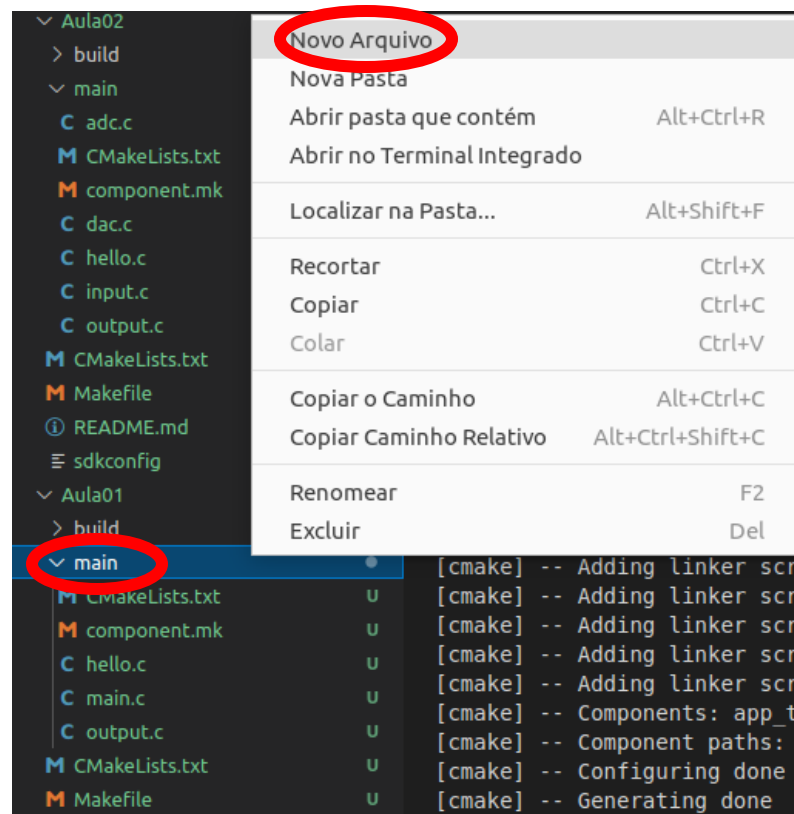
    bool isOn = 0;
    while (true)
    {
        isOn = !isOn;
        gpio_set_level(PIN_LED, isOn);
        vTaskDelay(pdMS_TO_TICKS(1000));
    }
}
```

Pino como entrada



Criando arquivo input.c

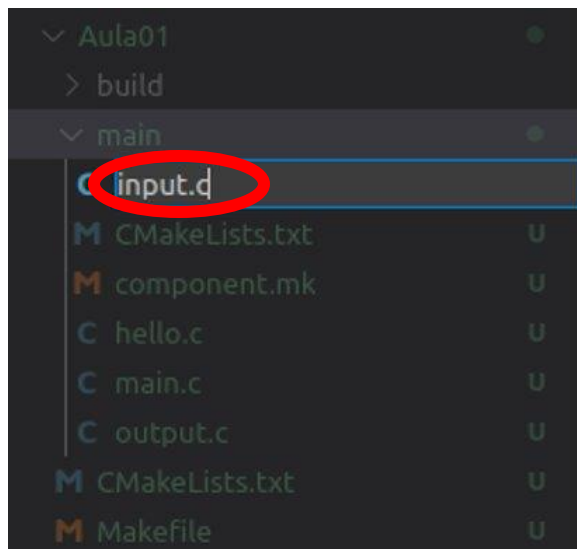
- Clique com o botão direito sobre "main"
- No menu que surge, clique em Novo Arquivo



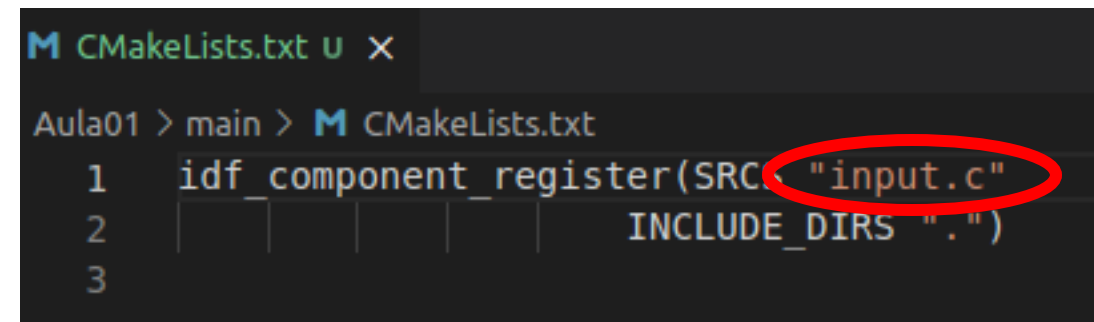
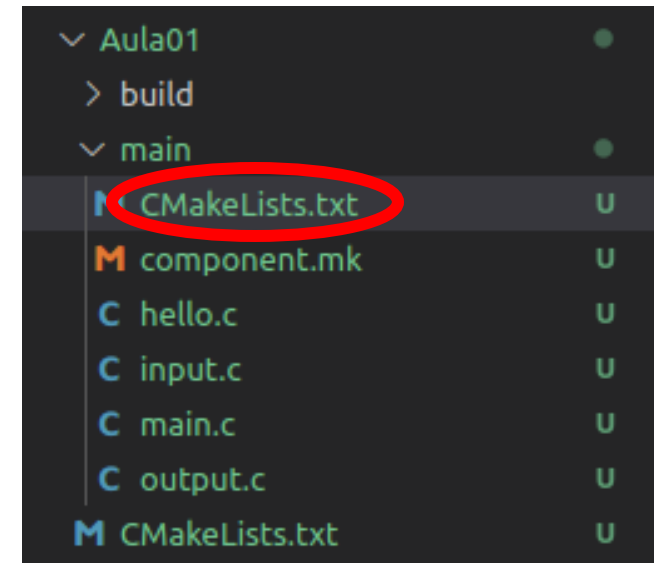
Criando arquivo input.c (cont.)



- Digite output.c como nome do arquivo



- Edite o arquivo CMakeLists.txt de dentro do diretório "main"



input.c



