

$$J(x_0, 0) = \min_{\substack{u_j \in U_j \\ j=0,1,\dots,N-1}} \mathbb{E} \left[ \sum_{j=0}^{N-1} \{L(x_j, u_j, j)\} + G(x_N, N) \right] \quad (1)$$

*s.t.*

$$x_{k+1} = f(x_j, u_j, j) + \sigma_{j+1} \xi_{j+1}$$

$$j = 0, 1, \dots, N-1$$

$$J(x_N, N) = G(x_N, N) \quad (2)$$

$$J(x_k, k) = \min_{u_k \in U_k} \mathbb{E} [J(x_{k+1}, k+1) + L(x_k, u_k, k)] \quad (3)$$

$$\bar{x}_{k+1} = f(\bar{x}_k, \bar{u}_k, k) \quad (4)$$

$$\bar{x}_0 = x_0$$

$$f(x_k, u_k, k) = f(\bar{x}_k, \bar{u}_k, k) + f_x \delta x_k + f_u \delta u_k \quad (5)$$

$$+ \frac{1}{2} f_{xx} (\delta x_k)^2 + \frac{1}{2} f_{uu} (\delta u_k)^2$$

where

$$\delta x_k = x_k - \bar{x}_k$$

$$\delta u_k = u_k - \bar{u}_k$$

$$\delta x_{k+1} = f(x_k, u_k, k) + \sigma_{k+1} \xi_{k+1} - f(\bar{x}_k, \bar{u}_k, k)$$

or,  $\delta x_{k+1} = f_x \delta x_k + f_u \delta u_k + \frac{1}{2} f_{xu} (\delta x_k) (\delta u_k) \quad (6)$

$$+ \frac{1}{2} f_{xx} (\delta x_k)^2 + \frac{1}{2} f_{uu} (\delta u_k)^2 + \sigma_{k+1} \xi_{k+1}$$

Similarly,

$$L(x_k, u_k, k) = L(\bar{x}_k, \bar{u}_k, k) + L_x \delta x_k + L_u \delta u_k$$

$$+ \frac{1}{2} L_{xx} (\delta x_k)^2 + \frac{1}{2} L_{uu} (\delta u_k)^2 \quad (7)$$

and,

$$J(x_k, k) = J(\bar{x}_k, k) + \delta x + \frac{1}{2} J_{xx} (\delta x_{k+1})^2 \quad (8)$$