MULTI-PERIOD OPTIMAL POWER FLOW

Ву

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То	the	Faculty	of	Washington	State	University	:

The members of the Committee appointed to examine the dissertation of ARYAN RIT-WAJEET JHA find it satisfactory and recommend that it be accepted.

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MULTI-PERIOD OPTIMAL POWER FLOW

Abstract

by Aryan Ritwajeet Jha, Ph.D. Washington State University May 2023

: Anamika Dubey

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Dedication

Chapter One

SOME FORMATTING EXAMPLES

1.1 Chapter one tittle section

TBA

1.1.1 Another subsection of section - citations

Example of citation altschul1997gapped. TBA

Example of multiple citations altschul1997gapped; baker2007novel.TBA.

Subsubsection of section - italic text

TBA.

Chapter Two

LINKS

2.1 Chapter one tittle section - links examples

TBA.

- 2.1.1 Subsection title more links examples
- . Another example of hyperlink Wikibooks home.

Chapter Three

FIGURES AND TABLES

3.1 Examples of a figure

Example of a figure.

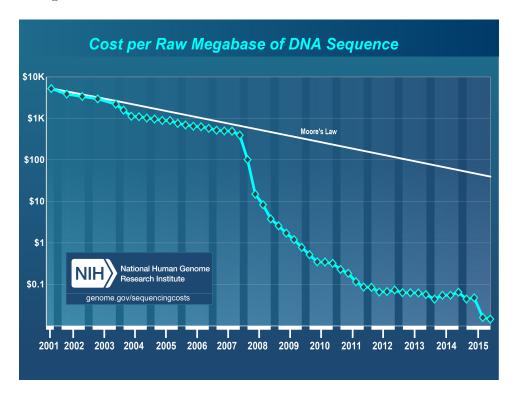
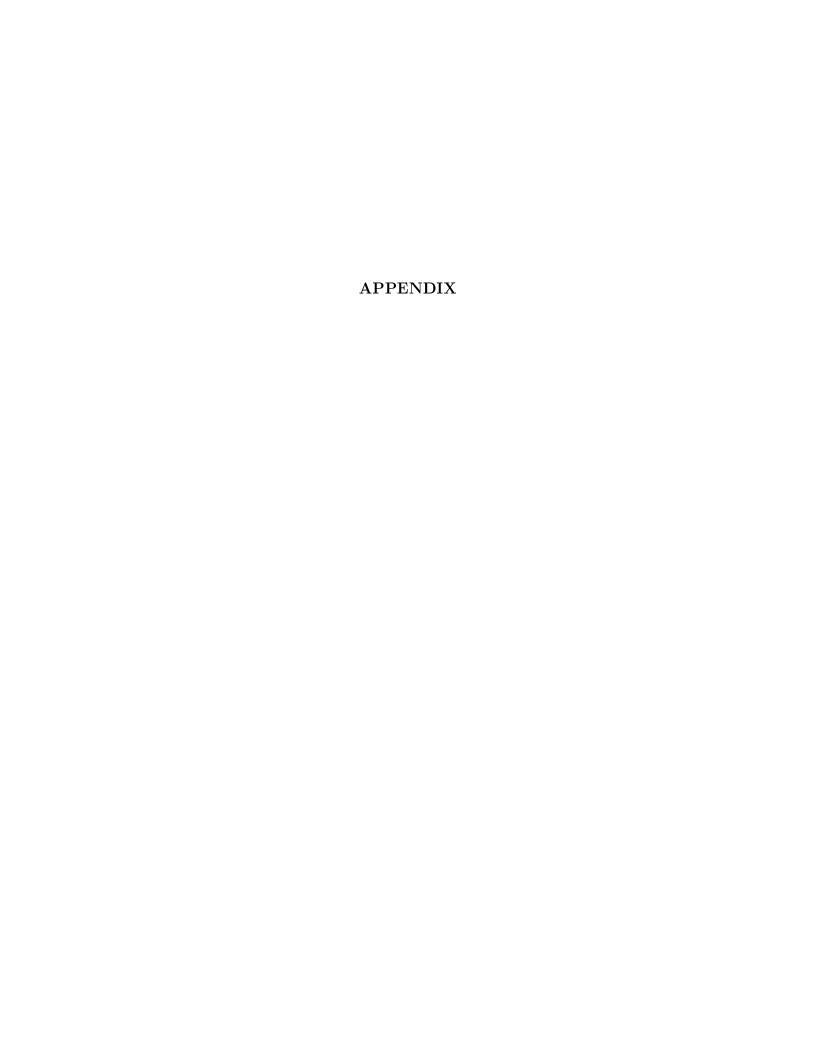


Figure 3.1 Cost per raw megabase of DNA sequence from 2001 to 2015. Straight line - Moore's Law, blue curve - cost in US dollars, Y-axis scale is logarithmic. Graph reproduced from wetterstrand2016

Example of reference to a figure in the text (Fig. 3.1).



Appendix A

Branch Flow Model: Relaxations and

Convexification

 ${\bf Table\ A.1\ Table\ describing\ the\ Branch\ Flow\ Model\ equations}.$

Equation $\#$	Equation	Unknowns	Knowns	No. of Equations
		$1 \times p_0$	$n \times p_j$	
13	$p_j = \sum P_{jk} + \sum (P_{ij} - r_{ij}l_{ij}) + g_j v_j$	$m \times P_{ij}$	$m \times r_{ij}$	(n+1)
10	$p_j = \angle F_{jk} + \angle (F_{ij} - T_{ij}v_{ij}) + g_jv_j$	$m \times l_{ij}$	$(n+1) \times g_j$	(n+1)
		$n \times v_j$	$1 \times v_0$	
		$1 \times q_0$	$n \times q_j$	
1.4	$\alpha = \Sigma O + \Sigma (O - m \cdot l) + b \cdot m$	$m \times Q_{ij}$	$m \times x_{ij}$	(n+1)
14	$q_j = \Sigma Q_{jk} + \Sigma (Q_{ij} - x_{ij}l_{ij}) + b_j v_j$	$m \times l_{ij}$	$(n+1) \times b_j$	(n+1)
		$n \times v_j$	$1 \times v_0$	
		$m \times P_{ij}$		
15	(2 + 2)1	$m \times Q_{ij}$	$b \times r_{ij}$	
15	$v_j = v_i + (r_{ij}^2 + x_{ij}^2)l_{ij} - 2(r_{ij}P_{ij} + x_{ij}Q_{ij})$	$m \times l_{ij}$	$m \times x_{ij}$	m
		$n \times v_j$	$1 \times v_0$	
		$m \times P_{ij}$		
16	$l_{ij}=rac{P_{ij}^2+Q_{ij}^2}{v_i}$	$m \times Q_{ij}$	_	200
16	$t_{ij} = \frac{1}{v_j}$	$m \times l_{ij}$	$1 \times v_0$	m
		$n \times v_j$		
		1	$n \times p_j$	
		$1 \times p_0$	$n \times q_j$	
		$1 \times q_0$	$m \times r_{ij}$	
13 to 16		$m \times P_{ij}$	$m \times x_{ij}$	2(n+1+m)
		$m \times Q_{ij}$	$(n+1) \times g_j$	
		$m \times l_{ij}$	$(n+1) \times b_j$	
		$n \times v_j$	$1 \times v_0$	
		2(n+1+m)	4n + 2m + 3	2(n+1+m)

Appendix B

Abstracts: Optimization-based Methods for solving MP-OPF

Appendix C

Abstracts: Dynamic Programming
Methods for solving MP-OPF

TBA.