```
#include <stdio.h>
#include "freertos/FreeRTOS.h"
#include "freertos/task.h"
#include "driver/gpio.h"
#include "esp_log.h"

#define PIN_SWITCH 15
#define PIN_LED 2

const char *TAG = "input.c";
```

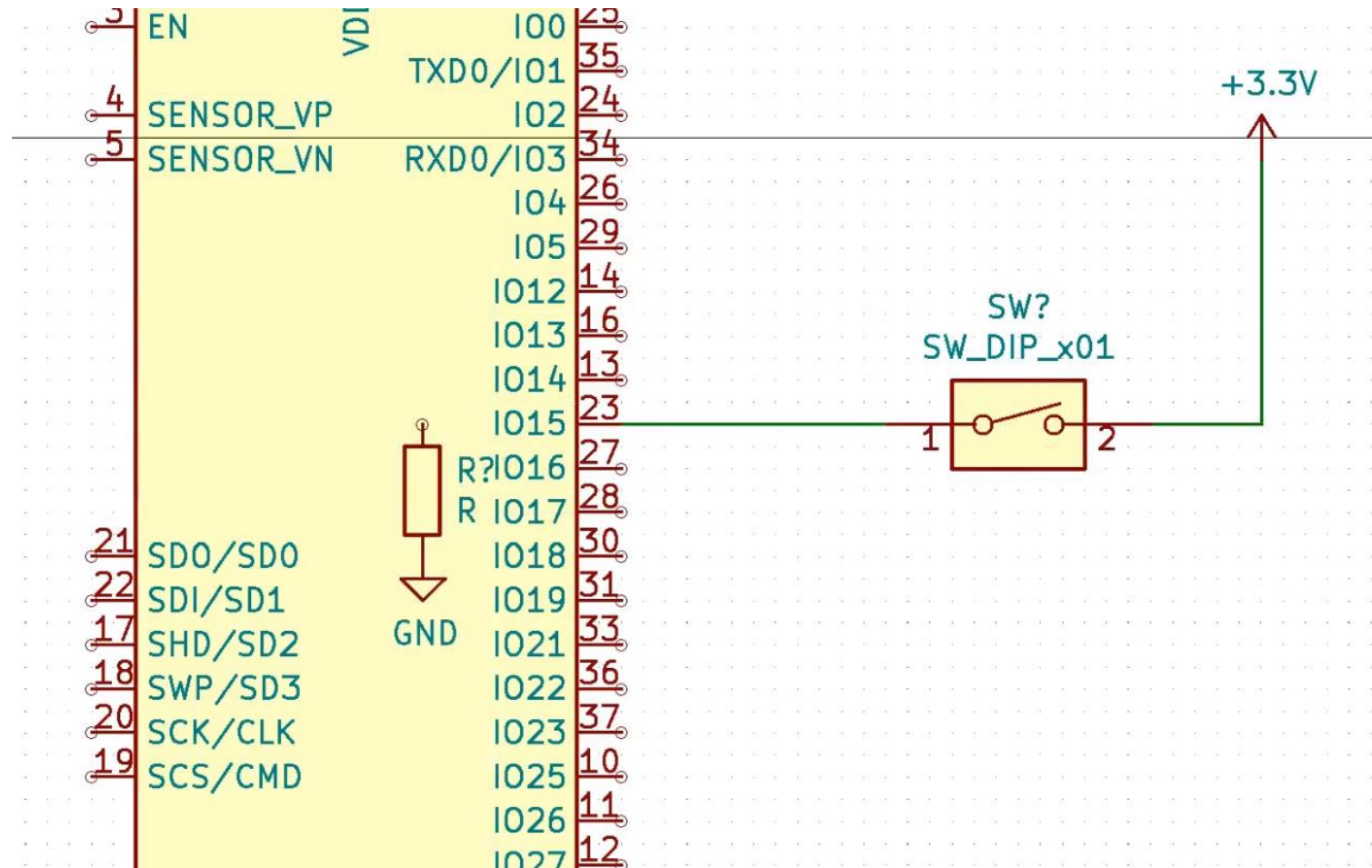
```
void app_main(void)
{
    printf("Switch and LED\n");
    ESP_LOGI(TAG, "Starting!");

