Class: B.E. A Batch: A1

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```
#include <iostream>
#include <cuda runtime.h>
using namespace std;
__global__ void vectorAdd(int *A, int *B, int *C, int N) {
  int i = blockldx.x * blockDim.x + threadldx.x;
  if (i < N) C[i] = A[i] + B[i];
}
int main() {
  int N;
  cout << "Enter the size of vectors: "; cin >> N;
  int h_A = \text{new int}[N], h_B = \text{new int}[N], h_C = \text{new int}[N];
  cout << "Enter elements of vector A:\n";
  for (int i = 0; i < N; i++) cin >> h A[i];
  cout << "Enter elements of vector B:\n";
  for (int i = 0; i < N; i++) cin >> h B[i];
  int *d A, *d B, *d C;
  cudaMalloc(&d A, N * sizeof(int));
  cudaMalloc(&d B, N * sizeof(int));
  cudaMalloc(&d C, N * sizeof(int));
  cudaMemcpy(d A, h A, N * sizeof(int), cudaMemcpyHostToDevice);
  cudaMemcpy(d_B, h_B, N * sizeof(int), cudaMemcpyHostToDevice);
  vectorAdd<<<(N + 255) / 256, 256>>>(d_A, d_B, d_C, N);
  cudaMemcpy(h_C, d_C, N * sizeof(int), cudaMemcpyDeviceToHost);
  cout << "Result of vector addition:\n";
  for (int i = 0; i < N; i++) cout << h C[i] << " ";
  cout << endl;
```

```
cudaFree(d_A); cudaFree(d_B); cudaFree(d_C);
delete[] h_A; delete[] h_B; delete[] h_C;
return 0;
}
```

## 

Enter the size of vectors: 5 Enter elements of vector A: 1 2 3 4 5 Enter elements of vector B: 10 20 30 40 50

Result of vector addition: 11 22 33 44 55