    gpio_pad_select_gpio(PIN_LED);
    gpio_set_direction(PIN_LED, GPIO_MODE_OUTPUT);

    gpio_pad_select_gpio(PIN_SWITCH);
    gpio_set_direction(PIN_SWITCH, GPIO_MODE_INPUT);

    while (true)
    {
        int level = gpio_get_level(PIN_SWITCH);
        gpio_set_level(PIN_LED, level);
        vTaskDelay(1);
    }
}
```


Pull Down interno



Pull-down enable

```
#include <stdio.h>
#include "freertos/FreeRTOS.h"
#include "freertos/task.h"
#include "driver/gpio.h"
#include "esp_log.h"

#define PIN_SWITCH 15
#define PIN_LED 2

const char *TAG = "input.c";
```

```
void app_main(void)
{
    printf("Switch and LED\n");
    ESP_LOGI(TAG, "Starting!");

    gpio_pad_select_gpio(PIN_LED);
    gpio_set_direction(PIN_LED, GPIO_MODE_OUTPUT);
    gpio_pad_select_gpio(PIN_SWITCH);
    gpio_set_direction(PIN_SWITCH, GPIO_MODE_INPUT);

    gpio_pullup_en(PIN_SWITCH);
    gpio_pullup_dis(PIN_SWITCH);

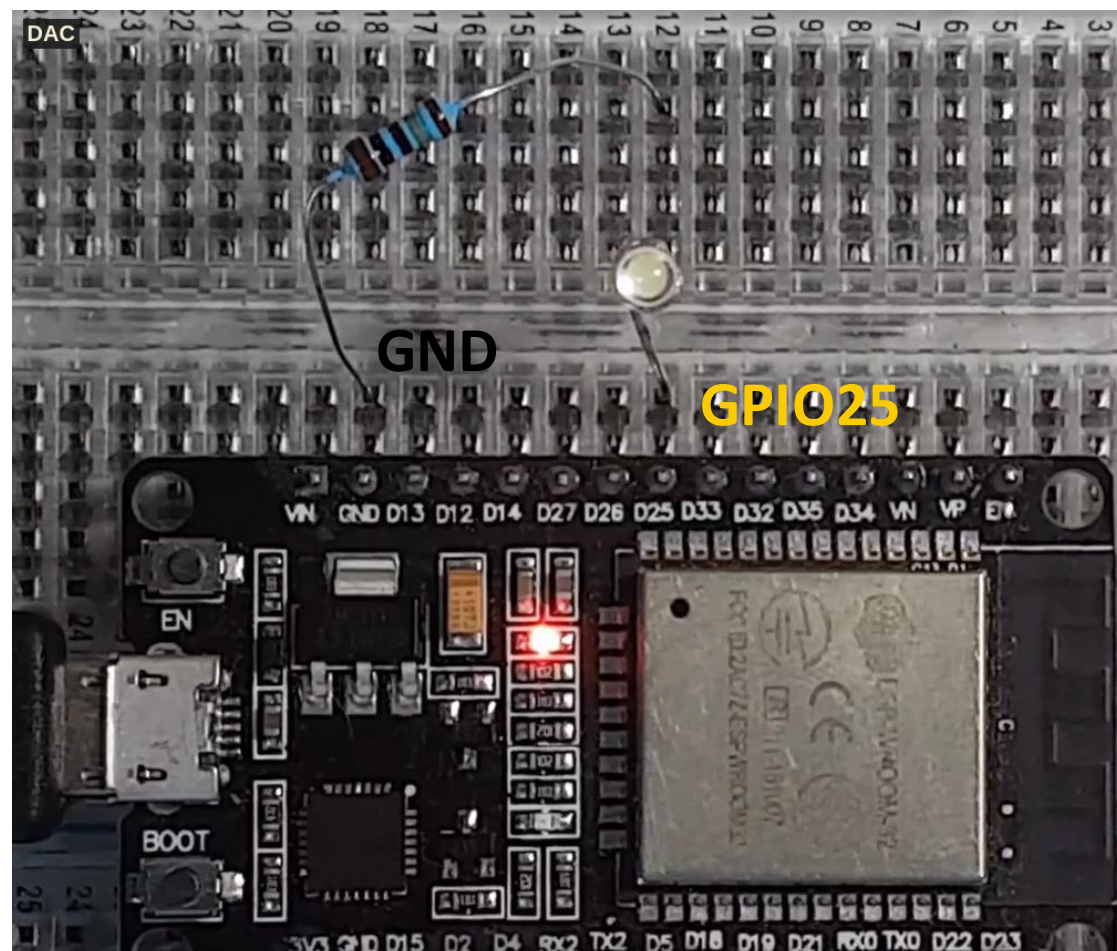
    while (true)
    {
        int level = gpio_get_level(PIN_SWITCH);
        gpio_set_level(PIN_LED, level);
        vTaskDelay(1);
    }
}
```

DAC



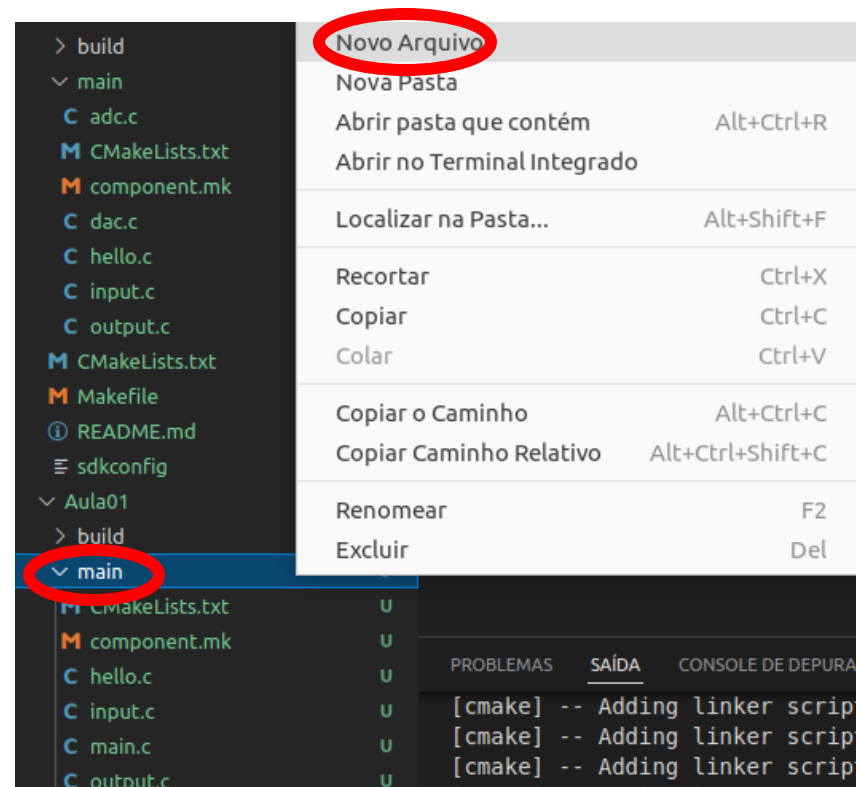
- Digital to Analog Converter;
- 2 canais: GPIO25 (canal 1) e GPIO26 (canal 2);
- Permite alterar os níveis de tensão em um pino;

Montagem DAC



Criando arquivo dac.c

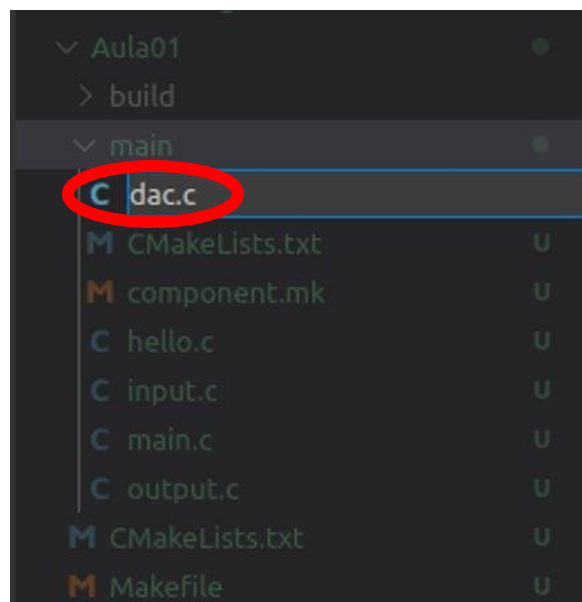
- Clique com o botão direito sobre "main"
- No menu que surge, clique em Novo Arquivo



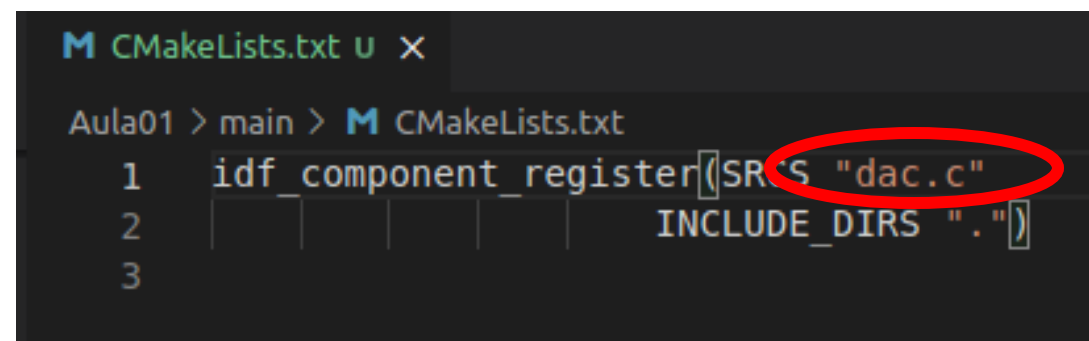
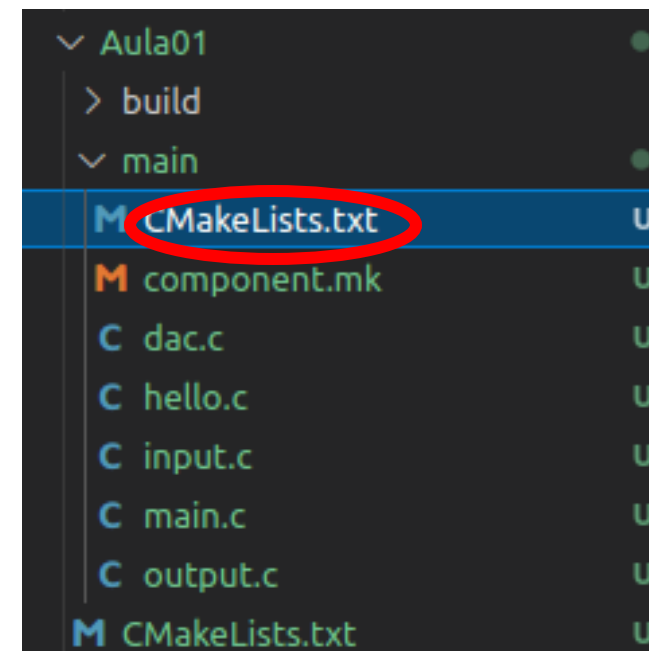
Criando arquivo dac.c (cont.)



- Digite output.c como nome do arquivo



- Edite o arquivo CMakeLists.txt de dentro do diretório "main"



Código DAC



```
#include <stdio.h>
#include "freertos/FreeRTOS.h"
#include "freertos/task.h"
#include "driver/gpio.h"
#include "driver/dac.h"

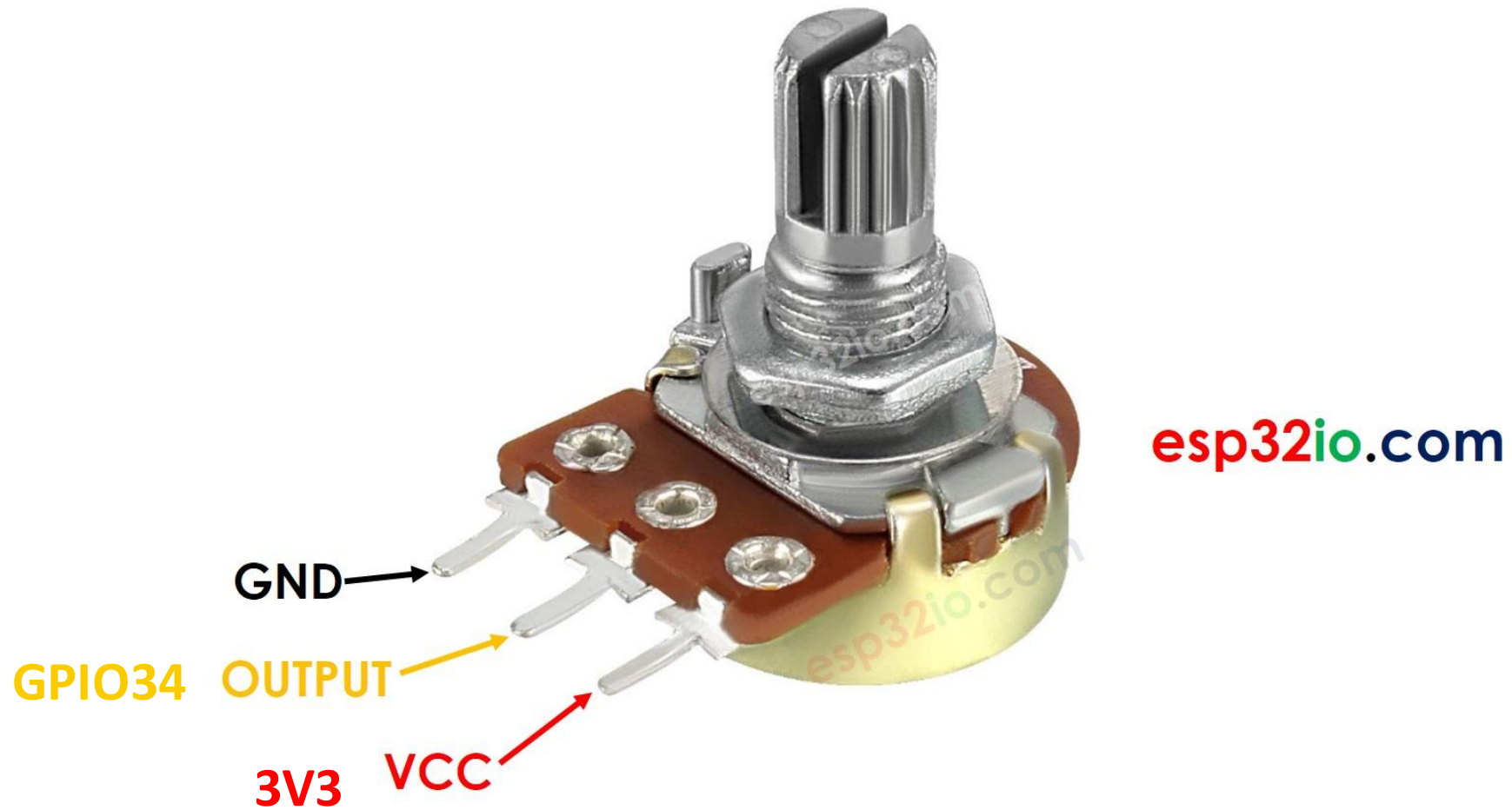
void app_main()
{
    dac_output_enable(DAC_CHANNEL_1);
    dac_output_voltage(DAC_CHANNEL_1, 255);
}
```

ADC



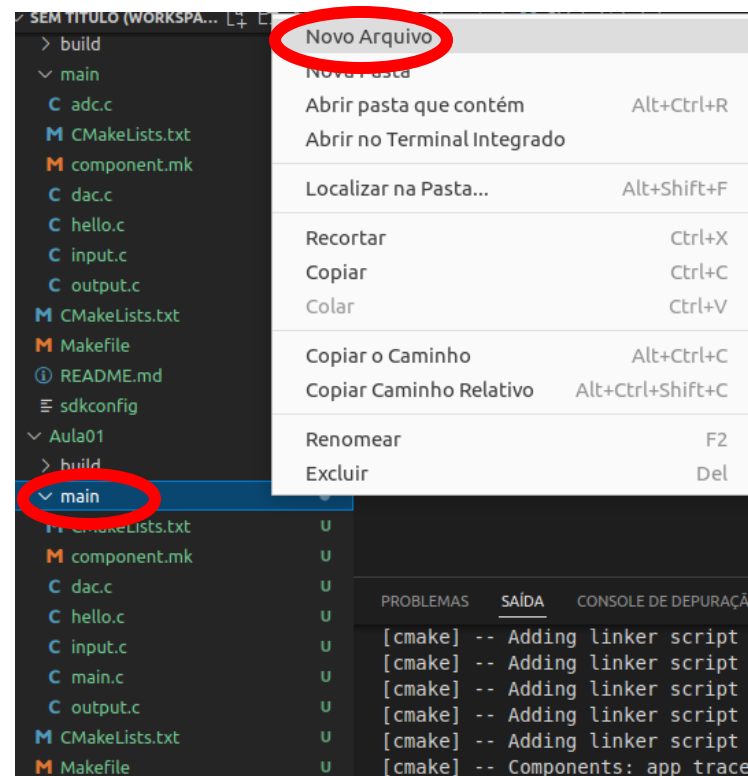
- Analog to Digital Converter;
- **ADC1:** 8 canais: GPIO32 - GPIO39
- **ADC2:** 10 canais: GPIO0, GPIO2, GPIO4, GPIO12 - GPIO15, GPIO25 – GPIO27
- Faz leituras de tensão nos pinos;
- [ESP32 DevKitC](#): GPIO 0 não pode ser utilizado devido a circuitos externos de auto programação;
- ADC2 é também utilizado pelo Wi-Fi,

ADC Montagem:



Criando arquivo adc.c

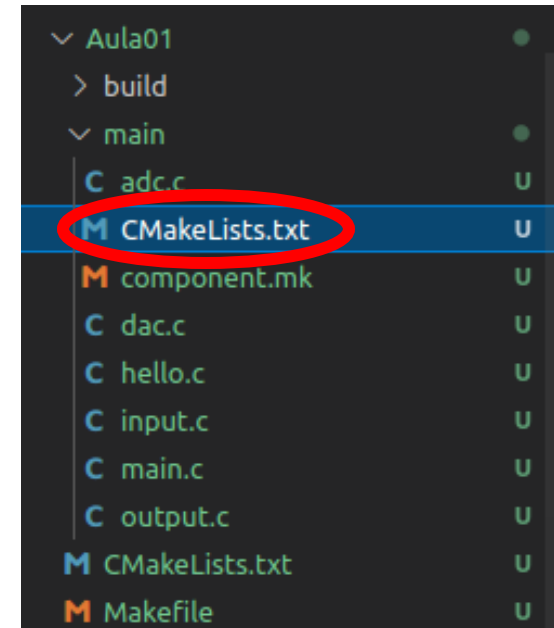
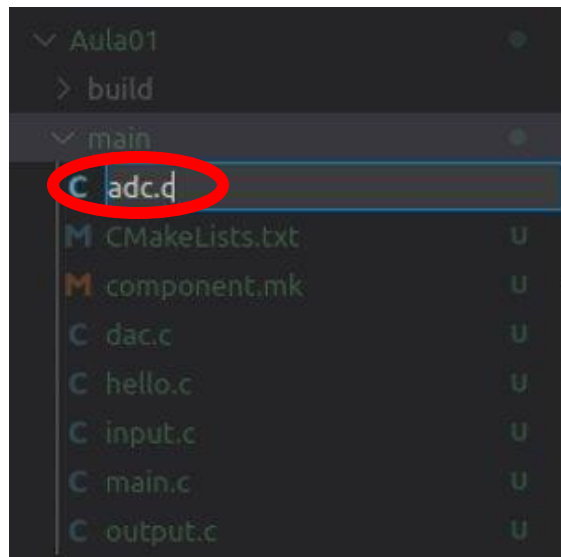
- Clique com o botão direito sobre "main"
- No menu que surge, clique em Novo Arquivo



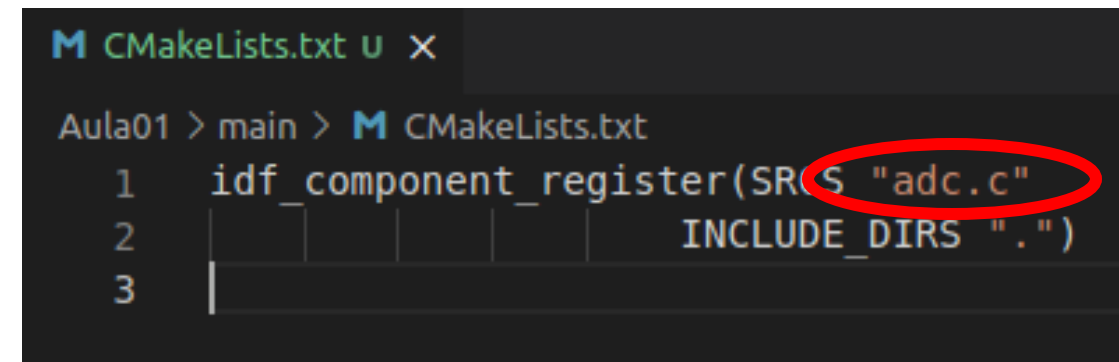
Criando arquivo adc.c (cont.)



- Digite adc.c como nome do arquivo



- Edite o arquivo CMakeLists.txt de dentro do diretório "main"



ADC: Código



```
#include <stdio.h>
#include "freertos/FreeRTOS.h"
#include "freertos/task.h"
#include "driver/adc.h"

void app_main()
{
    adc1_config_width(ADC_WIDTH_12Bit);
    adc1_config_channel_atten(ADC1_CHANNEL_6, ADC_ATTEN_11db);

    while(1)
    {
        int val = adc1_get_raw(ADC1_CHANNEL_6);
        printf("value is %d\n", val);
        vTaskDelay(pdMS_TO_TICKS(1000));
    }
}
```

Exercícios



1. Faça um programa que ao manter o botão pressionado o LED pisca em uma frequência de 10 Hz e quando solto em 2 Hz
2. Faça um programa que ao pressionar o botão o led pisca e pressionar novamente o led fica ligado

Exercícios (cont.)

3. Faça um programa que a medida que o botão é pressionado aumente a intensidade do LED ao atingir o valor máximo volte a zero. Adicione 5 passos.
4. O ESP32 possui um sensor hall integrado. Descubra como fazer leituras dele e apresente os dados a cada 500ms

Exercícios (cont.)

5. Faça um monitor de bateria de Li Íon.

- Crie um circuito com um potenciômetro que simule os valores da bateria: 2,8V a 4,2V.
- Com o ESP32 faça a leitura desses valores e acenda os leds de acordo com a tabela

LED Ligado	Faixa de Tensão
Verde	4,2V à 3,75V
Amarelo	3,75 à 3,4V
Vermelho	3,4 à 2,8V

Recomendados

- Kolban's Book on ESP32
 - <https://leanpub.com/kolban-ESP32>
- Andreas Spiess
 - <https://www.youtube.com/playlist?list=PL3XBzmAj53RnZPeWe799F-uoXERBldhn9>
- Projetos com ESP32
 - <https://hackaday.com/tag/ESP32/>
 - <https://www.hackster.io/search?i=projects&q=ESP32>
 - <https://www.instructables.com/howto/ESP32/>

